

Derivation of the Exponential Moving Average

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1 Overview

The essence of the *exponential moving average* (EMA) is to provide a *localized* estimate of a time series as it proceeds. It does this by using a weighted average of the values in a "window" around each point of the series in way that each summand in the average is multiplied by powers of a factor, λ , in the interval $(0, 1)$. In what follows below we will assume a 1-based index, and that the data series \mathbf{x} has length N .

Specifically, the exponential moving average (over a window of length m) is defined as:

$$e_n = \sum_{k=0}^{m-1} x_{n-k} w_{k+1} \quad (1)$$

To get the *exponential decay* in weights we assume that $w_{k+1} = \lambda w_k$.¹ Since the parameter $\lambda \in (0, 1)$ it is a decay factor. Notice that the indices of \mathbf{x} and that of \mathbf{w} go in the "opposite direction". This is done so that the largest weights are associated with the most recent data in the averaging window.

Before we go further, there is a problem with the formula as stated. If $n = 1$; or, in fact any value that is less than or equal to m , the expression x_{n-k} does not make sense for $k \geq n$. That is, at the start of the computation and for a little while, there is not a full window of values over a window of length m . As there is no information before x_1 , we interpret these values to be x_1 . We will apply this principal more generally below. That is, if \mathbf{z} is a data series, we extend the definition of \mathbf{z} so that it is defined for indices less than 1 as:

$$z_k = \begin{cases} z_k & k \geq 1; \\ z_1 & \text{otherwise.} \end{cases} \quad (2)$$

While we can use (1) to compute the EMA it is *inefficient*. The purpose of this paper is to derive a recursive formula that is fast to compute.

¹The reason this is called exponential is that it is the discrete analog of continuous exponential decay. To see this let $f(x) = e^{-kt}$ for $k > 0$. Then sampling this function at regular intervals of say 1 we get the sequence: $\{e^{-k}, e^{-2k}, e^{-3k}, \dots\}$. Here we can see that the elements of the sequence are powers of a value, $\lambda = e^{-k}$. That is, the sequence is nothing other than: $\{\lambda, \lambda^2, \lambda^3, \dots\}$.

The formula takes advantage of the fact that when the weights are exponentials (powers of λ) we don't have to recompute the bulk of the sums in the averaging window.

Regardless of the averaging scheme we want our weights to sum to one.² But we also want the weights to be exponential; that is, $w_{k+1} = \lambda w_k$.

Ideally, all we want to do is give the decay factor, λ . If so, how do we determine the weights? We briefly describe the process. The weights can be constructed as follows once a λ is given.

For $i \in [1, m]$ define

$$\hat{w}_i = \lambda^i \quad (3)$$

The $\hat{\mathbf{w}}$ have the property that they decay with λ . That is, $\lambda w_k = w_{k+1}$. However, how do we ensure that these values sum to 1 over the window.

To do this, we simply normalize the weights:

$$w_i = \frac{\hat{w}_i}{\sum_{k=1}^m \hat{w}_k} \quad \forall i \in [1, m] \quad (4)$$

In doing this, do the proposed weights, \mathbf{w} , lose the decay factor property? The answer is no, the property remains: $\lambda w_i = w_{i+1} \quad \forall i \in [1, m-1]$.

Note: We will use this fact in our derivation below.

2 Recursive Formula for EMA

Define the exponential moving average of x as:

$$e_n = \sum_{k=0}^{m-1} x_{n-k} w_{k+1} \quad (5)$$

We examine the formula for the next element in the smoothing sequence and try to relate it to the present element at index n .

²This is because the moving average is an estimate of the mean and we wish our estimate to be *unbiased*: $E \left[\sum_{k=1}^m x_{n-k} w_{k+1} \right] = \sum_{k=0}^{m-1} E[x_{n-k}] w_{k+1}$. Which is $\mu \sum_{k=0}^{m-1} w_{k+1} = \mu \sum_{k=1}^m w_k = \mu$.

$$\begin{aligned}
e_{n+1} &= \sum_{k=0}^{m-1} x_{n+1-k} w_{k+1} \\
&= \sum_{k=0}^{m-1} x_{n-(k-1)} w_{k+1} \\
&= \sum_{k=-1}^{m-2} x_{n-k} w_{k+2} \\
&= \sum_{k=0}^{m-2} x_{n-k} w_{k+2} + x_{n+1} w_1 \\
&= \lambda \sum_{k=0}^{m-2} x_{n-k} w_{k+1} + x_{n+1} w_1 \quad (\text{Since } \lambda w_{k+1} = w_{k+2}) \\
&= \lambda \sum_{k=0}^{m-1} x_{n-k} w_{k+1} + x_{n+1} w_1 - \lambda x_{(n+1)-m} w_m
\end{aligned}$$

Finally, we may write

$$e_{n+1} = \lambda e_n + x_{n+1} w_1 - \lambda x_{(n+1)-m} w_m \quad \forall n \in [1, N-1] \quad (6)$$

$$e_1 = x_1 \quad (7)$$

3 Recursive Formula for the Std of EMA

In practice, one also wants to know a localized standard deviation of the process. In applications, one can provide "Bollinger" bands around the EMA estimate. These bands are some multiple of the standard deviation of the process.

We derive the standard deviation of the exponential moving average starting with the definition of the exponential moving average and its moving variation.³

$$e_n = \sum_{k=0}^{m-1} x_{n-k} w_{k+1} \quad (8)$$

$$v_n = \sum_{k=0}^{m-1} (x_{n-k} - e_{n-k})^2 w_{k+1} \quad (9)$$

³This variance formula needs to be corrected by a factor which we leave to the end. The correction is a factor that is used to make the estimated standard deviation of the moving average *unbiased*. The formula for this factor is independent of the structure of the weights.

As in the previous section, we look at the next element of the sequence and try to show its relation to the present value at index n .

$$\begin{aligned}
v_{n+1} &= \sum_{k=0}^{m-1} (x_{(n+1)-k} - e_{(n+1)-k})^2 w_{k+1} \\
&= \sum_{k=0}^{m-1} (x_{n-(k-1)} - e_{n-(k-1)})^2 w_{k+1} \\
&= \sum_{k=-1}^{m-2} (x_{n-k} - e_{n-k})^2 w_{k+2} \\
&= \sum_{k=0}^{m-2} (x_{n-k} - e_{n-k})^2 w_{k+2} + ((x_{n+1} - e_{n+1})^2 w_1 \\
&= \lambda \sum_{k=0}^{m-2} (x_{n-k} - e_{n-k})^2 w_{k+1} + (x_{n+1} - e_{n+1})^2 w_1 \quad (\text{Since } \lambda w_{k+1} = w_{k+2}) \\
&= \lambda \left[\sum_{k=0}^{m-1} (x_{n-k} - e_{n-k})^2 w_{k+1} - (x_{(n+1)-m} - e_{(n+1)-m})^2 w_m \right] + (x_{n+1} - e_{n+1})^2 w_1
\end{aligned}$$

Therefore,

$$v_{n+1} = \lambda v_n + (x_{n+1} - e_{n+1})^2 w_1 - \lambda (x_{(n+1)-m} - e_{(n+1)-m})^2 w_m \quad \forall n \in [1, N-1] \quad (10)$$

$$v_1 = w_m (x_1 - e_1)^2 = 0 \quad (11)$$

Finally, the standard deviation of the exponential moving average is:

$$s_n = \sqrt{\frac{v_n}{1 - \sum_{i=1}^m w_i^2}} \quad (12)$$

The variance corrective factor, $1 - \sum_{i=1}^m w_i^2$ is a one time calculation independent of n . This factor is the standard correction when determining empirical variance of a weighted average.

Note:. In practice, one may wish to use some prior estimate of the standard deviation of the process and smoothly move from that to the estimate above over the averaging windows when $n \in [1, m]$.

4 How to Specify the λ Factor

When using the EMA, practitioners do not specify the factor λ directly; instead they provide the "half-life" of the decay. By half-life we mean the number of powers of λ , N , so that $\lambda^N \approx \frac{1}{2}$.

In our case we are interested in the reverse; namely, given a half life, N , determine the factor λ . To do this we solve the equation $\lambda^N = \frac{1}{2}$ for λ . Taking the log of this equation and solving for λ we have:

$$\begin{aligned}\log(\lambda^N) &= \log\left(\frac{1}{2}\right) \\ N \log(\lambda) &= \log(1) - \log(2) \\ \log(\lambda) &= -\frac{\log(2)}{N}\end{aligned}$$

The formula for λ given N becomes:

$$\lambda = e^{-\frac{\log(2)}{N}} \tag{13}$$