

Readme

Type of controller: feedforward-plus-PI

Tsc_initial = [1 0 0 1; 0 1 0 0; 0 0 1 0.025; 0 0 0 1]

Updated final location

Tsc_final = [0 1 0 1; -1 0 0 -1; 0 0 1 0.025; 0 0 0 1]

Kp = 1.9

Ki = 0.001