

CONNECTING CONSTRAINT SOLVERS TO AMPL

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AMPL Optimization

CPAIOR 2013, Yorktown Heights, NY, USA May 18-22, 2013

WHY AMPL?

- **AMPL** is a popular modeling system
 - used in businesses, government agencies, and academic institutions (over 100 courses in 2012)
 - large community (~ 1,400 members in **AMPL Google Group** alone)
 - the most popular input format on **NEOS** (> 200,000 or 57% submissions in 2012)
- AMPL is high-level, solver-independent and efficient.
- Supports a variety of solvers and problem types: linear, mixed integer, quadratic, second-order cone, nonlinear, complementarity problems and more.

HISTORY OF CP SUPPORT IN AMPL

- 1996: first experiments with adding logic programming features to AMPL.
- Fourer (1998). *Extending a General-Purpose Algebraic Modeling Language to Combinatorial Optimization: A Logic Programming Approach* [1]
- Fourer and Gay (2001). *Hooking a Constraint Programming Solver to an Algebraic Modeling Language*
- Fourer and Gay (2002). *Extending an Algebraic Modeling Language to Support Constraint Programming* [2]
- First **IBM/ILOG CP Optimizer** was connected.
- Gecode was connected in 2012, JaCoP - in early 2013.

SUPPORTED CP CONSTRUCTS

- Logical operators: and, or, not; iterated exists, forall
- Conditional operators: if-then, if-then-else, ==>, ==> else, <==, <==>
- Counting operators: iterated count, atmost, atleast, exactly, numberof
- Pairwise operators: alldiff

See <http://www.ampl.com/NEW/LOGIC/>

CONNECTED CP SOLVERS

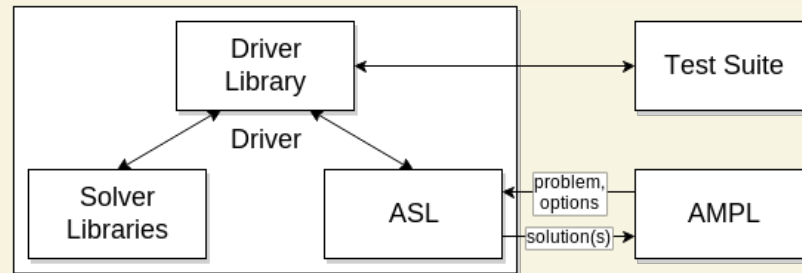
- Solvers:
 - ilogcp: **IBM/ILOG CP Optimizer**
 - gecode: **Generic constraint development environment**. **New:** Gecode 4.0, more solver options
 - **New:** jacop: **Java constraint solver**
- How to get:
 - Ilogcp is available to all CPLEX-for-AMPL users
 - AMPL Gecode and JaCoP (soon) downloads:
<https://code.google.com/p/ampl/>
 - Source code: <https://github.com/vitaut/ampl-solvers/gecode> | [solvers/ilogcp](https://github.com/vitaut/ampl-solvers/ilogcp) | [solvers/jacop](https://github.com/vitaut/ampl-solvers/jacop)

AMPL SOLVER LIBRARY

AMPL Solver Library (ASL) is an open-source library for connecting solvers to AMPL.

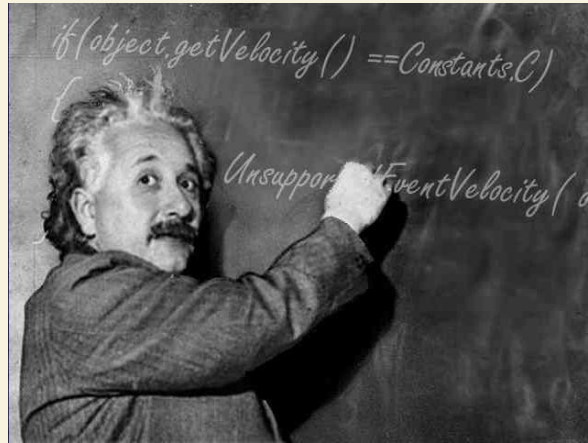
- C interface:
 - described in **Hooking Your Solver to AMPL**
 - used by most non-CP solvers
- **C++ interface:**
 - makes connecting new solvers super easy
 - type-safe: no casts needed when working with expression trees
 - efficient: no overhead compared to the C interface
 - used by the gecode, ilogcp and jacop (via JNI) drivers

AMPL SOLVER ARCHITECTURE



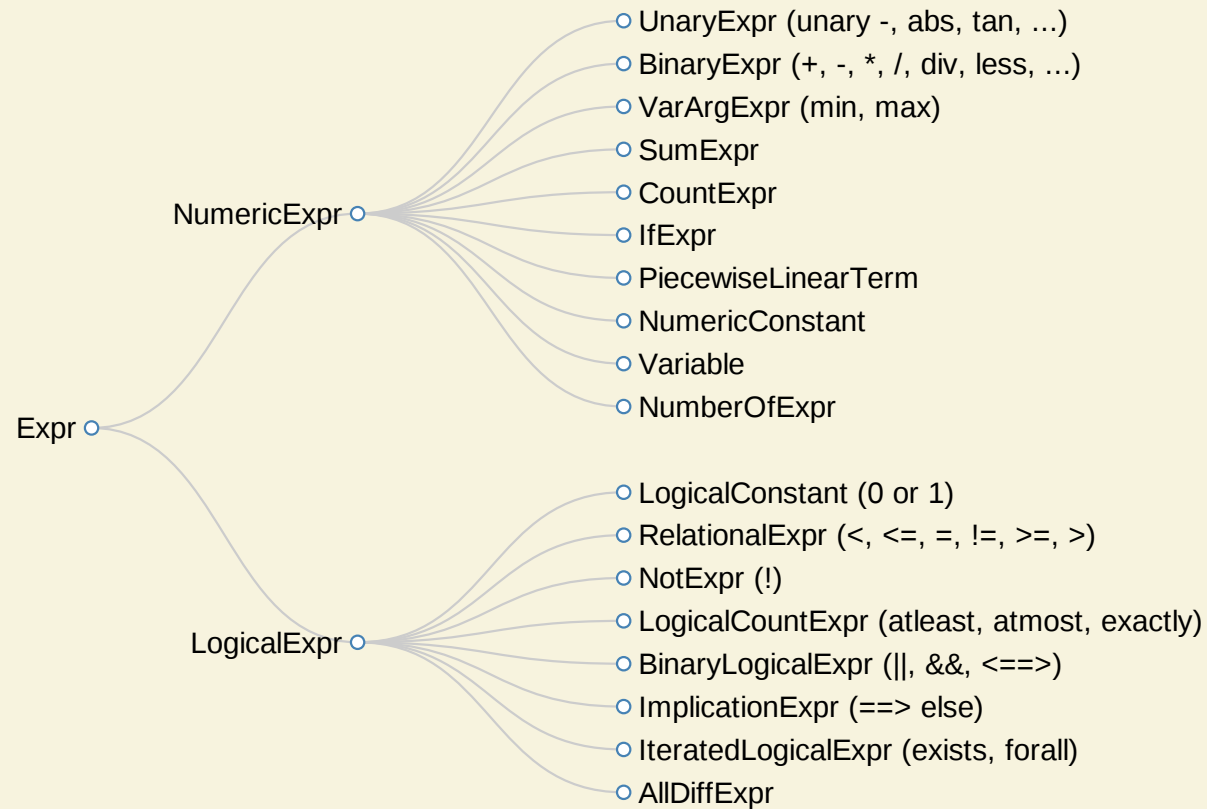
- Driver library is optional but facilitates testing.
- The test suite is used to verify correctness of driver implementation.
- The test suite is solver independent and can be reused when connecting a new solver.

CONNECTING JAVA SOLVERS



- JNI allows using ASL via the C++ API
- The JaCoP driver can be used as an example
- Initialization is tricky on Windows (delay loading of `jvm.dll`, check installation path in registry, ...)

EXPRESSION TREES



CONVERTING NUMERIC EXPRESSIONS

```
IloExpr VisitNumericConstant(NumericConstant n) {  
    return IloExpr(env_, n.value());  
}  
  
IloExpr VisitVariable(Variable v) {  
    return vars_[v.index()];  
}  
  
IloExpr VisitPlus(BinaryExpr e) {  
    return Visit(e.lhs()) + Visit(e.rhs());  
}  
  
IloExpr VisitPow(BinaryExpr e) {  
    return IloPower(Visit(e.lhs()), Visit(e.rhs()));  
}  
  
IloExpr VisitSum(SumExpr e) {  
    IloExpr sum(env_);  
    for (auto arg: e) // Iterating over arguments (C++11)  
        sum += Visit(arg);  
    return sum;  
}
```

CONVERTING LOGICAL EXPRESSIONS

```
IloConstraint VisitLogicalConstant(LogicalConstant c) {  
    return IloNumVar(env_, 1, 1) == c.value();  
}  
  
IloConstraint VisitEqual(RelationalExpr e) {  
    return Visit(e.lhs()) == Visit(e.rhs());  
}  
  
IloConstraint VisitGreater(RelationalExpr e) {  
    return Visit(e.lhs()) > Visit(e.rhs());  
}  
  
IloConstraint VisitAnd(BinaryLogicalExpr e) {  
    return Visit(e.lhs()) && Visit(e.rhs());  
}  
  
IloConstraint VisitExists(IteratedLogicalExpr e) {  
    IloOr disjunction(env_);  
    for (auto arg: e) // Iterating over arguments (C++11)  
        disjunction.add(Visit(arg));  
    return disjunction;  
}
```

PERFORMANCE CONSIDERATIONS

Map AMPL expressions into the most efficient solver equivalents.

Examples:

- `numberof` with constant values
-> `IloDistribute (ilogcp)`
controlled by the `usenumerofof` option
- `if logical-expr then 1 (else 0)`
-> channel constraint (`gecode`)

SUPPORTING MULTIPLE SOLVERS

- Separate hierarchies for logical and numeric expressions (ilogcp and gecode) are handled easily
- Possible to deal with more complex expression hierarchies, but with more efforts
- Not necessary to convert all expressions, solver will report an error when unhandled expression is encountered and exit gracefully.

EXAMPLES

Disjunctive constraint:

```
subject to Multi_Min_Ship {i in ORIG, j in DEST}:  
    sum {p in PROD} Trans[i,j,p] = 0 or  
    minload <= sum {p in PROD} Trans[i,j,p] <= limit[i,j];
```

Implication:

```
subject to Multi_Min_Ship {i in ORIG, j in DEST}:  
    sum {p in PROD} Trans[i,j,p] > 0 ==>  
        minload <= sum {p in PROD} Trans[i,j,p] <= limit[i,j];
```

SCHEDULING EXAMPLE WITH NUMBEROF

```
param n integer > 0;

set JOBS := 1..n;
set MACHINES := 1..n;

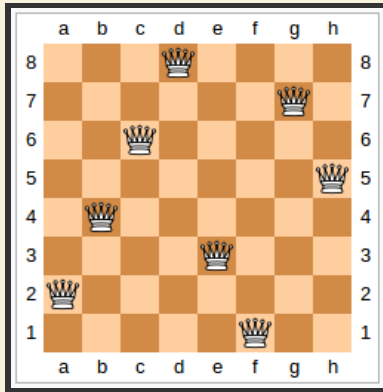
param cap {MACHINES} integer >= 0;
param cost {JOBS,MACHINES} > 0;

var MachineForJob {JOBS} integer >= 1, <= n;

minimize TotalCost:
    sum {j in JOBS, k in MACHINES}
        if MachineForJob[j] = k then cost[j,k];

subj to CapacityOfMachine {k in MACHINES}:
    numberof k in ({j in JOBS} MachineForJob[j]) <= cap[k];
```


N QUEENS EXAMPLE WITH ALLDIFF



```
# Place n queens on an n by n board  
# so that no two queens can attack  
# each other (nqueens.mod).
```

```
param n integer > 0;  
var Row {1..n} integer >= 1 <= n;
```

```
subj to c1: alldiff ({j in 1..n} Row[j]);  
subj to c2: alldiff ({j in 1..n} Row[j]+j);  
subj to c3: alldiff ({j in 1..n} Row[j]-j);
```

More examples available at
<http://www.ampl.com/NEW/LOGIC/examples.html>.

USAGE EXAMPLE

```
ampl: model nqueens-mip.mod
ampl: let n := 100;
ampl: option solver cplex;
ampl: solve;
CPLEX 12.4.0.0: optimal integer solution; objective 0
1416 MIP simplex iterations
0 branch-and-bound nodes
Objective = find a feasible point.
ampl: print _solve_time;
2.7680000000000002
ampl: model nqueens-cp.mod
ampl: option solver ilogcp;
ampl: solve;
ilogcp 12.4.0: feasible solution
1704 choice points, 781 fails
ampl: print _solve_time;
0.11599999999999966
ampl: option gencode_options 'val_branching=med';
ampl: solve;
gencode 4.0.0: val_branching=med
gencode 4.0.0: feasible solution
18382 nodes, 9145 fails
ampl: print _solve_time;
0.076000000000000273
```

SUMMARY

- AMPL now supports multiple constraint programming solvers.
- Connecting new solvers is super easy especially with the new C++ API.
- Java solvers are supported as well.

LINKS

- AMPL Logic and Constraint Programming Extensions:
<http://www.ampl.com/NEW/LOGIC/>
- Trial version of AMPL with IBM/ILOG CP:
<http://www.ampl.com/trial.html>
- Downloads for open-source AMPL solvers and libraries including Gecode: <https://code.google.com/p/ampl/>
- AMPL models by Hakan Kjellerstrand including 100 new CP models: <http://www.hakank.org/ampl/>
- Source code for ilogcp, gecode and jacop interfaces on GitHub: <https://github.com/vitaut/ampl>