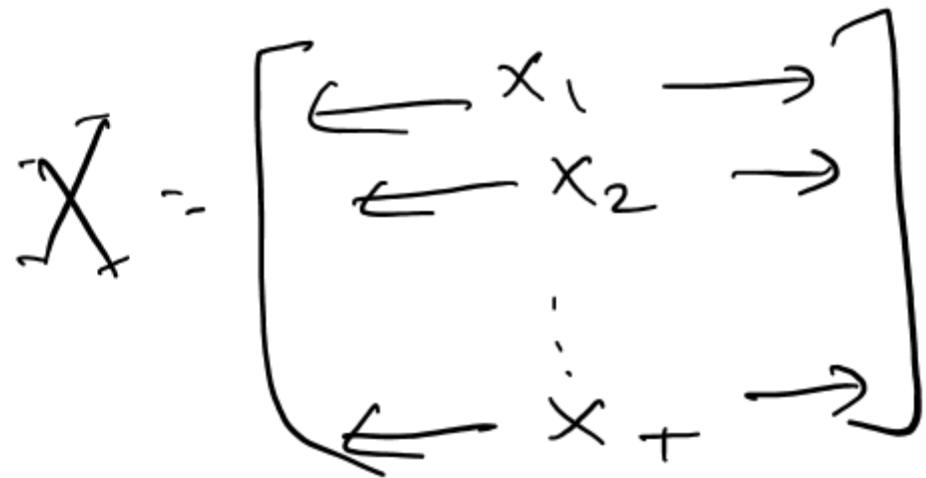


15-780: Graduate AI

Lecture 10: transformers continued

Aditi Raghunathan

Recap of self-attention



XW : treat rows
independently
"batching"

$$A \underline{X}$$

$$A(\underline{X}) \quad \bar{X}$$

Recap of self-attention

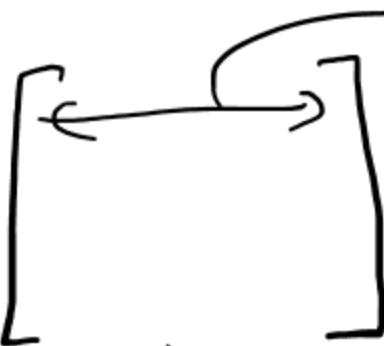
$$A = \text{softmax} \left(\frac{\underset{T \times d}{x^T w_q}}{\sqrt{d}} + \underset{T \times d}{w_k^T x} \right)$$

$y \in \mathbb{R}^{T \times d}$

$$y = (A) \underset{T \times d}{x^T w_v}$$

colored quantities are "learnt" (by SGD)

one set of linear coefficients



A

$$x \leftarrow \tilde{e}_{\text{the}} W_2 w^T e_{\text{quick}}$$

Properties of self-attention

Order invariant: permutations don't change the mixing

- Multi-head attention
- Full mixing: every word can depend on everything else, *masking*

Position embeddings

$$T \times d \quad \begin{bmatrix} x \\ \vdots \\ x \end{bmatrix} + \begin{bmatrix} E_{pos} \\ \vdots \\ E_{pos} \end{bmatrix} \quad E_{pos} \text{ depends on pos}$$

$$A(x) \rightarrow A(x + E) \neq A(x) + E$$

$$(x + E) W_Q W_K^T (x + E)^T$$

Position embeddings

→ $E_{\text{pos}} : u_{\text{pos}} \in \mathbb{R}^d$ that is learnt

→ "Sine embeddings"

$$E_{\text{pos}} = \begin{bmatrix} \sin c_1 \cdot \text{pos} \\ \cos c_1 \cdot \text{pos} \\ \sin c_2 \cdot \text{pos} \\ \cos c_2 \cdot \text{pos} \\ \vdots \end{bmatrix}$$

$$c_i = \left(\frac{i}{10,000} \right)^{1/d}$$

for $\text{pos} = 1 \dots T$

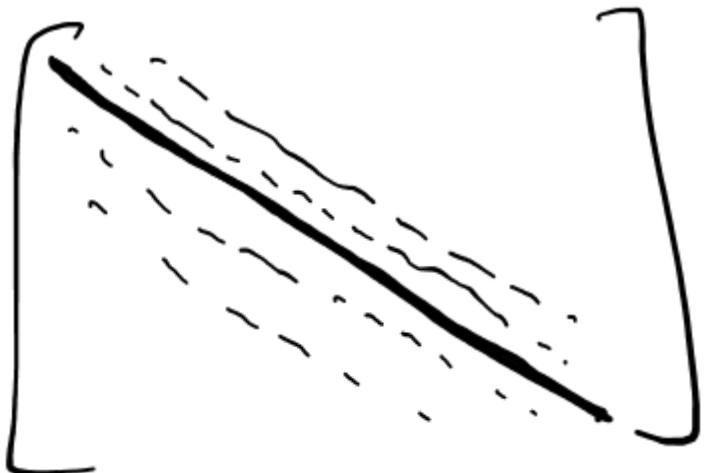
Interpretation of position embedding

For now, $w_Q, w_K \equiv \text{identity}$

$$A(x) = (x + \epsilon)(x + \epsilon)^T = \underbrace{xx^T}_{\text{original attention term}} + \cancel{x\epsilon^T} + \cancel{\epsilon x^T} + \underbrace{\epsilon\epsilon^T}_{\text{newly added}}$$

can ignore

$$\epsilon\epsilon^T =$$



large at diagonal and slowly decay



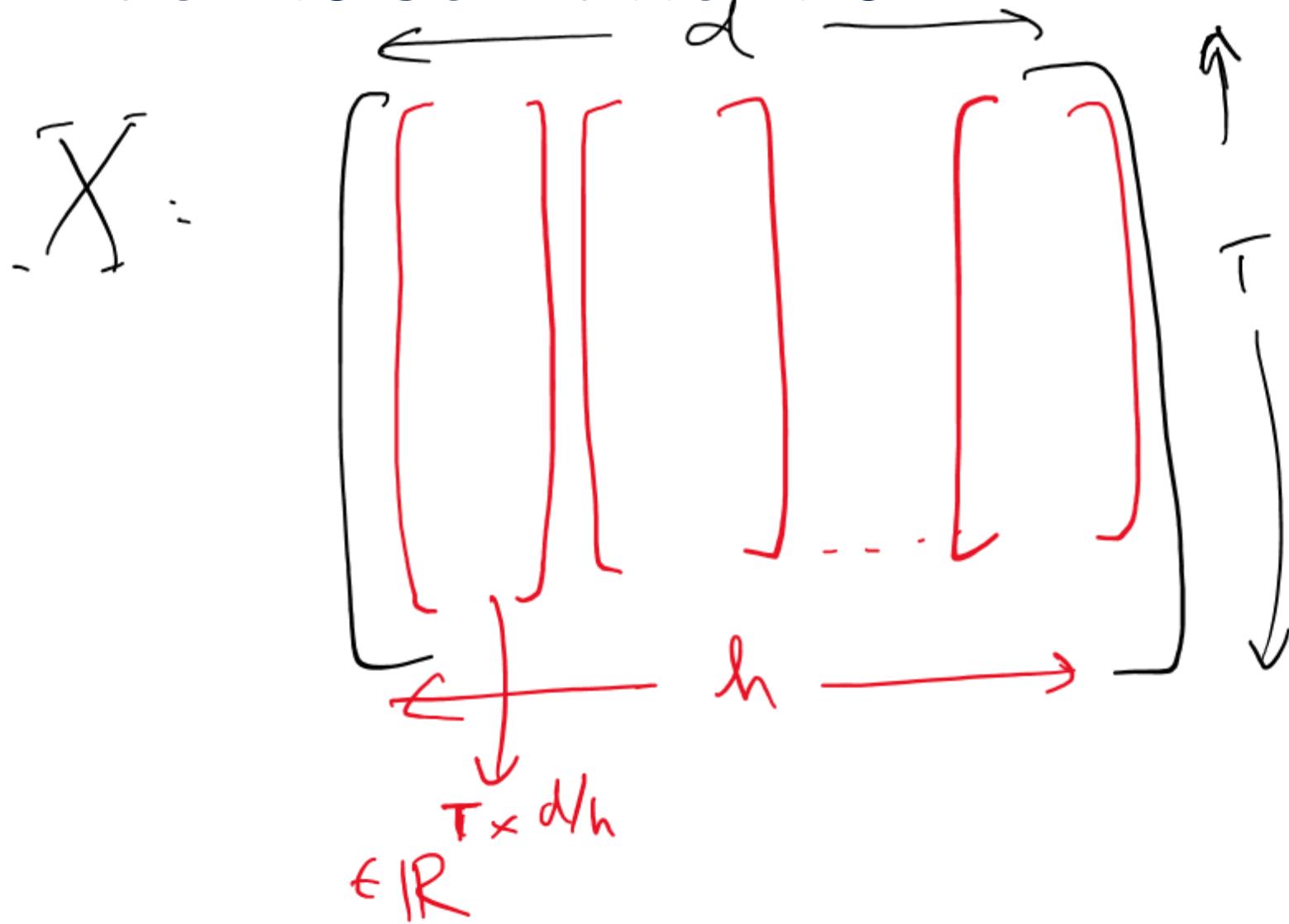
Relative embeddings

- $A(x) = xx^T + \epsilon E^T$
 \uparrow write the dot product directly
 $\rightarrow (E_i)^T (E_j) = \alpha_{ij} \rightarrow$ learnt ϵ
depends on $(j-i)$
- "rotary embeddings": E matrix that encodes relative position
 $*E$ (multiplied)

Back to self-attention

$$Y = AX$$

$$A = \text{softmax} \left(\frac{xw_q w_k^T x^T}{\sqrt{d}} \right)$$



h diff blocks

Back to self-attention

$$Y = A \tilde{X} = \begin{bmatrix} A \\ \vdots \end{bmatrix} \begin{bmatrix} \tilde{x}^{(1)} \\ \tilde{x}^{(2)} \\ \vdots \\ \tilde{x}^{(h)} \end{bmatrix}$$

$\tilde{Y} = \tilde{A} \tilde{X}$ mixes the rows

Same mixing vs different mixing

$$\begin{bmatrix} \lambda & (1-\lambda) \\ \beta & (1-\beta) \end{bmatrix} \begin{bmatrix} \bar{a}, \bar{b} \\ \bar{c}, \bar{d} \end{bmatrix} = \begin{bmatrix} \lambda \bar{a} + (1-\lambda) \bar{c} & \lambda \bar{b} + (1-\lambda) \bar{d} \\ \beta \bar{a} + (1-\beta) \bar{c} & \beta \bar{b} + (1-\beta) \bar{d} \end{bmatrix}$$

Piazza poll

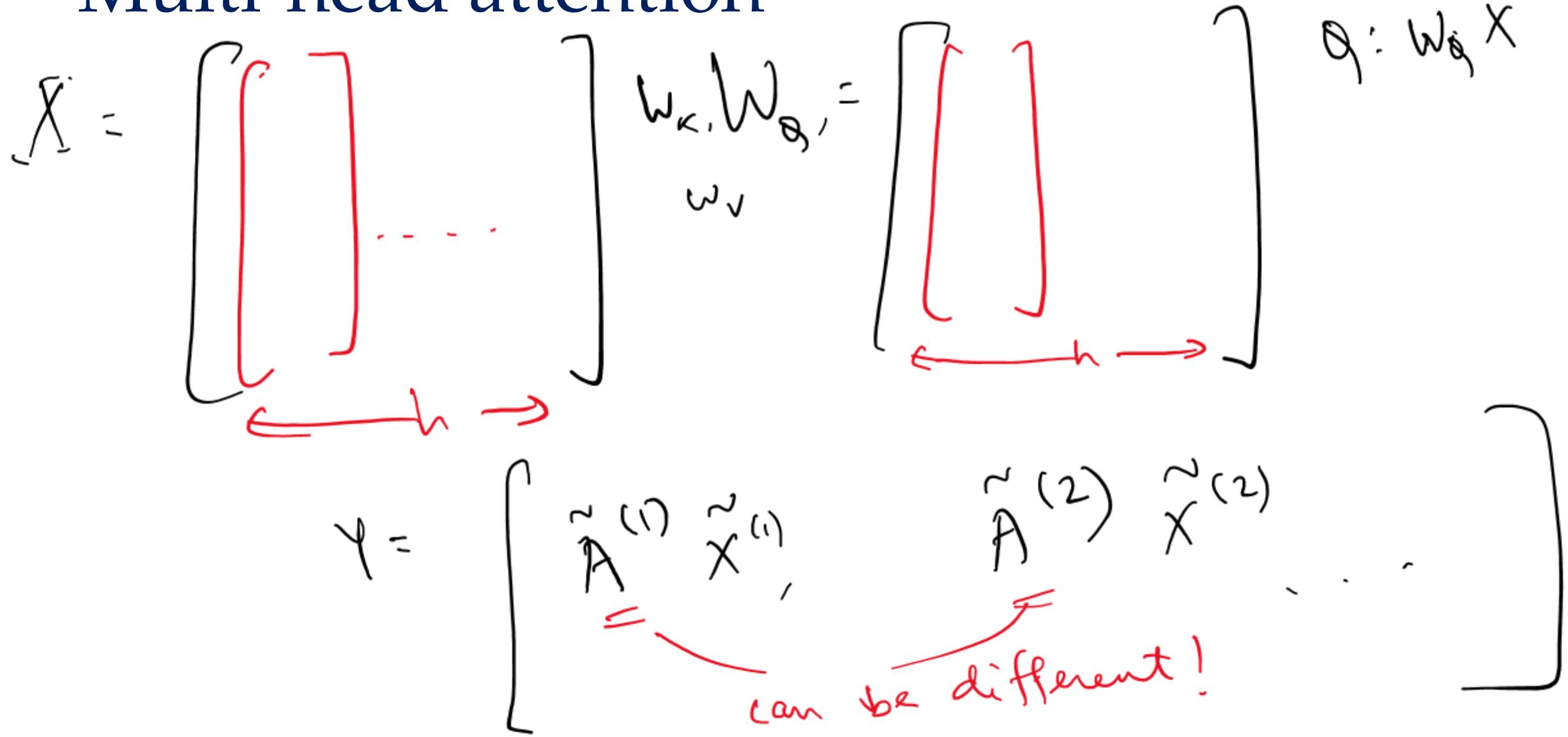
$$X = \left[\begin{array}{c} [] \\ [] \\ [] \\ \vdots \end{array} \right] \quad h \text{ diff blocks}$$

Select the true statements under the standard self-attention formulation $Y = A X$:

- ~~(A)~~ All blocks share the same linear combination or mixing
(B) Different blocks can have different mixing

we want
this in
practice

Multi-head attention



Multi-head attention

w_v : could be of higher dimensions

w_o : combines the different heads in some way

$$Y = \underbrace{A(x) \times w_v w_o}_{\text{multi-head}}$$

Transformer block

$$\begin{cases} Y = \text{LayerNorm} \left(X + \text{MSelfA}(X) \right) \\ Z = \text{LayerNorm} \left(Y + \sigma(XW_1)W_2 \right) \end{cases}$$

$Y \in \mathbb{R}^{T \times d_{\text{model}}}$

$d_{\text{model}} \times d_{\text{ff}}$

$W_1 \in \mathbb{R}^{d_{\text{model}} \times d_{\text{ff}}}$

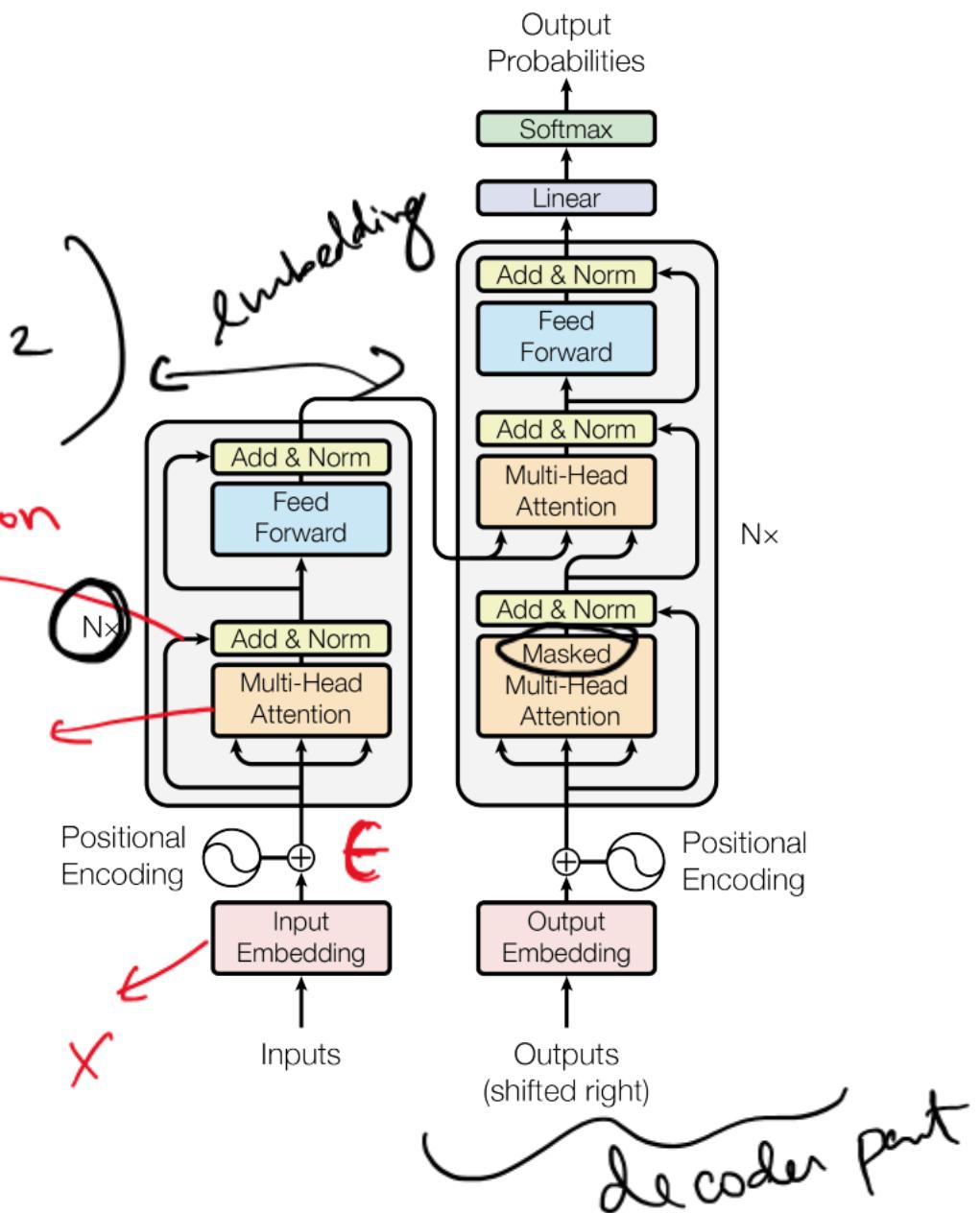
$d_{\text{ff}} \times d_{\text{model}}$

$W_2 \in \mathbb{R}^{d_{\text{ff}}}$



residual
normalization

w_k, w_q, w_v, w_o



GPT-3

- Dimension of hidden state: $d_{\text{model}}=12288$
- Dimension of the intermediate feed-forward layer: $d_{\text{ff}}=4d_{\text{model}}$
- Number of heads: $n_{\text{heads}}=96$
- Context length: $L=2048$

Masking

- A way to set certain attention scores to zero

A: completely determined by $w_Q, w_K, w_V, \epsilon, x$



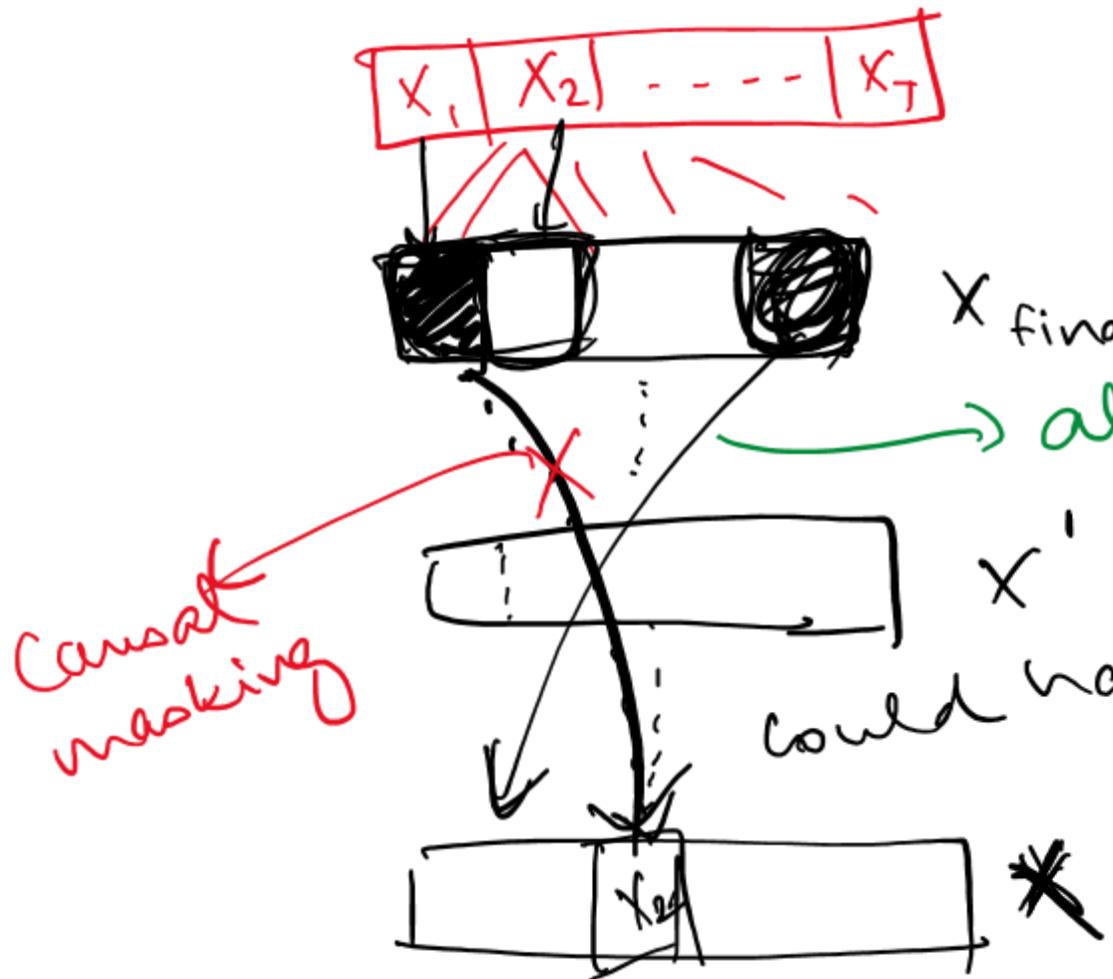
Masking

$$P(x_i | x_1, \dots, -i)$$

"Causal masking"

$$y = [x_1, x_2, \dots, x_T]$$

$$x = [x_1, \dots, x_T]$$

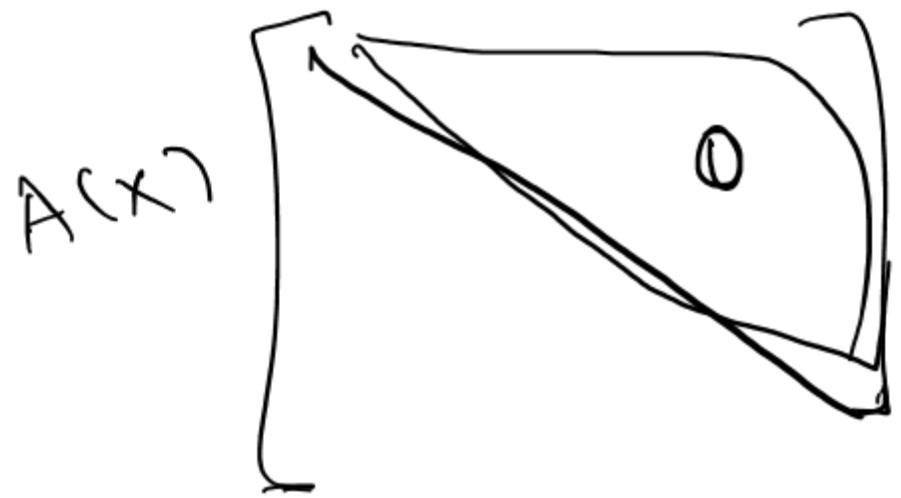


\rightarrow contextual embedding

$$x_{\text{final}} \in \mathbb{R}^{T \times d}$$

Causal
masking

x'
could have mixed information



$$A(x) = \text{softmax}$$

$$K Q^T + \begin{bmatrix} & -\infty \\ 0 & \end{bmatrix}$$

$$A_{ij} = 0 \quad \text{if } j > i$$

Summary

- You know how to build GPT3!

} train by minimizing
loss via Adam

→ MLPs

→ Add Norm

→ Self Attention

→ position embeddings

mult-head

masking