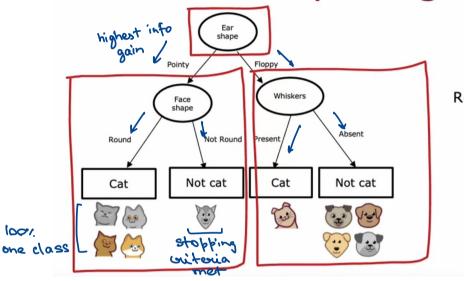
This is a basic layout of how a decision tree is veated :-

- · Stoot with all the training examples at the root node.
- · Calc. information gain to check which feature gives you the highest information gain and then choose it.
- · Split the tree left and right branches with the no. of training examples at each branch depending on the feature chosen.
- · Keep repeating until a stopping criteria is met:

  - → A node is 100% one class (i.e. entropy is 0)

    → Tree has reached the maximum depth which was
    - Information gain from additional splits is less than threshold.
      - -> No. of examples in a node is less than threshold.

## Recursive splitting



It is basically a necursion algorithm (calls itself). There are open-source libraries that make it easier to choose a moximum depth parameter

You could use a cr set for choosing a maximum depth parameter because it is kinda like having a higher degree polynomial, but open source libraries are better.