↳ For algorithms, this is breaking it down into running time and memory space.

- Time complexity:
- Space complexity:

fixed

- Basic operation:

↳ Otherwise, we physically do not have the time to calculate them.

- Worst case:

- Best case:

↳ if the best case is unsatisfactory, we can disregard the algorithm entirely.

- Average case:

$$C_{avg}(n) = [1 \cdot \frac{p}{n} + 2 \cdot \frac{p}{n} + \cdots + i \cdot \frac{p}{n} + \cdots + n \cdot \frac{p}{n}] + n \cdot (1-p)$$
$$= \frac{p}{n}[1 + 2 + \cdots + i + \cdots + n] + n(1-p)$$
$$= \frac{p}{n}\frac{n(n+1)}{2} + n(1-p) = \frac{p(n+1)}{2} + n(1-p).$$

- Average case is very important because it is usually better than the worst case, and scientists would have skipped over many useful algorithms if they only considered the worst-case efficiency.

- Amortized eff.:

→ Worst case can be expensive, but over time if you amortize its price.

$g(n)$ → any nonnegative functions defined on the set of natural numbers.

- O big oh :

$n \in O(n^2)$ $\quad 100n+5 \in O(n^2)$ $\quad \frac{1}{2}n(n-1) \in O(n^2)$

- Ω big omega:

$n^3 \in \Omega(n^2)$ $\quad \frac{1}{2}n(n-1) \in \Omega n^2$, but $100n+5 \notin \Omega(n^2)$

- Θ big theta:

$$t_1(n) + t_2(n) \in O(\max\{g_1(n), g_2(n)\})$$

$$\lim_{n\to\infty} \frac{t(n)}{g(n)} = \begin{cases} 0 & \text{implies that } t(n) \text{ has a smaller order of growth than } g(n), \\ c & \text{implies that } t(n) \text{ has the same order of growth as } g(n), \\ \infty & \text{implies that } t(n) \text{ has a larger order of growth than } g(n).^3 \end{cases}$$

O, Ω & Θ are rarely used for comparing orders of growth between two specific functions

TABLE 2.2 Basic asymptotic efficiency classes

Class	Name	Comments
1	*constant*	Short of best-case efficiencies, very few reasonable examples can be given since an algorithm's running time typically goes to infinity when its input size grows infinitely large.
$\log n$	*logarithmic*	Typically, a result of cutting a problem's size by a constant factor on each iteration of the algorithm (see Section 4.4). Note that a logarithmic algorithm cannot take into account all its input or even a fixed fraction of it: any algorithm that does so will have at least linear running time.
n	*linear*	Algorithms that scan a list of size n (e.g., sequential search) belong to this class.
$n \log n$	*linearithmic*	Many divide-and-conquer algorithms (see Chapter 5), including mergesort and quicksort in the average case, fall into this category.
n^2	*quadratic*	Typically, characterizes efficiency of algorithms with two embedded loops (see the next section). Elementary sorting algorithms and certain operations on $n \times n$ matrices are standard examples.
n^3	*cubic*	Typically, characterizes efficiency of algorithms with three embedded loops (see the next section). Several nontrivial algorithms from linear algebra fall into this class.
2^n	*exponential*	Typical for algorithms that generate all subsets of an n-element set. Often, the term "exponential" is used in a broader sense to include this and larger orders of growth as well.
$n!$	*factorial*	Typical for algorithms that generate all permutations of an n-element set.

ALGORITHM *MaxElement*$(A[0..n-1])$

```
//Determines the value of the largest element in a given array
//Input: An array A[0..n − 1] of real numbers
//Output: The value of the largest element in A
maxval ← A[0]
for i ← 1 to n − 1 do
    if A[i] > maxval
        maxval ← A[i]
return maxval
```

General Plan for Analyzing the Time Efficiency of Nonrecursive Algorithms

1. Decide on a parameter (or parameters) indicating an input's size.
2. Identify the algorithm's basic operation. (As a rule, it is located in the innermost loop.)
3. Check whether the number of times the basic operation is executed depends only on the size of an input. If it also depends on some additional property, the worst-case, average-case, and, if necessary, best-case efficiencies have to be investigated separately.
4. Set up a sum expressing the number of times the algorithm's basic operation is executed.[4]
5. Using standard formulas and rules of sum manipulation, either find a closed-form formula for the count or, at the very least, establish its order of growth.

- Recurrence relations:
- Initial condition:

General Plan for Analyzing the Time Efficiency of Recursive Algorithms

1. Decide on a parameter (or parameters) indicating an input's size.
2. Identify the algorithm's basic operation.
3. Check whether the number of times the basic operation is executed can vary on different inputs of the same size; if it can, the worst-case, average-case, and best-case efficiencies must be investigated separately.
4. Set up a recurrence relation, with an appropriate initial condition, for the number of times the basic operation is executed.
5. Solve the recurrence or, at least, ascertain the order of growth of its solution.

"One should be careful with recursive algorithms because their succinctness may mask their inefficiency."

- Smoothness rule:

General Plan for the Empirical Analysis of Algorithm Time Efficiency

1. Understand the experiment's purpose.
2. Decide on the efficiency metric M to be measured and the measurement unit (an operation count vs. a time unit).
3. Decide on characteristics of the input sample (its range, size, and so on).
4. Prepare a program implementing the algorithm (or algorithms) for the experimentation.
5. Generate a sample of inputs.
6. Run the algorithm (or algorithms) on the sample's inputs and record the data observed.
7. Analyze the data obtained.