Atmel AVR2051:
Atmel BitCloud SerialNet
User Guide







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Section 1

Introduction

SerialNet is a manufacturer-specific profile developed on top of the Atmel[®] BitCloud[®] C API. It offers control of an embedded BitCloud stack through a serial interface using a standardized AT command set, and requires no embedded API programming. Node parameters can be easily accessed over the air without a specifically dedicated protocol, thus opening a way to network management and remote node control.

The document presents the description of the SerialNet AT command language.



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2.2 Abbreviations and acronyms

Table 2-1. Abbreviations and acronyms.

| ARQ | Automatic repeat-request |
|--------|--|
| ASCII | American Standard Code for Information Interchange |
| BS | Backspace character |
| CCITT | Consultative Committee on International Telephony and Telegraphy |
| CR | Carriage return character |
| CRE | Coordinator / router / end device (meaning any of those) |
| CTS | Clear to send |
| DCE | Data communication equipment |
| DTR | Data terminal ready |
| EEPROM | Electrically erasable programmable read-only memory |
| GPIO | General purpose input/output |

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Table 2-1. Abbreviations and acronyms. (Continued)

| , |
|---|
| Identifier |
| Institute of Electrical and Electronics Engineers |
| International Telecommunications Union |
| Light-emitting diode |
| Line feed character |
| Link quality indicator |
| Least-significant bit |
| Medium access control (sublayer) |
| Microcontroller unit/multichip unit |
| Network layer |
| Original equipment manufacturer |
| Personal area network |
| Physical layer |
| Pulse width modulation |
| Read-only parameter |
| Received signal strength indicator |
| Request to send |
| Read-write parameter |
| Receiver |
| To be defined |
| Transmitter |
| Universal asynchronous receiver transmitter |
| Universal synchronous/asynchronous receiver transmitter |
| ZigBee device object |
| |



Overview

SerialNet is based on the AT command protocol, which is widely used in embedded networking systems due to its simplicity, textual parameter representation, and inherent flexibility. This chapter gives a brief introduction into the concept of the SerialNet protocol, lists hardware platforms SerialNet is available for, and describes conventions used throughout the document.

3.1 Supported platforms

The following hardware platforms are supported by SerialNet:

Table 3-1. Supported hardware platforms.

| Name in this | Platform | ZigPit modulos | Appropriate SDK | | | |
|--------------|----------------------------|----------------------------|-----------------------------|--|--|--|
| document | (MCU + RF) | ZigBit modules | Appropriate SDK | | | |
| RZUSBSTICK | AT90USB1287 + AT86RF230 | N/A | BitCloud for | | | |
| NZUSBSTICK | See Step 1. in Section 2-1 | IN/A | ATAVRRZRAVEN | | | |
| | | ATZB-24-B0 (ZigBit B0); | | | | |
| ZigBit | ATmega1281 + AT86RF230 | ATZB-24-A2 (ZigBit A2). | BitCloud for ZigBit modules | | | |
| | | See Step 2. in Section 2-1 | | | | |
| ZiaDit Amn | ATmega1281 + AT86RF230 | ATZB-A24-UFL (ZigBit Amp) | PitCloud for ZigPit modulos | | | |
| ZigBit Amp | ATTILEGATZOT + ATOONF230 | See Step 3. in Section 2-1 | BitCloud for ZigBit modules | | | |
| ZiaPit 000 | ATmogo1201 : AT96DE212 | ATZB-900-B0 (ZigBit 900) | PitCloud for ZigPit modulos | | | |
| ZigBit 900 | ATmega1281 + AT86RF212 | See Step 4. in Section 2-1 | BitCloud for ZigBit modules | | | |
| megaRF | ATmega128RFA1 | N/A | BitCloud for megaRF | | | |

Most of the SerialNet commands are hardware-independent and can be executed on all supported platforms. However, a few commands either exhibit platform-specific behavior or are supported on particular hardware platforms only. For such cases, command descriptions given in the Section "Command descriptions" provide corresponding differences in the command functionality for various platforms. If no reference to a platform is given in a command description, then platform-independence is implied.

3.2 Conventions

The term *module* will be used throughout the document to imply a supported platform (MCU + RF chip) is controlled by *host* equipment using AT commands.

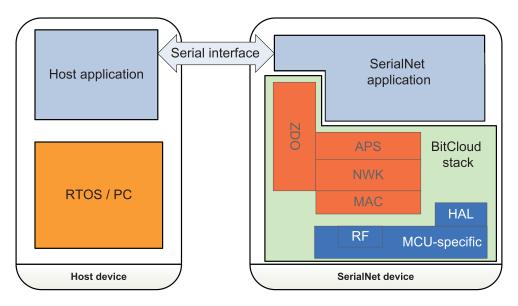
The term *node* will be used in reference to a device's role in the network (end device, router or coordinator).

To be distinguished from the rest, the definitions of commands directed to a module are denoted in the Courier font, while module responses are shown in **Courier Bold** font. Angle brackets, < >, enclose mandatory parameters. Square brackets, [], contain optional parameters.

3.3 Architecture overview

The SerialNet application is developed on top of the Atmel BitCloud ZigBee PRO-certified stack (see - [Step 10.] in Section 2-1). It provides an easy-to-use control over ZigBee PRO networking functionality that is accessible to the host device through a serial connection using an extensive set of AT commands in ASCII format. A SerialNet device executes received requests and responds to the host. Figure 3-1 illustrates the basic architecture.

Figure 3-1. SerialNet usage scheme.

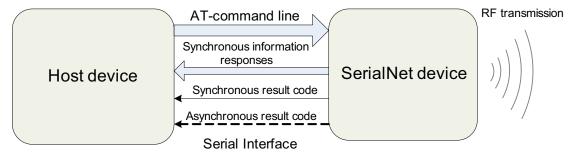


An important feature of SerialNet is the capability to request execution of a particular function over the air via the ATR command (see Table 5-8 on page 5-8). It allows transferring the AT command to the remote node in the network, executing it there and redirecting the execution output to the originator. Thus, the remote node can be monitored and commissioned, and the corresponding parameters can be set.

3.3.1 Protocol principles

SerialNet supports an extensive set of AT commands that provide full control over different functionality of the module. Read/write commands to S-registers can be used to access device and network parameters. In many cases, AT command functionality can be duplicated by certain S-registers to reduce overhead of the serial protocol. The basic principle of the SerialNet protocol is illustrated in Figure 3-2.

Figure 3-2. SerialNet command executions.



The host device shall transmit a command line prefixed by the "AT" string and followed by the chained SerialNet commands to be executed consecutively. Upon successful execution of each command in the sequence, corresponding information responses are returned to the host device in an easily recognizable string format. The final result of the command line execution is indicated by the result code. In case any command is executed incorrectly, the command sequence



is interrupted and the **ERROR** result code is returned. The **OK** result code is returned if all commands in the sequence were executed successfully.

Each command in a sequence may have a different syntax, depending on whether it is used to execute an action, read or write parameter(s), or test a valid parameter range. An example illustrating different command and response types is provided in Table 3-2.

Table 3-2. At command string execution.

| | Command/response | Comment |
|-----------------------|---------------------------------------|--|
| Command to device | ATE1V1+WTXPWR=- 4+WLQI2+WRSSI2S22? | Turn echo on (E1), enable verbose response, set TX power level to -4dBm, request LQI and RSSI for link with node 2, request active channel |
| | +WLQI:254 | LQI value is 254 |
| Information responses | +WRSSI:-80 | RSSI is -80dBm |
| | В | Node is operating on channel 0x0B |
| Result code | OK | Execution is completed successfully |

More complex examples are provided in "Examples" on page 5-6.

In addition to synchronous result codes indicating command execution status, a SerialNet device can send asynchronous result codes to the host device upon specific events. The full list of both verbose and numeric forms of the result codes can be found in "Parameter persistence" on page 5-4.

"AT commands" on page 5-1 summarizes the basic specifications of AT commands grouped into functional categories, while detailed definition for each command is given in Section 6 on page 6-1.

"S-registers" on page 5-5 is a functional representation of S-registers with the corresponding AT commands.



Getting started

4.1 Connection with board

The supported platform (see "Supported platforms" on page 3-1) is first programmed (via JTAG, USB or RS-232) with the SerialNet firmware version for the corresponding platform. After that it is connected to a host device (a PC, MCU, etc.) using a USB or RS-232 interface. To start communication, the host device configures its serial port with default SerialNet parameters.

Table 4-1. Default SerialNet parameters.

| Baud rate | 38400 |
|--------------|-------|
| Data bits | 8 |
| Parity | None |
| Stop bits | 1 |
| Flow control | None |

Note that these parameters can be modified for a SerialNet device and saved in persistent memory using the corresponding commands described in Section 6.8.8 on page 6-44 and Section 6.8.9 on page 6-45.

If a PC is the host, the HyperTerminal application included with Microsoft® Windows® can be used to communicate with the SerialNet device. To check the connection, "AT" should be entered in the terminal window, followed by a CR. If the board responds with an OK result code, the communication between the host and SerialNet devices has been established successfully.

"Examples" on page 5-6 includes examples showing how a SerialNet device can be configured for networking operations, data exchange, and remote control.



Command summary

5.1 AT commands

The AT commands implemented in SerialNet fall into the following categories:

- Network configuration and management
- Data transmission
- Power management
- Generic control
- Host interface control
- Hardware controlRemote management

Table 5-1 provides a full list of SerialNet commands, along with information about supporting node roles, syntaxes, corresponding S-registers (if any), persistence, and references to the detailed command description in Section 5.4.5 on page 5-9.

Table 5-1. Command summary.

| Command Networking paramete | Function | Node type (C/R/E) | S-register | Action syntax | Parameter set syntax | Parameter read syntax | Parameter test syntax | Persistence | Reference |
|-----------------------------|-------------------------|-------------------|------------|---------------|----------------------|-----------------------|-----------------------|-------------|-----------|
| +WPANID | Extended PAN ID | CRE | 20, 21 | | х | х | х | х | 6.2.1 |
| +WCHAN | Active channel | CRE | 22 | | | х | | | 6.2.2 |
| +WCHMASK | Channel mask | CRE | 23 | | х | х | х | х | 6.2.3 |
| +WCHPAGE | Channel page | CRE | 25 | | х | х | х | х | 6.2.4 |
| +WAUTONET | Automatic networking | CRE | 24 | | х | х | х | х | 6.2.5 |
| +WROLE | Node role | CRE | 33 | | х | Х | х | х | 6.2.6 |
| +GSN or I4 | Device extended address | CRE | | | х | х | | | 6.2.7 |
| +WSRC | Node short address | CRE | 55 | | х | Х | х | х | 6.2.8 |
| +WNWKPANID | Short (network) PAN ID | CRE | 55 | | х | Х | х | х | 6.2.9 |
| Network management | t Function | | | | | | • | • | |
| +WJOIN | Start/join the network | CRE | | х | | | | | 6.3.1 |

Table 5-1. Command summary. (Continued)

| Table 5-1. Command s | Summary. (Oominueu) | | T | | | | | | |
|----------------------|--|-----|--------|---|---|---|---|---|--------|
| +WLEAVE | Leave the network | CRE | | Х | | | | | 6.3.2 |
| +WNWK | Request for networking status | CRE | | х | | | | | 6.3.3 |
| +WPARENT | Request for parent address | Е | | | | х | | | 6.3.4 |
| +WCHILDREN | Request for children addresses | CR | | | | х | | | 6.3.5 |
| +WNBSIZE | Request for a number of neighbor nodes | CRE | | | | х | | | 6.3.6 |
| +WNB | Request for neighbors' information | CRE | | | | х | | | 6.3.7 |
| S30 | Network addressing mode | CRE | 30 | | х | х | | | 6.3.8 |
| +WLQI | Request for LQI | CRE | | х | | | | | 6.3.9 |
| +WRSSI | Request for RSSI | CRE | | х | | | | | 6.3.10 |
| Security | | | | | | | | | |
| +WSECON | Enable/disable security | CRE | х | х | | | | | 6.4.1 |
| +WSECSTATUS | Set/get security status | CRE | | х | | | | | 6.4.2 |
| +WNETKEY | Set/get network encryption key | CRE | | х | | | | | 6.4.3 |
| +WTCADDR | Set/get trust center address | Е | | | | х | | | 6.4.4 |
| Data transmission | | | | | | | | | |
| D | Send data to a specific node | CRE | | х | | | | | 6.5.2 |
| DB | Send binary data to a specific node | CRE | | х | | | | | 6.5.3 |
| DU | Send broadcast data | CRE | | х | | | | | 6.5.4 |
| DS | Send S-register value to a specific node | CRE | | х | | | | | 6.5.5 |
| +WPING | Ping the node | CRE | | х | | | | | 6.5.6 |
| +WSYNCPRD | Indirect poll rate | CRE | 37 | | х | х | х | | 6.5.7 |
| +WTIMEOUT | Data delivery timeout | CRE | 51 | | | х | | | 6.5.8 |
| +WRETRY | Repetition count | CRE | 52 | | | х | | | 6.5.9 |
| +WWAIT | Data transmission waiting timeout | CRE | 53 | | х | х | х | х | 6.5.10 |
| Power management | | | | | | · | , | , | |
| +WPWR | End device sleep parameters | CRE | 31, 32 | | х | х | х | х | 6.6.1 |
| +WSLEEP | Force to sleep | E | | х | | | | | 6.6.2 |
| +WTXPWR | TX power level | CRE | 34 | | х | х | х | х | 6.6.3 |
| Generic control | | | | | | | | | |
| z | Warm reset | CRE | | х | | | | | 6.7.1 |
| &H | Help | CRE | | х | | | | | 6.7.2 |
| %Н | Display parameters and S-register values | CRE | | x | | | | | 6.7.3 |
| I, IO | Display product identification information | CRE | | х | | | | | 6.7.4 |
| +GMI or I1 | Request manufacturer identification | CRE | | Х | | | | | 6.7.5 |
| +GMM or I2 | Request model identification | CRE | | х | | | | | 6.7.6 |



Table 5-1. Command summary. (Continued)

| +GMR or I3 | Request hardware/software revision identification | CRE | | х | | | | | 6.7.7 |
|----------------------|---|------|-------------------|---|---|---|---|---|--------|
| &F | Set to factory-defined configuration | CRE | | х | | | | | 6.7.8 |
| +WACALIBRATE | Configure periodic internal clock calibration | CRE | | х | | | | | 6.7.9 |
| +WCALIBRATE | Calibrate internal clock | CRE | | х | | | | | 6.7.10 |
| Host interface comma | nds | | | | | | | | |
| S3 | Termination character | CRE | 3 | | х | х | | х | 6.8.1 |
| S4 | Response formatting character | CRE | 4 | | х | х | | х | 6.8.2 |
| S5 | Command editing character | CRE | 5 | | х | х | | Х | 6.8.3 |
| E | Command echo | CRE | | Х | | | | х | 6.8.4 |
| Q | Result code suppression | CRE | | Х | | | | х | 6.8.5 |
| V | Response format | CRE | | Х | | | | Х | 6.8.6 |
| х | Result code selection | CRE | | Х | | | | Х | 6.8.7 |
| +IPR | Serial port communication rate | CRE | | | х | х | х | Х | 6.8.8 |
| +IFC | Serial port flow control | CRE | | | х | х | х | Х | 6.8.9 |
| &D | DTR behavior | CRE | 50 | Х | | | | Х | 6.8.10 |
| S0 | Request the latest result code | CRE | 0 | | | х | | | 6.8.11 |
| Hardware control | -1 | | | | ! | | | | |
| S120S128 | GPIO configuration | CRE | 120 128 | | х | х | | х | 6.9.1 |
| S130S138 | GPIO | CRE | 130 138 | | х | х | | | 6.9.2 |
| S100 | A/D configuration | CRE | 100 | | х | х | | Х | 6.9.3 |
| S101S104 | A/D | CRE | 101 104 | | | х | | | 6.9.4 |
| S140, S141, S142 | PWM configuration | CRE | 140 141 142 | | x | x | | | 6.9.5 |
| S143, S144, S145 | PWM frequency control | CRE | 143 144 145 | | x | х | | | 6.9.6 |
| S146, S147, S148 | PWM duty cycle control | CRE | 146 147 148 | | x | х | | | 6.9.7 |
| POKE | Writing to hardware registers | CRE | | х | | | | | 6.9.8 |
| PEEK | Reading from hardware registers | CRE | | х | | | | | 6.9.8 |
| Remote management | | | | | ı | | | | ı |
| | Sat a pageword | CRE | | Х | | | | Х | 6.10.1 |
| +WPASSWORD | Set a password | OLIC | | ^ | | | ļ | ^ | 0.10.1 |

Note: 1. The second column contains roles of nodes to which a given command is applicable. C stands for coordinator, R for router, and E for end device.



5.1.1 Parameter persistence

In Table 5-1, many parameters associated with AT commands are indicated as persistent. This means that their values are stored in the MCU's persistent memory, and in contrast to nonpersistent parameters, they will not be set to default configuration upon device reset.

However, the value assigned to a persistent parameter by the corresponding AT command is not written to the persistent memory right away. Instead, it is applied to the SerialNet operation, but is kept in RAM. SerialNet periodically (with a five-minute interval) verifies whether or not the values of persistent parameters in EEPROM match their actual values in RAM. If differences are detected, the corresponding values in EEPROM are updated. For platforms with warm reset command support (see Table 6-48 on page 6-34), persistent parameters in EEPROM are updated to actual values (if necessary) automatically upon ATZ command execution.

Upon device reset, SerialNet assigns persistent parameters to their values stored in EEPROM. If a parameter value has not been transferred from RAM to EEPROM, then the old EEPROM value will be used.

5.2 Result codes

Result codes appear either synchronously in response to a command, or asynchronously due to specific events in the network or on a SerialNet device. See a detailed description of result codes in "Device responses" on page 6-6. Table 5-2, which provides both verbose and numeric forms for available result codes.

Table 5-2. Result codes.

| Verbose code | Numeric code | Parameters | Description |
|--------------|--------------|--|---|
| ок | 0 | None | Command is executed successfully |
| ERROR | 4 | None | Error occurred during command execution |
| | | <addr>, <bcast>, <length>: <data></data></length></bcast></addr> | Indicates data reception from a remote node |
| | | | addr is a short (network) address of the source node the data is originating from |
| | | | bcast is set to 1 if data are sent by broadcast transmission; otherwise, it is set to 0 |
| | | | length is a length of the <data> field</data> |
| DATA | 8 | | data is a byte sequence of received data |
| | | | Note: The +WPING command (see Table 6-40 on page 6-29) results in the following code on the destination node: |
| | | | DATA <addr>,0,0:</addr> |
| EVENT | 7 | : <text></text> | text is text specifying an event |
| | | :JOINED | Indicates that the node has joined the network |
| | | | Note: Event is returned in auto-network mode only, and not after the +WJOIN command |
| | | :LOST | Indicates that the node has lost connection to the network (that is, to its current parent) |
| | | | Note: This event can occur on end-device nodes only, and is not returned after +WLEAVE |



Table 5-2. Result codes. (Continued)

| :CHILD_JC | DINED <addr></addr> | Indicates to the node that a device with extended address <addr></addr> has just joined to it as a child | |
|-----------|---------------------|--|--|
| :CHILD_LC | OST <addr></addr> | Indicates to the node that its child end device with extended address <addr></addr> has disconnected from the node. | |
| | | Note: This event occurs when the child end device switches to a new parent, when it leaves the network using the +WLEAVE command, or when it is not accessible (powered off, no link, etc.) for 3*(sleep_interval + sync_period), as configured on the parent device by the +WPWR and +WSYNCPRD commands | |
| :CALIBR | | Indicates that the device has successfully calibrated its internal clock after encountering errors on the serial interface | |

5.3 S-registers

An extensive set of S-registers available in SerialNet provides easy read/write access to device and networking parameters. In many cases, AT command functionality can be duplicated by certain S-registers to reduce overhead of the serial ASCII protocol.

Table 5-3. S-registers.

| Parameter | Acceptable operations (R/RW) | S-register | Command reference |
|-----------------------------------|------------------------------|------------|-------------------|
| The latest result code | R | S0 | 6.8.11 |
| Termination character | RW | S3 | 6.8.1 |
| Response formatting character | RW | S4 | 6.8.2 |
| Command editing character | RW | S5 | 6.8.3 |
| PAN ID | RW | S21, S20 | 6.2.1 |
| Active channel | R | S22 | 6.2.2 |
| Channel mask | RW | S23 | 6.2.3 |
| Automatic networking | RW | S24 | 6.2.5 |
| Channel page | RW | S25 | 6.2.4 |
| Network addressing mode | RW | S30 | 6.3.8 |
| Power management | RW | S31, S32 | 6.6.1 |
| Node role | RW | S33 | 6.2.6 |
| TX power level | RW | S34 | 6.6.3 |
| Indirect poll rate | RW | S37 | 6.5.7 |
| DTR behavior | RW | S50 | 6.8.10 |
| Data delivery timeout | R | S51 | 6.5.8 |
| Repetition count | R | S52 | 6.5.9 |
| Data transmission waiting timeout | RW | S53 | 6.5.10 |



Table 5-3. S-registers. (Continued)

| Own network address | RW | S55 | 6.2.8 |
|------------------------|----|------------------|-------|
| A/D configuration | RW | S100 | 6.9.3 |
| A/D | R | S101S104 | 6.9.4 |
| GPIO configuration | RW | S120S128 | 6.9.1 |
| GPIO | RW | S130S138 | 6.9.2 |
| PWM configuration | RW | S140, S141, S142 | 6.9.5 |
| PWM frequency control | RW | S143, S144, S145 | 6.9.6 |
| PWM duty cycle control | RW | S146, S147, S148 | 6.9.7 |

5.4 Examples

The examples given below show the usage of AT commands to control SerialNet devices, and are valid for all supported platforms listed in "Supported platforms" on page 3-1.

5.4.1 Prepare nodes for networking

The following examples require at least two nodes. The first step is to configure network parameters. One of the nodes should function as a coordinator, and the others can be routers or end devices. It is important that all nodes have different extended (MAC) and short (NWK) addresses. The coordinator node shall have short address 0, and all other nodes shall have nonzero addresses.

Note: Selection of particular addresses is application dependent. It should be done only the first time during the manufacturing process of initial installation.

Table 5-4. Network coordinator.

| Command/response | Comment |
|--------------------|---|
| ATX | Set a node to transmit EVENT and DATA to a host |
| ОК | |
| AT+GSN=1 | Set extended address for the node |
| ОК | |
| AT+WPANID=1620 | Set node's extended PAN ID |
| ОК | |
| AT+WCHMASK=100000 | Set node's channel mask (this one enables channel 0x14, only) |
| ОК | |
| AT+WROLE=0 +WSRC=0 | Set coordinator role and short address to 0x0000 |
| ОК | |
| AT+WJOIN | Perform network start |
| OK | Result code for successful network start |



If the node indicates **ERROR**, it means the embedded software does not support the coordinator function and cannot be configured in such a way. In this case, try checking the coordinator support on other nodes using the AT+WROLE? command, as described in Table 6-18 on page 6-11.

Then configure another device to be a router node:

Table 5-5. Network router.

| Command/response | Comment |
|---------------------|---|
| ATX | Set a node to transmit EVENT and DATA to a host |
| ОК | |
| AT+GSN=2 | Set extended address for the node |
| ОК | |
| AT+WPANID=1620 | Set node's extended PAN ID |
| ОК | |
| AT+WCHMASK=100000 | Set node's channel mask (this one enables channel 0x14, only) |
| ОК | |
| AT+WROLE=1 +WSRC=55 | Set router role, short address equal to 0x0055 |
| ОК | |
| AT+WJOIN | Perform network join |
| OK | Indication for router having joined the network |

5.4.2 Checking network status and basic data transmission

Now we can easily verify networking status on both devices by sending the AT+WNWK command and performing data exchange between them. For example, on the coordinator:

Table 5-6. Verify networking status on the coordinator.

| Command/response | Comment |
|------------------|--|
| AT+WNWK | Request networking status |
| OK | Means the node is in the network |
| AT+WWAIT=3000 | Set three-second timeout to wait for input, and send HELLO to the node with short address 55 |
| OK | |
| ATD55 | |
| HELLO | |
| OK | |

Simultaneously, HELLO will appear on the terminal connected to the router in the form of a DATA event:

Table 5-7. Verify networking status on router terminal.

| Command/response | Comment |
|---------------------|--|
| DATA 0000,0,5:HELLO | Data (five bytes) came from the device with address 0 by unicast request |



5.4.3 Remote extension

The ATR command provides a mechanism for AT command execution on a remote node with command response redirection to the originator. Thus, it allows remote monitoring and configuration over the air.

The example below demonstrates how to execute AT commands on the router device remotely using the ATR command on the coordinator:

Table 5-8. Remote execution of AT commands on the router.

| Command/response | Comment |
|---|--|
| ATR55,0,+WROLE?+GSN? | Get node role and extended address from the router |
| +WROLE:1 | |
| +GSN:000000000000000000000000000000000000 | |
| OK | |
| ATR55,0,+GMI? | Get model number from the router |
| +GMI:ATMEL | |
| OK | |
| ATR55,0,+WAUTONET=1S30=1 | Set auto-network mode and command addressing mode |
| OK | |

5.4.4 End device power control

This example demonstrates how to configure an end-device node with a certain duty cycle, perform a network join, and deliver data to an end device:

Table 5-9. Configure end-device node with duty cycle.

| Command/response | Comment |
|-------------------------------|---|
| ATX | |
| OK | Set a node to transmit EVENT and DATA to a host |
| AT+GSN=3 | Set extended (MAC) address for the node |
| OK | Set the board as an end device with short address 0x0056 |
| AT+WROLE=2 +WSRC=56 | Set extended PAN ID and channel mask (channel 0x14) for this |
| OK | node |
| AT+WPANID=1620+WCHMASK=100000 | Configure RTS and CTS line modes for end device flow control |
| OK | Reconfigure flow control on the host accordingly (for example, |
| AT+IFC=2,2 | select hardware mode for flow control in HyperTerminal) |
| OK | |
| AT+WPWR=100,100 | |
| ОК | Set duty cycle to 10s sleep / 1s active |
| AT+WPWR? | |
| +WPWR:100,100 | Verify that the duty cycle is accepted successfully |
| OK | |
| AT+WJOIN | Perform a network join |
| OK | Result code indicating successful network join for the end device |



Now, the data intended for the end device can be sent from the coordinator:

Table 5-10. Test data from the coordinator.

| Command/response | Comment |
|-------------------|---|
| ATD56,0,4 test OK | Send test data from the coordinator to the end device staying in sleep mode |

In the active state, the end device periodically polls its parent for buffered data with an interval configured by the +WSYN-CPRD parameter. In the example given, it retrieves the test frame:

Table 5-11. Polling of buffered data from parent.

| Command/response | Comment |
|--------------------|---|
| DATA 0000,0,4:test | The word test is received by the end device after wake up |

5.4.5 Control of LEDs and DIP switches

The example below is valid only for MeshBean2 development boards. Mapping of ZigBit module I/O pins and their functions on the MeshBean2 board is summarized in Table 5-12.

Table 5-12. GPIO pin summary.

| Component | I/O pin | Description |
|-----------|---------|--|
| LED1 | GPIO0 | Output, 1 means LED on |
| LED2 | GPIO1 | Output, 1 means LED on |
| LED3 | GPIO2 | Output, 1 means LED on |
| SW4:1 | GPIO3 | Input (no pull-up on the board), ON – logical zero |
| SW4:2 | GPIO4 | Input (no pull-up on the board), ON – logical zero |
| SW4:3 | GPIO5 | Input (no pull-up on the board), ON – logical zero |
| | GPIO6 | Reserved for MeshBean2 sensor interfaces |
| | GPIO7 | Reserved for MeshBean2 sensor interfaces |
| | GPIO8 | Reserved for MeshBean2 sensor interfaces |

Initially, physically set DIP switches as SW4:1 to OFF, SW4:2 and SW4:3 to ON, and, next, configure the I/O pins via commands:

Table 5-13. Configure I/O pins.

| Command/response | Comment |
|------------------------|---|
| ATS120=3 S121=3 S122=3 | Configure GPIO0, GPIO1, GPIO2 for output |
| ок | |
| ATS123=1 S124=1 S125=1 | Configure GPIO3, GPIO4, GPIO5 for input, and turn on internal pull-up |
| ок | |



Afterwards, it is possible to control the LEDs and obtain DIP switch status using the corresponding S-registers:

Table 5-14. Control LEDs and check DIP switches.

| Command/response | Comment |
|------------------------|---------------------------|
| ATS130=1 S131=0 S132=1 | Turn on LED1 and LED3 |
| OK | |
| ATS133? S134? S135? | |
| 1 | SW4:1 is in the OFF state |
| 0 | SW4:2 is in the ON state |
| 0 | SW4:3 is in the ON state |
| ок | |





Command descriptions

6.1 Protocol general description

6.1.1 Character formatting and data rates

Data transmitted between the host and the module over a serial interface conform to the requirements for start-stop data transmission specified in the ITU-T Recommendation V.4 [Step 8.] on page 2-1. Parity is even, odd, or not used. Each character has at least one complete stop bit. The module accepts commands using any combination of parity and stop bits supported. These include, at least, the following combinations, each of which consists of up to 10 bits (including the start bit):

- 7 data bits, even parity, 1 stop bit
- 7 data bits, odd parity, 1 stop bit
- 8 data bits, no parity, 1 stop bit

Both the host and the module are able to accept commands at 1200 bits per second, at least. Particular character formatting and the data rate can be changed using appropriate AT commands (see Table 6-66 on page 6-44, Table 6-67 on page 6-45 and Section 6.8.6 on page 6-43). The host has the means to explicitly select the data rate and character formatting according to the specifications above.

6.1.2 Alphabet

For any information exchange between the module and the host, the T.50 International Alphabet 5 (IA5) is used (see [Step 7.] in "Related documents and references" on page 2-1.) Only the seven low-order bits of each character are significant, and any eighth or higher-order bit(s), if present, are ignored for the purpose of identifying commands and parameters. Lowercase characters (hex codes 0×61 through $0 \times 7A$) are considered identical to their upper-case equivalents (hex codes 0×41 through $0 \times 5A$) when received from the host by the module. Result codes from the module, which are particularly defined, are specified in uppercase.

6.1.3 Basic command-line operations

Command-line editing, echoing, and repeating are done in accordance with Clauses 5.2.2, 5.2.3, and 5.2.4 of the Recommendation V.250. The description below follows the statements introduced in [Step 7.] in "Related documents and references" on page 2-1.

The module may echo back to the host the characters received from the host, depending on the setting of the E command (see Section 6.8.4 on page 6-42). If enabled, the characters received from the host are echoed at the same rate, parity, and format as those received.

The module checks on the characters coming from the host first to see if they match the termination character, S3 (see Table 6-58 on page 6-40). Next, it checks the editing character, S5 (see Table 6-60 on page 6-41), before considering any other character. This insures the characters will be properly recognized even though they were set to values the module uses for other purposes. If S3 and S5 are set to the same value, the character checked will be treated as a character matching S3 (as S3 is checked before S5).

The character defined by the S5 parameter (by default, it is the backspace character, BS [hex code 0×08], see Table 6-60 on page 6-41) is intended to be interpreted as a request from the host to the module to delete the previous character. Any control characters (hex codes 0×00 through $0 \times 1F$, inclusive) that remain in the command line after receiving the termination character will be ignored by the module.

Once the module finds the termination character, it starts processing the command line. The command line starts with AT (characters 0x41 and 0x54) and should contain a sequence of commands in the following syntax formats (Table 6-1):

Table 6-1. Command syntax formats.

| Command | Syntax |
|---------------------------------|--|
| Action command | <pre><command/>[<value>]</value></pre> |
| Parameter set command | <pre><command/>=<value></value></pre> |
| Parameter read command | <pre><command/>?</pre> |
| Testing a range of valid values | <pre><command/>=?</pre> |

where <command> is one of the following:

- a single character
- '&' character (0x26), followed by a single character
- '%' character (0x25), followed by a single character
- '+' character, followed by a string of characters

The characters allowed to be used in <command> should be taken from the T.50 International Alphabet 5. The first three of the command cases above are referred to as basic commands; they may be of the action command syntax only. Commands beginning with the plus sign are known as extended syntax commands, and can fit all the syntax rules, depending on their type. Typically, a command that supports the parameter set syntax also supports the testing syntax.

A command (with associated parameters, if any) may be followed by additional commands in the same command line without using any delimiting character. Some commands may cause the remainder of the command line to be ignored (the D command, for instance, see Table 6-36 on page 6-26).

If the command line is started with the 'A/' or 'a/' prefix (hex codes 0×41 , $0 \times 2F$ or 0×61 , $0 \times 2F$), the module immediately repeats the execution of the preceding command line. No editing is possible, and no termination character is required. With this mechanism, a command line may be repeated as much as desired.

6.1.4 Parameter values

Parameters may take either a single value or multiple (compound) values. A compound value consists of any combination of numeric values (as defined in the description of the action or parameter command). The comma character (hex code $0 \times 2C$) is included as a separator before the second and all subsequent values in the compound value. If a value is not specified as missed (that is, defaults assumed), the required comma separator should be specified; however, trailing comma characters may be omitted if all the associated values are also omitted.

Note: When any of optional parameters is misused in a command, the command would be performed as if the parameter was omitted. That parameter would be further treated as if the other subsequent command were input, probably causing an **ERROR** message. To avoid confusion, follow the command syntax.

Actions may have more than one associated sub-parameter, and parameters may have more than one value. These are known as "compound values," and their treatment is the same in both the action command syntax and the parameter command syntax.

Each value may be either a decimal or hexadecimal number. The choice depends on whether or not a particular command and hexadecimal number is preceded with $^{\circ}0x$. Hexadecimal numbers can represent 16-bit, 32-bit, 64-bit and 128-bit values.



Decimal numeric constants consist of a sequence of one or more of the characters '0' (hex code 0x30) through '9' (hex code 0x39), inclusive, and can be preceded by minus "-." The most-significant digit is specified first. Leading '0' characters will be ignored.

Hexadecimal numbers consist of characters "0" through "9" and "A" through "F, " inclusive. The minus sign is not allowed. Leading '0' characters will be ignored. To prevent misinterpretation of hexadecimal numbers in cases when the command containing them is not the last in the AT string, it is strongly recommended to add the leading zeroes. Thus, if a parameter is 32 bits long, it would be eight characters long, and if it is a 64-bit number, it would contain 16 characters, and so on.

As a special case, a string constant appears in the R command (see Table 6-80 on page 6-55) only. Then it is just a sequence of display-able IA5 characters, each in the range of 0x20 to 0x7F, inclusive.

6.1.5 Command types

A command type may be one of the following:

- An action command
- A parameter command
- An S-register command

Parameters may be defined as "read-only" (R) or "read/write" (RW). Read-only parameters are used to provide the host with status or identifying information, but are not set by the host. Attempting to set such a parameter will result in an error. In some cases (depending on the particular parameter), the module may ignore any attempt to set the value for such a parameter rather than respond with the **ERROR** result code. Read-only parameters may be read and tested.

Read/Write parameters may be set by the host in order to store a value or values for later use. Read/Write parameters may be set, read, and tested.

If <command> is not recognized, the module generates the **ERROR** result code and stops processing the command line. The **ERROR** result code is also generated if: a sub-parameter is specified for an action that does not imply using sub-parameters; too many sub-parameters are specified; a mandatory sub-parameter is not specified; a value of the wrong type is specified; or if a value that is not within the supported range is specified.

Some commands allow omitting a value. If a command does omit one, then it should be immediately followed by another command (or the termination character) in the command line. The 0 value is assumed unless otherwise specified in the <command> description. If the <command> does not expect a value, but the value is present, the ERROR code is generated.

6.1.6 Action command syntax

The format of the action commands, except for the D, DU, and S commands, is as follows:

Table 6-2. Action command syntax.

| Command | AT syntax |
|---|--|
| Action command with no parameters used | <command/> |
| Action command with one or more sub- parameters used | <pre><command/>[<value>]</value></pre> |



The value may be either a single value parameter or a compound value parameter, as described in Section 6.1.4 on page 6-2. Some commands may have no parameters at all. Expected value is noted in the description of a particular command.

Table 6-3. Example of action command.

| Command/Response | Comment |
|------------------|--|
| AT+WLEAVE | Leave the network |
| ОК | Result code |
| ATX2 | 2 - Disables events and data indications |
| OK | Result code |

6.1.7 Parameter set command syntax

The following syntax is used for a parameter set command:

Table 6-4. Parameter set command syntax.

| Command | AT syntax |
|-----------------------|---|
| Parameter set command | <pre><command/>=[<value>]</value></pre> |

If the named parameter is implemented in the module, all the mandatory values are specified, and all values are valid according to the definition of the parameter where the specified values should be stored. If <command> is not recognized, one or more of mandatory values are omitted, or one or more values are of the wrong type or beyond the valid range, then the module generates the **ERROR** result code and terminates processing of the command line. **ERROR** is also generated if too many values are specified. In case of an error, the previous values of the parameter are unaffected:

Table 6-5. Example of parameter set command.

| Command/response | Comment |
|------------------|----------------------|
| AT+WWAIT=4000 | Set parameter +WWAIT |
| OK | Result code |

6.1.8 Parameter read command syntax

The host may determine the current value or values stored in a parameter by using the following syntax:

Table 6-6. Parameter read command syntax.

| Command | AT Syntax |
|------------------------|------------------------|
| Parameter read command | <pre><command/>?</pre> |

If the named parameter is implemented, its current values are sent to the host in an information text response. The format of this response is described in the definition of the parameter. Generally, the response string begins with <command> followed by the ':' character and the values represented in the same form in which they would be generated by the host in a parameter set command. If multiple values are supported, they will generally be separated by commas, as in a parameter set command. For example:

Table 6-7. Example of parameter read command syntax.

| Command/response | Comment |
|------------------|-------------------------------|
| AT+WRETRY? | Request for parameter +WRETRY |
| +WRETRY:3 | Returned value |
| OK | Result code |



6.1.9 Parameter test command syntax

Table 6-8. Parameter test command syntax.

| Command | AT Syntax |
|------------------------|-------------------------|
| Parameter test command | <pre><command/>=?</pre> |

If the module does not recognize the indicated <command>, it returns the **ERROR** result code and terminates processing of the command line. If the module does recognize the parameter name, it returns an information text response to the host, followed by the OK result code. The information text response will indicate the values supported by the module for each of the sub-parameters, and, possibly, additional information. The format of this information text response is defined for each parameter. See "Information text formats" on page 6-6 for the general formats for the specification of sets and ranges of numeric values. Generally, an information text response starts with a <command> followed by the ':' character.

When an action/parameter accepts a single numeric sub-parameter, or the parameter accepts only one numeric value, the set of supported values may be presented in an information text as an ordered list of values. The list should be preceded by left parenthesis, '(' (hex code 0×28), and closed by right parenthesis, ')' (hex code 0×29). If that very single value is supported, it should appear in parentheses. If more than one value is supported, then the values may be listed individually, separated by comma characters (hex code 0×20). When a continuous range of values is supported, the values appear in the form of the first value in the range and the last value in the range, both separated by a hyphen character (hex code 0×20). The specification of single values and value ranges may be alternated within a single information text. Nevertheless, the supported values should be indicated in an ascending order. The following are some examples of value range indications:

Table 6-9. Value range indications.

| Value | Comment |
|-------------------|---|
| (0) | Only the 0 value is supported |
| (1,2,3) | The values 1, 2, and 3 are supported |
| (1-3) | The values 1 through 3 are supported |
| (0,4,5,6,9,11,12) | The several listed values are supported |
| (0,4-6,9,11-12) | Alternative expression of the previous list |

The value may be either a single value parameter or a compound value parameter as described in Section 6.1.4 on page 6-2. Some commands may have no parameters at all. Expected values are noted in the description of a particular command.

Table 6-10. Example of parameter test command syntax.

| Command/response | Comment |
|--------------------|--|
| AT+WSRC=? | Request for valid range of the short address |
| +WSRC: (0000-FFF7) | Returned value |
| OK | Result code |

When an action/parameter accepts more than one sub-parameter, or the parameter accepts more than one value, the set of supported values may be presented as a list of the parenthetically-enclosed value range strings, separated by commas. For example, the information text in response to testing an action that accepts three sub-parameters and supports various ranges for each of them could appear as follows:

$$(0)$$
, $(1-3)$, $(0,4-6,9,11-12)$

This indicates that the first sub-parameter accepts only the 0 value, the second accepts any value from 1 through 3, inclusively, and the third sub-parameter accepts any of the values 0, 4, 5, 6, 9, 11, or 12.



6.1.10 S-registers

S-registers represent a group of numerical parameters that can be addressed in a special syntax. Each S-register has its own address and value. Some S-registers are standardized by the V.250 recommendations, and are used in the module. Some of the S-registers are non-standard, defined specifically by the SerialNet software.

AT commands that begin with the 'S' character are allowed for S-register access. These differ from other AT commands in some respects. The number following the 'S' character indicates the referenced "register number." If the number is not recognized as a valid register number (register is omitted), the **ERROR** result code is generated.

Immediately following that number, either a '?' or '=' character (hex codes 0x3F or 0x3D, respectively) should appear. '?' is used to read the current value of the indicated S-parameter. '=' is used to set the S-parameter to a new value.

Table 6-11. S-registers.

| Command | AT Syntax |
|------------------------|---|
| Reading the S-register | S <parameter_number>?</parameter_number> |
| Setting the S-register | S <parameter_number>=[<value>]</value></parameter_number> |

If the '=' character is used, the new value to be stored in the S-parameter is specified in decimal form following the '=' character. If no value is given (that is, the end of the command line occurs or the next command follows immediately), the corresponding S-parameter will be set to 0. The ranges of acceptable values are given in the description of each S-register.

"S-registers" on page 6-6 gives functional representation of S-registers associated to the commands.

6.1.11 Device responses

There are two types of responses that may be generated by the module:

- Information responses
- Result codes

Basically, any information response consists of three parts: header, text, and trailer. The characters generated in the header are determined by the user's setting (see V command, Table 6-63 on page 6-43). The trailer consists of two characters, namely the ordinal value of parameter S3, followed by the ordinal value of parameter S4. Information text may contain multiple lines, and the text may include any formatting characters to improve readability.

A result code consists of three parts: header, result text, and trailer. The characters to be generated in the header and trailer are determined by the user's setting (see the V command, Table 6-63 on page 6-43). The result text may be generated as a number or a string, depending on the user-selected setting (see the V command, Table 6-63 on page 6-43).

There are two general types of result codes: final and unsolicited.

Final result codes (**OK/ERROR**) indicate completion of the module action and readiness to accept new commands from the host. Unsolicited result codes (such as **DATA**) may not be directly associated with the issuance of a command from the host. They indicate the occurrence of another **EVENT** causing them.

Command X (see Table 6-65 on page 6-44) controls the generation of result codes, while command Q (see Table 6-62 on page 6-42) results in their total suppression.

"Parameter persistence" on page 5-4 summarizes the result codes in both verbose and numeric forms with their corresponding parameter(s), if any, and a brief description. Each command description refers to the specific result codes that may be generated in relation to the command and the circumstances under which they may be issued.

6.1.12 Information text formats

In general, the particular information text format returned by extended syntax commands will be specified in the command definition.



Note that the module may insert intermediate <CR> characters in very long information text responses, in order to avoid overflow in the host receive buffers. If intermediate <CR> characters are included, the module does not include the character sequences " $\mathbf{0}$ <CR>" (0x30, 0x0D) or " $\mathbf{0}\mathbf{K}$ <CR>" (0x4F, 0x4B, 0x0D), so that the host can avoid false detection of the end of these information text responses.

6.2 Networking parameters

This section describes SerialNet commands associated with networking parameters. Most of the parameters shall be set on each device according to the desired network characteristics prior to executing the network start/join procedure. Note that if the default setting or persistent value from the EEPROM (see "Parameter persistence" on page 5-4) already has the desired value for a network parameter, there is no need to assign it explicitly again prior to the network start/join.

There are also a number of hard-coded parameters that cannot be changed by AT commands, but which have direct impact on possible network topology and performance. Table 6-12 lists such parameters, and provides their values in SerialNet firmware with and without security support.

Table 6-12. Values of ConfigServer parameters applied in SerialNet firmware.

| BitCloud ConfigServer parameter | No security support | With security support |
|-----------------------------------|---------------------|-----------------------|
| CS_NEIB_TABLE_SIZE | 25 | 10 |
| CS_MAX_CHILDREN_AMOUNT | 25 | 10 |
| CS_MAX_CHILDREN_ROUTER_AMOUNT | 10 | 5 |
| CS_ROUTE_TABLE_SIZE | 40 | 25 |
| CS_MAX_NETWORK_DEPTH | 6 | 5 |
| CS_NWK_BTT_SIZE | 50 | 30 |
| CS_ADDRESS_MAP_TABLE_SIZE | 10 | 10 |
| CS_ROUTE_DISCOVERY_TABLE_SIZE | 4 | 3 |
| CS_APS_DATA_REQ_BUFFERS_AMOUNT | 4 | 4 |
| CS_APS_ACK_FRAME_BUFFERS_AMOUNT | 3 | 3 |
| CS_DUPLICATE_REJECTION_TABLE_SIZE | 5 | 5 |
| CS_NWK_BUFFERS_AMOUNT | 4 | 4 |

Their values shall be taken into account during network establishment and operation. Details about each parameter can be found in BitCloud Stack Documentation (see [Step 11.] in "Related documents and references" on page 2-1).



6.2.1 "+WPANID" - Set/Get extended PAN ID

Table 6-13. "+WPANID" - Set/Get extended PAN ID.

| Syntax/descriptor | Explanation |
|--------------------------|--|
| +WPANID= <value></value> | The command sets the extended PAN ID for the device. |
| | value is the extended PAN ID in the form of a 64-bit hexadecimal number that uniquely identifies the target network. |
| | If PAN ID is set to 0, the coordinator will form a network with the extended PAN ID equal to its extended (MAC) address. Router and end device nodes in such case will join the first available network, irrespective of its extended PAN ID. |
| | Notes: 1. Setting the extended PAN ID is possible only when the device is not in the network. 2. Several networks with different PANIDs can be operated in parallel on the same frequency channel. |
| +WPANID? | The command returns the extended PAN ID that is specified on the device for network operation. |
| +WPANID=? | The command requests a valid range for the extended PAN ID value. |
| S-register | S21 (RW). This register is just keeping a copy of the parameter accessible through the +WPANID command. |
| | S20 (R). This register contains the actual extended PAN ID that is used for networking. If the S21 register is set to 0 and the device is in the network, this register will keep the extended PAN ID of the selected network. If the device has not been connected, this register contains 0. |
| Result codes | The set command is executed if the device is not in the network and the extended PAN ID is in the valid range. In such case, the device returns oK upon completion. Otherwise, the extended PAN ID is ignored, and the device responds with ERROR . |
| | AT+WPANID=10 |
| | OK |
| | AT+WPANID? |
| Example | +WPANID:000000000000000000000000000000000000 |
| Example | OK |
| | AT+WPANID=? |
| | +WPANID: (00000000000000-FFFFFFFFFFFF) |
| | OK |
| Default value | 0000000000000 |
| Persistence | value is stored in EEPROM |
| Node types | Coordinator / router / end device |

6.2.2 "+WCHAN" - Get active channel

Table 6-14. "+WCHAN" - Get active channel.

| Syntax/descriptor | Explanation |
|-------------------|---|
| +WCHAN? | The command requests the channel number (in hexadecimal form) the device is currently operating on. If the node is not in the network, FF is returned. |
| S-register | S22 (R) |
| Result codes | OK |
| | AT+WCHAN? |
| Example | +WCHAN: 0B |
| | OK |
| Node types | Coordinator / router / end device |



6.2.3 "+WCHMASK" - Set/Get channel mask

Table 6-15. "+WCHMASK" - Set/Get channel mask.

| Syntax | Explanation | | |
|----------------------------|--|--|--|
| +WCHMASK= <value>-</value> | The command sets the channel mask to be used for network operation. | | |
| | value is a 32-bit field that specifies the channel numbers supported by the node. The five most-significant bits of the channel mask $(b31,,b27)$ shall be set to 0. The remaining 27 bits $(b26, b25,,b0)$ indicate availability status for each of the 27 valid channels (1 = supported, 0 = unsupported). Channels are distributed across frequency bands as follows: | | |
| | 780MHz: channel numbers 0 – 3 | | |
| | 868MHz: channel number 0 | | |
| | 915MHz: channel numbers 1 – 10 | | |
| | 2.4GHz: channel numbers 11 – 26 | | |
| | For sub-GHz bands, the corresponding channel page shall be configured by the +WCHPAGE command (see Table 6-16 on page 6-10). | | |
| | A detailed description of the channel mask parameter can be found in clause 6.1.2 of the 802.15.4-2006 standard. | | |
| | Notes: 1. Only channels from frequency bands supported by the platform's RF chip can be selected in the channel mask. | | |
| | 2. The command is not accessible when the node is joined to a network. | | |
| +WCHMASK? | The command returns the actual channel mask. | | |
| | The returned channel mask can be different from the channel mask set by the +WCHMASK= <value> command, and depends on the hardware capabilities. The cleared bits mark unsupported channels.</value> | | |
| +WCHMASK=? | The command returns the channel capability mask in the form of two 32-bit unsigned hexadecimal numbers. It returns 00000800-07FFF800 for 2.4GHz chipsets and 00000001-000007FF for sub-GHz. | | |
| | Note: Strictly speaking, these two numbers do not represent "range" in its direct sense, but are rather the maximum and minimum values achievable by the composition of corresponding bits. | | |
| S-register | S23 (RW) | | |
| Result codes | The set command is executed if the node is not in the network and the channel mask is set according to hardware capabilities actually available. In such case, the device returns ox . Otherwise, the channel mask is ignored, and the device responds with ERROR . | | |
| | AT+WCHMASK=40000 | | |
| | ок | | |
| Example | AT+WCHMASK? | | |
| | +WCHMASK:00040000 | | |
| | OK | | |
| | AT+WCHMASK=? | | |
| | +WCHMASK(00000800-07FFF800) | | |
| Default value | 00000800 for 2.4GHz chipsets or 00000001 for sub-GHz | | |
| Persistence | value is stored in the EEPROM | | |
| | | | |
| Node types | Coordinator / router / end device | | |



6.2.4 "+WCHPAGE" - Set/Get channel page

The command is available only for platforms with the Atmel AT86RF212 radio part.

Table 6-16. "+WCHPAGE" - Set/Get channel page.

| Syntax | Explanation | |
|---------------------------|---|--|
| +WCHPAGE= <value></value> | The command sets the channel page that will be used for networking. | |
| | Values 0 and 2 correspond, respectively, to BPSK and O-QPSK modulations on 868/915MHz channels. Value 5 means that the 780MHz frequency band with O-QPSK modulation shall be used. | |
| | A detailed description of the channel page parameter can be found in clause 6.1.2 of the 802.15.4-2006 standard. | |
| | Note: The command is not accessible when the node is joined to a network. | |
| +WCHPAGE? | The command returns actual channel page. | |
| +WCHPAGE=? | The command returns possible channel pages: 0,2,5. | |
| S-register | s25 (RW) | |
| Result codes | οκ if the device contains the RF212 radio chip and is not in the network; otherwise, ERROR is returned. | |
| | AT+WCHPAGE=0 | |
| | OK | |
| | AT+WCHPAGE? | |
| Example | +WCHPAGE: 0 | |
| Example | OK | |
| | AT+WCHPAGE=? | |
| | +WCHPAGE: (0,2,5) | |
| | OK | |
| Default value | 0 | |
| Persistence | value is stored in the EEPROM | |
| Node types | Coordinator / router / end device | |

6.2.5 "+WAUTONET" - Enable/Disable automatic networking

Table 6-17. "+WAUTONET" - Enable/Disable automatic networking.

| Syntax | Explanation |
|----------------------------|--|
| +WAUTONET= <value></value> | The command controls the node activity behavior at power up, reset, or when a connection loss is detected. |
| | value has a Boolean type. 1 implies automatic joining to the network, 0 means that automatic joining is disabled and the +WJOIN command shall be used for the network start procedure. |
| +WAUTONET? | The command requests current automatic networking configuration. |
| +WAUTONET=? | The command requests the range of supported values. |
| S-register | S24 (RW) |
| Result codes | ОК |



Table 6-17. "+WAUTONET" - Enable/Disable automatic networking. (Continued)

| | 3 \ |
|---------------|--------------------------------------|
| | AT+WAUTONET=1 |
| | OK |
| | AT+WAUTONET? |
| Example | +WAUTONET:1 |
| Lxample | OK |
| | AT+WAUTONET=? |
| | +WAUTONET: (0,1) |
| | OK |
| Default value | 0 – automatic networking is disabled |
| Persistence | value is stored in the EEPROM |
| Node types | Coordinator / router / end device |

6.2.6 "+WROLE" - Set/Get node role (coordinator / router / end device)

Table 6-18. "+WROLE" - Set/Get node role (coordinator / router / end device).

| Syntax | Explanation | | |
|-------------------------|---|--|--|
| +WROLE= <value></value> | The command sets the node role to value as follows: | | |
| | 0 – Coordinator 1 – Router | | |
| | | | |
| | 2 – End device | | |
| | Note: The command is not a | ccessible when the node is joined to a network. | |
| +WROLE? | The command requests the act | ual node role. | |
| +WROLE=? | The command requests the not | The command requests the node roles available for the device. | |
| | Actual capabilities depend on the particular firmware version loaded on the device. | | |
| S-register | s33 (RW) | | |
| Result codes | OK is returned if value is in the v | OK is returned if value is in the valid range; otherwise, ERROR is returned. | |
| | AT+WLEAVE | Leave the network | |
| | OK | | |
| | AT+WROLE=? | | |
| | +WROLE: (0,1,2) | | |
| Example | OK | | |
| Example | AT+WROLE=2 | Switch to the end device role | |
| | OK | | |
| | AT+WROLE? | | |
| | +WROLE: 2 | | |
| | OK | | |
| Default value | Depends on the firmware version. Typically 1 – Router | | |
| Persistence | value is stored in the EEPROM | | |
| Node types | Coordinator / router / end device | | |



6.2.7 "+GSN" - Set/Get extended (MAC) address

Table 6-19. "+GSN" - Set/Get extended (MAC) address.

| Syntax | Explanation | |
|-----------------------|--|---------------------|
| +GSN= <value></value> | The command assigns the device extended (MAC) address. value is a 64-bit hexadecimal number that uniquely identifies the device. Note: The command is not accessible when the node is joined to a network. | |
| +GSN? | The command returns the device extended (MAC) address in the form of a 64-bit hexadecimal number. | |
| Result codes | ок is always returned. | |
| Example | AT+GSN=FEDCBA0987654321 OK AT+GSN? +GSN:FEDCBA0987654321 OK AT14 FEDCBA0987654321 OK | Just an alias to ⊥4 |
| Default value | Notes: 1. If extended address is equal to zero, then upon power up or reset SerialNet searches for the MAC address on the 1-wire interface and applies it if detected. 2. User-defined MAC address shall be a non-zero values less than 0xffffffffffffffffffffffffffffffffffff | |
| Persistence | value is stored in EEPROM | |
| Node types | Coordinator / router / end device | |

6.2.8 "+WSRC" - Set/Get short (NWK) address

Table 6-20. "+WSRC" - Set/Get short (NWK) address.

| Syntax | Explanation | |
|------------------------|--|--|
| +WSRC= <value></value> | The command assigns the device short (network) address. value is a 16-bit hexadecimal number that will be used by the device for communication in the network. It shall be unique within the network. | |
| | There are two approaches for the short address assignment: | |
| | ■ Stochastic addressing is applied if value is set to FFFF when the device is not in the network. In such case, short address is assigned randomly by the stack when the device joins the network. The stack also automatically resolves all possible address conflicts. After network join, this parameter contains the current short address of the node, but after leaving the network, the +WSRC value is reset to FFFF. Hence the node can get a new short address assigned during the next network join. | |
| | ■ Static addressing is applied if value is set to non-FFFF prior to network join. After joining the network, the device will use the assigned value as its short address. Moreover, after leaving the network, the +WSRC value will be kept and reused during the next network join attempt, unless explicitly overwritten with another value. If static addressing is used, the user is responsible for ensuring that the node's short address is unique within the network. | |
| | All nodes across the network shall use the same addressing mode. | |
| | Notes: 1. The command is not accessible when the node is joined to a network. 2. The coordinator node shall always have its short address set as 0000. Nodes of other roles shall have nonzero short addresses. | |
| +WSRC? | The command returns the device short address in the form of a 16-bit hexadecimal number. | |
| | If the node is in the network, the command returns its actual short address independently of the addressing scheme used. | |
| | If the node is not joined to a network, FFFF is returned if stochastic addressing is used on the device and the user pre-configured address in the case of static addressing. | |
| +WSRC=? | The command requests the range of valid addresses. | |
| S-register | S55 (RW) | |
| Result codes | OK is returned if value is in range; otherwise, ERROR is returned. | |
| | AT+WSRC=2ABC OK AT+WSRC? | |
| Example | +WSRC: 2ABC | |
| | OK AT+WSRC=? | |
| | +WSRC: (0000-FFF7) | |
| | OK | |
| Default value | FFFF | |
| | Note: The FFFF default value implies that stochastic addressing will be used on the device upon network join. | |
| Persistence | value is stored in the EEPROM | |
| Node types | Coordinator / router / end device | |
| | • | |



6.2.9 "+WNWKPANID" - Set/Get short (NWK) PANID

The short PAN ID value is used in ZigBee frame headers during data exchange to identify which network frames belong to. Its 16-bit value is set by the coordinator during network formation.

By default, the short PAN ID is chosen randomly and is intentionally different from the short PAN IDs of other networks present in the same location on channels specified in the channel mask.

Such behavior may lead to the following issue. If the network coordinator leaves the current network while routers continue their operation and then initiates a new network formation, it will establish a network with a short PAN ID different from the short PAN ID of its previous network. Hence, communication between the coordinator and its former network will not be possible.

To avoid the problem described above, the +WNWKPANID command can be used to configure a predefined short PAN ID on the network coordinator.

Table 6-21. "+WNWKPANID" - Set/Get short (NWK) PAN ID.

| Syntax | Explanation | | |
|-----------------------------|--|--|--|
| +WNWKPANID= <value></value> | The command assigns the device short (network) PAN ID of the target network for the device. value is a 16-bit hexadecimal number. If the node is configured as the coordinator, then upon the +WJOIN command, it will form the network with its short PANID equal to value. | | |
| | If +WNWKPANID is set to FFFF, the stack running on a coordinator automatically assigns the short PAN ID randomly and intentionally different from all the other networks detected while forming its own network. | | |
| | If +WNWKPANID is set to FFFF on an end device or a router, it will join to any network matching its +WPANID [ref] setting. Otherwise it will be able to join only to a network with a target short PAN ID equal to value. | | |
| | Notes: 1. The command is not accessible when the node is joined to a network. 2. Using +WNWKPANID does not cancel configuration of the +WPANID parameter, and both parameters need to be used together to achieve the desired behavior. | | |
| +WNWKPANID? | The command returns device short address in the form of 16-bit hexadecimal number. | | |
| +WNWKPANID=? | The command requests the range of valid addresses. | | |
| S-register | Not available | | |
| Result codes | OK is returned if value is in range; otherwise, ERROR is returned. | | |
| Example | AT+WNWKPANID=3A2F OK AT+WNWKPANID? +WNWKPANID:3A2F OK AT+WNWKPANID=? | | |
| | +WNWKPANID: (0000-FFFF) | | |
| Default value | OK | | |
| Delault value | FFFF | | |
| | Note: The default FFFF value implies that no predefined short PAN ID is used by the device. | | |
| Persistence | value is stored in the EEPROM | | |
| Node types | Coordinator / router / end device | | |



6.3 Network management functions

SerialNet commands described in this section execute various network management functionality, including network join and leave operations, obtaining network topology-related information, getting link quality data, etc.

When exploring network topology, it is important to take into account the fact that due to mesh networking, only an end device node can be a child and have a dedicated parent node (coordinator or router) during its lifetime in the network. Router nodes use the coordinator or other routers only as network entry points, and are not associated as direct children after network join. However, if there is enough space in the node's neighbor table, it will contain information about neighbor coordinator/router nodes.

6.3.1 "+WJOIN" - Start/Join to the network

Table 6-22. "+WJOIN" - Start/Join to the network.

| Syntax | Explanation | |
|--------------|--|--|
| +WJOIN | The command forces the device to form a network (for coordinator node) or join an existing network (for router or end device nodes). | |
| | The desired network and device characteristics shall be set prior to the +WJOIN request using, if necessary, SerialNet commands from "Networking parameters" on page 6-7. | |
| Result codes | OK is returned if network formation/join is completed successfully; ERROR is returned if failed. If the node is in the network already, it returns OK immediately. | |
| Example | AT+WJOIN | |
| Lxample | OK | |
| Node types | Coordinator / router / end device | |

6.3.2 "+WLEAVE" - Leave the network

Table 6-23. "+WLEAVE" - Leave the network.

| Syntax | Explanation | |
|--------------|--|--|
| +WLEAVE | The command forces the node to leave the network. | |
| | If the node has any children, it will automatically force them to leave the network, too. | |
| | Note: Parameters stored in EEPROM persist even after the node leaves the network. | |
| Result codes | OK is returned on process completion. If the device was not connected before starting the process, it returns ERROR immediately. | |
| Example | AT+WLEAVE | |
| Lxample | OK | |
| Node types | Coordinator / router / end device | |



6.3.3 "+WNWK" - Get networking status

Table 6-24. "+WNWK" – Get networking status.

| Syntax | Explanation | |
|--------------|---|--------------------------------|
| +WNWK | The command requests the current networking status of the device. | |
| Result codes | OK is returned if the device is joined to a network; otherwise, it returns ERROR. | |
| | AT+WLEAVE | Leave the network first |
| | OK | |
| Example | AT+WNWK | |
| | ERROR | Device is not in a network now |
| Node types | Coordinator / router / end device | |

6.3.4 "+WPARENT" - Get parent address

Table 6-25. "+WPARENT" - Get parent address.

| Syntax | Explanation | |
|--------------|--|--|
| +WPARENT? | The command requests the parent node address the device is associated with. | |
| | The extended (MAC) address of the parent node is returned as a 64-bit hexadecimal number if the S30 register is set to 0. | |
| | The short (NWK) parent address is returned if the S30 register is set to 1. See Table 6-29 on page 6-19 for details. | |
| | Note: This command does not cause network operations, and just returns a copy of the parent address assigned during the joining process. | |
| Result codes | OK is returned if the module is in the network and has a parent. ERROR will be returned if the device is not in the connected state or has a node role of coordinator or router. | |
| | AT+WPARENT? | |
| Example | +WPARENT: 0123456789ABCDEF | |
| | OK | |
| Node types | End devices | |

6.3.5 "+WCHILDREN" – Get children addresses

Table 6-26. "+WCHILDREN" - Get children addresses.

| Syntax | Explanation | |
|-------------|--|--|
| +WCHILDREN? | The command requests the addresses of children end devices associated with the node. | |
| | The extended (MAC) addresses of children nodes are returned as 64-bit hexadecimal numbers if the S3 register is set to 0. | |
| | The short (NWK) addresses of children nodes are returned if the S30 register is set to 1. See Table 6-29 on page 6-19 for details. | |
| | The children addresses returned are delimited by commas. | |
| | Notes: 1. An end device is removed from the children list if the parent node receives no poll requests from the child during 3*(sleep_interval + sync_period) time interval as configured on the parent device by +WPWR and +WSYNCPRD commands. 2. This command does not cause network operations, and just returns copies of the children addresses stored in the parent memory. | |



Table 6-26. "+WCHILDREN" - Get children addresses. (Continued)

| Result codes | OK is returned if the module is in the network, even though there is no child connected yet. ERROR will be returned if the device is not in the connected state or has an end device node role. | |
|--------------|---|--|
| | AT+WCHILDREN? | |
| Example | +WCHILDREN:0123456789ABCDEF,123456789ABCDEF0 | |
| | OK | |
| Node types | Coordinator and routers | |

6.3.6 "+WNBSIZE" - Get number of neighbors

Table 6-27. "+WNBSIZE" - Get number of neighbors.

| Syntax | Explanation | |
|--------------|--|--|
| +WNBSIZE? | The command requests a number of entries in node's neighbor table. | |
| | Returned result consists of two values: the first is the current number of occupied entries in node's neighbor table; the second is the maximum possible number of entries (size of the neighbor table). | |
| Result codes | OK is returned if the node is in the network. If the device is not in the connected state, ERROR will be returned. | |
| | AT+WNBSIZE? | |
| Example | +WNBSIZE:2,5 | |
| | OK | |
| Node types | Coordinator / router / end device | |



6.3.7 "+WNB" - Get neighbor information

Table 6-28. "+WNB" - Get neighbor information.

| Syntax | Explanation | | |
|---|---|--|--|
| +WNB <node_role> [,<device_addr>]</device_addr></node_role> | The command requests the contents of node's neighbor table. The node_role parameter specifies the node role of neighboring nodes to be extracted from the neighbor table. The following values are accepted: 0 - coordinator 1 - router 2 - end device 3 - all device types Optional parameter device_addr specifies the address of the neighboring node to be extracted. If the s30 register is set to 0, device_addr is accepted as the short (NWK) address. If the s30 register is set to 1, device_addr is expected to be an extended (MAC) address. See Table 6-29 on page 6-19 for details. The command's information response has the following format: seqNr nodeRole extAddr nwkAddr relationship depth where seqNr - is the sequence number in the neighbor table nodeRole - is the neighbor's extended address nwkAddr - is the neighbor's extended address nwkAddr - is the neighbor's network address relationship - is the neighbor's relationship to the current node (0 - parent, 1 - child, 3 - no relationship) depth - is the neighbor's network depth Notes: 1. A neighbor entry is removed from the table if the node, during a certain interval, doesn't receive any periodic management frames, expected from the neighbor. If neighbor is a router/coordinator, this interval is 45 seconds (management frames are sent once per 15 seconds). If the neighbor is an end device, then the interval equals 3 × (sleep_interval + sync_period), as configured on the node by +WPWR and +WSYNCPRD commands. 2. Although right after network join an end device node can have information about other nodes is removed shortly after an end device join. The same is valid for information about other nodes is not directly "visible" for other routers in its neighborhood. 3. This command does not cause network operations, and just returns information from the | | |
| Result codes | node's current neighbor table. ok is returned if the node is in the network. If the node is not in the connected state, ERROR will be returned | | |
| Example | AT+WNB 3 1 0 000000000000000 0000 3 2 2 1 0000000000000 0002 0 1 OK AT+WNB 1,2 1 1 00000000000000 0002 0 1 OK | | |
| Node types | Coordinator / router / end device | | |

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6.3.8 "S30" - Set node addressing mode

Table 6-29. "S30" - Set node addressing mode.

| Syntax | Explanation | |
|----------------------|---|--|
| S30= <value></value> | The command sets the node addressing scheme to be used by some SerialNet commands. value specifies the addressing mode: | |
| | 0 – extended (64-bit) addressing 1 – short (16-bit) addressing | |
| S30? | The command requests the current addressing mode | |
| Result codes | The command returns ox if value is in range; otherwise, it returns ERROR . | |
| S-register | s30 (RW) | |
| Example | ATS30=0 OK AT+WPARENT? +WPARENT:000100000A3B98CC OK ATS30=1 OK AT+WPARENT? +WPARENT:0000 OK | |
| Node types | Coordinator / router / end device | |
| Default value | 0 | |
| Persistence | value is NOT stored in EEPROM | |

Note: Setting the addressing mode, the S30 command affects the performance of the following commands: +WPAR-ENT? (see Section Table 6-25 on page 6-16), +WCHILDREN? (see Table 6-26 on page 6-16), and +WNB (see Table 6-28 on page 6-18). These commands use an extended (MAC) address if S30 is set to 0, but will switch to using short (NWK) addressing if S30 is set to 1.

6.3.9 "+WLQI" - Get LQI value

Table 6-30. "+WLQI" - Get LQI value.

| Syntax | | Explanation | |
|---------------------|--|--|--|
| +WLQI <addr></addr> | The command requests the LQI value for the link to the node with short (NWK) address equal to addr specified in 16-bit hexadecimal format. | | |
| | The command returns the actual LQI | The command returns the actual LQI value in the range of 0255. | |
| | LQI information can be retrieved for links within a one-hop radius only. An end device can obtain LQI only to its current parent node, and vice versa: LQI to an end device can be obtained only from its current parent node. LQI value is measured during data transmission initiated by the ATD command. If ATD has not been performed yet, +WLQI may return an irrelevant value. | | |
| Result codes | The node returns ok if the device is in the network and the LQI value for this particular link exists; otherwise, ERROR will be returned. | | |
| Example | AT+WLQI 1 +WLQI:254 OK | Request LQI for the link to the node with short address 0x0001 | |
| Node types | Coordinator / router / end device | | |



6.3.10 "+WRSSI" - Get RSSI value

Table 6-31. "+WRSSI" - Get RSSI value.

| Syntax | Explanation | Explanation | |
|----------------------|--|--|--|
| +WRSSI <addr></addr> | The command requests the RSSI value for the link to the node with short (NWK) address equal to addr specified in 16-bit hexadecimal format. | | |
| | The command returns the actual RSSI value expressed in dBm. If RSSI is not available, then the value -91 is returned. | | |
| | RSSI information can be retrieved for links within a one-hop radius only. An end device can obtain RSSI only to its current parent, and vice versa: RSSI to an end device can be obtained only from its current parent node. RSSI value is measured during data transmission initiated by the ATD command. If ATD has not been performed yet, +WRSSI may return an irrelevant value. | | |
| Result codes | The node returns o k if the device is in the network and the RSSI value for this particular link exists; otherwise, ERROR will be returned. | | |
| Example | AT+WRSSI 0001 +WRSSI:-80 OK | Request RSSI for the link to the node with short address 0x0001 -80dBm | |
| Node types | Coordinator / router / end device | | |



6.4 Security

SerialNet firmware images with names having _Security at the end support standard security mechanism defined in the ZigBee PRO specification, see [Step 5.] in section "References" on page 2-1. In this scheme, a special128-bit key (called the network key in ZigBee PRO), the same for all devices, is used in the network to encrypt/decrypt messages with the AES-128 algorithm. The security mechanism can be enabled/disabled using the +WSECON command and configured as described below. If security is enabled, then the payload of all data frames sent by the device will be encrypted with the network key.

To employ the security mechanism, the network coordinator shall be configured as a trust center (TC) by assigning a +WTCADDR value to its extended address. The TC shall also be programmed with a network key (+WNETKEY command) prior to network start.

Joining a secured network can be organized in an unsecured or secured way using the +WSECSTATUS command. To avoid possible confusion during the network join, all nodes, including the TC, shall have the same +WSECSTATUS configuration prior to network join/start.

For an unsecured join, +WSECSTATUS shall be set to 3. In this case, only the TC shall know the network key in advance, while other devices usually only have information about the TC's extended address (+WTCADDR). In such a configuration, when a new device tries to enter the network, a special message is propagated to the TC informing it about the joining device. Then, the TC replies with the transport key command that contains the current network key. However, to allow the joining device to understand this command, it is delivered over the last hop in an un-encrypted frame. The joining device accepts the key if the sender address of the received transport key command matches its pre-configured TC's extended address, and rejects the key if the addresses don't match. After the key is accepted, the device is authenticated and starts exchanging data using the received network key.

A secured join completely eliminates the un-encrypted key transmission performed in an unsecured join. For a secured join, nodes shall have +WSECSTATUS set to 0 and be pre-configured with the network key (+WNETKEY command) prior to a network join attempt. The +WTCADDR setting is required on the joining device only if it has +WPANID set to 0 and +WSRC set to FFFF (stochastic addressing). In such a configuration, the device expects a transport key command from the TC as in an unsecured join. But in this case, the command payload contains zeros, and, hence, doesn't reveal the secret network key.

The sections below provide detailed descriptions of the commands that shall be used to configure and operate a secured network.

6.4.1 "+WSECON" -Enable/Disable security

Table 6-32. "+WSECON" - Enable/Disable security.

| Syntax | Explanation | | | |
|--------------------------|--|--|--|--|
| +WSECON= <value></value> | The command enables/disables security for a network join and data exchange on the device. value is a Boolean type. 1 means that the ZigBee PRO standard security mechanism is enabled on the node. 0 implies that encryption is not used by the node. | | | |
| | Notes: 1. The command is not accessible when the node is joined to a network. 2. The command configures the CS_SECURITY_ON parameter in the BitCloud stack. | | | |
| +WSECON? | The command returns value indicating whether security on the node is enabled or not. | | | |
| +WSECON=? | The command requests the range of supported values. | | | |
| S-register | Not available. | | | |
| Result codes | OK is returned if value is in range; otherwise, ERROR is returned. | | | |



Table 6-32. "+WSECON" - Enable/Disable security. (Continued)

| | AT+WSECON=1 | |
|---------------|-----------------------------------|--|
| | OK | |
| | AT+WSECON? | |
| Example | +WSECON:1 | |
| Example | OK | |
| | AT+WSECON=? | |
| | +WSECON: (0-3) | |
| | OK | |
| Default value | 0 | |
| Persistence | value is stored in the EEPROM | |
| Node types | Coordinator / router / end device | |

6.4.2 "+WSECSTATUS" - Set/Get security status

Table 6-33. "+WSECSTATUS" - Set/Get security status.

| Syntax | Explanation | | |
|------------------------------|---|--|--|
| +WSECSTATUS= <value></value> | The command configures the security status on the devices as follows: | | |
| | 0 – for secured key transmission; the device should have a pre-configured, nonzero network key prior to network join. | | |
| | 3 – the device obtains the network key from the trust center via un-encrypted transmission over the air. | | |
| | 1, 2 – reserved for high-security mode, not supported in SerialNet. | | |
| | Notes: 1. The command is not accessible when the node is joined to a network. 2. The command configures the CSZDO_SECURITY_STATUS parameter in the BitCloud stack. 3. On the trust center, independently of +WSECSTATUS configuration, +WNETKEY shall be set to the non-zero network key to be used for encryption. | | |
| +WSECSTATUS? | The command returns device security status. | | |
| +WSECSTATUS=? | The command requests the range of valid statuses. | | |
| S-register | Not available. | | |
| Result codes | OK is returned if value is in range; otherwise, ERROR is returned. | | |
| | AT+WSECSTATUS=3 | | |
| | OK | | |
| | AT+WSECSTATUS? | | |
| Example | +WSECON: 3 | | |
| | OK | | |
| | AT+WSECSTATUS=? | | |
| | +WSECSTATUS: (0-3) | | |
| 5 (); (| OK | | |
| Default value | 0 | | |
| Persistence | value is stored in the EEPROM | | |
| Node types | Coordinator / router / end device | | |



6.4.3 "+WNETKEY" - Set/Get network encryption key

Table 6-34. "+WNETKEY" - Set/Get network encryption key.

| Syntax | Explanation | | |
|--|---|--|--|
| +WNETKEY= | The command assigns the network key on the device. | | |
| <pre><val64bit0,val64bit1></val64bit0,val64bit1></pre> | val64bit0 and val64bit1 are 64-bit hexadecimal numbers that compose the 128-bit secret encryption key to be used for data encryption/decryption in the network. | | |
| | Notes: 1. The command is not accessible when the node is joined to a network. 2. Zero value implies no encryption to be used. 3. The command configures the CS_NETWORK_KEY parameter in the BitCloud stack. | | |
| +WNETKEY? | The command returns the network key configuration on the node. | | |
| +WNETKEY=? | The command requests the range of valid values for the network key. | | |
| S-register | Not available. | | |
| Result codes | OK is returned if val64bit0 and val64bit1 are in range; otherwise, ERROR is returned. | | |
| | AT+WNETKEY=CCCCCCCCCCCCC, BBBBBBBBBBBBBBBBBB | | |
| | OK | | |
| | AT+WNETKEY? | | |
| +WNETKEY:CCCCCCCCCCCCCC, BBBBBBBBBBBBBBB | | | |
| Example | OK | | |
| | AT+WNETKEY=? | | |
| | +WNETKEY:(00000000000000-FFFFFFFFFFFFF),(000000000000000- | | |
| | FFFFFFFFFFFFF) | | |
| | OK | | |
| Default value | 000000000000,0000000000000 | | |
| Persistence | val64bit0 and val64bit1 are stored in the EEPROM | | |
| Node types | Coordinator / router / end device | | |

6.4.4 "+WTCADDR" - Set/Get Trust Center address

Table 6-35. "+WTCADDR" - Set/Get Trust Center address.

| Syntax | Explanation | |
|---------------------------|--|--|
| +WTCADDR= <value></value> | The command assigns the trust center extended address. | |
| | value is a 64-bit hexadecimal number that defines the extended address of the trust center node in the network. The trust center itself shall set it to its own extended address. The value shall be configured on the device prior to network join. | |
| | If the device cannot know the TC address in advance, it can use a FFFFFFFFFFFFA value instead. In this case, the device considers the first node replying with the transport key command during network join to be the network's TC. | |
| | Notes: 1. The command is not accessible when the node is joined to a network. 2. The command configures the CS_APS_TRUST_CENTER_ADDRESS parameter in the Bit-Cloud stack. | |
| +WTCADDR? | The command returns the trust center address configured on the node. | |
| +WTCADDR=? | The command requests the range of valid values. | |
| S-register | Not available. | |
| Result codes | OK is returned if value is in range; otherwise, ERROR is returned. | |



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Table 6-35. "+WTCADDR" - Set/Get Trust Center address. (Continued)

| | AT+WTCADDR=000100001090C96D | |
|---------------|--|--|
| | OK | |
| | AT+WTCADDR? | |
| Evernale | +WTCADDR:000100001090C96D | |
| Example | OK | |
| | AT+WTCADDR=? | |
| | +WTCADDR: (0000000000001-FFFFFFFFFFFF) | |
| | OK | |
| Default value | ААААААААААА | |
| Persistence | value is stored in the EEPROM | |
| Node types | Coordinator / router / end device | |



6.5 Data transmission

In SerialNet, data can be transmitted in two ways:

- Unicast transmission to a particular node using the D, DS, or +WPING commands
- Broadcast transmission to all nodes using the DU or D commands with broadcast address

It is important that extended (MAC) addresses are not used for data transmission directly; instead, they are substituted by short (network) addresses, which are convenient for node replacement in network installation and maintenance.

The route establishment procedure to the target node is implemented inside the stack. It is executed automatically upon a data transmission request, and then if a route exists, data delivery (one-hop or multi-hop) is performed to the destination node.

The following application identifiers are used in SerialNet for all data exchange operations:

Profile ID: 0xC31AEndpoint ID: 0x01Cluster ID: 0x00

Note: To ensure safe data transmission over a serial interface between a host and an MCU, it is strongly recommended to set hardware flow control (see Table 6-67 on page 6-45 for details). When running terminal software to control the node, the chosen COM port should be set with the hardware flow control option selected.

6.5.1 Parent polling mechanism

Data delivery to an end device over the last hop (that is, from the parent node to the child) is performed using the polling mechanism described below.

Upon receiving a frame destined for its child node or a broadcast frame with a non-exhausted transmission radius and a destination address equal 0xFFFF, the parent node buffers the frame and waits for a poll request from the child. The maximum waiting time is (sleep_interval + 3 × sync._period), as configured on the parent by the +WPWR and +WSYNCPRD commands.

In awake state, an end device polls its parent node periodically every +WSYNCPRD milliseconds (as configured on the end device). The parent node can transmit a data frame to a child only after receiving a corresponding data poll from it. After data frame reception is completed, the end device issues another data poll request to verify whether there are any frames buffered at the parent.



6.5.2 "D" - Send data to a specific node

Table 6-36. "D" - Send data to a specific node.

| Syntax | Explanation | | |
|--------------------------------|---|---|--|
| D <addr>[,[<arq>]</arq></addr> | The command sends data to a specific node. | | |
| [, <length>]]</length> | addr is the 16-bit hexadecimal short (network) address of the destination node. | | |
| <data></data> | An optional arg parameter (equal to 1 or 0) controls the ARQ/nonARQ data delivery mode, with 1 (that is, ARQ) as the default, if omitted. | | |
| | The length parameter specifies the length in bytes of the data portion to be semaximum allowable number (95 bytes for an un-encrypted frame, and 77 bytes If the length parameter is omitted, the maximum possible value is implied by | | |
| | Data transmission starts either when the specified number of data bytes is received over the serial interface, or when the time interval between two consecutive data symbols exceeds the timeout preset (+WWAIT command - see Table 6-44 on page 6-30). | | |
| | Notes: 1. data should be preceded by <cr> (S3 character, see Table 6-58 on page 6-40). This symbol is not transmitted over the air, and it is not counted in length.</cr> If the destination address is a broadcast address (FFFF for all nodes or FFFE for router/coordinator nodes), the broadcast transmission is performed. | | |
| | If data transmission requires acknowledgement from the destination node (ARQ is set to 1), then OK is returned only after such acknowledgement frame is received. If no acknowledgement is received after +WRETRY transmission attempts, then ERROR is returned as a result code for the DB command. | | |
| Result codes | If an acknowledgement is not requested (arq is set to 0), then OK is returned just upon successful data transmission over the first hop. There is no guarantee on frame delivery to the final destination. If first-hop transmission cannot be performed (channel busy, route unknown, etc.), or if the sending node is not in the network, then ERROR is returned. | | |
| | ATD 12,1,5 | | |
| | HELLO | Send HELLO to the node with address 12 using ARQ | |
| Example | OK | | |
| Lampio | ATD 12 | The same as above, but the node will be waiting for | |
| | HELLO | the timeout expiration before going to the air | |
| | OK | | |
| Node types | Coordinator / router / end device | | |

6.5.3 "DB" - Send binary data to a specific node

Table 6-37. "DB" - Send binary data to a specific node.

| Syntax | Explanation | | |
|-------------------------------|--|---|--|
| DB <addr>[,<arq></arq></addr> | The command sends binary data (not encoded in ASCII symbols) to a specific node. | | |
| [, <length>]]</length> | addr is the 16-bit hexadecimal short (network) address of the destination node. | | |
| <data></data> | An optional arg parameter (equal to 1 or 0) controls the ARQ/nonARQ data delivery mode. If omitted, then ARQ is used. | | |
| | The length parameter specifies the length in bytes of the data portion to be sent. It shall not exceed the maximum allowable number (95 bytes for an un-encrypted frame, and 77 bytes for an encrypted frame) If the length parameter is omitted, the maximum possible value is implied by default. | | |
| | data should be preceded by <cr> (S3 character. See ""S3" - Termination character" on page This symbol is not included in frame payload to be transmitted over the air, and it is not counted in 1</cr> | | |
| | Data transmission starts either when the specified number of data bytes is received over the serial interface, or when the time interval between two consecutive data symbols exceeds the timeout preset (+WWAIT command, see Table 6-44 on page 6-30). In contrast to the D command, data transmission doesn't start if a <cr> code (S3 character, see See ""S3" - Termination character" on page 6-40.) occurs inside the data.</cr> | | |
| | Note: If the destination address is a broadcast address (FFFF for all nodes or FFFE for router/coordinator nodes), the broadcast transmission is performed. | | |
| Decult and a | If data transmission requires an acknowledgement from the destination node (arq is set to 1), then an OK result code is returned only after such acknowledgement frame is received. If no acknowledgement is received after +WRETRY transmission attempts, then ERROR is returned as a result code for the DB command. | | |
| Result codes | If an acknowledgement is not requested (arq is set to 0), then OK is returned just upon successful data transmission over the first hop. There is no guarantee on frame delivery to the final destination. If first-hop transmission cannot be performed (channel busy, route unknown, etc.), or if the sending node is not in the network, ERROR is returned. | | |
| | ATDB 12,1,5 | | |
| | 97CA2 | Send 97CA2 to the node with address 12 using ARQ | |
| | OK | | |
| Example | ATDB 12,0 | | |
| | 97CA2 | The same as above, but without using ARQ, and with the node waiting for timeout expiration before sending | |
| | HELLO | data | |
| | OK | | |
| Node types | Coordinator / router / end device | | |

6.5.4 "DU" - Send broadcast data

Table 6-38. "DU" - Send broadcast data.

| Syntax | Explanation | | |
|-------------------------|---|---|--|
| DU [<length>]</length> | The command sends data using broadcast transmission. | | |
| <data></data> | The length parameter specifies the length in bytes of the data portion to be sent. It shall not exceed the maximum allowable number (95 bytes for an un-encrypted frame, and 77 bytes for an encrypted frame). If the length parameter is omitted, the maximum possible value is implied by default. | | |
| | Data transmission starts either when the specified number of data bytes is received over the serial interface, or when the time interval between two consecutive data symbols exceeds the timeout preset (+WWAIT command, Table 6-44 on page 6-30). | | |
| | Notes: 1. ATDU is, in fact, shorthand for the ATD command with broadcast address (FFFF) as the destination. Data should be preceded by <cr> (S3 character, see Table 6-58 on page 6-40). This symbol is not transmitted over the air, and it is not counted in length.</cr> Data are broadcasted to the whole network (radius 0). | | |
| Result codes | The node responds with o k immediately after the transmission if the node itself is in the network. Otherwise, error is returned. | | |
| | ATDU | | |
| Example | HELLO | Send HELLO to all nodes in the network | |
| | OK | | |
| Node types | Coordinator / router / end device | | |

6.5.5 "DS" - Send S-register value to a specific node

Table 6-39. "DS" - Send S-register value to a specific node.

| Syntax | Explanation | |
|--|---|---|
| DS <s-reg>,<addr> [,[<arq>]</arq></addr></s-reg> | The command sends the S-register value to a specific node. The default arg parameter (set to 1 or 0) specifies whether the ARQ or non-ARQ data delivery mode is used. 1 is implied if arg is omitted. The addr destination node address should be a 16-bit hexadecimal short (network) address. S-register data are sent in the form readable by ATS command without the line termination characters. Note: S-registers defined by user extensions are also accessible by this command. | |
| Result codes | If an acknowledgement is requested (arg is set to 1), the node responds with ox upon receiving an acknowledgement in several attempts (see parameter +WRETRY, Table 6-43 on page 6-30); otherwise, it returns ERROR. If the destination node or the sending node itself is not in the network, ERROR is returned. Also, if the specified S-register cannot be read, the command returns ERROR, and the node does not send anything to the air. | |
| Example | ATDS130,2,0 OK | Send GPIO0 value to the node with address 2 without using ARQ |
| Node types | Coordinator / router / end device | |



6.5.6 "+WPING" - Ping the node

Table 6-40. "+WPING" - Ping the node.

| Syntax | Explanation | |
|----------------------|--|--|
| +WPING <addr></addr> | The command pings the targeted node. addr specifies the destination address as a 16-bit hexadecimal short (network) address. This command is equivalent to the D command with ARQ and zero data length: ATD <addr>,1,0.</addr> | |
| Result codes | The node responds with ok upon receiving an acknowledgement in several attempts (see parameter +WRETRY, Table 6-43 on page 6-30); otherwise, it returns ERROR . If the destination node or the sending node itself is not in the network, ERROR is returned. | |
| Example | AT+WPING 1 OK | |
| Node types | Coordinator / router / end device | |

6.5.7 "+WSYNCPRD" - Poll rate for requesting indirect transactions from the parent

Table 6-41. "+WSYNCPRD" - Poll rate for requesting indirect transactions from the parent.

| Syntax | Explanation | |
|--------------------------|--|-----------------------------|
| +WSYNCPRD= <rate></rate> | The command sets the poll interval to the <rate> value, measured in milliseconds. This value is used by the end device as the poll rate for requesting indirect transmission messages from the parent. Coordinator and router use this rate to verify children presence.</rate> | |
| | Notes: 1. On end devices, the <rate> value must not be increased by this command. Otherwise, Bit-Cloud behavior is unpredictable.</rate> 2. On routers and coordinators, this parameter must be set to the largest <rate> value among all children. Otherwise, child presence status may be detected incorrectly.</rate> 3. This value should be at least two times smaller than the value of +WTIMEOUT (see Table 6-42 on page 6-30). 4. The command is not accessible when the node is joined to a network. | |
| +WSYNCPRD? | The command requests the actual poll rate. | |
| +WSYNCPRD=? | The command requests the allowable range of poll rate values. | |
| S-registers | s37 (RW) | |
| Result codes | ок is always returned. | |
| Example | AT+WSYNCPRD=1000 OK ATS37? 300 OK AT+WSYNCPRD=? +WSYNCPRD: (10-30000) OK | Set poll rate to one second |
| Default values | 1400 | |
| Node types | Coordinator / router / end device | |
| Persistence | rate is NOT stored in EEPROM | |



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6.5.8 "+WTIMEOUT" - Data delivery timeout

Table 6-42. "+WTIMEOUT" - Data delivery timeout.

| Syntax | Explanation | | |
|--------------|---|--|--|
| +WTIMEOUT? | The command returns the timeout value, in milliseconds. The returned value corresponds to the apscAckWaitDuration variable introduced by ZigBee recommendation [Step 2.] in "Related documents and references" on page 2-1. | | |
| S-register | s51 (R) | | |
| Result codes | οκ is always returned. | | |
| | AT+WTIMEOUT? | | |
| Example | +WTIMEOUT:2800 | | |
| | OK | | |
| Node types | Coordinator / router / end device | | |

6.5.9 "+WRETRY" - Repetition count

Table 6-43. "+WRETRY" - Repetition count.

| Syntax | Explanation | | |
|--------------|--|--|--|
| +WRETRY? | The command returns the actual number of retransmission. The returned value corresponds to the apscMaxFrameRetries variable introduced by ZigBee recommendation. | | |
| S-register | S52 (R) | | |
| Result codes | ок is always returned. | | |
| | AT+WRETRY? | | |
| Example | +WRETRY:3 | | |
| | OK | | |
| Node types | Coordinator / router / end device | | |

6.5.10 "+WWAIT" - Data transmission waiting timeout

Table 6-44. "+WWAIT" - Data transmission waiting timeout.

| Syntax | Explanation | | | |
|-------------------------|---|--|--|--|
| +WWAIT= <value></value> | The value parameter sets the timeout (in milliseconds) for the module to wait for entering the D (see Table 6-36 on page 6-26) or the DU (see Table 6-38 on page 6-28) command. If a pause between two consecutive characters coming from the serial interface exceeds the specified timeout, the node will start data transmission even though the data length encountered has not yet reached the number specified by the length argument of the D/DU command. In this case, the length is replaced with its actual value according to the data transmitted. | | | |
| +WWAIT? | The command returns actual timeout value. | | | |
| +WWAIT=? | The command requests the range of valid timeouts. | | | |
| S-register | s53 (RW) | | | |
| Result codes | OK is returned if the value is in the range; otherwise, ERROR is returned. | | | |



Table 6-44. "+WWAIT" - Data transmission waiting timeout. (Continued)

| | AT+WWAIT=500 | | |
|---------------|-----------------------------------|--|--|
| Example | OK | | |
| | AT+WWAIT? | | |
| | +WWAIT:500 | | |
| | OK | | |
| | AT+WWAIT=? | | |
| | +WWAIT: (100-5000) | | |
| | OK | | |
| Default value | 5000 | | |
| Persistence | value is stored in the EEPROM | | |
| Node types | Coordinator / router / end device | | |



6.6 Power management

Because power consumption is a major concern in applications with battery-powered devices, SerialNet provides AT commands that allow switching between awake and sleep modes, as well as setting the transmit power level.

Note that sleep mode is supported on end device nodes designed on ZigBit modules only, and is not available for nodes using the RZUSBSTICK platform. To avoid issues in network stability, coordinator and router nodes are always kept in active mode, and, hence, require continuous power supply.

In addition to power management of ZigBit modules, SerialNet simplifies power management of external peripherals or the host device via the CTS line. If hardware flow control is enabled by the +IFC command (see Table 6-67 on page 6-45), the line becomes high when the ZigBit module is in the sleep state.

6.6.1 "+WPWR" - Configuration of sleep/active intervals

Table 6-45. "+WPWR" - Configuration of sleep/active intervals.

| Syntax | Explanation | | | |
|-------------------------|--|--|--|--|
| +WPWR= <sleep>,</sleep> | The command sets the duration of sleep and active intervals for end device nodes. | | | |
| <active></active> | The sleep duration is specified in 100ms units, but active duration isspecified in 10ms units. | | | |
| | Zero active period means that the node can be put asleep explicitly only by the +WSLEEP command (in which case it will stay asleep for the given sleep duration). | | | |
| | On a coordinator/router node, sleep interval is used for children tracking, and should be not less than on its children nodes. It is also used as the maximum time interval the data destined for the child can be buffered. See "Parent polling mechanism" on page 6-25 for more details. | | | |
| | Note: 1. Actual sleep/active periods will be slightly different, and their values depend on multiple circumstances, such as the network activity, external interfaces to the sensors, and so on. They cannot be used for absolute timing. | | | |
| | 2. The command is not accessible when the node is joined to a network. | | | |
| +WPWR? | The command requests current sleep/active intervals. | | | |
| +WPWR=? | The command requests valid ranges of sleep/active intervals. | | | |
| S-registers | s31, s32 (RW) | | | |
| Result codes | OK is returned if parameters are within their valid ranges. Otherwise, ERROR is returned. | | | |
| | AT+WPWR=600,10 | | | |
| | OK | Set duty cycle for one minute sleep / 100ms active | | |
| | AT+WPWR? | Verify setting is applied | | |
| | +WPWR:600,10 | verify setting is applied | | |
| | OK | | | |
| Example | ATS31? | Get sleep interval via S-register | | |
| | 600 | Got Gloop interval via a register | | |
| | OK | | | |
| | AT+WPWR=? | Get valid ranges for sleep/active intervals | | |
| | +WPWR: (2-30000), (0-30000) | Got valid ranges for disoprastive intervals | | |
| | OK | | | |
| Default values | 100,0 (the node sleeps for ten seconds if put asleep by the +WSLEEP command) | | | |
| Persistence | The sleep, active values are stored in the EEPROM | | | |
| Node types | Coordinator / router / end device | | | |



6.6.2 "+WSLEEP" - Force node to sleep

Table 6-46. "+WSLEEP" - Force node to sleep.

| Syntax | Explanation | | | |
|--------------|--|--|--|--|
| +WSLEEP | The command forces the node into the sleep mode. | | | |
| | The command is supported on ZigBit modules only, and is not available on the RZUSBSTICK platform. | | | |
| | Important: | | | |
| | The node in sleep mode can respond to the subsequent commands with a delay, depending on the sleeping interval specified (see Table 6-45 on page 6-32), the node version, and DTR configuration (see Table 6-68 on page 6-46). | | | |
| | The command is accessible only when the node is joined to a network. | | | |
| | OK is returned for end devices; otherwise, ERROR is returned. | | | |
| Result codes | Note: The command is executed as follows: the node returns the result code first, and then it disables any subsequent commands, completes pending operations, and finally goes into the sleep mode. Wake up occurs as scheduled by the +WPWR command or DTR interrupt, if enabled. | | | |
| Example | AT+WSLEEP | | | |
| Liample | OK | | | |
| Node types | End devices | | | |

6.6.3 "+WTXPWR" - TX power level

Table 6-47. "+WTXPWR" - TX power level.

| Syntax | Explanation | | |
|--------------------------|--|------------------|--|
| +WTXPWR= <value></value> | The command sets the transmit power level for the device. | | |
| | The value represents the TX power level, r | neasured in dBm. | |
| | Note: This setting will be applied to the radio circuitry during the warm reset procedure only. Thus, the accurate setting of TX power requires warm reboot of the node in using the z command (see Table 6-48 on page 6-34). | | |
| +WTXPWR? | The command requests the actual TX power level. | | |
| | Notes: 1. Power level resolution is hardware dependent, and may be coarser than 1dB, and so some power values (-4, -6, -8) may be forbidden despite being within the allowed range. On input, such values are rounded to the nearest allowed value. This command returns only the number set by the +WTXPWR= command, and does not indicate the real power level, which can vary due to temperature, supply voltage, and other factors. | | |
| +WTXPWR=? | The command requests the allowable range of TX power levels. | | |
| S-register | s34 (RW) | | |
| Result codes | OK is returned if value is in the valid range; otherwise, ERROR is returned. | | |
| Example | AT+WTXPWR=-5 OK AT+WTXPWR? +WTXPWR:-5 OK AT+WTXPWR=? +WTXPWR:(-17-3) set -5dBm TX power level | | |
| | OK 27 37 | | |



Table 6-47. "+WTXPWR" - TX power level. (Continued)

| Default value | Hardware dependent, typically 3 | | |
|---------------|-----------------------------------|--|--|
| Persistence | value is stored in the EEPROM | | |
| Node types | Coordinator / router / end device | | |

6.7 Generic control

6.7.1 "Z" - Warm reset

Table 6-48. "Z" - Warm reset.

| Syntax | Explanation | | |
|--------------|--|--|--|
| Z | The command instructs the device to execute a warm (software) reset. | | |
| | This command resets the hardware, restores all persistent variables from EEPROM, and restarts the firmware. | | |
| | The command is supported on ZigBit modules only, and is not available on the RZUSBSTICK platform. Important: | | |
| | The command should be used with caution since it does not send "leaving the network" signals to other nodes, and, hence, can affect PAN integrity. Therefore, it is better to put the node out of the network prior to reset using the +WLEAVE command. | | |
| | If automatic networking is disabled, then the node will not join the network automatically after reset. | | |
| | Note that the parameters stored in EEPROM persist after software reset; to erase them, use the AT&F command (see Table 6-55 on page 6-38). | | |
| | If z is put in a line together with some other commands, the processing of commands placed after z is disabled. | | |
| | The result code is sent after the reset process is completed. | | |
| | During the reset process, some transients may be observed on the module pins (including GPIO) because of the nature of the MCU used. It is strongly recommended to wait until the ox result code is received (or an equivalent numerical code) before sending any new command to the module. | | |
| Result codes | OK is returned if the command is supported by the device's platform. Otherwise, ERROR is returned. | | |
| F | ATZ | | |
| Example | OK | | |
| Node types | Coordinator / router / end device | | |

6.7.2 "&H" - Command Help

Table 6-49. "&H" - Command Help.

| Syntax | Explanation | | |
|--------------|--|--|--|
| H.3 | The command outputs a list of valid AT- commands. | | |
| | The listing order may change, depending on the firmware version. | | |
| Result codes | ок is always returned. | | |
| | AT&H | | |
| | E | | |
| | v | | |
| | Q | | |
| | z | | |
| | &F | | |
| | +IPR | | |
| | +IFC | | |
| | &D | | |
| | &H | | |
| Example | %Н | | |
| | I | | |
| | +GMI | | |
| | +GMM | | |
| | +GMR | | |
| | +GSN | | |
| | (skipped) | | |
| | S146 | | |
| | S147 | | |
| | S148 | | |
| | OK | | |
| Node types | Coordinator / router / end device | | |

6.7.3 "%H" - Display parameters and S-register values

Table 6-50. "%H" - Display parameters and S-register values.

| Syntax | Explanation | | | |
|--------------|---|--|--|--|
| %Н | The command outputs the values of parameters and S-registers. The listing order may change, depending on the firmware version. | | | |
| Result codes | ок is always returned. | | | |
| Example | The command outputs the values of parameters and S-registers. The listing order may change, depending on the firmware version. | | | |
| Node types | Coordinator / router / end device | | | |



6.7.4 "I" - Display product identification information

Table 6-51. "I" - Display product identification information.

| Syntax | Explanation | | | |
|---------------------|--|--|--|--|
| I[<value>]</value> | | The command instructs the node to return information text identifying the device. Information text depends on value, as follows: | | |
| | Value | Information text | Reference | |
| | 0 1 2 3 4 If value is omit | All the identifiers below Manufacturer identifier Model identifier Hardware/software revision identifier Product serial number identifier tted, 0 is implied by default. | Section 6.7.5 Section 6.7.6 Section 6.7.7 Section 6.2.7 | |
| Result codes | OK for any of the aforementioned values; ERROR otherwise. | | | |
| Example | ATIO ATMEL ZIGBIT BitCloud v.1.5.0; SerialNet v.2.2.0 000100001090C3F9 OK | | | |
| Node types | Coordinator / router / end device | | | |

6.7.5 "+GMI" - Get manufacturer identifier

Table 6-52. "+GMI" - Get manufacturer identifier.

| Syntax | Explanation | |
|--------------|---|-----------------------|
| +GMI? | The command instructs the node to output information text identifying the manufacturer. | |
| Result codes | οκ is always returned. | |
| Example | AT+GMI? +GMI:ATMEL OK ATI1 ATMEL | Just an alias to +GMI |
| Node types | OK Coordinator / router / end device | |

6.7.6 "+GMM" - Request for the model identifier

Table 6-53. "+GMM" - Request for the model identifier.

| Syntax | Explanation | |
|--------------|---|-----------------------|
| +GMM? I2 | The command instructs the node to transmit information text identifying the particular model of the device. | |
| Result codes | οκ is always returned. | |
| Example | AT+GMM? +GMM:ZIGBIT OK ATI2 ZIGBIT OK | Just an alias to +GMM |
| Node types | Coordinator / router / end device | |

6.7.7 "+GMR" - Request for the hardware/software revision identifier

Table 6-54. "+GMR" - Request for the hardware/software revision identifier.

| Syntax | Explanation | | |
|--------------|--|-----------------------|--|
| +GMR? | This command instructs the node to transmit an information text intended to identify the actual revision of hardware or software product burned into the device. | | |
| Result codes | ок is always returned. | | |
| Example | AT+GMR? +GMR: BitCloud v. 1.5.0; SerialNet v.2.2.0 OK ATI3 +GMR: BitCloud v. 1.2 5.0; SerialNet v.2.2.0 OK | Just an alias to +GMR | |
| Node types | Coordinator / router / end device | | |

6.7.8 "&F" - Set to factory default configuration

Table 6-55. "&F" – Set to factory default configuration.

| Syntax | Explanation |
|--------------|--|
| &F | The command instructs the module to set all the parameters (including the persistent variables from EEPROM) to the factory defaults. This command forces a hardware reset just like the ${\tt Z}$ command, and so all the same precautions should be considered. |
| | The result code will be issued according to the actual result code suppression setting (see Table 6-62 on page 6-42), response formatting (see Table 6-63 on page 6-43), and the transmission rate (see Table 6-66 on page 6-44) set before execution of this command. |
| | Note that the &F command does not reset the password once it has been set by the +WPASSWORD command (see Table 6-79 on page 6-54). |
| Result codes | ox is always returned. |
| Example | AT&F OK |
| Node types | Coordinator / router / end device |



6.7.9 "+WACALIBRATE" - Configure periodic internal clock calibration

Table 6-56. "+WACALIBRATE" - Configure periodic internal clock calibration.

| Syntax | Explanation |
|-----------------------|--|
| +WACALIBRATE=< value> | The command requests the device to automatically calibrate the internal clock. <code>value</code> is an unsigned integer between 0 and 65535 that determines the period of calibration, in minutes (that is, how many minutes will elapse between consecutive calibrations). The command is supported on ZigBit modules only, and is a no-op on the RZUSBSTICK platform. It can be used to prevent frequency drift of the MCU's internal RC oscillator, which can impact or even block serial communication with the host. |
| +WACALIBRATE? | The command returns the period of calibration (in minutes). |
| +WACALIBRATE=? | The command returns the permitted range of values for the period of calibration. |
| Result codes | ${\tt ox}$ is returned on successful command completion. Otherwise, ${\tt value}$ is ignored, and the device responds with ${\tt error}$. |
| Example | AT+WACALIBRATE=60 OK AT+WACALIBRATE? +WACALIBRATE:60 OK AT+WACALIBRATE=? +WACALIBRATE(0-65535) OK |
| Default value | 0 |
| Persistence | The value is stored in the EEPROM |
| Node types | Coordinator / router / end device |

6.7.10 "+WCALIBRATE" - Calibrate internal clock

Table 6-57. "+WCALIBRATE" - Calibrate internal clock.

| Syntax | Explanation |
|--------------|---|
| +WCALIBRATE | The command requests the device to calibrate the internal clock. The command is supported on ZigBit modules only, and is a no-op on the RZUSBSTICK platform. It can be used to prevent frequency drift of the MCU's internal RC oscillator, which can impact or even block serial communication with the host. |
| Result codes | OK is returned on successful calibration. Otherwise, the device responds with ERROR. |
| Example | AT+WCALIBRATE OK |
| Node types | Coordinator / router / end device |

6.8 **Host interface commands**

6.8.1 "S3" - Termination character

Table 6-58. "S3" - Termination character.

| Syntax | Explanation |
|---------------------|---|
| S3= <value></value> | The command sets the ASCII code to be used as the termination character in command line, response, and result code formatting. value may be specified in the range of 0127. |
| | Note: It is strongly recommended to avoid changing this parameter during network operation. |
| S3? | The command requests the actual ASCII code currently used as the termination character. |
| Result codes | The module returns ok if value is in range; otherwise, ERROR is returned. Important: The current value of S3 is used to terminate the command line when entering the S3 setting command to specify a new command line termination character. However, the result code will use the new value of S3-specified in the command line. For example, if S3 is currently set to 13 when the 'ATS3=30' command line is issued, the command line must be terminated with a <cr></cr> character, but the result code will use the character with a decimal value of 30. |
| Example | ATS3=13 OK ATS3? 13 OK |
| Node types | Coordinator / router / end device |
| Default value | 13 - <cr>> (carriage return character)</cr> |
| Persistence | value is stored in the EEPROM |

6.8.2 "S4" - Response formatting character

Table 6-59. "S4" - Response formatting character.

| Syntax | Explanation | |
|---------------------|---|--|
| S4= <value></value> | The command sets the ASCII code of the character used in response and result code formatting along with the s3 parameter (see Table 6-58 on page 6-40). The description of the v command shows the parameter usage (see Table 6-63 on page 6-43 for details). value may be specified in the range of 0127. Note: It is strongly recommended to avoid changing this parameter during network operation. | |
| S4? | The command requests the actual ASCII code currently used as the response formatting character. | |



Table 6-59. "S4" - Response formatting character. (Continued)

| | The module returns ok if value is in the allowed range, and ERROR otherwise. | | |
|---------------|--|--|--|
| Result codes | Note: The changed value of ${\tt S4}$ will be used to format the result code and information responses immediately after processing the ' ${\tt S4='}$ command. If the value of ${\tt S4}$ is changed in a command line, the result code issued in response to that command line will be formatted using the new value of ${\tt S4}$. | | |
| | ATS4=10 | | |
| | OK | | |
| Example | ATS4? | | |
| | 10 | | |
| | OK | | |
| Node types | Coordinator / router / end device | | |
| Default value | 10 – <lf> (Line Feed character)</lf> | | |
| Persistence | value is stored in the EEPROM | | |

6.8.3 "S5" - Command editing character

Table 6-60. "S5" - Command editing character.

| Syntax | Explanation | | |
|---------------------|--|--|--|
| S5= <value></value> | The command sets the ASCII code used as the control character to delete the immediately preceding character in the command line (see "Basic command-line operations" on page 6-1). value may be specified in the range of 0127. | | |
| | Note: It is strongly recommended not to set this parameter to any letter or other symbol that can be a part of a command. For example, setting it to letter A, either upper- or lowercase (ASCII code 65 or 97), would effectively prevent the entering of any subsequent AT- command. | | |
| S5? | The command requests the actual ASCII code of the command editing character. | | |
| | The module returns ok if value is in range; otherwise, error is returned. | | |
| Result codes | Note: The new value of S5 will be used when editing of subsequent command lines, and will be applied after processing the line containing the S5 register change. | | |
| | ATS5=8 | | |
| | OK | | |
| Example | ATS5? | | |
| | 8 OK | | |
| Node types | Coordinator / router / end device | | |
| 31 | | | |
| Default value | 8 – <bs> (backspace character)</bs> | | |
| Persistence | value is stored in the EEPROM | | |

6.8.4 "E" - Command echo

Table 6-61. "E" - Command echo.

| Syntax | Explanation | |
|---------------------|--|--------------|
| E[<value>]</value> | This parameter instructs the module to echo characters received by the UART. value may be specified as 0 or 1 to disable or enable echoing, correspondingly. If value is omitted, 0 is implied by default. | |
| Result codes | The module returns ok if value is 0 or 1; otherwise. ERROR is returned. | |
| Example | ATE OK ATE1 | Disable echo |
| | OK | Enable echo |
| Node types | Coordinator / router / end device | |
| Default value | 1 – echoing is enabled | |
| Persistence | value is stored in the EEPROM | |

6.8.5 "Q" - Result code suppression

Table 6-62. "Q" - Result code suppression.

| Syntax | Explanation | Explanation | |
|---------------------|---|--|--|
| Q[<value>]</value> | This parameter instructs the module to transmit result codes to the UART. When result codes are being suppressed, no portion of any intermediate, final, or unsolicited result code – header, result text, line terminator, or trailer (see "Result codes" on page 5-4) – is transmitted. Information text transmitted in response to a command is not affected by the setting of this parameter. There are two possibilities for value: 0 – The module transmits result codes 1 – Result codes are suppressed and not transmitted If value is omitted, 0 is implied. | | |
| Result codes | | Nothing will be received for the ATQ1 command. OK if value is 0; otherwise, the module returns ERROR. | |
| Example | ATQ0 OK | Enable result codes | |
| | ATQ1 | Suppress result codes. No ox will be sent because it is suppressed | |
| Node types | Coordinator / router / end device | | |
| Default value | 0 – enables result codes | | |
| Persistence | value is stored in the EEPROM | | |



6.8.6 "V" - Response format

Table 6-63. "V" - Response format.

| Syntax | | Explanation | |
|---------------------|--|---|--|
| V[<value>]</value> | This parameter defines the contents of the header and trailer transmitted with result codes and information responses. It also determines whether result codes are transmitted in numeric, alphabetic, or "verbose" form. The text portion of information responses is not affected by this setting. | | |
| | A result code shows the e text and result codes. | ffect of the setting of this parameter on the format of information | |
| | If value is omitted, 0 is in | mplied. | |
| 0 If value is | | If value is 0 (because numeric response text is being used). | |
| | OK | If value is 1. | |
| Result codes | 4 | For unsupported values (if previous value was 0). | |
| | ERROR | For unsupported values (if previous value was 1). | |
| | ATV1 | | |
| | OK | | |
| Example | ATV0 | | |
| | 0 | 0 will be output on the same line because $<\!\!\mathrm{LF}\!\!>$ is not used for formatting of the result code | |
| Node types | Coordinator / router / end device | | |
| Default value | 1 – verbose format | | |
| Persistence | value is stored in the EEPROM | | |

Table 6-59 on page 6-40, below, summarizes the usage of response formats. All references to <CR> mean the character ASCII coded specified in parameter S3 (see Table 6-58 on page 6-40); likewise, all references to <LF> mean the character ASCII coded specified in parameter S4 (see Table 6-59 on page 6-40). Numeric and verbose codes are discussed in "Parameter persistence" on page 5-4.

Table 6-64. Response formatting.

| Value | 0 | 1 |
|-----------------------|--------------------------------------|---|
| Information responses | <text><cr><lf></lf></cr></text> | <cr><lf><text><cr><lf></lf></cr></text></lf></cr> |
| Result codes | <numeric code=""><cr></cr></numeric> | <cr><lf><verbose code=""><cr><lf></lf></cr></verbose></lf></cr> |



6.8.7 "X" - Result code selection

Table 6-65. "X" - Result code selection.

| Syntax | Explanation | | |
|---------------------|--|--|--|
| X[<value>]</value> | This parameter defines whether the module transmits particular result codes (see "Result codes" on page 5-4) to the host or not. | | |
| | value | | Description |
| | 0 | | All result codes are sent to the host |
| | 1 | | EVENT result codes are not sent |
| | 2 | | EVENT and DATA result codes are not sent |
| | If value is omitted, 0 is implied. | | |
| Result codes | OK if value is from valid range. Otherwise, ERROR is returned. | | |
| Example | ATX2 OK Disable events and data indications | | |
| Node types | Coordinator / router / end device | | |
| Default value | 1 – all result codes will be sent, excluding EVENT | | |
| Persistence | value is stored in the EEPROM | | |

6.8.8 "+IPR" - Serial port communication rate

Table 6-66. "+IPR" - Serial port communication rate.

| Syntax | Explanation | | |
|-----------------------|---|--|--|
| +IPR= <value></value> | The command specifies the data rate at which the DCE will accept commands and respond. At minimum, 1200b/s and 9600b/s are supported, but specific hardware may support an extended set of rates. | | |
| | Note: The rate specified takes effect following the issuance of any result code associated with the current command line, even if subsequent commands in a command line return ERROR . | | |
| +IPR? | The command requests the actual communication rate. | | |
| +IPR=? | The command requests the list of supported rates. This depends on the hardware capabilities of the particular model. | | |
| Result codes | The module returns ox if the requested rate is present in the supported list; otherwise, it returns error . | | |
| | AT+IPR=38400 | | |
| | OK | | |
| | AT+IPR? | | |
| Example | +IPR:38400 | | |
| | OK | | |
| | AT+IPR=? | | |
| | +IPR: (1200,9600,38400) | | |
| | OK | | |



Table 6-66. "+IPR" - Serial port communication rate. (Continued)

| Node types | Coordinator / router / end device | |
|---------------|-----------------------------------|--|
| Default value | 38400 | |
| Persistence | value is stored in the EEPROM | |

6.8.9 "+IFC" - Serial port flow control

Table 6-67. "+IFC" - Serial port flow control.

| Syntax | Explanation | |
|--|--|--|
| +IFC= <rx_flow> , <tx_flow< td=""><td colspan="2">The command is used to specify the methods for local flow control over the UART interface between the host and the module. It accepts two numeric sub-parameters: rx_flow, which specifies the method for the host to control the flow of data received from the module tx_flow, which specifies the method for the module to control the flow of data transmitted from the host</td></tx_flow<></rx_flow> | The command is used to specify the methods for local flow control over the UART interface between the host and the module. It accepts two numeric sub-parameters: rx_flow, which specifies the method for the host to control the flow of data received from the module tx_flow, which specifies the method for the module to control the flow of data transmitted from the host | |
| | rx_flow Description | |
| | None use RTS (request to send) line | |
| | tx_flow Description | |
| | None use CTS (clear to send) line | |
| | Note: It is strongly recommended to use the CTS method because there would be r means to use power-down modes if no flow control method is selected as the module is not accepting any data from the UART. | |
| +IFC? | The command requests the actual flow control settings. | |
| +IFC=? | The command requests a list of the flow control settings supported. | |
| Result codes | οκ is returned if the specified flow control combinations are supported; otherwise, it returns ERROR . | |
| Example | AT+IFC=2,2 OK AT+IFC? +IFC:2,2 OK AT+IFC=? +IFC:(0,2),(0,2) OK | |
| Node types | Coordinator / router / end device | |
| Default value | Depends on the hardware version. For MeshBean2 boards, it is 0, 0 | |
| Persistence | value is stored in the EEPROM | |

6.8.10 "&D" - DTR behavior

Table 6-68. "&D" - DTR behavior.

| Syntax | Explanation | |
|--------------------|--|---|
| &D <value></value> | The command specifies how the module manages the DTR line. | |
| | value | Description |
| | 0 | The module ignores the DTR line |
| | 1 | The module wakes up if it is sleeping and with a short delay can start processing data coming from the UART |
| S-register | S50 (RW) | |
| Result codes | OK is returned if the requested mode is supported; otherwise, ERROR is returned. | |
| Example | AT&D1 OK | |
| Node types | Coordinator / router / end device | |
| Default value | 0 | |
| Persistence | value is stored in the EEPROM | |

6.8.11 "S0" - Request for the latest result code

Table 6-69. "S0" - Request for the latest result code.

| Syntax | Explanation | Explanation | |
|--------|-------------|--|--|
| S0? | • | result code from the most recently executed command. If that command with an ERROR result code, register S0 will contain a nonzero value. | |
| | 0 | No error | |
| | 1 | Syntax error | |
| | 2 | Improper number of parameters | |
| | 3 | Parameter value(s) is out of range (example: | |
| | 4 | AT+IFC=12,34) | |
| | 5 | Unspecified error | |
| | | Requested value cannot be read (example: +WLQI command for nonexistent link) | |
| | 6 | Operation is not permitted in current state (example: setting PAN ID in the connected state or +WSLEEP for router) | |
| | 7 | Operation cannot be completed due to networking problems (example: connection loss) | |
| | 8 | Data transmission error | |



Table 6-69. "S0" - Request for the latest result code. (Continued)

| Result codes | Always ox | |
|--------------|-----------------------------------|--|
| | AT+WROLE=0+WPWR=30 ,30 | |
| | ERROR | |
| | ATSO? | |
| | 6 | Setting +WPWR is not permitted for a coordinator |
| | OK | |
| | AT+ABCD | |
| Example | ERROR | Syntax error |
| Example | ATSO? | |
| | 1 | |
| | OK | |
| | AT+IFC=12,34 | |
| | ERROR | Parameter is out of range |
| | ATSO? | |
| | 3 | |
| | OK | |
| Node types | Coordinator / router / end device | |

6.9 Hardware control

AT commands described in this section are supported for ZigBit modules only, and provide control over hardware functionality, such as GPIO, A/D conversion, and PWM.

6.9.1 GPIO configuration

Table 6-70. GPIO configuration.

| Syntax | Explanation | |
|-------------------------------|---|--|
| S <reg>=<value></value></reg> | Command selects the configuration of particular GPIO pins. reg corresponds to the GPIO pins, GPIO0GPIO8, on the module, and it is in the range of 120128. | |
| | value | Description |
| | 0 3 2 1 | Input pin, no internal pull-up Output Tri-state Input pin, internal pull-up is turned on |
| | Note: Use of internal pull-up improves noise immunity, but also results in increased power consumption. On the MeshBean2 board, tri-stated pins are configured as input with no pull-up. | |
| S <reg>?</reg> | The command requests the actual GPIO pin configuration. | |
| Result codes | OK is returned if value is in the valid range; otherwise, ERROR is returned. | |
| Example | ATS120=1 S121=3 Set GPIO0 as input with internal pull-up and GPIO1 as output | |
| Default value | 2, tri-state | |
| Persistence | Values are stored in the EEPROM | |
| Node types | Coordinator / router / end device | |



6.9.2 GPIO

Table 6-71. GPIO.

| Syntax | Explanation | |
|-------------------------------|---|---|
| S <reg>=<value></value></reg> | The command assigns value to a particular GPIO pin. Each pin, GPIO0GPIO8, of the module is numbered by reg, which is in the range of 130138, correspondingly. | |
| | <value></value> | Description |
| | 0 1 | Logical 0 Logical 1 |
| | Note: This command do | pes not affect any pin configured as input or tri-state. |
| S <reg>?</reg> | The command reads a particular GPIO pin, numbered and coded as above, and returns 0 or 1. If the pin is configured for output or as tri-state, the returned value is not defined. | |
| Result codes | OK is returned if value is 0 or 1; otherwise, ERROR is returned. | |
| Example | ATS120=1 S121=3 ATS130? 1 OK | Set GPIO0 as input and GPIO1 as output, both with internal pull-up GPIO0 is 1 |
| | ATS131=0 OK | Clear GPIO1 |
| Default value | 0 | |
| Persistence | Values are NOT stored in the EEPROM because GPIO pins are configured as tri-state at startup | |
| Node types | Coordinator / router / end device | |



A/D configuration 6.9.3

Table 6-72. A/D configuration.

| Syntax | Explanation | Explanation | |
|-----------------------|--|--|--|
| S100= <value></value> | a bit field. The four least-significant b channels. Bits b4 b7 are ignored in If a bit is cleared, then A/D conversion high-impedance state without international Notes: 1. Enabling A/D conversion 2. Conversion is executed clock rate and external mately 5kb/s. 3. Proper conversion result applied to the A_VREF p to tri-state. 4. Pins AD4AD7 can be these inputs is disabled. 5. When using the ZigBit in imposed due to the boat you must configure GPIC. | n of a corresponding channel is disabled and the A/D pin goes to the I pull-up. I increases power consumption. In single conversion mode (see the ATmega datasheet with 125kHz reference), thus enabling the maximum conversion rate of approxits are achieved for ZigBit if the external reference signal of 1.25V is in. If conversion is disabled on all A/D pins, the A_VREF pin is moved also used as a JTAG port, and then A/D conversion functionality for module installed on the MeshBean2 board, the following restriction is red schematics. Before configuring or reading the particular A/D pins, 26, GPIO7, and GPIO8 for output, and then set GPIO6 to 0 while set to 1. For example, you must send the following commands: 28=3 38=1 | |
| S100? | The command requests the actual A/ | The command requests the actual A/D configuration. | |
| Result codes | οκ is always returned. | | |
| Example | ATS100=08 OK | Enable conversion on pin AD3 | |
| Default value | 00 - disable A/D conversion for all four A/D pins | | |
| Persistence | value is stored in the EEPROM | | |
| Node types | Coordinator / router / end device | | |

6.9.4 A/D

Table 6-73. A/D.

| Syntax | Explanation | Explanation | |
|----------------|---|--|--|
| S <reg>?</reg> | The command reads a particular A/D pin and returns its value in decimal format. reg corresponds to pins ADOAD3 on the module, and it is in the range of 101104. If A/D conversion for a particular channel is disabled by the S100 register, no value is returned. Note: When using the ZigBit module installed on the MeshBean2 board, the following restriction is imposed due to the board schematics. Configure GPIO6, GPIO7, and GPIO8 for output. Set GPIO6 to 0 while setting GPIO7 and GPIO8 to 1. Then you can configure or read the particular A/D pins. For example, you must send the following commands: ATS126=3 S127=3 S128=3 ATS136=0 S137=1 S138=1 before performing these commands: ATS100=0F ATS101? S102? S103? S104? | | |
| Result codes | οκ is always returned. | οκ is always returned. | |
| Example | ATS100=08 OK ATS104? 125 OK | Enable conversion on pin AD3 Read AD3 pin | |
| Node types | Coordinator / router / end device | | |



6.9.5 PWM configuration

Table 6-74. PWM configuration.

| Syntax | Explanation | | | |
|-------------------------------|--|---|--|--|
| | The command configures a particular PWM channel: | | | |
| | PWM channel | Output pin | reg | |
| S <reg>=<value></value></reg> | 0 | GPIO0 | 140 | |
| | 1 | GPIO1 | 141 | |
| | 2 | GPIO2 | 142 | |
| | <value></value> | Description | | |
| | 0, 2 | Disable PWM channel | | |
| | 1 | | non-inverted output polarity (output is low and high when duty cycle = 100%) | |
| | 3 | Enable channel, setting inverted output polarity (output is high when duty cycle = 0% and low when duty cycle = 100%) tes: 1. When a PWM channel is enabled, the corresponding output pin is configured as output to be controlled by that PWM channel. Duty cycle for the channel is set to 0. PWM channel frequency is set to the default value (5kHz) if no channel has yet been opened. Otherwise, the frequency last set for any other channel is used. 2. When a PWM channel is disabled by setting reg to 0 or 2, the corresponding output pin is configured as tri-state and is fully controlled as GPIO. 3. On the MeshBean2 board, the GPIO0GPIO2 pins are connected to LEDs. | | |
| | channe (5kHz) set for 2. When ing out | | | |
| Result codes | OK is returned if the value is in the valid range; otherwise, ERROR is returned. | | | |
| S <reg>?</reg> | The command requests the current PWM configuration. | | | |
| Result codes | ок is always returned. | | | |
| Example | ATS140=1 S142=3 OK | Enable PWM channel 0, setting noninverted polarity output, and enable PWM channel 2, setting inverted polarity output | | |
| Default value | 0, disabled | | | |
| Persistence | value is NOT stored in the EEPROM | | | |
| Node types | Coordinator / router / end device | | | |

6.9.6 PWM frequency control

Table 6-75. PWM frequency control.

| Syntax | Explanation | | |
|-------------------------------|---|---|------------------|
| S <reg>=<value></value></reg> | The command selects the PWM operating frequency for a particular PWM channel | | |
| | PWM channel | Output pin | Frequency reg |
| | 0 | GPIO0 | 143 |
| | 1 | GPIO1 | 144 |
| | 2. | GPIO2 | 145 |
| | <value></value> | PWM frequency | |
| | 0 | 5kl | Hz |
| | 1 | 10k | Hz |
| | 2 | 20k | ·· ·= |
| | 3 | 50k | |
| | 4 100kHz | | |
| Result codes | all channels). Changing frequency for any PWM channel results in the reset of the duty cycle to 0 for a channels. OK is returned if value is in the valid range; otherwise, ERROR is returned. | | |
| S <reg>?</reg> | The command reads the PWM operating frequency for a particular PWM channel, coded as above, and returns 0 to 4. | | |
| Result codes | ox is always returned. | | |
| Example | ATS143=2 OK ATS144=4 OK ATS143? 4 OK | Set the PWM frequency to 20kHz for PWM channel 0. Set the PWM frequency to 100kHz for PWM channel 1. Request the PWM frequency on channel 0. The most recent frequency set is returned. | |
| Default value | 0 (meaning 5kHz) | | |
| Persistence | value is NOT stored in the EEPROM | | |
| Node types | Coordinator / router / end device | | |

6.9.7 PWM duty cycle control

Table 6-76. PWM duty cycle control.

| Syntax | Explanation | | |
|-------------------------------|---|-------|----------------|
| | The command selects the duty cycle value for a particular PWM channel | | |
| S <reg>=<value></value></reg> | PWM channel Output pin Duty cycle | | Duty cycle reg |
| | 0 | GPIO0 | 146 |
| | 1 | GPIO1 | 147 |
| | 2 | GPIO2 | 148 |



Table 6-76. PWM duty cycle control. (Continued)

| | in percent. Notes: 1. The duty cycle the current peri | Notes: 1. The duty cycle currently set on the output pin will be changed as soon as the current period of PWM frequency is ended. 2. Resolution of the duty cycle setting depends on the PWM frequency, as | |
|----------------|--|--|--|
| | PWM frequency | | |
| | 5kHz | 1% | |
| | 10kHz | 1% | |
| | 20kHz | 1% | |
| | 50kHz | 2.5% | |
| | 100kHz | 5% | |
| Result codes | ок is returned if value is in | OK is returned if value is in the valid range; otherwise, ERROR is returned. | |
| S <reg>?</reg> | The command reads the du | The command reads the duty cycle for a particular PWM channel, in percent. | |
| Result codes | ок is always returned. | οκ is always returned. | |
| Evample | ATS146=45 | Cat duty avala to 45% for DMM abannal 0 | |
| Example | ОК | Set duty cycle to 45% for PWM channel 0 | |
| Default value | 0 (%) | 0 (%) | |
| Persistence | value is NOT stored in the | value is NOT stored in the EEPROM | |
| Node types | Coordinator / router / end de | Coordinator / router / end device | |

6.9.8 Reading and writing registers

Table 6-77. Writing to hardware registers.

| Syntax | Explanation | |
|--|---|--|
| POKE <type>, <addr>, <value></value></addr></type> | Command writes <value> at the address specified by <addr> in registers. <type> specifies the type of registers. For more information about registers available for a certain platform, and ranges of addresses and values, refer to the hardware datasheets.</type></addr></value> | |
| | <type></type> | Description |
| | 0 1 3 | Radio transceiver registers MCU internal RAM MCU internal EEPROM |
| | Note: By using this command, it is not possible to write to MCU internal flash memory. | |
| Result codes | OK is returned if the address is within the allowed range. ERROR is returned if type or address is out of range. | |
| Example | Write value 0x06 (RX_ON command) to the TRX_STATE register (of Atmel AT86RF231 transceiver): ATPOKE 0, 002, 00000006 OK | |
| Node types | Coordinator / router / end device | |



Table 6-78. Reading from hardware registers.

| Syntax | Explanation | | |
|---------------------------------------|--|-----------------------------|--|
| PEEK <type>, <addr></addr></type> | Command reads the value from registers at the address specified by <addr>. <type> specifies the type of registers.</type></addr> | | |
| | For more information about registers available for a certain platform, and ranges of addresses and values, refer to the hardware datasheets. | | |
| | <type></type> | Description | |
| | 0 | Radio transceiver registers | |
| | 1 | MCU internal RAM | |
| | 2 | MCU internal flash | |
| | 3 | MCU internal EEPROM | |
| Result codes | OK is returned if the address is within the allowed range. ERROR is returned if type or address is out of range of available addresses. | | |
| | Write and read GPIOR1 (address 0x004A) register of the Atmel ATmega1281 MCU: ATPOKE 1, 004A, 000000AA | | |
| | | | |
| Evennle | OK | | |
| Example | ATPEEK 1, 004A | | |
| | 000000AA | | |
| | OK | | |
| Node types | Coordinator / router / end device | | |

6.10 Remote management

Remote management functions include the password-protected AT commands that come from the originating node to a target node. The received AT command sequences are executed on the destination node as if they came from a serial port. Information response and result codes of the command execution are sent back to the originating node in the same form as if they were returned over a serial interface.

Remote execution service is protected by a 32-bit password that can be set during node installation or manufacturing.

Remote management function is an important tool that allows the organization of commissioning procedures on a PC using commercial, off-the-shelf terminal software.

6.10.1 "+WPASSWORD" - Set a password

Table 6-79. "+WPASSWORD" - Set a password.

| Syntax | Explanation | |
|------------------------|---|--|
| +WPASSWORD <psw></psw> | The command sets a new password for the remote management command. The password is in form of a 32-bit hexadecimal number. Note: This command is not to be confused with the parameter set commands. Unlike those, it does not include the "=" symbol. | |
| Result codes | ox is always returned. | |
| Example | AT+WPASSWORD 65432178 OK | |



Table 6-79. "+WPASSWORD" - Set a password. (Continued)

| Default value | 0 |
|---------------|--|
| Persistence | The psw value is stored in the EEPROM. Note: The password cannot be reloaded with a default value through the &F command (see Table 6-55 on page 6-38), but it can be rewritten over the air using the remote execution AT command (see Table 6-80 on page 6-55). |
| Node types | Coordinator / router / end device |

6.10.2 "R" - Remote execution of AT command

Table 6-80. "R" - Remote execution of AT command.

| Syntax | Explanation | | |
|--|--|--------------------------------|--|
| R <addr>,<psw>, <cmd></cmd></psw></addr> | The command enables the execution of AT commands on a remote node, with output redirected. Password (psw) is a 32-bit hexadecimal number, which is set for this specific node. | | |
| | addr specifies the short (network) address of the destination node. | | |
| | cmd is a sequence of AT commands without the AT prefix. | | |
| | Note: It is strongly recommended not to use the &H and %H commands for cmd, as they produce extremely lengthy output. | | |
| Result codes | All the responses and result codes are received from the remote node in text form that can be processed normally. If a connection loss is detected, the ERROR result code will be returned after a timeout from when the last response packet was received (approx. three seconds). In particular, remote execution of the +WLEAVE command will result in an ERROR code, despite being executed successfully. If the remote execution command is sent to an end device with a sleeping period longer than the timeout, ERROR will be returned. If the controlled node is not in the PAN, ERROR will be returned. Remote execution is not allowed for commands that cause the receiving node to send data over the network: D, DU, DS, +WPING, R. Attempting this will result in an ERROR code, with the command processing aborted. | | |
| | ATR1,65432178,+GMM?+WRSSI 2 | Get model number and | |
| | +GMM:ZIGBIT | RSSI | |
| Example | +WRSSI:-80 | | |
| Lxample | OK | Remove node from | |
| | ATR1,65432178,+WLEAVE | network – ERROR will be | |
| | ERROR | returned, but delayed | |
| Node types | Coordinator / router / end device | | |



User guide revision history

7.1 Rev. 8369B - 05/12

B. Section 6.9.8, and "POKE" and "PEEK" in Table 5-1 is added.

7.2 Rev. 8369A - 08/11

Please note that the referring page numbers in this section are referred to this document. The referring revision in this section is referring to the document revision.

A. Initial version





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