Simulations of collapsed polymers as a simple model of bacterial nucleoids

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We aim at using computer simulations in order to test models which can predict the experimental measurements [3, 15, 23] that show insight about the physical organization of the DNA polymer and the interaction with Nucleoid associated proteins (NAPs).

The DNA in $E.\ coli$ is a polymer with arc-length of 1.57mm and diameter of 2.37nm which gets continuously replicated over a period of 40 minutes. The Nucleoid is a protein-DNA complex where the active processes which are related to the DNA functionality such as transcription and replication happen inside the bacterial cell. Thus the nucleoid is made of DNA, RNA, and various functional proteins such as transcriptiona factors, nucloid associated proteins, RNA and DNA polymerases which bind, associate and interact each other in order to make dynamic and static structures.

It is known that the nucleoid is collapsed in a volume which is comparable to 1/6 of the cell [], this property not only makes the polymer much smaller than the volume between the cell walls but also it results in a stronger viscoelastic behaviour [24]. Two possible mechanism have been proposed for the collapse of the nucloid: confinement due to the cell walls [] and depletion due to the interaction with the cytoplasm []. The first hypotesis is in contradiction with the fact that the nucleoid occupies only a small region of the bacterial cell, while the second is in agreement with recent experiments which [20] have shown that purified nucleoids can collapses due to the depletion with a crowding agent (PEG); the concentration of proteins in the cytoplasm is comparable to the concentration of PEG which collapse the DNA in purified nucleoid just at the transition between coiled and collapsed state.

An important role in the DNA organization in the nucleoid is played by the NAPs, proteins which bind and structure the DNA. The role of NAPs is still a research subject and it has been shown that most of them have also a fundamental role in gene expression regulation as hubs of the transctiptional network of $E.\ coli$. Between all of them H-NS is particularly interesting because it make crosslinks between different segments of the DNA bringing part of the distant part of the chromosome in the genome close together in space and also because it can oligomerize thus making complexes which bind strongly to DNA. Recent experiments have shown that H-NS is the only NAP which makes between two and four foci, which are globules where the protein with the bound DNA aggregates, into living cells.

In this work we will investigate a model for the DNA in the nucleoid as a polymer which cooks two ingredients: a weak glue that describe the depletion of the molecular crowding to the nucleoid and a strong localized interaction which describes the binding of H-NS to the binding sites. We aim at exploring the different configuration possibilities of the nucleoid following the varying of the those different kind of interctions.

1 The model

The DNA is a polymer with Khun length of $\sim 105 \text{nm}(308 \text{bp})$ and diameter of 2.37nm. In E.~coli DNA is a single circular polymer of length $\sim 1.577 \text{mm}(4639 \text{kbp})$.

We simulate the DNA polymer as a bead spring model. In our model the polymer segments are represented by beads in three dimensional space. The number of beads which we use to represent the

polymer is arbitrary, we call this parameter N. We define four fundamental forces on the beads in order to obtain a macroscopical description which reproduces the phenomena we want to investigate about the nucleoid. Each of these forces define a term in the interaction energy.

- 1. The chain links force: in the DNA molecule monomers are covalently bounded together to form a polymeric chain. In our model we represent this connectivity by a link network which connect the beads which represent adjacent segments of the chain. The distance in three dimensional space between two bead which are linked correspond to the length of the link. We assign an infinite energy to every configuration which carry a link longer than a characteristic length λ .
- 2. The hard core repulsion: the DNA molecule self-interact through electromagnetic forces. In ionic solutions this correspond to a short ranged repulsion between different part of the polymer. Due to this force different segment of DNA does not overlap with each other. In our model we set a minimum distance σ between every bead and we assign an infinite energy to all configurations which carry two beads at a smaller distance.
- 3. Cytoplasm protein crowding: the concentration of proteins in the cytoplasm is enough to collapse the DNA into a globular state [20]. The depletion of the macromolecules in the cytoplasm due to the presence of the long DNA macromolecule results in an effective attraction between couples of DNA double Helix segments, the range of this force is comparable to the diameter of a typical crowding protein. In our model we represent this force as a weak attractive glue between every bead. The configuration energy will be decremented by ϵ_u for every couple of beads which are at a distance smaller than a the characteristic length of attraction α , this gives more stability to the configuration.
- 4. **DNA** binding proteins: *H-NS* makes crosslinks between different segments of the *DNA*, it can oligomerize thus it makes strong bounded complexes. This mechanism mediates for an effective attraction between the binding sites of *H-NS*. In our model we represent this force as a strong attractive localized interaction between a selected set of beads which represent the ones which carry a *H-NS* binding sites. The configuration energy will be decremented by ϵ_l ($\epsilon_l > \epsilon_u$) for every couple of binding site carrying beads which are at a distance smaller than the characteristic length of attraction α .

The interaction potential can be described by a function of the distance between interacting pairs of beads U(r), which is reported in Fig. 1.

In this model we disregard the possible liquid crystalline ordering of interacting DNA chains [19].

2 Monte Carlo algorithm

We use an off lattice Monte Carlo algorithm with Metropolis rejection rule in order to simulate the polymer configuration in the Gibbs ensamble. In every step the algorithm moves a random bead of the chain by a vector chosen with a uniform spherical distribution of radius Δr , then acceptance rules are applyed according to the defined fundamental forces. A resume of the acceptance rules is give in Fig. 2.

Our algorithm was inspired by a work on the behaviour of polymers under confinement [7].

By considering only the energy interactions, it is not possible to guarantee topological invariance of ring polymers. A supplementary topological interaction acceptance rule have been implemented in order to overcome this limitation.

2.1 Topological interaction

In order to prevent the dynamic to break topological barriers, the simulation need to avoid any monomer movement which would cross two links of the polymer. We do so by testing the interseption

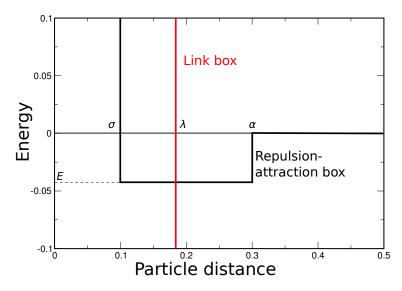


Figure 1: The interaction potential: The link potential (red line) imposes beads which are connected in the chain to be close to each other; the interaction potential (black line) represent the energy in function of the distance between different interactions beads U(r) which is the sum of an hard-core repulsion and an attraction box.

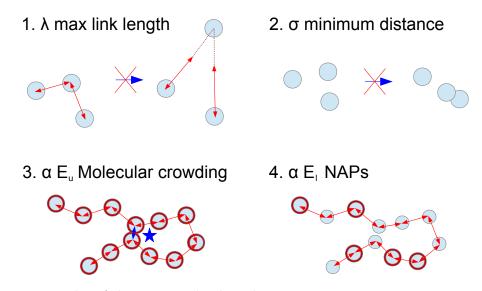


Figure 2: Acceptance rules of the montecarlo algorithm.

- 1. Maximum link length: every new configuration which have a link longer than λ is rejected.
- 2. Hard core repulsion: every new configuration in which there is a couple of beads with distance smaller than σ is rejected.
- 3. Uniform attraction: for every new configuration, the difference in energy due to the molecular crowding is evaluated. The Metropolis acceptance rule is applied in order to reject low probability configurations.
- 4. Localized attraction: for every new configuration, the difference in energy due to the localized binding-protein mediated attraction is evaluated. The Metropolis acceptance rule is applied in order to reject low probability configurations.

between each link of the polymer seen as segment in three dimensional space and the two triangles spanned by the movement of the links connected to the monomer which is to be moved (see fig.3). We test this interseption using common ray-tracing algorithms [18] and in the positive case we reject the move.

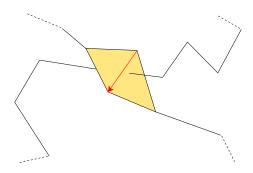


Figure 3: Rejected topological move, the yellow area represent the two triangles spanned by a MC move (red arrow).

3 Thermodinamic of the single polymer

Our approach is to simulate the DNA in the nucleoid as a bead spring model. In this model the number of beads N is arbitrary and fixes the amount of details we take into account: by taking a smaller number we save computational resources but we are in fact re-summing the degree of freedom of the system and discarding all the microscopical details for contour lengths less then 2L/N (where L is the length of the polymer); on the other end it seems reasonable to discard those details since a gene in E. coli is normally 1kb long and we don't really have enough information to go at resolution lower than that.

We want to keep the freedom of choosing the appropriate N. The other parameters $(\lambda, \sigma, \alpha, \epsilon_u, \epsilon_u)$ and ϵ_l need to be choosen as a function of N in order to keep the results consistents at different values. The parameters need to be set and compared to biophysical quantities of the nucleoid so we elaborated a *protocol* explained in the following sections in order to be able to set them.

3.1 Square distance as a function of arc-length

A statistical configuration of a polymer in our model is completely described by N vectors $\{\vec{r}_i\}_{i\in 1..N}$ which identify for each bead its position. Due to the translational simmetry for the center of mass, the rotational symmetry in three dimensional space, and the translational simmetry on the chain backbone (in the circular polymer case) it is more convenient to take the mean square distance R between beads as a function of their arc-length distance s, $\langle R^2(s) \rangle$, as the main observable we measure in our simulations.

Through $\langle R^2(s) \rangle$ it is possible to measure the size of the polymer and also to extimate the probability of loop formation as a function of the arc-length; this observable is thus connected to the results of the biological experiments of Fluorescence in situ hybridization (FISH) and Chromosome conformation capture (Hi-C).

3.2 Scaling of the link length parameter λ , the ideal polymer

In the case where we neglect all the interaction forces between beads (the hard core repulsion, the molecular crowding and the localized interactions) but we keep a linear polymer link connectivity we obtain a model which describes the ideal polymer. In absence of other energetic or topological constraints, the separation in space for two beads in an ideal polymer can be calculated easily in the following way:

$$\vec{R}(s) = \vec{b}_1 + \vec{b}_2 + \dots + \vec{b}_s = \sum_{i=1}^{s} \vec{b}_i \quad \text{where} \quad \vec{b}_i = \vec{r}_{i+1} - \vec{r}_i.$$
 (1)

The square distance as a function of the arc-distance is:

$$\langle R^2(s) \rangle = \langle \vec{R}(s) \cdot \vec{R}(s) \rangle = \langle \sum_{i=1}^s \vec{b}_i \cdot \sum_{j=1}^s \vec{b}_j \rangle = \langle |\vec{b}_i| |\vec{b}_j| \cos \theta_{ij} \rangle = \langle b^2 \rangle s. \tag{2}$$

and in our specific case, where \vec{b}_i are random vector in the sphere of radius λ :

$$\langle b^2 \rangle = \frac{3}{5} \lambda^2, \quad \text{and} \quad \langle R^2(s) \rangle = \frac{3}{5} \lambda^2 s.$$
 (3)

This latter formula show that for the ideal polymer the scaling of the square distance as a function of the arc-length is predictable for our model. We can use this prediction to define a practical unit of length l_0 by setting, for every N, the mean end-to-end distance in units of l_0 to unity:

$$\langle R^2(N) \rangle / l_0^2 \equiv 1; \tag{4}$$

which implies the first rule of parameter normalization:

$$\hat{\lambda}^2 \equiv \left(\frac{5}{3}\frac{1}{N}\right). \tag{5}$$

This latter formula fixes the scaling of the link length λ in function of the arbitrary parameter N. In this and in the following formulae we use an hat (as in $\hat{\lambda}$) on top of length-type variables in order to express their numerical value in units of l_0 . In our model the link length $\hat{\lambda}$ does not depend on any other parameters than N.

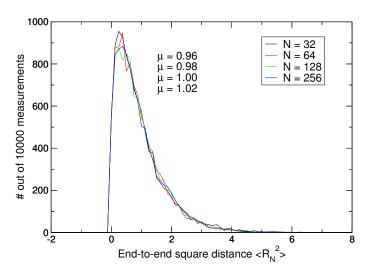


Figure 4: $\langle \hat{R}^2(N) \rangle$ with N=32,64,128,256 for the ideal polymer. The distribution is the same regarding the value of the resolution N after proper normalization of parameter λ using formula 5. The unit length is equal to l_0 thus the distibutions have unit mean values.

3.3 Free energy of the ideal polymer

The Helmholtz free energy $F(\vec{r})$ associated with all chain conformation starting from an origin $(\vec{r} = 0)$ and ending at the point \vec{r} is simply related to the number of distinct polymers with N beads $\mathbb{Z}_N(\vec{r})$ going from (0) to (\vec{r}) :

$$F(\vec{r}) = -k_b T \ln \left[\mathbb{Z}_N(\vec{r}) \right]. \tag{6}$$

The probability distribution ρ of \vec{r} defined by

$$p_N(\vec{r}) = \frac{\mathbb{Z}_N(\vec{r})}{\int_r \mathbb{Z}_N(\vec{r})},\tag{7}$$

for the ideal polymer is given by the convolution of the distributions of consecutive \vec{b}_i as defined in Eq. 1. For $s \gg 1$ due to the central limit theorem we can extimate that

$$p_N(\vec{r}) = \left(\frac{5\pi}{2\lambda^2 N}\right)^{3/2} \exp\left(-\frac{5}{2}\frac{\vec{r}^2}{\lambda^2 N}\right) = \left(\frac{3\pi}{2{l_0}^2}\right)^{3/2} \exp\left(-\frac{3}{2}\frac{\vec{r}^2}{{l_0}^2}\right). \tag{8}$$

The above end-to-end distribution combined with Eq. 6 gives an important formula for the entropy of the ideal polymer at fixed elongation:

$$F_{ideal}(\vec{r}) = F(0) + \frac{3}{2l_0^2} k_b T \langle \vec{r}^2 \rangle, \tag{9}$$

By deriving we can write the equation of state for the tension in function of elongation for the ideal polymer:

 $\tau_j = -\frac{\partial F}{\partial r_i} = -3\frac{k_b T}{l_0} \cdot \frac{r_j}{l_0} \tag{10}$

which resembles the spring equation. This equation is valid only for the cases in which the hard core repulsion and the attractive interactions are negligible. It has been tested in microrehological experiments by measuring the mechanical response of DNA or other polymers attached to dielectric beads under deformation applyed using optical traps and it has been found as a good first order approximation. Under strong stretching $(\tau_j \gg k_b T/l_0)$ the Gaussian distribution (eq. 8) is not a valid model for the polymer due to the finite exensibility of the chain and a alternative potentials should be used instead (cite Siggia).

This equation have been also recently used as a null model (cite Wiggins) for the bacterial necleoid, it's derivation is obtained by neglecting interactions of the polymer with himself and for this reason the results of the experiment didn't agree with this simple theory. Although the effect of finite extensibility can be important in the microscopic DNA processes we consider this effect not relevant for the equilibrium state of the Nucleoid.

We can check the consistency of the free energy and the equation of state by calculating the extensibility, which should be equal to the fluctuations of r_i :

$$\langle \vec{r}^2 \rangle = k_b T \sum_j \frac{\partial r_j}{\partial \tau_j} = l_0^2.$$
 (11)

3.4 Coil-globule transition

In the following three paragraph we try to understand the behavior of our model by describing the configurations that the polymer assumes in presence of the hard core repulsion (electromagnetic) and the uniform attraction (molecular crowding of the cytoplasm). Note that we still neglect *only* the localized interaction (crosslinking proteins).

In presence of repulsive and attractive interactions some aspect of the behaviour of the polymer are well known and intuitive. If the interactions are repulsive only ($\epsilon_u = 0$) the polymer is in the coil phase: the volume increase, and the scaling of $R^2(s)$ differ from the linear dependence on s (see Eq. 3) in the ideal polymer case. If, in the opposite case, we take configurations at very strong attraction energy ($\epsilon_u \to \infty$) the effect of attraction overwhelm the repusion due to hard core interactions and the polymer collapse in a globular compact state. Between the two extreme conditions the polymer undergoes a phase transition (represented in Fig. 5).

In order to qualitatively describe the transition from coil to globular state we can introduce the effect of two-beads interactions in the free energy as a virial coefficient expansion:

$$F_{coil} = F_{ideal} + k_b T v \rho^2 V \tag{12}$$

where $\rho \equiv N/V$ is the number density of the polymer beads and v is the effective volume of interaction of a bead of the polymer to other beads. This procedure will lead to what is known as the Flory-Huggins theory of the interacting polymer.

The above free energy can be rewritten explicitly in volume and number of beads by setting with a mean field approach V as a function of the size of the fluctuations of the end-to-end distance:

$$F_{coil} = F(0) + \frac{5}{2} \frac{k_b T}{\lambda^2 N} V^{2/3} + k_b T N \left(\frac{N-1}{2} \frac{v}{V} \right) \quad \text{with} \quad \langle \hat{R}^2 \rangle \approx \hat{V}^{2/3}; \tag{13}$$

The calculation of the effective volume of interaction v shows the different behaviour of the system, with respect to the ideal polymer case, as a function of the ratio between the interaction energy and the temperature ϵ_u/k_bT . Since the interaction energy $U_u(r)$ (represented in Fig. 1) is a function of only the mutual distance between two beads in the model, we can obtain the effective volume of interaction v by integrating the Mayer f-function defined as $f(r) = \exp[-U_u(r)/k_bT] - 1$ over the distance between two beads:

$$v \equiv -4\pi \int_0^\infty f(r)r^2 dr \approx 4\pi \int_0^\sigma r^2 dr - \frac{4\pi}{k_b T} \int_\sigma^\alpha \epsilon_u r^2 dr \approx b - \frac{a}{k_b T},\tag{14}$$

where

$$b = \frac{4}{3}\pi\sigma^3 \quad \text{and} \quad a = \frac{4}{3}\pi\epsilon_u(\alpha^3 - \sigma^3). \tag{15}$$

From this formulation it is possible to extract the critical energy of the coil-globule transition. A null effective volume is obtained for $a = (k_b T)b$:

$$\hat{\epsilon}_u \approx \frac{\sigma^3}{\alpha^3 - \sigma^3} \equiv \hat{\Theta},\tag{16}$$

where $\hat{\epsilon}_u$ is the numerical value of ϵ_u in units of k_bT . This condition defines a critical energy Θ at which the polymer undergoes transition: if it is satisfied ($\epsilon_u = \Theta$) we obtain $F_{flory} = F_{ideal}$ and the polymer behaves as a Gaussian chain (i.e. effectively zero interactions). In the condition where $a < (k_bT)b$ the effective volume is positive which means that the hard core repulsive forces dominates over the attractive forces, while opposite conditions, where $a > (k_bT)b$ the effective volume becomes negative and the attractive forces are strong enough to lead to a polymer collapse.

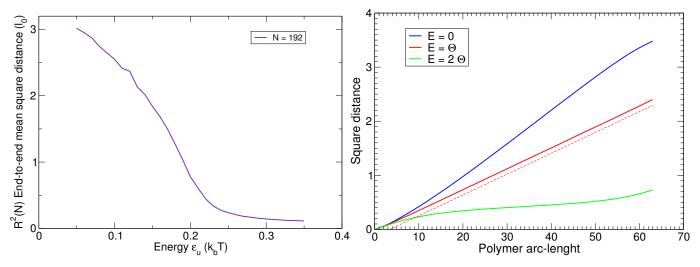


Figure 5: Coil-globule transition: The left graph shows that the size of the polymer which is in function of the fluctuations of the end-to-end distance $\langle \vec{r}^2 \rangle$ undergoes a transition from a coiled state to a globular state as a function of the interaction energy ϵ_u . The right picture shows the behaviour of the mean square distance as a function of arc-length distance at different values of interaction energy E, for chain length (N=64). The relation is linear at the Θ energy in evident agreement with the mean field implication that $F_{flory} = F_{ideal}$ at $\epsilon_u = \Theta$. Coil and globular behaviours are found for respectively lower and higher interaction energies. In the limit-case of E=0 the polymer is a coil fractal with measured exponent of $R \propto N^{0.598}$ in remarcable agreement with Flory-Huggins theory predictions (Eq. 18). The two plots have been obtained using as parameters $\hat{\lambda} = 0.19$, $\hat{\sigma} = 0.1$, $\hat{\alpha} = 0.3$, parameters with hat are in units of l_0 .

In order to understand the coiled state we can calculate the equation of state of the interacting polymer:

$$P = -\frac{\partial F}{\partial V} = \left(-\frac{5}{3\lambda^2 N}V^{2/3} + \frac{N(N-1)}{2}\frac{v}{V}\right) \cdot \frac{k_b T}{V}.$$
 (17)

Under those conditions, this equation sets the mean size of the coiled polymer, assuming v positive, P = 0 and taking the leading term in N we obtain:

$$V = \left(\frac{3}{10}v\lambda^2\right)^{3/5} N^{9/5}$$
 or $R \propto N^{3/5}$ (18)

which sets the scaling of the size of the coiled polymer as a function of the polymer length in remarcable agreement with simulation results (see Fig. 5).

In our model the length of the Nucleoid is a fixed parameter, so we are not interested in the scaling of the size with length but instead in renormalizing the paramiters so that the size remain fixed despite of the number of beads N we use to represent the polymer. The physical size V in units of l_0^3 can be rewritten as:

$$\frac{V}{l_0^3} = \left(\frac{1}{2l_0^3}vN^2\right)^{3/5}. (19)$$

We impose this value to be constant for different N, this sets the scaling of v as a proportional to a effective volume parameter $\nu \equiv vN(N-1) \approx vN^2$ which is carachteristic of the physical system of polymer and solvent and not of the details of the simulation. Since this physical parameters can be written by the following formula:

$$\nu = \frac{4}{3}\pi N(N-1)(\Theta - \epsilon_u)(\alpha - \sigma). \tag{20}$$

the scaling of the simulation parameters σ , α and ϵ_u are still not univocally determinated.

A definitive explanation of the scaling behaviour can be given only by making an argument about the size of the polymer in the globular phase: for very large attractive energies or for large pressures the polymer will collapse on his excluded volume, and become incompressible. Since the total excluded volume in the simulations is proportional to the number and the size of the beads $N\sigma^3$ the excluded volume parameter σ^3 should scale as the inverse of N in order to keep the size of the globule constant and indipendent on the number of beads. The attraction volume parameter α^3 should behave the same in order to keep Θ constant. From equation 20 then we can interpret the scaling of the interaction energy ϵ_u . This argument lead to the second, third and fourth rule of parameter normalization:

$$\frac{4}{3}\pi\sigma^3 = \Sigma/N$$
 and $\frac{4}{3}\pi\alpha^3 = A/N$ and $\epsilon_u - \Theta \equiv \Delta\epsilon_u = \Delta E_u/(N-1)$. (21)

The rules of parameter normalization set the hard core repulsion volume σ^3 and the volume of interaction α^3 proportional to physical volumes which can be considered global observable characteristic of the specific polymer being simulated (Σ and A). In the same way the difference between attraction energy per beads and the theta energy $\epsilon_u - \Theta$ is proportional to a physical internal energy ΔE_u which is positive for collapsed polimers and negative for coiled ones. Using this notation, the effective volume parameter can be written as $\nu = -\Delta E (\Sigma - A)$.

The simulation parameters σ^3 , α^3 and $\Delta \epsilon_u$ are inverse proportinal on the number of beads N; those parameters can thus be respectively interpreted in the most intuitive way as excluded volume, interaction volume and internal energy per unit bead (or link). The total excluded volume Σ , the total interaction volume A and the total internal energy ΔE_u are thus by definition extensive variables of the system.

Also, those rules of parameter normalization show also a limitation in our simulations: the shape of our interaction potential fixes ϵ_u to be defined positive, the scaling law for the difference between this parameter and the critical energy Θ thus fixes a lower limit to the simulable internal energy which depends on the resolution N fixed by the following indetermination relation:

$$\Delta E_u \cdot \Delta s > -\Theta L,\tag{22}$$

where $\Delta s \equiv L(N-1)^{-1}$ is the link arc-length and is inverse proportional to the degree of discretization, L is the polymer length. The practical meaning of this realation is that in order to simulate

configurations of coiled polymers with large negative internal (repulsive) interaction $-\Delta E_u$, we will be forced to increase the number of beads N (details) accordingly.

The implementation of the fourth rules of parameter normalization (summarized in table 1) is an instrument which let us to remove the dependence of the free energy from the number of beads N. As a result we have a theory which gives us consistent results for simulations runned at different N.

#	(1)	(2)	(3)	(4)
1^{st}	λ	l_0	$\lambda = l_0 \sqrt{\frac{5}{3} \frac{1}{N}}$	Mean end-to-end distance at Θ transition
2^{nd}	σ	\sum	$\sigma^3 = \frac{3}{4\pi} \Sigma / N$	Hard core repulsion volume
3^{rd}	α	A	$\alpha^3 = \frac{3}{4\pi}A/N$	Interaction volume
4^{th}	$\Delta \epsilon_u$	ΔE_u	$\Delta \epsilon_u = \Delta E_u / (N - 1)$	Total internal energy

Table 1: Rules of parameter normalization: (1) Simulation parameter, (2) Physical observable, (3) Scaling, (4) Interpretation

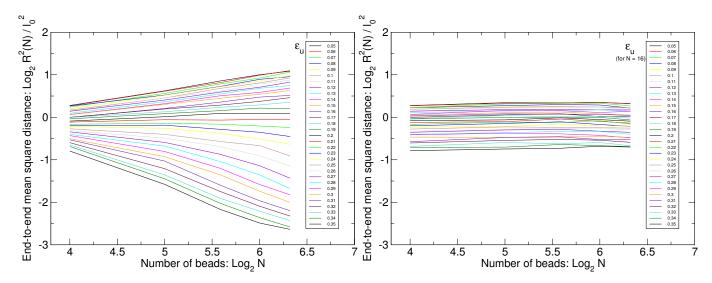


Figure 6: Parameter normalization: end-to-end mean square distance as a function of the number of beads after application of the first three rules of parameter normalization (left graph) and after application of all four rules of parameter normalization (right graph). The graphs are the result of simulations using our algorithm and are made for different interaction energy parameter ϵ_u for a range which span the coilglobule transition. For a summary of the rules see table 1. The left graph is necessary in order to find the critical energy (straight line for $\epsilon_u = 0.21$) while the right graph shows that after proper normalization of the parameters the number of beads is a free parameter N of the simulation which doesn't influence in a significant way the physical observable of the end-to-end square distance as a function of ϵ_u .

Using only the global observables $(V, A, \Sigma, \Delta E_u, T)$ we can obtain the renormalized Flory free energy for the coiled state:

$$F_{coil} = F(0) + \frac{3}{2l_0^2} k_b T V^{2/3} - k_b T \frac{\Delta E_u}{k_b T} \frac{A - \Sigma}{V},$$
(23)

with equation of state:

$$P = \left(\frac{V^{2/3}}{l_0^2} + \frac{\Delta E_u}{k_b T} \frac{A - \Sigma}{V}\right) \cdot \frac{k_b T}{V}, \quad \text{and} \quad V_{coil} = \left(l_0^2 \frac{-\Delta E_u}{k_b T}\right)^{3/5} (A - \Sigma)^{3/5} \quad \text{unconfined.} \quad (24)$$

A peculiar property of this last relation is the monotonical growth of the volume as a function of the effective renormalized interaction energy $-\Delta E$. One could think from this relation that the fluctuation of the coil end-to-end distance can grows indefinely in function of this parameter, this is not true since relation (22) fixes an upper bound for this parameter for any finite number of statistical

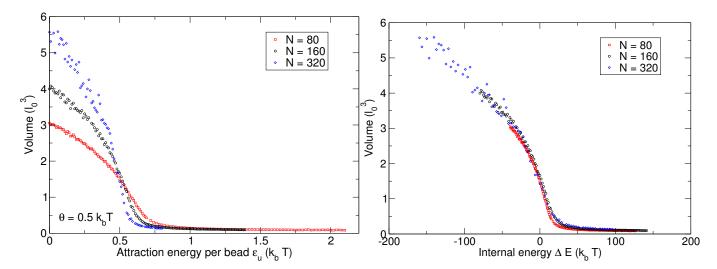


Figure 7: Parameter normalization: collapse diagram (Volume as a function of interaction energy) for the same polymer ($\Sigma = 0.1 l_0^3$ and $A = 6\Sigma$) with different discretization parameter N. The left graph is after application of the first three rules of parameter normalization. The right graph is after application of the fourth rule. From the left to the right graph the following two operations have been applied: $x \to x - 0.5$, $x \to (N-1)x$.

elements N and in turn for any finite N the polymer is confined in a finite volume V of the space. In turn this is a realistic description of a self-interacting *single* polymer, since the swelling is limited not only by the ultraviolet natural cutoff given by the Kuhn length but also by the length of the polymer. In comparison to previous works [], the model doesn't aim at a description of the "thermodynamic limit" $N \to \infty$, in which the polymer can be described by the self avoiding walk model [9].

The free energy in the virial expansion elaborated by Flory lets us predict the size of the coiled phase, the existence of a critical energy of transition and the formula of the order parameter. Thus it helped us to write rules of parameter normalization which let use keep the discretization of the problem N as a free parameter. On the other end this approach alone fails to describe the globular phase and the transition from ideal to globular state.

3.5 The globular phase

In the globular phase ($\epsilon_u > \Theta$, $\Delta E_u > 0$, see equation 16) the effective volume becomes negative. In this conditions the polymer start to collapse and the second order virial expansion is not enough to find the equilibrium mean size. An approximate model for the size of the globule can be obtained by using a third order expansion for the free energy although this approach seems an ad hoc hypotesis and in fact it fails to catch important properties of the globular state.

In order to derive a good formula for the free energy in the globular phase, we can study the plots of the square distance of beads in function of the arc-length in the globular phase using our simulations. The typical results for such a plot follow the shape of the green line in the right graph of Fig. 5: the square distance grows linearly for very short arc-lengths, then, at arc-length bigger than a characteristic length which depends on the interaction energy, the distance plateau.

An explanation of the linear growth for short arc-length distance is that the polymer behaves as a random walk trying to find his way out of the crowded environment made by himself, the interactions are thus screened for small distances. For larger arc-length distances the polymer reaches the globule surface and thus return in the inside of the globule, it is at this point that the distance in function of the arc-length plateaus.

At arc-length distances greater than the interaction screening length, the correlations between the positions of the beads are null which means that the information about the existence of a link network is totally lost. This suggest the form of the free energy of the globule:

$$F_{globule} = F(0) - k_b T C \log \left(\frac{V - \Sigma}{l_0^3} \right). \tag{25}$$

where the volume V depends on the pressure, energy of interaction and temperature $V = V(P, E_u, T)$ and C is a numerical parameter which should contain the number of degree of freedom of the system and hypotetically can depend on other variables. This is the formula for the free energy of a confined gas: we choose this formula because the polymer behave as a gas if the information of the link network is lost for big enough arc-length distances.

The free energy of the globule have some important features. For volumes which are smaller than the hard core repulsion volume Σ the argument of the logarithm becomes negative, also the free energy diverges for $V \to \Sigma$ which means that for big enough attractive energies E_u the polymer becomes incompressible like a liquid.

3.6 Free energy of the real polymer

Now that we know how the free energy can behave in the two limiting cases of coil and globular phase, we can write down the free energy for the real polymer which catch the incompressible globular state and describe the transition from coil to globule as the most simple interpolation formula between the two. We do this by arbitrarily choosing:

$$F_{real} = F_{coil} + F_{globule}, (26)$$

and setting the following constraints:

$$F_{real} \to F_{coil} \text{ for } V \to \infty \quad \text{and} \quad F_{real} \to F_{globule} \text{ for } V \to \Sigma;$$
 (27)

which set the value of the C parameter. Finally we obtain:

$$F_{real} = F(0) + \frac{3}{2l_0^2} k_b T V^{2/3} - k_b T \left[\frac{\Delta E_u}{k_b T} \frac{A - \Sigma}{V} + \frac{\Sigma}{V} \right] - k_b T \log \left(\frac{V - \Sigma}{l_0^3} \right). \tag{28}$$

This formula can be regarded as a mean field argument for the polymer free energy where the parameter of our simulation appear explicitly. This formula converges to the one proposed by Flory for the coiled state and is also able to describe the collapse to the globular state. This also let us calculate an equation of state for single polymer which can eventually be used in microfluidic experiments:

$$P = \left[\frac{V^{2/3}}{l_0^2} + \frac{\Delta E_u}{k_b T} \frac{A - \Sigma}{V} + \frac{\Sigma}{V} - \frac{V l_0^3}{V - \Sigma} \right] \cdot \frac{k_b T}{V}, \tag{29}$$

our simulations run without confinement, we can thus solve implicitly for the size of the polymer $V(P, \Delta E_u, T)$ as a function of the interaction energy E_u by setting the pressure to zero $P(V, \Delta E_u, T) = 0$, obtaining the plot in figure 8. This prediction show remarcable agreement with the results of the simulations (Fig. 9).

It is evident that this results defines a critical globular volume Σ_c . For $\Sigma > \Sigma_c$ (Big globule) the transition is the well studied second order Θ transition while for $\Sigma < \Sigma_c$ (Small globule) the coil-globule transition is sharp (first-order type) and the energy moves at greater values then Θ . This phenomenology is in agreement with the description of the Θ transition given by Lifshitz in 1978 though obtained with different methods [16]. We show a schematical phase diagram as a function of the parameters in figure 10 in order to explain the phenomenology.

4 Extimation of the parameters for *E. coli* nucleoid

In this paper we are interested in modeling the behaviour of the E.~coli nucleoid in different enviromental conditions. We will thus keep the interaction energies ΔE_u and ΔE_l and the configuration of the localized interactions free and instead extimate and fix the volume parameters (l_0, Σ, A) .

A rough extimate those parameters can be done with different approaches:

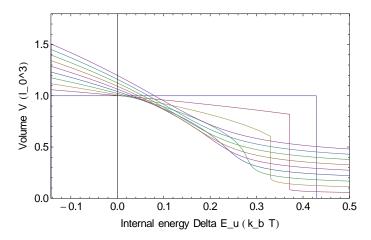


Figure 8: Phase diagram of the size of the polymer $V(P, \Delta E_u, T)$ in function of the interaction energy ΔE_u at P=0 and T= const. The lines are obtained solving Eq. 29 using numerical methods at different value of hard core repulsion parameter Σ and $A=8\Sigma$.

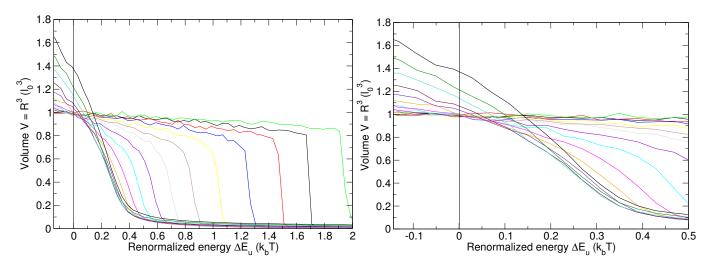


Figure 9: Phase diagram of the size of the polymer $V(P, \Delta E_u, T)$ in function of the interaction energy ΔE_u . The lines are obtained by simulating the polymer at different value of hard core repulsion parameter Σ and $A = 3\Sigma$, the abscissa is rescaled. The graph on the right is a zoom of the graph on the left for comparison with the theoretical predictions.

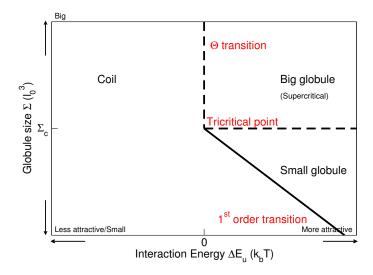


Figure 10: Parameters phase space as a function of uniform interaction energy ΔE_u and volume of globular phase Σ .

• The first approach would be to take as a comparison a Worm-Like-Chain with the length, the persistence length and the volume radious of the DNA molecule of the *E. coli* chromosome,

and from this simplified model extract an extimate of the parameters for the nucloid; this would give us a very inaccurate extimation because we would neglect the RNA and proteins bounded to DNA as well as the global effect of the molecule supercoiling and topology which are currently not extimable.

• The second approach would be to extract the observed global parameters from recent experiments performed on purified nucleoids under optical microscopy, in this case we would introduce an experimental due to the difficulty of identifying the theta transition.

4.1 Comparison to a Worm-like-chain

An extimate of the end-to-end distance of the nucleoid at Θ transition l_0 in nanometer can be given by taking as a comparison the end to end distance for a Worm-Like-Chain which can be approximated for long chains by the formula:

$$l_0^2 = 2l_p L \tag{30}$$

where L is chain contour length and l_p is the persistence length in nanometers. Substituting the contor length of DNA in E. coli nucleoid ($\sim 1.577mm$) and the persistence length of naked DNA in physiological conditions ($\sim 50nm$) we obtain

$$l_0 = 12.85 \mu m. \tag{31}$$

The excluded volume Σ can be roughly eximating by calculating the volume of the cylinder containing the DNA molecule as if it was straight using the formula:

$$\Sigma = (\pi/2)d^2L \tag{32}$$

where d is the DNA diameter taken by the sum of the DNA Helix Diameter (23.7Å) and two times the DNA screening length in physiological condition (~ 4 nm). We obtain for the excluded volume:

$$\Sigma \sim 0.1 \mu m^3 \sim 5 \cdot 10^{-5} l_0^{\ 3} \tag{33}$$

This number is calculated by considering the volume of a *naked* B-*DNA* double helix, which mean without any *protein* attached and no plectonemic or secondary structures. Those effect could increase the excluded volume of the *DNA* in-vivo conditions.

4.1.1 Attraction box

In our model beads interact with each other by their repulsive excluded volume force and by an attractive uniform force which we assume is due to the molecular crowding of the cytoplasm. The depletion of the molecules in the cytoplasm due to the presence of the long DNA macromolecule results in an effective attraction between couples of DNA double Helix segments. This effect have been recently shown in DNA and PET solutions [14] and has been advanced as a possible driving force of chromosomal organization¹ [17].

In the cell, this force have a maximum range of (~ 5 nm), which is the diameter of a typical crowding protein². In our model the range of the attractive interaction is represented by a global

 $^{^{1}}$ In their work, the Cook group doesn't investigate the coil globule transition but they focus on DNA looping instead, in the cited paper Marenduzzo states "There are entropic costs associated with forming DNA or chromatin into a loop, but these can be overcome if large enough complexes are bound to the template" which assumes that depletion forces are excerted on the DNA through large enough complexes.

² Actually Asakura and Oosawa [2] in their original work stated that "The attractive potential between particles is of long range" thought subsequent works assume the opposite. An example of long range depletion interaction is the Casimir effect, but in that case there is not a characteristic size of the photons. A proper account of the energy shape due to molecular crowding on rigid spheres can be investigated following the Casimir-effect explanation procedure taking into account the protein size distribution of the cytoplasm proteome.

volume parameter A. We estimate this parameter by integrating a cylindrical volume of interaction of 5nm uniformly distributed along the contour length of the DNA in the nucleoid. We thus use for A the same formula we used for Σ (Eq. 32) this time setting d equal to the sum of the DNA excluded volume diameter (6.37nm) plus two time the interaction range (10nm). We obtain:

$$A \sim 0.66 \mu m^3 \sim 6.6 \cdot \Sigma \sim 3 \cdot 10^{-4} l_0^{3},$$
 (34)

which is comparable the other recent extimations [17] which set to the number of 6 the number of beads that can collapse which each other in a depleting environment.

From the Asakura Oosawa potential [2] we know that the interaction energy E_u is proportional to the density of the macromolecule solution, which can vary from (~ 0.2) to (~ 0.3) in cells³. Experimental results and mean-field extimates indicate a total free energy from depletion interaction in the range of $\sim 10^3 - 10^4 k_b T$ per nucleoid [14].

4.2 Using experimental data

Recent measurements of purified nucleoids [20], although incomplete, can give an extimate of the real order of magnitude of the volume parameters of the *E. coli* nucleoid.

They produced three interesting graph which we can use to extimate the parameters:

- the first graph shows as a time series the compression and the decompression of the nucleoid upon addition and removal of the PEG crowding agent. From that graph we can easily extrapolate the value of $\Sigma/l_0^3 \sim 0.1$.
- The second graph shows the nucleoid size in function of the concentration of PEG and thus the theta transition due to crowding agent. It is very interesting that they notice that at values of PEG concentration comparable to the crowding due to the cytoplasm in in-vivo cells the nucloid is right at the Theta transition. This gives us an idea of the order of magnitude of the uniform interaction energy which should be $E_u \sim \Theta$.
- The third graph shows the force/extension behaviour of the nucleoid under confinement due to a micropiston.

They fit that graph with the following simple formula which is basically a first order expansion of the free polymer model with interactions:

$$\frac{f}{Y} = \left(\frac{R}{R_0}\right) - \left(\frac{R}{R_0}\right)^{-2}.\tag{35}$$

and obtain as extimations $R_0 = (10.1 \pm 2.2)\mu m$ and for the interaction parameter parameter $Y = (-2.04 \pm 1.24)pN$; the negative sign of the interaction parameter tell us that the polymer is in coiled state. We can make a comparison of the two parameter with the parameter in our model to fill the constants in the equation 23. By comparing the two models we can set:

$$\frac{Y}{R_0} = -\frac{k_b T}{l_0^2}, \quad \text{and} \quad \frac{Y}{R_0^2} = -\frac{\Delta E}{l_0^3} \frac{A - \Sigma}{l_0^3}.$$
 (36)

If we set $A \sim 6.6\Sigma$ as in the previous paragraph, then we can extract the values of $\Delta E/k_bT$ (self avoiding energy) for the nucleoid in the coiled state as well as the values of l_0 (radius at theta transition). We obtain $l_0 \sim 0.15\mu m$ and $\Delta E \sim 0.025k_bT$. Those values are not compatible to the one calculated from a Worm-like-chain approximation: this could mean that either the approximation of formula 35 are not acceptable (unlikely) or that the worm-like-chain is a terrible model due to the heavily crosslinked nature of the nucleoid.

³ The AO potential have been written for rigid spheres, in the case of polymers this is not directly applicable. Work have been done by Grosberg and Shakhnovitch in this direction [11] and we have either to cite it or to understand it's implications.

5 Localized interaction model

In the same way we explored in detail the phase diagram of the nucleoid under the uniform attractive force and hardcore repulsion, in the following three paragraphs we will try to understand the behavior of our model by describing the configurations that the polymer assumes in presence of additional localized attractive interactions which describe the effect of nucleoid-associated crosslinking proteins, in particular we will try to describe the effect of H-NS.

We try to model a situation in which high H-NS binding regions of the genome frequently crosslink between each other. The crosslink can be either due to the zipping of plectonemes by H-NS or by the effect of H-NS oligomerization or by an increase effect of depletion on those regions due to the size of the H-NS oligomer. At the same time our model assumes that the effect of H-NS in other part of the nucleoid is negligible. In comparison to other NAP, the binding of H-NS has been shown to form strong signals around specific regions along the E. coli genome [13], those regions correlates well with transcriptionally silent regions [22].

The H-NS binding regions can be defined by two parameters: p is the number of binding regions, and η is the fraction of chain volume occupied by the binding regions. We assume that η is a small fraction. We have chosen the parameters (p, η) because the observables on the system are invariant under renormalization of the number of statistical units N:

$$V(p, \eta, N, \dots) = V(p, \eta, N', \dots) \quad \text{with} \quad N \neq N', \tag{37}$$

and there is a very simple bijective map between the phase space of those two parameters and the space of equispaced regions on the polymer chain at fixed N: by discretizing our polymer with N beads (see Fig. 11),

- we will assume that all the binding regions have equal length (and binding strenght): this way we fix the length of every binding region in number of beads $N\eta/p$. In case this number is not an integer some approximations should be done, for increasing N the importance of those approximations on the result decrease.
- we set the *H-NS* binding regions at fixed intervals along the genome: the distance between those region will be a genomic region of size in beads $N(1-\eta)/p$. Those regions of the chromosome will not interact due to crosslinking proteins but will still interact only with the uniform forces (molecular crowding) described in the previous sections.

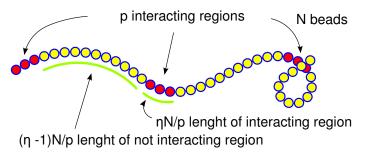


Figure 11: The parameters η and p define for fixed N univocally a configuration of equispaced locally interacting regions along the polymer chain.

Those rules could be relaxed by introducing stochasticities or information from experiments but in the following paragraph we are going to stick to the minimal rules in order to get more insight on the general behaviour of the system before approaching more complex cases. We can think of this exercise as a form of mean field approach.

As explained in section 1, the beads belonging to the two regions interact with each other with two different energy parameters: ϵ_u is the uniform interaction which define an attraction between each bead with any other and ϵ_l is the localized interaction which belongs only to the *H-NS* binding regions.

5.1 Collapse due to localized interactions

The first question we can ask is wherever the localized interaction alone can induce a polymer collapse and at which values of ϵ_l it would happen. We know that in the limit for $\eta \to 1$ the localized interactions would behave as the uniform so a θ transition is to be expected in that limit.

Since in realistic configurations η will be a small fraction of the chromosome, a collapse of the volume occupied by the chain is to be expected at growing values of ϵ_l (in comparison to θ) for smaller η , this expectation is confirmed by the results of the simulation (see Fig. 12).

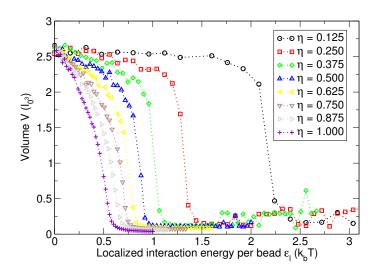


Figure 12: Collapsed of polymer as a function of local interaction energy ϵ_l . The collapse is shown for different locally interaction proportion per chain η . Other parameters are set to $(N=256, \Sigma=0.043, p=16)$. The collapse of the volume of the chain happen at higher values of ϵ_l for smaller η .

We recall that the transition energy is fixed by the second virial coefficient going to zero in forumla 13. In the same way we write a free energy term for the block-interactions between the p identical blocks along the chain comprising one locally interacting and one non locally interacting region:

$$F_{local} = k_b T p \left(\frac{p-1}{2} \frac{v_{local}}{V} \right), \text{ where } v_{local} = \left(b - \frac{a}{k_b T} \right)$$
 (38)

In order to do so we need to extimate the contributions to the repulsive part b and the attractive part a to the effective exclusion volume.

The contribution to the attractive a part is given by the uniform and localized interaction of one region with the other, $a = a_{uni} + a_{loc}$. The uniform attraction for is between every couple of locally interacting regions and the non locally interacting region which sorround it, thus:

$$a_{uni} = \frac{N}{p} \frac{4}{3} \pi \epsilon_u (\alpha^3 - \sigma^3); \tag{39}$$

The local attraction instead is only between the locally interacting regions, thus:

$$a_{loc} = \frac{N\eta}{p} \frac{4}{3} \pi \epsilon_l (\alpha^3 - \sigma^3). \tag{40}$$

The contribution to the repulsive b part is given by the sum of the hard core repulsion and the entropy cost of closing the loop between two locally interacting regions, $b = b_{hc} + b_{loop}$. The hard core repulsion can be extimated as:

$$b_{hc} = \frac{N}{p} \frac{4}{3} \pi \sigma^3; \tag{41}$$

while the looping entropy can be extimated at the zeroth order by assuming the non locally interacting chains to be free, we know the probability distribution function for the free chain from eq. 8, we can

extimate the partition function determined by the closing of all p-1 possible loops as following:

$$\mathbb{Z}_{loop}(p,\eta) = \left(1 - \int_{|\vec{r}| < \alpha} d\vec{r} \ p_{gN}(\vec{r})\right)^{p-1} \quad \text{with} \quad g = \frac{1-\eta}{p} \\
= \left(1 - \sqrt{\frac{6}{\pi}} \frac{\alpha}{l_0 g^{1/3}} e^{-\frac{3\alpha^2}{2g^{2/3} l_0^2}} + \text{Erf}\left(\sqrt{\frac{3}{2}} \frac{\alpha}{l_0 g^{1/3}}\right)\right)^{p-1} \\
= (1 - \Xi(p,\eta))^{p-1}, \tag{42}$$

to notice that the loop partition function goes to 0 for $\eta \to 1$ as it is expected. The Helmholtz free energy of collapse due to this term is thus equal to:

$$F_{loop} = -k_b T(p-1) \log [1 - \Xi(p, \eta)]$$
(43)

taking the first order expansion of the logarithm and comparing with eq. 38, putting at the transition $V = l_0^3$, we can extimate an effective interaction term:

$$b_{loop} = l_0^3 \Xi(p, \eta) \tag{44}$$

We can thus extract the energy at which the effective volume is null by summing the four term end comparing to zero $b - a/k_bT = 0$:

$$\epsilon_l|_{v=0} = \frac{\Theta_{loc} - \epsilon_u}{\eta}; \qquad \Theta_{loc} = \Theta\left(1 + \frac{3}{4\pi} \frac{l_0^3}{\Sigma} p \; \Xi(p, \eta)\right).$$
(45)

This equation for the transition energy behaves as expected for $\eta \to 1$ and $\epsilon_u \to 0$, because $\Theta_{loc} \to \Theta$ and the polymer collapse exactly at the Θ transition; however, as η decrease, it requires an higher attractive energy ϵ_l for the transition to happen; in the limit of small η , we can take the first order of the expansion of $\Xi(p,\eta)$ for the parameter $\frac{(1-\eta)N}{p} \gg 1$:

$$\Xi(p,\eta) \simeq \sqrt{\frac{6}{\pi}} \frac{\alpha^3}{l_0^3} \frac{p}{1-\eta} = \sqrt{\frac{6}{\pi}} \frac{A_l}{l_0^3 (1-\eta)}.$$
 (46)

where $A_l = \alpha^3 p$ is the renormalized localized interaction volume, the corrispettive in the uniform case was $A = \alpha^3 N$; Also $l_0^3 (1 - \eta)$ is a physical parameter and correspond to the total volume occupied by the portion of the chain which is not locally interacting at the Θ transition, the corrispettive in the uniform case would have been l_0^3 .

The dependence of the transition point can thus be approximated by the following formula:

$$|\epsilon_l|_{v=0} (\eta) \underset{\eta^{-1} \gg 1}{\sim} -\frac{\epsilon_u}{\eta} + \frac{1 + Cp}{\eta} \Theta$$
 (47)

where C is a constant that depend on other variables of the simulation. We thus predict that,

- the transition energy is equal to Θ indipendently of p for $\eta \to 1$.
- the transition energy is a linear function of η^{-1} for small η ; at fixed η , the transition energy increase with an increase of the number of interacting regions p.

Results of simulation confirm those two predictions (see Fig. 13). Also those results can be compared qualitatively with the SBS (strings and binders switch) model [3] if we consider the proportion of interacting regions η as a growing function of the mean number of H-NS molecules in the living cell (see appendix A for details).

As for the uniform interaction, we should choose a suitable set of energy parameters which behave well under renormalization of the number of statistical units N; The indipendent extensive variables which describe the polymer energy are:

$$\frac{E_1}{k_b T} = (p-1) \left(\epsilon_l + \frac{\epsilon_u - (1+Cp)\Theta}{\eta} \right) \quad \text{and} \quad \frac{E_2}{k_b T} \simeq (N-1)(\epsilon_u - \Theta), \text{ for small } \eta$$
 (48)

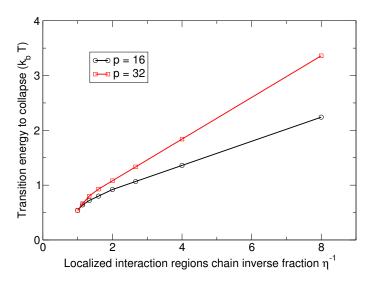


Figure 13: Collapse transition energy per bead $\epsilon_l|_{v=0}$ as a function of local interaction regions fraction η . Measurement were taken for p=16 and p=32 and confirm the trends of equations 45 and 47 which predict $\epsilon_l|_{v=0} = \Theta = 0.5k_bT$ for $\eta \to 1$, and a linear dependence of the transition energy in η^{-1} for smaller values of η . To note that the correction due to \mathbb{Z}_{loop} accounts for the dependence of the transition energy from the p parameter. Other parameters are set to $(N=256, \Sigma=0.043, \epsilon_u=0)$.

 E_1 represents the internal energy of the H-NS binding regions, alternatively we can call it the strong localized beads interaction, while E_2 represents the internal energy of the regions where there is no H-NS binding, the soft concentrated beads interaction and is equal to E_u in the absence of localized interactios. Those variables renormalize properly with a change of resolution N and are null at the transition point.

As in the only uniform attraction case, while the Flory-type analysis is satisfying in the swollen case, it cannot explain the behaviour in the collapsed phase. We can transpose some elements of the qualitative phenomenology of the uniform collapse to this different kind of collapse: in the cases of strong localized interaction $(E_1 \gg 0)$ and small uniform interaction $(E_2 < 0)$, which is the most interesting case, the size of the collapsed phase will be equal to the portion of volume occupied by the localized beads $(V = \eta \Sigma)$; for small globle sizes $(\eta \Sigma < \Sigma_c)$ the transition from coil to globular phase will become first-order-like. On the other end the effect of the localized interactions will be big in the collapsed case due to micro-phase segregation happening between the strongly interacting and the softly interacting regions.

Our simulations show that the strongly interacting beads collapse in a compact globule while the swollen regions which are softly interacting form a branched structure on the surface. In the simpler case the result is a structure which resemble a micelle (see Fig. 14). The size and the number of micelles which are formed per polymer is not constant across the parameter space.

5.2 Micelle size and properties

The formation of a micelle is an evidence of self-assembly of the bacterial nucleoid structure. The theory for explaining the size and the stability of this structure can be studied by implementing the mothodology developed for membrane micelles in the book of Israelachvili [12]. The theory of membrane micelles predict that there is a typical micelle size in function of the microscopical parameters which is set by the equilibrium between the repulsion between the hydrophilic heads on the surface and the attraction of the hydrophobic tails. If the concentration of surfactant molecules is high enough, due to this typical micelle size, multiple micelles are produced in solution with a size distribution which is peaked around the typical micelle size till the number of isolated surfactant molecules goes to a small quantity (called the critical micelle concentration).

In our simulations micelles are formed in the conditions where we set a strong localized attractive interaction $(E_1 \gg 0)$, which keeps the core of the micelle in a collapsed state comparable to the

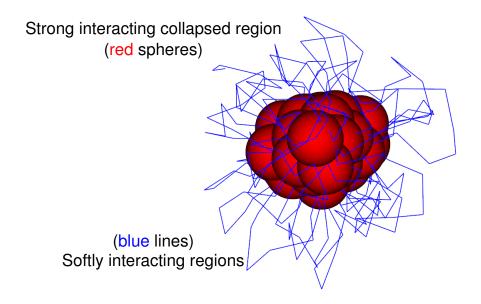


Figure 14: Strongly interacting and softly interacting regions can self-assemble to form a structure that reflect a polymeric micelle.

hydrophobic portion of surfactant micelles, and a negative uniform interaction ($E_2 < 0$) which in turns creates a corona of swollen chain around the core as in Fig. 14.

Since the localized attractive beads and the other beads phase segregate in a swollen corona and a collapsed core, which are sub-structures with a big difference in the dynamics, we can use an adiabatic approximation and write the free energy of the a micelle formed by n localized interaction regions as a sum of the free energy of the core and that of the corona:

$$F_{micelle}(n, V, E_1, E_2) = F_{core}(n, E_1) + F_{corona}(n, V, E_2),$$
 (49)

with p and η fixed, also, for stable micelles we can ignore the fluctuations in the volume $V_{core} = n\eta \Sigma/p$ of the core which are negligible in comparison to the space fluctuations of the swollen corona.

The size and the number of micelles formed in the single polymer is not constant across the parameter space. We can expect this fenomenology due to the physical analogy of our sistem to a surfactant colloidal solution confined by the link chain. The volume of a single micelle is going to increase with the decrease of the parameter E_2 since it correspond to an increase of the effective volume of the beads and thus to a swelling of the corona around the globule; correspondingly, it is expectable a monotonical increase of F_{corona} as a function of the decrease of the E_2 parameter. At some point F_{corona} is going to outweight F_{core} in the micelle free energy because F_{core} is expected to stay approximately constant as a function of E_2 . The question is if there is a critical corona energy E_2 under which a polymer with a single micelle undergoes fission and the stable polymer configuration shows states with two, or multiple micelle.

In order to answer this question we simulated the polymer with fixed p, η and E_1 starting from a initial configuration which correspond to a single micelle per polymer (Fig. 14), lowering the uniform interaction parameter E_2 in order to find a transition to a multiple micelle configuration. The initial configuration was fixed by running the system with the corona at the theta transition $E_2 = 0$, in this conditions the free energy of the corona is purely enthropic and thus there are no elements which would suggest a free energy advantage of the multiple micelle scenario over the single micelle one.

While we expect the transition between a single micelle to a two micelle scenario to not change the volume of the fluctuations of the polymer by a great amount, we do expect the breaking of the rotational simmetry around the three space dimensions. This simmetry breaking is not something unusual in such transition and is present also in the coil-globule transition. We expect this breaking because fluctuation of the volume occupied by the polyme along the vector which connects the two cores would be bigger than the fluctuation around the other two axis of simmetry of the two cores taken individually (see Fig. 15).

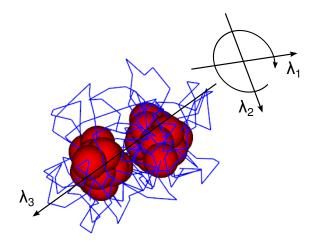


Figure 15: The volume occupied by the polyme along the vector which connects the two cores would be bigger than the fluctuation around the other two axis of simmetry of the two cores taken individually.

It is possible to measure this effect by taking the mean of the ratio of the first and the third eigenvalue of the inertia matrix of single realization along the montecarlo time.

$$\Gamma = \left\langle \frac{\lambda_1}{\lambda_3} \right\rangle$$
 where $\det(I - \lambda_i) = 0$ and I is the inertia matrix of single configuration (50)

we measured this quantity in simulations as well as the volume as a function of the corona interaction energy E_2 , we were able to show, for a sufficient number of statistical units N, the micelle binary fission under a critical corona energy E_2^{crit} (see Fig. 16 and Fig. 17).

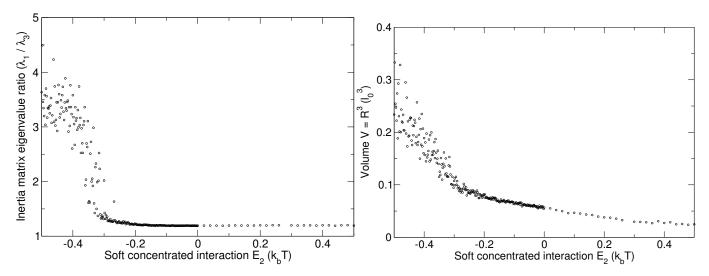


Figure 16: Left: mean ratio between the first and the third eigenvalue of the inertia matrix (Γ) over single realizations along the montecarlo time as a function of the corona energy E_2 . Right: Volume occupied by the fluctuations of the end-to-end distance in function of corona energy E_2 . The plot show a phase transition at the energies for which the single micelle fission in two micelles. The other parameters of the simulation are set to: $(\epsilon_u + \epsilon_l = 3.4, \eta = 0.125, p = 32, N = 256, \Sigma = 0.042 \cdot l_0^3)$.

A binary fission of the micelle is to be expected given the condition of $F_{micelle}(n, E_1, E_2) > 2 \cdot F_{micelle}(n/2, E_1, E_2)$. We can generalize and write the free energy of q micelles, trascuting any interaction term:

$$F_{micelles}(n, q, V, E_2) = qF_{micelle}(n/q, V, E_2)$$
(51)

The free energy of the core can be extimated as follows: the energy carried by the beads which are deep inside the cores carry a fixed energy indipendent of the number of micelles because they

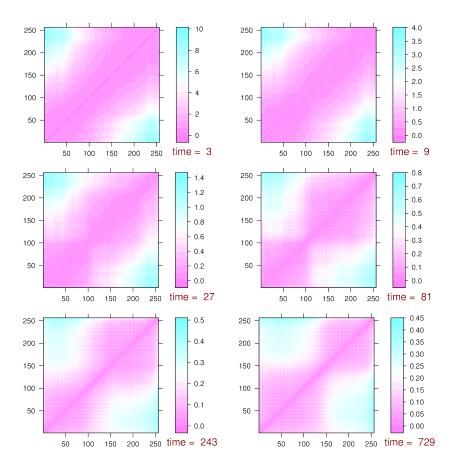


Figure 17: Contact matrix for a polimer with localized interactions in function of time. This figure show the collapse of the polymer in two different micelles. The matrix are plotted for ineteraction energies and localized interaction configuration ($\epsilon_u = 0, \epsilon_l = 3.4, \eta = 0.125, p = 32$). The polymer have the following parameters: $N = 256, \Sigma = 0.042 \cdot l_0^3$. The simulations are started with initial condition of the swollen coil and the mean contact matrix is measured over 6 different time ranges.

at most interact with a fixed number of core beads, proportional to the ratio $(A - \Sigma)/\Sigma$; the beads which are instead on the surface of the core interact only on the side which is in contact with other core beads thus they will carry only a fraction of the energy carried by the beads deep inside the core. The energy difference between the surface and the central beads create a surface tension of the globule. The surface tension is the force which keeps spherical shape of the globule and avoid the splitting of it in order to minimize the core surface. The energy is can be written as [12]:

$$F_{core} = \gamma a, \tag{52}$$

where γ is the a function of E_1 and a is the surface area of the core. Since we know that the volume of the core made by n localized interacting beads, for $E_1 \gg 0$ is $V_{core} \simeq \eta \Sigma n/p$, we can extimate $F_{core}(n, E_1) = \gamma(E_1) \cdot (\eta \Sigma n/p)^{2/3}$. The free energy carried by q cores is:

$$F_{cores}(n, q, E_1) = q \cdot F_{core}(n/q, E_1) = q^{1/3} F_{core}(n, E_1)$$
 (53)

which increase by increasing the blob number q.

Without approaching the problem of the eximation of the free energy of the corona as a function of the number of interacting regions n, we can guess already that if the free energy is a power law this parameter:

$$F_{corona}(n, V, E_2) = \nu(E_2, V)n^{\rho} \tag{54}$$

then the corona free energy carried by q micelles is also a power law of the blob number q:

$$F_{coronas}(n, q, V, E_2) = q^{1-\rho} F_{corona}(n, V, E_2)$$

$$(55)$$

with exponent $1 - \rho$. In order to have an equilibrium number of micelles which is different from 1 it thus suffice to have the exponent $\rho > 1$.

We can extimate the form of eq. 54 by analogy with the free energy of the star polymer. Daoud and Cotton studied the density shape of the star polymer using a blob representation [8], they extimate the size of the thermal blob as a function of the distance r from the star polymer center to be $\xi \sim r f^{1/2}$ where f is the number of branches. They also suppose that considering the volume of between the spheres of radius r and $r + \xi$ the whole shell contains f blobs, one for each branch. Thus the total number of blobs per star polymers should scale as $n_{blobs} \sim f \xi^{-1} \sim f^{3/2}$. If, as an analogy, we compare the corona of a micelle to a star polymer with 2n branches, we can extimate using the blob ansatz ($F \sim k_b T$ per number of blobs) the exponent $\rho = 3/2$. Using this extimation we can write:

$$F_{micelles} = q^{1/3} F_{core}(n, E_1) + \frac{1}{q^{1/2}} F_{corona}(n, V, E_2)$$
 (56)

The number of micelles which minimises the energy is thus equal to:

$$q = \left(\frac{3}{2} \frac{F_{corona}(n, V, E_2)}{F_{core}(n, E_1)}\right)^{6/5}$$
(57)

If we replace n by p, we can extimate using this formula the number of micelles per chain: by increasing the weight of F_{corona} to F_{coron} , for instance by reducing the negative corona energy E_2 we increase the stability of the splitted micelle q > 1 case respect to the single micelle.

The behaviour of polymeric micelles is very similar to the case of polysoaps. Polysoaps are hydrophilic polymers which incorporate amphiphilic monomers, the hydrophilic part of the polysoap is swollen while the amphiphilic part is collapsed due to the interaction with the solvent by definition; this situation is similar to the collapsed phase of our model with strong localized interaction and small uniform interaction. It has been shown that also polysoap forms micelles of different size and number, also the interactions their interactions of the micelles between each other give place to complex ternary structures [5,6].

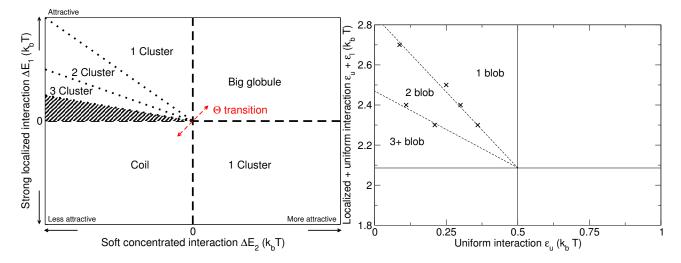


Figure 18: Theoretical phase diagram of micelle formation and results from simulations (hand made/totally unreliable). Simulation parameters are $(N=256, \Sigma=0.043, \eta=0.125, p=32)$.

6 Contact matrices and contact probabilities from HiC experiments

6.1 Typical contact matrices in different polymer phases from simulations

Appendices

A Binding profiles as a function of concentration and specificity

The section 5.1 describe the collapse of the polymer in function of the localized interactions. We learned that the transition energy is equal to Θ in the limit for $\eta \to 1$ and that it increase with η^{-1} and p. While η and p are very convenient parameters for the calculation purpouse, we would like in this section to address the problem of extimating the collapse energy of etheropolimer in function of the H-NS concentration which is more close to the possible experimental verifications of the model.

In this simplified model we will consider the length of H-NS binding regions as fixed to η/p . In order to extract the transition energy per bead $\epsilon_l|_{v=0}$ (see eq. 47) in function of H-NS concentration we will thus simulate the collapse at fixed p with η/p fixed, then we will apply a transformation which redefines the axes $(p, \epsilon_l) \to (c(p, \epsilon_l), \epsilon_l)$ with $c(p, \epsilon_l)$ concentration of H-NS molecules that will be appropriately defined in the following paragraphs.

The binding probability of a transcription factor to specific sites follows in the most simple case the logistic equation [1,4]. We will transcure in this work the experimental evidence that H-NS binding regions are a results of an interplay between specific binding and oligomerization [10,21] because this effect are difficult to quantify. If, in general, we define with the letters E the binding of a protein and S the protein by itself, we can write the equation for the chemical binding of the protein with it's binding sites:

$$S + E \underset{k^{-}}{\overset{k^{+}}{\rightleftharpoons}} ES \tag{58}$$

This, with the law of concentration of the total number of binding sites $[E_0] = [E] + [ES]$ let us wite an equation for the concentration at the steady state:

$$\frac{[ES]}{[E_0]} = \frac{[S]}{\frac{k^-}{k^+} + [S]}. (59)$$

Finally we can use Arrhenius law to extimate the value of k^-/k^+ : and obtain the probability of a binding site to be bound in function of the concentration of binding molecules $c \equiv [S]$:

$$\mathscr{P}_{\text{bound}} = \frac{c}{e^{-\frac{E}{k_b T}} + c},\tag{60}$$

where E is the energy per binding site (see E_1 in eq. 48): $\frac{E}{k_b T} \sim \epsilon_l$ for ϵ_u and Θ small. And c can be expressed in protein units per base pair.

On the $E.\ coli$ chromosome there are multiple H-NS binding sites. The number N of binding sites per chromosome has been extimated in [13] to be respectively 458 in middle exponential phase and 537 in stationary phase. We can write the number of occupied H-NS binding sites as:

$$p = N \mathcal{P}_{\text{bound}} = N \frac{c}{e^{-\epsilon_l} + c},\tag{61}$$

inverting we finally find the equation for $c(p, \epsilon_l)$:

$$c(p, \epsilon_l) = \frac{p}{N - p} \exp(\epsilon_l). \tag{62}$$

Thus we now we have a tool to substitute in the graphs the parameter p with the concentration c. The results of this substitution is a phase diagram comparable to the one optained by Nicodemi [3]

and an example is reported in Fig 19. In line to the Nicodemi work, in this calculation we are not considering the fact that multiple H-NS molecules binds to single binding sites, the fact that the different binding sites have a size distribution and the and the cohoperativity between H-NS binding.

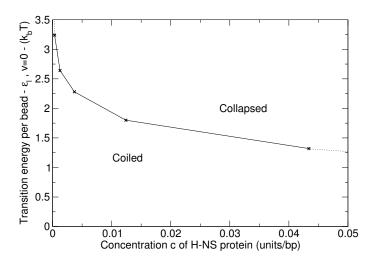


Figure 19: The simulations have been runned with parameters N=256, $\Sigma=0.043$, $\eta/p=0.250/32$ and variating p in 4, 8, 16, 32, 64. The points of collapse (p, ϵ_l) have then been converted to cohordinates (c, ϵ_l) using the transformation in eq. 62.

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