# DEEP LEARNING FRAMEWORKS WORKSHOP

SAIG – Winter 2018

### **NEURAL NETS REVIEW**

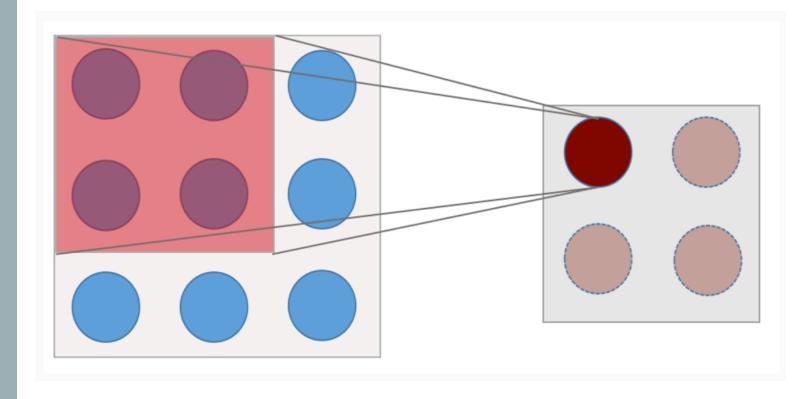
- Set of matrix multiplications to transform and input into an output
- We are given input data and target
- Transform input to our guess at target, and compare our guess to the answer
  - We compute a loss value—how wrong our guess was
  - Want to minimize this loss value by doing gradient descent on loss function

### CONVNET BASICS

#### CONVOLUTIONAL LAYER

- Computes dot product over input map to create output map
  - Map is 3D tensor with spatial dimensions
  - Input map is image, output map is representation
- Layer has one shared weight called a filter
- Filter is "slid" over the input
  - Amount it is slide is called stride
  - Size of filter is called kernel size or spatial extent
  - We can surround the border with zeros, called padding

CONV LAYER VISUALIZED



### MAX POOLING LAYER

- Same idea of "sliding" as a convolutional layer
- The difference: no dot product, just tax the max!

#### RECTIFIED LINEAR UNIT LAYER

- In general, activation functions take a single number and performs a mathematical operation upon it. They provide nonlinear properties to the network
- Computes the activation function f(x) = max(0, x)
- Found to accelerate the convergence of SGD
- Easier to implement than other activation functions (sigmoid, tanh)
- Avoids saturation problems with sigmoid and tanh neurons, but this comes at a cost – if x is ever less than 0, the neuron "dies"

#### SOFTMAX LAYER

- Defines an output layer for neural networks
- First, forms weighted outputs defined as

$$z_{j}^{L} = \sum_{k} w_{jk}^{L} a_{k}^{L-1} + b_{j}^{L}$$

and applies the softmax function to these outputs defined as

$$a_j^L = \frac{e^{z_j^L}}{\sum_k e^{z_k^L}}$$

we can prove that this function squashes all outputs so that the sum of the outputs is equal to 1. So, the output of softmax can be thought of as a probability distribution.

### **TENSORFLOW**

### CREATE MODEL

```
def cnn model fn(features, labels, mode):
  input layer = tf.reshape(features["x"], [-1, 28, 28, 1])
  conv1 = tf.layers.conv2d(
      inputs=input layer,
      filters=32,
      kernel size=[3, 3],
      padding="same",
      activation=tf.nn.relu)
  conv2 = tf.layers.conv2d(
      inputs=conv1,
      filters=64,
      kernel size=[3, 3],
      padding="same",
      activation=tf.nn.relu)
  pool = tf.layers.max pooling2d(inputs=conv2, pool_size=[2, 2], strides=2)
  dropout1 = tf.layers.dropout(
      inputs=pool, rate=0.25, training=mode == tf.estimator.ModeKeys.TRAIN)
  flat = tf.reshape(dropout1, [-1, 14 * 14 * 64])
  dense = tf.layers.dense(inputs=flat, units=128, activation=tf.nn.relu)
  dropout2 = tf.layers.dropout(
      inputs=dense, rate=0.25, training=mode == tf.estimator.ModeKeys.TRAIN)
  logits = tf.layers.dense(inputs=dropout2, units=10)
```

### SETTING UP LOSS FUNCTION AND LOSS

```
predictions = {
    # Generate predictions (for PREDICT and EVAL mode)
    "classes": tf.argmax(input=logits, axis=1),
    # Add `softmax tensor` to the graph. It is used for PREDICT and by the
    # `logging hook`.
    "probabilities": tf.nn.softmax(logits, name="softmax tensor")
if mode == tf.estimator.ModeKeys.PREDICT:
  return tf.estimator.EstimatorSpec(mode=mode, predictions=predictions)
# Calculate Loss (for both TRAIN and EVAL modes)
loss = tf.losses.sparse softmax cross entropy(labels=labels, logits=logits)
# Configure the Training Op (for TRAIN mode)
if mode == tf.estimator.ModeKeys.TRAIN:
  optimizer = tf.train.GradientDescentOptimizer(learning rate=0.001)
 train op = optimizer.minimize(
      loss=loss,
      global step=tf.train.get global step())
  return tf.estimator.EstimatorSpec(mode=mode, loss=loss, train op=train op)
# Add evaluation metrics (for EVAL mode)
eval metric ops = {
    "accuracy": tf.metrics.accuracy(
        labels=labels, predictions=predictions["classes"])}
return tf.estimator.EstimatorSpec(
    mode=mode, loss=loss, eval metric ops=eval metric ops)
```

### LOADING AND PREPARING DATA

```
def main(unused argv):
  # Load training and eval data
  mnist = tf.contrib.learn.datasets.load dataset("mnist")
  train data = mnist.train.images # Returns np.array
  train labels = np.asarray(mnist.train.labels, dtype=np.int32)
  eval data = mnist.test.images # Returns np.array
  eval labels = np.asarray(mnist.test.labels, dtype=np.int32)
  # Create the Estimator
  mnist classifier = tf.estimator.Estimator(
     model fn=cnn model fn, model dir="/tmp/mnist convnet model")
  # Set up logging for predictions
  # Log the values in the "Softmax" tensor with label "probabilities"
     tensors to log = {"probabilities": "softmax tensor"}
     logging hook = tf.train.LoggingTensorHook(
         tensors=tensors to log, every n iter=1000)
```

## TRAIN AND EVAL MODEL

```
# Train the model
train_input_fn = tf.estimator.inputs.numpy_input_fn(
    x = {"x": train data},
    y=train labels,
    batch size=100,
    num_epochs=None,
    shuffle=True)
mnist classifier.train(
input fn=train input fn,
steps=20000)
# Evaluate the model and print results
eval input fn = tf.estimator.inputs.numpy input fn(
    x={"x": eval data},
    y=eval labels,
    num_epochs=1,
    shuffle=False)
eval results = mnist classifier.evaluate(input fn=eval input fn)
print(eval results)
```

### **KERAS**

#### INITIALIZE

```
from __future__ import print_function
import keras
from keras.datasets import mnist
from keras.models import Sequential
from keras.layers import Dense, Dropout, Flatten
from keras.layers import Conv2D, MaxPooling2D
from keras import backend as K
```

Using Theano backend.

```
batch_size = 128
num_classes = 10
epochs = 12
img_rows, img_cols = 28, 28
```

### LOAD DATA AND VARIABLES

```
# the data, shuffled and split between train and test sets
(x_train, y_train), (x_test, y_test) = mnist.load_data()

if K.image_data_format() == 'channels_first':
    x_train = x_train.reshape(x_train.shape[0], 1, img_rows, img_cols)
    x_test = x_test.reshape(x_test.shape[0], 1, img_rows, img_cols)
    input_shape = (1, img_rows, img_cols)

else:
    x_train = x_train.reshape(x_train.shape[0], img_rows, img_cols, 1)
    x_test = x_test.reshape(x_test.shape[0], img_rows, img_cols, 1)
    input_shape = (img_rows, img_cols, 1)
```

## CREATE

## TRAIN AND EVAL MODEL

### **PYTORCH**

### CREATE MODEL

```
class Flatten(nn.Module):
    def init (self):
        super(Flatten, self). init ()
    def forward(self, X):
        X = X.view(X.size(0), -1)
        return X
class SimpleCNN(nn.Module):
    def init (self):
        super(SimpleCNN, self). init ()
        self.model = nn.Sequential(nn.Conv2d(1, 32, kernel_size=3),
                                   nn.ReLU(),
                                   nn.Conv2d(32, 64, kernel size=3),
                                   nn.MaxPool2d(2),
                                   nn.Dropout(0.25),
                                   Flatten(),
                                   nn.Linear(9216, 128),
                                   nn.Dropout(0.5),
                                   nn.Linear(128, 10)
    def forward(self, X):
       X = self.model(X)
        return X
```

### LOAD DATA AND VARIABLES

```
transform = transforms.Compose([
                                transforms.ToTensor(),
                                transforms.Normalize((0.5,),(1.0,))
train set = dset.MNIST(root='./data', train=True,
                       transform=transform, download=True)
test set = dset.MNIST(root='./data', train=False, transform=transform)
batch size = 100
train loader = torch.utils.data.DataLoader(
                 dataset=train set,
                 batch size=batch size,
                 shuffle=True)
test loader = torch.utils.data.DataLoader(
                dataset=test set,
                batch size=batch size,
                shuffle=False)
model = SimpleCNN()
criterion = nn.CrossEntropyLoss()
optimizer = optim.Adam(model.parameters(), lr=1e-2)
```

### DEFINE RUN FUNCTION

```
def run model(loader, train=False, optimizer=None):
    avg loss, avg acc = 0, 0
    for i, (X, y) in enumerate(loader):
        if train:
            optimizer.zero grad()
        X, y = Variable(X), Variable(y)
        y hat = model(X)
        loss = criterion(y hat, y)
        if train:
            loss.backward()
            optimizer.step()
        pred = np.argmax(y_hat.data.numpy(), axis=1)
        acc = float(len(np.where(pred == y.data.numpy())[0]))
        acc /= batch size
        avg_loss += loss.data[0]
        avg acc += acc
    avg loss \neq (i+1)
    avg acc \neq (i+1)
    return avg loss, avg acc
```

## TRAIN AND EVAL MODEL