

Mech A Idea for summer

Velcore head
camera
clips Robotic Arm

microphone GLANGUAGE
NEED TO LEARN CODIN

TOUCH - Has cameras to react
to gesture.

Stop

[] : A flat arm indicate
stop or stay

Come

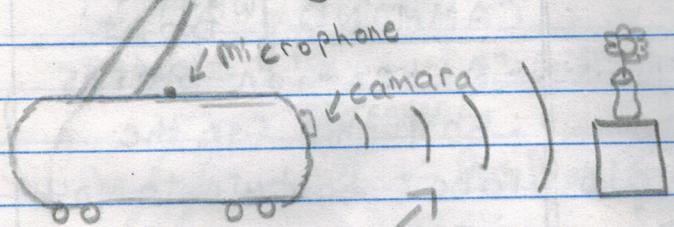
[] + [] : When the fingers
touch the palm
of your hand it
gestures come

Voice Commands!

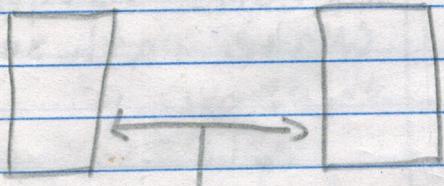
• Jarvis
(Name) Call for the robot's attention

Look at Chart for
all command ways

Guiding / Path sensing Idea

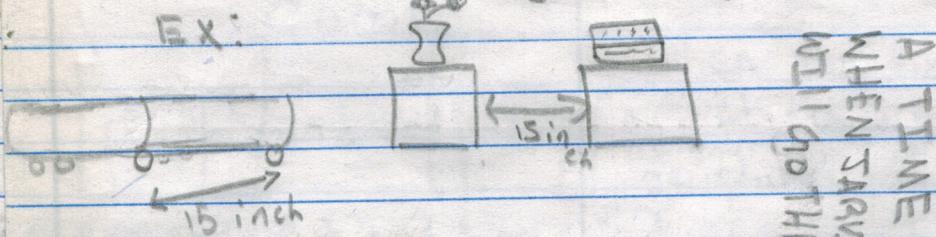


{ - Requir Advance Coding! }

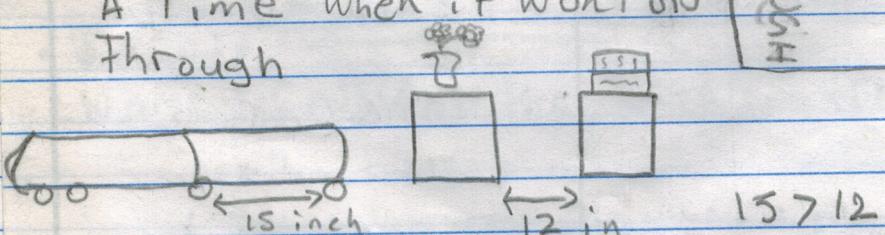


senses distance and if
there is enough distance
it would go through

Ex:



A Time When it Won't Go
Through



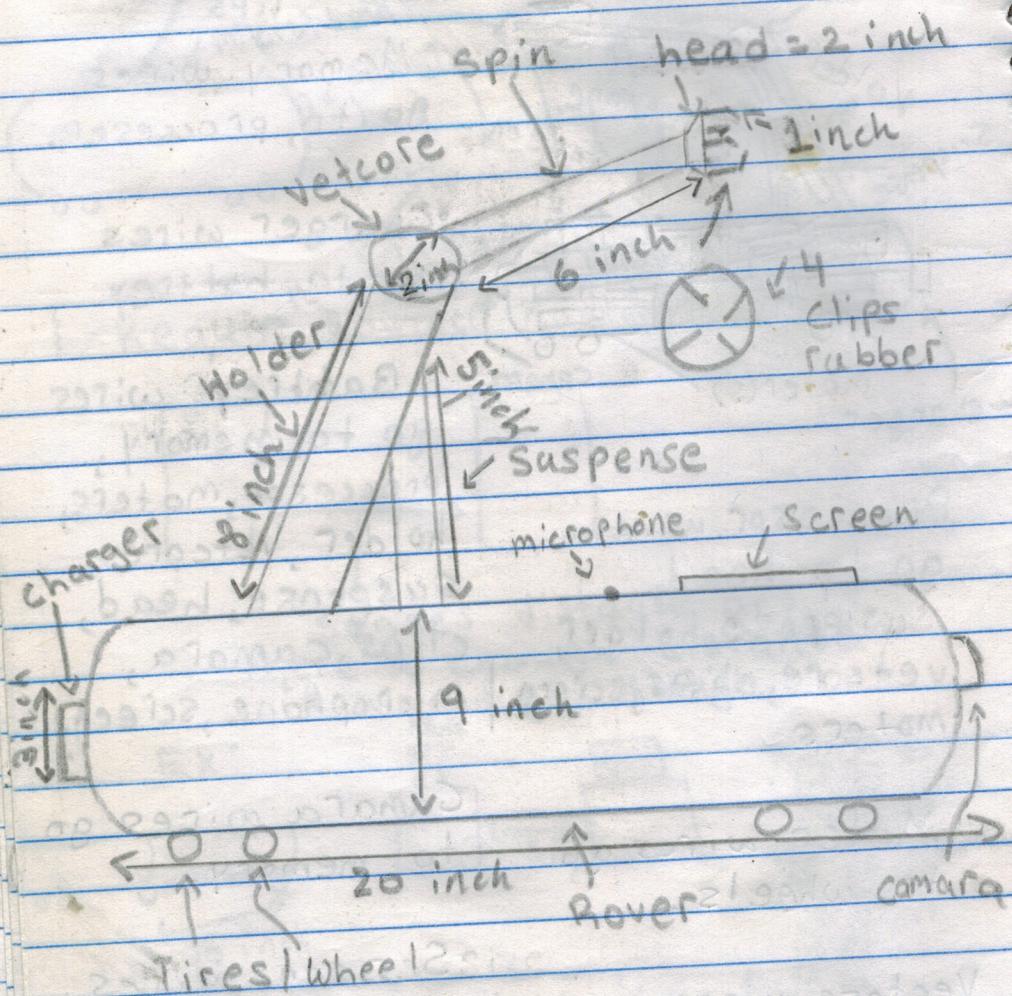
ALL VOICE COMMANDS

WORD	CMD / WHAT IT DOES
- Hey	- Jarvis
- Look here	- Attention words
- Help ~ Hold this	- Say this for the robot to turn to you
- You	
- Now	
- Come here	Get the robot
- Come to me	to come to you
- Get here	(Make path sensing thing.)
- Hurry to me	
- Get to me	

June 5, 2019 (13 year old)

Sizing + Material

Idea T

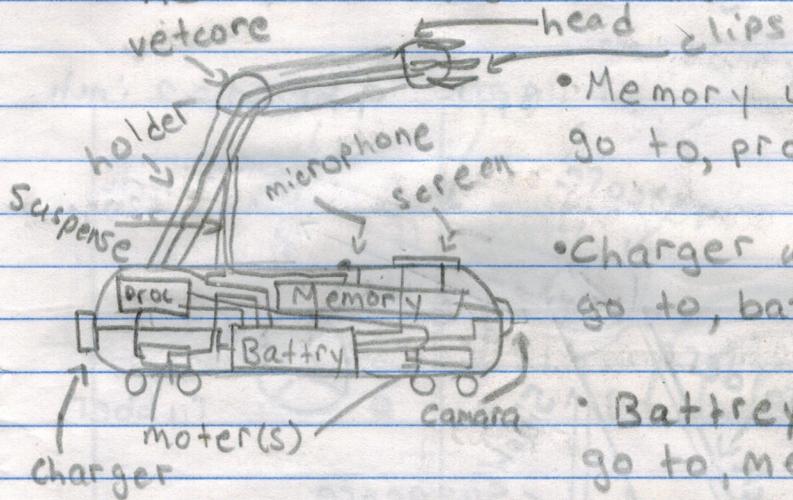


Parts needed?

- 20 inch hollow compartment
- 3 inch port
- 30 inch long wires
- 4 wheels
- 8 inch long hollow round (3 inch diameter)
ect...

1000000000 Plastic robot

The Internals (circuit)



- Memory wires go to, processor.

- Charger wires go to, battery

- Battery wires go to, memory, processor, motors, holder, vectore, suspense, head, clips, camera, microphone, screen.

Processor wires

go to head, suspense, holder, vectore, clips, screen | microphone, screen, motors

Moter wires go to wheels.

Camara wires go to memory.

Vectore wires go to head and clip.

Screen wires go to memory

Microphone wires go to memory

Got to work on a digital circate plan