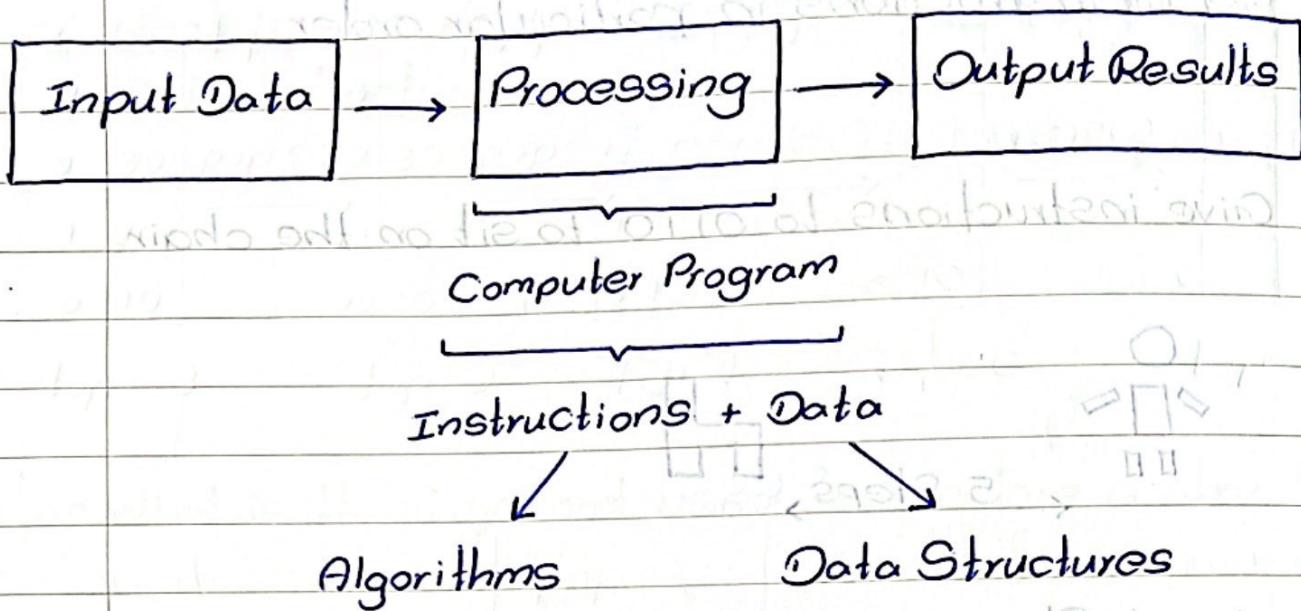


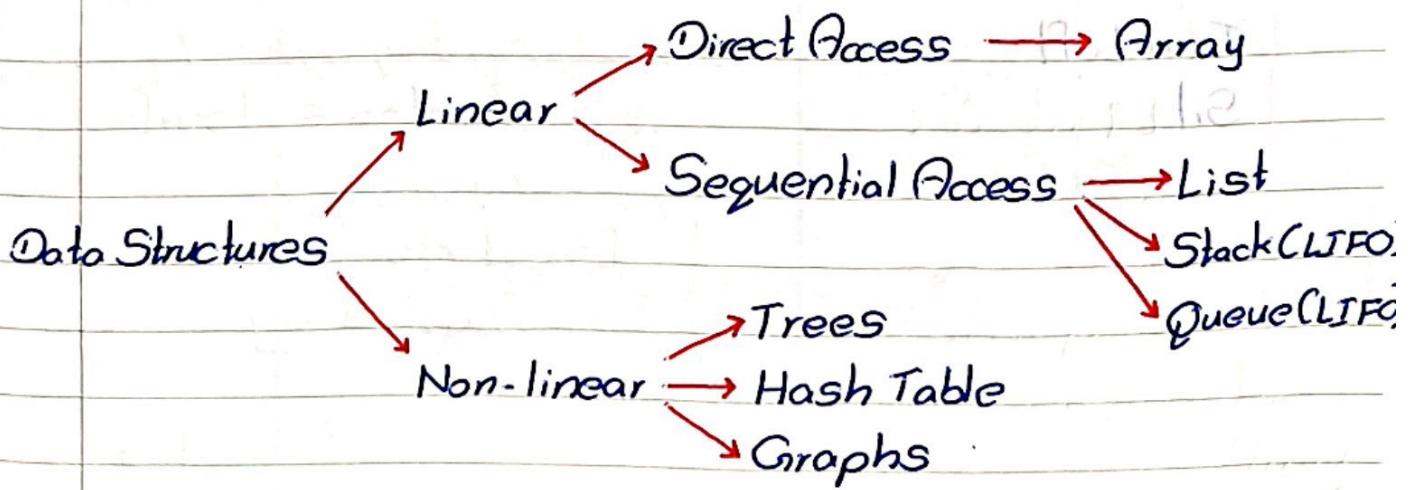
Context of Computing



Data Structures

A way of storing data or it's a memory arrangement

Data Structures Classification

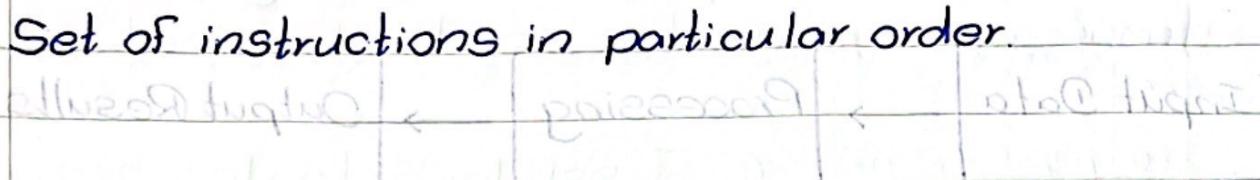


* LIFO → Last In First Out.
* FIFO → First In First Out.

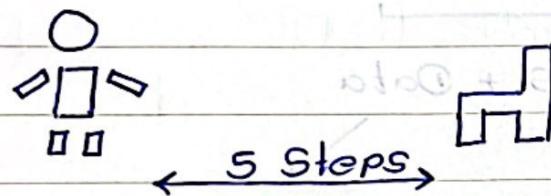
ProMate

Algorithms.

Set of instructions in particular order.



Give instructions to OTTO to sit on the chair.



Turn Left

Walk

Walk

Walk

Walk

Turn Left

Turn Left

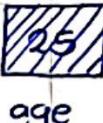
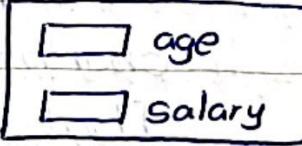
Sit

Edgar

Structures in C

Q1. What is the main difference between an array and a structure?

Q2. What is the keyword used to declare a structure?

Variable	Structure	Array			
<pre>int age;</pre> <p style="text-align: center;">↑ data type</p> <p style="text-align: center;">variable name</p> 	<pre>struct employee { int age; float salary; };</pre> 	<pre>char arr [3];</pre> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr> <td>T</td><td>O</td><td>M</td> </tr> </table>	T	O	M
T	O	M			

Assume we need to store empID, name and salary of each employee.

Declare a structure to store above components.

```
struct employee {  
    int empID;  
    char name [10];  
    float salary;  
};
```

* Do not initialize values inside the declaration.

Use the above declared structure to store structure variables for each employee.

There're 3 employees working.

Method 01: (with structure definition)

```
struct employee {  
    int empID;  
    char name [10];  
    float salary;  
};  
emp1, emp2, emp3;
```

Method 02: (seperately)

```
struct employee {  
    int empID;  
    char name [10];  
    float salary;  
};
```

```
struct employee emp1, emp2, emp3;
```

Use the above declared structure and structure variables to store details of each employee.

```
emp1.empID = 1290;  
strcpy(emp1.name, "John");  
emp1.salary = 345.67;
```

Struct employee emp1 = {1290, "John", 345.67};

```
#include <stdio.h>  
#include <string.h>  
  
struct employee {  
    int empID;  
    char name [10];  
    float salary;  
};  
  
int main () {  
    struct employee emp1;  
    emp1.empID = 1290;  
    strcpy(emp1.name, "John");  
    emp1.salary = 345.67;
```

```
printf("EmpID of emp1 is %d \n", emp1.empID);
printf("Emp Name of emp1 is %s \n", emp1.name);
printf("Emp Salary of emp1 is %f \n", emp1.salary);

return 0;
}
```

```
#include <stdio.h>
#include <string.h>

struct employee {
    int empID;
    char name [10];
    float salary;
};

int main ()
{
    struct employee emp1 = {1290, "John", 345.67};

    printf("EmpID of emp1 is %d \n", emp1.empID);
    printf("Emp Name of emp1 is %s \n", emp1.name);
    printf("Emp Salary of emp1 is %f \n", emp1.salary);

    return 0;
}
```

```
#include <stdio.h>
#include <string.h>

typedef struct {
    int empID;
    char name[10];
    float salary;
} employee;

int main() {
    employee emp1 = {100, "John", 350.90};
    emp1.empID = 100;
    strcpy(emp1.name, "John");
    emp1.salary = 350.90;

    employee emp3 = {200, "John2", 450.80};

    printf("Details: %s", emp3.name); // just to check
                                    // whether values
                                    // are stored.

    return 0;
}
```

Structure.

A structure is a user defined data type in C language that allows us to combine different types.

Structure helps to construct a complex data type that is more meaningful.

Defining a Structure.

```
struct [structure_tag] {  
    //member variable 01  
    //member variable 02  
    //member variable 03  
    ...  
} [structure_variables];
```

Example:

```
struct Employee {  
    char name [50];  
    int empID;  
    char name [50];  
    float salary;  
};
```

o nuburde a la pista

o nuburde a la pista

o nuburde a la pista no se le dio el aviso

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o nuburde a la pista no se le dio el aviso

Array of Structure.

We can also declare an array of structure variables, in which each element of the array will represent a structure.

Example:

```
struct employee emp [5];
```

The below program defines an array emp of size 5. Each element of the array emp is of type employee.

```
#include <stdio.h>
```

```
struct employee {  
    int sal;  
    char name [10];  
};
```

```
struct employee emp [5];  
int i, j;
```

```
void ask () {
```

```
for (i=0; i<3; i++) {  
    printf ("\n Enter %dst employee record \n",  
           i+1);  
    printf ("\n Employee name \t");  
    scanf ("%s", &emp[i].name);  
    printf ("\n Salary \t");  
    scanf ("%d", &emp[i].sal);  
}  
  
printf ("\n Displaying Employee Record \n");  
for (i=0; i<3; i++) {  
    printf ("\n Employee name is %s", emp[i].name);  
    printf ("\n Salary is %d", emp[i].sal);  
}  
  
void main() {  
    ask();  
}
```

```
#include <stdio.h>
#include <conio.h>
struct employee {
    int empID;
    char name[10];
    float salary;
};
```

```
struct employee emp1 = {1290, "John", 345.67};
```

```
struct employee emp[5];
```

```
int i;
```

```
void main() {
```

```
    for (i = 0; i <= 3; i++) {
```

```
        printf("Enter emp %d ID", i);
```

```
        scanf("%d", &emp[i].empID);
```

```
        printf("Enter emp %d name", i);
```

```
        scanf("%s", &emp[i].name);
```

```
        printf("Enter emp %d salary", i);
```

```
        scanf("%f", &emp[i].salary);
```

```
}
```

```
void out () {
```

```
    printf ("Printing Employee Details\n");
```

```
    for (i=1; i<=3; i++) {
```

```
        printf ("Employee %d ID, %d name, %f  
            salary\n", i, emp[i].empID, emp[i].name,  
            emp[i].salary);
```

```
}
```

```
{
```

```
int main () {
```

```
    in();
```

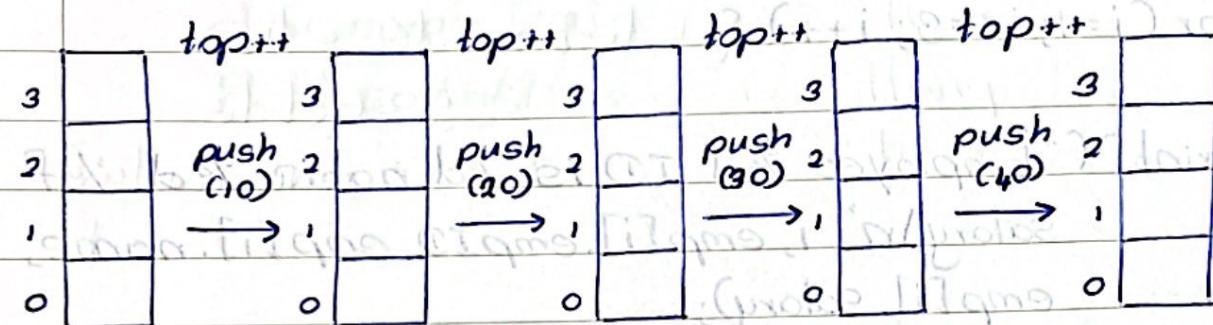
```
    out();
```

```
    return 0;
```

```
}
```

Stacks in C (LIFO) - Last In First Out

Push Operation

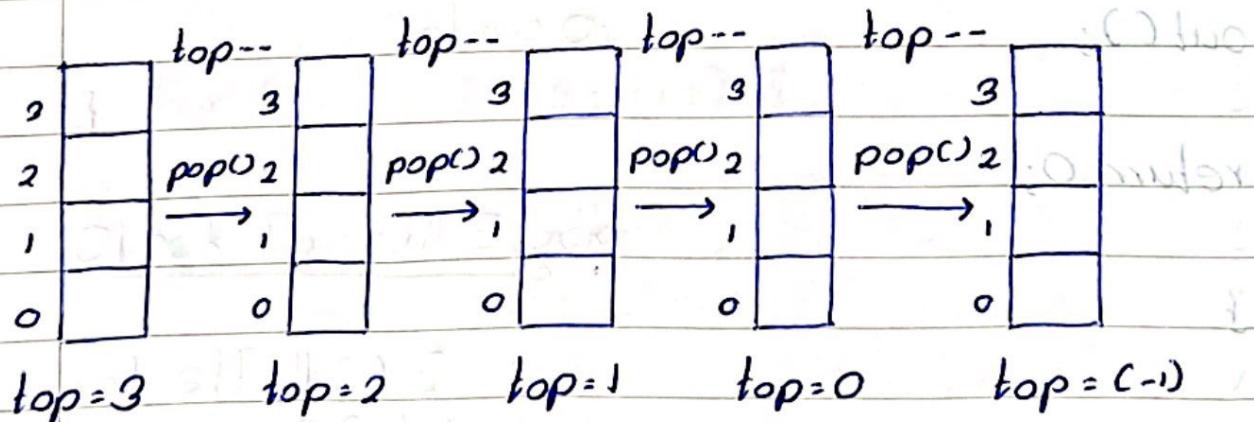
 $\text{top} = -1$

(Initial)

 $\text{top} = 0$ $\text{top} = 1$ $\text{top} = 2$ $\text{top} = 3$

push (ele)

Pop Operation

 $\text{top} = 3$ $\text{top} = 2$ $\text{top} = 1$ $\text{top} = 0$ $\text{top} = -1$

pop ()

Creating a New Stack

```
#define size 5
```

```
//stack structure
```

```
struct stack {
```

```
    int arr [size];
```

```
    int top;
```

```
} st;
```

→ st.arr []

→ st.top



Inserting an Element - (Push)

```
void push (int ele) {
```

```
    st.top++;

```

```
    st.arr [st.top] = ele;
}
```

* Added to the top of the stack.

3 () (Hello for

(1-size <= st.top) ?

else

{0 marks}

ProMate

Removing an Element - Pop

```
int pop() {
    int out;
    out = st.arr[st.top];
    st.top--;
    return out;
}
```

* Removed from the top of the stack.

Check for Empty Stack.

```
int stempty() {
    if (st.top == -1) return 1;
    else return 0;
}
```

Check for Full Stack.

```
int stfull() {
    if (st.top >= size - 1) return 1;
    else return 0;
}
```

Evaluate a Postfix Notation Using Stacks.

Algorithm: maintain a stack and scan the postfix expression from left to right.

If the element is a number, push it into the stack.

If the operator is an operator O, pop twice and get A and B respectively.

Calculate $B \text{ } O \text{ } A$ and push it back to the stack.

When the expression is ended, the number in the stack is the final answer.

Edged 2-petal star shape after 9.6 orbit

number of antecedents in the model.

xit engsoft mode base. Has been a significant challenge!
- feedback from most stakeholders

ofici intanto, vediamo di tenere conto dell'eff

the following state off

2019/2020. O resultado da auditoria está na figura 27.

development & has a top bar

9/27 At about 11:30 AM, the AOE started

① ② ③ ④ ⑤ ⑥ ⑦ ⑧ ⑨ ⑩ ⑪ ⑫ ⑬ ⑭ ⑮ ⑯ ⑰ ⑱ ⑲ ⑳

Mapeo de los sectores y establecimientos en los que se realizan las actividades de generación de empleo.

...söndagen föll en dagsbok om medborgarskapet.

Page 1

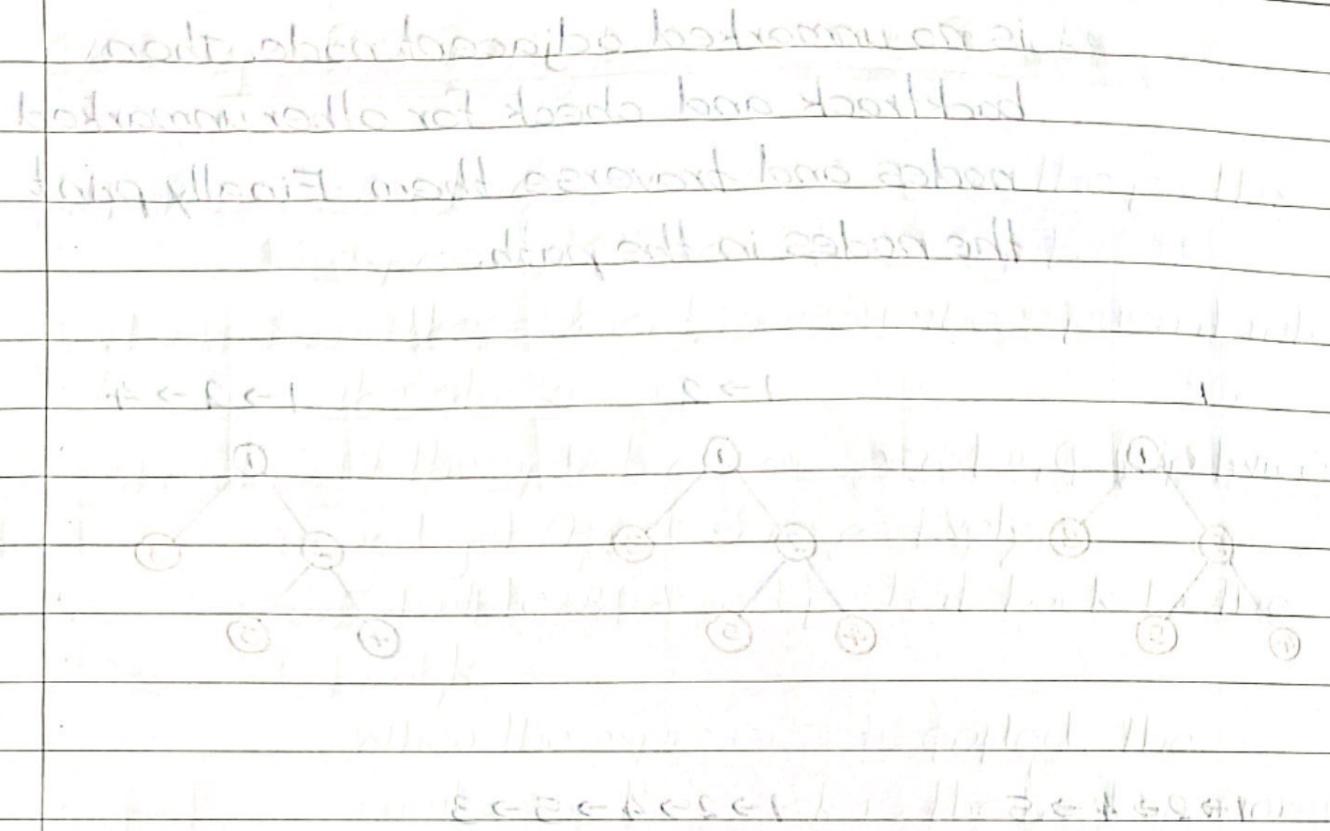
Digitized by srujanika@gmail.com

10. *What is the name of the author of the book?*

10. *What is the name of the author of the book?*

For more information about the study, please contact Dr. John P. Morrissey at (212) 639-7300 or via email at jmorrissey@nyp.edu.

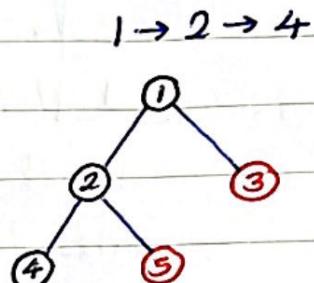
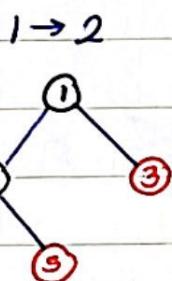
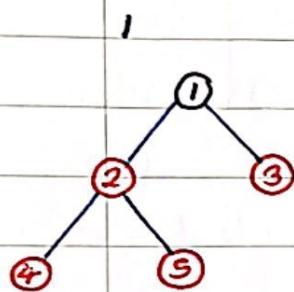
10. The following table shows the number of hours worked by 1000 employees in a company.



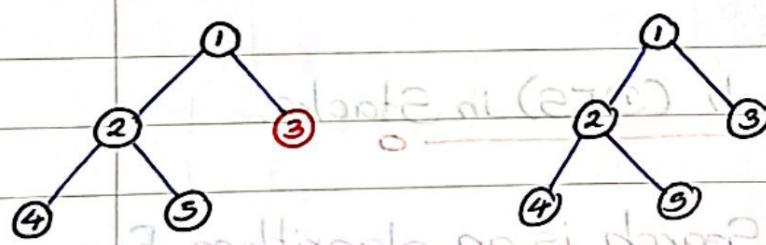
Using Depth First Search (DFS) in Stacks.

Approach: Depth First Search is an algorithm for traversing or searching tree or graph data structures. The algorithm starts at the root node (selecting some arbitrary node as the root node in the case of a graph) and explores as far as possible along each branch before backtracking. So the basic idea is to start from the root or any arbitrary node and mark the node and move to the adjacent unmarked node and continue this loop until there

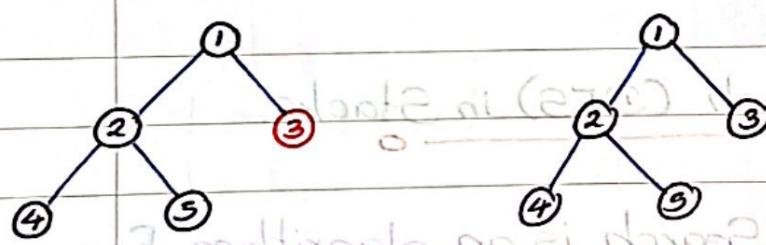
is no unmarked adjacent node. Then backtrack and check for other unmarked nodes and traverse them. Finally print the nodes in the path.



$1 \rightarrow 2 \rightarrow 4 \rightarrow 5$



$1 \rightarrow 2 \rightarrow 4 \rightarrow 5 \rightarrow 3$



Queues in C (FIFO) - First In First Out

There're 2 types of Queues.

01. Linear Queue.

02. Circular Queue.

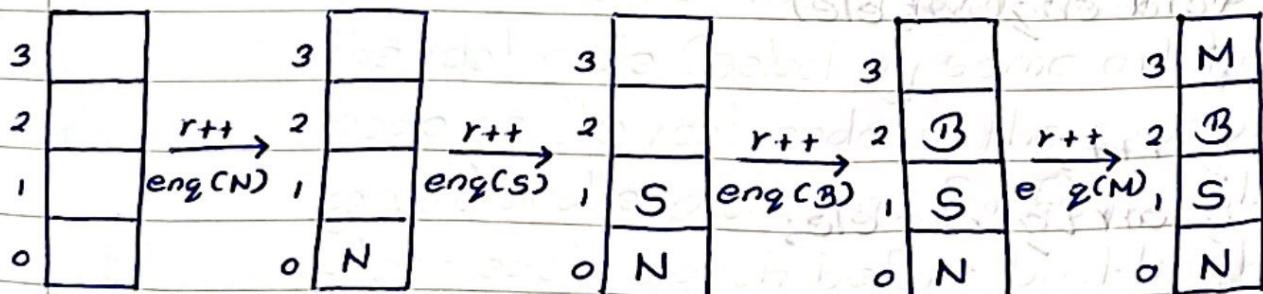
01) Linear Queue.

* Insert element \rightarrow eng

* Remove element \rightarrow deg

N, S, B, M

Eng Operation.



front=0

front=0

front=0

Front=0

front=0

rear=-1

rear=0

rear=1

rear=2

rear=3

Deg Operation

3	M	3	M	3	M	3	M	3	
2	B	2	B	2	B	2		2	
1	S	1	S	1		1		1	
0	N	0		0		0		0	

front =

rear =

#define size 5

struct queue {

int arr [size];

int r,f;

} q;

M S P N

void enq(int ele)

{

q.r++;

q.arr[q.r] = ele;

}

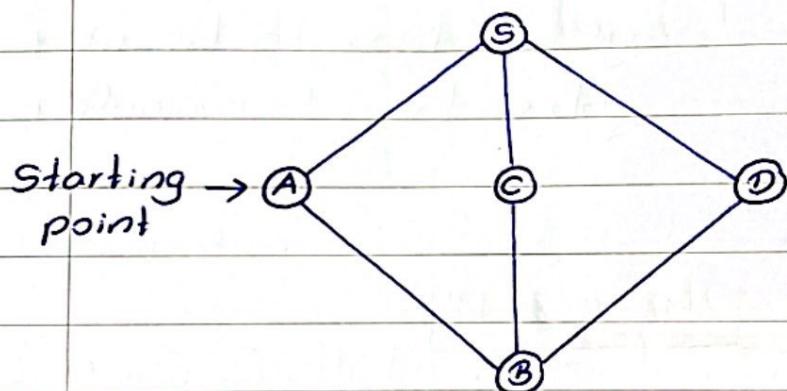
int deg()

{

int.out;

```
out = q.arr[q.f];
q.f++;
return out;
}
```

Breadth First Search



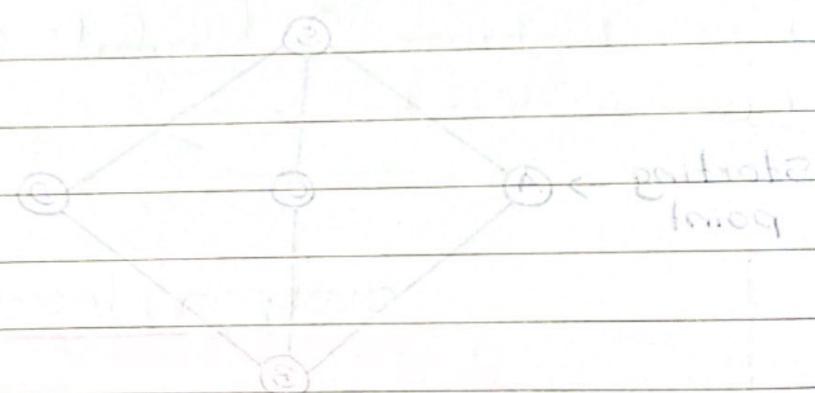
Tuesday 28th March 2017
Biology class notes

17.3.2017

Light energy - photosynthesis

Chlorophyll - light energy - energy conversion

Light energy - photosynthesis



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2020-09-26

Creating a new Queue.

#define size 5

//Queue structure.

```
struct queue {  
    int q [size];  
    int rear = -1, front = 0;  
} st;
```

Inserting an Element; enqueue

```
void enqueue (int item)  
{  
    st.rear++;  
    st.q [st.rear] = item;  
}
```

* Added to the rear of the queue.

* Before you should check for the queue is full or not.

Removing an element; dequeue

int dequeue()

{

 int item;

 item = st.s[st.front];

 st.front++;

 return(item);

}

- * Removed the front item from the queue.

Check for Empty Stack

(rear == MAX)

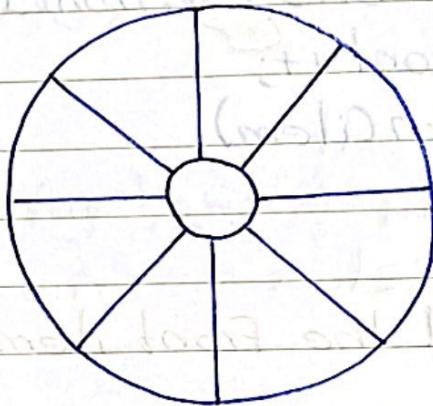
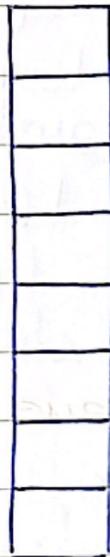
Check for Full Stack

(front == rear)

- * Efficiency of insert / remove from queue is O(1)

02.) Circular Queue

Linear queue $\xrightarrow{\text{wrapping}}$ Circular queue.



* Declare all the elements.

Array
Front = -1
rear = -1

* Function to perform enqueue.

→ Empty
→ Full
→ Few elements

* Function to perform deque

- Full / Few
- Empty
- Single.

```
#include <stdio.h>
```

```
int arr[5];
```

```
int Front = -1;
```

```
int rear = -1;
```

```
// Function to perform enq
```

```
void enqueue(int x) {
```

```
    if (Front == -1 && rear == -1) {
```

```
        front = 0;
```

```
        rear = 0;
```

```
// Access the rear
```

```
arr[rear] = x;
```

```
}
```

```
if else ((rear + 1) % 5 == front) {
```

```
    printf ("Queue is Full");
```

```
}
```

```
else {  
    rear = (rear + 1) % N;  
    arr[rear] = n;  
}
```

// Function to perform deg

```
void dequeue () {  
    if (front == -1 && rear == -1) {  
        printf ("No elements");  
    }
```

```
    else if (rear == front) {  
        printf ("%d", arr[front]);  
    }
```

Front = -1;

rear = -1; } (extra) unsigned long

```
} (extra) 22 (1-1000) 73
```

Queue in Action

Active part of the queue keeps on moving and hit the array limit at some stage

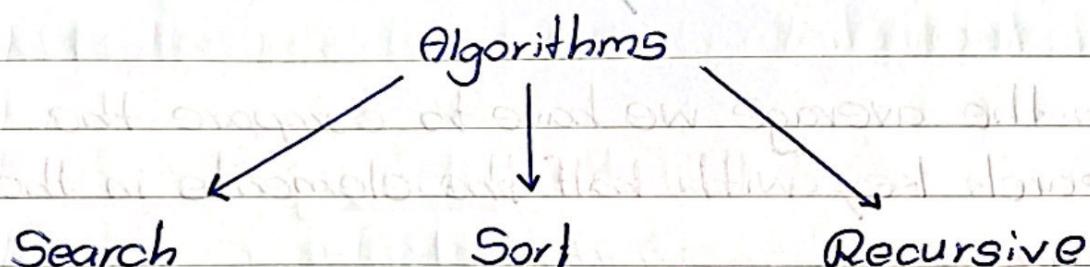
(initial = 3 & (max)) add 7

(initial = 3) 7 long.

Applications

- Print Queue.
- Buffers for communication between two entities.
 - Network cards need a packet buffer.
 - Secondary storage write through buffer.

Searching Algorithms



Linear

- Small, unsorted arrays.

Binary

- Large sorted arrays.

Linear Search Algorithm

- 01.) Start at the first element of array.
 - 02.) Compare value to value (key) for which you're searching.
 - 03.) Continue with next element of the array until you find a match or reach the last element in the array.
- * On the average we have to compare the search key with half the elements in the array.

0	1	2	3	4	5
10	20	30	40	50	60

Search Key = 40
(SK)

A [0] == SK? X
A [1] == SK? X
A [2] == SK? X
A [3] == SK? ✓

number	10	100	1000
case			
Best	0 th		
Average	4 th mid		
Worst	9 th (end) not found		

$t_1 \quad t_2 \quad t_3$

Time taken for 10 is t_1 , for 100 is t_2 , for 1000 is t_3

Worst case:

$$10 \rightarrow t_1$$

select + branch + loop + branch + loop

$$100 \rightarrow t_2$$

select + branch, < t_2 < t_3

$$1000 \rightarrow t_3$$

loop + selection + branch + loop

$$10 \rightarrow t_1$$

select + branch + loop + branch + loop

$$100 \rightarrow t_2$$

select + branch, < t_2 < t_3

$$1000 \rightarrow t_3$$

loop + selection + branch + loop

$$t \propto N$$

Increasing number

- * For a larger data set, linear search won't work.
Because when the time increase, the performance of the algorithm decrease.
- * Linear search algorithm is suitable for small data sets. (sorted or unsorted.)

Algorithm

```
int lsearch (int arr[], int sk, int N) {  
    bool found = false;  
    int position = -1;  
    int index = 0;  
  
    while (index < N && !found) {  
        if (arr[index] == sk) {  
            position = index;  
            found = true;  
        }  
        index++;  
    }  
    return position;  
}
```

Ex:	-1	0	1	2	3	4	5
	10	2	15	25	18	30	

SK = 18

index	arr[index]	SK	found	position
0	10	18	F	-1
1	2	18	F	-1
2	15	18	F	-1
3	25	18	F	-1
4	18	18	T	4

* If $SK \neq arr[index]$,
found & position will remain same.

A Linear Search Function.

```
int searchlist (int list[], int numelems, int value) {
    int index = 0; // used as a subscript to search array
    int position = -1; // to record position of search value
    bool found = false; // flag to indicate if value was found
    while (index < numelems && !found) {
        if (list[index] == value) // if the value is found {
            found = true; // set the flag
            position = index; // record the value's subscript
    }
}
```

```
    }  
    index++; //go to the next element  
}
```

```
return position; //return the position, or -1
```

```
} //Binary search algorithm
```

Binary Search Algorithm

- 01) May only be used on a sorted array.
- 02) Eliminates one half of the elements after each comparison.
- 03) Locate the middle of the array.
- 04) Compare the value at that location with the search key.
- 05) If they're equal - DONE!
- 06) Otherwise, decide which half of the array contains the search key.
- 07) Repeat the search on that half of the array and ignore the other half.
- 08) The search continues until the key is matched or no elements remain to be searched.

3. $f(l, r) \rightarrow$ sort & binary search

4. $o(l, r) \rightarrow$ binary search

0	1	2	3	4	5
10	2	15	25	18	30

$$SK = 18$$

↓ sorting

midI

0	1	2	3	4	5
2	10	15	18	25	30

lower boundary (LB) upper boundary (UB)

$$\boxed{midI = \frac{f + l}{2}} = \frac{0 + 5}{2} = 2.5 \rightarrow 2$$

01) $\underbrace{arr[midI]}_{15} == \underbrace{SK}_{18}$

02) $\underbrace{arr[midI]}_{15} > \underbrace{SK}_{18} \parallel LB$

$$l = midI - 1;$$

03.) II U3

81 = 18	30	81	25	21	5	10
---------	----	----	----	----	---	----

$$f = \text{midI} + 1$$

$$\frac{Q + R}{2} = \frac{2 + 0}{2} = \frac{1 + 7}{2} = \text{mid}$$

```
while(!found && first <= last) {
```

```
    int midI = (first + last) / 2;
```

```
    if (arr[midI] == sk) {
```

```
        found = true;
```

```
        position = midI;
```

```
    } else if (arr[midI] > sk) {
```

```
        last = midI - 1;
```

```
    } else {
```

```
        first = midI + 1;
```

```
}
```

```
}
```

```
return position;
```

```
}
```

Ex: -1	0	1	2	3	4	5
	2	10	15	18	25	30

SK = 18

First	last	midI	arr[midI]	SK	found	position
0	5	2	15	18	F	-1
3	5	4	25	18	F	-1
3	3	3	18	18	T	3

if the SK = 12 (within the boundary (2-30))

First	last	midI	arr[midI]	SK	found	position
0	5	2	15	12	F	-1
0	1	0	2	12	F	-1
1	1	1	10	12	F	-1

if the SK = 35 (outside the boundary)

first	last	midI	arr[midI]	SK	found	position
0	5	2	15	35	F	-1
3	5	4	25	35	F	-1
5	5	5	30	35	F	-1

Efficiency of Binary Search.

- * Searching an array of 1024 elements will take at most 10 passes to find a match or determine that the element does not exist in the array.

- 512, 256, 128, 64, 32, 16, 8, 4, 2, 1

- * An array of one billion elements takes a maximum of 30 comparisons.

- * The bigger the array the better a binary search is as compared to a linear search

A Binary Search Function.

```
int binarySearch(int arr[], int size, int value){
    int first = 0, //First array element
        last = size - 1, //last array element
        middle, //mid point of search
        position = -1; //position of search value
    bool found = false; //Flag
    while (!found && first <= last) {
        middle = (first + last) / 2; //calculate mid point
        if (arr[middle] == value) { //if value is found at mid
            found = true;
        }
    }
}
```

```

position = middle;
3
else if (arr[middle] > value)
    last = middle - 1; //if value is in lower half
else
    first = middle + 1; //if value is in upper half
3
return position;
3

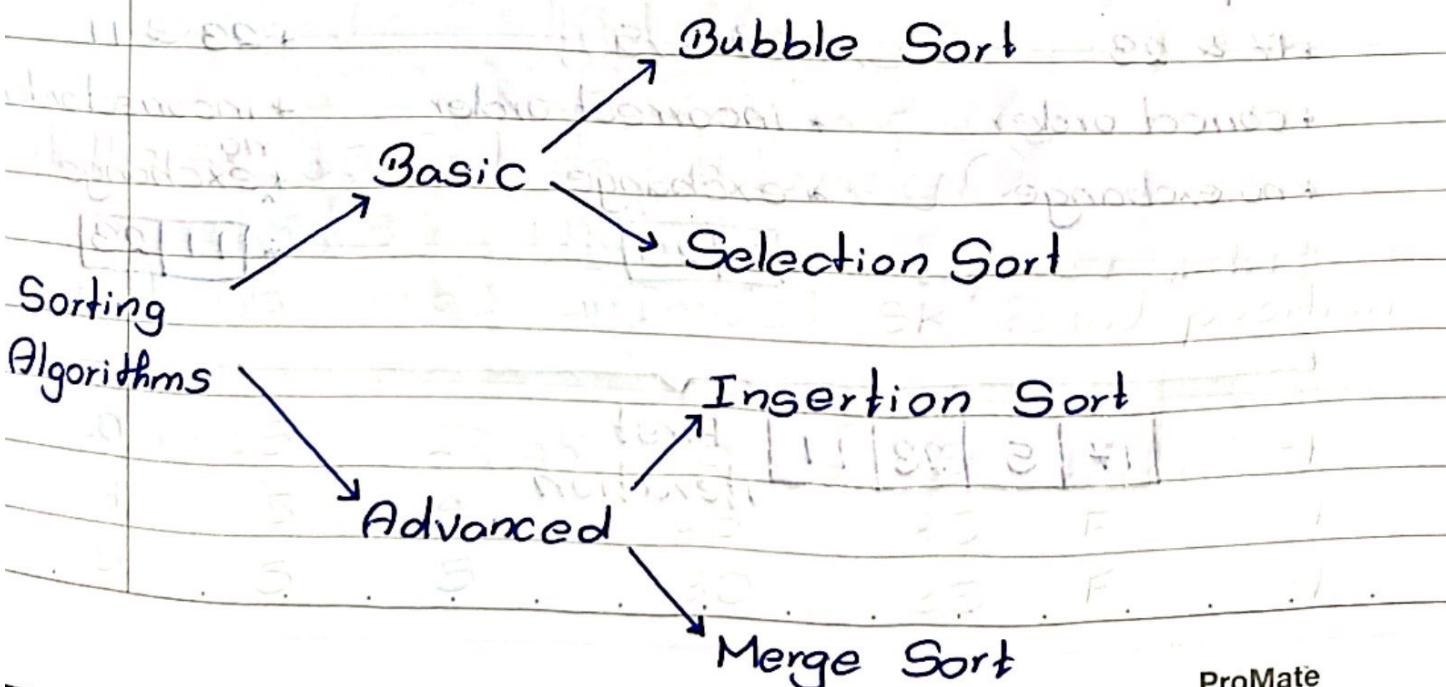
```

Introduction to Sorting Algorithms

* Sorting methods: Alphabetical.

Ascending numeric.

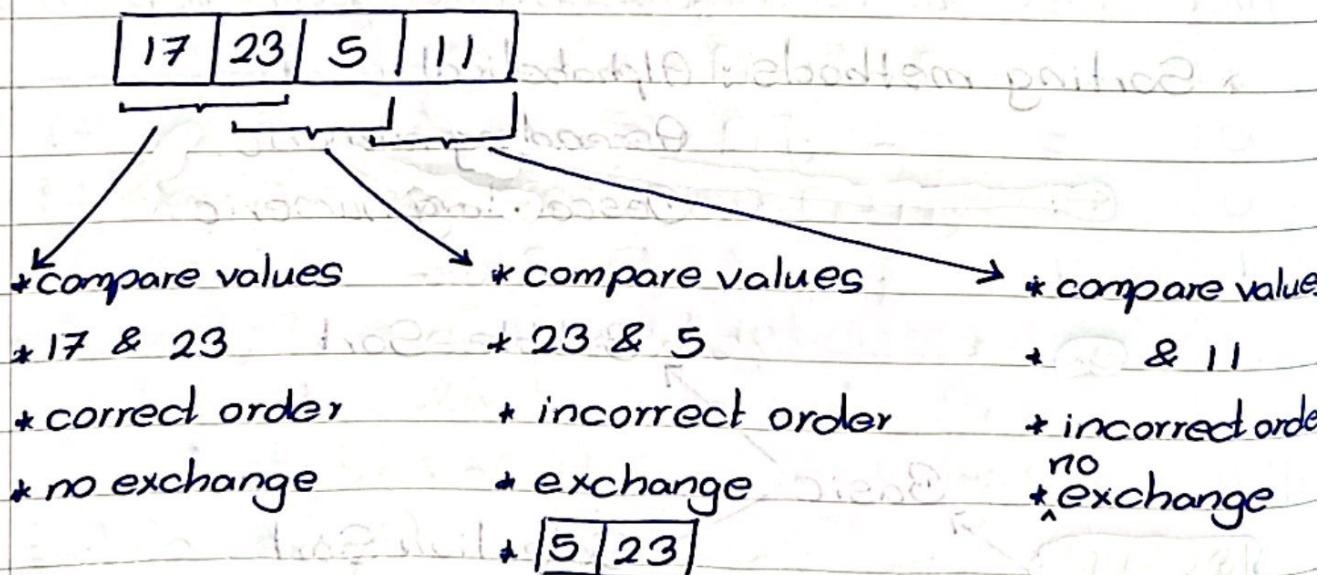
Descending numeric.



Bubble Sort

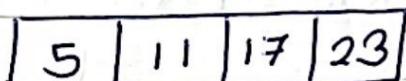
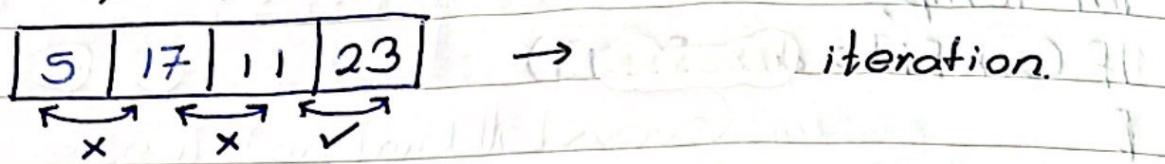
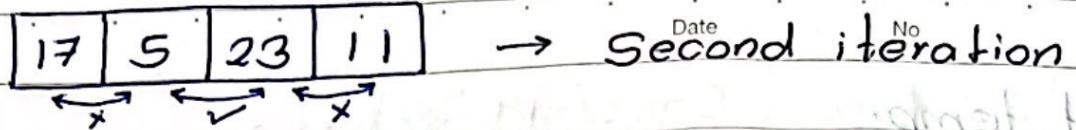
- 01.) Compare 1st two elements.
- * If out of order, exchange them to put in order.
- 02.) Move down one element, compare 2nd and 3rd elements, exchange if necessary.
- 03.) Continue until end of array.
- 04.) Pass through array again, exchanging, as necessary.
- 05.) Repeat until pass made with no exchanges.

Ex:

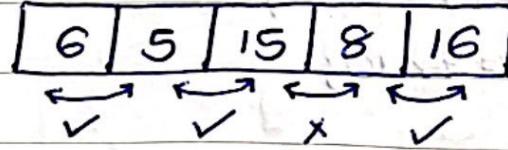
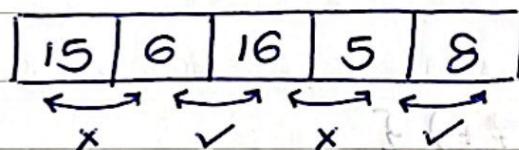
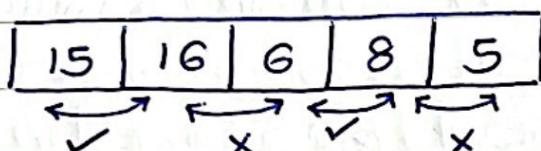


First
Iteration.

two swap



Ex:



Date 18/2/21 No 2/51

```
int temp;
if (arr[i] > arr[i+1])
{
    temp = arr[i];
    arr[i] = arr[i+1];
    arr[i+1] = temp;
}

do {
    swap = false;
    for (i=0; i<n; i++) {
        if (arr[i] > arr[i+1]) {
            temp = arr[i];
            arr[i] = arr[i+1];
            arr[i+1] = temp;
            swap = true;
        }
    }
} while (swap)
```

if conditional check
 $\text{arr}[i] > \text{arr}[i+1] \rightarrow i < n$
moves to swap
Date No

Iteration	i	i+1	arr[i]	arr[i+1]	swap
0	1	12	<	20	F
1	2	20	>	18	T
2	3	20	>	10	(T) → 12, 18, 10, 20

O (global) interface methods defined by symbols in (e)

... i passi ai fratelli Isolome e Isolao

1. (x) 2. (x) 3. (x) 4. (x) 5. (x) 6. (x) 7. (x) 8. (x) 9. (x) 10. (x)

I would begin the telephone interview by asking the question "Can you tell me about your child?"

1. What is the difference between a primary and secondary market?

1. What is the relationship between the two main characters?

1. What is the difference between a primary and secondary consumer?

Reiterski 1991

times for
volvo

1. **What is the main idea of the text?**

10. What is the best way to learn English?

~~100% Natural~~ 100% Natural

* Benefit of Bubble Sort:

- Easy to understand & implement.

- Easy to understand & implement.

* Disadvantage of Bubble Sort:

- Inefficient: slow for large arrays.

Selection Sort

Concept for sort in ascending order:

- 01.) Locate smallest element in array.
- 02.) Exchange it with element in position (index) 0.
- 03.) Locate next smallest element in array.
- 04.) Exchange it with element in position (index) 1.
- 05.) Continue until all elements are arranged in order.

Ex1:-

0	1	2	3	4
15	16	8	12	3

Assume

1st iteration.

3	16	8	12	15
---	----	---	----	----

minIndex =

minValue =

0	2	4
15	8	3

not equal

swap

2nd iteration.

3	8	16	12	15
---	---	----	----	----

minIndex =

minValue =

1	2
16	8

not equal

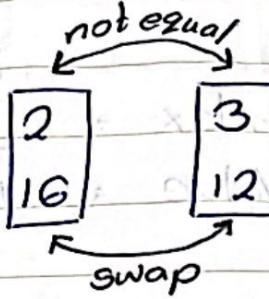
swap

3rd iteration.

3	8	12	16	15
---	---	----	----	----

minIndex =

minValue =

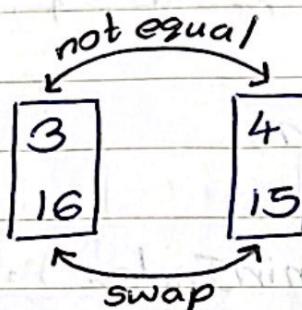


4th iteration.

3	8	12	15	16
---	---	----	----	----

minIndex =

minValue =



Ex2:-

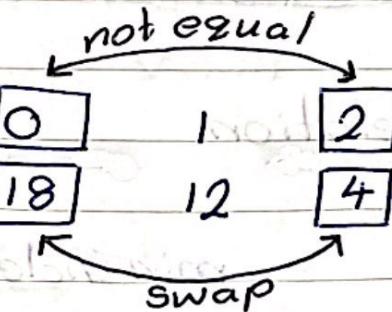
0	1	2	3	4
18	12	4	20	16

Assume

1st iteration.

minIndex =

minValue =



0	1	2	3	4
4	12	18	20	16

2nd iteration

$\minIndex = 1$ same
 $\minValue = 12$

0	1	2	3	4
4	12	18	20	16

3rd iteration

$\minIndex = 2$ not equal
 $\minValue = 18$

Swap

0	1	2	3	4
4	12	16	20	18

4th iteration.

$\minIndex = 3$ not equal

$\minValue = 20$

Swap

0	1	2	3	4
4	12	16	18	20

Ex3:-

0	1	2	3	4	5	6	7	8	9	10
15	16	6	8	12	5	1	2	3	4	0

1st iteration.

not equal

$$\min I = \boxed{0} \quad \boxed{5}$$

$$\min V = \boxed{15} \quad \boxed{5}$$

swap

0	1	2	3	4	5	6	7	8	9	10
5	16	6	8	12	15	1	2	3	4	0
0	1	2	3	4	5	6	7	8	9	10

2nd iteration.

not equal

$$\min I = \boxed{1} \quad \boxed{2}$$

$$\min V = \boxed{16} \quad \boxed{6}$$

swap

0	1	2	3	4	5	6	7	8	9	10
5	6	16	8	12	15	1	2	3	4	0
0	1	2	3	4	5	6	7	8	9	10

3rd iteration.

not equal

$$\min I = \boxed{2} \quad \boxed{3}$$

$$\min V = \boxed{16} \quad \boxed{8}$$

swap

0	1	2	3	4	5
5	6	8	16	12	15

4th iteration

$\text{mini} = \boxed{3}$ $\boxed{4}$
 ↓ ↓
 $\text{minV} = \boxed{16}$ $\boxed{12}$
 ↓ ↓
 swap

0	1	2	3	4	5
5	6	8	12	16	15

5th iteration

$\text{mini} = \boxed{4}$ $\boxed{5}$
 ↓ ↓
 $\text{minV} = \boxed{16}$ $\boxed{15}$
 ↓ ↓
 swap

0	1	2	3	4	5
5	6	8	12	15	16

```

for (int i=0; i<n-1; i++) {
    int minI = i;
    for (int j = i+1; j < n; j++) {
        if (arr[j] < arr[minI])
            minI = j
    }
    if (minI != i)
        swap (arr[i], arr[minI]);
}

```

Desk Search

Ex:-

0	1	2	3
18	19	20	25

outer loop inner loop

i	j	minI	arr[j]	arr[minI]	arr[j] < arr[minI]
0	1	0	19	18	F
	2	0	20	18	F
	3	0	25	18	F
1	2	1	20	19	F
	3	1	25	19	F
2	3	2	25	20	T

0	1	2	3
18	17	20	16

(Q1.)

(Ans. 1-5th & 0-6th row)

the 7th row

the 8th row

(Ans. 7-10th & 11-14th row)

the 15th row

the 16th row

the 17th row

the 18th row

the 19th row

the 20th row

the 21st row

the 22nd row

the 23rd row

the 24th row

the 25th row

the 26th row

the 27th row

the 28th row

the 29th row

the 30th row

the 31st row

the 32nd row

the 33rd row

the 34th row

the 35th row

the 36th row

```
void selectionSort (int array[], int size)
```

{

```
    int startScan, minIndex, minValue;
```

```
    for (startScan = 0; startScan < (size - 1); startScan++)
```

{

```
        minIndex = startScan;
```

```
        minValue = array[startScan];
```

```
        for (int index = startScan + 1; index < size; index++)
```

{

```
            if (array[index] < minValue)
```

{

```
                minValue = array[index];
```

```
                minIndex = index;
```

}

Final Array

62	59	8	24	37	80
----	----	---	----	----	----

```
array[minIndex] = array[startScan];
```

```
array[startScan] = minValue;
```

}

}

62	59	8	24	37	80
----	----	---	----	----	----

62	59	8	24	37	80
----	----	---	----	----	----

Selection Sort.

* Benefits of Selection Sort.

- More efficient than Bubble Sort, since fewer exchanges.

* Disadvantages of Selection Sort.

- May not be as easy as Bubble Sort to understand.

only for partial
data sets

Date

No

Insertion Sort

While some elements unsorted:

- 01.) Using linear search, find the location in the sorted portion where the first element of the unsorted portion should be inserted.
- 02.) Move all the elements after the insertion location up one position to make space for the new element.

Ex:-

23	78	45	8	32	56
----	----	----	---	----	----

Original list

boundary → | unsorted

23	78	45	8	32	56
----	----	----	---	----	----

After Pass 1

sorted unsorted

23	45	78	8	32	56
----	----	----	---	----	----

After Pass 2

sorted unsorted

8	23	45	78	32	56
sorted			unsorted		

After Pass 3

8	23	32	45	78	56
sorted			unsorted		

After Pass 4

8	23	32	45	56	78
sorted			unsorted		

After Pass 5

Ex:-

12	20	18	10
unsorted			sorted

Original list

12	20	18	10
sorted			unsorted

After Pass 1

12	18	20	10
sorted			unsorted

After Pass 2

10	12	18	20
sorted			unsorted

After Pass 3

* Insertion Sort Implementation 01:

```

for (k=1; k<size; k++) {
    temp = A[k];
    j = k-1;
    while (j >= 0 && A[j] > temp)
        {
            A[j+1] = A[j];
            j--;
        }
    A[j+1] = temp;
}

```

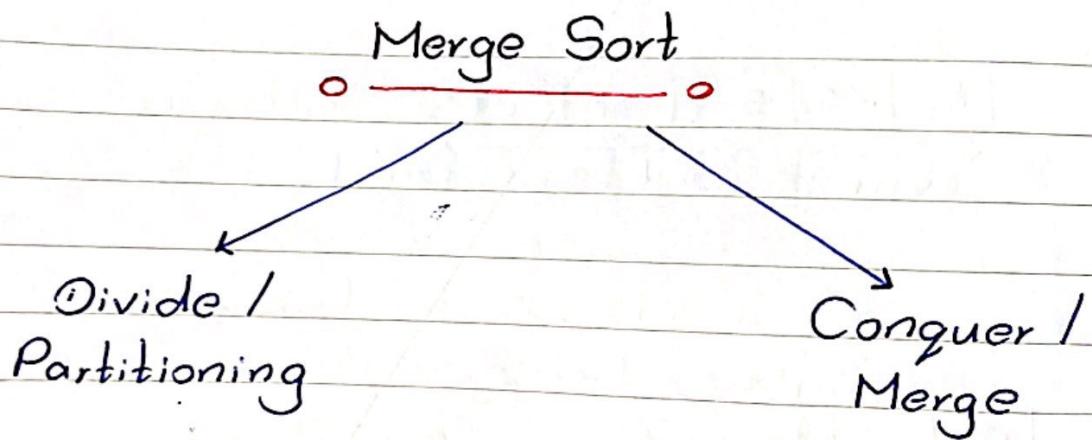
* Insertion Sort Implementation 02:

```

void insert (float d[], int size) {
    int i, k, l;
    float temp;
    For (k=1; k<size; k++) //insert elements starting from 2nd
        for (i=0; i<k && d[i]<=d[k]; i++);
        temp = d[k]; //copy kth element to temp
        for (l=k; l>i; l--) d[l] = d[l-1];
        d[i] = temp; //insert kth element to ith place
}

```

}



Merge Sort algorithm uses divide and conquer programming technique.

Merge Sort execute in 2 phases.

01.) Dividing / Partitioning

(The entire data set is partitioning into single element level)

02.) Conquering / Merging.

(The actual sorting and merging happens here)

How to divide:

$n/2$, balanced part

* Partitioning - Choice 01

- First $n-1$ elements into set A, last element set B.
- Sort A using this partitioning scheme recursively
 - B already sorted.
- Combine A and B using method Insert() (C=insertion into sorted array)
- Leads to recursive version of InsertionSort()

* Partitioning - Choice 02

- Put elements with largest key in B, remaining elements in A.
- Sort A recursively.
- To combine sorted A and B, append B to sorted A.
 - Use Max() to find largest element \rightarrow recursive SelectionSort()
 - Use bubbling process to find and move largest element to right-most position \rightarrow recursive BubbleSort()

* Partitioning - Choice 03

- Let's try to achieve balanced partitioning.
- A gets $n/2$ elements, B gets rest half.
- Sort A and B recursively.
- Combine sorted A and B using a process called merge, which combines two sorted lists into one.

①, ②... → indicates the order in which steps are processed

Date

No

Ex:

Phase 01

F	0	1	2	3	4	5	midpoint = $\frac{f+1}{2}$
	10	3	25	18	15	12	$= \frac{0+5}{2} = 2$

F	0	1	2	1
	10	3	25	

F	3	4	5	1
	18	15	12	

first half

FH (Carr, F, m)

second half

SH (Carr, m+1, 1)

0	1	2
10	3	25

3	4	5
18	15	12

0	1
10	3

2
25

3	4	5
18	15	12

0	1
10	3

2
25

3	4	5
18	15	12

doesn't satisfy
 $f > m$
(stopping criteria)

Phase 02

10	3	25	18	15	12
----	---	----	----	----	----

3	10
10	3

15	18
18	15

3	10	25
25	10	3

15	18	12
12	18	15

FH (Carr, F, m)

SH (Carr, m+1, 1)

MS (Carr, f, m, m+1, 1)

ProMate

* Algorithm:

MergeSort (Carr[], F, L)

IF ($L > F$)

- Find the middle point to divide the array into 2 halves.
 - $\text{middle } m = (F + L) / 2$
- Call mergeSort for First half
 - call mergeSort (Carr, F, m)
- Call mergeSort for second half
 - call mergeSort (Carr, m+1, L)
- Merge the two halves sorted in steps 2 and 3.
 - call merge (Carr, F, m, L)

msort (int d[], int l, int r) {

if ($l < r$)

 mid = $(l+r) / 2$

 msort (d, l, mid); // sort first half of d[] by a recursive call
 msort (d, mid+1, r); // sort second half of d[] by a recursive call
 merge (d, l, mid, r);

}

(01)

F	0	1	2	3	4	1
	10	9	8	12	5	

Phase 01:

F	0	1	2	1
	10	9	8	

F	3	4	1
	12	5	

0	1
10	9

2
8

3
12

4
5

Phase 02:

9	10
---	----

5	12
---	----

8	9	10
---	---	----

5	8	9	10	12
---	---	---	----	----

(02)

F	0	1	2	3	4	5	6	7	1
	15	16	6	3	8	20	12	5	

Phase 01:

F	0	1	2	3	1
	15	16	6	3	

F	4	5	6	7	1
	8	20	12	5	

0	1
15	16

2	3
6	3

4	5
8	20

6	7
12	5

15

16

6

3

8

20

12

5

Phase 02:

15	16	8	20	3	6
----	----	---	----	---	---

8	20
01	15

12	5	1	0
----	---	---	---

3	6	15	16
---	---	----	----

01	5	8	12	20
----	---	---	----	----

3	5	6	8	12	15	16	20
---	---	---	---	----	----	----	----

* Merge Sort Implementation using Recursion:

```
void msort ( int d[], int size) {  
    int i, j, k, result [size], mid = size/2;  
    if (size == 1) return;  
    msort (d, mid);  
    msort (&d[mid], size - mid);  
    for (k=0, i=0, j=mid; i<mid && j<size; k++)  
        result [k] = d [i] < d [j] ? d [i++]: d [j++];  
    while (i < mid) result [k++] = d [i++];  
    while (j < size) result [k++] = d [j++];  
    for (k=0; k<size; k++) d [k] = result [k];  
}
```

How MergeSort Algorithm

Works Internally.

- 01.) Divide the array into 2 parts.
- 02.) Divide the array into 2 parts again.
- 03.) Break each element into single parts.
- 04.) Sort the elements from smallest to largest.
- 05.) Merge the divided sorted arrays together.
- 06.) The array has been sorted.

Recursion & Recursive Algorithms

Recursion

- * A recursive function is a function that calls itself.
- * Recursive Functions can be useful in solving problems that can be broken down into smaller or simpler subproblems of the same type.
- * A base case should eventually be reached, at which time the breaking down (recursion) will stop.

Recursive Functions

Consider a function for solving the count-down problem from some number num down to 0:

- * The base case is when num is already 0 : the problem is solved and we "blast off!"
- * If num is greater than 0, we count off num and then recursively count down from num-1.

Base Case / Recursive Call

A recursive function for counting down to 0:

```
void countDown(int num)
{
    if (num == 0)
        print "Done!";
    else
        print num;
        countDown(num - 1); //recursive call
}
```

What happens when called?

If a program contains a line like `countDown(2);`

- 01) `countDown(2)` generates the output 2..., then it calls `countDown(1)`
- 02) `countDown(1)` generates the output 1..., then it calls `countDown(0)`
- 03) `countDown(0)` generates the output Done!, then returns to `countDown(1)`
- 04) `countDown(1)` returns to `countDown(2)`
- 05) `countDown(2)` returns to the calling function.

Stopping the Recursion.

- * A recursive function should include a test for the base cases.
- * In the sample program, the test is:
if (num == 0)

```
void countDown (int num)
```

{

```
    if (num == 0)
```

```
        print ("Done!"); // test
```

```
    else
```

{

```
        print (n);
```

```
        countDown (num - 1); // recursive call
```

}

value passed to recursive call
is closer to base case of
num = 0.

- * With each recursive call, the parameter controlling the recursion should move closer to the base case.

- * Eventually, the parameter reaches the base case and the chain of recursive calls terminates.

What Happens When Called?

- * Each time a recursive function is called, a new copy of the function runs, with new instances of parameters and local variables being created.
- * As each copy finishes executing, it returns to the copy of the function that called it.
- * When the initial copy finishes executing, it returns to the part of the program that made the initial call to the function.

Types of Recursion

01) Direct Recursion.

- * A function calls itself.

02) Indirect Recursion.

- * Function A calls function B and B calls function A.

- * Function A calls function B, which calls..., which calls function A.

The Recursive Factorial Function.

* The factorial of a nonnegative integer n is the product of all positive integers less or equal to n .

* Factorial of n is denoted by $n!$

* The factorial of 0 is 1

$$0! = 1$$

$$n! = n \times (n-1) \times \dots \times 2 \times 1 \quad \text{if } n > 0$$

* Factorial of n can be expressed in terms of the factorial of $n-1$.

$$0! = 1$$

$$n! = n \times (n-1)!$$

* Recursive Function

```
int factorial (int n) {  
    if (n == 0)  
        return 1;  
    else  
        return n * factorial (n-1);
```

{

* Any given recursion function has 2 components.

01.) Base case / Stopping condition / Termination point.

02.) The Recursive Call. (recursive call runs towards the base case).

Q1.) Write the outputs of following functions.

I) void countDown (int num) if num = 5

{

 if (num == 0)
 print Done!;

 else

 {

 5 4 3 2 1 Done!

 print num;
 countDown (num - 1);

 }

}

II) void countDown (int num)

{

 if (num == 0)

 Done! 1 2 3 4 5

 print Done!;

 else

 {

 countDown (num - 1);
 print num;

}

}