Final Exam

15-19 / 8, 10-12 / 1-6 / 13 : 14 /

Spring 2021

#### Student name:

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| 1<br>37 | 2<br>5 | 3<br>12 | 4<br>20 | 5<br>6 | 6<br>5 | 7<br>15 | Total |
|---------|--------|---------|---------|--------|--------|---------|-------|
|         |        |         |         |        |        |         |       |

**1.** An embedded microcontroller program is used to measure temperature with thermistor with the following characteristics:

$$R(t) = 161 \cdot e^{-0.013 * t} [K\Omega]$$

where t is temperature in degrees Fahrenheit [°F]. Thermistor is used in voltage divider configuration with fixed resistor of 75 K $\Omega$  connected to power supply and thermistor connected to the ground. Microcontroller uses a 12 bit AD converter with 2.5V positive reference and ground as negative reference. Signal conditioning circuit uses power supply of 3V. Maximum expected frequency of the signal is 150Hz.

Q1: What is the minimum sampling frequency of the signal?

Q2: What is the minimum voltage of the signal if the expected range of temperatures is 40-80 °F?

Q3: What is the maximum voltage of the signal if the expected range of temperatures is 40-80 °F?

Q4: How many seconds of the signal you can buffer on the microcontroller without optimization? (Check Canvas for the amount of available memory).

Q5: How many seconds of the signal you can buffer on the microcontroller with optimization? (Check Canvas for the amount of available memory).

Q6: What is the quantization step of the AD converter in milivotls [mV]?

Q7: The system transmits data using UART with 8 data bits, 1 start bit, 1 stop bit, and bit rate of 115,200 bps. What is the maximum sampling frequency that allows real-time transmission of samples using UART?

Q8: What is the output of the AD converter when the temperature is 60°F?

Q9: The embedded microcontroller runs at clock speed of 10MHz and spends 240 cycles to process each sample. Total data acquisition time is 0.2 ms and sampling frequency is 40 Hz. In addition, every 1,024 samples the controller is running the FFT analysis which takes <check Canvas> instructions. What is the ratio of average processing time (including data acquisition time) and sampling interval Ts?

Q10:Can system run in real-time?

```
井 7×150= 300HZ
      Q(80)= 16|xe ~0.013(80)
#2
      56.906/56.906+75 X3 = 1.2942 U
 #3
       R(40)= 161e-0013(40)_
     = 95.77/95.72+75 K3 = 1.6820v
#4
    12/8=1.5->2 300Hz x 2Bps = 600 Bps 8000/600=13.3333
#5 12/8=1.5 300x1.5 = 450
                                 8000/450 = 17.7778
       2.5-0=2.5 2.5/212 = .000610352 = 6.1035 E-4V
#6
        · 000610352 V = 0.6104mV .6104mV
         .000,610352 0.6104 mV
      115200 bps 10 bits for 1 set of data 777
t t
        11 520 5
                       14 400 Bps
                       1.25 Bosample
#8 \Omega(60) = [61e^{-0.013(60)} = 73.8034 .000610352
    73.8034/
73.8034+75 \times 3 = 1.4879
  1.4879-0/
0.6104mv = 2437.8
```

#9 
$$\left[\frac{240}{10,000,000}.40\right] + \left[.2ms.40Hz\right] + \frac{\left(\frac{82,000}{1024}\right)}{10,000,000}$$
 ×40  $0.000,000$   $0.000$ 

#10 NO!

0.3717 > .025 -> 1/40

Sono, it cunnot work in real time.

1/1+P(S S = 500 x 2 ti)

**2**. A low-pass filter is implemented using R=4.7 $K\Omega$  and C = 1  $\mu F$  (series of resistor and capacitor, and capacitor is parallel to output).

 $|H(SOO)| = \sqrt{\int [H(Y_{X})_{X}]^{000}} |H(Y_{Y})|^{2} = \sqrt{|H(Y_{Y})_{X}|^{000}} |H(Y_{Y})^{2} = \sqrt{|H(Y_{Y})_{Y}|^{000}} |H(Y_{Y})^{000} = \sqrt{|H$ 

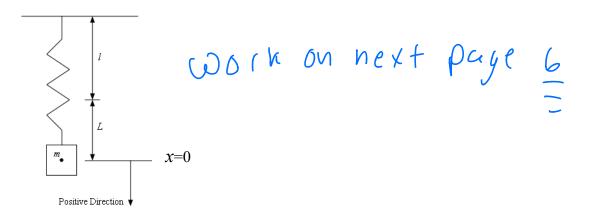
3. Let x[n] = [0.1 0.3 0.24 0.39 0.41 0.3 0.23 -0.2 -0.15 0.2 0.4] and h[n]=[-0.1 0.2 -0.05]

Compute and plot the convolution y[n] = x[n] \* h[n].

See matlas below (also manually did it):

√Q12: What is the value of the sixth sample of the result?

**4.** A 1 kg weight is hung on the end of a vertically suspended spring, thereby stretching the spring  $L = \frac{10}{17}$  [m]. The weight is pulled 1m below its equilibrium position and released from rest at time t=0. The damping coefficient is c = 2. Find the displacement x of the weight from its equilibrium position at time t. Use g=10m/s². All forces, velocities, and displacements in the upward direction will be negative, according to the Figure below.



Q13: What is the value of position x at t=1.6s?

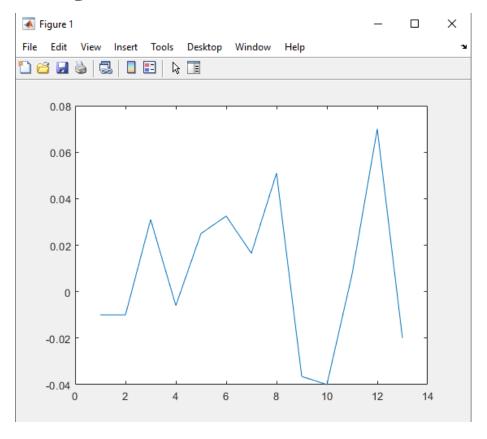
Q14:What is the steady state value of x(t)?

$$\chi(1.6) = 0.2064$$

#17

|      | <i>ن</i><br>ا ، | , 3   | 2<br>. 24 | 3<br>.39 | <i>५</i><br>. ५। | 5<br>,3 | ,23    | -,2   | -,15  | , 2  | , ٤ |
|------|-----------------|-------|-----------|----------|------------------|---------|--------|-------|-------|------|-----|
|      |                 |       |           |          |                  |         |        |       | .015  |      |     |
| . 2  | ٠٥٢             | .06   | .048      | .078     | .082             | 0b      | . 046  | -, 04 | - 03  | . oy | .08 |
| -,05 | -005            | 7.013 | 7.012     | -, O 147 | 7.<br>0205       | -015    | ٠٥١١٥٠ | .01   | .0075 | 701  | 02  |

{-,0100, -,0100, .0310, -,0060, .0250, .0325, .0165, .0510, -,0365, -,0460, .0700, -.02003



# 13/ work

$$K = \frac{m \times g}{L} = \frac{1 \times y \times 10^{m/5}}{(0)_{17}} = 17^{n/m}$$

# Eq:  $m \frac{d^2x}{dt^2} + kx + C \frac{dx}{dt} = 0$ 

$$\int_{0}^{2} \left[ 1 \cdot \ddot{y}(t) + 17x + 2 \dot{y} = 0 \right]$$

$$\int_{0}^{2} \chi(s) - S \chi(t) - 1 - \chi^{1}(0) + 17\chi(s) + 2s \chi(s) - 2\chi(s) - 2\chi(s) = 0$$

$$\int_{0}^{2} \chi(s) - S \chi(t) - 1 - \chi^{1}(0) + 17\chi(s) + 2s \chi(s) - 2\chi(s) - 2\chi(s) = 0$$

$$\chi(s) \left[ S^{2} + 2s + 17 \right] - S - 2 = 0$$

$$\chi(s) \left[ S^{2} + 2s + 17 \right] - S - 2 = 0$$

$$\chi(s) = \frac{S+2}{S^{2} + 2s + 17} \qquad \int_{0}^{1} \left[ \frac{S+2}{S^{2} + 2s + 17} \right] \int_{0}^{1} g_{s}t \sin^{2}t \cos^{2}t \cos^{2$$

XL1.6)= 0.2064

**5.** A and B are vectors with coefficients of a 5-point averaging filter in C program.

 $\int \frac{2 \, \Omega_0 + .2 \, \omega_0(n-1) + .2 \, \omega_0(n-2) + .2 \, \omega_0(n-3) + .2 \, \omega_0(n-3) + .2 \, \omega_0(n-4)}{\text{Q15: What is the value of A[0]?}}$  $\sqrt{Q16}$ : What is the value of B[3]?

- 6. Signal is sampled at Fs=500 Hz and discrete Fourier transform is performed by using N=2048 point window.

 $\sqrt{\text{Q17: What is the frequency resolution of the result - df?}}$ 

500/2048=0.2441

final.mat from Canvas using the link in the problem description. Signal x is 7. Load sampled at Fs=200 Hz. Analyze signal using Matlab function fft and NFFT=1024 point window and a 1024 point hanning window. Plot the spectrum and publish the file

 $\sqrt{}$  Q18: How many discrete frequency components do you have in spectrum of the real signal x? Please explain your answer!?

3 - there we 3 spikes on the graph (see selow) spectrum of x? Please use 4 decimal digits in your answer.

5, 8594 (5.86938)

# Header

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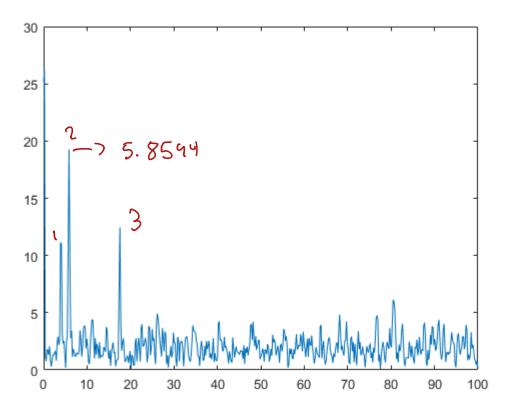
Nolan Anderson CPE 381 Final Exam Final.m Plots the spectrum using a hanning function and input .mat file.

### Load and initialize

```
load('fintest.mat');
Fs = 200; %sampling frequency
NFFT = 1024; %NFFT
H = 1024; %Hanning window size
Window = transpose(hann(H));
```

## **Calculate and Plot**

```
x = x .* Window;
out = fft(x, NFFT);
f = Fs*(0:(NFFT/2))/NFFT; % Half samp freq.
sp2 = abs(out / NFFT);
sp1 = sp2(1:NFFT/2+1);
sp1(2:end-1) = 2*sp1(2:end-1);
plot(f,sp1)
```



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