

SMT-based task- and network-level static schedule generation for time-triggered networked systems

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TTTech Computertechnik AG

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Time Triggered Networks

Ensuring Reliable Networks

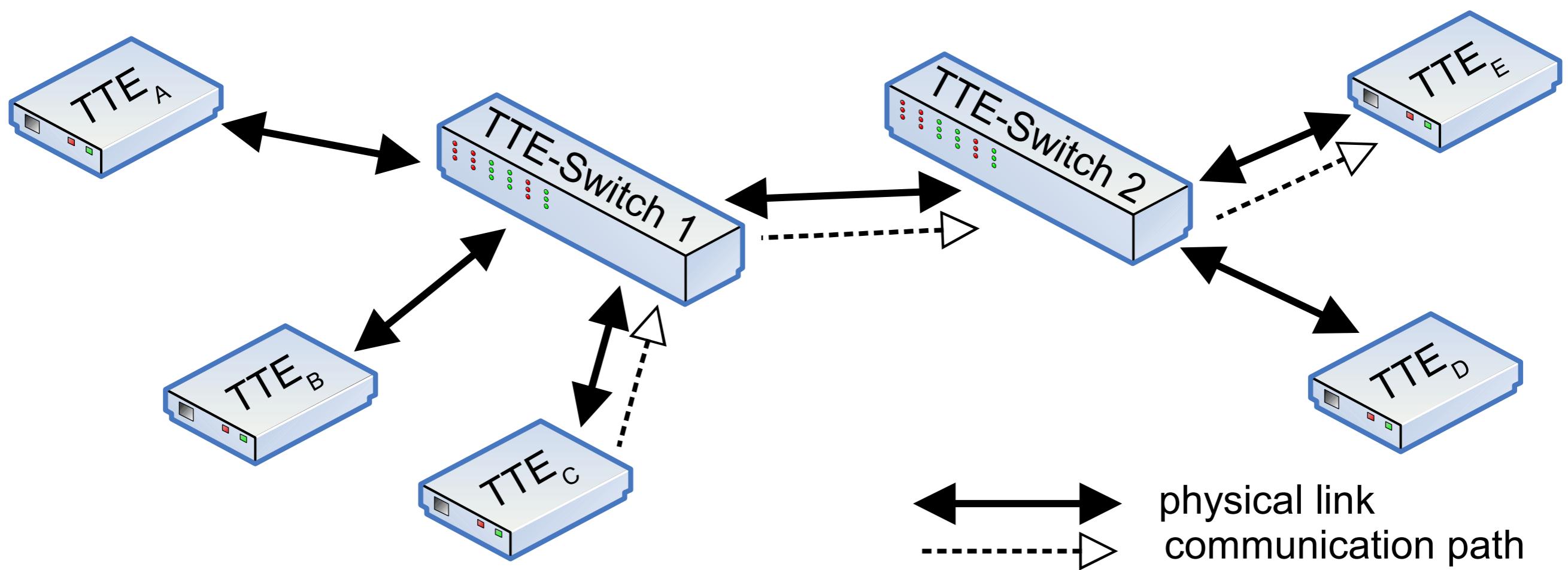
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Time triggered communication

Ensuring Reliable Networks

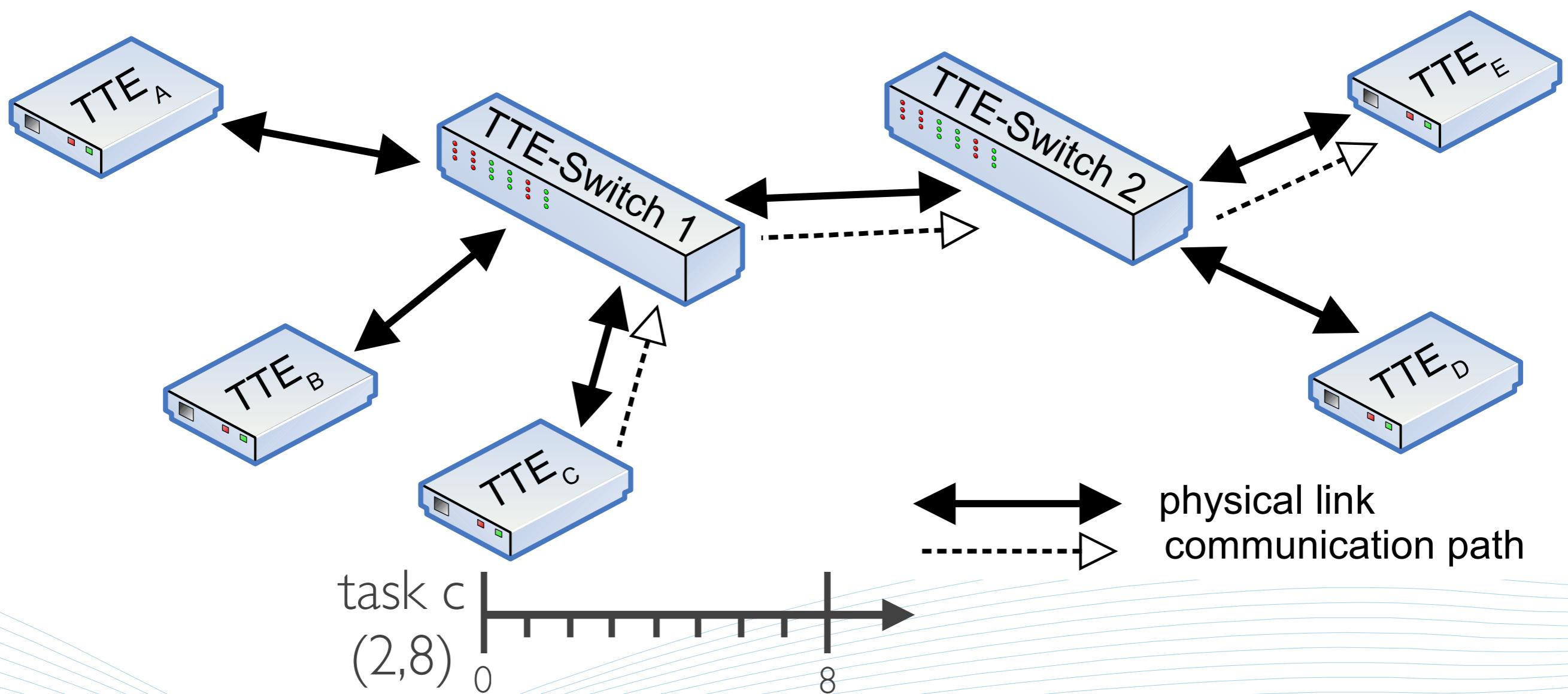
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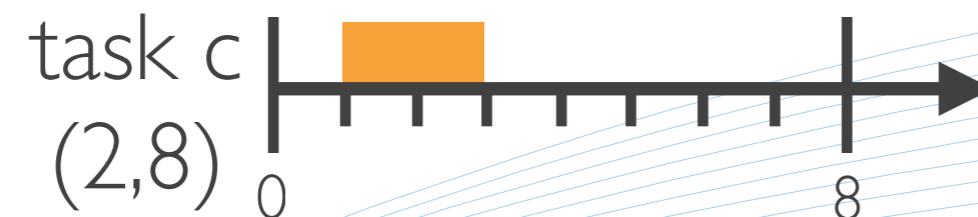
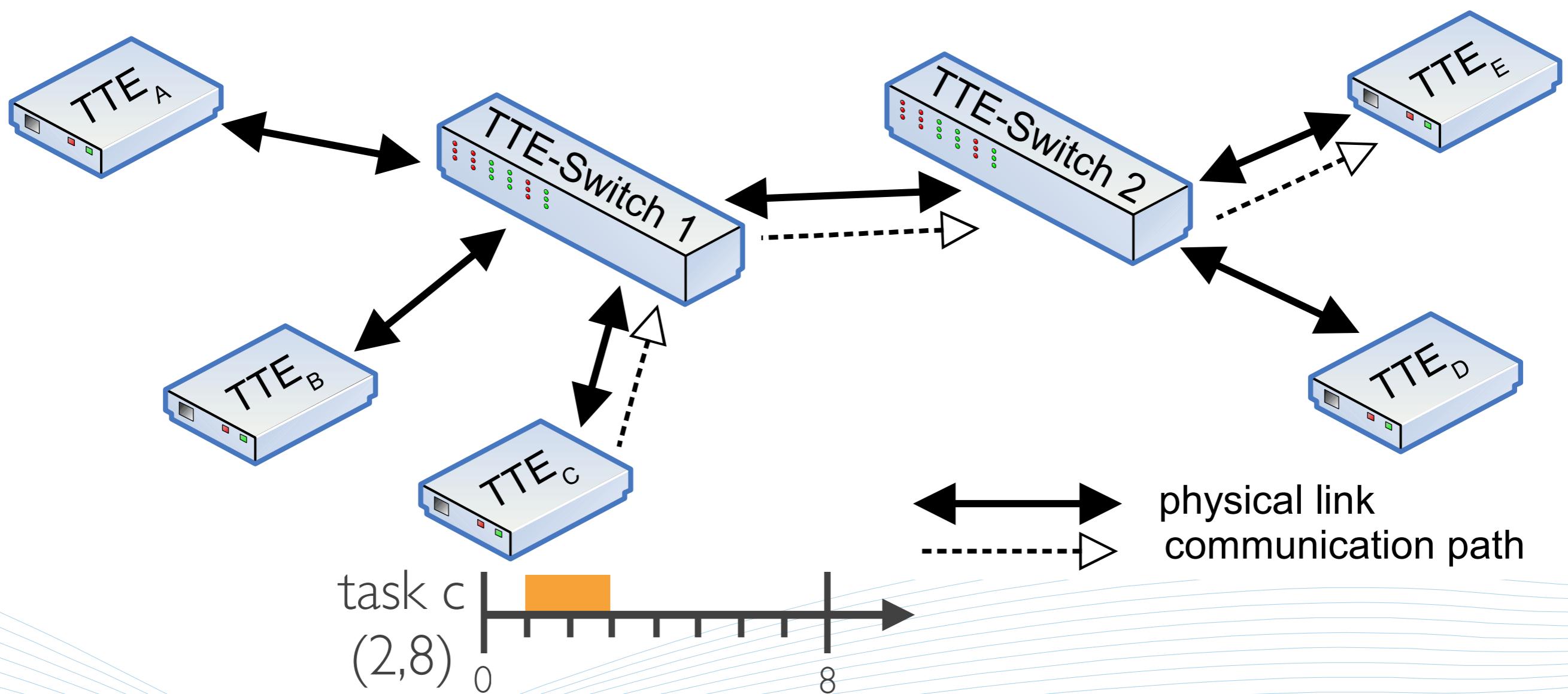
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Ensuring Reliable Networks

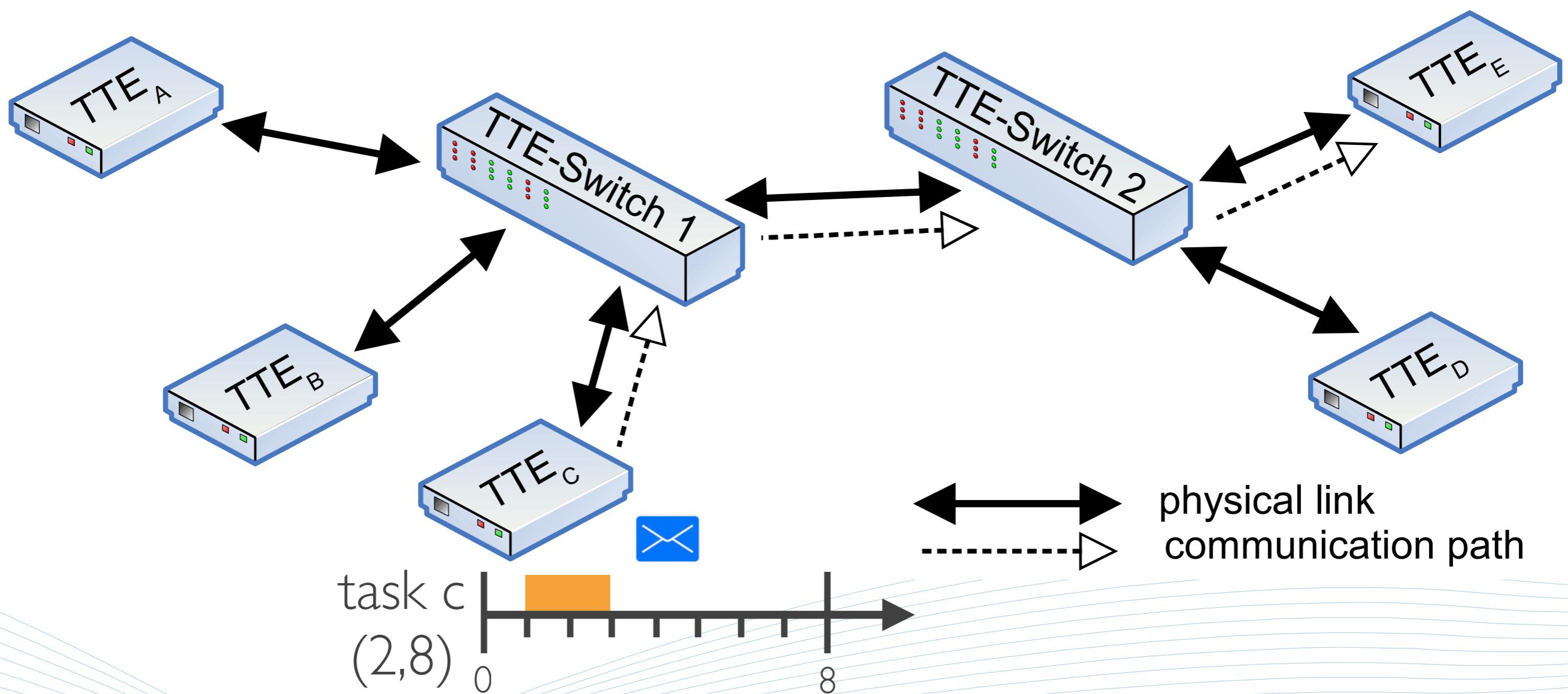
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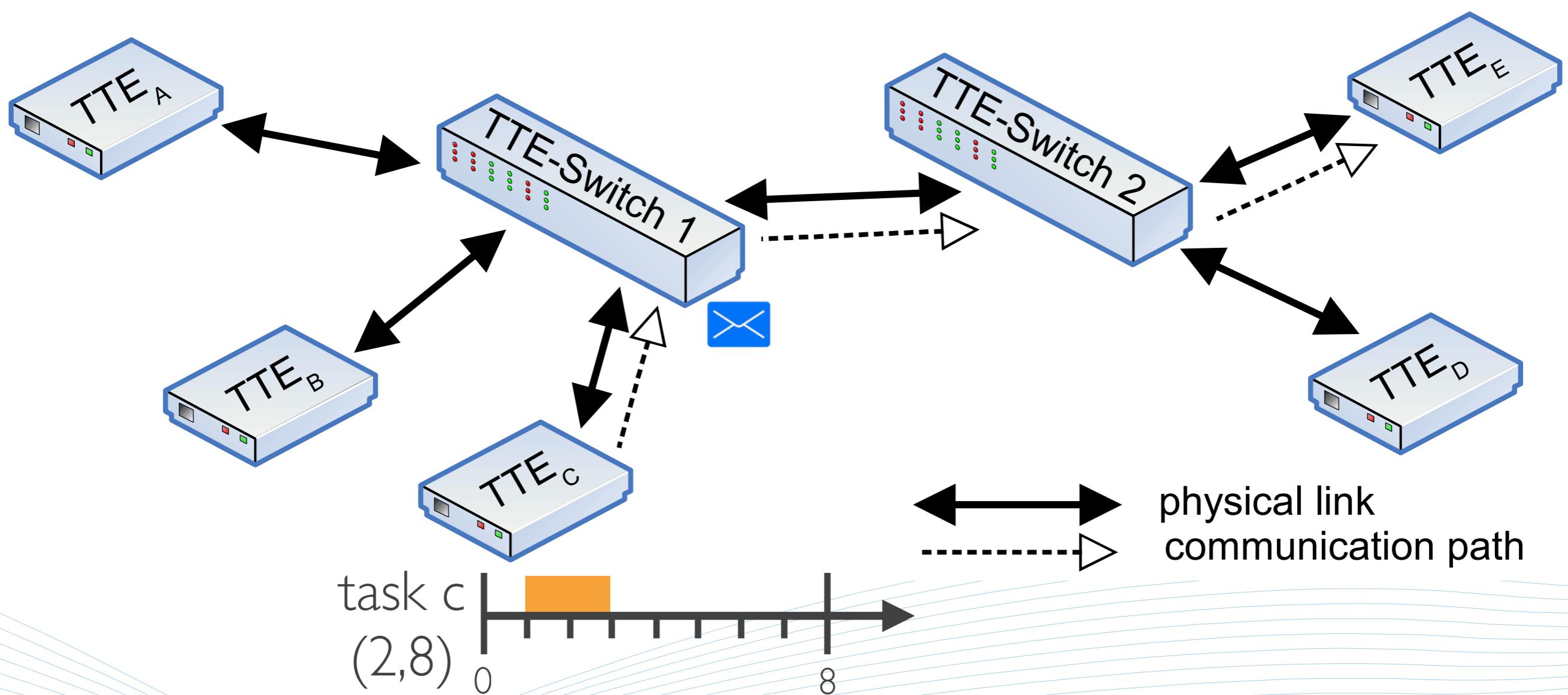
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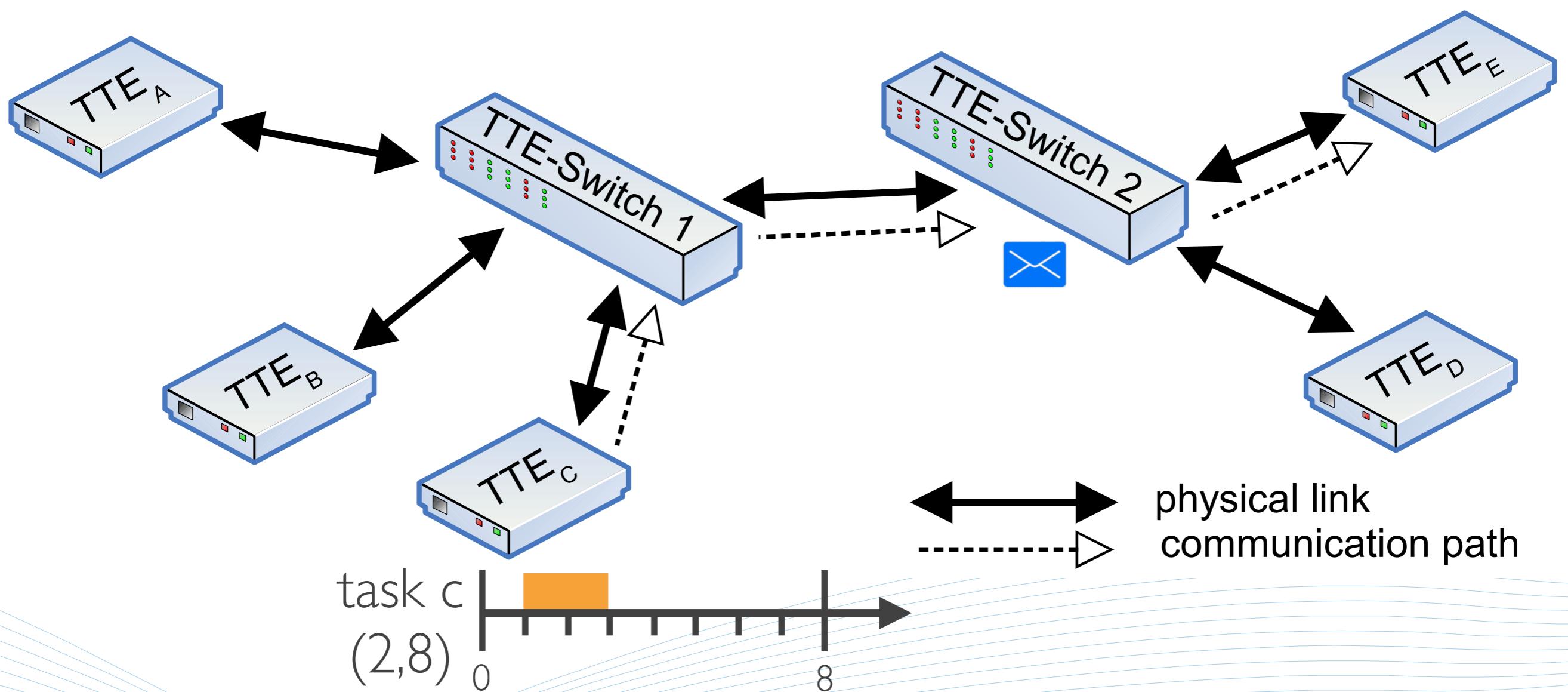
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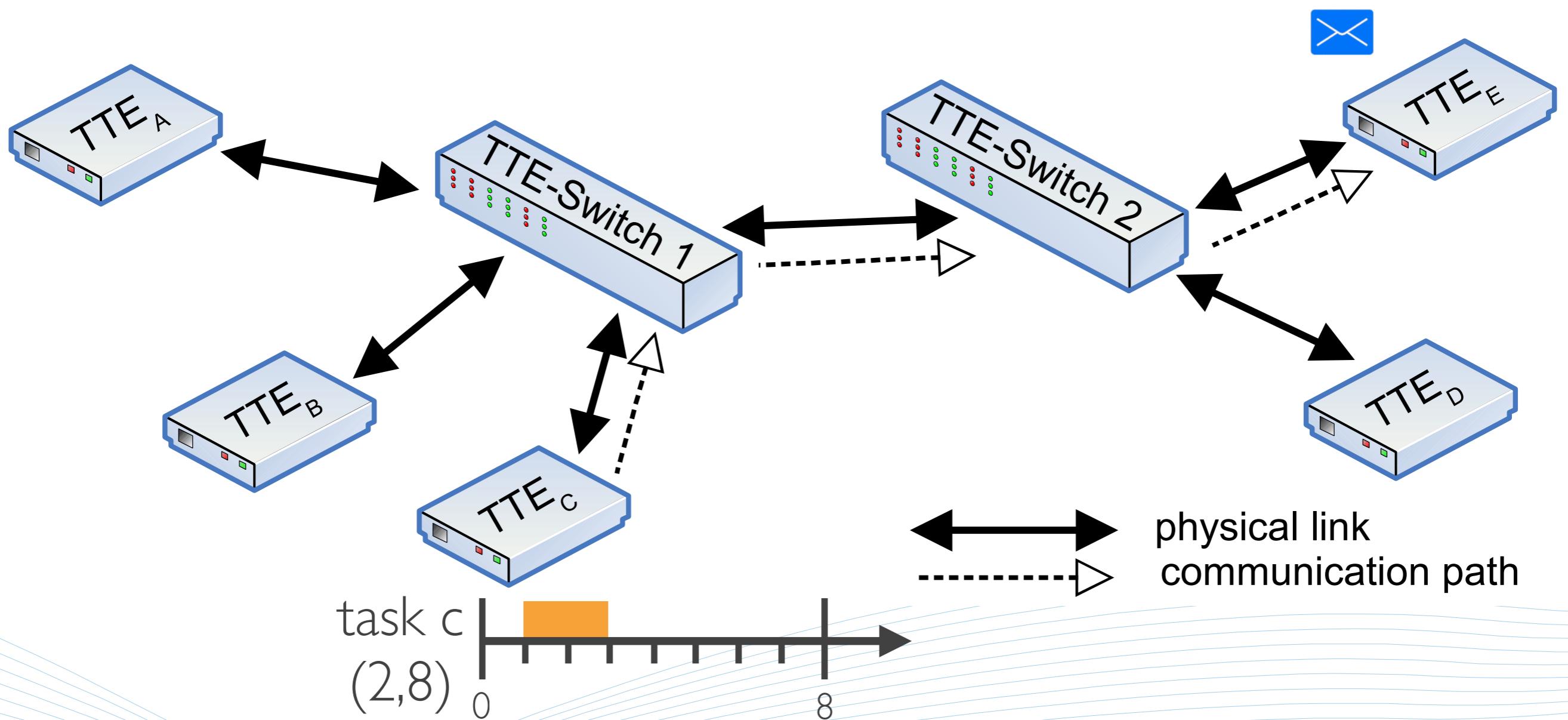
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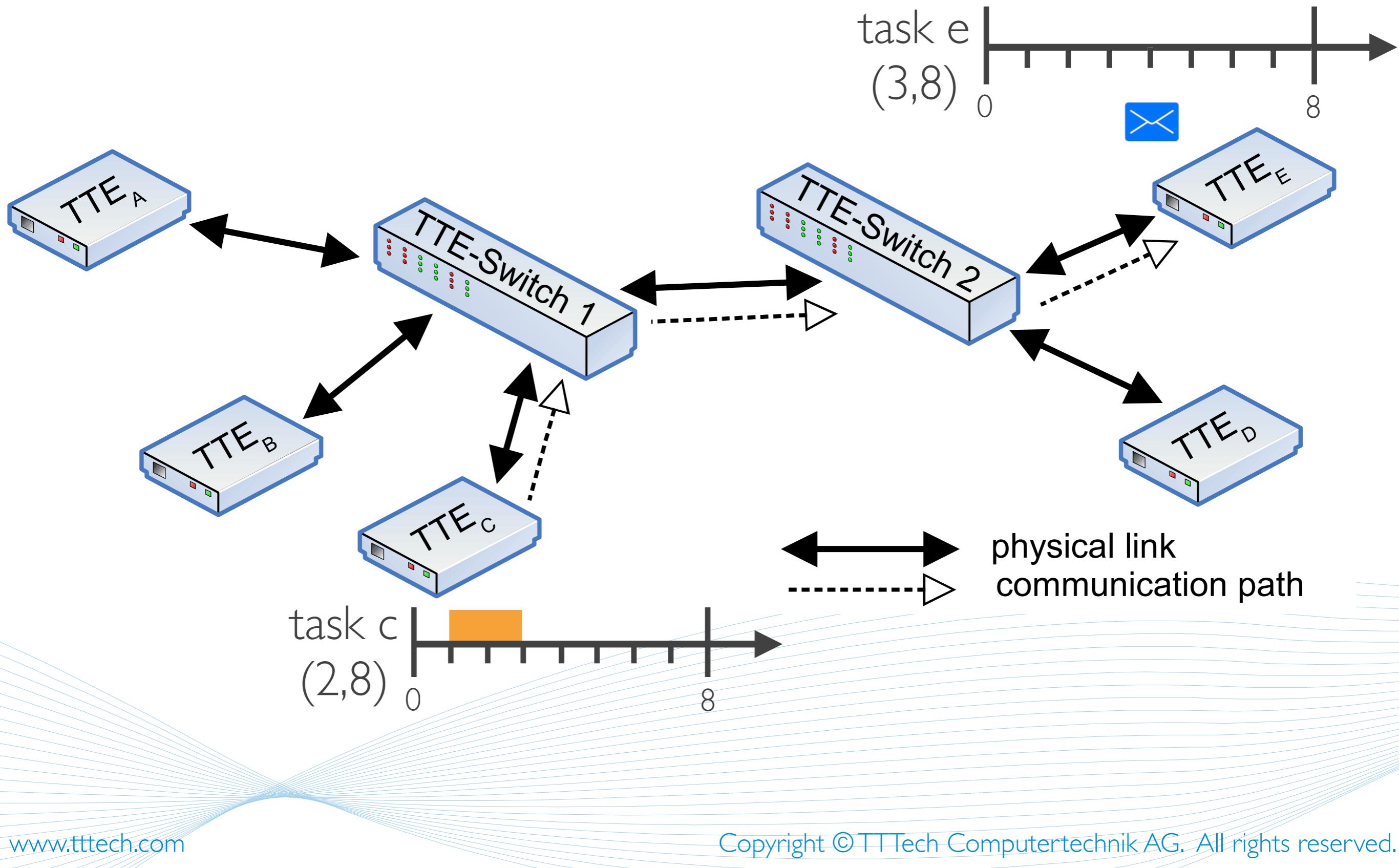
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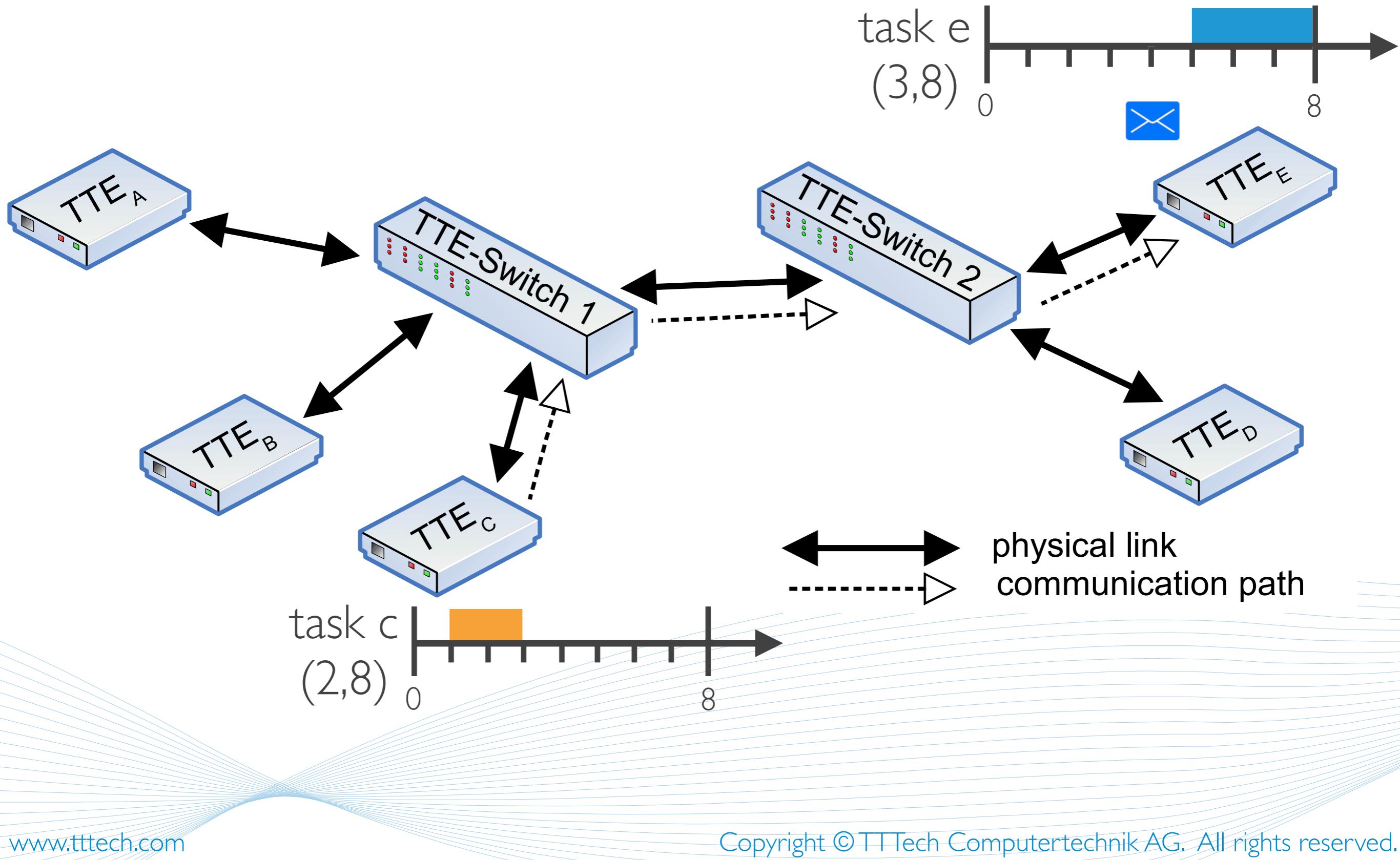
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Time triggered communication

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Ensuring Reliable Networks



Scheduling

Scheduling

Sequential scheduling

- Network [[Steiner@RTSS10](#)] ▷ Tasks [[Craciunas@ETFA14](#)]
- Tasks ▷ Network [[Hanzalek@ECRTS09](#)]



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Combined scheduling



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Network model



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Network model



Task model



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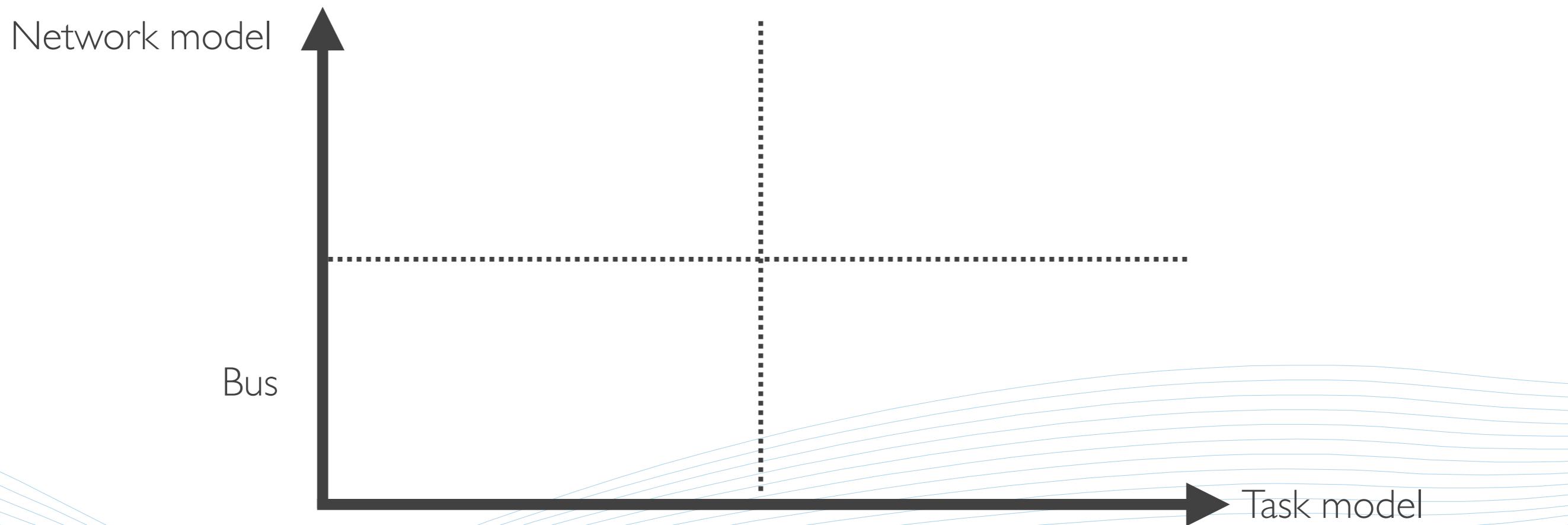
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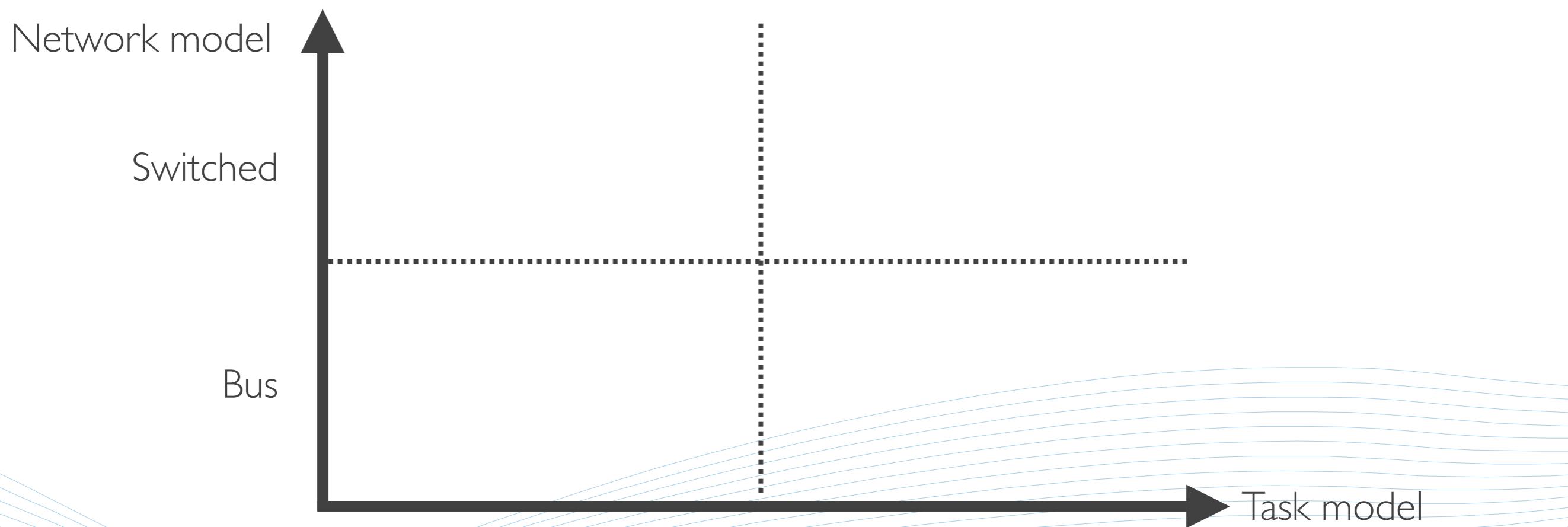


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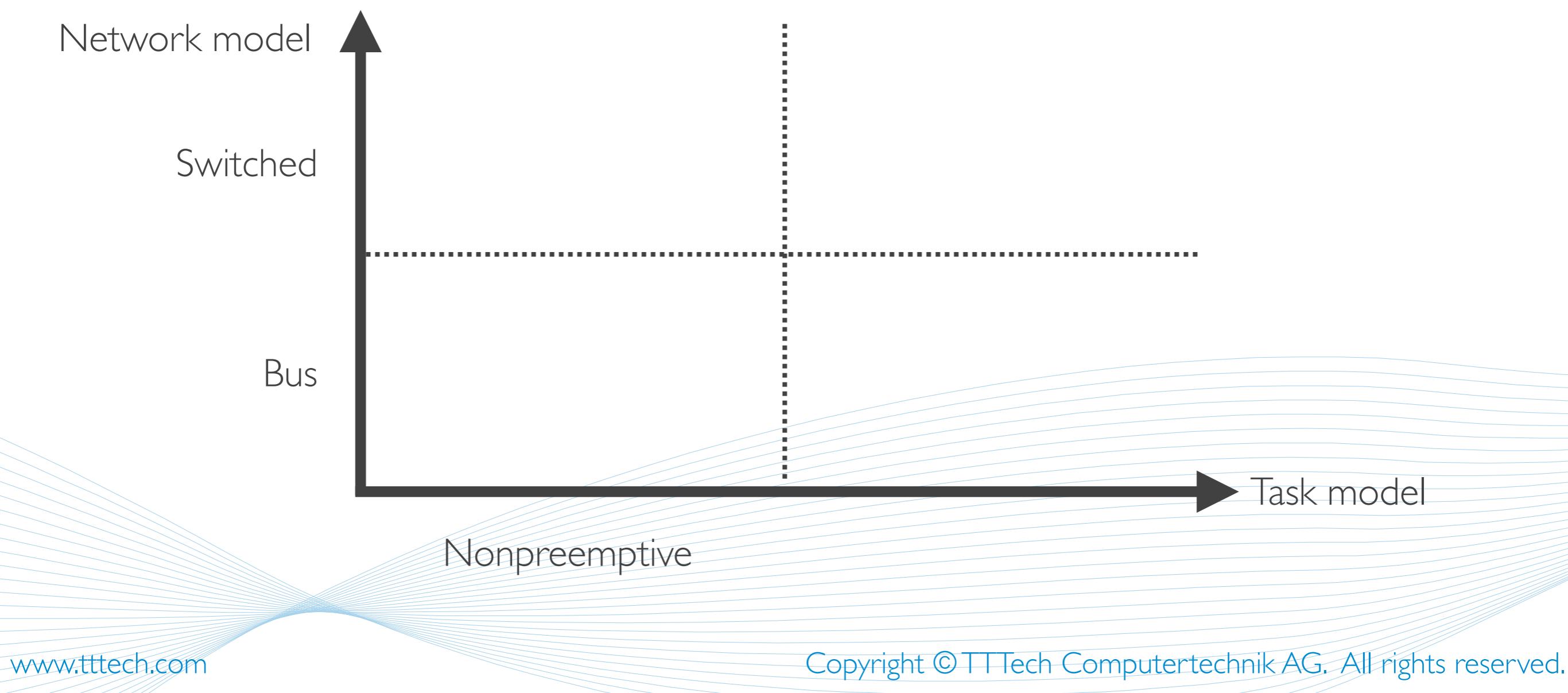


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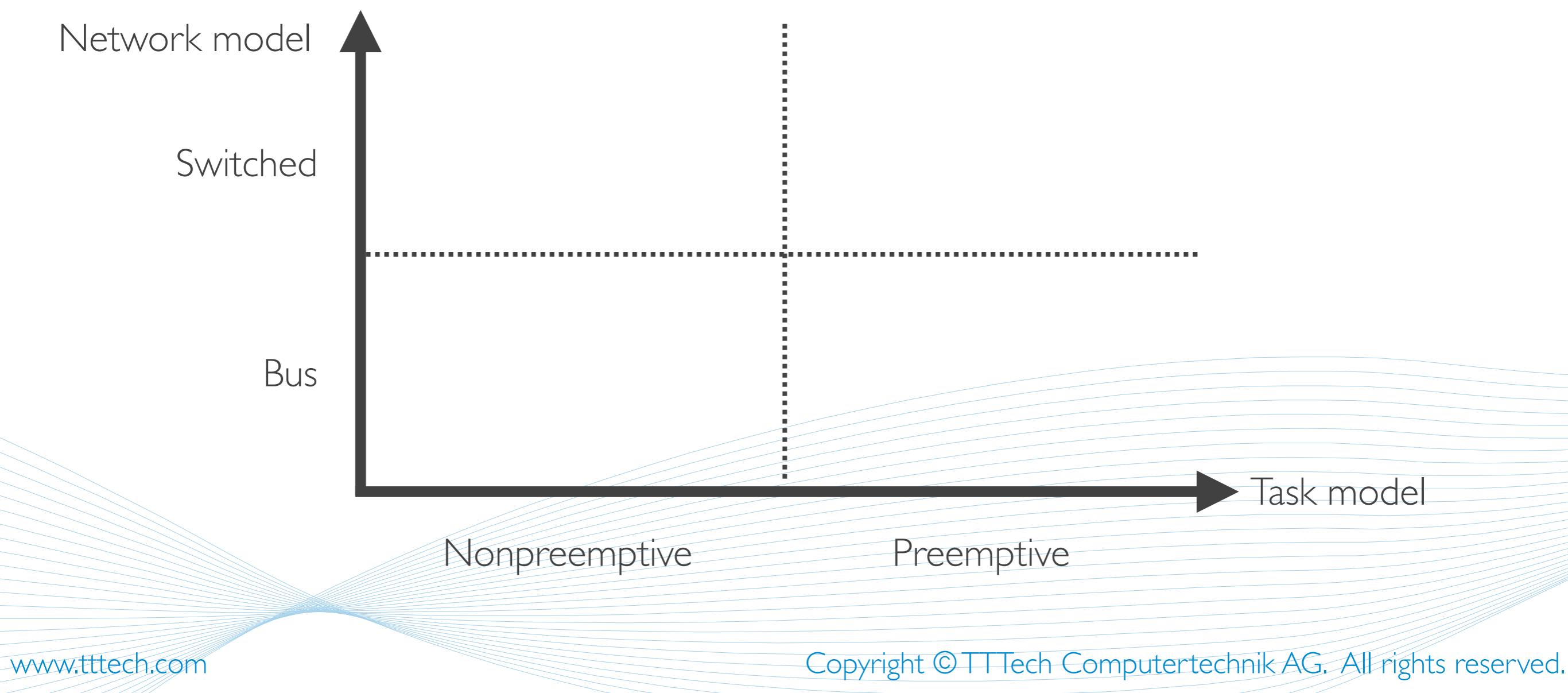


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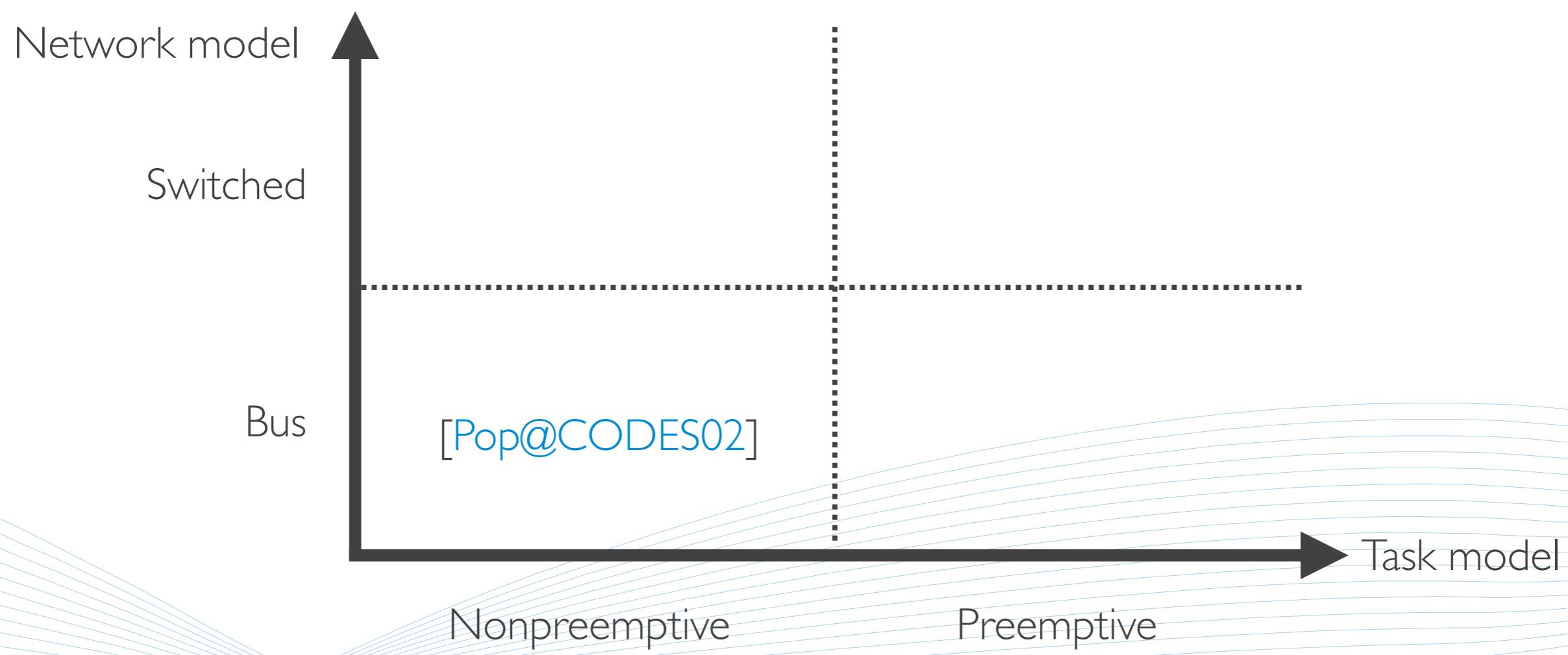


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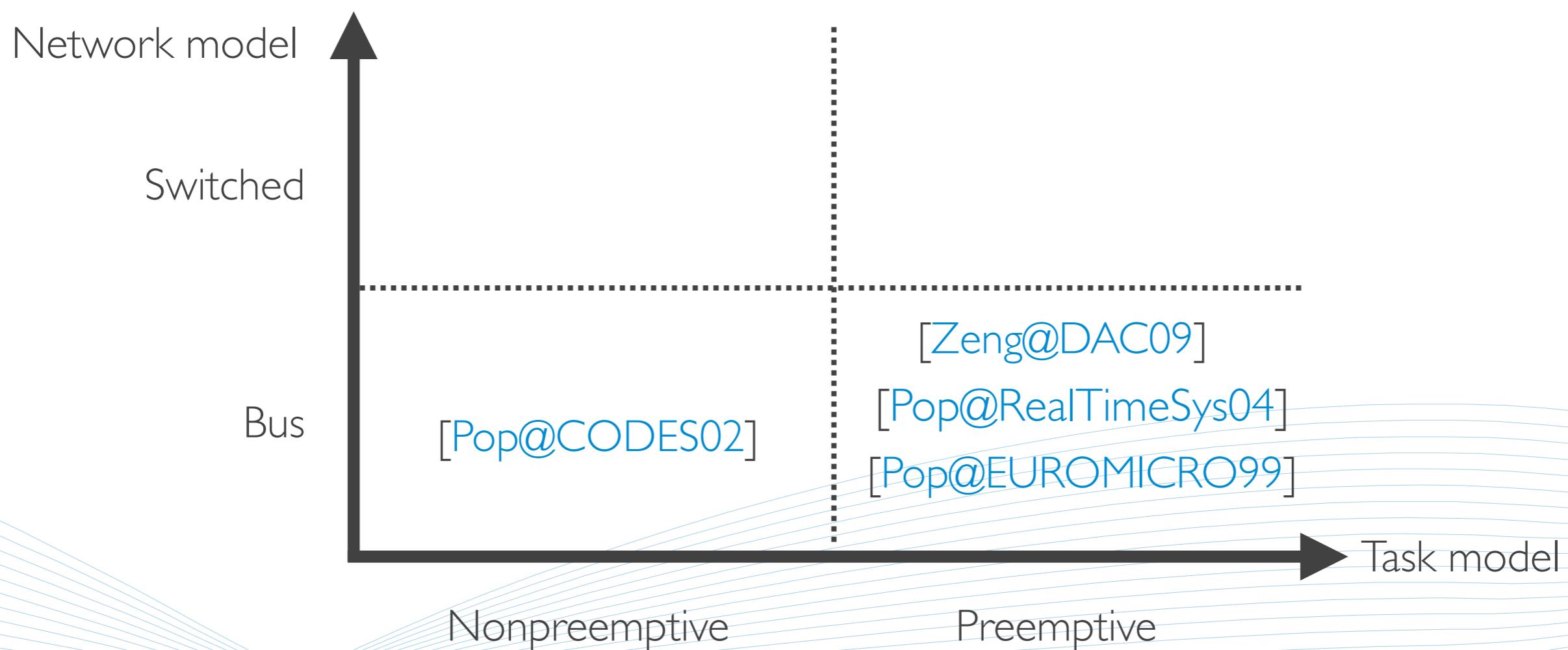


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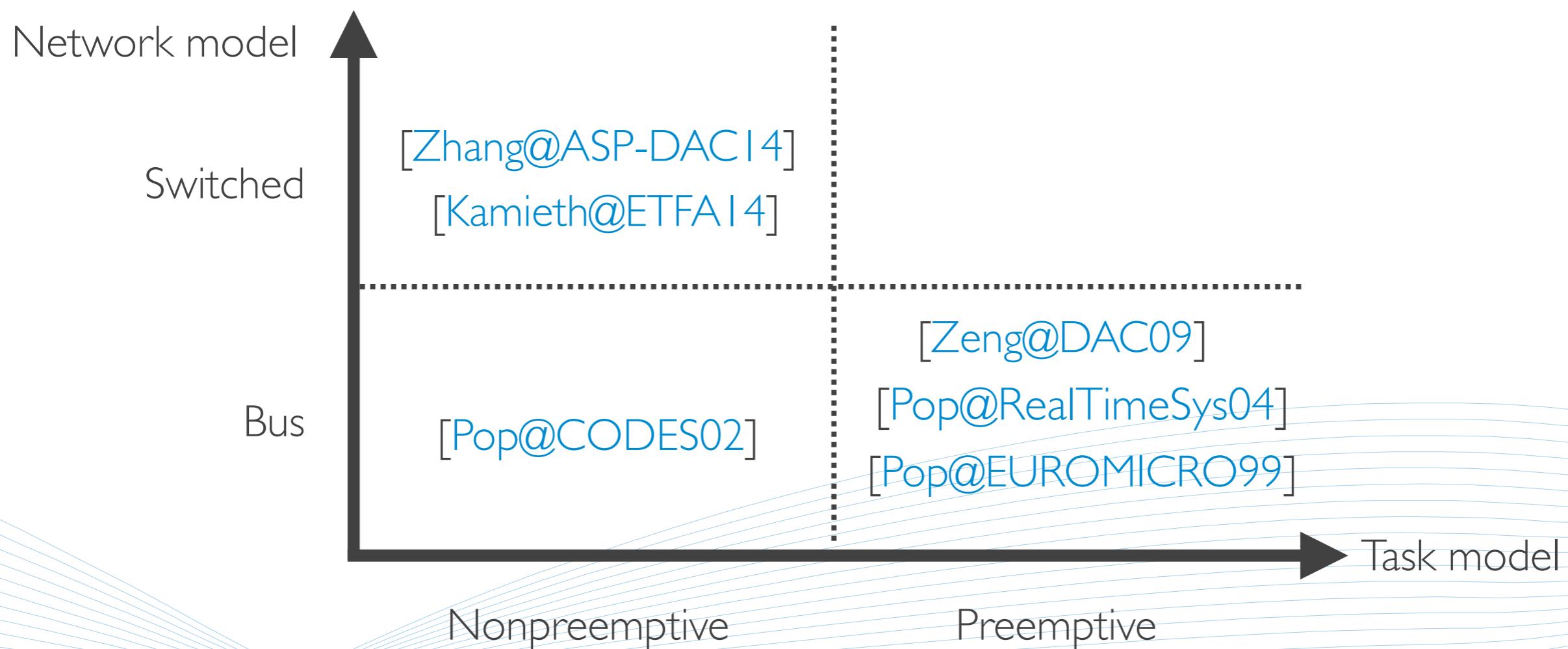


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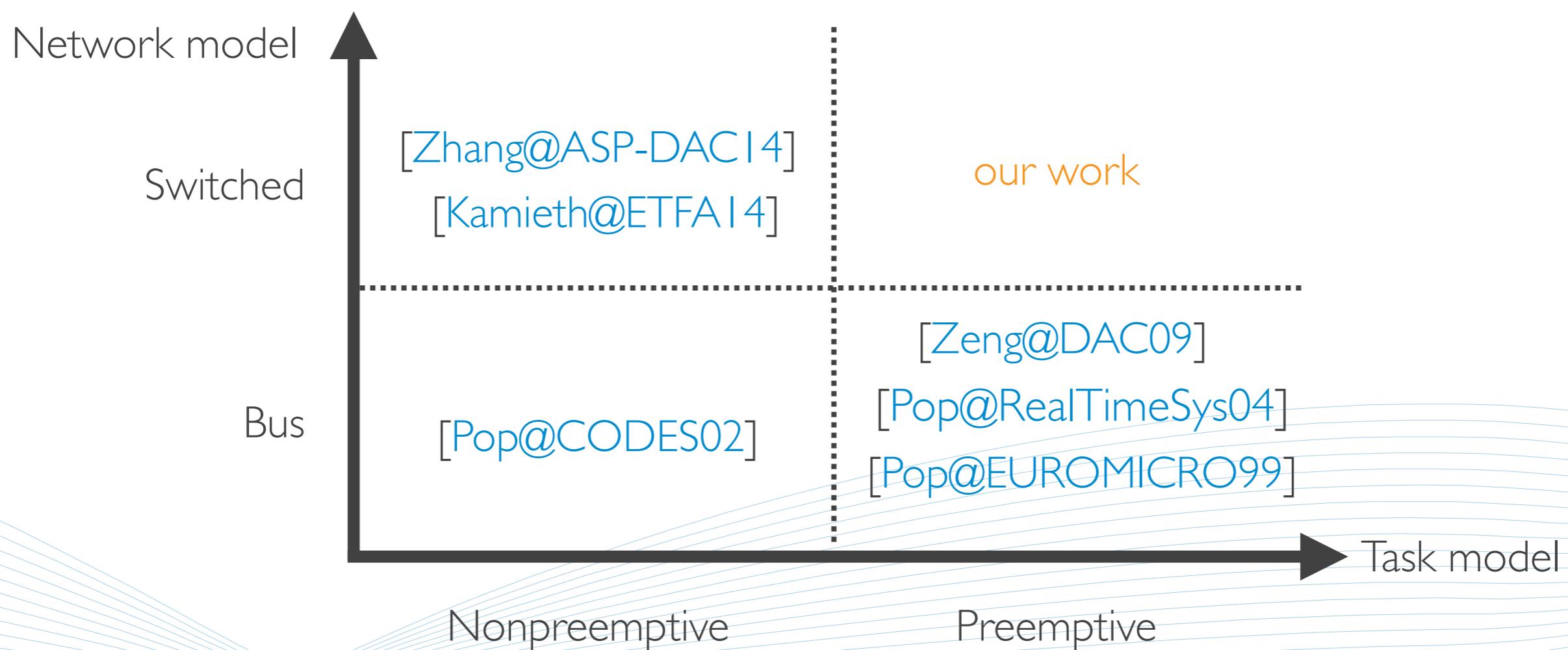


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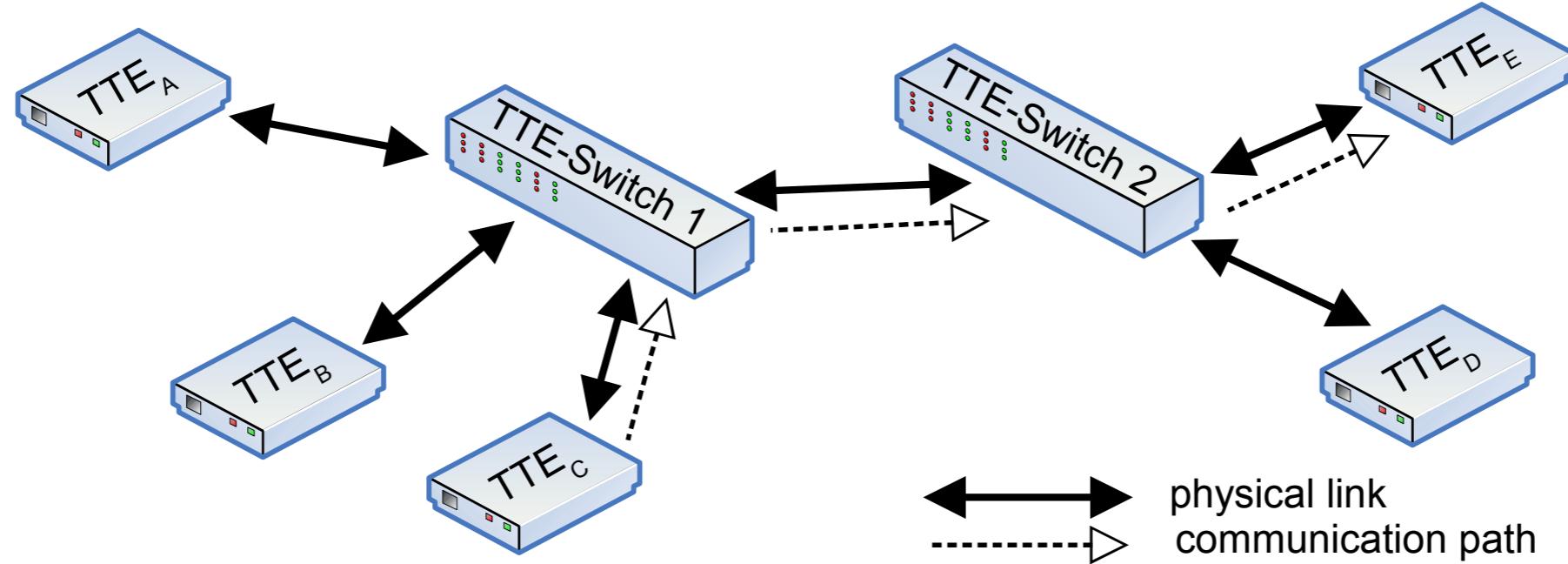
Combined scheduling



Network model

Ensuring Reliable Networks

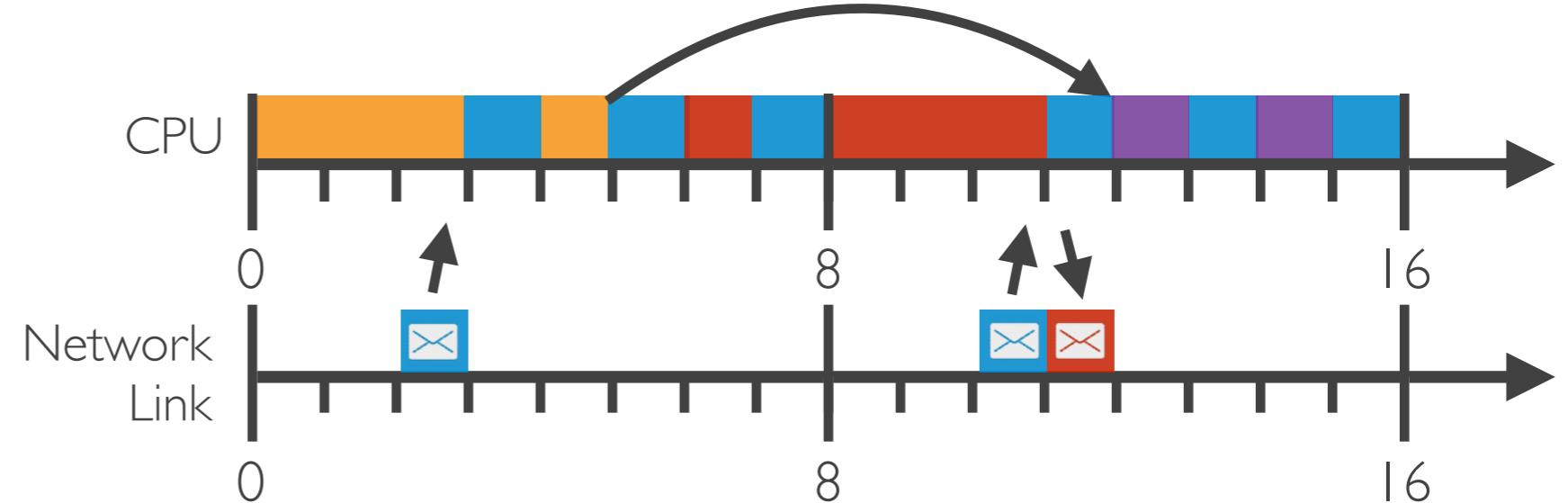
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- multi-hop layer 2 switched network via full-duplex multi-speed links
- virtual links (ARINC 664 P-7)
- TT-traffic class (RC [Tamas-Selicean@CODES+ISSI12], BE)
- synchronised time (< 1 used precision)
- link delay for each link
- memory buffers on switches

Task model

free		(0, 4, 16, 16)
consumer		(3, 3, 8, 6)
producer		(5, 4, 16, 6)
free		(12, 2, 16, 3)



- periodic asynchronous TT-tasks (offset ϕ , wcet C, period T, deadline D)
- static time-driven schedule with preemption
- 3 types of tasks (producer, consumer, free)
- macrotick on ES (usec - ms)
- communication at beginning/end of consumer/producer ([Derler@CITI0])
- end-to-end latency, dependencies between tasks

Networked system model

Ensuring Reliable Networks

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Network

$$G(\mathcal{V}, \mathcal{L}) \quad \mathcal{L} \subseteq \mathcal{V} \times \mathcal{V}$$

$$\forall [v_a, v_b] \in \mathcal{L} \Rightarrow [v_b, v_a] \in \mathcal{L}$$

Network links

$$[v_a, v_b]$$

(speed, link delay, macrotick, memory buffer)

CPU self-links

$$[v_a, v_a]$$

Virtual link - dataflow from one producer to one receiver

$$vl_i = [[v_a, v_a], [v_a, v_1], [v_1, v_2], \dots, [v_{n-1}, v_n], [v_n, v_b], [v_b, v_b]].$$

Ensuring Reliable Networks



Frames

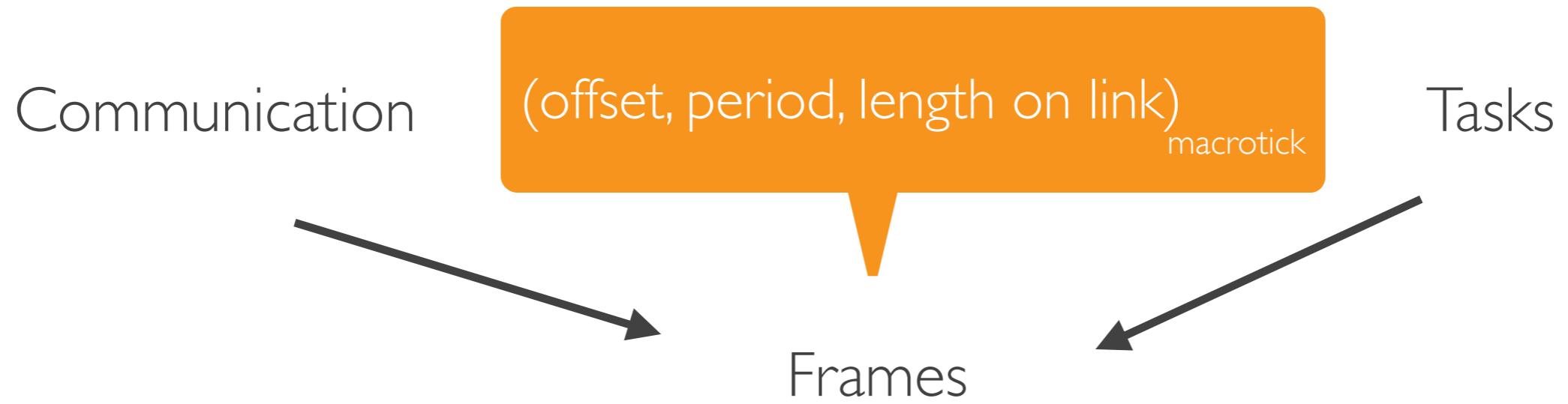
Frames

Communication

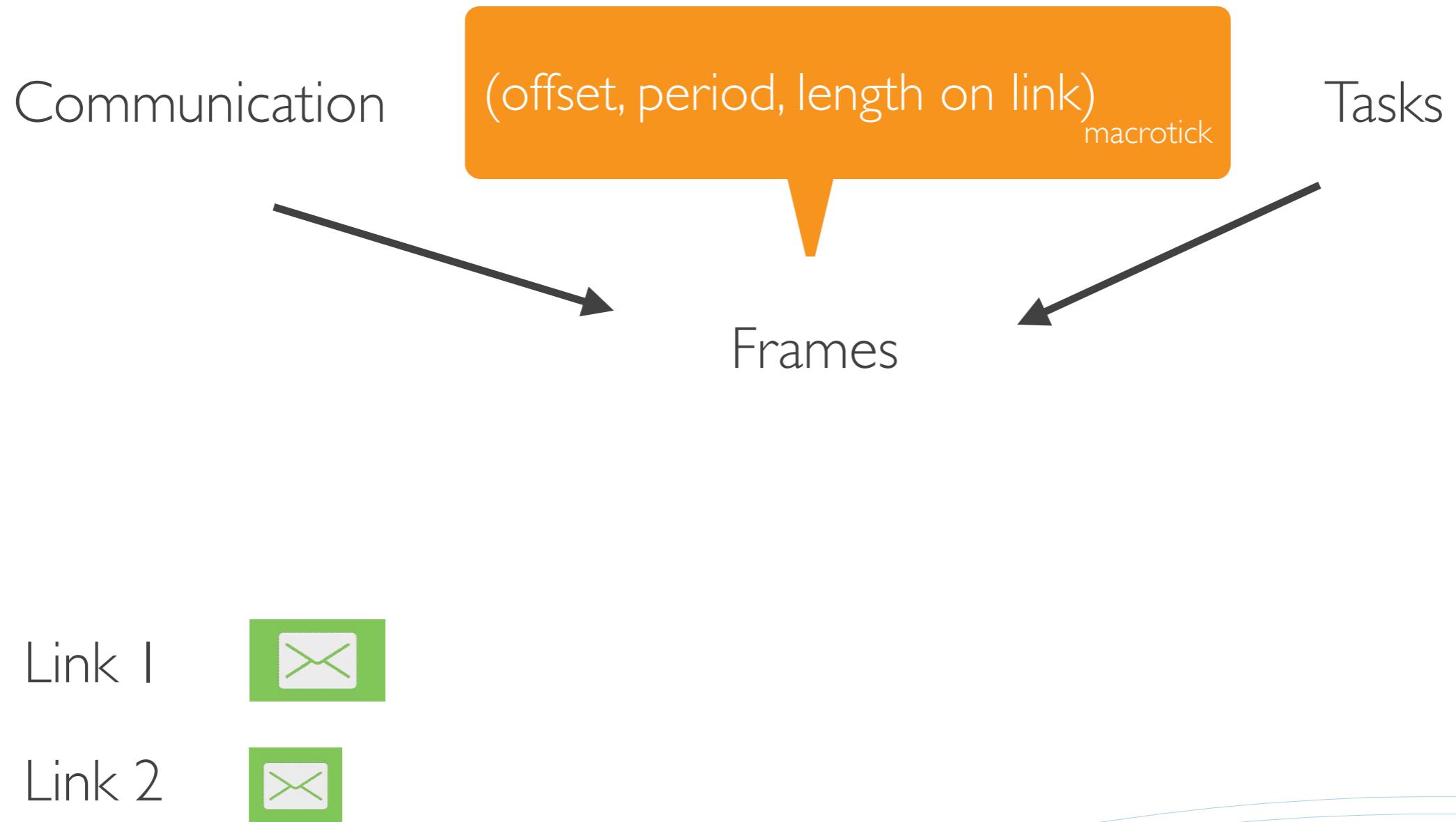
Tasks



Frames



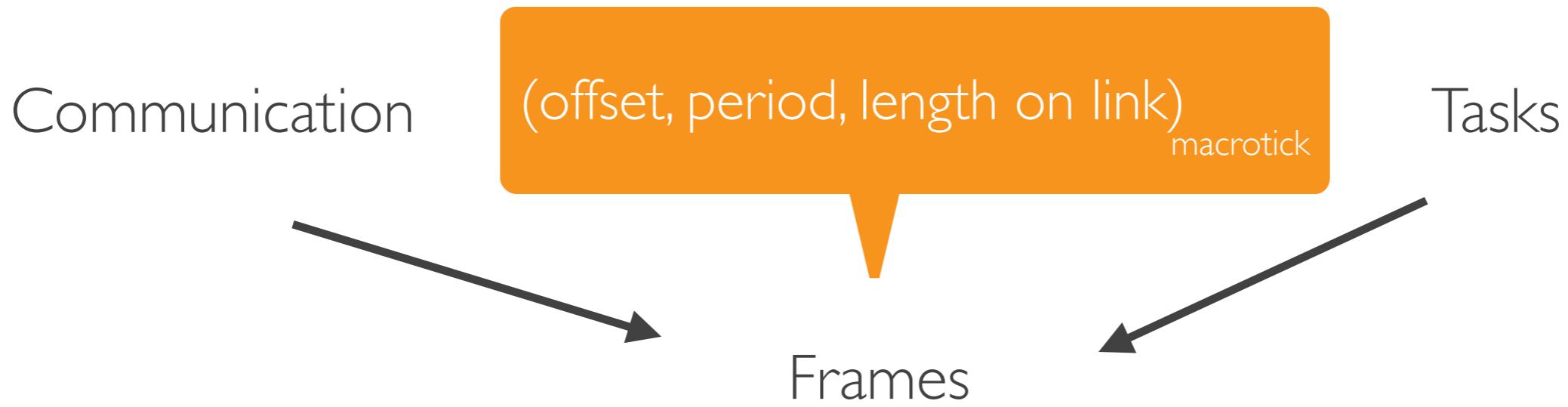
Frames



Frames

Ensuring Reliable Networks

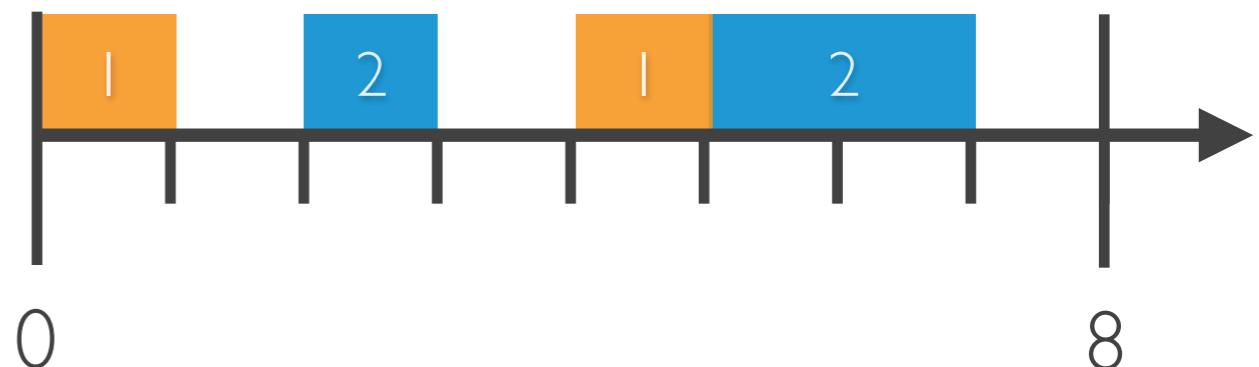
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Link 1



Link 2



Task 1



Task 2



Scheduling problem



Scheduling problem

Ensuring Reliable Networks



find **offsets** for the frames (on links and virtual task frames)



Scheduling problem

find **offsets** for the frames (on links and virtual task frames)

reduces to finding a solution for a set of constraints

- frame constraints
- link constraints
- virtual link constraints
- memory constraints
- end-to-end latency constraints
- precedence constraints



Scheduling problem

find **offsets** for the frames (on links and virtual task frames)

reduces to finding a solution for a set of constraints

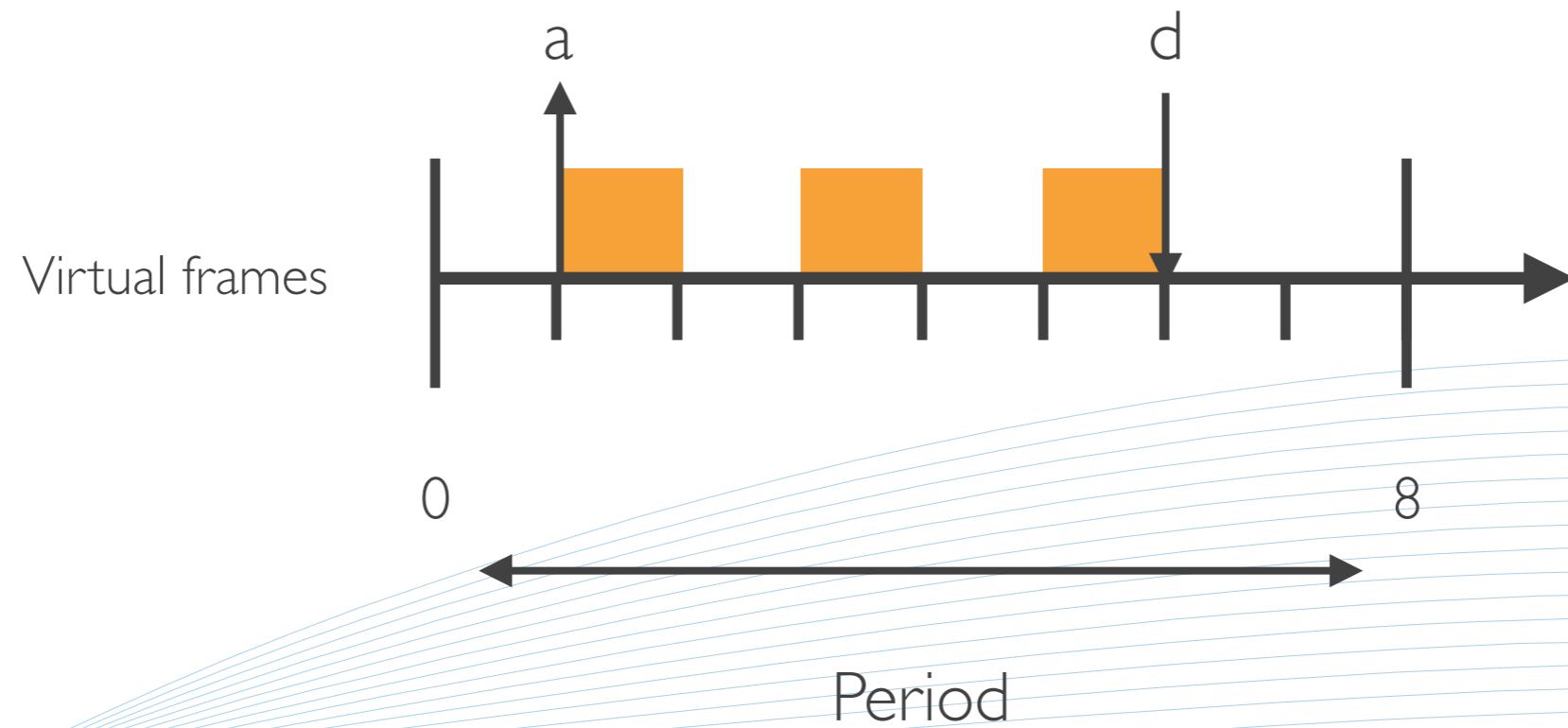
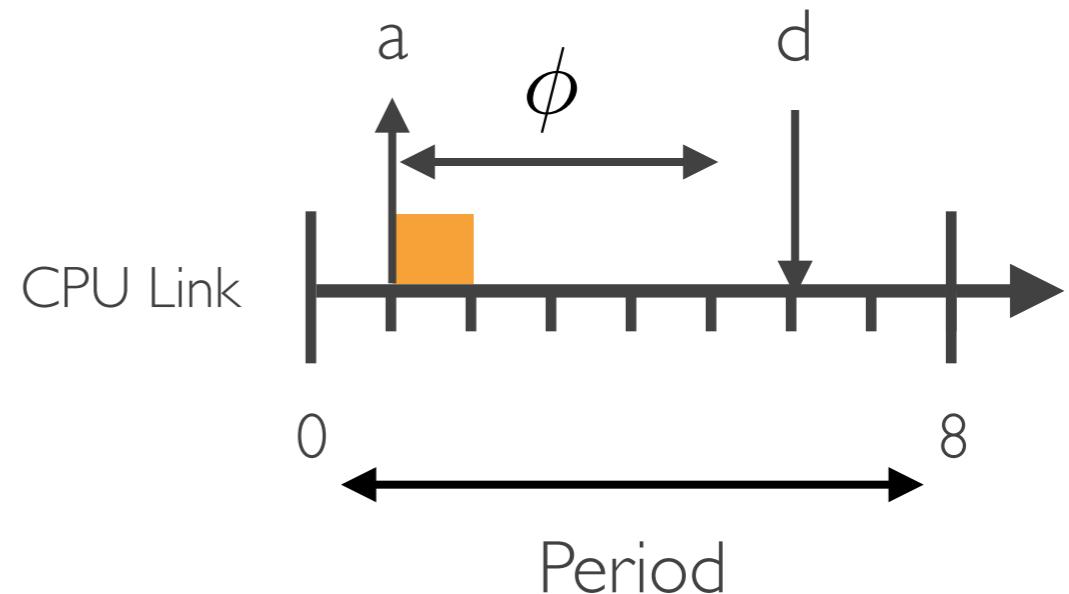
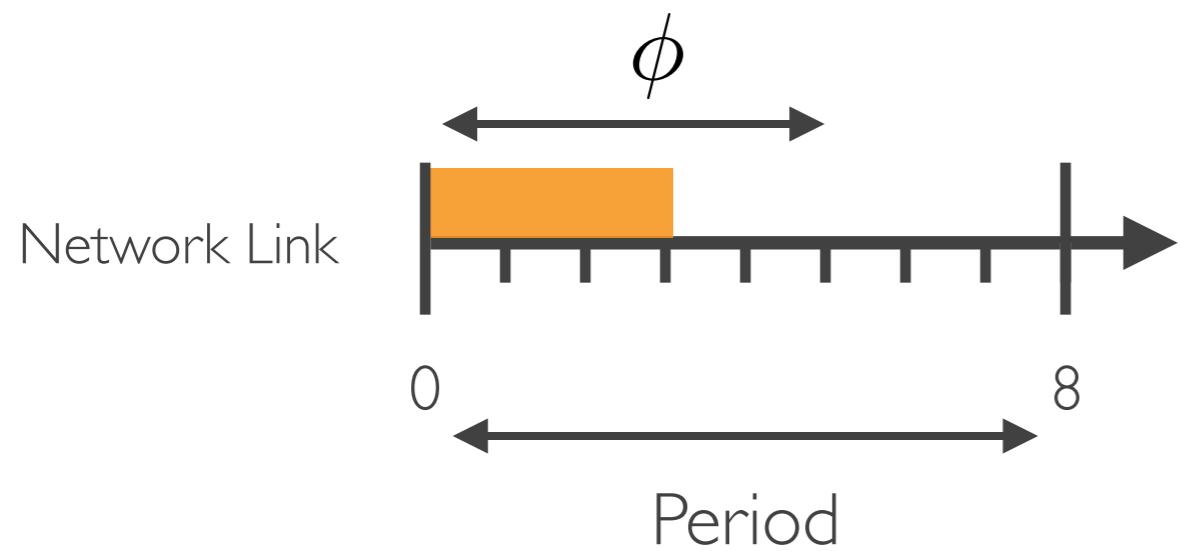
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NP-complete

Frame constraints

Ensuring Reliable Networks

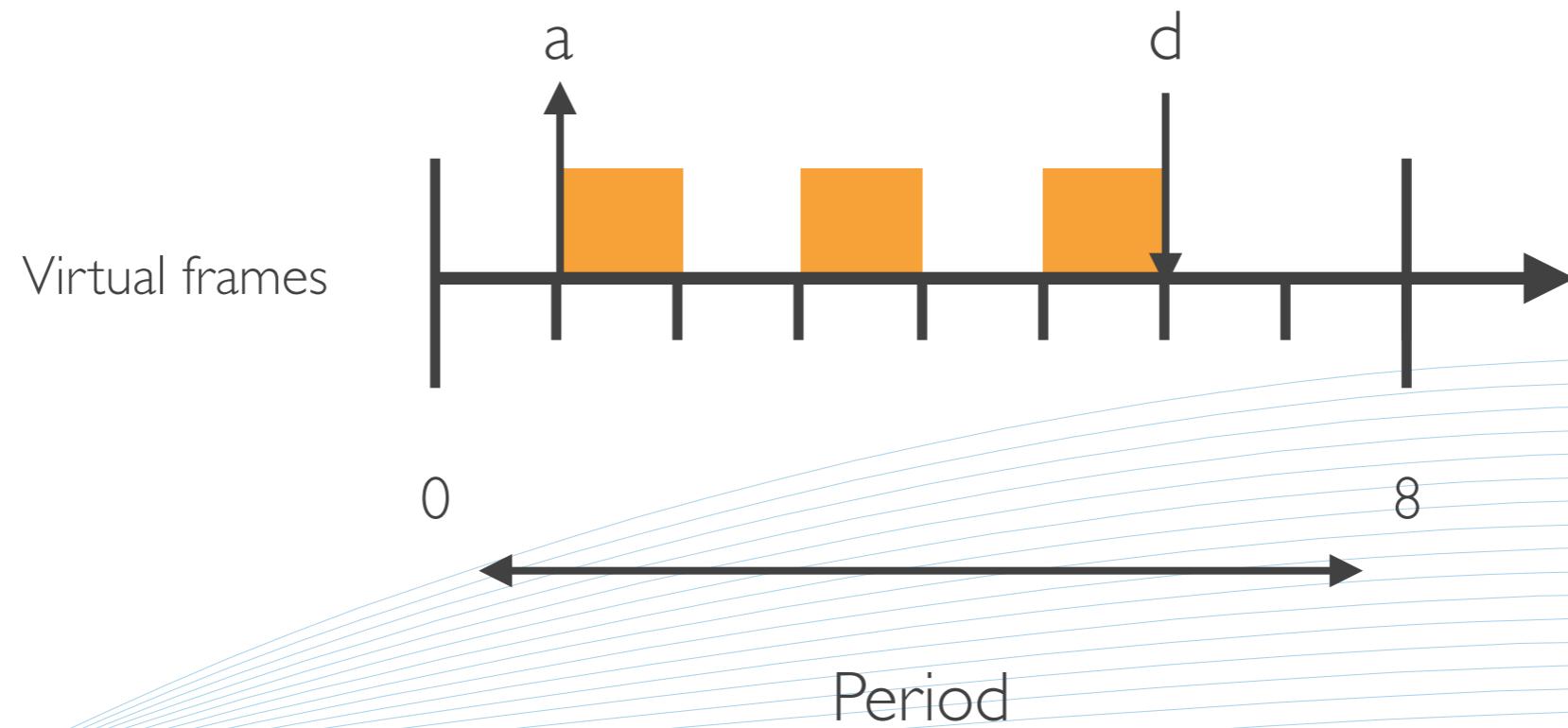
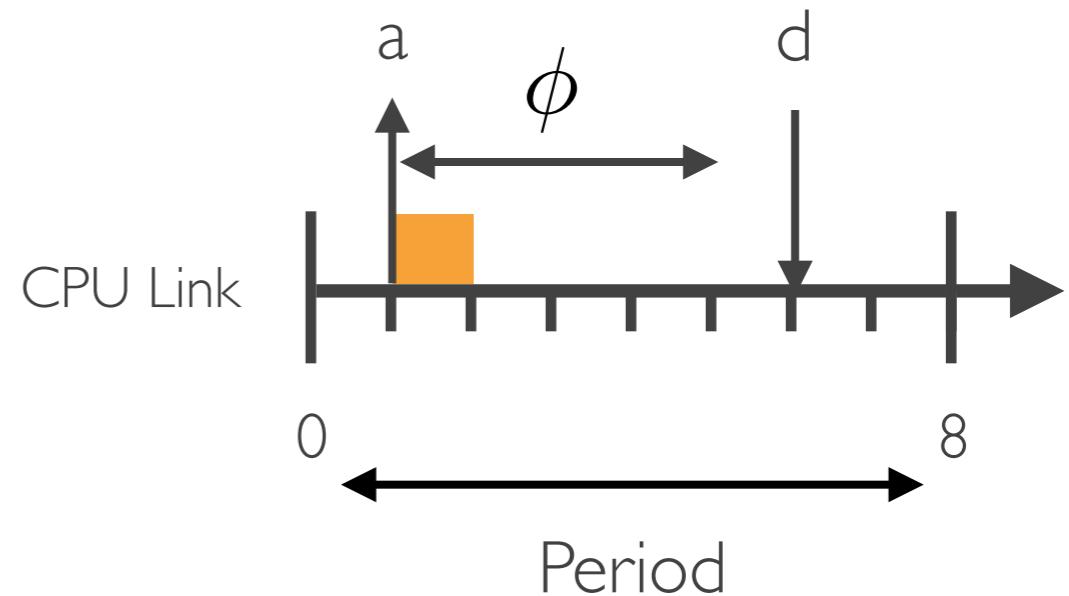
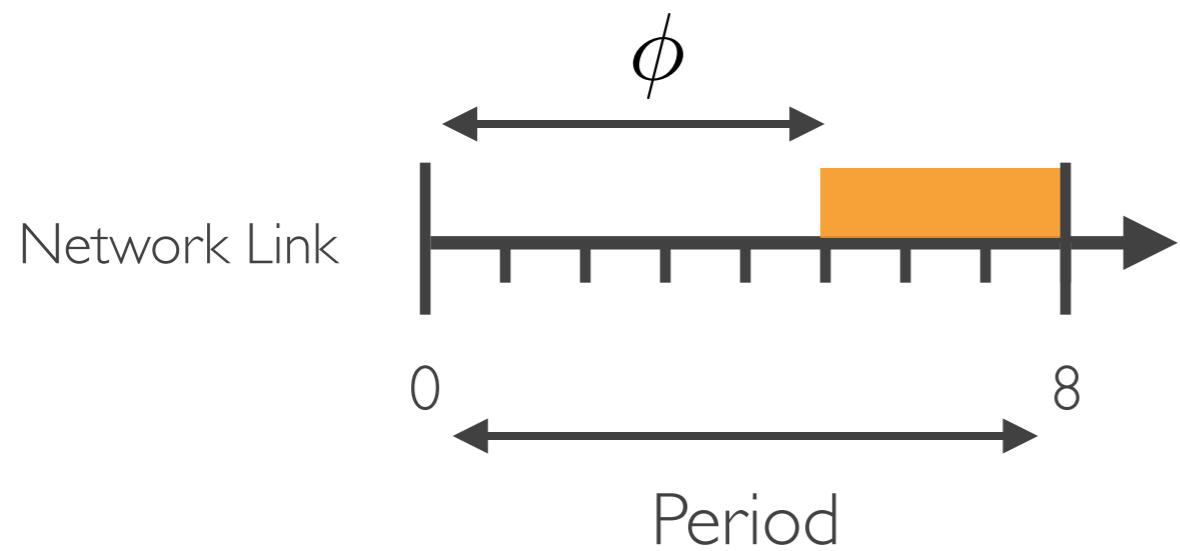
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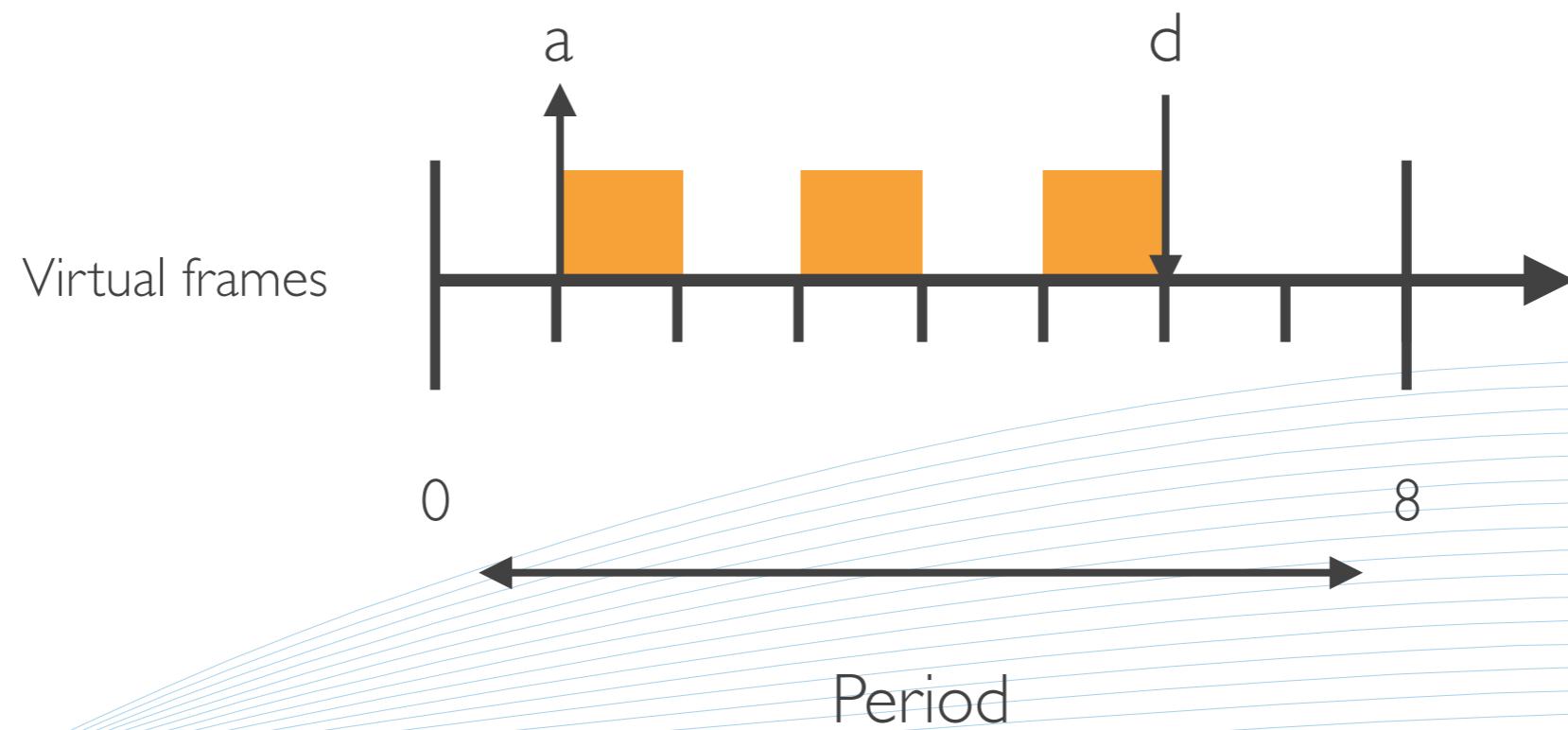
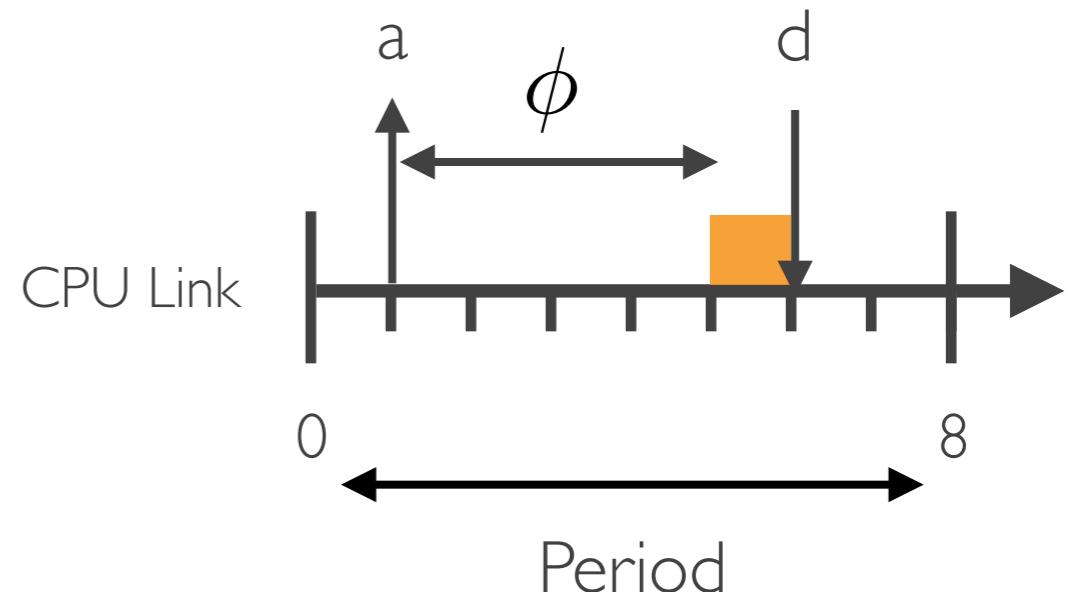
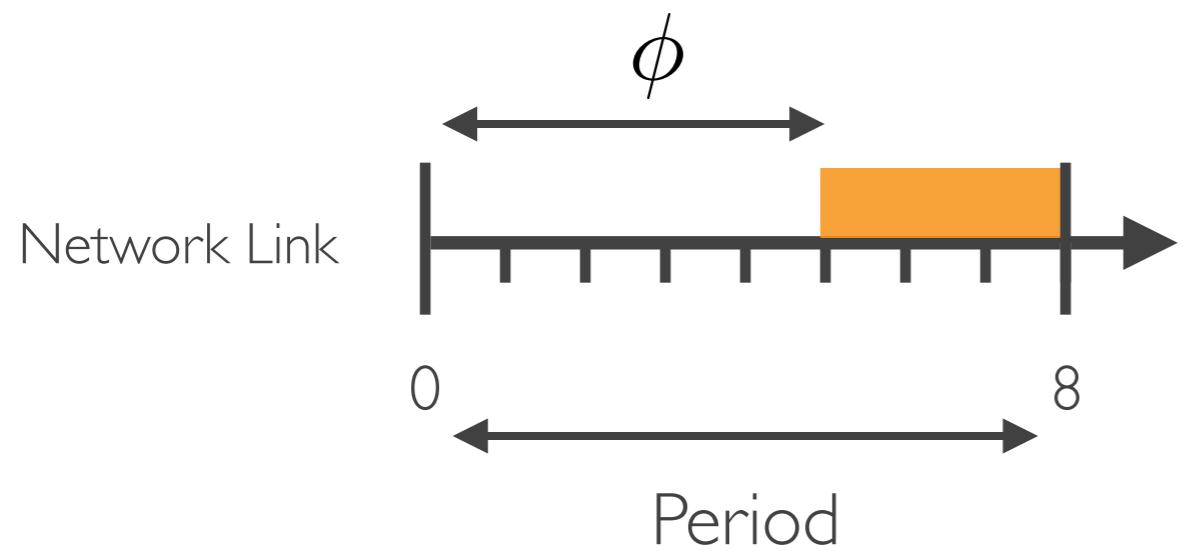
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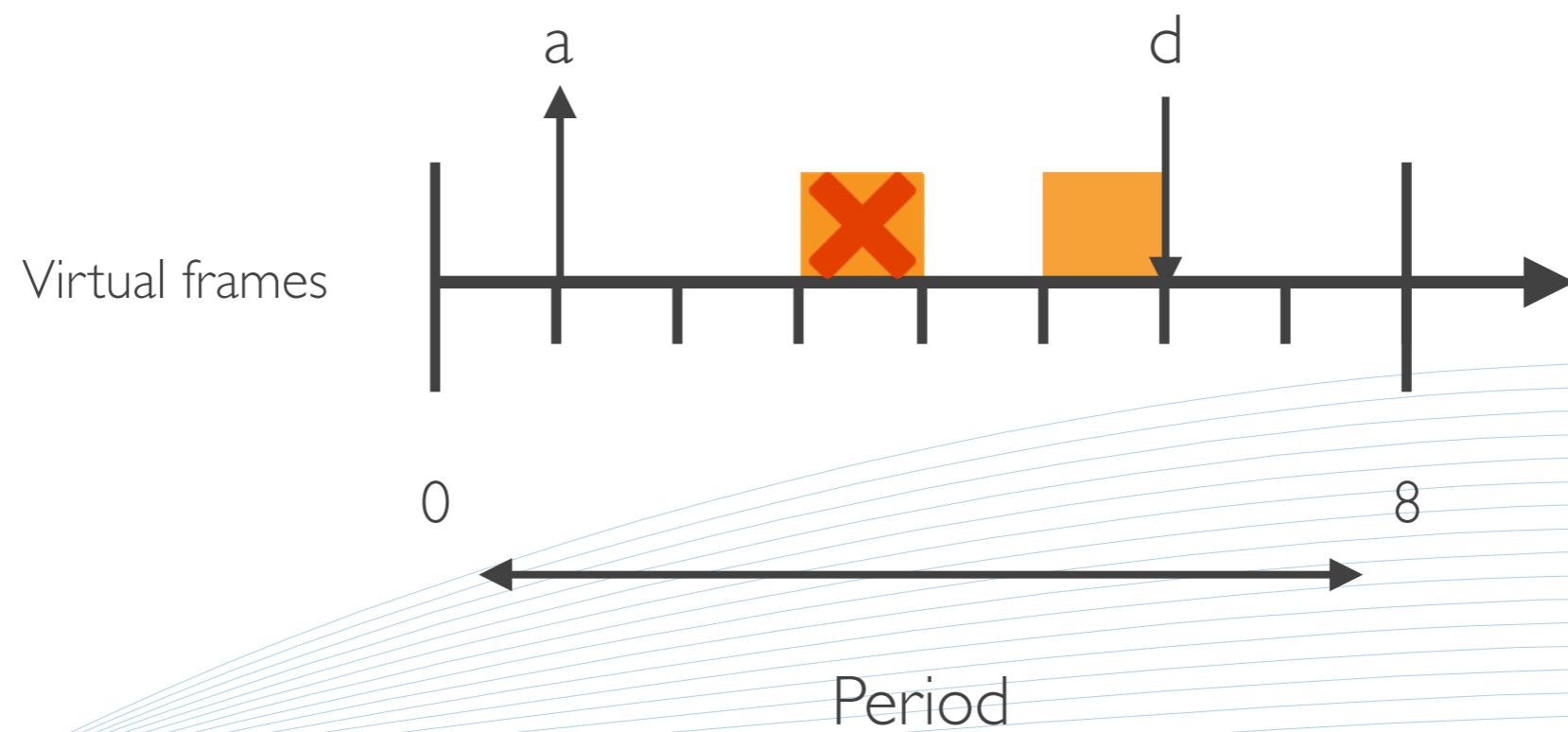
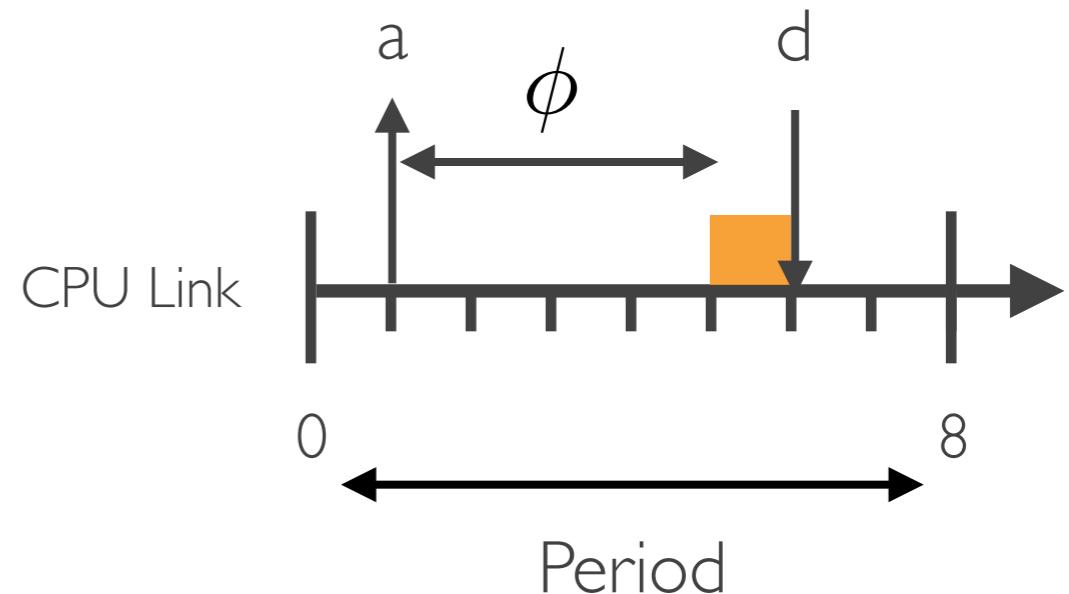
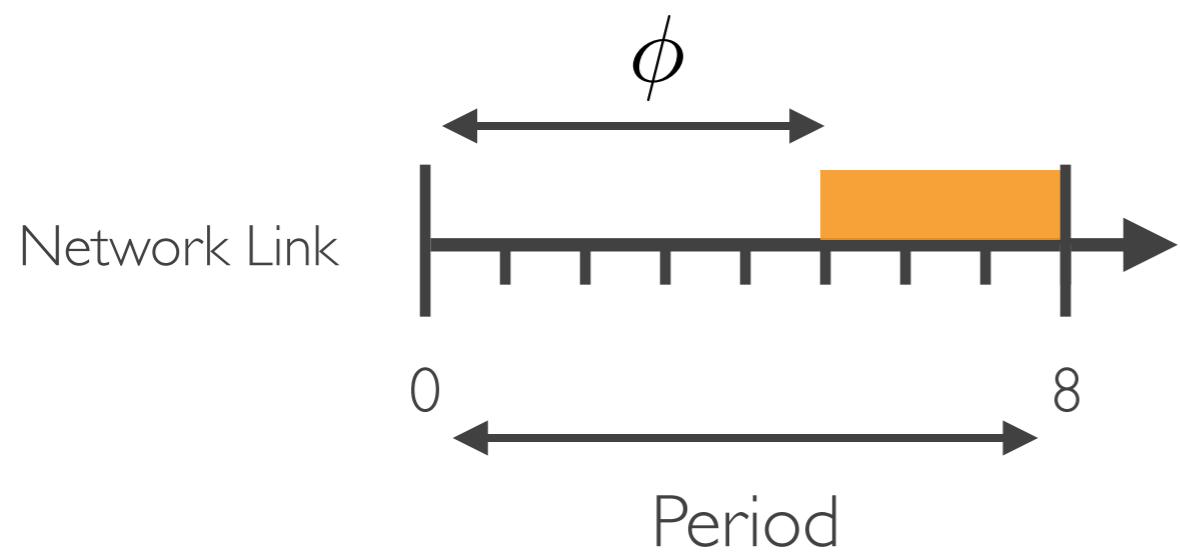
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Frame constraints



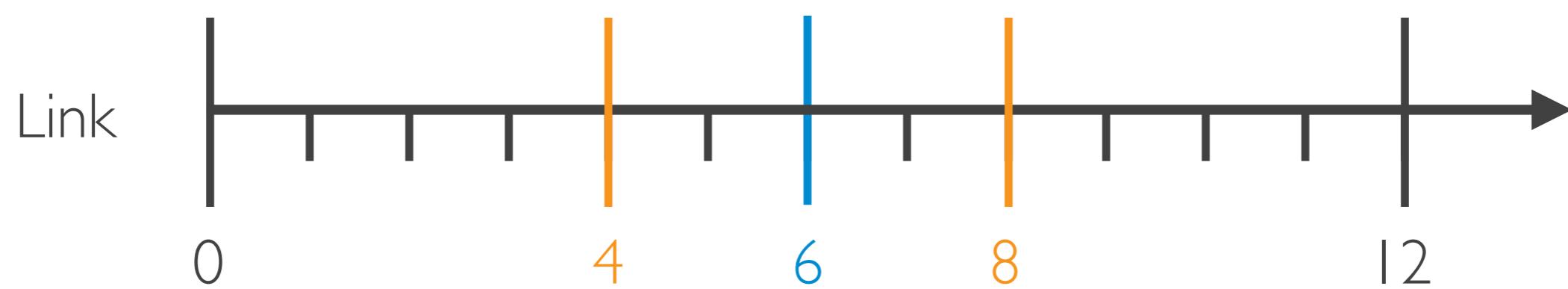
Frame constraints



Link constraints

Ensuring Reliable Networks

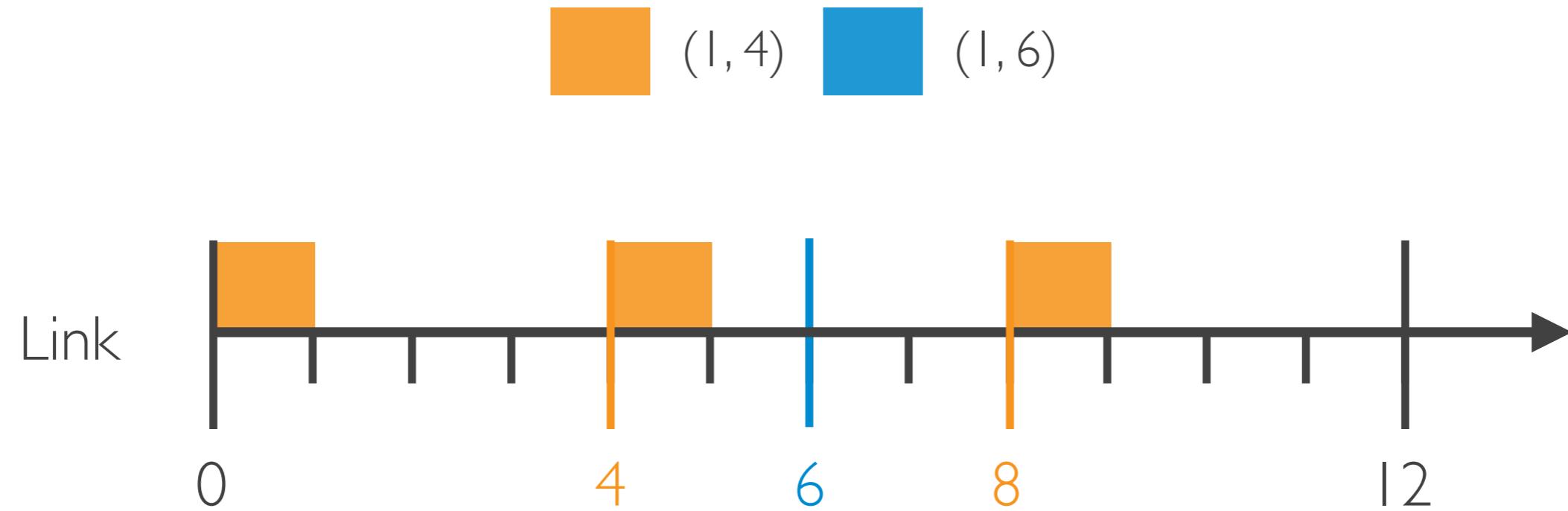
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Link constraints

Ensuring Reliable Networks

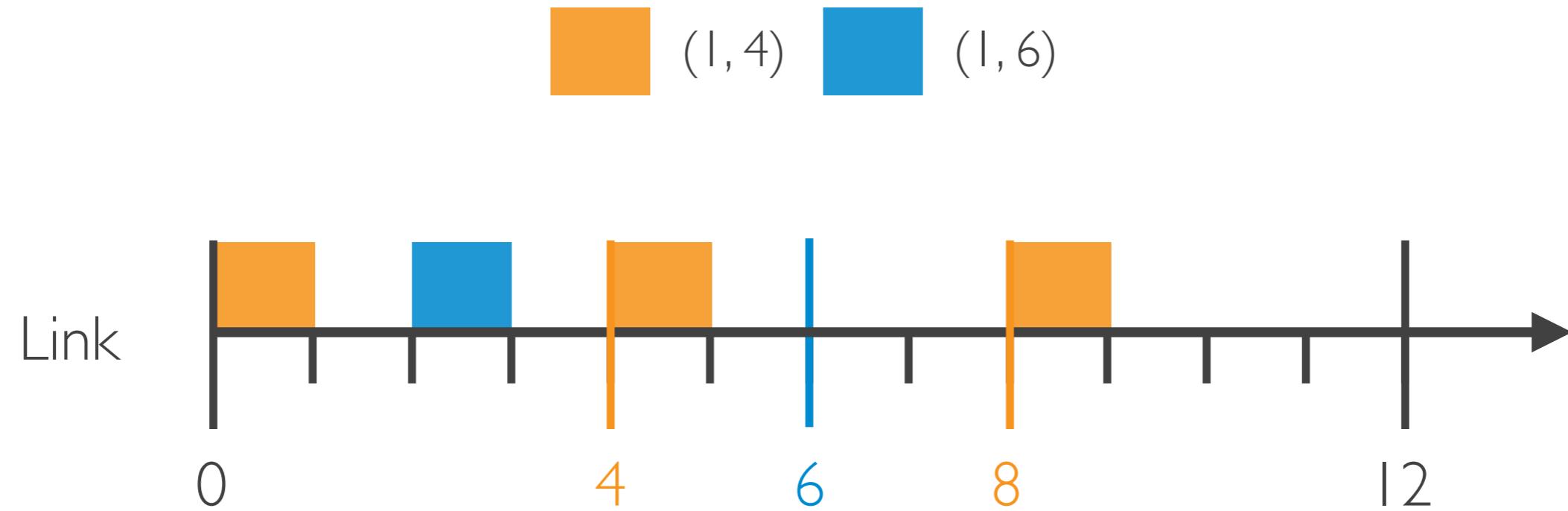
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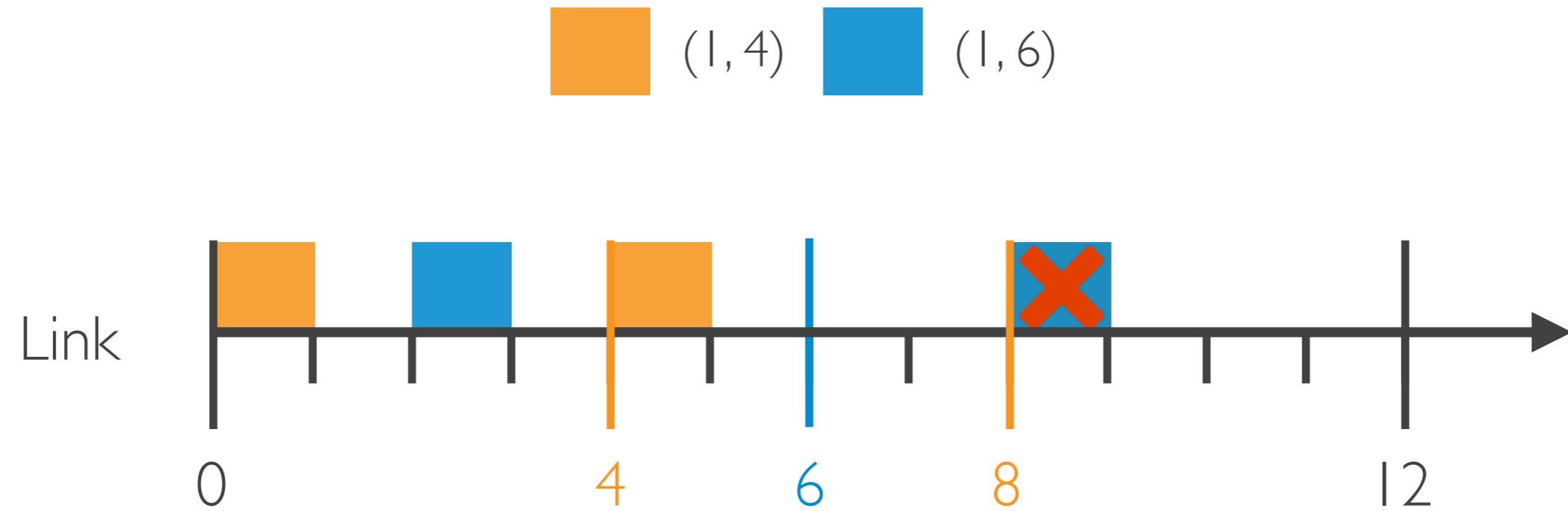
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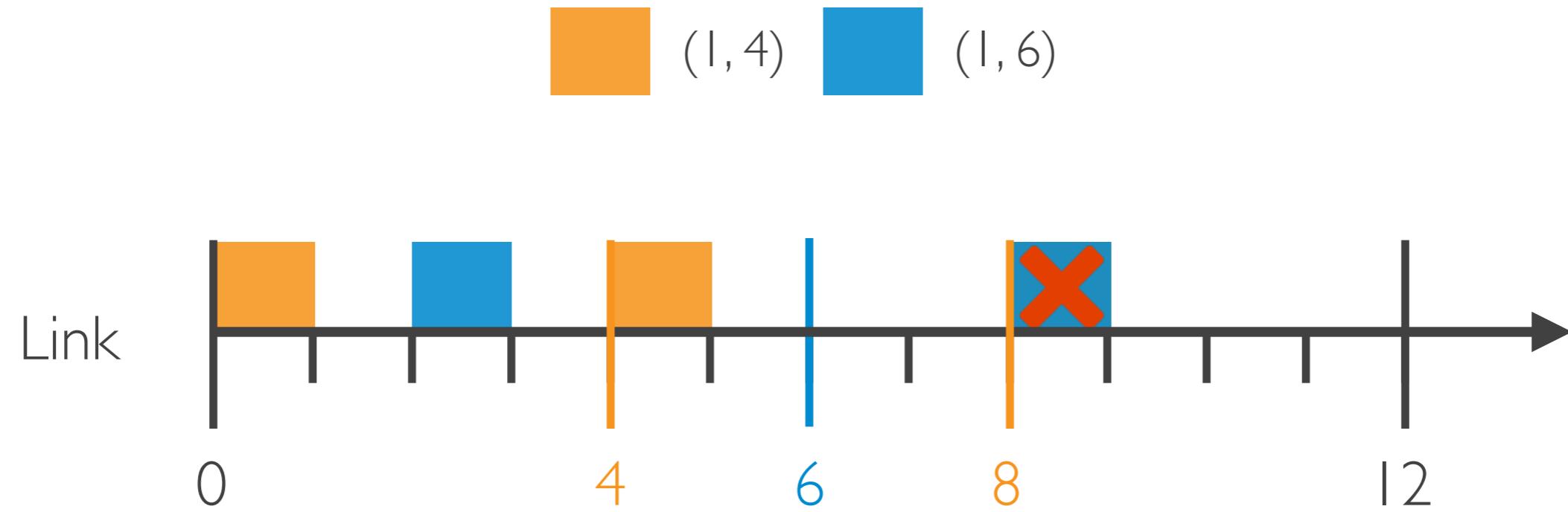
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Link constraints

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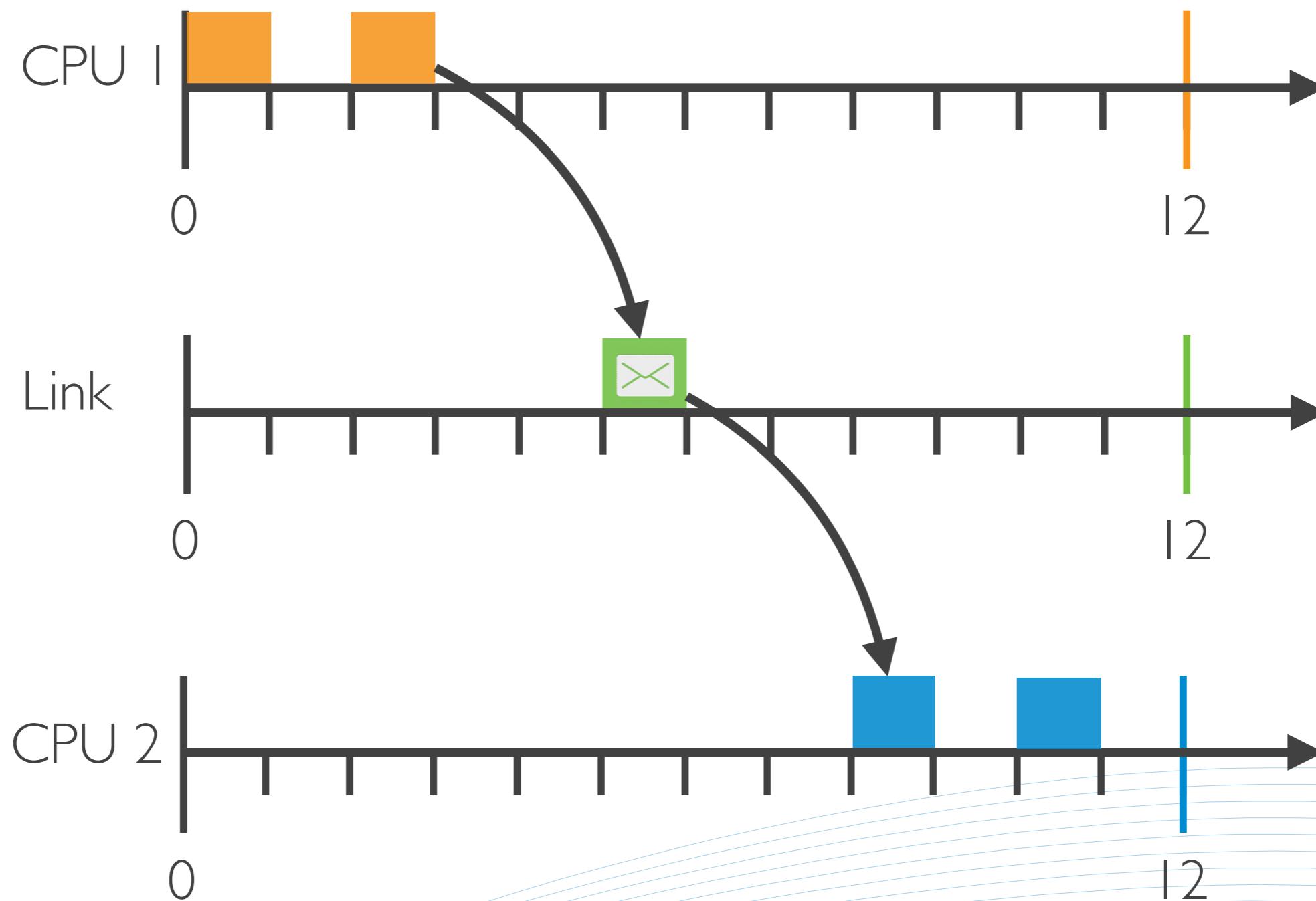


no two frames scheduled on the same link may overlap

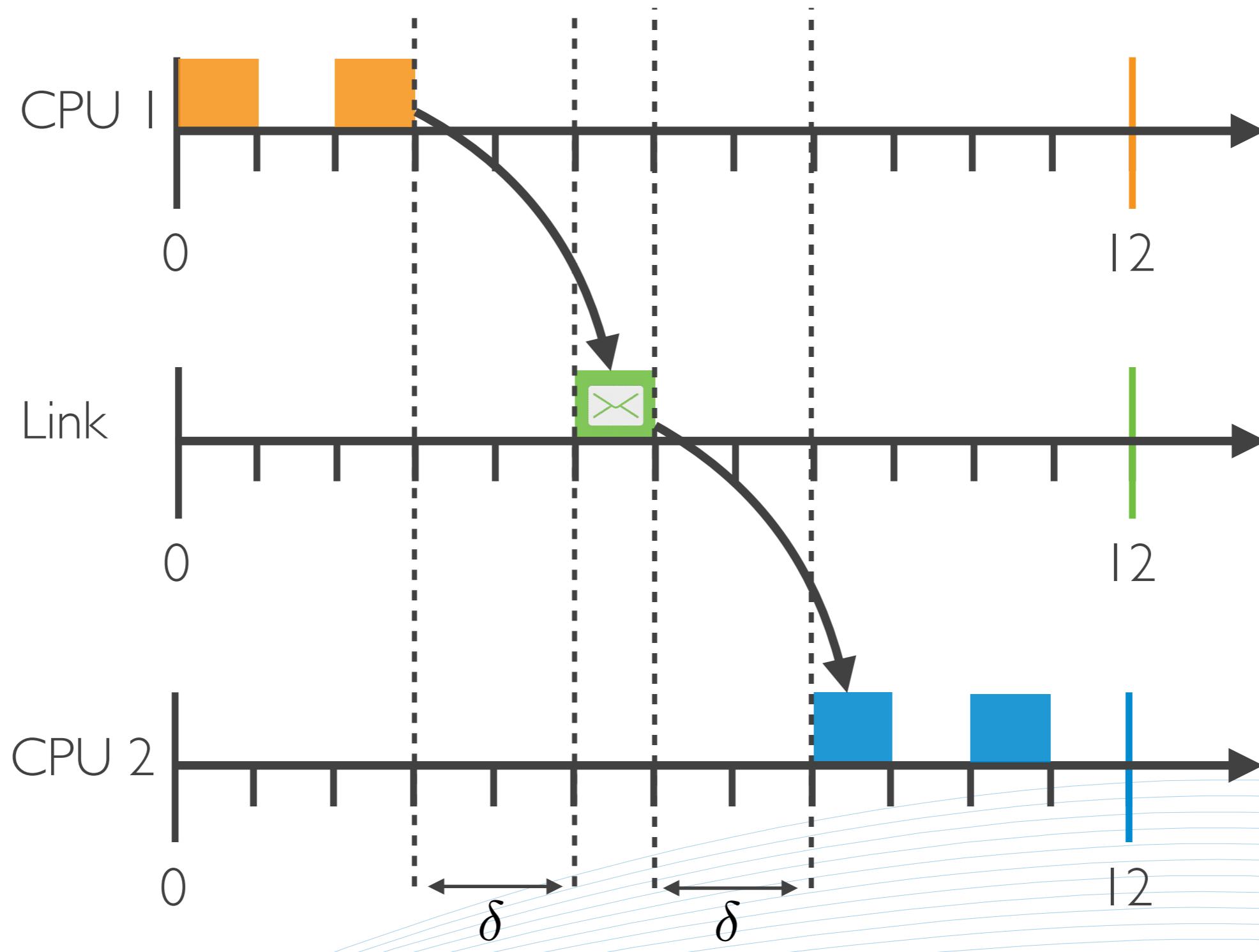
Virtual link constraints

Ensuring Reliable Networks

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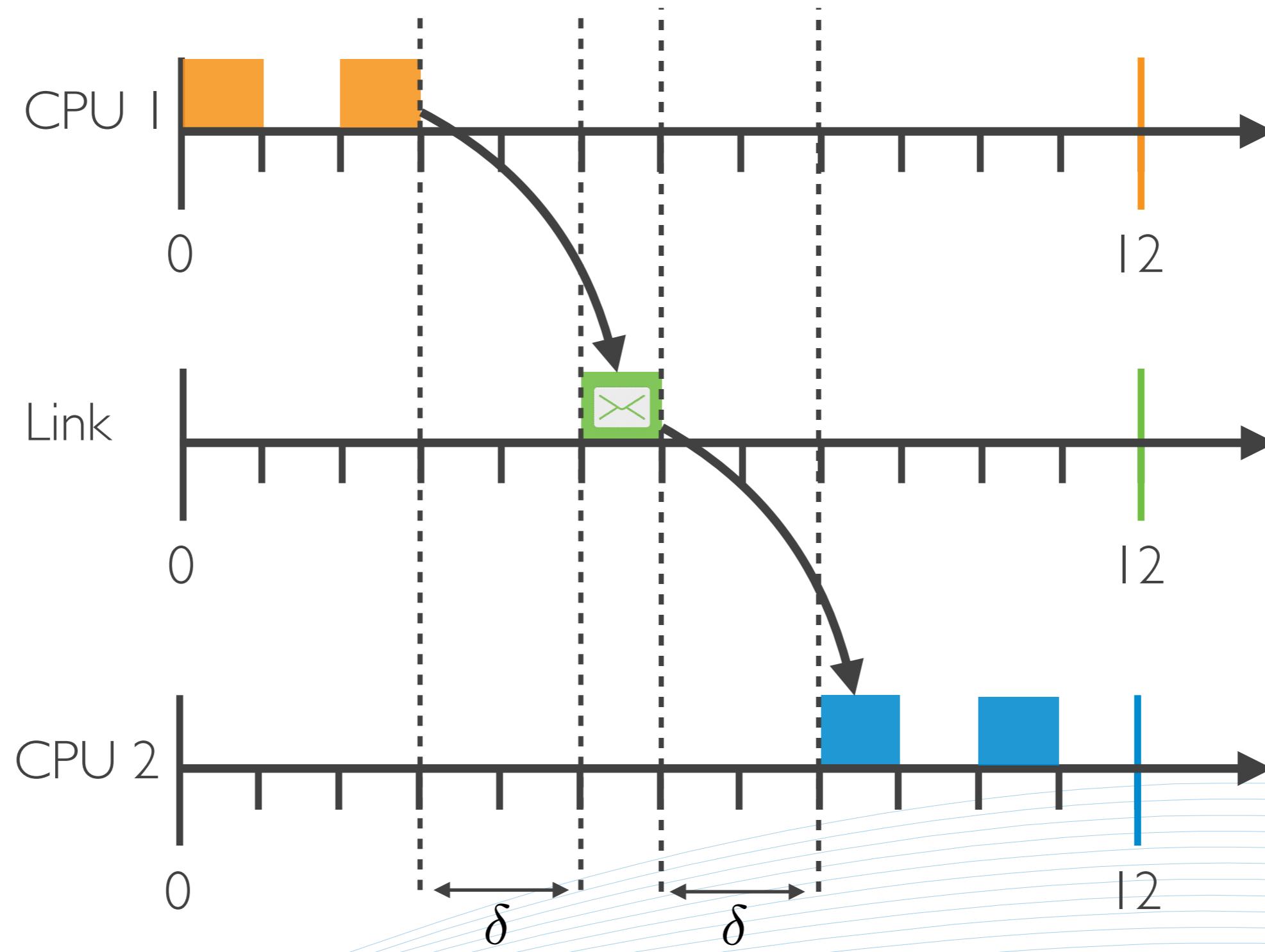
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E2E latency constraints

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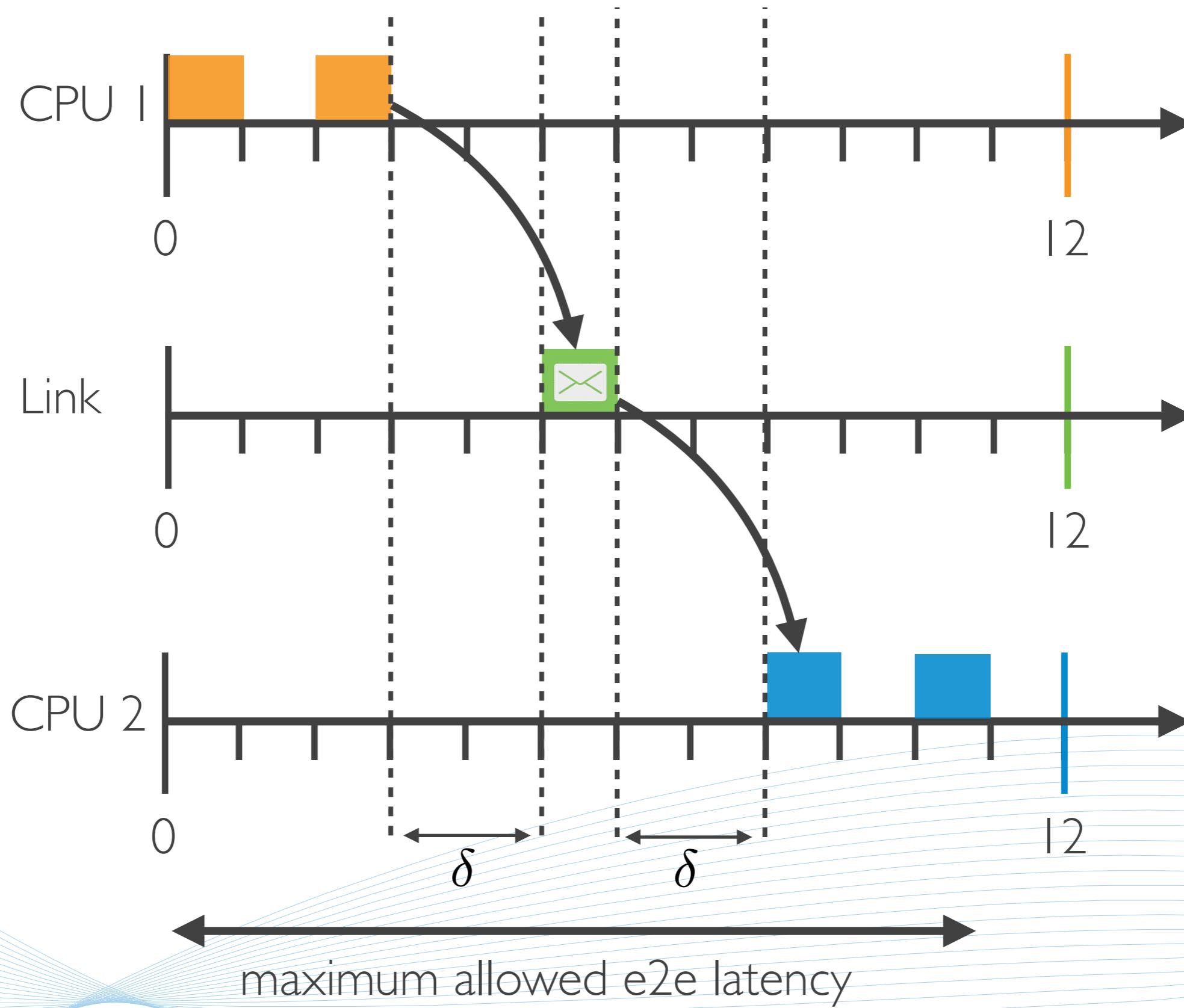
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E2E latency constraints

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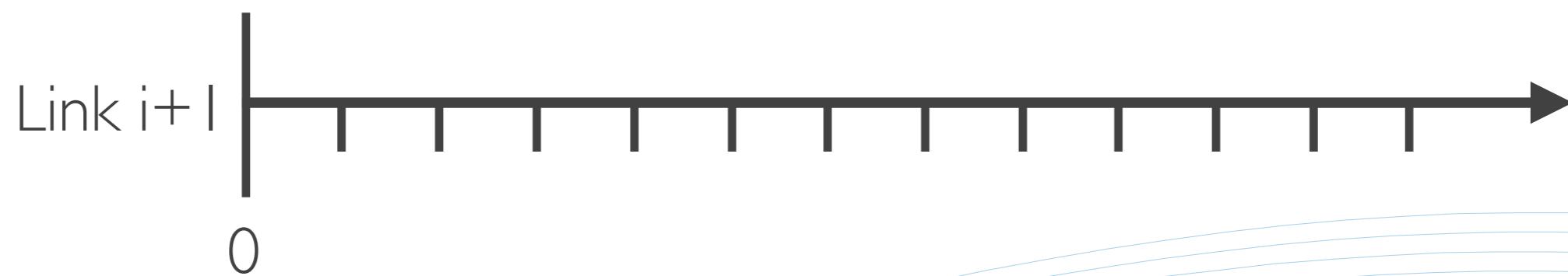
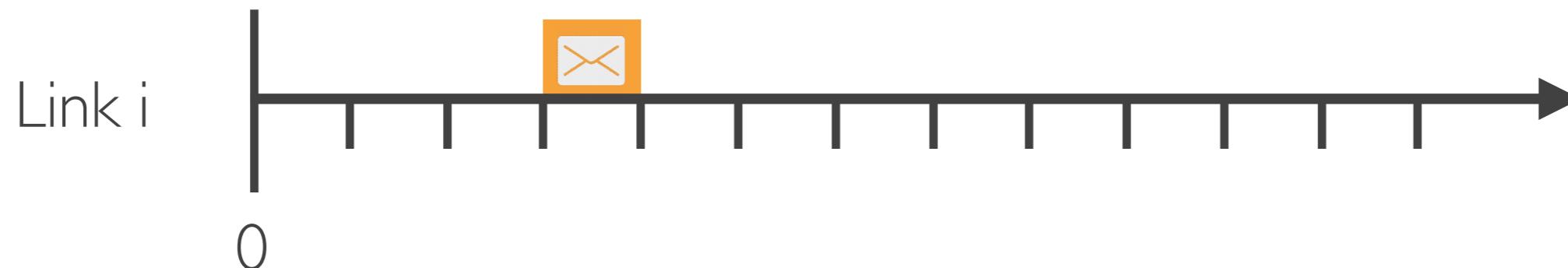
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Memory constraints

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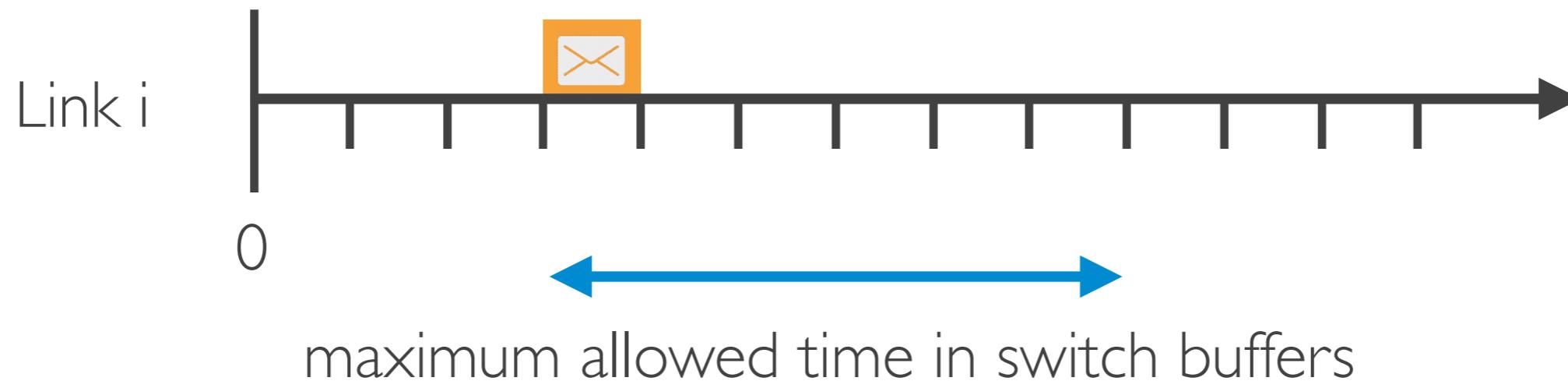
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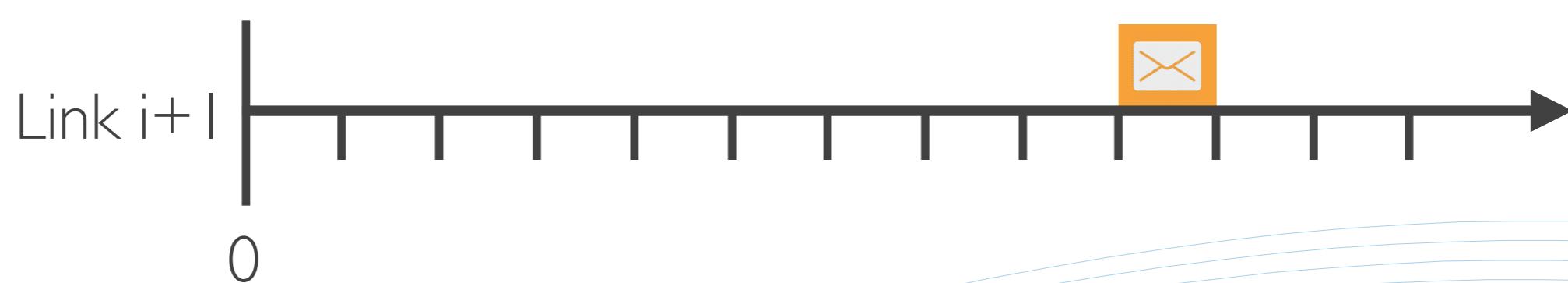
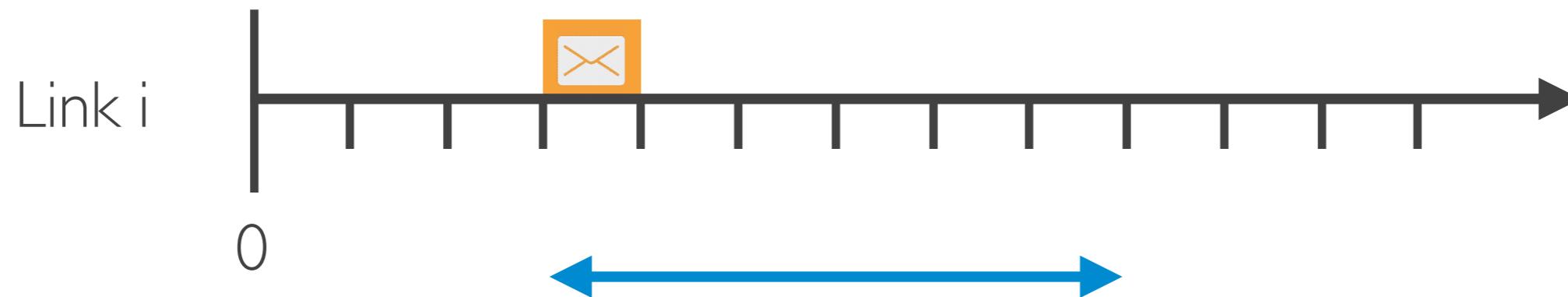
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Satisfiability Modulo Theories

Ensuring Reliable Networks



Satisfiability Modulo Theories

Ensuring Reliable Networks



satisfiability of logical formulas in first-order formulation

background theories

$\mathcal{LA}(\mathbb{Z})$ \mathcal{BV}

variables

x_1, x_2, \dots, x_n

logical symbols

$\vee, \wedge, \neg, (,)$

non-logical symbols

$+, =, \%, \leq$

quantifiers

\exists, \forall

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A lot of solvers and a very active community

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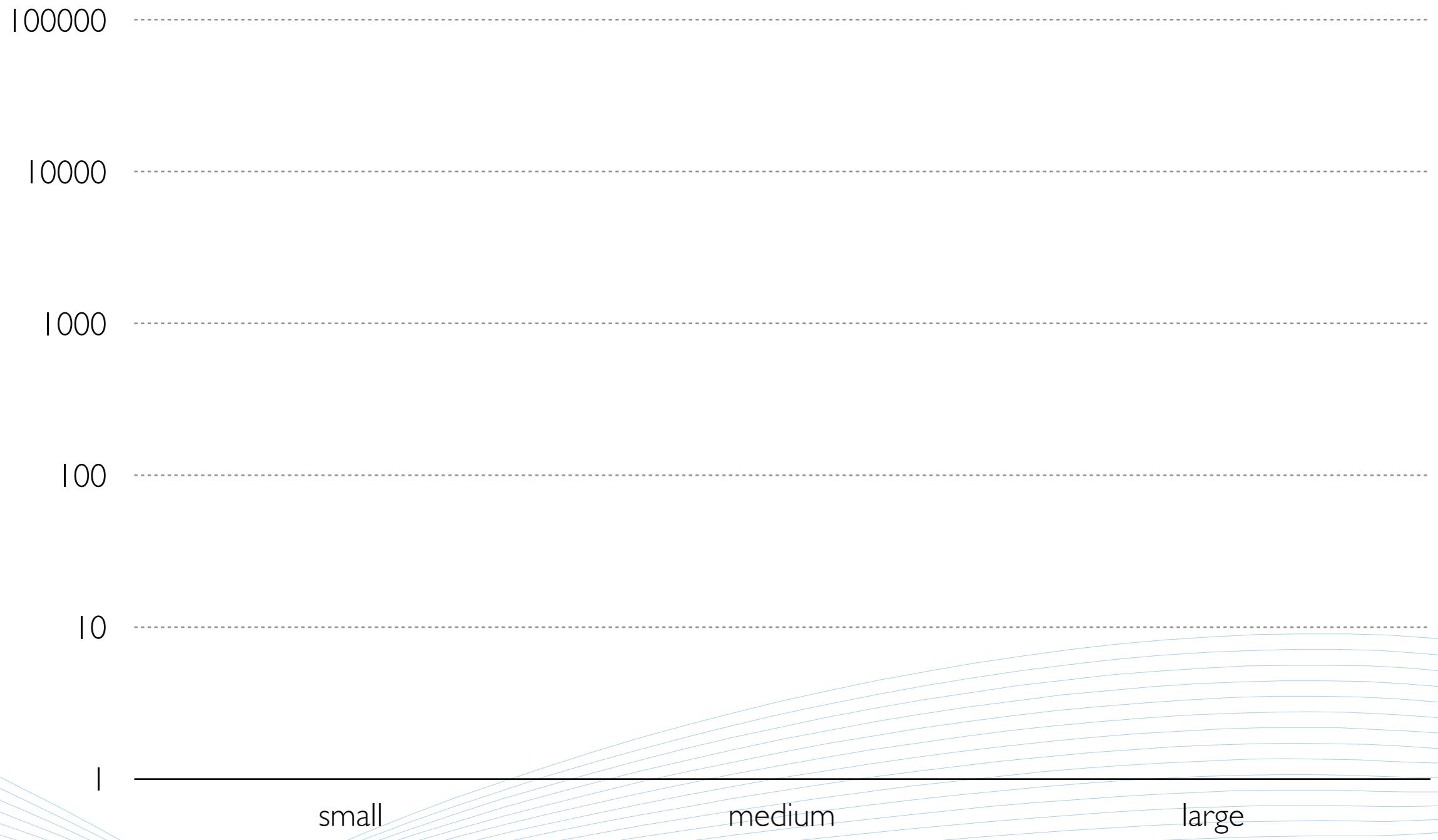
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One-shot

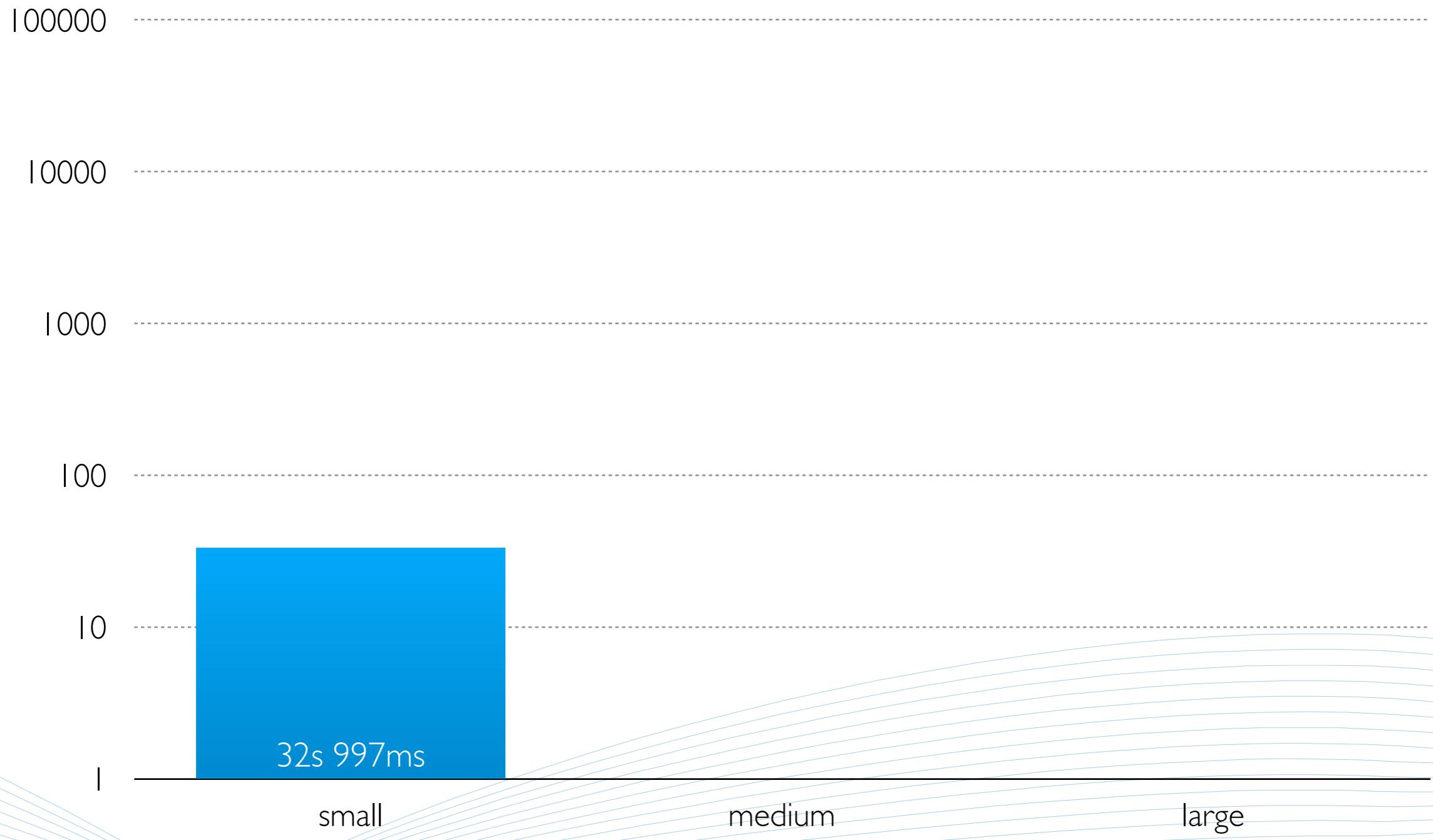
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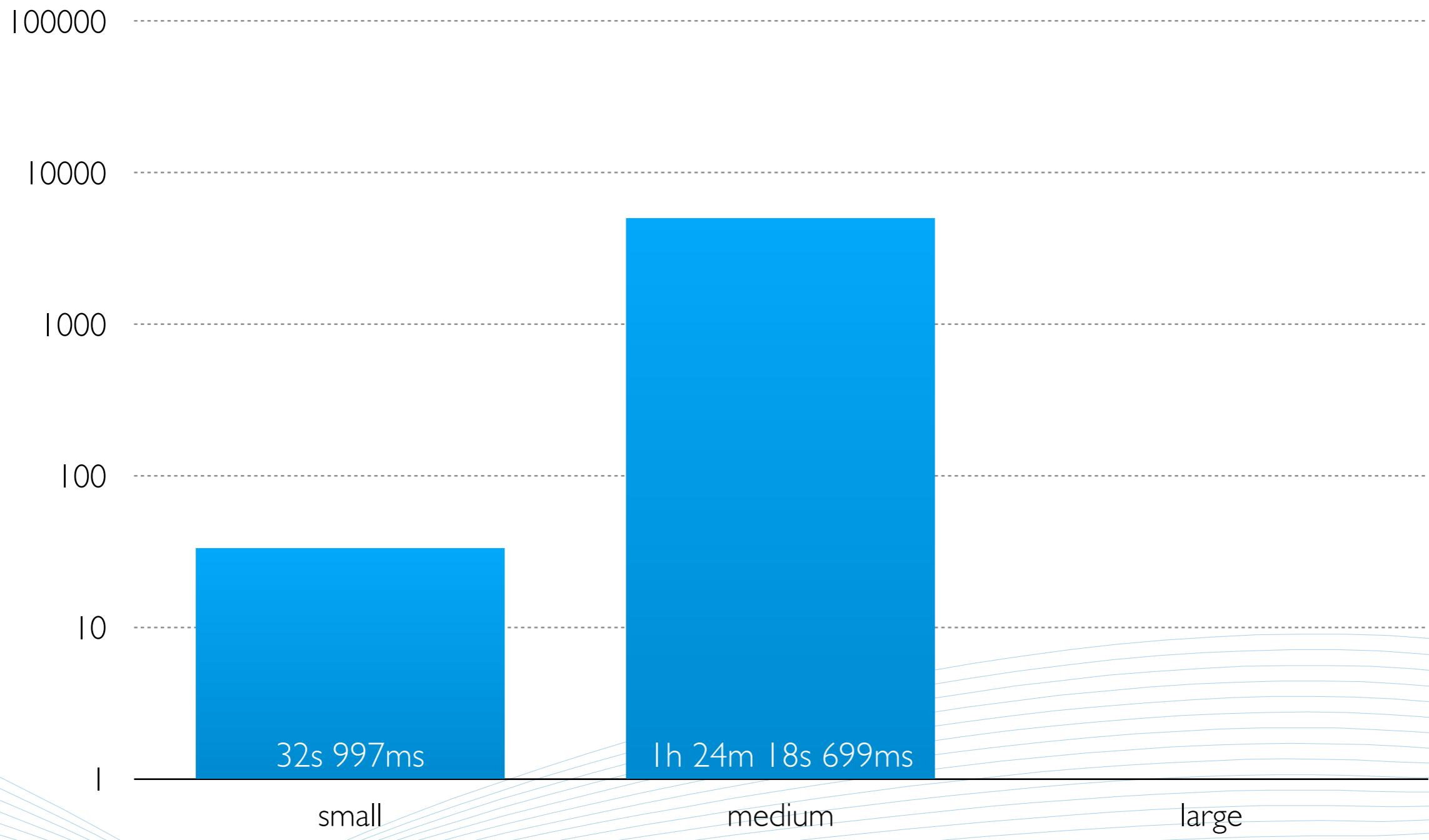
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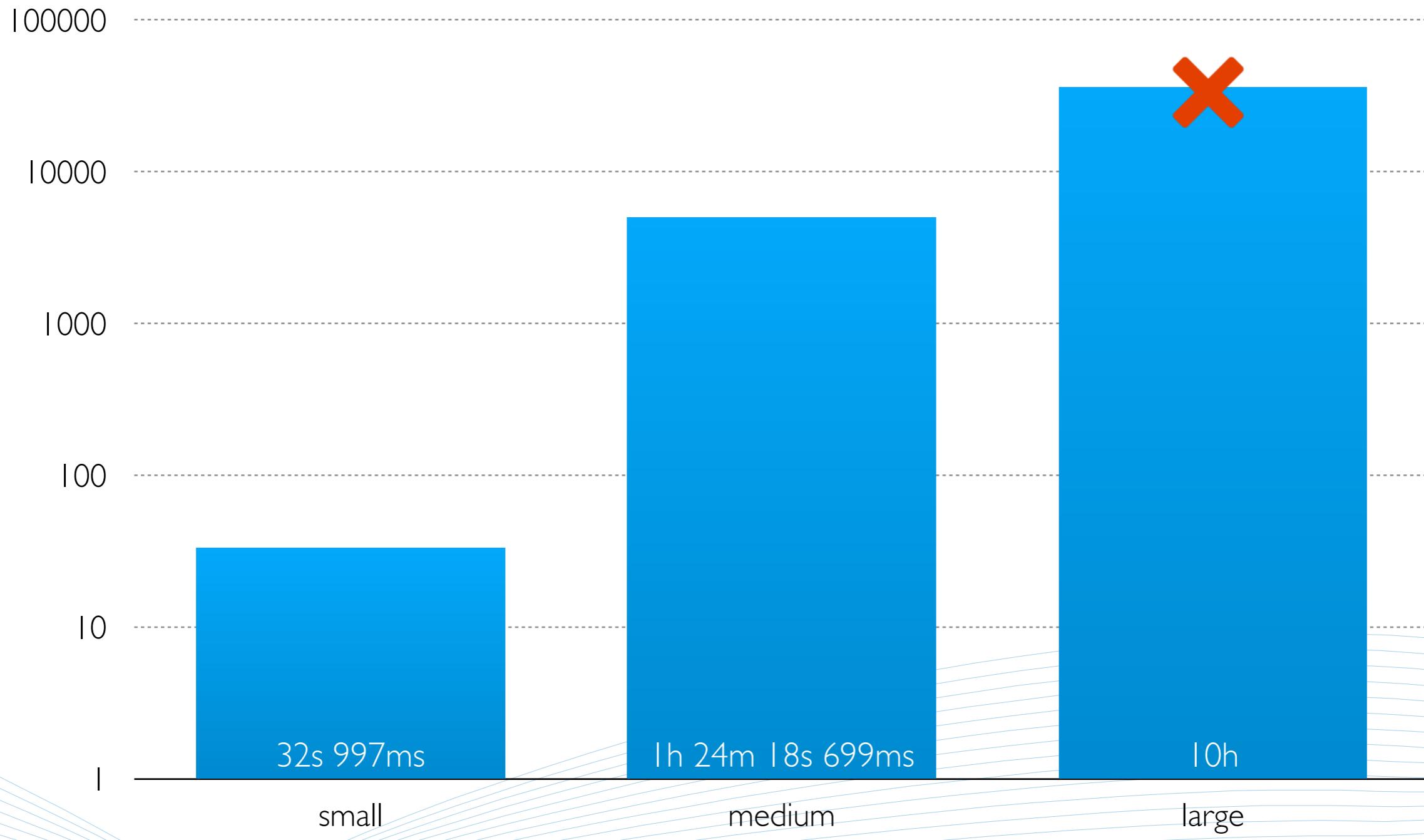
One-shot



One-shot

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One-shot

Ensuring Reliable Networks



where does the complexity come from?



where does the complexity come from?

where do the frames come from?



One-shot

where does the complexity come from?

where do the frames come from?

consumer tasks
producer tasks
communication



where does the complexity come from?

where do the frames come from?

consumer tasks
producer tasks
communication

free tasks

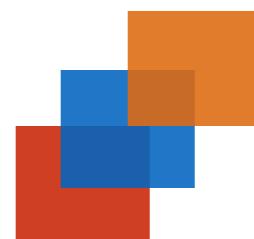


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consumer tasks
producer tasks
communication

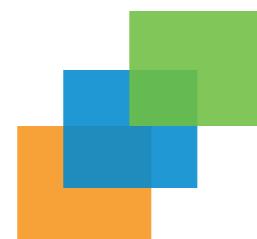
free tasks



where does the complexity come from?

where do the frames come from?

consumer tasks
producer tasks
communication



free tasks



let's treat them differently

Demand-based



Demand-based

Ensuring Reliable Networks



consumer tasks
producer tasks
communication

free tasks



Demand-based

Ensuring Reliable Networks



consumer tasks
producer tasks
communication

free tasks



Demand-based

free tasks

SMT



Demand-based

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free tasks

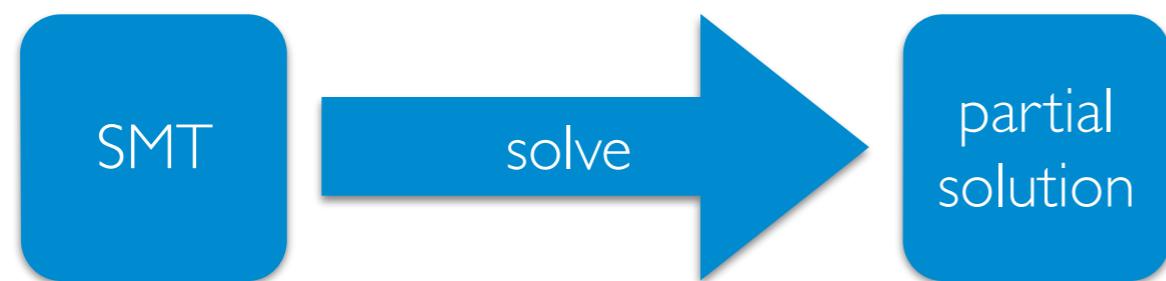


Demand-based

Ensuring Reliable Networks

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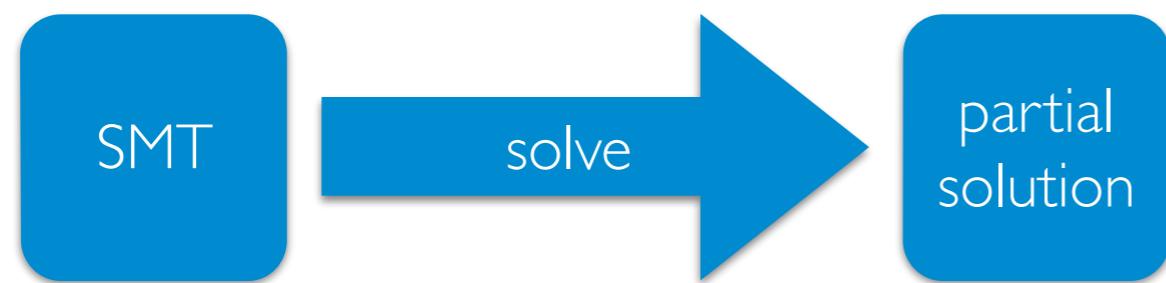
free tasks



Demand-based

Ensuring Reliable Networks

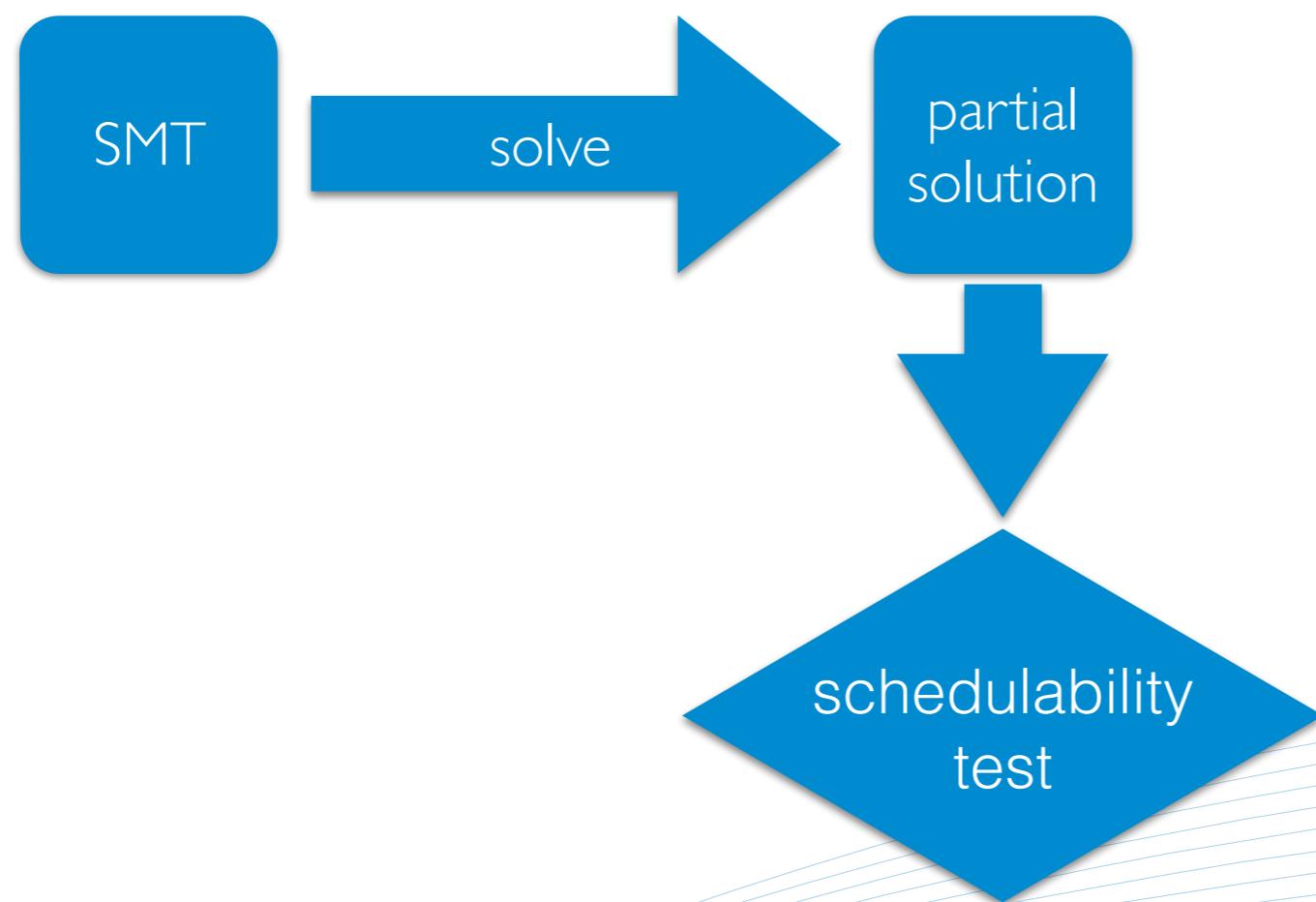
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Demand-based

Ensuring Reliable Networks

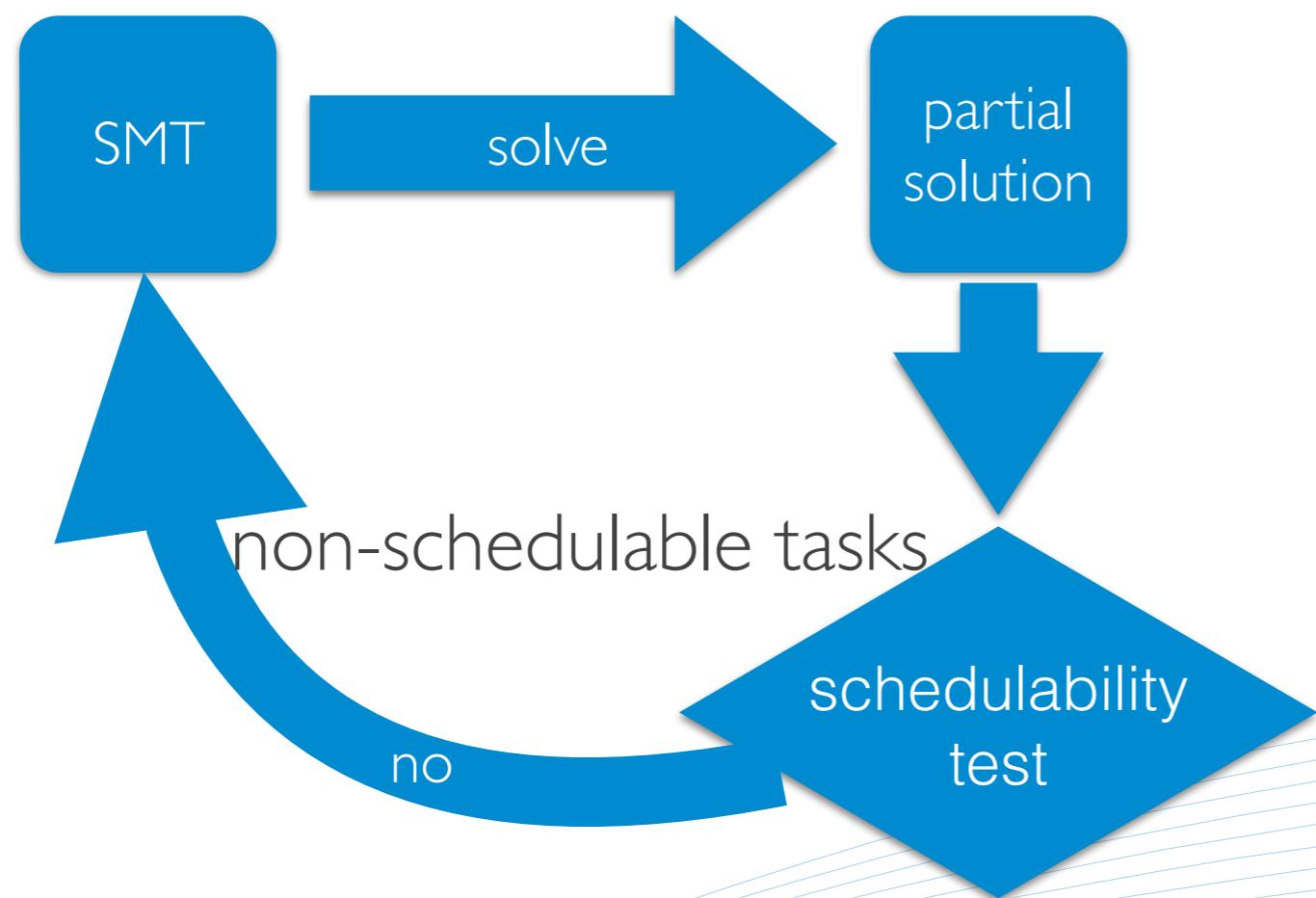
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Ensuring Reliable Networks

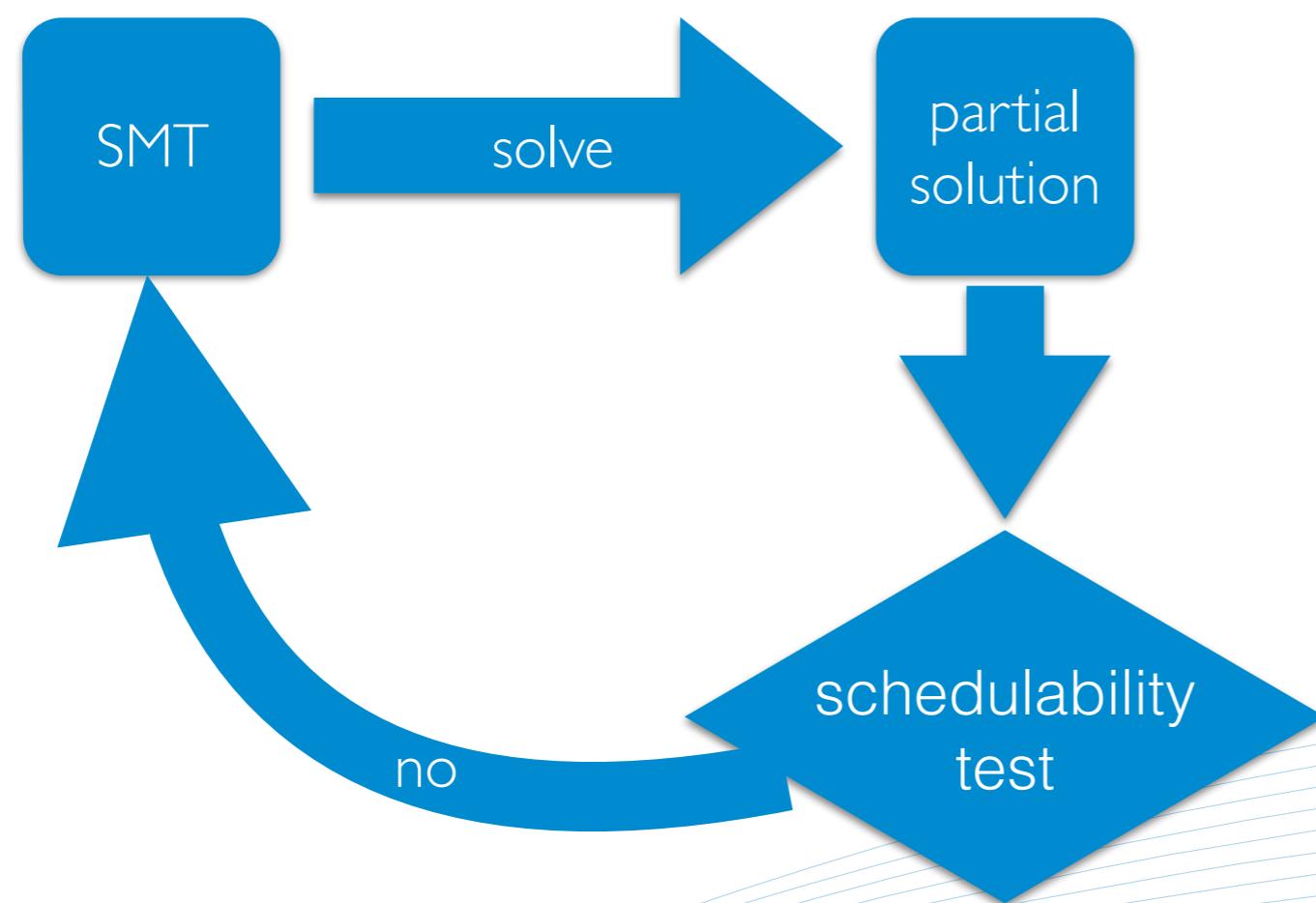
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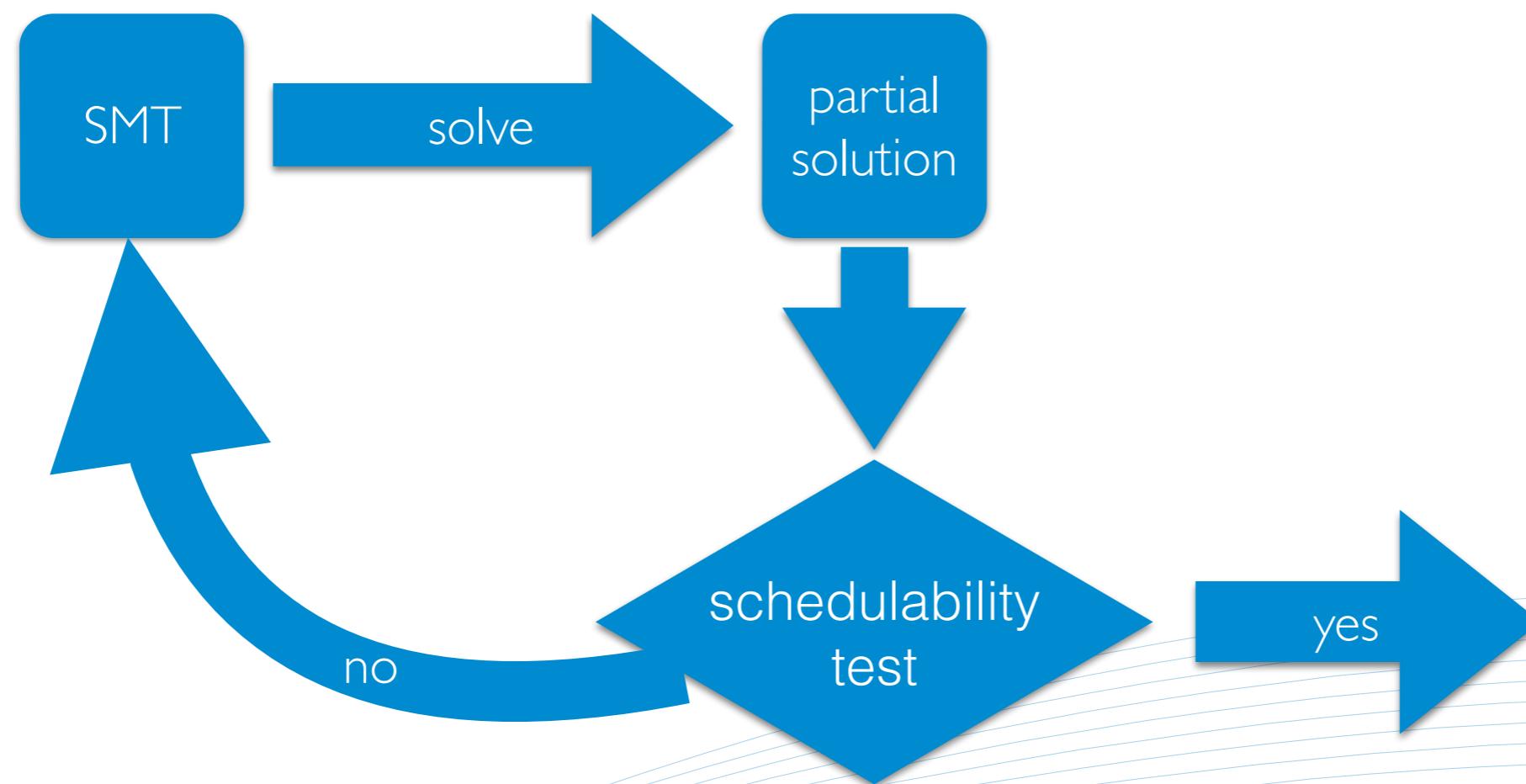
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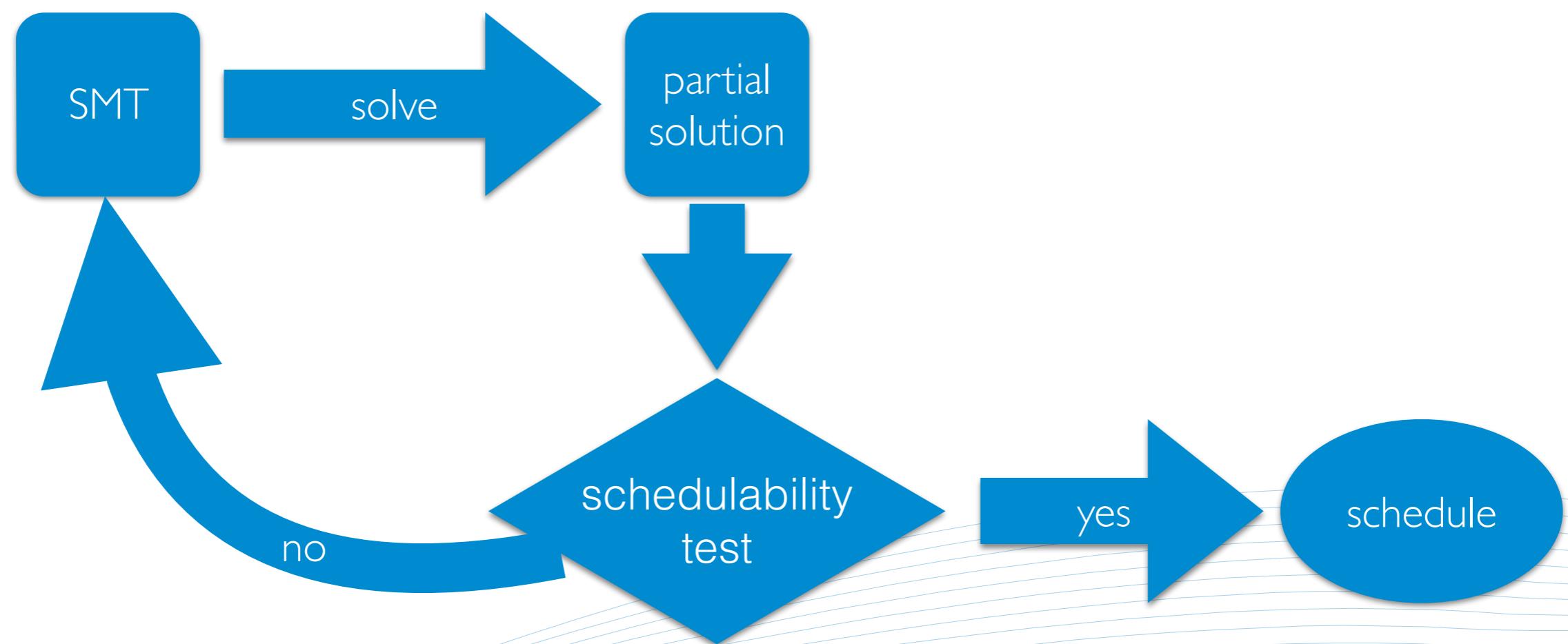
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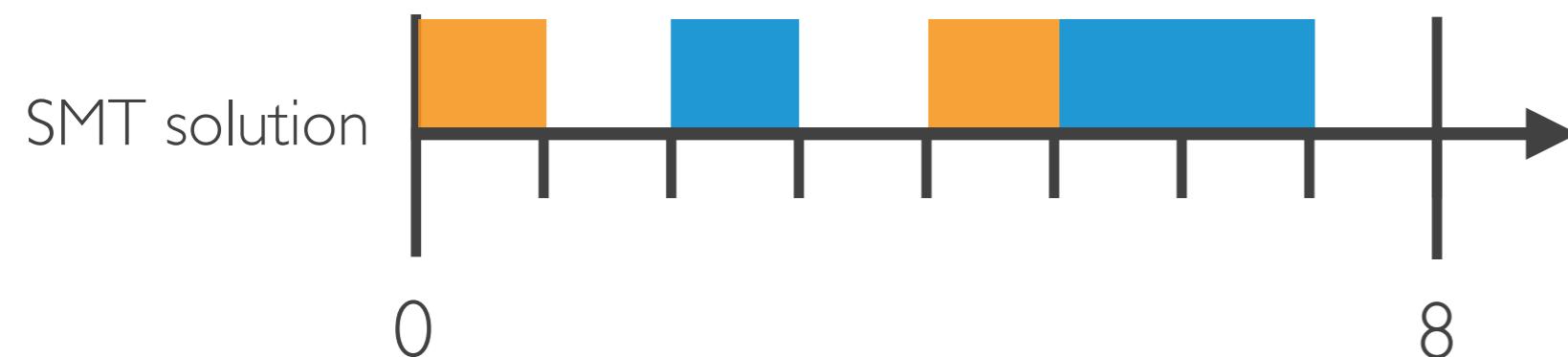
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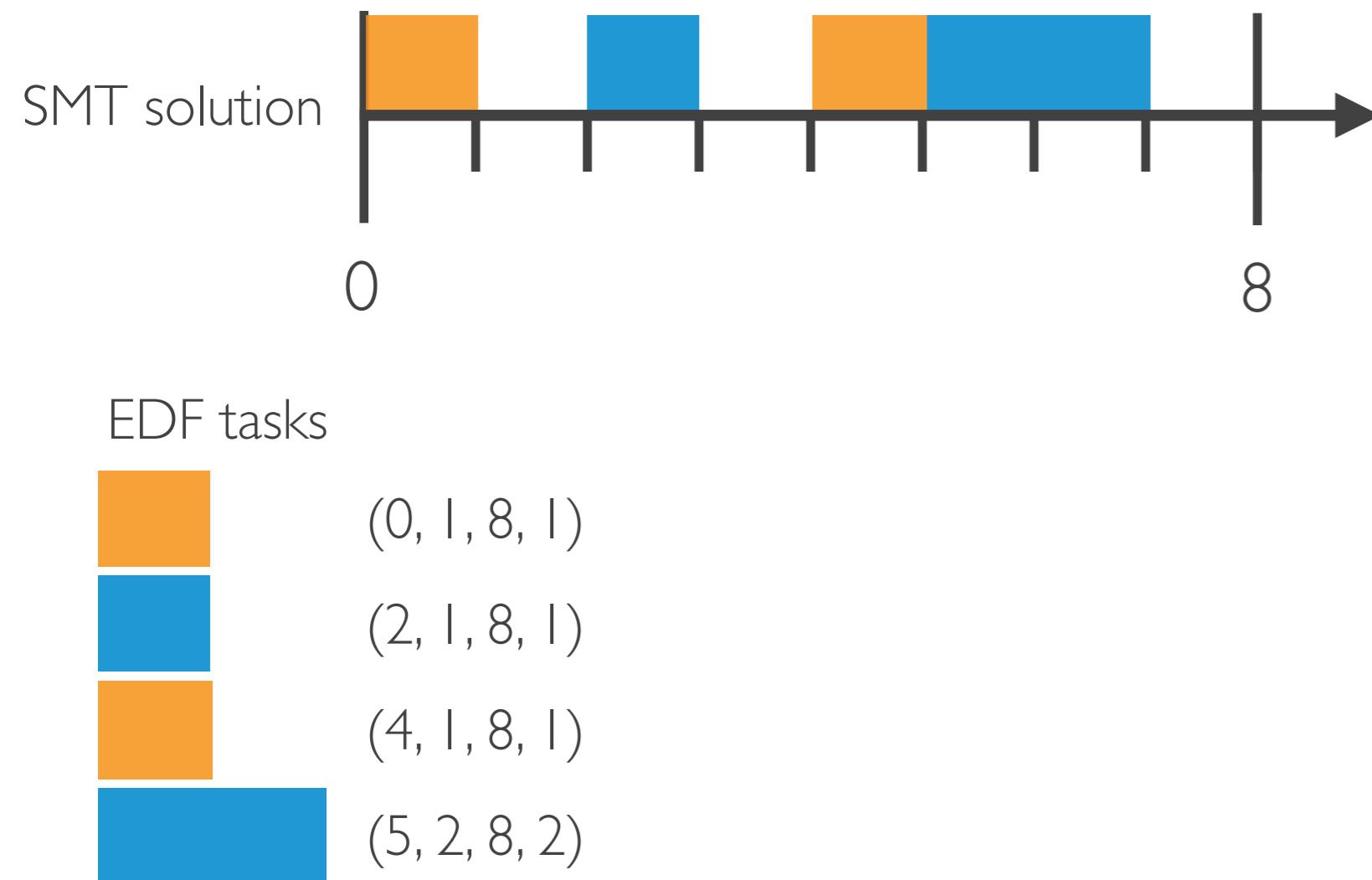
Demand-based



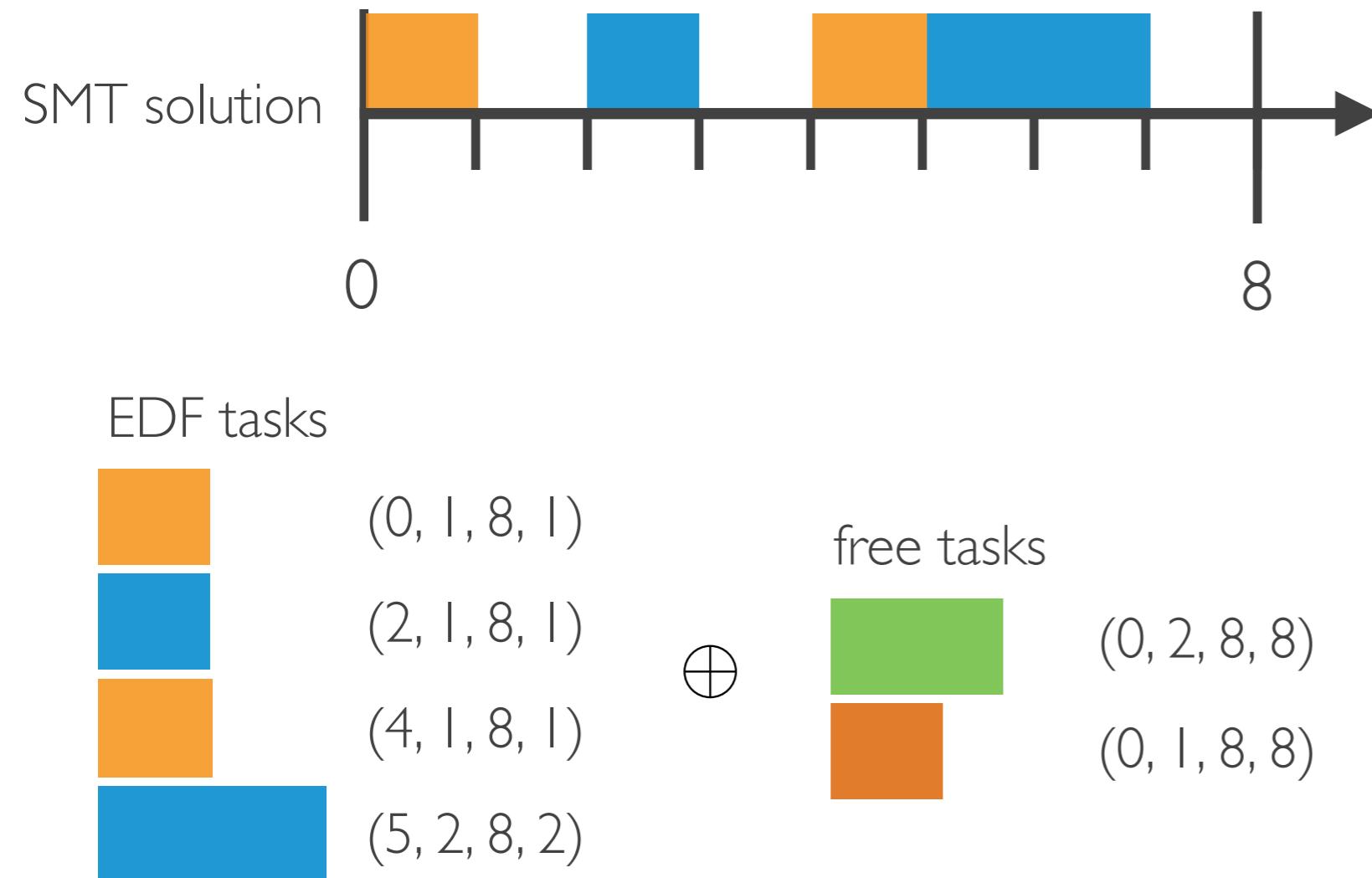
Demand-based



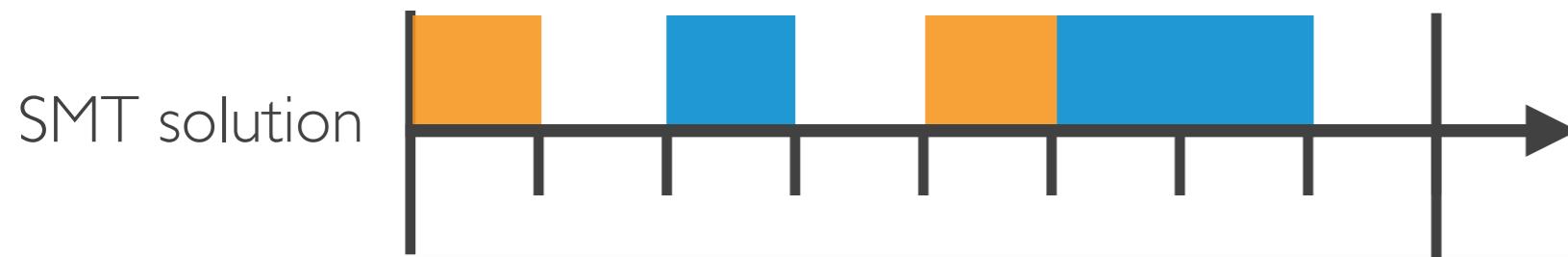
Demand-based



Demand-based



Demand-based



$\forall v_a \in \mathcal{V}, \forall t_1 \in \Phi^{v_a}, \forall t_2 \in \Delta^{v_a}, t_1 < t_2 :$

EDF task

$$\sum_{\tilde{\tau}_i^{v_a} \in \tilde{\Gamma}^{v_a}} \tilde{\tau}_i^{v_a}.C \times \left(\left\lfloor \frac{t_2 - \tilde{\tau}_i^{v_a}.\phi - \tilde{\tau}_i^{v_a}.D}{\tilde{\tau}_i^{v_a}.T} \right\rfloor - \left\lceil \frac{t_1 - \tilde{\tau}_i^{v_a}.\phi}{\tilde{\tau}_i^{v_a}.T} \right\rceil + 1 \right)_0 \leq t_2 - t_1,$$

where

$$\Phi^{v_a} \stackrel{def}{=} \{a_{i,j}^{v_a} = \tilde{\tau}_i^{v_a}.\phi + j \times \tilde{\tau}_i^{v_a}.T | \tilde{\tau}_i^{v_a} \in \tilde{\Gamma}^{v_a}, j \geq 0, a_{i,j}^{v_a} \leq \lambda^{v_a}\},$$

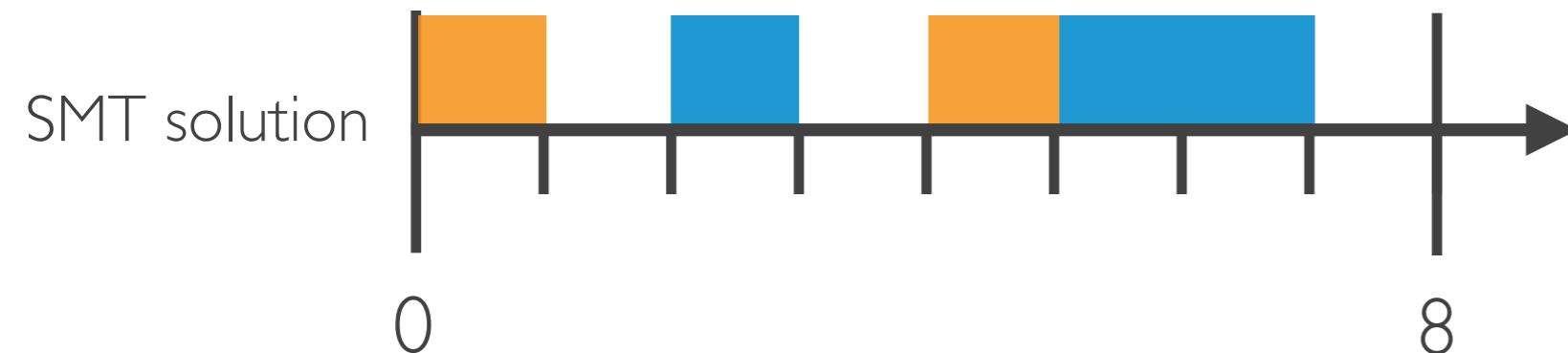
$$\Delta^{v_a} \stackrel{def}{=} \{d_{i,j}^{v_a} = a_{i,j}^{v_a} + \tilde{\tau}_i^{v_a}.D | \tilde{\tau}_i^{v_a} \in \tilde{\Gamma}^{v_a}, j \geq 0, d_{i,j}^{v_a} \leq \lambda^{v_a}\},$$

$$\lambda^{v_a} = \max(\{\tilde{\tau}_i^{v_a}.\phi | \tilde{\tau}_i^{v_a} \in \tilde{\Gamma}^{v_a}\}) + 2 \times \text{lcm}(\{\tilde{\tau}_i^{v_a}.T | \tilde{\tau}_i^{v_a} \in \tilde{\Gamma}^{v_a}\}).$$

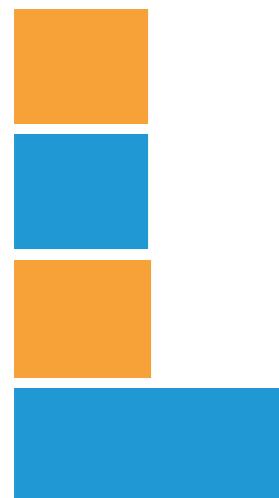
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EDF tasks



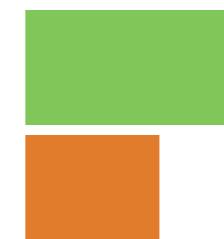
(0, 1, 8, 1)

(2, 1, 8, 1)

(4, 1, 8, 1)

(5, 2, 8, 2)

free tasks



(0, 2, 8, 8)

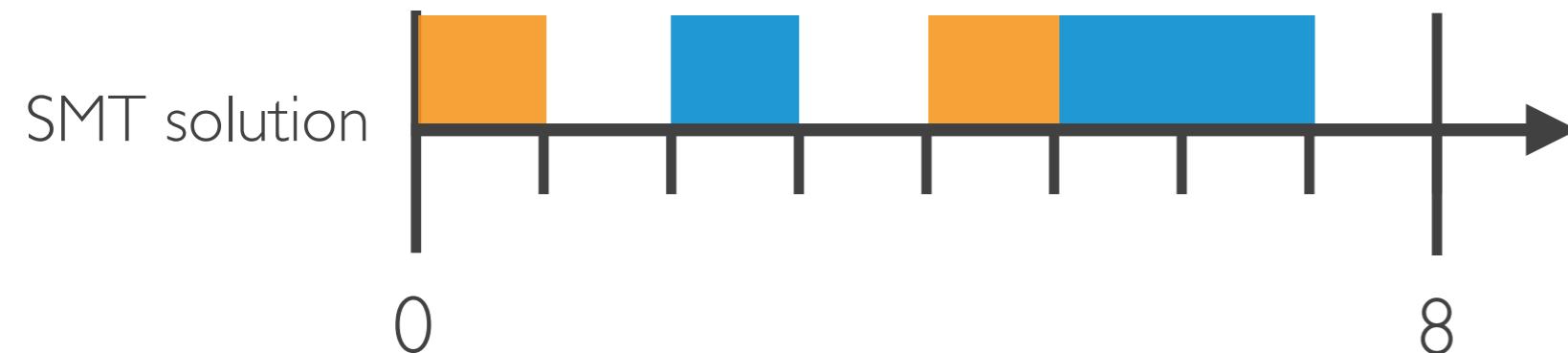
(0, 1, 8, 8)

$$\forall v_a \in \mathcal{V}, \forall t_1 \in \Phi^{v_a}, \forall t_2 \in \Delta^{v_a}, t_1 < t_2 : \\ \sum_{\tilde{\tau}_i^{v_a} \in \tilde{\Gamma}^{v_a}} \tilde{\tau}_i^{v_a}.C \times \left(\left\lfloor \frac{t_2 - \tilde{\tau}_i^{v_a}.\phi - \tilde{\tau}_i^{v_a}.D}{\tilde{\tau}_i^{v_a}.T} \right\rfloor - \left\lceil \frac{t_1 - \tilde{\tau}_i^{v_a}.\phi}{\tilde{\tau}_i^{v_a}.T} \right\rceil + 1 \right)_0 \leq t_2 - t_1, \\ \text{where} \\ \Phi^{v_a} \stackrel{\text{def}}{=} \{a_{i,j}^{v_a} = \tilde{\tau}_i^{v_a}.\phi + j \times \tilde{\tau}_i^{v_a}.T \mid \tilde{\tau}_i^{v_a} \in \tilde{\Gamma}^{v_a}, j \geq 0, a_{i,j}^{v_a} \leq \lambda^{v_a}\}, \\ \Delta^{v_a} \stackrel{\text{def}}{=} \{d_{i,j}^{v_a} = a_{i,j}^{v_a} + \tilde{\tau}_i^{v_a}.D \mid \tilde{\tau}_i^{v_a} \in \tilde{\Gamma}^{v_a}, j \geq 0, d_{i,j}^{v_a} \leq \lambda^{v_a}\}, \\ \lambda^{v_a} = \max(\{\tilde{\tau}_i^{v_a}.\phi \mid \tilde{\tau}_i^{v_a} \in \tilde{\Gamma}^{v_a}\}) + 2 \times \text{lcm}(\{\tilde{\tau}_i^{v_a}.T \mid \tilde{\tau}_i^{v_a} \in \tilde{\Gamma}^{v_a}\}).$$

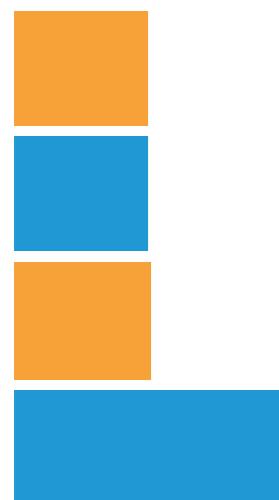
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EDF tasks



(0, 1, 8, 1)

(2, 1, 8, 1)

(4, 1, 8, 1)

(5, 2, 8, 2)

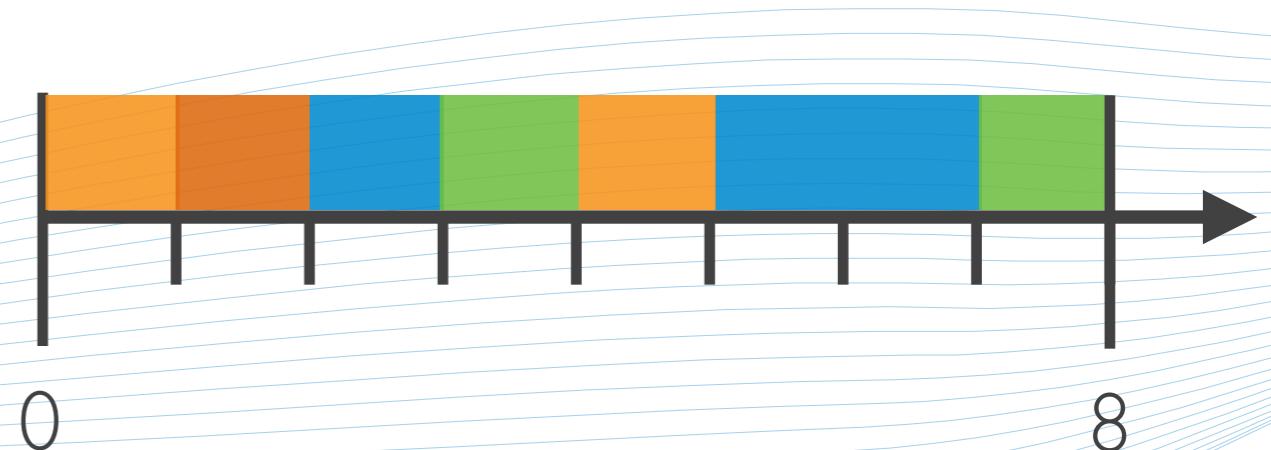
free tasks



(0, 2, 8, 8)

(0, 1, 8, 8)

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Demand-based



Demand-based

- transform scheduled frames on CPUs into asynchronous periodic tasks



Demand-based

Ensuring Reliable Networks



- transform scheduled frames on CPUs into asynchronous periodic tasks
- add free tasks and apply schedulability test [Pellizzoni@RealTimeSyst05]



Demand-based

Ensuring Reliable Networks



- transform scheduled frames on CPUs into asynchronous periodic tasks
- add free tasks and apply schedulability test [Pellizzoni@RealTimeSyst05]
- if not schedulable, increment number of tasks that are solved with SMT

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- add free tasks and apply schedulability test [Pellizzoni@RealTimeSyst05]
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Demand-based

Ensuring Reliable Networks



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- if not schedulable, increment number of tasks that are solved with SMT
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- incremental algorithm so we don't lose schedulability



Demand-based

- transform scheduled frames on CPUs into asynchronous periodic tasks
- add free tasks and apply schedulability test [Pellizzoni@RealTimeSyst05]
- if not schedulable, increment number of tasks that are solved with SMT
- if schedulable, generate final schedule by simulating EDF until HP
- incremental algorithm so we don't lose schedulability
- we are still exponential but scale better for the average case

Ensuring Reliable Networks



Evaluation

Evaluation

time

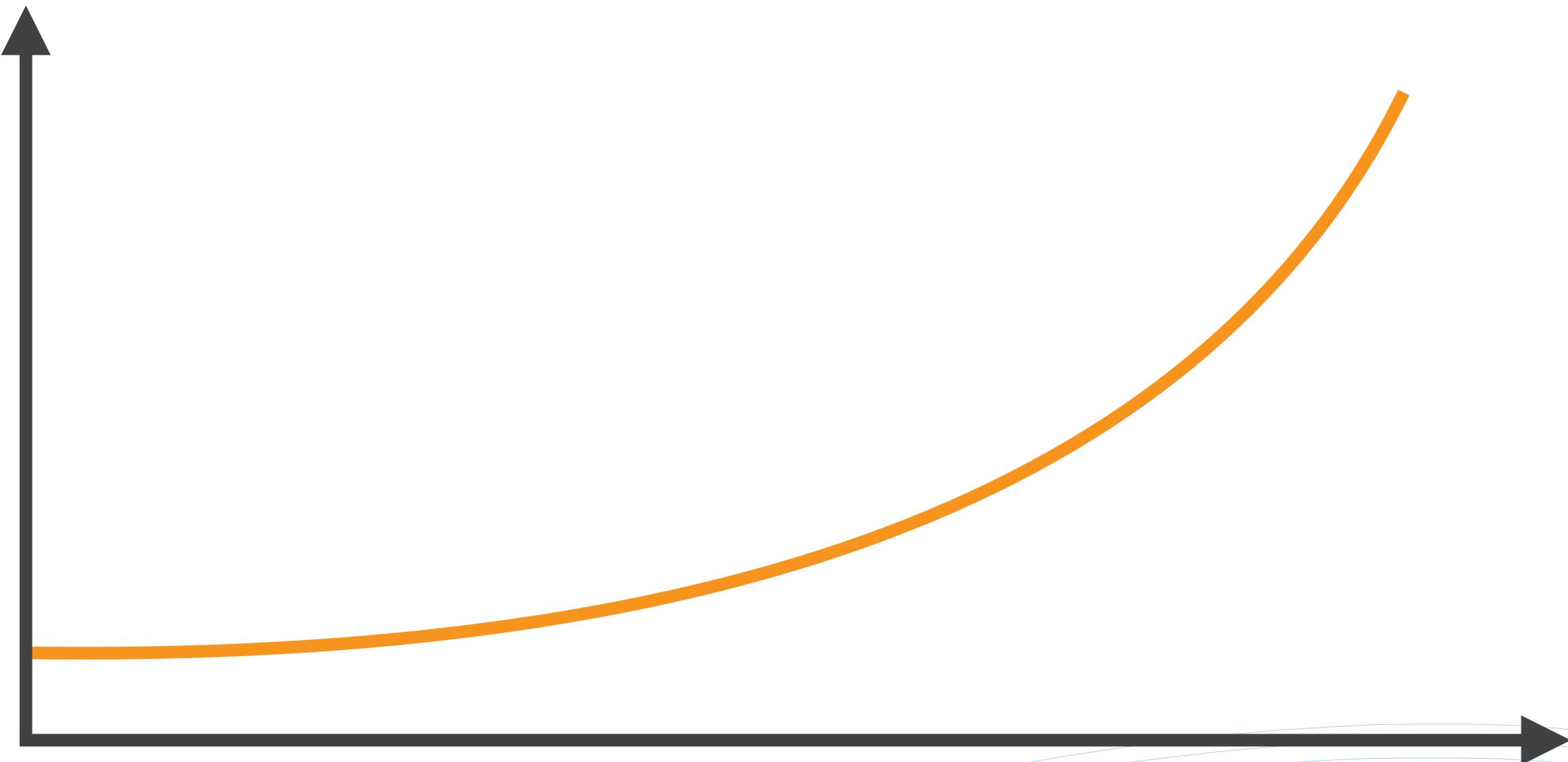


Evaluation

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time

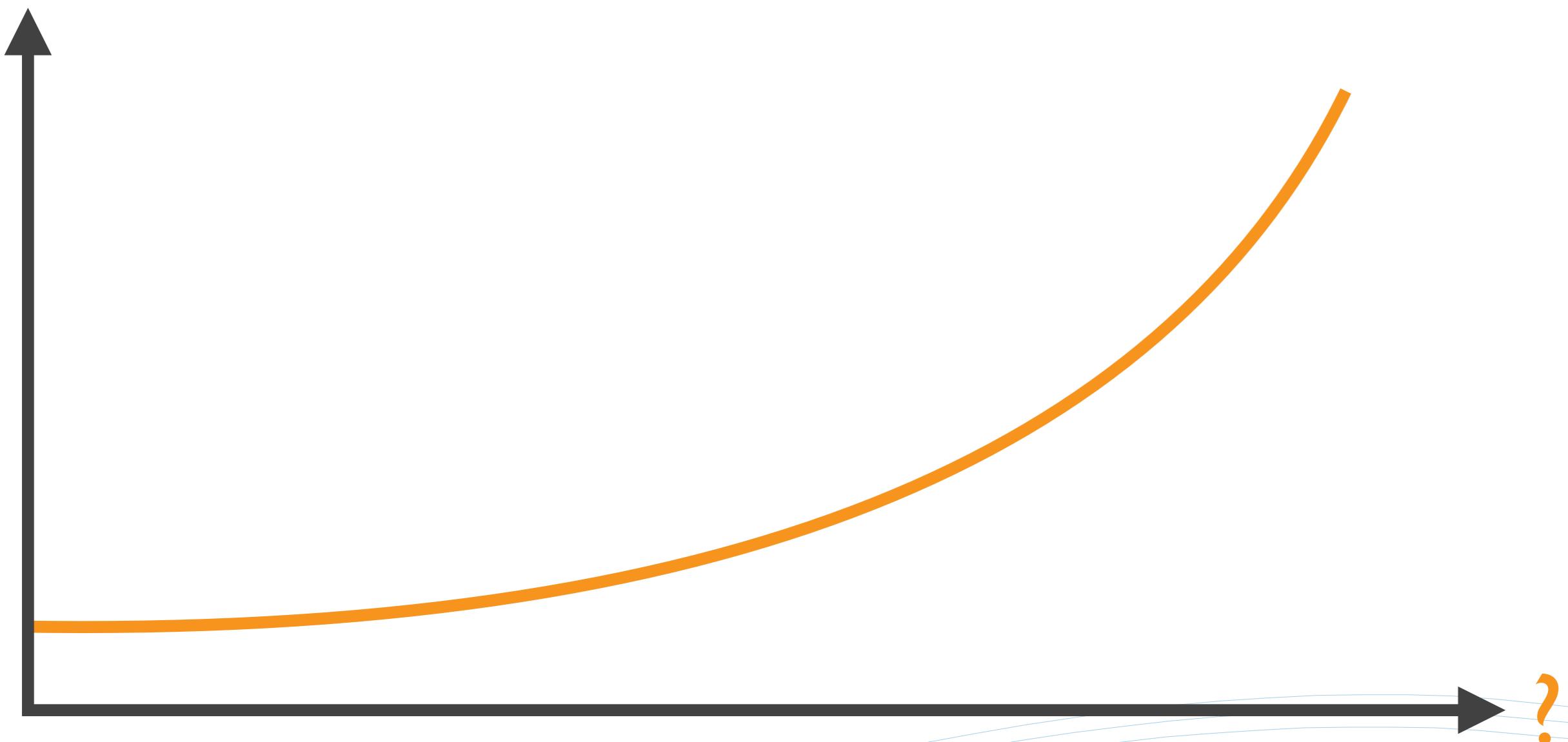


Evaluation

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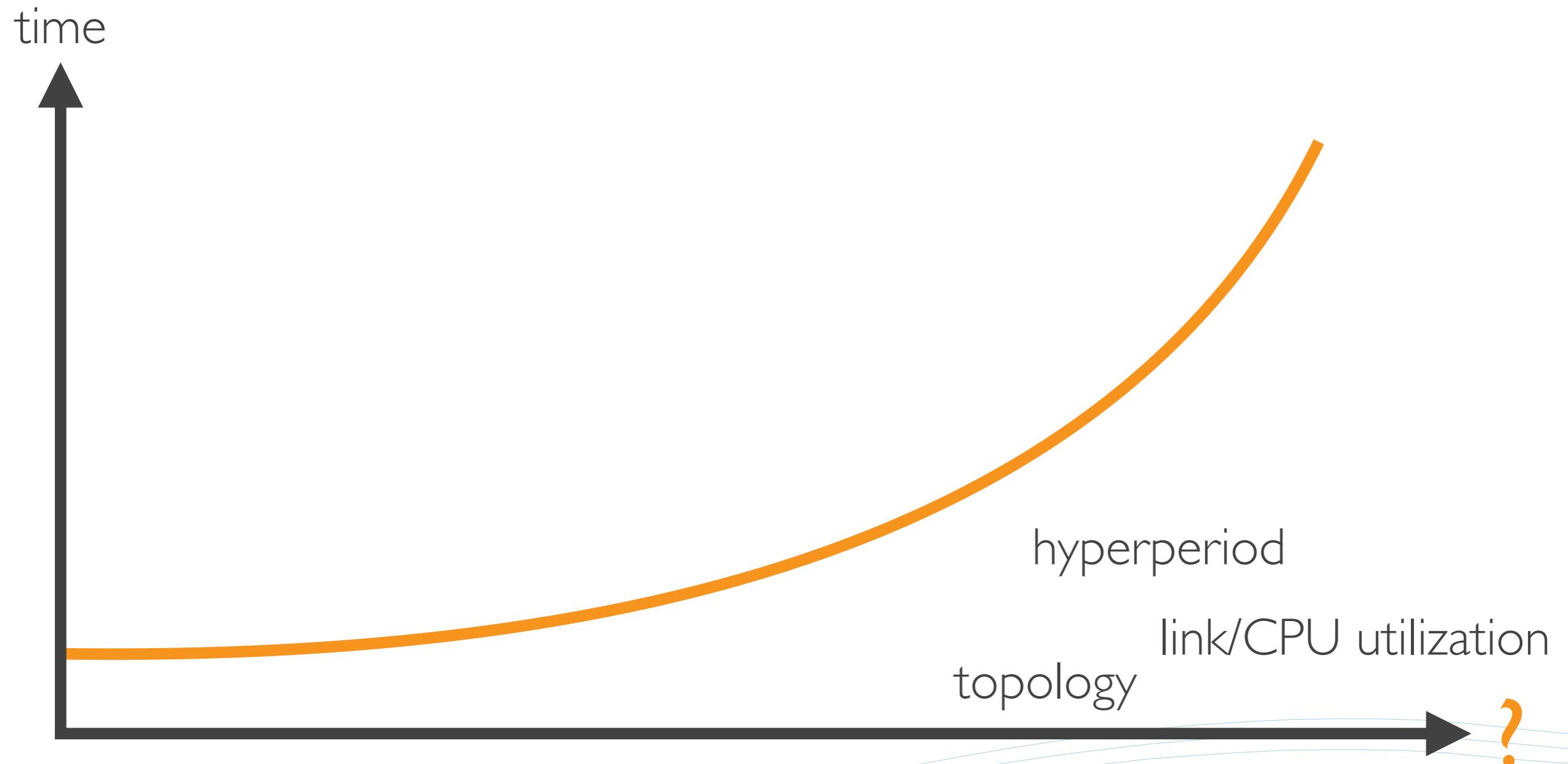
time



Evaluation

Ensuring Reliable Networks

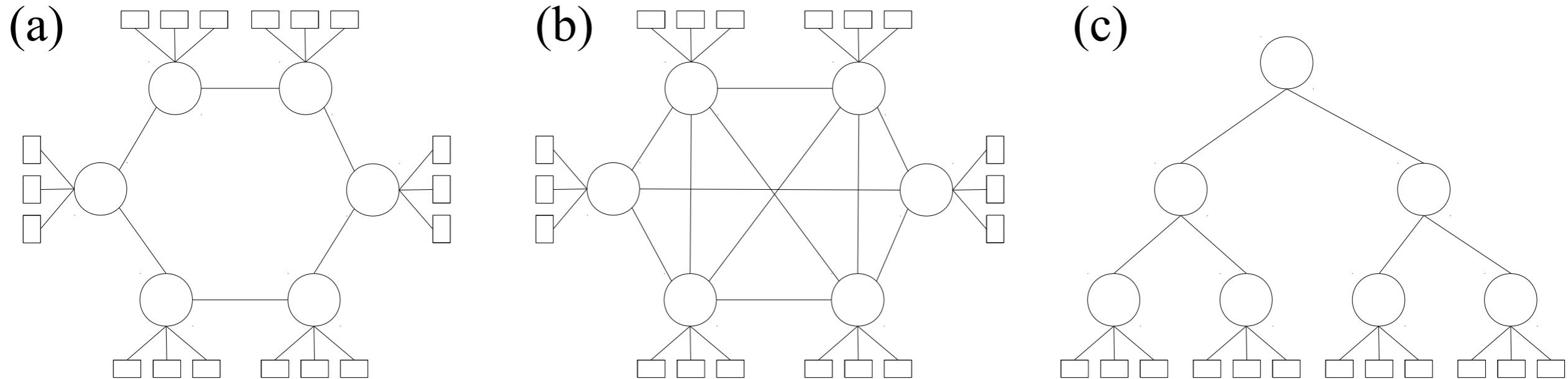
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Topologies

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Periods {10,20,25,50,100}, {10,30,100}, {50,75} ms

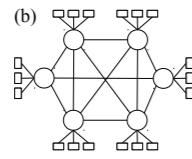
1usec network link granularity

100Mbit/s and 1Gbit/s

random message size and virtual links

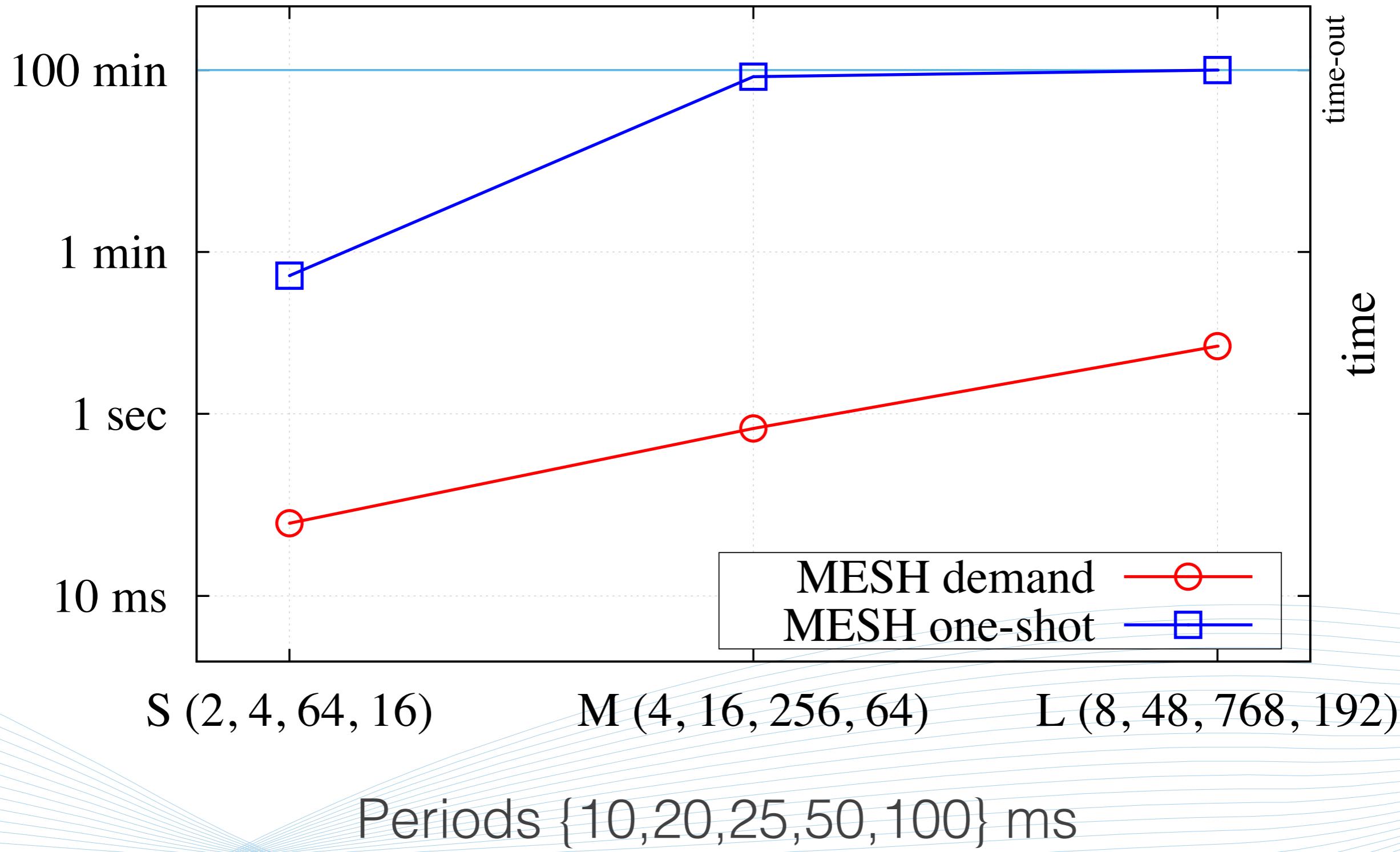
different macrotick and utilization configurations

Mesh

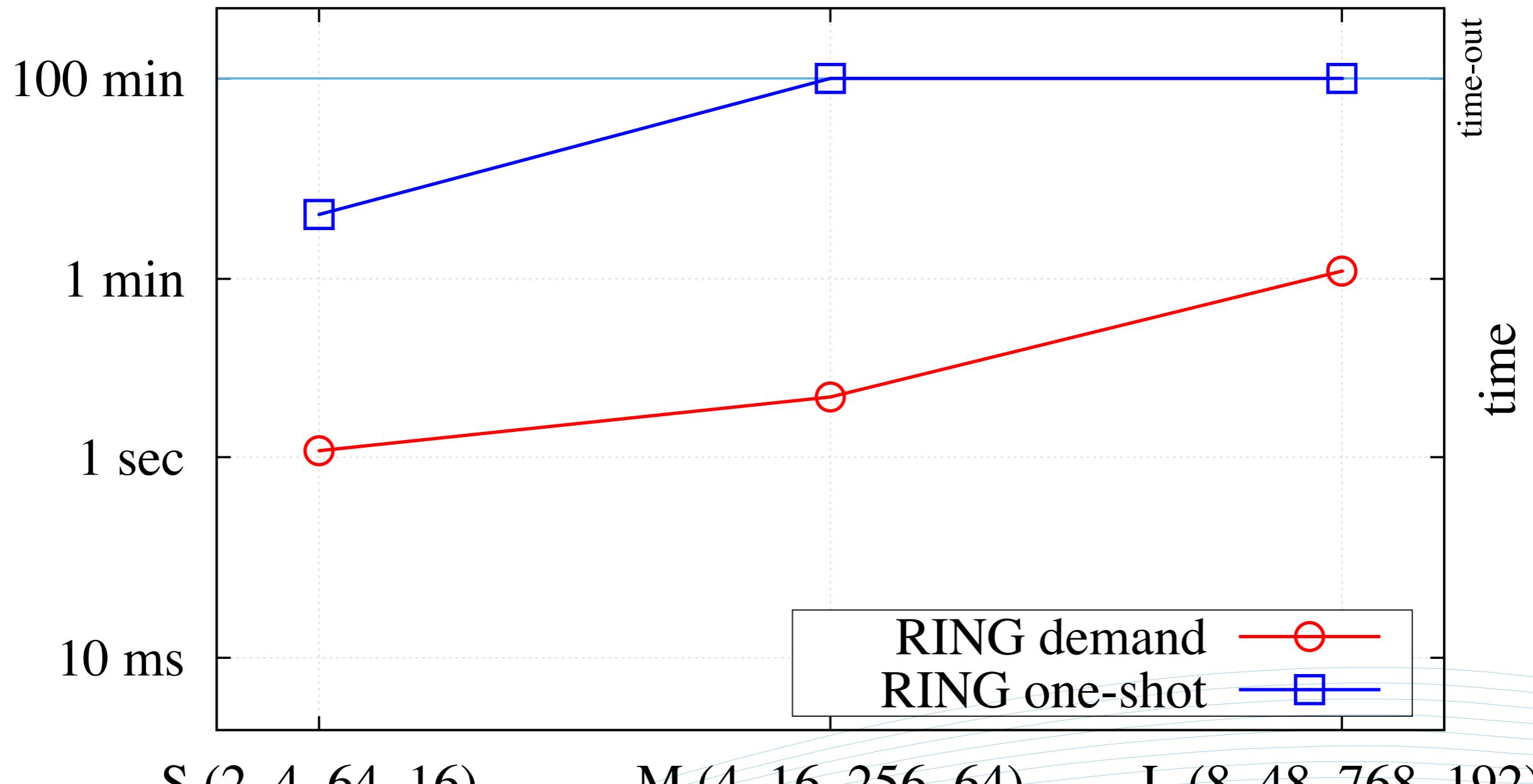
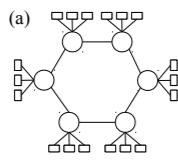


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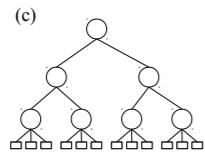


Ring



Periods {10,30,100} ms

Tree



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100 min

1 min

1 sec

10 ms

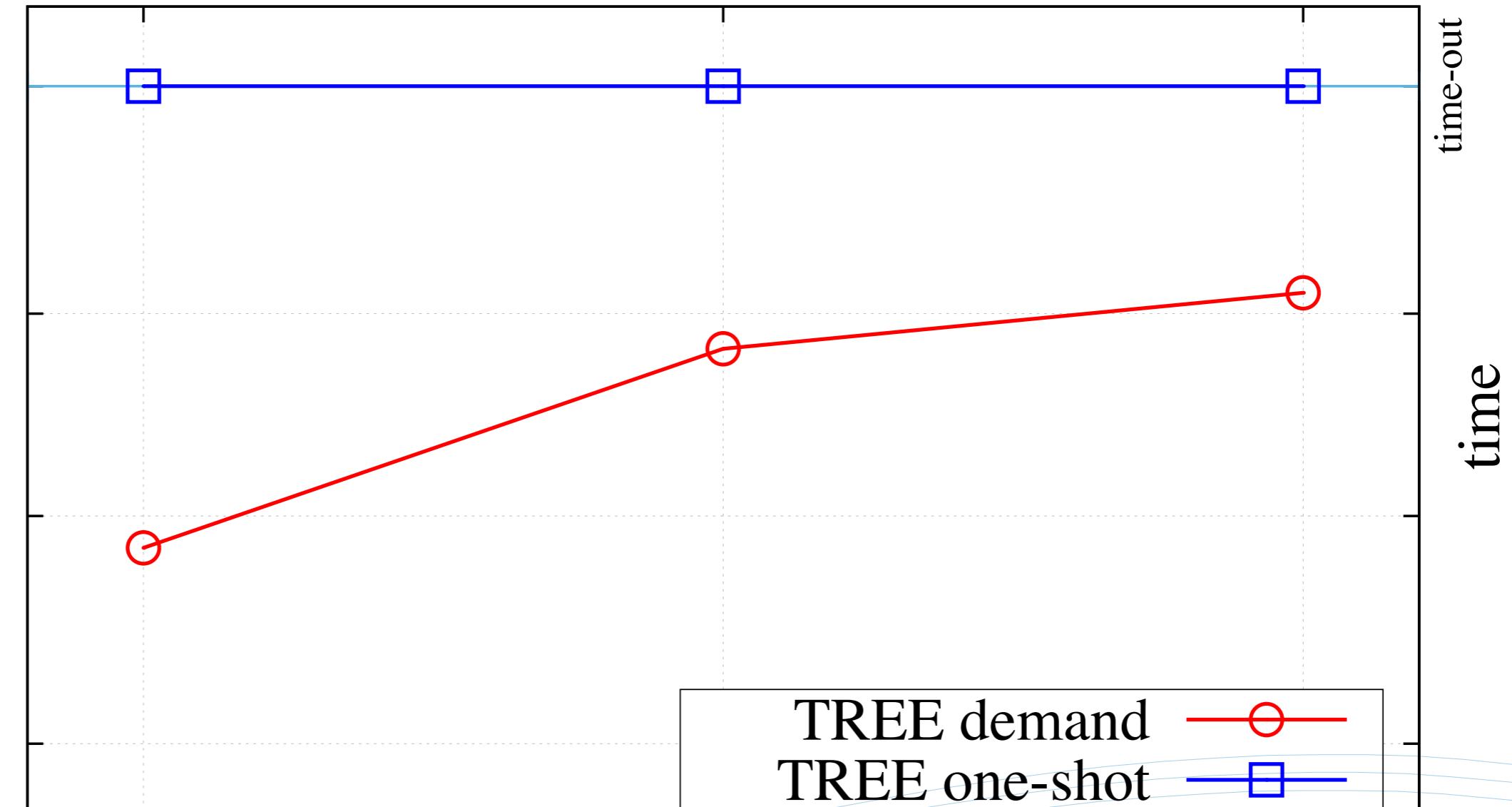
S (4, 6, 96, 24)

M (13, 36, 576, 144)

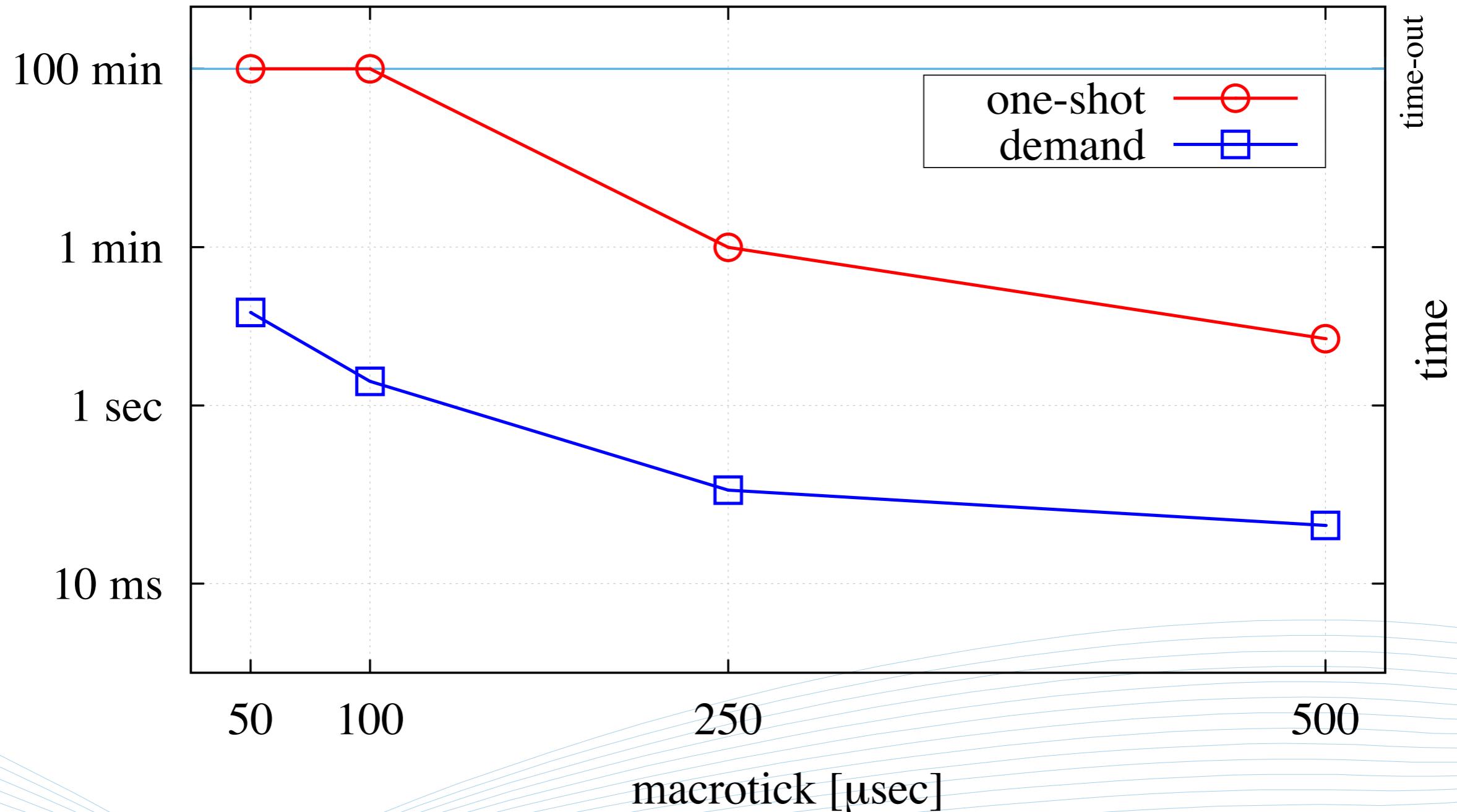
L (15, 48, 768, 192)

Periods {50,75} ms

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$P=\{10, 20, 25, 50, 100\}[\text{ms}]$, HP=100ms, Size=S, U=50%, T=MESH

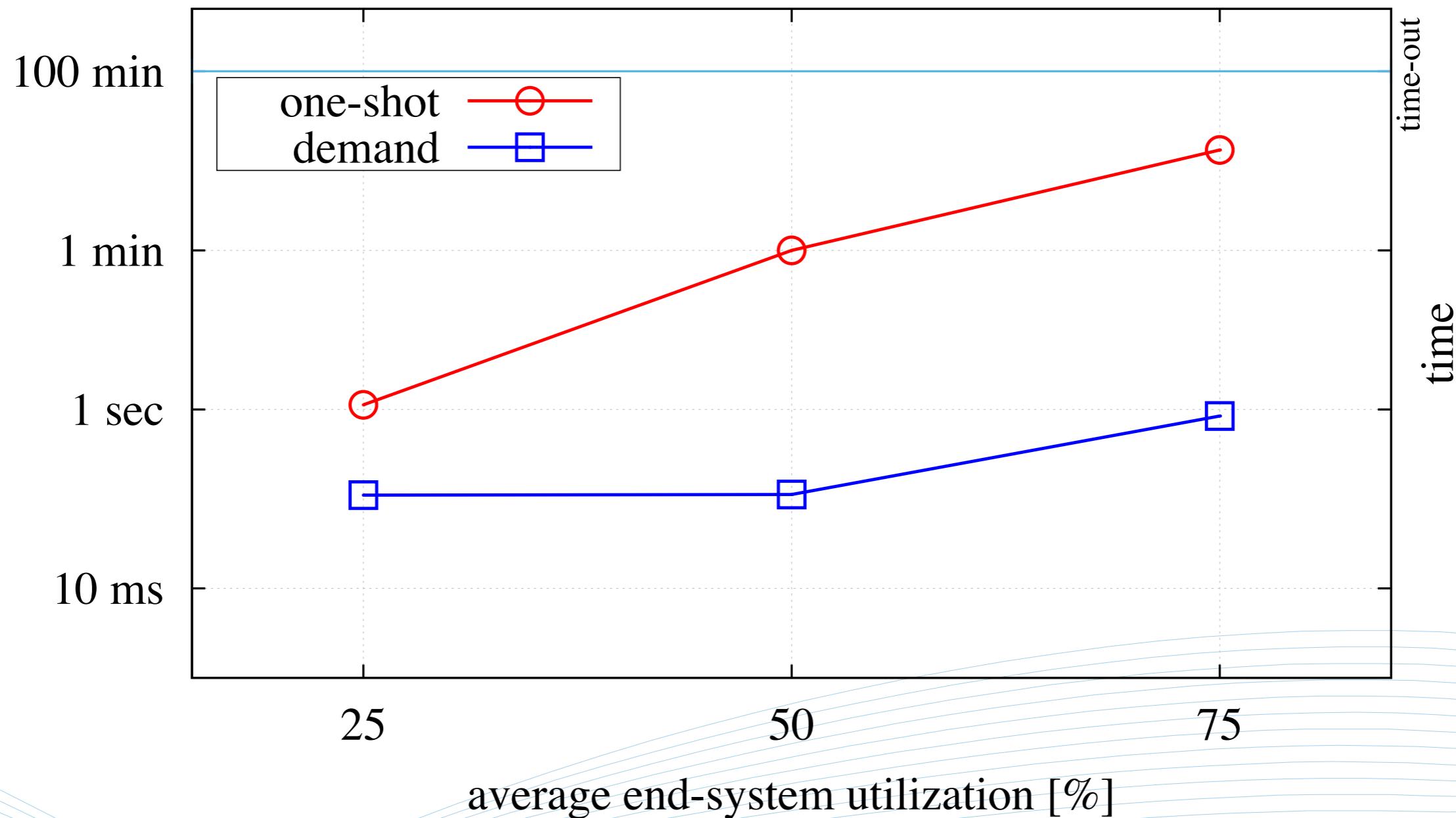


Utilization

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$P=\{10, 20, 25, 50, 100\}[\text{ms}]$, HP=100ms, MT=250 μ sec, Size=S, T=MESH

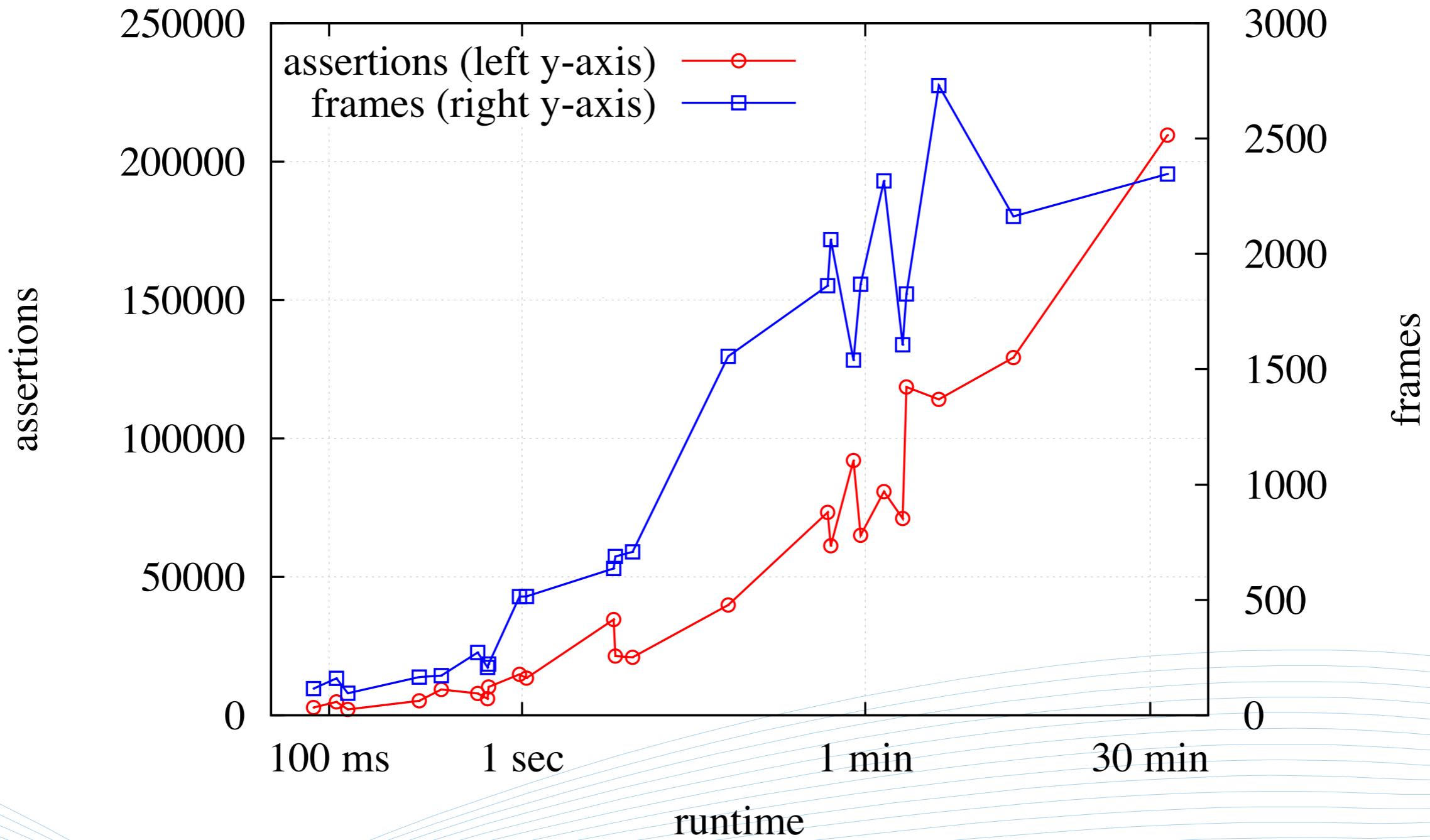


SMT assertions

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MT=250 μ sec, ALG=DEMAND



Conclusions

Conclusions

co-synthesis of task and message schedules



Conclusions

co-synthesis of task and message schedules
preemptive tasks



Conclusions

co-synthesis of task and message schedules

preemptive tasks

switched multi-speed TT Ethernet networks



Conclusions

co-synthesis of task and message schedules

preemptive tasks

switched multi-speed TT Ethernet networks

satisfiability modulo theories



Conclusions

co-synthesis of task and message schedules

preemptive tasks

switched multi-speed TT Ethernet networks

satisfiability modulo theories

demand based approach



Conclusions

co-synthesis of task and message schedules

preemptive tasks

switched multi-speed TT Ethernet networks

satisfiability modulo theories

demand based approach

scales for medium to large industrial systems



Thank you!

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SMT-scheduled frames

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