

# SVM

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April 1

# Outline

- Margin and VC-dimension
- The separable case
- Non- separable case: Hing Loss
- Kernels

# SVM: Intuition

- Remember LR

- Predict  $Y=1$  if  $\frac{1}{1 + \exp(-(w \cdot x + b))} > 0.5$
- or if  $w \cdot x > 0$
- The more prob.  $\gg 0.5$ , the more confident we are about our prediction
- Or the more  $w \cdot x + b \gg 0$  (margin), the more we are confident about our prediction
- Same in SVM

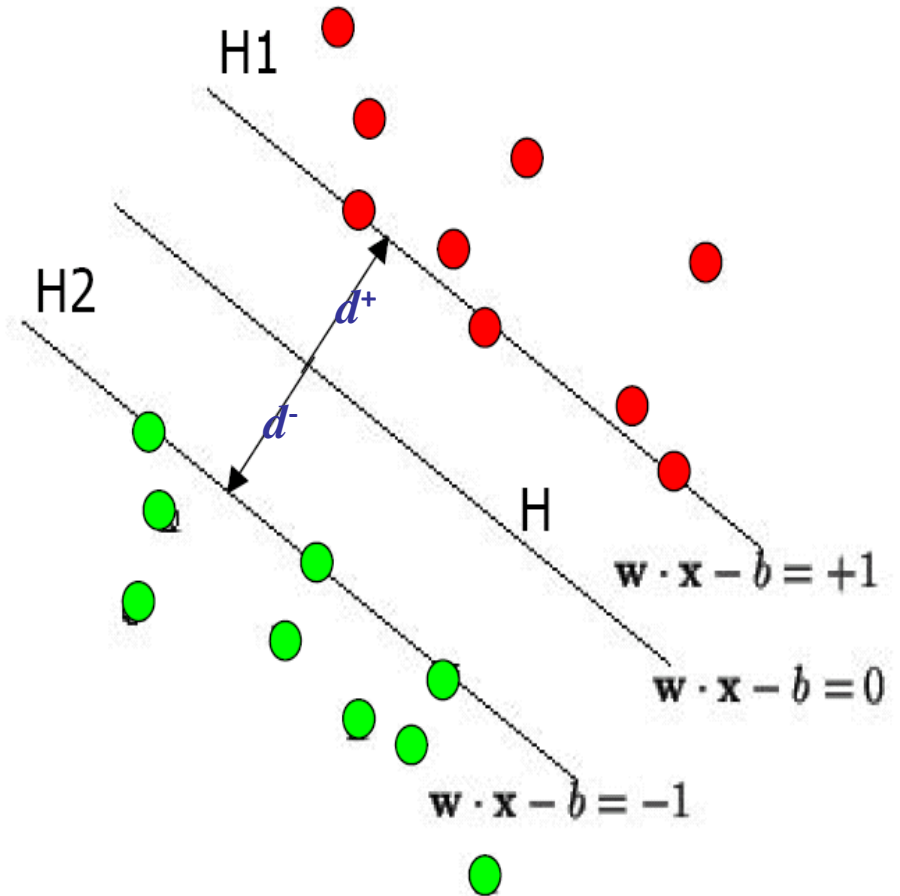
# SVM

- SVM problem

$$\begin{array}{ll}\max_{w,b} & \frac{1}{\|w\|} \\ \text{s.t} & y_i(w^T x_i + b) \geq 1, \quad \forall i\end{array}$$

- Or equivalently

$$\begin{array}{ll}\min_{w,b} & \frac{1}{2} w^T w \\ \text{s.t} & y_i(w^T x_i + b) \geq 1, \quad \forall i\end{array}$$



# SVM using VC-dimension

## VC Theory

(Vapnik, 1982)

Given  $x_1, \dots, x_n \in \mathbb{R}^d$  iid and  $\|x_i\|_2 \leq D$ , if  $\mathcal{H}_\gamma$  is the hypothesis space of linear classifiers in  $\mathbb{R}^d$  with margin  $\gamma$ ,

$$VC(\mathcal{H}_\gamma) \leq \min \left\{ d, \left\lceil \frac{4D^2}{\gamma^2} \right\rceil \right\}.$$

$$error_{true}(h) < error_{train}(h) + \sqrt{\frac{VC(H)(\ln \frac{2m}{VC(H)} + 1) + \ln \frac{4}{\delta}}{m}}$$

# SVM using VC-dimension

- Thus large-margin  $\rightarrow$  small VC-dim  $\rightarrow$  better generalization bound
- Recall that  $d+1$  is the upper bound for a linear classifier in  $d$ -space

$$VC(\mathcal{H}_\gamma) \leq \min \left\{ d, \left\lceil \frac{4D^2}{\gamma^2} \right\rceil \right\}.$$

$$error_{true}(h) < error_{train}(h) + \sqrt{\frac{VC(H)(\ln \frac{2m}{VC(H)} + 1) + \ln \frac{4}{\delta}}{m}}$$

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# Solution Sketch

$$\begin{array}{ll} \min_{w,b} & \frac{1}{2} w^T w \\ \text{s.t} & y_i (w^T x_i + b) \geq 1, \quad \forall i \end{array}$$

- Form the Lagrangian
- Optimize with respect to primal variable
- Subs. Into Lagrangian to get dual problem
- Exploit the KKT condition



# Lagrangian

$$\begin{aligned} \operatorname{argmin}_{w,b} \quad & \frac{1}{2} \|w\|^2 \\ \text{s.t.} \quad & y_i(w \cdot x_i + b) \geq 1. \end{aligned}$$

$$L(w, b, \alpha) = \frac{1}{2} w \cdot w - \sum_i \alpha_i [y_i(w \cdot x_i + b) - 1]$$

- One dual variable per constraints

$$L(w, b, \alpha) = \frac{1}{2} w \cdot w - \sum_i \alpha_i [y_i (w \cdot x_i + b) - 1]$$

$$\frac{\partial}{\partial w} L(w, b, \alpha) = w - \sum_i \alpha_i y_i x_i = 0 \rightarrow w = \sum_i \alpha_i y_i x_i.$$

$$\frac{\partial}{\partial b} L(w, b, \alpha) = \sum_i \alpha_i y_i = 0.$$

$$\operatorname{argmax}_{\alpha} L(w, b, \alpha) = \operatorname{argmax}_{\alpha} \sum_i \alpha_i - \frac{1}{2} \sum_{i,j} \alpha_i \alpha_j y_i y_j (x_i \cdot x_j)$$

$$s.t. \quad \alpha_i \geq 0,$$

$$\sum_i \alpha_i y_i = 0.$$

# KKT conditions

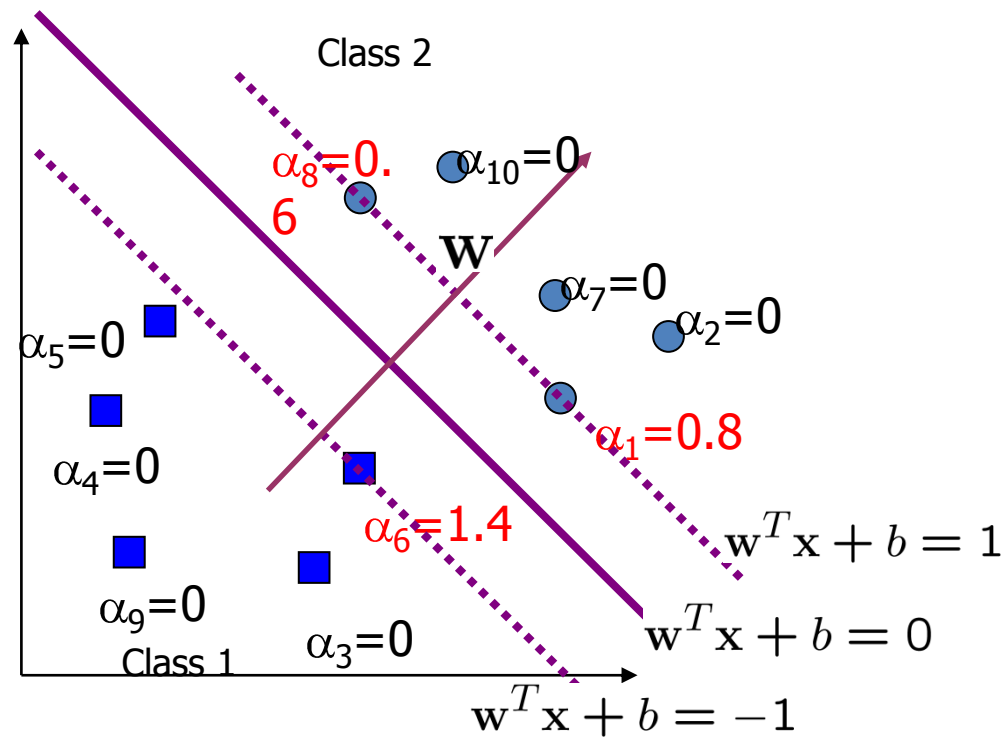
- For convex objective and affine constraints we have
- Only a few  $\alpha_i$  can be non-zero.

$$w = \sum_{i \in SV} \alpha_i y_i x_i$$

- How about  $b$ ?

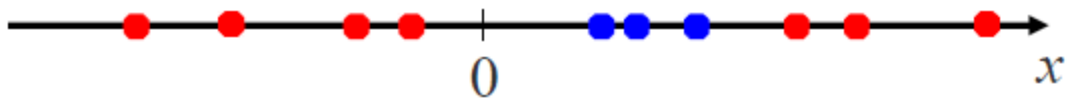
$$y^*(z) = \text{sign} \left( \sum_{i \in SV} \alpha_i y_i x_i^T z + b \right)$$

$$\alpha_i [-y_i (w^T x_i + b)] = 0, \quad i = 1, \dots, m$$

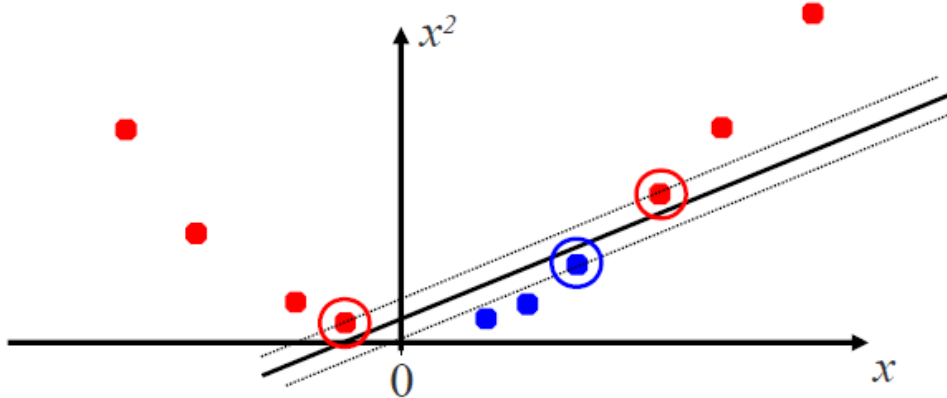


# Kernel Trick

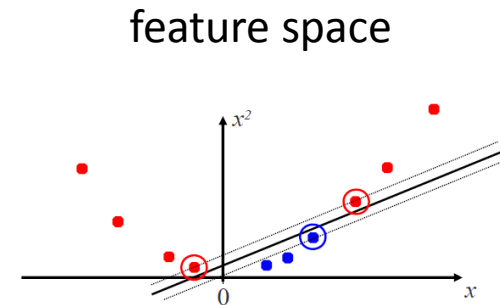
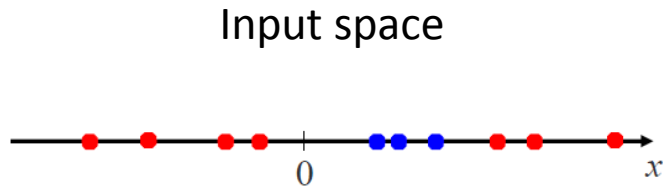
- Is this data linearly-separable?



- How about a quadratic mapping  $\phi(x_i)$ ?



# Kernel Trick



- Simply replace  $x_i$  with  $\phi(x_i)$  !

$$\max_{\alpha} \sum_{i=1}^m \alpha_i - \frac{1}{2} \sum_{i,j=1}^m \alpha_i \alpha_j y_i y_j \phi(\mathbf{x}_i)^t \phi(\mathbf{x}_j)$$

$$\text{s.t. } \alpha_i \geq 0, \quad i = 1, \dots, k$$

$$\sum_{i=1}^m \alpha_i y_i = 0.$$

$$y^*(z) = \text{sign} \left( \sum_{i \in SV} \alpha_i y_i \phi(\mathbf{x}_i)^t \phi(\mathbf{z}) + b \right)$$

- So what is the deal?

# Kernel Trick

- Computation depends on feature space
  - Bad if its dimension is much larger than input space

$$\begin{aligned} \max_{\alpha} \quad & \sum_{i=1}^m \alpha_i - \frac{1}{2} \sum_{i,j=1}^m \alpha_i \alpha_j y_i y_j K(\mathbf{x}_i, \mathbf{x}_j) \\ \text{s.t.} \quad & \alpha_i \geq 0, \quad i = 1, \dots, m \\ & \sum_{i=1}^m \alpha_i y_i = 0. \end{aligned}$$

Where  $K(\mathbf{x}_i, \mathbf{x}_j) = \phi(\mathbf{x}_i)^T \phi(\mathbf{x}_j)$

$$y^*(z) = \text{sign} \left( \sum_{i \in SV} \alpha_i y_i K(\mathbf{x}_i, z) + b \right)$$

# Example Kernel

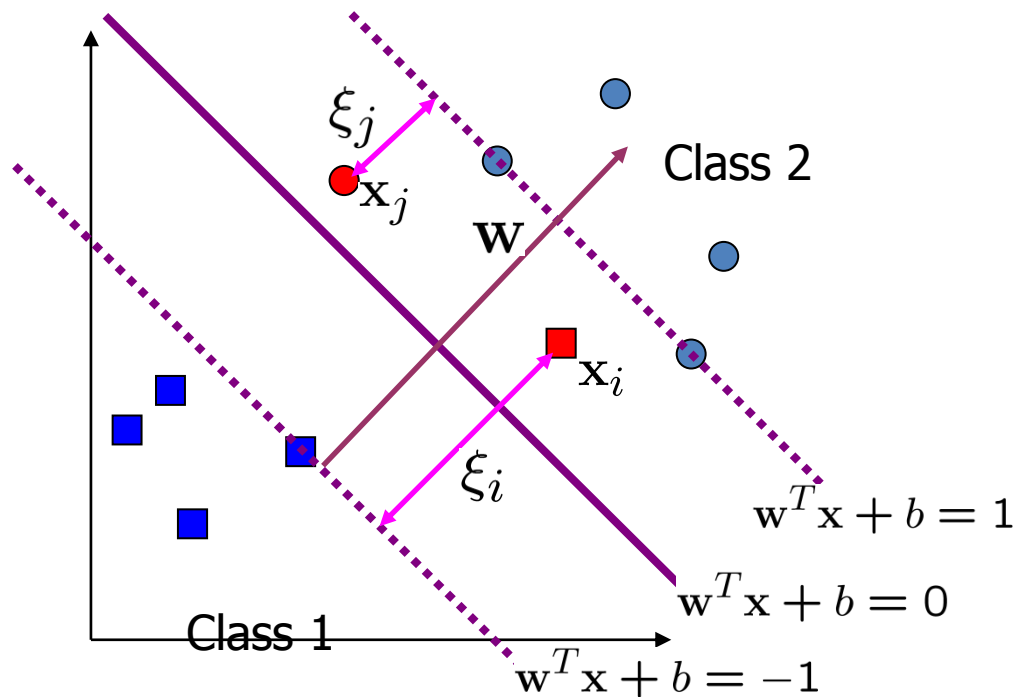
- $x_i$  is a bag of words
- Define  $\phi(x_i)$  as a count of every  $n$ -gram up to  $n=k$  in  $x_i$ .
  - This is huge space  $26^k$
  - What are we measuring by  $\phi(x_i)^t \phi(x_j)$ ?
- Can we compute the same quantity on input space?
  - Efficient linear dynamic program!
- Kernel is a measure of similarity
- Must be positive semi-definite

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# Non-separable case



$$\min_{w,b} \quad \frac{1}{2} w^T w + C \sum_{i=1}^m \xi_i$$

$$\text{s.t.} \quad y_i (w^T x_i + b) \geq 1 - \xi_i, \quad \forall i$$
$$\xi_i \geq 0, \quad \forall i$$

# Remember Ridge regression

- Min [squared loss +  $\lambda w^t w$ ]
- How about SVM?

$$\operatorname{argmin}_{\{w,b\}} \underbrace{w^t w}_{\text{regularization}} + \lambda \underbrace{\sum_1^m \max(1 - y_i(w^t x_i + b), 0)}_{\text{Loss: hinge loss}}$$

regularization

Loss: hinge loss

$$\begin{aligned}
 \min_{w,b} \quad & \frac{1}{2} w^T w + C \sum_{i=1}^m \xi_i \\
 \text{s.t.} \quad & y_i(w^T x_i + b) \geq 1 - \xi_i, \quad \forall i \\
 & \xi_i \geq 0, \quad \forall i
 \end{aligned}$$

$$\xi_i \geq \max(0, 1 - y_i(w^T x_i + b))$$



Why?

$$\xi_i = \max(0, 1 - y_i(w^T x_i + b))$$

$$\operatorname{argmin}_{\{w,b\}} \underbrace{w^t w}_{\text{regularization}} + \lambda \underbrace{\sum_1^m \max(1 - y_i(w^t x_i + b), 0)}_{\text{Loss: hinge loss}}$$

regularization

Loss: hinge loss