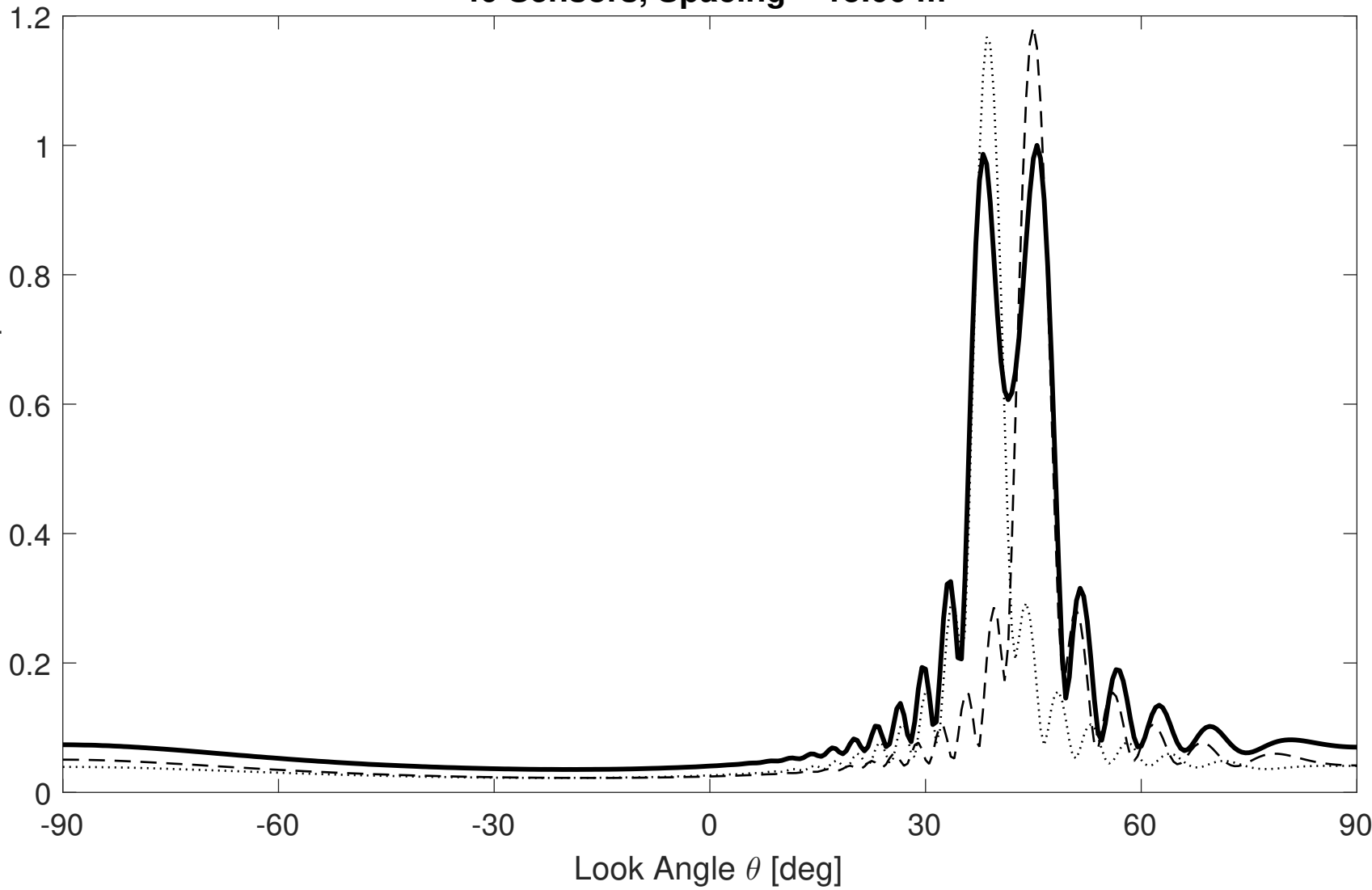


40 Sensors, Spacing = 15.00 m

Normalized Response



Look Angle  $\theta$  [deg]