

CPE 381: Fundamentals of Signals and Systems for Computer Engineers

Homework #3

Due: Monday, March 8 at 9:35 am

Please upload PDF files of the assignment to Canvas

Student name:

Nolan Anderson

1 20	2 20	3 20	4 20	5 20	Total

1. (20 points) What is the inverse Laplace transform of the function

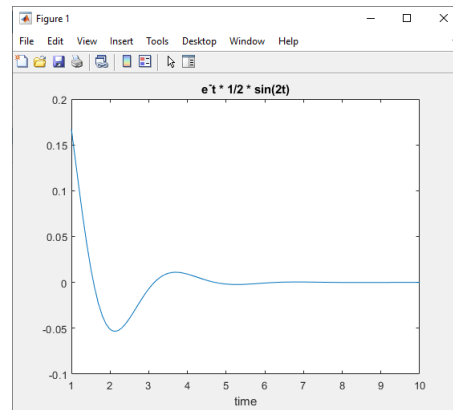
$$X(s) = \frac{1}{(s+1)^2 + 4}$$

$$\frac{1}{s^n} = \frac{t^{n-1}}{(n-1)!} \rightarrow \frac{t^{2-1}}{(2-1)!} = \frac{t}{1!}$$

$$e^{-at} u(t) = \frac{1}{s+a} \rightarrow e^{-4t} u(t)$$

Plot the function in time domain.

$$te^{-t} u(t) = \frac{1}{(s+1)^2} \rightarrow e^{-t} \frac{1}{2} \sin(2t)$$



2. (20 points) A system with input $x(t)$ and output $y(t)$ is defined by the following differential equation:

$$\frac{d^2 y(t)}{dt^2} + 3 \frac{dy(t)}{dt} + 2y(t) = x(t)$$

Find the impulse response $h(t)$ and the unit-step response $s(t)$. $n(t) \rightarrow S(t)$

$$\left. \begin{aligned} Y(s) &= \mathcal{L}[y(t)] \\ X(s) &= \mathcal{L}[x(t)] \end{aligned} \right\} Y(s)[s^2 + 3s + 2] = X(s); \quad Y(s) = H(s) = \frac{1}{s^2 + 3s + 2} = \frac{1}{(s+1)(s+2)} = \frac{A}{s+1} + \frac{B}{s+2}$$

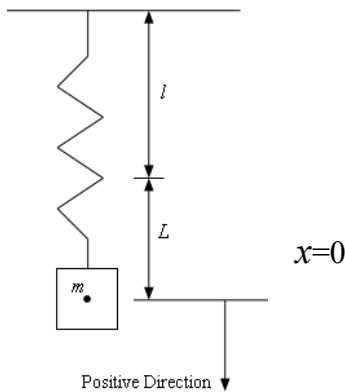
$$A = H(s)(s+1) \Big|_{s=-1} = \frac{1}{-1+2} = 1 \quad B = H(s)(s+2) \Big|_{s=-2} = \frac{1}{-2+1} = -1 \rightarrow h(t) = [e^{-t} - e^{-2t}] \cdot u(t)$$

$$S(s) = \frac{H(s)}{s} = \frac{1}{s \cdot (s+1)(s+2)} = \frac{A}{s} + \frac{B}{s+1} + \frac{C}{s+2}$$

$$S(t) = 0.5 \cdot u(t) - e^{-t} \cdot u(t) + 0.5e^{-2t} \cdot u(t)$$

3. (20 points) A 1 kg weight is hung on the end of a vertically suspended spring, thereby stretching the spring $L = 20$ cm. The weight is raised 10 cm above its equilibrium position and released from rest at time $t=0$. Find the displacement x of the weight from its equilibrium position at time $t=2.5$ s. Use $g=10\text{m/s}^2$.

All forces, velocities, and displacements in the upward direction will be negative, according to the Figure below.



$$F = kL, k = \frac{F}{L} = \frac{mg}{L} = \frac{1 \text{ [kg]} \cdot 10 \text{ [m/s}^2\text{]}}{0.2 \text{ [m]}}$$

$$k = 50 \text{ kg/s}^2$$

$$m\ddot{x} + kx = 0$$

$$-0.10 \text{ m } x(0) = 0$$

$$(s^2 + 50) X(s) = -0.10$$

$$X(s) = -0.10 / (s^2 + 50)$$

$$x(t) = \mathcal{L}^{-1}(X(s)) = -0.01 \sin(7.07t)$$

$$x(2.5) = -0.01 \sin(7.07 \times 2.5)$$

$$x(2.5) = -0.043 \text{ m}$$

4. (20 points) An unstable system can be stabilized by using negative feedback with gain K in the feedback loop. For the given unstable system with pole in the right-hand s -plane:

$$\mathcal{L}^{-1} \left\{ \frac{1}{-4s+3} \right\} = -\frac{1}{4} e^{3/4 t} \rightarrow h(t) \quad F(s) = \frac{1}{2s-3}$$

what should be the value of the gain K (K is integer greater than zero) with $F(s)$ in the forward loop that will make the system BIBO stable.

Draw block diagram of the system, write overall transfer function of the system $H(s)$, and impulse response $h(t)$.

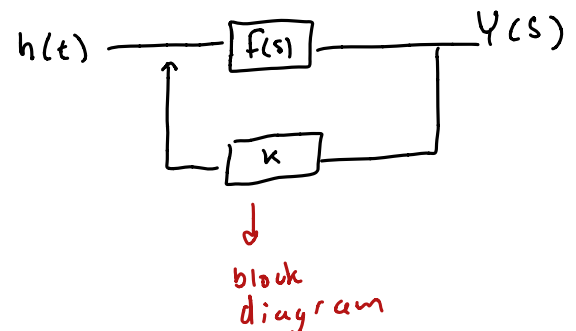
$$F(s) = \frac{1}{2s-3} \rightarrow \mathcal{L}^{-1}\{F(s)\} = \frac{1}{2} e^{3/2 t}$$

$$Y(s) = \frac{F(s)}{1 + K F(s)} = \frac{1}{2s-3} \cdot \frac{1}{1 + K \left(\frac{1}{2s-3} \right)}$$

$$1 + K: 3 \angle \times \infty$$

$$K = 4 \cdot \frac{1}{2s-3} = \frac{4}{2s-3}$$

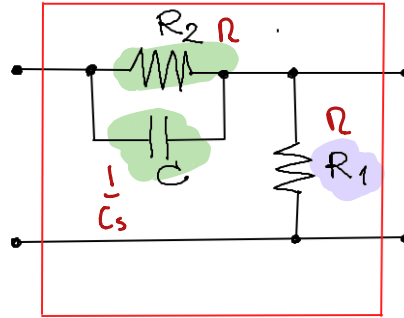
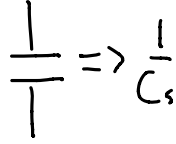
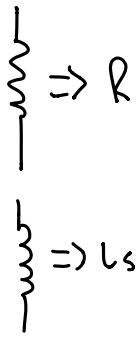
$$\mathcal{L}^{-1} \left\{ \frac{4}{2s-3} \right\} = 2 e^{3/2 t} = h(t)$$



$$H(s) = \frac{Y(s)}{X(s)}$$

$R_1 \rightarrow \text{numerator}$
 R_2 ; $C \rightarrow \text{denom.}$

5. a) (4 points) What is the transfer function of the following circuit:



$$\frac{R}{R + R \parallel \frac{1}{Cs}} = \frac{R}{R + \frac{R}{RCs + 1}}$$

$$= \frac{RCs + 1}{RCs + 2} = \frac{s + 1/RC}{s + 2/RC}$$

$$H(s) = \frac{s + 1/RC}{s + 2/RC}$$

b) (6 points) What is the transfer function of the following circuit?

Hints:

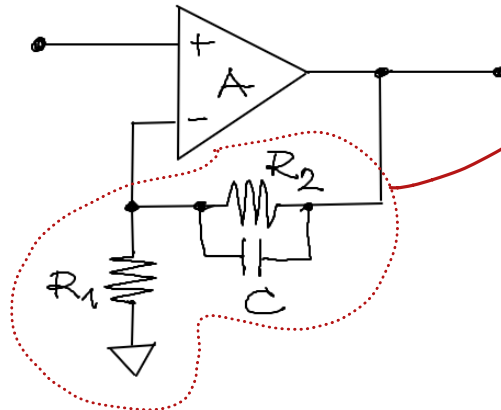
- you can use solutions of problems #4 and #5a
- to simplify the result you can assume that $A \rightarrow \infty$

$$H(s) = \frac{s + 1/RC}{s + 2/RC}$$

$$f(s) = A, \quad G(s) = \frac{s + 1/RC}{s + 2/RC}$$

$$H(s) = \frac{A}{1 + A G(s)}$$

$$A \rightarrow \infty \quad H(s) = \frac{s + 2/RC}{s + 1/RC}$$



c) (10 points) Find and plot the unit-step response $s(t)$ of the system.

Assume $R_1 = 1\Omega$, $R_2 = 2\Omega$, $C = 1F$.

$$S(s) = \frac{1}{s} \cdot \frac{s + 2/RC}{s + 1/RC} = \frac{A}{s} + \frac{B}{s + 1/RC} = \frac{2}{s} - \frac{1}{s + 1/RC}$$

$$S(t) = (2 - e^{-t/RC}) \cdot u(t)$$

