

Task 3g GCN model

March 26, 2024

0.1 Import Libraries

```
[1]: !pip install torch-geometric

import os
import numpy as np
import pyarrow as pa
import pandas as pd
import pyarrow.parquet as pq

import torch
import torch.nn as nn
import torch.nn.functional as F
from torch_geometric.nn import GCNConv, global_mean_pool
from torch_geometric.data import Data, DataLoader
from sklearn.metrics import roc_curve, roc_auc_score
from scipy.spatial.distance import cdist
from tqdm import tqdm
import matplotlib.pyplot as plt
```

Collecting torch-geometric

Downloading torch_geometric-2.5.1-py3-none-any.whl.metadata (64 kB)
64.2/64.2 kB

2.5 MB/s eta 0:00:00

Requirement already satisfied: tqdm in /opt/conda/lib/python3.10/site-packages (from torch-geometric) (4.66.1)

Requirement already satisfied: numpy in /opt/conda/lib/python3.10/site-packages (from torch-geometric) (1.26.4)

Requirement already satisfied: scipy in /opt/conda/lib/python3.10/site-packages (from torch-geometric) (1.11.4)

Requirement already satisfied: fsspec in /opt/conda/lib/python3.10/site-packages (from torch-geometric) (2024.2.0)

Requirement already satisfied: jinja2 in /opt/conda/lib/python3.10/site-packages (from torch-geometric) (3.1.2)

Requirement already satisfied: aiohttp in /opt/conda/lib/python3.10/site-packages (from torch-geometric) (3.9.1)

Requirement already satisfied: requests in /opt/conda/lib/python3.10/site-packages (from torch-geometric) (2.31.0)

Requirement already satisfied: pyparsing in /opt/conda/lib/python3.10/site-packages (from torch-geometric) (3.1.1)

Requirement already satisfied: scikit-learn in /opt/conda/lib/python3.10/site-packages (from torch-geometric) (1.2.2)

Requirement already satisfied: psutil>=5.8.0 in /opt/conda/lib/python3.10/site-packages (from torch-geometric) (5.9.3)

Requirement already satisfied: attrs>=17.3.0 in /opt/conda/lib/python3.10/site-packages (from aiohttp->torch-geometric) (23.2.0)

Requirement already satisfied: multidict<7.0,>=4.5 in /opt/conda/lib/python3.10/site-packages (from aiohttp->torch-geometric) (6.0.4)

Requirement already satisfied: yarl<2.0,>=1.0 in /opt/conda/lib/python3.10/site-packages (from aiohttp->torch-geometric) (1.9.3)

Requirement already satisfied: frozenlist>=1.1.1 in /opt/conda/lib/python3.10/site-packages (from aiohttp->torch-geometric) (1.4.1)

Requirement already satisfied: aiosignal>=1.1.2 in /opt/conda/lib/python3.10/site-packages (from aiohttp->torch-geometric) (1.3.1)

Requirement already satisfied: async-timeout<5.0,>=4.0 in /opt/conda/lib/python3.10/site-packages (from aiohttp->torch-geometric) (4.0.3)

Requirement already satisfied: MarkupSafe>=2.0 in /opt/conda/lib/python3.10/site-packages (from jinja2->torch-geometric) (2.1.3)

Requirement already satisfied: charset-normalizer<4,>=2 in /opt/conda/lib/python3.10/site-packages (from requests->torch-geometric) (3.3.2)

Requirement already satisfied: idna<4,>=2.5 in /opt/conda/lib/python3.10/site-packages (from requests->torch-geometric) (3.6)

Requirement already satisfied: urllib3<3,>=1.21.1 in /opt/conda/lib/python3.10/site-packages (from requests->torch-geometric) (1.26.18)

Requirement already satisfied: certifi>=2017.4.17 in /opt/conda/lib/python3.10/site-packages (from requests->torch-geometric) (2024.2.2)

Requirement already satisfied: joblib>=1.1.1 in /opt/conda/lib/python3.10/site-packages (from scikit-learn->torch-geometric) (1.3.2)

Requirement already satisfied: threadpoolctl>=2.0.0 in /opt/conda/lib/python3.10/site-packages (from scikit-learn->torch-geometric) (3.2.0)

Downloading torch_geometric-2.5.1-py3-none-any.whl (1.1 MB)

1.1/1.1 MB

27.5 MB/s eta 0:00:0000:01

Installing collected packages: torch-geometric

Successfully installed torch-geometric-2.5.1

0.2 Disable Warnings

```
[2]: import warnings
      warnings.filterwarnings("ignore")
      warnings.simplefilter("ignore")
```

0.3 Load the Data

```
[3]: def read_file(path):
    chunk_size = 25

    # Create a Parquet file reader object
    parquet_file = pq.ParquetFile(path)

    # Determine the total number of rows in the file
    total_rows = parquet_file.metadata.num_rows

    # Loop over the file in chunks
    data = []
    for i in range(0, total_rows, chunk_size):
        # Read a chunk of rows from the file
        chunk = (parquet_file.read_row_group(i))
        dm = (chunk.to_pandas())
        data.append(dm)

    # Concatenate all the DataFrames into a single DataFrame
    df = pd.concat(data, ignore_index=True)
    print(parquet_file.read_row_group(0).to_pandas())
    return df

[4]: df1 = read_file('/kaggle/input/common-task-2-dataset/Task - 2 Data (Parquet)/
    ↪jet0_run0.test.snappy.parquet')
df2 = read_file('/kaggle/input/common-task-2-dataset/Task - 2 Data (Parquet)/
    ↪jet0_run1.test.snappy.parquet')
df3 = read_file('/kaggle/input/common-task-2-dataset/Task - 2 Data (Parquet)/
    ↪jet0_run2.test.snappy.parquet')
```

```

                                X_jets      pt      m0  \
0  [[0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0...  112.411095  21.098248

      y
0  0.0

                                X_jets      pt      m0  \
0  [[0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0...  147.686737  32.114449

      y
0  0.0

                                X_jets      pt      m0  \
0  [[0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0...  107.854118  18.723455

      y
0  0.0
```

```
[5]: def construct_image_dataset(df):
    # Get the total number of samples
    num_samples = len(df)

    # Initialize empty arrays for X and y
    X = np.empty((num_samples, 3, 125, 125), dtype=np.float32)
    y = np.empty(num_samples, dtype=int)

    # Iterate through the DataFrame and fill X and y
    for i, row in df.iterrows():
        # Stack the three channels of X_jets and transpose them to match the
        ↪desired shape
        X[i] = np.transpose(np.dstack((np.stack(row['X_jets'])[0]), np.
        ↪stack(row['X_jets'])[1]), np.stack(row['X_jets'])[2]))), (2, 0, 1))
        # Assign the label to y
        y[i] = row['y']

    # Rearrange the dimensions of X to match the TensorFlow format (samples,
    ↪height, width, channels)
    X = np.transpose(X, (0, 2, 3, 1))

    return X, y
```

```
[6]: # Assuming 'df' is the pandas DataFrame
X1, y1 = construct_image_dataset(df1)
X2, y2 = construct_image_dataset(df2)
X3, y3 = construct_image_dataset(df3)
```

```
[7]: # Save X1 array to binary file 'X1.npy'
with open('X1.npy', 'wb') as f:
    np.save(f, X1)

# Save y1 array to binary file 'y1.npy'
with open('y1.npy', 'wb') as f:
    np.save(f, y1)

# Save X2 array to binary file 'X2.npy'
with open('X2.npy', 'wb') as f:
    np.save(f, X2)

# Save y2 array to binary file 'y2.npy'
with open('y2.npy', 'wb') as f:
    np.save(f, y2)

# Save X3 array to binary file 'X3.npy'
with open('X3.npy', 'wb') as f:
    np.save(f, X3)
```

```
# Save y3 array to binary file 'y3.npy'
with open('y3.npy', 'wb') as f:
    np.save(f, y3)
```

```
[8]: x1 = np.load('X1.npy')
      x2 = np.load('X2.npy')
      x3 = np.load('X3.npy')

      y1 = np.load('y1.npy')
      y2 = np.load('y2.npy')
      y3 = np.load('y3.npy')
```

```
[9]: # Combine x arrays along the first axis (axis=0)
      x = np.concatenate((x1, x2, x3), axis=0)

      # Combine y arrays along the first axis (axis=0)
      y = np.concatenate((y1, y2, y3), axis=0)

      # Save the combined X array to a binary file named 'X.npy'
      with open('x.npy', 'wb') as f:
          np.save(f, x)

      # Save the combined y array to a binary file named 'y.npy'
      with open('y.npy', 'wb') as f:
          np.save(f, y)
```

```
[10]: X = np.load("x.npy")
       y = np.load("y.npy")
```

0.3.1 Convert the numpy arrays to PyTorch tensors

```
[11]: X = torch.tensor(X, dtype=torch.float)
       y = torch.tensor(y, dtype=torch.int)
```

```
[12]: def linear_kernel(distance_matrix, gamma=None):
        if gamma is None:
            gamma = 1.0 / distance_matrix.shape[1]
        return gamma * np.dot(distance_matrix, gamma)
```

```
[13]: def construct_graph_using_linear_kernel(image, label):
        height, width, channels = image.shape
        nodes = []
        positions = []

        # Iterate over the 5x5 crops and extract features
```

```

for i in range(0, height, 5):
    for j in range(0, width, 5):
        crop = image[i:i+5, j:j+5]
        feature = crop.reshape(-1)
        nodes.append(feature)
        positions.append((i, j))

nodes = torch.stack(nodes)
positions = np.array(positions)

# Compute edge_index and edge_attr using Linear Kernel
distance_matrix = cdist(positions, positions)
linear_values = linear_kernel(distance_matrix)
edges = np.where(linear_values > 0.8) # Adjust threshold as needed
edge_index = torch.tensor(np.vstack(edges), dtype=torch.long)
edge_attr = torch.tensor(linear_values[edges], dtype=torch.float)

# Create the PyTorch Geometric Data object
data = Data(x=nodes, edge_index=edge_index, edge_attr=edge_attr, y=torch.
→tensor([label], dtype=torch.long))
return data

```

```

[14]: filename = "pyg_data_list.pkl"
if os.path.exists(filename):
    print(f"{filename} exists in the current directory.")
    with open("pyg_data_list.pkl", "rb") as file:
        pyg_data_list = pickle.load(file)
else:
    print(f"{filename} does not exist in the current directory.")
    # Create PyTorch Geometric Data objects for each image
    pyg_data_list = [construct_graph_using_linear_kernel(X[i], y[i]) for i in
→range(X.shape[0]), desc="Creating Data Objects")]

```

pyg_data_list.pkl does not exist in the current directory.

Creating Data Objects: 100%| | 5573/5573 [01:22<00:00, 67.35it/s]

0.4 Set up the train and test datasets

```

[15]: train_dataset = pyg_data_list[:int(len(pyg_data_list) * 0.75)]
test_dataset = pyg_data_list[int(len(pyg_data_list) * 0.75):]

```

0.5 Set up the data loader

```

[16]: train_loader = DataLoader(train_dataset, batch_size=32, shuffle=True)
test_loader = DataLoader(test_dataset, batch_size=32, shuffle=False)

```

0.6 Building GCN Model

```
[17]: class GCNModel(torch.nn.Module):
    def __init__(self, num_node_features, hidden_channels, num_classes):
        super(GCNModel, self).__init__()
        self.conv1 = GCNConv(num_node_features, hidden_channels)
        self.conv2 = GCNConv(hidden_channels, hidden_channels)
        self.fc = torch.nn.Linear(hidden_channels, num_classes)

    def forward(self, data):
        x, edge_index, edge_attr, batch = data.x, data.edge_index, data.
        ↪edge_attr, data.batch
        x = F.relu(self.conv1(x, edge_index))
        x = F.relu(self.conv2(x, edge_index))
        x = global_mean_pool(x, batch)
        x = F.dropout(x, p=0.5, training=self.training)
        x = self.fc(x)
        return x
```

0.7 Set up the GCN model, loss function, and optimizer

```
[18]: num_node_features = train_dataset[0].x.shape[1]
hidden_channels = 64
num_classes = 2

device = torch.device("cuda" if torch.cuda.is_available() else "cpu")
model = GCNModel(num_node_features, hidden_channels, num_classes).to(device)
criterion = torch.nn.CrossEntropyLoss()
optimizer = torch.optim.Adam(model.parameters(), lr=1e-3)
```

0.8 Define training and evaluation functions

```
[19]: def train():
    model.train()
    total_loss = 0
    for data in tqdm(train_loader, desc="Training"):
        data = data.to(device)
        optimizer.zero_grad() # To Clear gradients
        out = model(data) # Perform a single forward pass
        loss = criterion(out, data.y) # Compute the loss
        loss.backward() # Deriving gradients
        optimizer.step() # Updating parameters
        total_loss += loss.item()
    return total_loss / len(train_loader)

def test(loader):
    model.eval()
```

```

correct = 0
y_true = []
y_probs = []

for data in tqdm(loader, desc="Testing"):
    data = data.to(device)
    with torch.no_grad():
        logits = model(data)
        probs = F.softmax(logits, dim=-1)
        pred = logits.argmax(dim=-1)

    y_true.extend(data.y.tolist())
    y_probs.extend(probs[:, 1].tolist())

    correct += int((pred == data.y).sum())

fpr, tpr, _ = roc_curve(y_true, y_probs)
roc_auc = roc_auc_score(y_true, y_probs)
accuracy = correct / len(loader.dataset)

return accuracy, fpr, tpr, roc_auc

```

0.9 Function to plot the ROC curve

```

[20]: def plot_roc_curve(false_pr, true_pr, roc_auc, title="ROC curve"):
    plt.figure(figsize = (10, 10))
    plt.plot(false_pr, true_pr, color="darkorange", lw=2, label=f"ROC curve_
↪(AUC = {roc_auc:.4f})")
    plt.plot([0, 1], [0, 1], color="blue", lw=2, linestyle="-.")
    plt.xlim([0.0, 1.0])
    plt.ylim([0.0, 1.05])
    plt.xlabel("False Positive Rate")
    plt.ylabel("True Positive Rate")
    plt.title(title)
    plt.legend(loc="lower right")
    plt.savefig("gcn-roc-curve.png")
    plt.show()

```

```

[21]: num_epochs = 25
max_auc = 0

for epoch in range(num_epochs):
    loss = train()
    train_acc, _, _, train_roc_auc = test(train_loader)
    test_acc, false_pr, true_pr, test_roc_auc = test(test_loader)

```



```

    print(f"Epoch: {epoch + 1}, Loss: {loss:.4f}, Train (Accuracy): {train_acc:.4f}, Train (ROC-AUC): {train_roc_auc:.4f}, Test (Accuracy): {test_acc:.4f}, Test (ROC-AUC): {test_roc_auc:.4f}")
    if test_roc_auc > max_auc:
        max_auc = test_roc_auc
        max_false_pr, max_true_pr, = false_pr, true_pr

plot_roc_curve(max_false_pr, max_true_pr, max_auc, title="ROC curve (Test set)")

```

```

Training: 100%|      | 131/131 [00:02<00:00, 60.67it/s]
Testing: 100%|      | 131/131 [00:00<00:00, 132.33it/s]
Testing: 100%|      | 44/44 [00:00<00:00, 134.54it/s]

Epoch: 1, Loss: 0.6931, Train (Accuracy): 0.5085, Train (ROC-AUC): 0.6358, Test
(Accuracy): 0.5100, Test (ROC-AUC): 0.6218

Training: 100%|      | 131/131 [00:01<00:00, 105.85it/s]
Testing: 100%|      | 131/131 [00:00<00:00, 133.33it/s]
Testing: 100%|      | 44/44 [00:00<00:00, 116.74it/s]

Epoch: 2, Loss: 0.6919, Train (Accuracy): 0.5781, Train (ROC-AUC): 0.6691, Test
(Accuracy): 0.5703, Test (ROC-AUC): 0.6602

Training: 100%|      | 131/131 [00:01<00:00, 109.68it/s]
Testing: 100%|      | 131/131 [00:01<00:00, 128.99it/s]
Testing: 100%|      | 44/44 [00:00<00:00, 127.42it/s]

Epoch: 3, Loss: 0.6863, Train (Accuracy): 0.5970, Train (ROC-AUC): 0.6801, Test
(Accuracy): 0.5875, Test (ROC-AUC): 0.6679

Training: 100%|      | 131/131 [00:01<00:00, 113.45it/s]
Testing: 100%|      | 131/131 [00:00<00:00, 133.46it/s]
Testing: 100%|      | 44/44 [00:00<00:00, 129.65it/s]

Epoch: 4, Loss: 0.6705, Train (Accuracy): 0.6365, Train (ROC-AUC): 0.6947, Test
(Accuracy): 0.6155, Test (ROC-AUC): 0.6766

Training: 100%|      | 131/131 [00:01<00:00, 108.05it/s]
Testing: 100%|      | 131/131 [00:00<00:00, 137.53it/s]
Testing: 100%|      | 44/44 [00:00<00:00, 136.25it/s]

Epoch: 5, Loss: 0.6547, Train (Accuracy): 0.6557, Train (ROC-AUC): 0.7152, Test
(Accuracy): 0.6370, Test (ROC-AUC): 0.6901

Training: 100%|      | 131/131 [00:01<00:00, 115.95it/s]
Testing: 100%|      | 131/131 [00:00<00:00, 135.53it/s]
Testing: 100%|      | 44/44 [00:00<00:00, 129.08it/s]

Epoch: 6, Loss: 0.6432, Train (Accuracy): 0.6655, Train (ROC-AUC): 0.7278, Test
(Accuracy): 0.6385, Test (ROC-AUC): 0.6984

Training: 100%|      | 131/131 [00:01<00:00, 116.03it/s]
Testing: 100%|      | 131/131 [00:00<00:00, 134.55it/s]

```

Testing: 100%| | 44/44 [00:00<00:00, 144.40it/s]

Epoch: 7, Loss: 0.6341, Train (Accuracy): 0.6779, Train (ROC-AUC): 0.7360, Test (Accuracy): 0.6499, Test (ROC-AUC): 0.7066

Training: 100%| | 131/131 [00:01<00:00, 117.07it/s]
Testing: 100%| | 131/131 [00:00<00:00, 133.59it/s]
Testing: 100%| | 44/44 [00:00<00:00, 142.06it/s]

Epoch: 8, Loss: 0.6269, Train (Accuracy): 0.6829, Train (ROC-AUC): 0.7457, Test (Accuracy): 0.6420, Test (ROC-AUC): 0.7115

Training: 100%| | 131/131 [00:01<00:00, 102.82it/s]
Testing: 100%| | 131/131 [00:01<00:00, 121.98it/s]
Testing: 100%| | 44/44 [00:00<00:00, 131.36it/s]

Epoch: 9, Loss: 0.6199, Train (Accuracy): 0.6870, Train (ROC-AUC): 0.7532, Test (Accuracy): 0.6463, Test (ROC-AUC): 0.7152

Training: 100%| | 131/131 [00:01<00:00, 111.86it/s]
Testing: 100%| | 131/131 [00:01<00:00, 129.96it/s]
Testing: 100%| | 44/44 [00:00<00:00, 123.37it/s]

Epoch: 10, Loss: 0.6134, Train (Accuracy): 0.6994, Train (ROC-AUC): 0.7572, Test (Accuracy): 0.6593, Test (ROC-AUC): 0.7195

Training: 100%| | 131/131 [00:01<00:00, 112.02it/s]
Testing: 100%| | 131/131 [00:00<00:00, 135.14it/s]
Testing: 100%| | 44/44 [00:00<00:00, 136.94it/s]

Epoch: 11, Loss: 0.6084, Train (Accuracy): 0.7028, Train (ROC-AUC): 0.7616, Test (Accuracy): 0.6542, Test (ROC-AUC): 0.7230

Training: 100%| | 131/131 [00:01<00:00, 112.71it/s]
Testing: 100%| | 131/131 [00:01<00:00, 130.78it/s]
Testing: 100%| | 44/44 [00:00<00:00, 133.01it/s]

Epoch: 12, Loss: 0.6024, Train (Accuracy): 0.7073, Train (ROC-AUC): 0.7667, Test (Accuracy): 0.6578, Test (ROC-AUC): 0.7259

Training: 100%| | 131/131 [00:01<00:00, 106.85it/s]
Testing: 100%| | 131/131 [00:00<00:00, 131.28it/s]
Testing: 100%| | 44/44 [00:00<00:00, 132.75it/s]

Epoch: 13, Loss: 0.5982, Train (Accuracy): 0.7121, Train (ROC-AUC): 0.7703, Test (Accuracy): 0.6643, Test (ROC-AUC): 0.7301

Training: 100%| | 131/131 [00:01<00:00, 114.22it/s]
Testing: 100%| | 131/131 [00:01<00:00, 130.60it/s]
Testing: 100%| | 44/44 [00:00<00:00, 136.32it/s]

Epoch: 14, Loss: 0.5974, Train (Accuracy): 0.7150, Train (ROC-AUC): 0.7746, Test (Accuracy): 0.6628, Test (ROC-AUC): 0.7324

Training: 100%| | 131/131 [00:01<00:00, 110.62it/s]
 Testing: 100%| | 131/131 [00:00<00:00, 136.14it/s]
 Testing: 100%| | 44/44 [00:00<00:00, 136.96it/s]

 Epoch: 15, Loss: 0.5928, Train (Accuracy): 0.6956, Train (ROC-AUC): 0.7809, Test (Accuracy): 0.6492, Test (ROC-AUC): 0.7297

 Training: 100%| | 131/131 [00:01<00:00, 108.64it/s]
 Testing: 100%| | 131/131 [00:00<00:00, 134.62it/s]
 Testing: 100%| | 44/44 [00:00<00:00, 131.58it/s]

 Epoch: 16, Loss: 0.5880, Train (Accuracy): 0.7207, Train (ROC-AUC): 0.7822, Test (Accuracy): 0.6664, Test (ROC-AUC): 0.7320

 Training: 100%| | 131/131 [00:01<00:00, 108.30it/s]
 Testing: 100%| | 131/131 [00:01<00:00, 130.81it/s]
 Testing: 100%| | 44/44 [00:00<00:00, 135.02it/s]

 Epoch: 17, Loss: 0.5875, Train (Accuracy): 0.7246, Train (ROC-AUC): 0.7848, Test (Accuracy): 0.6750, Test (ROC-AUC): 0.7351

 Training: 100%| | 131/131 [00:01<00:00, 110.45it/s]
 Testing: 100%| | 131/131 [00:00<00:00, 132.99it/s]
 Testing: 100%| | 44/44 [00:00<00:00, 137.70it/s]

 Epoch: 18, Loss: 0.5850, Train (Accuracy): 0.7246, Train (ROC-AUC): 0.7907, Test (Accuracy): 0.6686, Test (ROC-AUC): 0.7364

 Training: 100%| | 131/131 [00:01<00:00, 108.99it/s]
 Testing: 100%| | 131/131 [00:00<00:00, 133.31it/s]
 Testing: 100%| | 44/44 [00:00<00:00, 135.81it/s]

 Epoch: 19, Loss: 0.5825, Train (Accuracy): 0.7231, Train (ROC-AUC): 0.7932, Test (Accuracy): 0.6686, Test (ROC-AUC): 0.7367

 Training: 100%| | 131/131 [00:01<00:00, 115.42it/s]
 Testing: 100%| | 131/131 [00:00<00:00, 138.34it/s]
 Testing: 100%| | 44/44 [00:00<00:00, 135.65it/s]

 Epoch: 20, Loss: 0.5736, Train (Accuracy): 0.7279, Train (ROC-AUC): 0.7944, Test (Accuracy): 0.6786, Test (ROC-AUC): 0.7396

 Training: 100%| | 131/131 [00:01<00:00, 108.52it/s]
 Testing: 100%| | 131/131 [00:01<00:00, 118.69it/s]
 Testing: 100%| | 44/44 [00:00<00:00, 114.23it/s]

 Epoch: 21, Loss: 0.5792, Train (Accuracy): 0.7227, Train (ROC-AUC): 0.8002, Test (Accuracy): 0.6628, Test (ROC-AUC): 0.7354

 Training: 100%| | 131/131 [00:01<00:00, 113.60it/s]
 Testing: 100%| | 131/131 [00:01<00:00, 128.62it/s]
 Testing: 100%| | 44/44 [00:00<00:00, 134.58it/s]

 Epoch: 22, Loss: 0.5706, Train (Accuracy): 0.7363, Train (ROC-AUC): 0.7993, Test (Accuracy): 0.6679, Test (ROC-AUC): 0.7406

Training: 100%| | 131/131 [00:01<00:00, 113.01it/s]
Testing: 100%| | 131/131 [00:00<00:00, 135.88it/s]
Testing: 100%| | 44/44 [00:00<00:00, 135.77it/s]

Epoch: 23, Loss: 0.5695, Train (Accuracy): 0.7289, Train (ROC-AUC): 0.8053, Test (Accuracy): 0.6729, Test (ROC-AUC): 0.7372

Training: 100%| | 131/131 [00:01<00:00, 113.39it/s]
Testing: 100%| | 131/131 [00:00<00:00, 133.36it/s]
Testing: 100%| | 44/44 [00:00<00:00, 128.81it/s]

Epoch: 24, Loss: 0.5644, Train (Accuracy): 0.7358, Train (ROC-AUC): 0.8088, Test (Accuracy): 0.6729, Test (ROC-AUC): 0.7376

Training: 100%| | 131/131 [00:01<00:00, 109.89it/s]
Testing: 100%| | 131/131 [00:00<00:00, 134.71it/s]
Testing: 100%| | 44/44 [00:00<00:00, 131.81it/s]

Epoch: 25, Loss: 0.5593, Train (Accuracy): 0.7449, Train (ROC-AUC): 0.8091, Test (Accuracy): 0.6729, Test (ROC-AUC): 0.7388

