

Readme

Type of controller: feedforward-plus-PI

Tsc\_initial = [1 0 0 1; 0 1 0 0; 0 0 1 0.025; 0 0 0 1]

Tsc\_final = [0 1 0 0; -1 0 0 -1; 0 0 1 0.025; 0 0 0 1]

Kp = 0.7

Ki = 0.0001