
Algorithm 1: repartitioning after Fennel

Input: v , threshold

```
1  $v.neighbors \leftarrow N(v)$ ;  
2 for  $neighbor$  in  $v.neighbors$  do  
3    $index \leftarrow partition(neighbor)$ ;  
4    $size \leftarrow getSizeInPartition(index, neighbor)$ ;  
5    $skipEpoch \leftarrow neighbor.skipEpoch$ ;  
6   if  $(skipEpoch + 1)/size \geq threshold$  then  
7      $repartition(neighbor)$ ;  
8      $neighbor.skipEpoch = 0$ ;  
9   else  
10     $neighbor.skipEpoch++$ ;  
11  end  
12 end
```
