

Progress Report: Designing an Interpreter for a dynamic language for graph algorithms

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1 Problem Statement

In this project we are planning to work on a dynamically typed language to represent graphs and apply various computations on them.

2 Language Syntax

The syntax of the language is an oversimplified version of C, but without mention of any types. The operations on incompatible types will be error-ed out while interpreting.

2.1 Progress

- We have implemented the tokenizer using flex. Appendix A shows the tokens sent to the parser routine.
- We are supporting syntax like `#include("filename")` and `#define("PI", "3.14")` while doing a single pass of parsing (i.e. Preprocessing of these constructs are done while parsing). This is achieved by using flex's internal stack to manage multiple buffers.
- Appendix B shows the parser rules. These are borrowed from <http://www.quut.com/c/ANSI-C-grammar-y.html>. The rules are compiled by bison tool to generate the C parser.
- We are able to generate the AST. Our AST is basically a list of function definitions. Each function definition class contains name of the function, a set of formal arguments and a list of body statements. These body statements could be an assignment, loop-statement, function call, etc. The leafs of the AST could be an identifier, int, float, true, false, null, string, vertex, edge or graph.
- Some of the key features of the parser is as follows:
 - Support of C statements like *if then*, *if then else*, *while*, *for*.
 - Support of *break*, *continue* within loop-body and *return* in function-body. As we are representing both loop-body and function-body (i.e. anything between “{” & “}”) as compound statements so we do not have to distinguish these two cases. The semantics of executing a *break*, *continue* and *return* will be discussed in the interpreter runtime section.
 - Supporting graph as first class object *valuegraph*. The syntax to declare a graph is *g = graph()*; which will be represented in AST as an assignment-node with left-node containing an identifier and right node as a function call. Now this function call corresponds to a built in function that returns a *valuegraph* (which is one of the leaf nodes of AST) on execution.
 - Supporting vertices and edges as first class objects which contains a map to add properties. This feature is useful in various graph algorithms like in dfs traversal we may use a vertex property “visited” to keep track of vertices already explored.

3 Language Semantics

The language semantics will be same as that of C as we are using a subset of it.

4 Interpreter Runtime

The following are the key features of the runtime:

- The runtime starts with searching for function definition *function main(argv)* and then creates a function call out of it and execute it. While creating the function call it uses the command-line parameters as the actual parameters of the function call.
- The execution of a function call involves finding the corresponding function definition, checking if the number of formal and actuals are equal and then pushing a call stack frame (which contains the mapping between the formal and actual values passed to them) in a global call stack. After that, the function is executed w.r.t the current context(i.e. the top of the call stack).
- The execution of the function involves executing a list of statements. The statements may add further mappings in the current call stack frame. Whenever a name (identifier) is refereed, the mapping in the current context need to be consulted to get the actual value of it.
- The semantics of *break*, *continue* or *return* is supported using the try-catch mechanism of C++. For example, while interpreting a loop-body, whenever a *break* is encountered, a corresponding object is thrown, which is caught in a place outside of the loop execution in order to implement the semantics of break.
- Occurrence of *break* and *continue* within non-loop body triggers an error. While interpreting a node-block (which is a set statements within “{” and “}”), whenever the runtime finds a *break* or *continue* it throws a object. Now if this object is caught inside a non-loop block then error is reported.
- Division by zero and operations on incompatible types are runtime errors.

5 Future Work

The following are the future work.

- To support additional operators to specify relationships between the nodes/edges or their groups. The operator that we are planning to support are the described next with their semantics.
 - $v1 \leftarrow v2$: Select all the directed edges from vertices $v1$ to $v2$.
 - $v1 \rightarrow v2$: Select all the directed edges from vertices $v2$ to $v1$.
 - $v1 \leftrightarrow v2$: Select all the directed edges between vertices $v1$ and $v1$.
 - $v1 ? v2$: Select all the edges (directed or undirected) between vertices $v1$ and $v1$.
 - $S1 \cap S2$: Selects the intersection between the set of vertices/edges.

Most of these ideas behind choosing the operators are borrowed from [2]. The intuition behind these operators is that the users do not have to remember longer commands. Also its very intuitive to build up complex operations using the simpler ones.

- To support saving of state and retrieving it back using routines like *saveStateFromFile* & *loadStateFromFile*. This idea is borrowed from [2] and this seems a useful service provided to do exploratory programming, as the user might be interested to checkout the last saved state (or a state with a any tag) or to undo all the experiments down to a particular state.

5.1 Evaluation Strategy

The baseline of our evaluation will be the open source [1] system. The evaluation will cover the following two aspects of our implementation:

- The convenience and intuitive extensibility provided by our programming model.
 - We will be implementing a couple of well know graph algorithms in both baseline and our implementation and use number of dynamic instructions interpreted as a measure to show the conciseness of our representation.
- Performance
 - As we are planning to keep the compiled version of frequently used graph routines (like `dfs_iterators(vertex)`, `bfs_iterators()`), we are expecting to achieve better performance in terms of runtime.

References

- [1] *Graphal: Graph algorithms interpreter*.
- [2] E. ADAR, *Guess: A language and interface for graph exploration*, in Proceedings of the SIGCHI Conference on Human Factors in Computing Systems, CHI '06, New York, NY, USA, 2006, ACM, pp. 791–800.