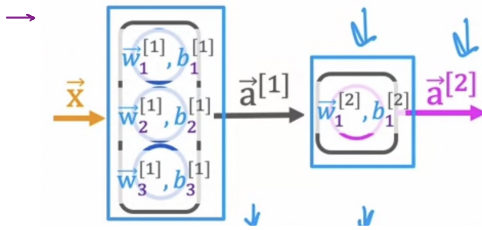


Issue :-

Understanding the logic behind what's happening during Forward prop. instead of just memorizing Tensorflow code.

Relevant point :-

- Hard code for each layer and its hidden neurons.



```
x = np.array([200, 17])  
w1_1 = np.array([1, 2])  
b1_1 = np.array([-1])  
z1_1 = np.dot(w1_1, x) + b1_1  
a1_1 = sigmoid(z1_1)
```

```
w1_2 = np.array([-3, 4])  
b1_2 = np.array([1])  
z1_2 = np.dot(w1_2, x) + b1_2  
a1_2 = sigmoid(z1_2)
```

```
w1_3 = np.array([5, -6])  
b1_3 = np.array([2])  
z1_3 = np.dot(w1_3, x) + b1_3  
a1_3 = sigmoid(z1_3)
```

layer 1

```
w2_1 = np.array([-7, 8, 9])  
b2_1 = np.array([3])  
z2_1 = np.dot(w2_1, x) + b2_1  
a2_1 = sigmoid(z2_1)
```

layer 2

• Create a Function —

→ we'll stack \vec{w} and create a matrix.

$$\vec{w}_1^{[1]} = \begin{bmatrix} 1 \\ 2 \end{bmatrix} \quad \vec{w}_2^{[1]} = \begin{bmatrix} -3 \\ 4 \end{bmatrix} \quad \vec{w}_3^{[1]} = \begin{bmatrix} 5 \\ -6 \end{bmatrix}$$

$W = \text{np.array}(\begin{bmatrix} 1, -3, 5 \\ 2, 4, -6 \end{bmatrix})$ 2 by 3

similarly,

$$b_1^{[1]} = -1 \quad b_2^{[1]} = 1 \quad b_3^{[1]} = 2$$

$b = \text{np.array}([-1, 1, 2])$

Function :-

$\text{def dense}(a_in, W, b):$

$\text{units} = W.\text{shape}[1]$

$a_out = \text{np.zeros}(\text{units})$

$\text{for } j \text{ in range}(\text{units}):$ → range(3) = 0, 1, 2 times loop

$w = W[:, j]$

$z = \text{np.dot}(w, a_in) + b[j]$

$a_out[j] = g(z)$

$\text{return } a_out$

$\vec{w}_1^{[1]} = \begin{bmatrix} 1 \\ 2 \end{bmatrix} \quad \vec{w}_2^{[1]} = \begin{bmatrix} -3 \\ 4 \end{bmatrix} \quad \vec{w}_3^{[1]} = \begin{bmatrix} 5 \\ -6 \end{bmatrix}$
 $W = \text{np.array}(\begin{bmatrix} 1, -3, 5 \\ 2, 4, -6 \end{bmatrix})$ 2 by 3

shape = (2, 3) ⇒ shape[1] = 3 ⇒ 3 neurons
row column

final output is initialized to (0, 0, 0) [np.zeros(3)]

If $j == 0$:

$$w = W[:, 0] \Rightarrow w = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$z = \text{np.dot}(w, a_in) + b[0]$$

$$a_out[j] = g(z) \text{ [sigmoid]}$$

The above loop goes on for 1 and 2 also.
Create another function for sequential.

```
def sequential(x):  
    a1 = dense(x, W1, b1)  
    a2 = dense(a1, W2, b2)  
    a3 = dense(a2, W3, b3)  
    a4 = dense(a3, W4, b4)  
    f_x = a4  
    return f_x
```

'W' refers to matrix
'w' refers to vectors, scalars

```
def dense(a_in, W, b):  
    units = W.shape[1]  
    a_out = np.zeros(units)  
    for j in range(units):  
        w = W[:, j]  
        z = np.dot(w, a_in) + b[j]  
        a_out[j] = g(z)  
    return a_out
```

```
def sequential(x):  
    a1 = dense(x, W1, b1)  
    a2 = dense(a1, W2, b2)  
    a3 = dense(a2, W3, b3)  
    a4 = dense(a3, W4, b4)  
    f_x = a4  
    return f_x
```