## Measure Theoretic Conditional Expectation in an Elementary Setting

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## Overview

The measure theoretic approach to conditional expectation can be confusing when compared to the traditional approach – especially in a discrete setting. In what follows we go through a conditional expectation problem within a discrete and familiar setting in an attempt to reduce this confusion. In the example shown, we show explicitly that the conditional expectation function is non-measurable in the origin measure space.

## Elementary Probability Example Using Measure Theory

Let  $X = \{D_1, D_2, D_3, D_4, D_5, D_6\}$  and define a function P by  $P(D_i) = \frac{1}{6}$ , for  $i \in \{1, 2, 3, 4, 5, 6\}$ . The intent is that P will become a probability measure for the space we construct. Let  $\mathcal{E} = 2^X$  be the sigma algebra consisting of the power set of X. We extend P for every element in the sigma algebra. Since the sigma algebra consists of all sets we need an assignment for an arbitrary set, A. The assignment is  $P(A) = \frac{|A|}{6}$ ; that is the cardinality of the set divided by A0. We now have a measure space; in fact, a probability space:  $P(A, X, \mathcal{E})$ 1. Note that for a probability space we need an event space,  $P(A, X, \mathcal{E})$ 2. Note that for a probability space we need an event space,  $P(A, X, \mathcal{E})$ 3. We have a light and algebra of sets (in the discrete case just an algebra), and a function  $P(A, X, \mathcal{E})$ 3. Which takes elements of the sigma algebra to  $P(A, X, \mathcal{E})$ 3. We have a measure space in fact, a probability space we need an event space,  $P(A, X, \mathcal{E})$ 3. We have a measure space in fact, a probability space we need an event space in fact, a probability space we need an event space in fact, a probability space in fa

$$P(\bigcup_{i=1}^{N} A_i) = \sum_{i=1}^{N} P(A_i)$$
 when  $A_k \cap A_j = \emptyset$   $k \neq j$ 

We now consider a random variable from which we will get a sub-sigma algebra. Let

$$g(D_i) = \begin{cases} 0 & \text{if } i \text{ is even;} \\ 1 & \text{if } i \text{ is odd} \end{cases}$$

In a discrete space the sigma algebra generated from g is the algebra of sets generated from the sets:  $g^{-1}(0), g^{-1}(1), g^{-1}(a)$ , for  $a \neq 0, 1$ . It is not too hard to see that  $\mathcal{F} = \{\emptyset, \{1, 3\}, \{2, 4, 6\}, \{1, 2, 3, 4, 5, 6\}\}$ .

For a discrete space a function, f, is measurable with respect to a sigma algebra if  $f^{-1}(a)$  is an element in the sigma algebra for all  $a \in (-\infty, \infty)$ . This has implications for the sigma algebra  $\mathcal{F}$ .

The claim is that any function which is measurable over  $\mathcal{F}$  has the property that f is constant on the sets  $\{1,3\}$  and  $\{2,4,6\}$ . That is, the minimal elements of the algebra, elements which have no non trivial subsets. To see this suppose that f(1) differs from f(3). Then  $f^{-1}(f(1))$  is a non trivial subset of  $\{1,3\}$  as is  $f^{-1}(f(3))$ . These two sets must differ since f(1) and f(3) differ. This means that they are respectively

 $\{1\}$  and  $\{3\}$ . But these sets are not in our sigma algebra. Therefore, f must be constant on  $\{1,3\}$ . In the same way it is the case that f is constant on the other minimal set  $\{2,4,6\}$ .

Notice that while any function over the measure space  $(P, X, \mathcal{E})$  is measurable, we can write down a specific function that is non-measurable with respect to  $\mathcal{F}$ . We know that all we have to do is come up with a function that differs on either of the sets  $\{1,3\}$  or  $\{2,4,6\}$ . Let  $f(D_i)=i$ , for  $i\in\{1,2,3,4,5,6\}$ , for instance.

## Conditional Expectation

Given a probability space  $(P, X, \mathcal{E})$ , the conditional expectation of a measurable function f with respect to a sub-sigma algebra  $\mathcal{F}$  is the unique  $\mathcal{F}$  measurable function (random variable) labeled,  $\mathbb{E}[f/\mathcal{F}]$ , such that

$$\int_{\Lambda} \mathbb{E}\left[f/\mathcal{F}\right] dP = \int_{\Lambda} f dP \quad \forall \Lambda \in \mathcal{F}$$
(1)

That is,  $\mathbb{E}[f/\mathcal{F}]$  is a measurable function in the probability space  $(P, X, \mathcal{F})$ . Although it seems that f itself satisfies this equation you have to be careful. The function we are looking for must be measurable with respect to  $\mathcal{F}$ , and since  $\mathcal{F}$  is a sub-sigma algebra of  $\mathcal{E}$ , it is quite possible that f is not  $\mathcal{F}$  measurable. However, if f is measurable with respect to  $\mathcal{F}$  then it is its own conditional expectation. We have the following basic facts about conditional expectation:

- $\mathbb{E}[f/\mathcal{F}] = f$  when f is measurable with respect to  $\mathcal{F}$ ;
- $\mathbb{E}\left[\mathbb{E}\left[f/\mathcal{F}\right]/\mathcal{F}\right] = \mathbb{E}\left[f/\mathcal{F}\right];$   $\mathbb{E}\left[\left(f \mathbb{E}\left[f/\mathcal{F}\right]\right)/\mathcal{F}\right] = 0.$

Consider the function of the last section,  $f(D_i) = i$ , which is measurable in the space  $(P, X, \mathcal{E})$ . Let  $\mathcal{F}$  be the sub-sigma algebra of the last section as well. We now compute the conditional expectation of f with respect to  $\mathcal{F}$ . Using (1) we choose two  $\Lambda$ 's:  $\Lambda_1 = \{1,3\}$  and  $\Lambda_2 = \{2,4,6\}$ . We have

$$\int_{\Lambda_1} \mathbb{E}\left[f/\mathcal{F}\right] dP = \int_{\Lambda_1} f dP \tag{2}$$

and

$$\int_{\Lambda_2} \mathbb{E}\left[f/\mathcal{F}\right] dP = \int_{\Lambda_2} f dP \tag{3}$$

We know  $\mathbb{E}[f/\mathcal{F}]$  is constant on  $\Lambda_1$ . We label this value as  $C_{\Lambda_1}$ . From (2) we have

$$\begin{split} \int_{\Lambda_1} \mathbb{E} \left[ f / \mathcal{F} \right] dP &= \int_{\Lambda_1} f \, dP \\ C_{\Lambda_1} \int_{\Lambda_1} dP &= \int_{\Lambda_1} f \, dP \\ C_{\Lambda_1} * P(\Lambda_1) &= \int_{\Lambda_1} f \, dP = f(D_1) * P(D_1) + f(D_3) * P(D_3) \\ C_{\Lambda_1} * P(\Lambda_1) &= 1 * \frac{1}{6} + 3 * \frac{1}{6} = \frac{2}{3} \end{split}$$

Since  $P(\Lambda_1) = \frac{2}{6} = \frac{1}{3}$ , we have that

$$C_{\Lambda_1} = 2$$

Consequently,

$$\mathbb{E}\left[f/\mathcal{F}\right](D_1) = \mathbb{E}\left[f/\mathcal{F}\right](D_3) = C_{\Lambda_1} = 2$$

Likewise,  $\mathbb{E}[f/\mathcal{F}]$  is constant on the set  $\Lambda_2$ . As we did above, we find the value of  $\mathbb{E}[f/\mathcal{F}]$  on the set  $\Lambda_2$ . Let  $C_{\Lambda_2}$  be the constant value of  $\mathbb{E}[f/\mathcal{F}]$  on  $\Lambda_2$ . We have

$$\int_{\Lambda_2} \mathbb{E}[f/\mathcal{F}] dP = \int_{\Lambda_2} f dP$$

$$C_{\Lambda_2} \int_{\Lambda_2} dP = \int_{\Lambda_2} f dP$$

$$C_{\Lambda_2} * P(\Lambda_2) = \int_{\Lambda_2} f dP = f(D_2) * P(D_2) + f(D_4) * P(D_4) + f(D_6) * P(6)$$

$$C_{\Lambda_2} * P(\Lambda_2) = 2 * \frac{1}{6} + 4 * \frac{1}{6} + 6 \frac{1}{6} = 2$$

Since  $P(\Lambda_2) = \frac{3}{6} = \frac{1}{2}$ , we have that

$$C_{\Lambda_2} = 4$$

Consequently,

$$\mathbb{E}\left[f/\mathcal{F}\right](D_2) = \mathbb{E}\left[f/\mathcal{F}\right](D_4) = \mathbb{E}\left[f/\mathcal{F}\right](D_6) = C_{\Lambda_2} = 4$$

Since a function is determined once we know what its values are on every  $x \in X$ , we have found the conditional expectation function,  $\mathbb{E}[f/\mathcal{F}]$ , as we know its values on every  $x \in X$ .