NEL Arduino-Based Motor Behavior File Format (*.ARDYMOTOR)

(Changes from previous versions are shown in red)

Version: -3 (incremental change from version -1, not version -2)

- (int8) Format version.
- (uint16) DayCode.
- (uint8) Booth number.
- (uint8) Number of characters in the rat's name.
 - (uchar) Characters of the rat's name.
- (float32) Input device position (in centimeters).
- (uint8) Number of characters in the stage title.
 - o (uchar) Characters of the stage title.
- (uint8) Number of characters in the device description.
 - o (uchar) Characters of the device description.
 - If the device is the pull, knob, or lever:
 - (float32) Coefficients of the calibration equation (m,b).
 - If the device is the wheel or the knob:
 - (float32) Number of degrees per tick.
- (uint8) Number of characters in the constraint description.
 - o (uchar) Characters of the constraint description.
- (uint8) Number of characters in the threshold units.
 - (uchar) Characters of the threshold units.
- Repeat through all trials:
 - (uint32) Trial Number.
 - A trial number of zero indicates a manual feeding or pause.
 - (float64) Start time of trial (serial date number).
 - o (uint8) Outcome
 - H (72) = Hit
 - \blacksquare M (77) = Miss
 - \blacksquare F (70) = Manual Feed
 - P (80) = Pause
 - If the outcome was a pause:
 - (float64) End time of the pause.
 - (float32) Response window (in seconds).
 - o (float32) Threshold for trial initiation.
 - (float32) Threshold for reward.
 - (uint8) Number of hits/rewards.
 - (float64) Hit/reward times (serial date number).
 - (uint8) Number of VNS events.
 - (float64) VNS event times (serial date number).
 - (uint32) Number of samples in the sensor signal.
 - o (int16) Signal timepoints (in microseconds).
 - (float32) Device signal values.
 - o (int16) IR signal values.

Version: -2

- (int16) Format version.
- (uint16) DayCode.
- (uint16) Booth number.
- (uint8) Number of characters in the rat's name.
 - (uchar) Characters of the rat's name.
- (float32) Input device position (in centimeters).
- (uint8) Number of characters in the stage title.
 - o (uchar) Characters of the stage title.
- (uint8) Number of characters in the device description.
 - (uchar) Characters of the device description.
 - If the device is the pull:
 - (float32) Coefficients of the calibration equation (m,b).
 - If the device is the wheel or the knob:
 - (float32) Number of degrees per tick.
- (uint8) Number of characters in the constraint description.
 - o (uchar) Characters of the constraint description.
- (uint8) Number of characters in the threshold units.
 - o (uchar) Characters of the threshold units.
- (float32) Pre-trial sampling duration (in milliseconds).
- Repeat through all trials:
 - (uint32) Trial Number.
 - A trial number of zero indicates a manual feeding or pause.
 - (float64) Start time of trial (serial date number).
 - (uint8) Outcome
 - H (72) = Hit
 - M (77) = Miss
 - \blacksquare F (70) = Manual Feed
 - Arr P(80) = Pause
 - If the outcome was a pause:
 - (float64) End time of the pause.
 - (float32) Response window (in seconds).
 - (float32) Threshold for trial initiation.
 - (float32) Threshold for reward.
 - (uint8) Number of hits/rewards.
 - (float64) Hit/reward times (serial date number).
 - (uint8) Number of VNS events.
 - (float64) VNS event times (serial date number).
 - (uint32) Number of samples in the sensor signal.
 - (uint16) Signal timepoints (in microseconds).
 - (float32) Device signal values.

o (int16) - IR signal values.

Version: -1

- (int8) Format version.
- (uint16) DayCode.
- (uint8) Booth number.
- (uint8) Number of characters in the rat's name.
 - (uchar) Characters of the rat's name.
- (float32) Input device position (in centimeters).
- (uint8) Number of characters in the stage title.
 - (uchar) Characters of the stage title.
- (uint8) Number of characters in the device description.
 - o (uchar) Characters of the device description.
 - If the device is the pull:
 - (float32) Coefficients of the calibration equation (m,b).
 - o If the device is the wheel or the knob:
 - (float32) Number of degrees per tick.
- (uint8) Number of characters in the constraint description.
 - (uchar) Characters of the constraint description.
- (uint8) Number of characters in the threshold units.
 - o (uchar) Characters of the threshold units.
- Repeat through all trials:
 - (uint32) Trial Number.
 - A trial number of zero indicates a manual feeding or pause.
 - o (float64) Start time of trial (serial date number).
 - o (uint8) Outcome
 - H (72) = Hit
 - M (77) = Miss
 - F(70) = Manual Feed
 - P(80) = Pause
 - If the outcome was a pause:
 - (float64) End time of the pause.
 - o (float32) Response window (in seconds).
 - \circ $\,$ (float32) Threshold for trial initiation.
 - o (float32) Threshold for reward.
 - (uint8) Number of hits/rewards.
 - (float64) Hit/reward times (serial date number).
 - (uint8) Number of VNS events.
 - (float64) VNS event times (serial date number).
 - o (uint32) Number of samples in the sensor signal.
 - o (int16) Signal timepoints (in microseconds).
 - (float32) Device signal values.
 - o (int16) IR signal values.

Version: Original

- (uint16) DayCode.
- (uint8) Booth number.
- (uint8) Number of characters in the rat's name.
 - o (uchar) Characters of the rat's name.
- (uint8) Input device position (in inches).
- (uint8) Response window (in seconds).
- (uchar) Characters of the stage title.
- (uchar) Characters of the device description.
- (uint8) Bin size.
- (uint8) Number of stimulus parameters.
 - o (int16) Number of characters in the name of parameter #1.
 - (uchar) Characters of parameter #1 name.
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- Repeat through all trials:
 - (uint16) Threshold for reward.
 - (float64) Start time of trial (serial date number).
 - o (float64) Hit/reward time (serial date number).
 - (float64) Trial Outcome (0 = miss, 1 = hit w/ no stim., 2 = hit w/ stim.)
 - (uint32) Number of beam breaks on IR#1
 - (float64) Beam break times (serial date number).
 - (uint32) Number of beam breaks on IR#2
 - (float64) Beam break times (serial date number).
 - (uint32) Number of beam breaks on IR#3
 - (float64) Beam break times (serial date number).
 - (uint32) Number of samples in the sensor signal.
 - (float64) Signal values.
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