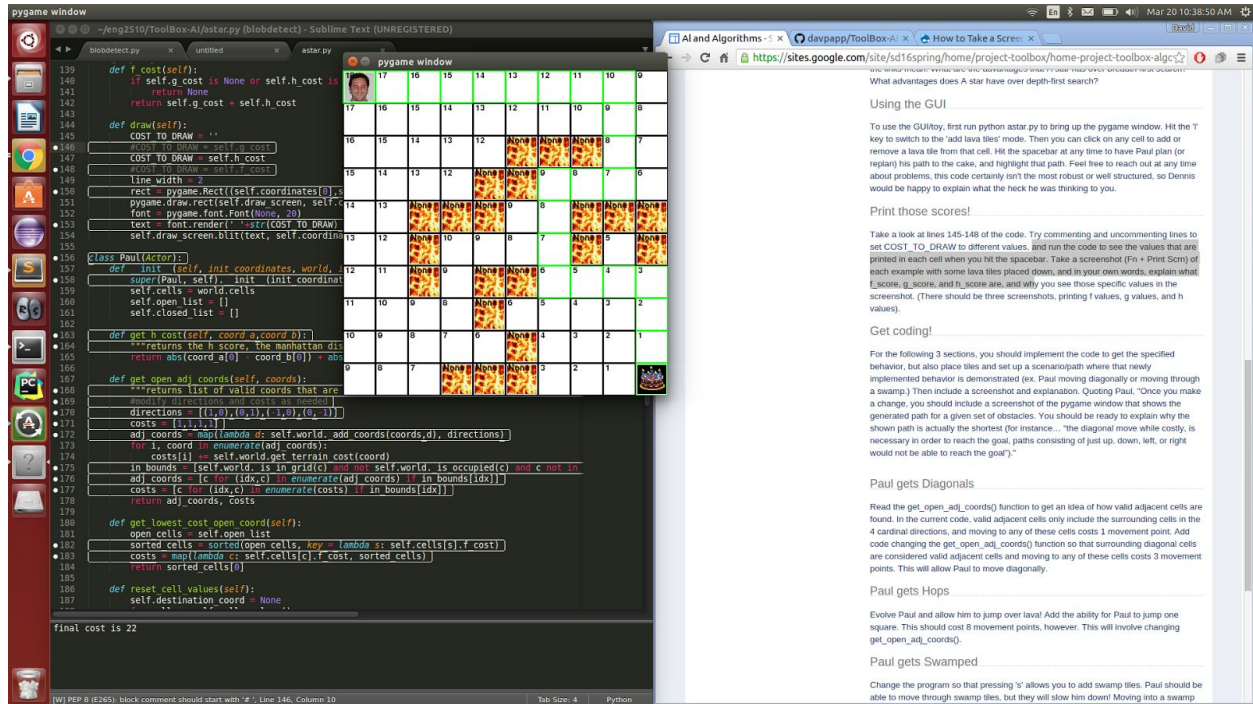
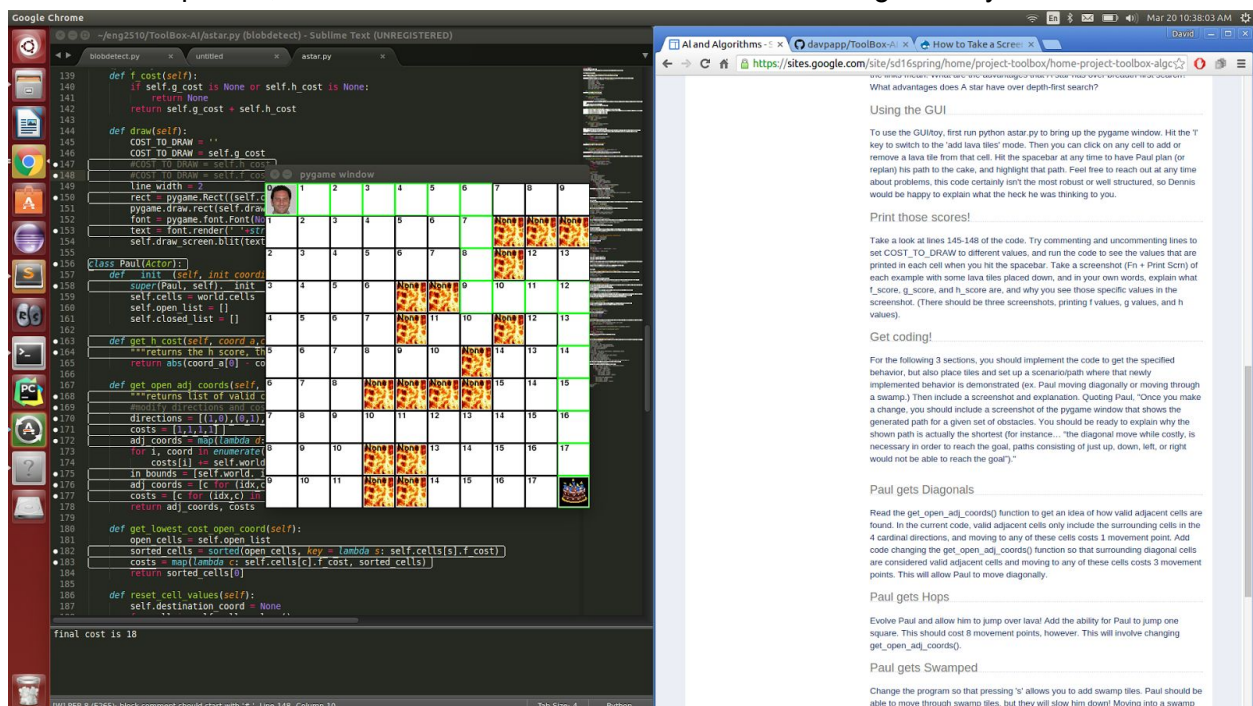


H: J is the distance between our chosen position and the target. It is square root of the sum of the squares of the horizontal and vertical differences in distance. In our picture, H has a linear gradient that decreases in the direction towards the target.



G: G is the cost of moving between two positions. It is based on the minimum cost of its parent nodes. In the picture, it's evident that the cost increases when taking the way around obstacles.



F: F is the sum of the H and G. The minimum path lies where the F values are the least.

The screenshot displays a development environment with a Python script in the background and a pygame window in the foreground. The script, located at `~/eng2510/ToolBox-AI/astar.py`, implements a pathfinding algorithm. It defines a `Paul` class that manages a grid world with obstacles (lava tiles) and a goal (cake). The script calculates the cost of moving between cells based on terrain (grass, lava, swamp) and the distance to the goal. The pygame window shows a 10x10 grid where the player (Paul) starts at the top-left, moves through the grid, and reaches the goal (cake) at the bottom-right. The cost of each cell is displayed as a number. The final cost is 18.

```
def f_cost(self):
    if self.g_cost is None or self.h_cost is None:
        return None
    return self.g_cost + self.h_cost

def draw(self):
    COST_TO_DRAW = ""
    COST_TO_DRAW = self.g_cost
    COST_TO_DRAW = self.f_cost
    line_width = 2
    rect = pygame.Rect(self.coordinates[0], self.coordinates[1], 10, 10)
    pygame.draw.rect(self.draw_screen, self.color, rect, line_width)
    font = pygame.font.Font(None, 20)
    text = font.render(str(COST_TO_DRAW), 1, (10, 10, 10))
    self.draw_screen.blit(text, self.coordinates)

class Paul(Actor):
    def __init__(self, init_coordinates, world, image_loc):
        super(Paul, self).__init__(init_coordinates, world, image_loc)
        self.cells = world.cells
        self.open_list = []
        self.closed_list = []

    def get_h_cost(self, coord_a, coord_b):
        """Returns the h score, the manhattan distance between coord a
        and coord b"""
        return abs(coord_a[0] - coord_b[0]) + abs(coord_a[1] - coord_b[1])

    def get_open_adj_coords(self, coords):
        """Returns list of valid coords that are adjacent to the argument
        Modify directions and costs as needed"""
        directions = [(1, 0), (0, 1), (-1, 0), (0, -1)]
        costs = [(1, 1), (1, 1), (1, 1), (1, 1)]
        adj_coords = map(lambda d: self.world.add_coords(coords, d), directions)
        for i, coord in enumerate(adj_coords):
            in_bounds = self.world.is_in_grid(coord)
            if not in_bounds:
                continue
            adj_coords = [c for (idx, c) in enumerate(adj_coords) if in_bounds[idx]]
            costs = [c for (idx, c) in enumerate(costs) if in_bounds[idx]]
        return adj_coords, costs

    def get_lowest_cost_open_coord(self):
        open_cells = self.open_list
        sorted_cells = sorted(open_cells, key=lambda s: self.cells[s].f_cost)
        costs = map(lambda c: self.cells[c].f_cost, sorted_cells)
        return sorted_cells[0]

    def reset_cell_values(self):
        self.destination_coord = None
```

final cost is 18

Diagonal:

In this case, avoiding diagonals forces Paul to take the long excursion in the bottom-left corner. It is quicker to jump over the diagonal.

The screenshot displays a development environment with a Python script in the background and a pygame window in the foreground. The script, located at `~/eng2510/ToolBox-AI/astar.py`, implements a pathfinding algorithm. It defines a `Paul` class that manages a grid world with obstacles (lava tiles) and a goal (cake). The script calculates the cost of moving between cells based on terrain (grass, lava, swamp) and the distance to the goal. The pygame window shows a 10x10 grid where the player (Paul) starts at the top-left, moves through the grid, and reaches the goal (cake) at the bottom-right. The cost of each cell is displayed as a number. The final cost is 19.

```
def f_cost(self):
    if self.g_cost is None or self.h_cost is None:
        return None
    return self.g_cost + self.h_cost

def draw(self):
    COST_TO_DRAW = ""
    COST_TO_DRAW = self.g_cost
    COST_TO_DRAW = self.f_cost
    line_width = 2
    rect = pygame.Rect(self.coordinates[0], self.coordinates[1], 10, 10)
    pygame.draw.rect(self.draw_screen, self.color, rect, line_width)
    font = pygame.font.Font(None, 20)
    text = font.render(str(COST_TO_DRAW), 1, (10, 10, 10))
    self.draw_screen.blit(text, self.coordinates)

class Paul(Actor):
    def __init__(self, init_coordinates, world, image_loc):
        super(Paul, self).__init__(init_coordinates, world, image_loc)
        self.cells = world.cells
        self.open_list = []
        self.closed_list = []

    def get_h_cost(self, coord_a, coord_b):
        """Returns the h score, the manhattan distance between coord a
        and coord b"""
        return abs(coord_a[0] - coord_b[0]) + abs(coord_a[1] - coord_b[1])

    def get_open_adj_coords(self, coords):
        """Returns list of valid coords that are adjacent to the argument
        Modify directions and costs as needed"""
        directions = [(1, 0), (0, 1), (-1, 0), (0, -1), (1, 1), (1, -1), (-1, 1), (-1, -1)]
        costs = [(1, 1), (1, 1), (1, 1), (1, 1), (1, 1), (1, 1), (1, 1), (1, 1)]
        adj_coords = map(lambda d: self.world.add_coords(coords, d), directions)
        for i, coord in enumerate(adj_coords):
            in_bounds = self.world.is_in_grid(coord)
            if not in_bounds:
                continue
            adj_coords = [c for (idx, c) in enumerate(adj_coords) if in_bounds[idx]]
            costs = [c for (idx, c) in enumerate(costs) if in_bounds[idx]]
        return adj_coords, costs

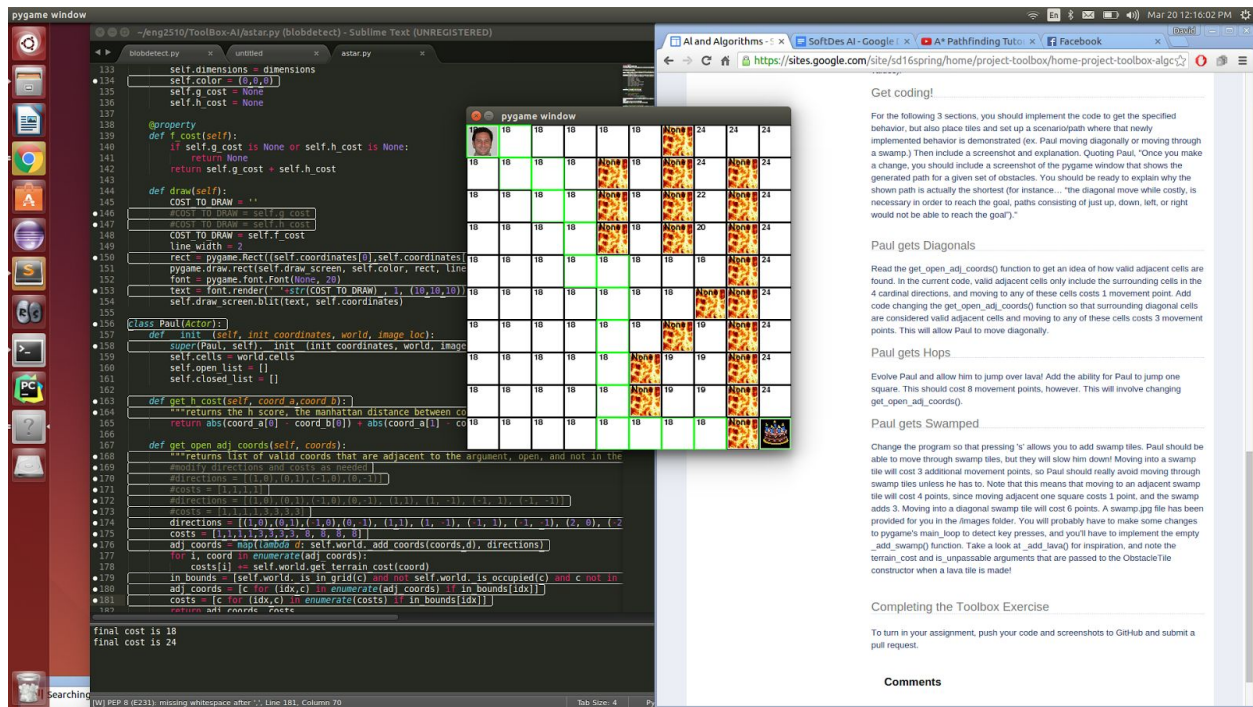
    def get_lowest_cost_open_coord(self):
        open_cells = self.open_list
        sorted_cells = sorted(open_cells, key=lambda s: self.cells[s].f_cost)
        costs = map(lambda c: self.cells[c].f_cost, sorted_cells)
        return sorted_cells[0]

    def reset_cell_values(self):
        self.destination_coord = None
```

final cost is 18
final cost is 19
final cost is 19

Jump:

In this case, it is quicker to jump over the last lava than it is to take the long excursion in the top-right corner. You can tell Paul jumped successfully because the lava it jumped over is not highlighted in green.



Swamp:

In this case, it is quicker to move through the swamp than take the long excursion in the top-right corner. You can tell Paul crossed the swamp rather than jumping over it because the

[illegible]