Numerical Algorithms for HPC

Parallel Fourier Transforms



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Overview

- Parallel FFT in 1 Dimension shared memory
- Parallel Fourier Transformations of 2D arrays
- Intro to FFTs of 3D arrays



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Fourier Transformation

- FFTs are often "the" critical bottleneck
 - preventing parallel application from scaling to larger numbers of processors due to communications
- This lecture discusses reasons and how we might parallelise an FFT to overcome this



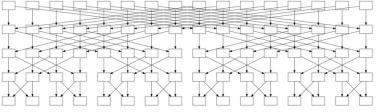
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Parallel 1D FFT

- · Parallelisation of a 1D FFT is hard
 - Combining of data requires a lot of inter-processor communication



- Typically N≈100-200 in many scientific codes e.g. materials chemistry small amount of data
- Algorithm is hard to decompose
- Literature examples:

Franchetti, Voronenko, Püschel, "FFT Program Generation for Shared Memory: SMP and Multicore", Paper presented at SC06, Tampa, FL http://sc06.supercomputing.org/schedule/pdf/pap169.pdf

Tang et al, "A Framework for Low-Communication 1-D FFT", SC12, https://software.intel.com/sites/default/files/bd/8b/fft-1d-framework.pdf



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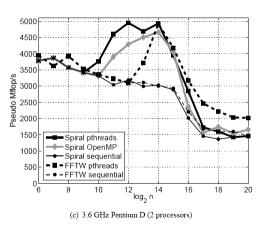


"Traditional" SMP 4 processor Intel Xeon - Communication via shared Memory (Bus) 2500 Wloop 2000 2000 1500 Benefits from: - N=2048 (Spiral) Spiral pthreads Spiral OpenMP 1000 - N=16384 (FFTW) Spiral sequential ■■FFTW pthreads FFTW sequentia 12 log₂ n Improvement for large problems (Factor about 2 (d) 2.8 GHz Xeon MP (4 processors) for 4 CPU)

Multicore Processor Intel Core Duo (laptop) - Shared L2 used for 3500 communication 3000 Seudo Mflop/s 2000 1500 · Benefits from - N=512 (Spiral) - N=4096 (FFTW) Spiral pthreads 1000 Spiral OpenMP
Spiral sequential Not as efficient for huge ■■ FFTW pthreads
■ FFTW sequential problems (a) 2.0 GHz Core Duo (2 processors) 6

Multicore processor with shared bus

- · Intel Pentium D
 - Multicore chip
 - Communication via Bus
- Benefits from:
 - N=2048 (Spiral)
 - N=8192 (FFTW)
- Little benefit for huge problems (shared bus)





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Summary: 1D parallel FFT

- Parallelisation works for large problems only ⊗
- Sensitive to contention (shared buses) ⊗
- Multicore chips with communications at cache level appear beneficial – might "be there" in a few years time
- ∘ Shows speedup, but not always "perfect" ⊜
- Presently: 1D FFT is an "expensive sum" of an array which is hard to parallelise





FFTs in two dimensions

· What needs calculating for a 2D FFT:

$$\tilde{f}(k,l) = \sum_{y=1}^{M} \left\{ \sum_{x=1}^{N} \left[f(x,y) \exp\left(-2\pi i \frac{kx}{N}\right) \right] \exp\left(-2\pi i \frac{ly}{M}\right) \right\}$$

• Do it in a 2 step approach:

$$\hat{f}(k,y) \equiv \sum_{x=1}^{N} \left[f(x,y) \exp\left(-2\pi i \frac{kx}{N}\right) \right]$$

$$\tilde{f}(k,l) = \sum_{y=1}^{M} \left\{ \hat{f}(k,y) \exp\left(-2\pi i \frac{ly}{M}\right) \right\}$$



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Distribute array onto 1D processor grid

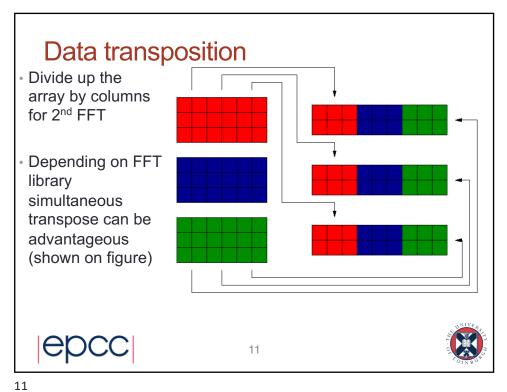
- Example:
 - 6 × 9 array
 - 3 processors
 - Assuming row major order (C convention)
- Perform 1st FFT:
 - Each processor transforms 3 arrays of 6 elements





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Perform 2nd FFT

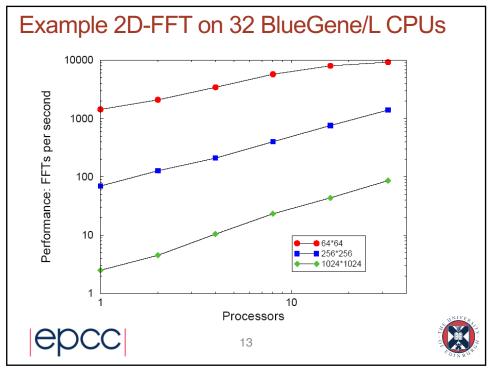
· What used to be the columns of the original array are now in row-major order ©

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- Do the 2nd FFT
 - In the example:
 - Each processor performs 2 FFTs of an array of length 9
- Rearrange data as required by following code
 - Examples:
 - Undoing the transpose
 - · Redistributing data onto 2D grid
 - Sometimes: nothing needs to be done ©







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Fourier Transformation of a 3D array

- Definition of the Fourier Transformation of a three dimensional array $A_{x,y,z}$

$$\tilde{A}_{u,v,w} := \sum_{x=0}^{L-1} \sum_{y=0}^{M-1} \sum_{z=0}^{N-1} A_{x,y,z} \exp(-2\pi i \frac{wz}{N}) \exp(-2\pi i \frac{vy}{M}) \exp(-2\pi i \frac{ux}{L})$$

$$\underbrace{\sum_{x=0}^{L-1} \sum_{y=0}^{M-1} \sum_{z=0}^{N-1} A_{x,y,z} \exp(-2\pi i \frac{wz}{N})}_{\text{1st 1D FT along } z} \exp(-2\pi i \frac{vy}{M}) \exp(-2\pi i \frac{ux}{L})$$

$$\underbrace{\sum_{x=0}^{L-1} \sum_{y=0}^{M-1} \sum_{z=0}^{N-1} A_{x,y,z} \exp(-2\pi i \frac{wz}{N})}_{\text{1st 1D FT along } z} \exp(-2\pi i \frac{vy}{M}) \exp(-2\pi i \frac{vz}{N})$$

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Can be performed as three subsequent 1 dimensional Fourier

Transformations



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FFT: Decomposition

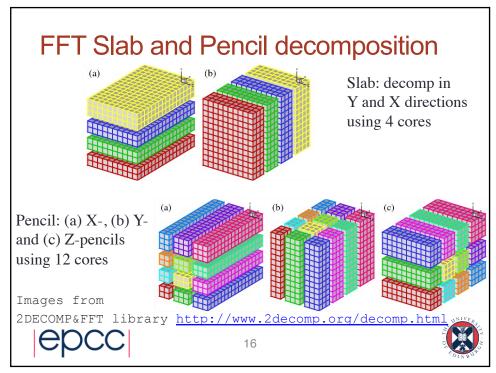
- For a d-dimensional problem we decompose in up to d-1 dimensions
 - i.e. one dimension should be left "intact" at any one time so that 1D FFTs can be performed on it
 - E.g. for a 2D problem we can parallelise over rows, carry out an FFT on each row, then transpose and do the same again
- For 3D, we have a choice of whether to do a 1D processor decomp ("slab") or a 2D decomp ("pencil")

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FFT: Slab vs Pencil

- Slab
 - Pros: Simple with moderate amount of inter-processor communication
 - Cons: Limited to N procs for N^3 data
- Pencil
 - Pros: faster on massively parallel supercomputers (i.e. lots of cores)
 - Cons: More communications and now more complicated
- Pencil generally better with high core count but not so good for larger arrays on moderate number of cores
- Note: FFTW only does slab!



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Summary

- · Parallelisation of an individual 1D FFT is hard
 - Presently works best for large problems
 - Recent advances in algorithms & hardware encouraging
- Multidimensional problems need to calculate many 1D FFTs
 - Parallelisable by distributing entire FFTs onto the processors and using a standard serial 1D FFT library
 - Requires redistributing the data between FFT dimensions
 - Need to think about decomposition (e.g. slab vs pencil)
- FFT can be used to reduce computational complexity of Fourier transform calculations from $O(n^2)$ to $O(n \log (n))$
 - Applications in signal processing, CFD, probability, etc.



