

ENVIRONMENT

Observation Space: Action Space

player hand strength fold
\$ on table raise
\$ remaining ...
round type
...

state: (hand strength, \$ on table, \$ remaining)

step from initialization
based on rules of game

MAIN

create episodes

episode: (state, action, reward)

(s1, a1, r)
(s1, a2, r)
(s2, a1, r)
(s1, a1, r)
(s1, a1, r)
...

100 instances by default
...break if...
everyone folds,
everyone checks

episode: (state, action, reward)

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episodes
(static user input)

choose action
by probability
(semi-exploratory)

train

for each episode....

for each state-action pair....

(s1, a1)
(s1, a2)
(s2, a1)
(s1, a1)
(s1, a1)
...

average r's

(running
average
from all
episodes)

look up reward for
state and action

update / train!

POLICY

Q nested dictionary
state --> (action --> value)

Observation
(state)

look up

s1 --> a1 --> reward
 a2 --> reward
 ...
s2 --> a1 --> reward
 a2 --> reward
 ...
...

increase probability of action
with highest reward

Action Probabilities

$$\begin{bmatrix} E + \\ E \\ \dots \end{bmatrix}$$

epsilon is a
static user input

AI Poker Overview/
Structure Map