Chapter 6

Communicating during Shared Plans Execution: what should the robot do with its head?

Contents

6.1 Scenario 1
6.2 Evaluation in simulation 1
6.3 User study 1

6.1 Motivations

6.2 Background

6.3 Identifications of needed signals

6.4 Unitary evaluation of signals

6.5 Proposed system

6.6 Results

Bibliography