# CS 466/566 Introduction to Deep Learning

Lecture 7 – Mid-class Summary

#### Neural Networks

- Capacity of a neuron and neural network
  - Perceptron: A linear neuron
  - Activation functions: required non-linearity
- Learning: Training a Neural Network
  - Cost function for regression
  - Cost function for classification
  - Finding weights: The Learning Algorithm
- Training Problems, Solutions
  - Underfitting / Overfitting / Model Complexity
  - Bias / Variance of a trained network
  - Simplifying the Model (ConvNet)
    - Local Receptive Fields
    - Weight Sharing
  - Regularization
- Recurrent Neural Networks
  - Word Embeddings

#### Types of Machine Learning

- Supervised Machine Learning:
  - Regression
  - Classification
    - Two-class classification Logistic Regression
    - Multi-class classification Multinomial Logistic Regression

#### Unsupervised Machine learning:

- Principal Component Analysis (PCA)
- Standard Auto-encoders
- Deep (stacked) Auto-encoders
- Convolutional Auto-encoders
- Denoising Auto-encoders
- Variational Auto-encoders
- Reinforcement Learning

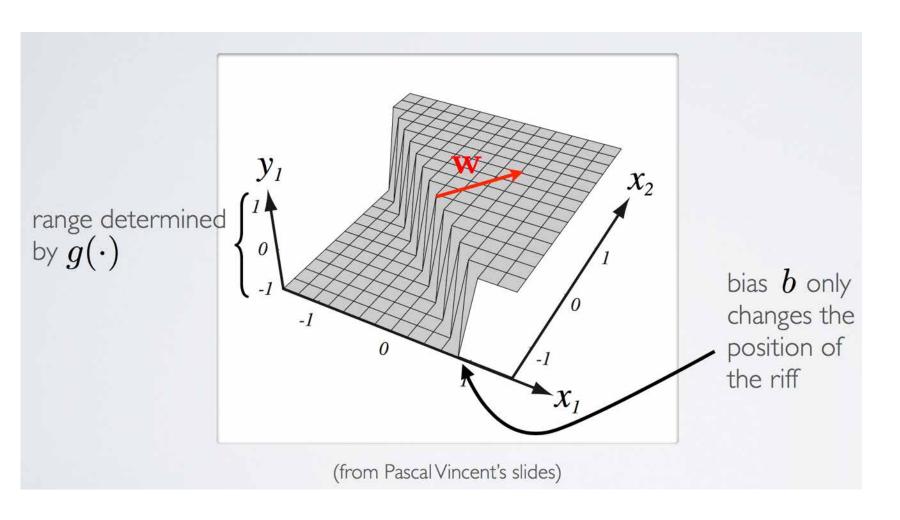
### Types of Models

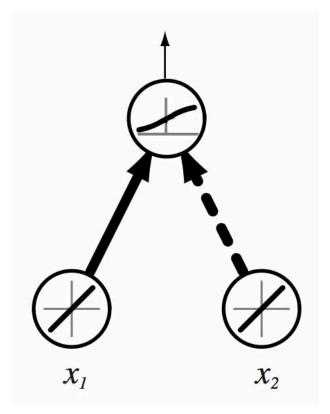
• Generative vs Discriminative Models

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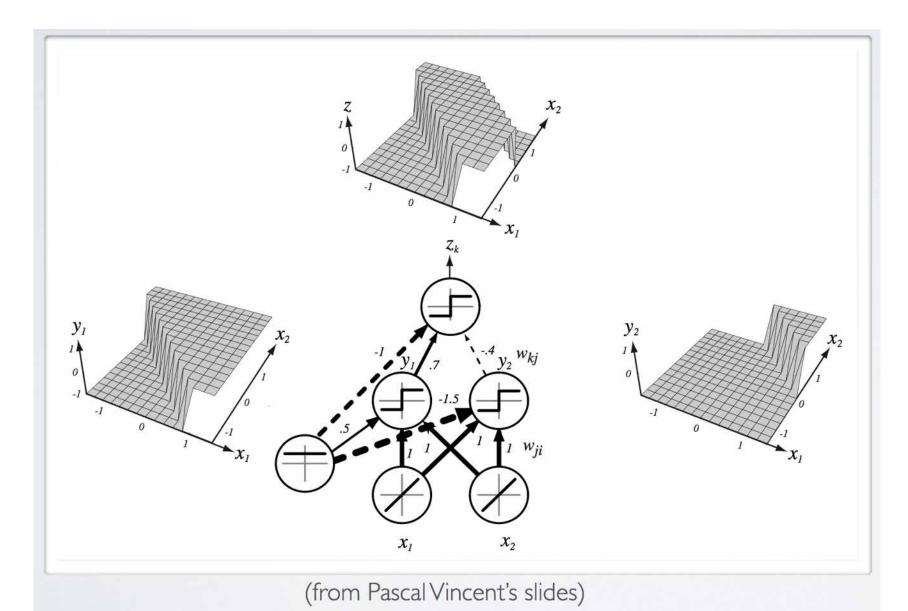
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# Capacity of a Neuron

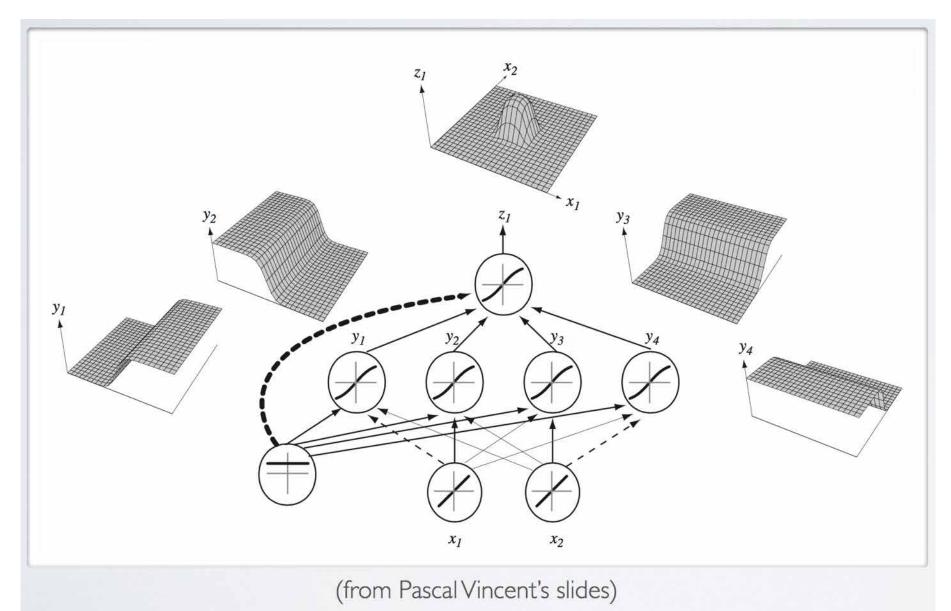




# Capacity of a Neural Network



# Capacity of a Neural Network

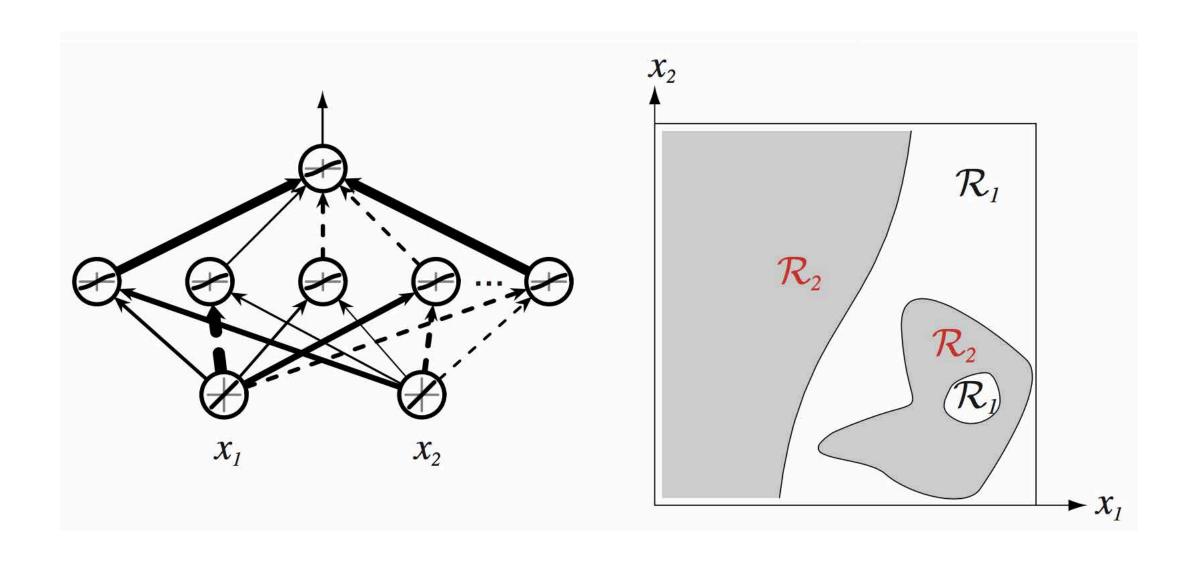


### Activation functions

Name	Plot	Equation	Derivative
Identity		f(x) = x	f'(x) = 1
Binary step		$f(x) = \begin{cases} 0 & \text{for } x < 0 \\ 1 & \text{for } x \ge 0 \end{cases}$	$f'(x) = \begin{cases} 0 & \text{for } x \neq 0 \\ ? & \text{for } x = 0 \end{cases}$
Logistic (a.k.a Soft step)		$f(x) = \frac{1}{1 + e^{-x}}$	f'(x) = f(x)(1 - f(x))
TanH		$f(x) = \tanh(x) = \frac{2}{1 + e^{-2x}} - 1$	$f'(x) = 1 - f(x)^2$
ArcTan		$f(x) = \tan^{-1}(x)$	$f'(x) = \frac{1}{x^2 + 1}$
Rectified Linear Unit (ReLU)		$f(x) = \begin{cases} 0 & \text{for } x < 0 \\ x & \text{for } x \ge 0 \end{cases}$	$f'(x) = \begin{cases} 0 & \text{for } x < 0 \\ 1 & \text{for } x \ge 0 \end{cases}$
Parameteric Rectified Linear Unit (PReLU) <sup>[2]</sup>		$f(x) = \begin{cases} \alpha x & \text{for } x < 0 \\ x & \text{for } x \ge 0 \end{cases}$	$f'(x) = \begin{cases} \alpha & \text{for } x < 0 \\ 1 & \text{for } x \ge 0 \end{cases}$
Exponential Linear Unit (ELU) <sup>[3]</sup>		$f(x) = \begin{cases} \alpha(e^x - 1) & \text{for } x < 0 \\ x & \text{for } x \ge 0 \end{cases}$	$f'(x) = \begin{cases} f(x) + \alpha & \text{for } x < 0 \\ 1 & \text{for } x \ge 0 \end{cases}$
SoftPlus		$f(x) = \log_e(1 + e^x)$	$f'(x) = \frac{1}{1 + e^{-x}}$

- Activation functions are the things that give non-linear separation power to Neural Networks.
- Do not confuse activations of hidden layer neurons and logistic regression.
- For a binomial (two class)
   classification problem, we may choose
   sigmoid function both for hidden layer
   activation and output layer at the
   same time.
- This doesn't mean that they are put there for the same purpose.

# Capacity of a Neural Network (Classification)



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• Generative vs Discriminative Models

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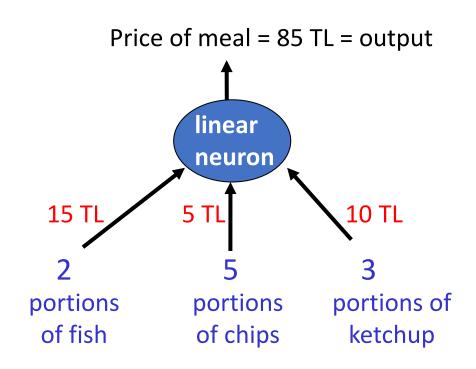
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Generative vs Discriminative Models

# A toy example to illustrate regression

- Each day you get lunch at the cafeteria.
  - Your diet consists of fish, chips, and ketchup.
  - You get several portions of each.
- The cashier only tells you the total price of the meal
  - After several days, you should be able to figure out the price of each portion.
- The iterative approach: Start with random guesses for the prices and then adjust them to get a better fit to the observed prices of whole meals.

# The true weights used by the cashier



### **Cost Functions**

- Cost function for regression
  - Quadratic cost: Also known as mean squared error or sum squared error

$$J(\theta) = \sum_{i} \left( y^{(i)} - h_{\theta}(x^{(i)}) \right)^{2}$$

- Cost function for classification (cross-entropy)
  - Two-class Classification = Logistic Regression:

$$J(\theta) = -\sum_{i} \left( y^{(i)} \log \left( h_{\theta}(x^{(i)}) \right) + \left( 1 - y^{(i)} \right) \log \left( 1 - h_{\theta}(x^{(i)}) \right) \right)$$

- Multi-class Classification = Multinomial Logistic Regression:
  - Apply Softmax to any vector **z** such that:  $z \to \left\{ \sum_{i} \frac{exp(z_i)}{\sum_{k} exp(z_k)} \right\}$

$$J(\theta) = \left\{ -\sum_{i} \left( y^{(i)} \log \left( h_{\theta}(x^{(i)}) \right) \right) \right\}$$

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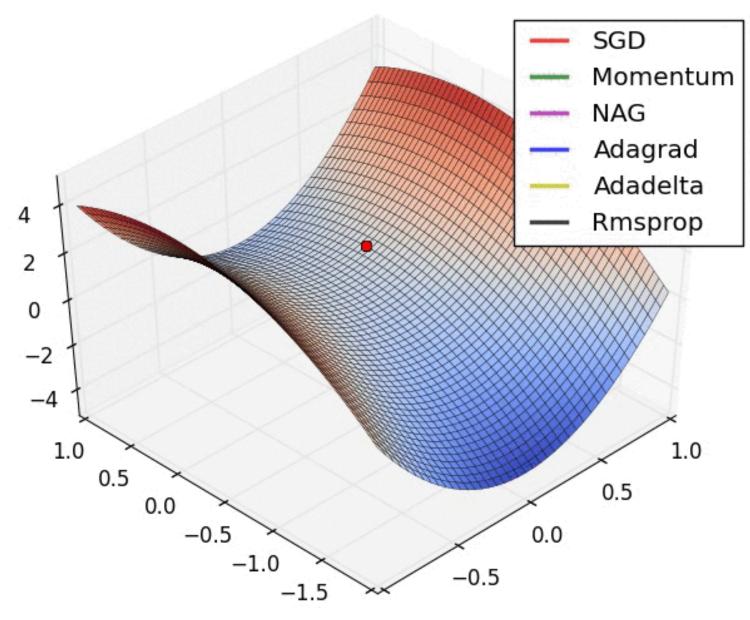
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Generative vs Discriminative Models

## Learning: Try to find minima of cost function



- Many training algorithms exist
  - Gradient Descent (Batch)
  - Stochastic Gradient Descent (online)
  - Minibatch Gradient Descent
- Learning Rate

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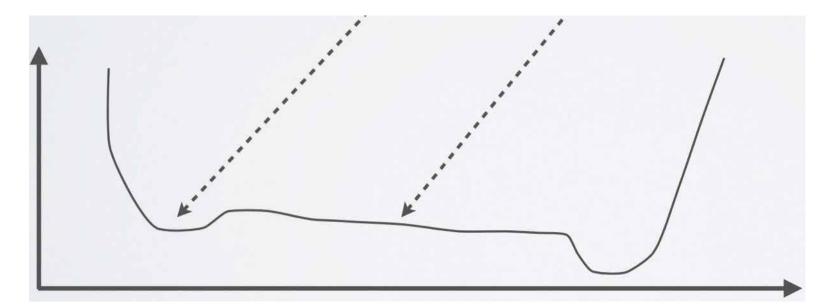
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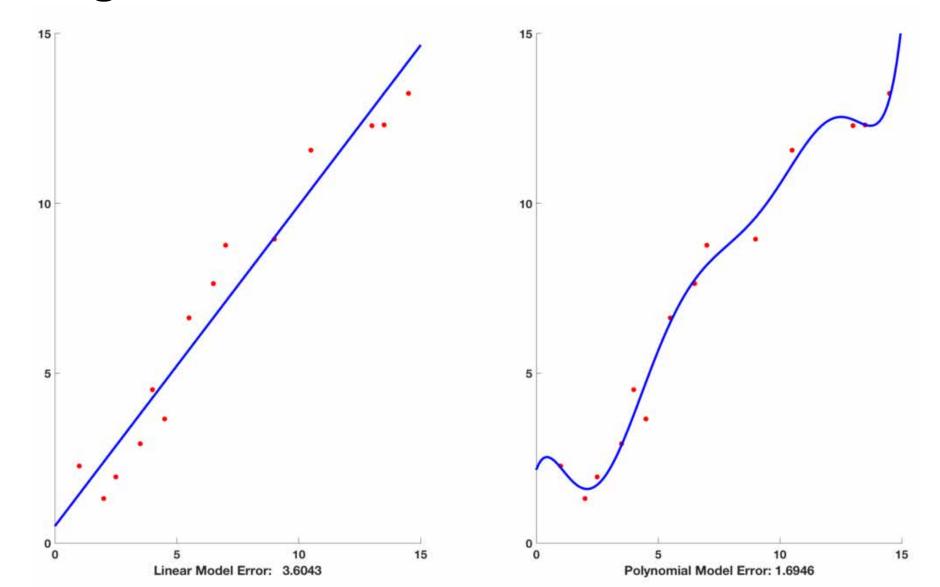
Generative vs Discriminative Models

# Walking on the landscape of cost function

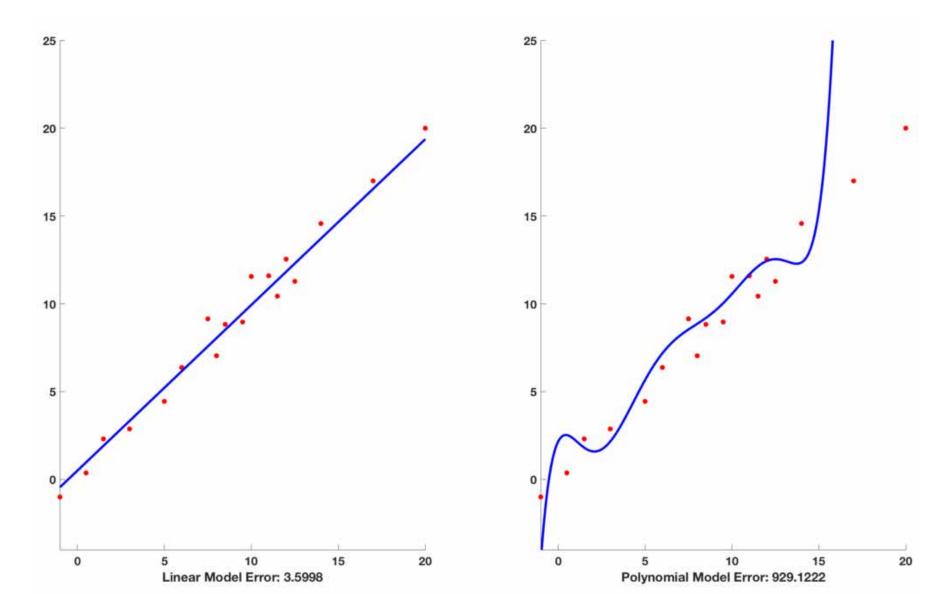
- there isn't a single global optimum (non-convex optimization)
  - we can permute the hidden units (with their connections) and get the same function
  - we say that the hidden unit parameters are not identifiable
  - Optimization can get stuck in local minimum or plateaus



# Training Set Performance



### Test Set Performance



# Bias / Variance

- Linear model had a higher bias.
- Polynomial model suffers from a different problem. The model depends a lot on the choice of training data.
- If you change the data slightly, the error will swing widely.
- Therefore, the model is said to have high variance.
- To keep the **bias** low, we need a complex model (e.g. a higher degree polynomial)
- But a complex model has a tendency to overfit and increase the variance.

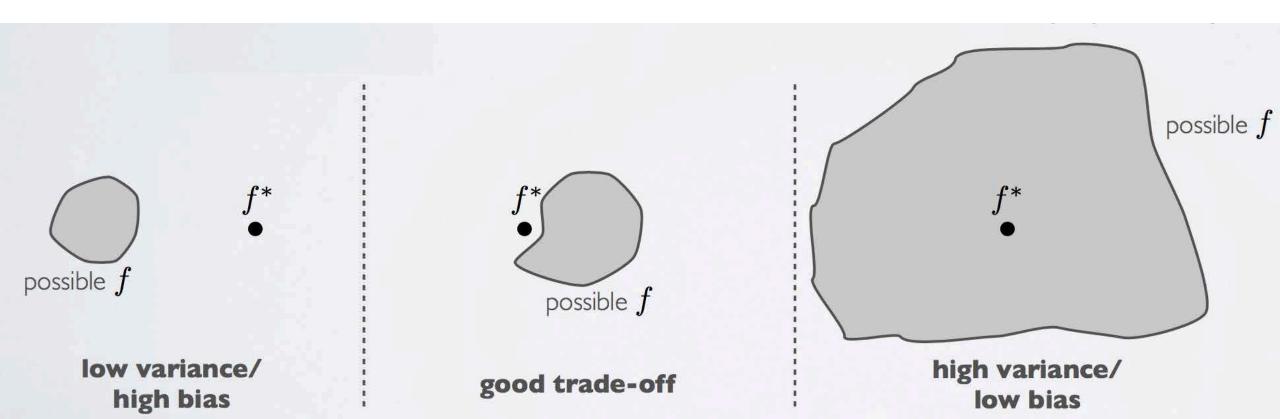
# Underfitting, Overfitting: Knowing when to stop

• To select the number of epochs, stop training when validation set error increases (with some look ahead)

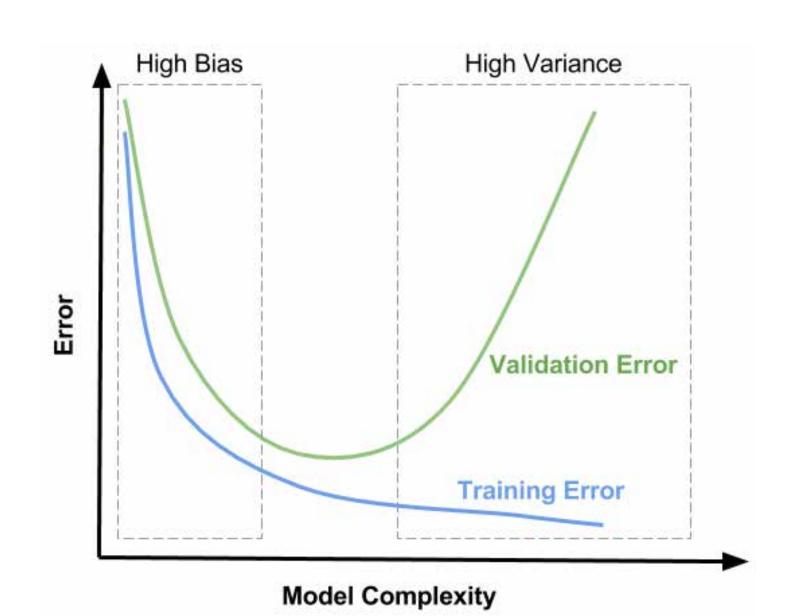


### Bias – Variance Trade-off

- Variance of trained model: does it vary a lot if the training set changes?
- Bias of trained model: the average model close to the true solution
- Generalization error: (can be seen as) the sum of the (squared) bias and variance



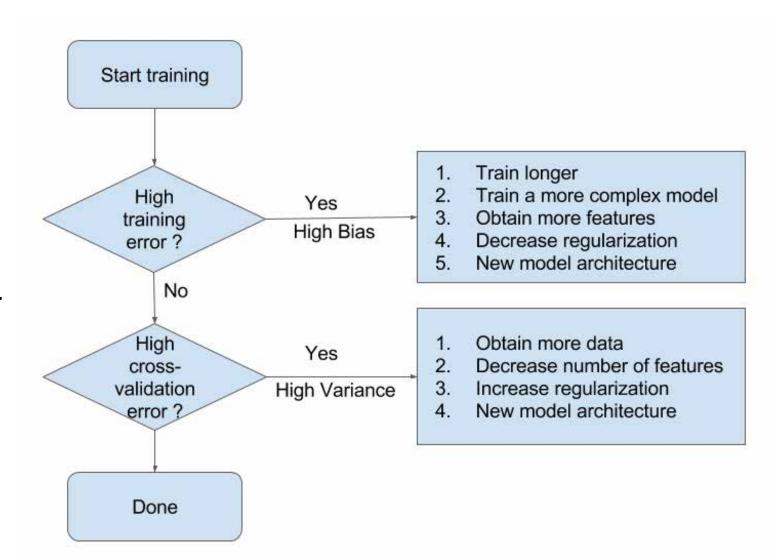
### Bias – Variance Trade-off



### How to detect?

- How to detect a high bias problem?
  - High training error.
  - Validation error is similar in magnitude to the training error.

- How to detect a high variance problem?
  - Low training error
  - Very high Validation error



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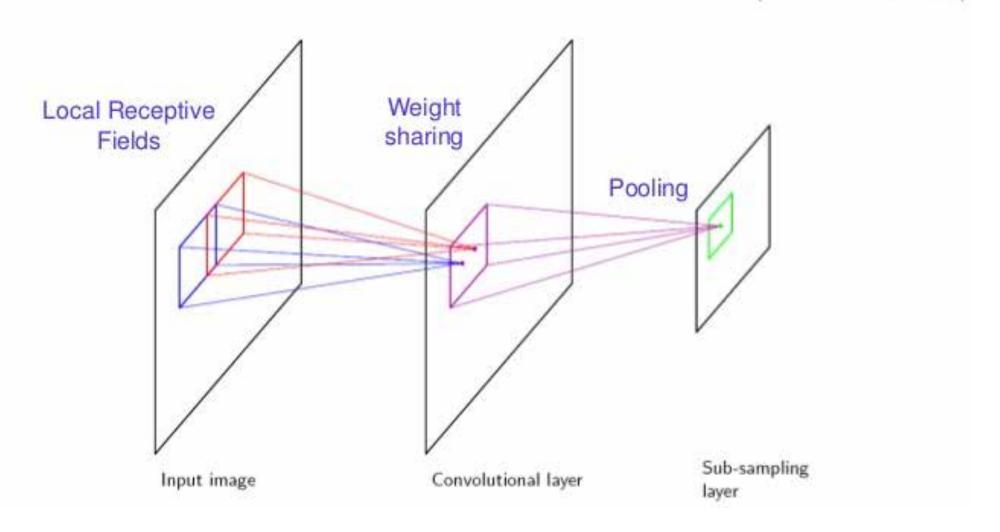
## 1<sup>st</sup> simplification: Local Receptive Fields

- Consider a 2D representation of input neurons (e.g. M-NIST data)
- Consider a specific neuron in the hidden layer.
- Now, it will be connected to a local neighborhood only
  - Instead of connected it to each and every input

input neurons hidden neuron 00000

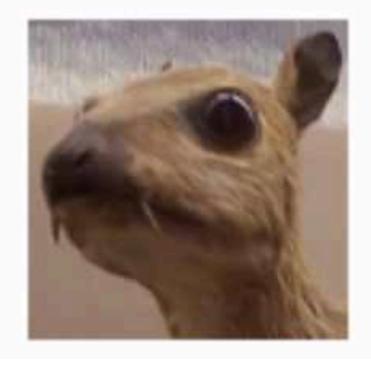
# 2<sup>nd</sup> Simplification: Shared Weights

(LeCun et al., 1989)

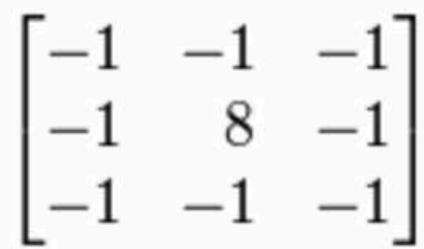


### Recall: Convolution

# Input image



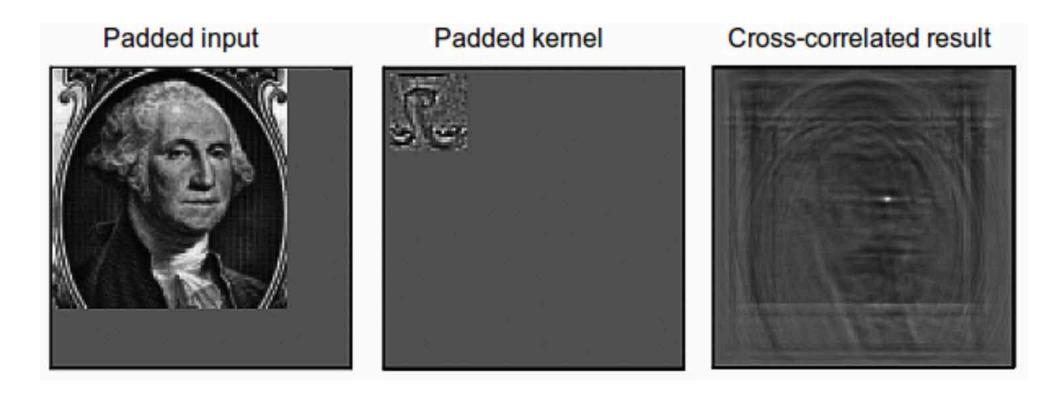
# Convolution Kernel



## Feature map

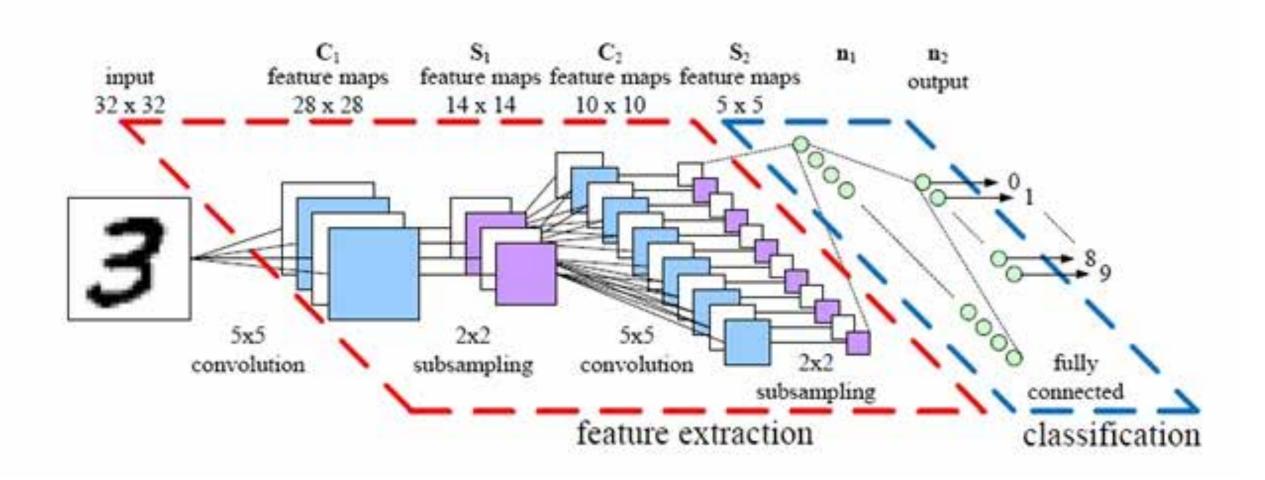


### Convolutional Filters



Convolutional filters can be interpreted as feature detectors, that is, the input (feature map) is filtered for a certain feature (the kernel) and the output is large if the feature is detected in the image.

# An example CNN pipeline



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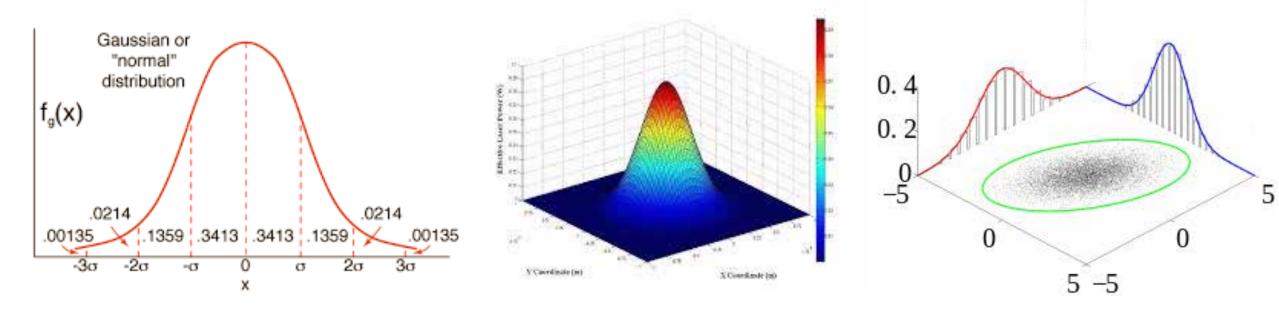
Generative vs Discriminative Models

# Regularization: L2 Regularization

• Penalizes the gradient term in back-prop algorithm:

$$\Omega(\boldsymbol{\theta}) = \sum_{k} \sum_{i} \sum_{j} \left( W_{i,j}^{(k)} \right)^{2} = \sum_{k} ||\mathbf{W}^{(k)}||_{F}^{2}$$

- Gradient:  $\nabla_{\mathbf{W}^{(k)}}\Omega(\boldsymbol{\theta}) = 2\mathbf{W}^{(k)}$ 
  - Only applied on weights, not biases
  - Can be interpreted as having a Gaussian Prior over weight values.

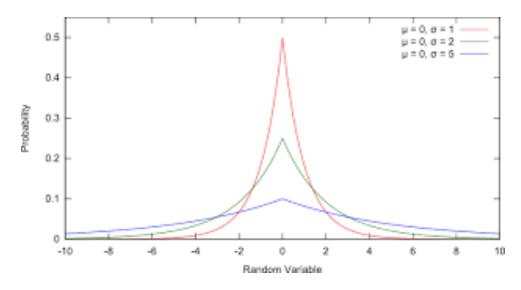


### Regularization: L1 Regularization

• Penalizes the gradient term in back-prop algorithm:

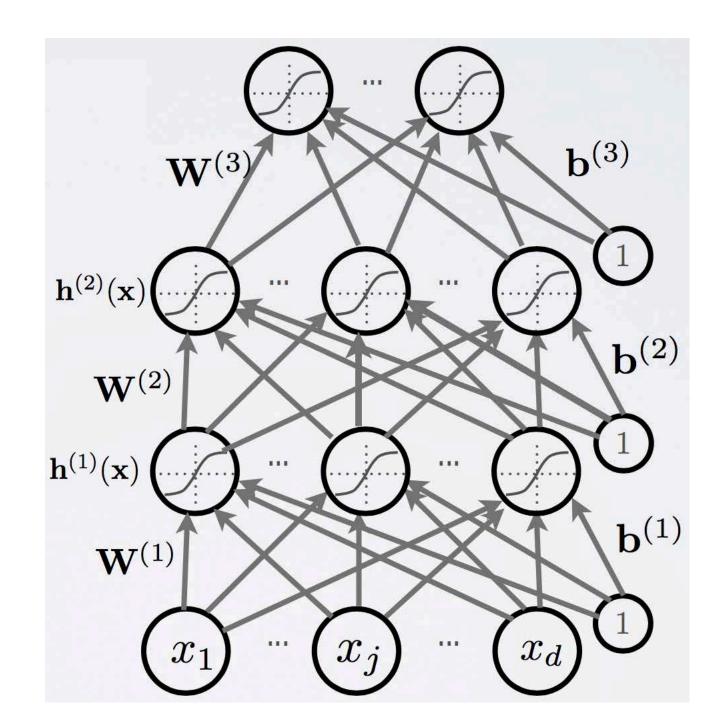
$$\Omega(\boldsymbol{\theta}) = \sum_{k} \sum_{i} \sum_{j} |W_{i,j}^{(k)}|$$

- Gradient:  $\nabla_{\mathbf{W}^{(k)}}\Omega(\boldsymbol{\theta}) = \operatorname{sign}(\mathbf{W}^{(k)})$ 
  - Only applied on weights, not biases (again)
  - Unlike L2, L1 regularization will make some of the weights exactly 0.
  - Can be interpreted as having a Laplacian Prior over weight values.



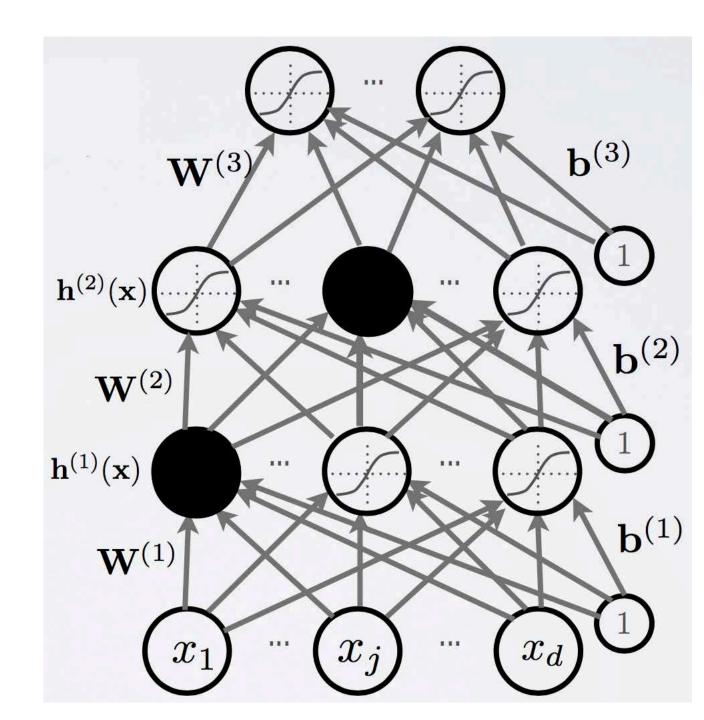
# Regularization: Dropout

- Idea: Cripple neural network by removing hidden units randomly.
  - Each hidden unit's activation is set to 0 with a probability, independently.
  - Usually 0.5 works well.



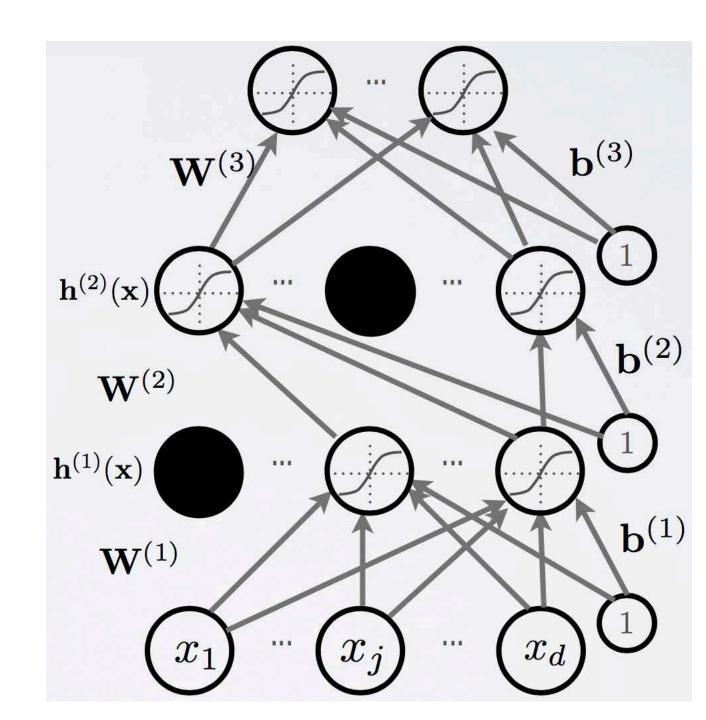
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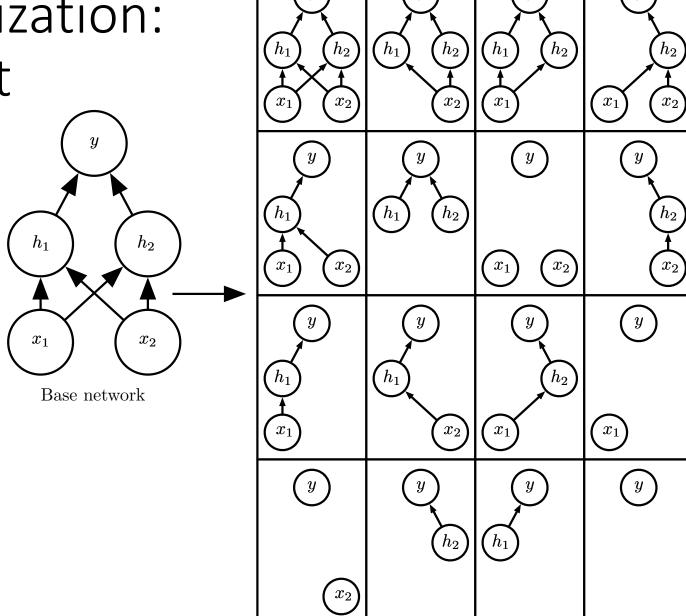


# Regularization: Dropout

- Idea: Cripple neural network by removing hidden units randomly.
  - Hidden units cannot cooperate with each other in a specific layer.
  - Therefore, hidden units must be more generally useful.

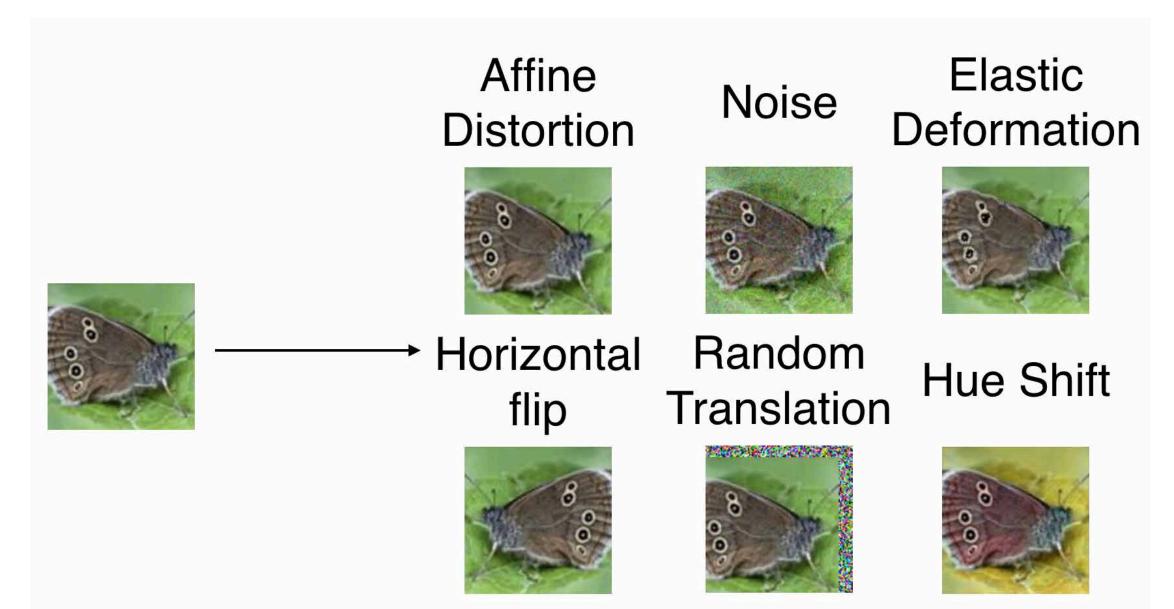


# Regularization: Dropout



Ensemble of subnetworks

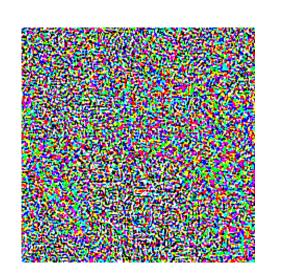
# Regularization: Dataset Augmentation



# Still Have a Problem: Adversarial Examples



$$+.007 \times$$



=



$$\boldsymbol{x}$$

y = "panda" w/57.7% confidence

 $sign(\nabla_{\boldsymbol{x}}J(\boldsymbol{\theta},\boldsymbol{x},y))$ 

"nematode" w/8.2% confidence

 $m{x} + \\ \epsilon \operatorname{sign}(\nabla_{m{x}} J(m{ heta}, m{x}, y)) \\ \text{"gibbon"} \\ \text{w/ 99.3 \%} \\ \text{confidence}$ 

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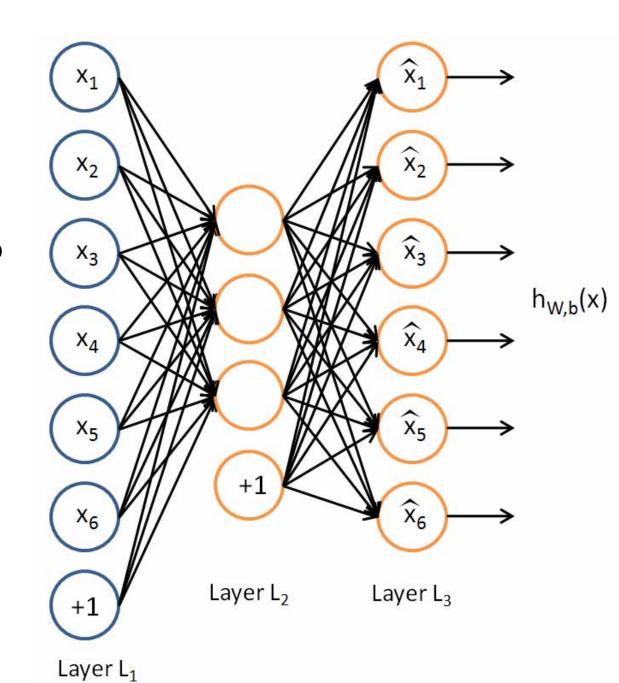
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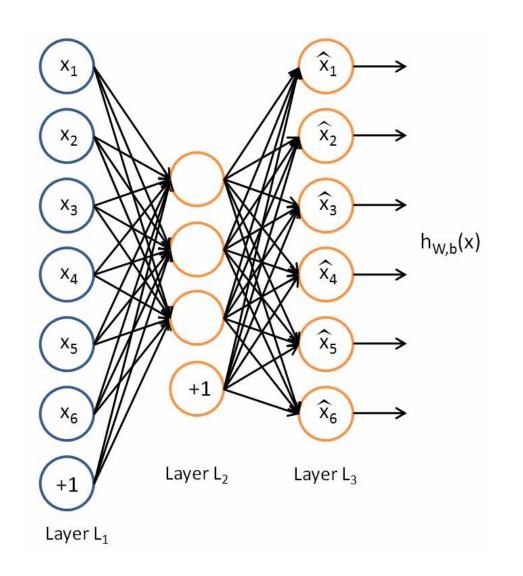
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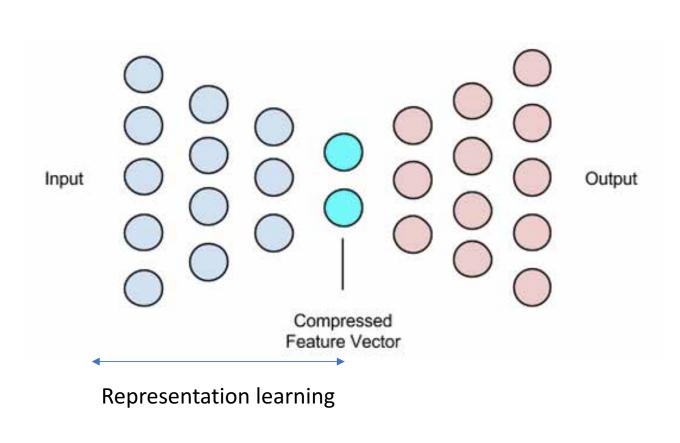
## Auto-encoders

- What was hard about training deep MLPs?
- An auto-encoder tries to match the input to the output!
- Basically, does nothing, right?
- Not right.
- It depends on the number of neurons in hidden layer.

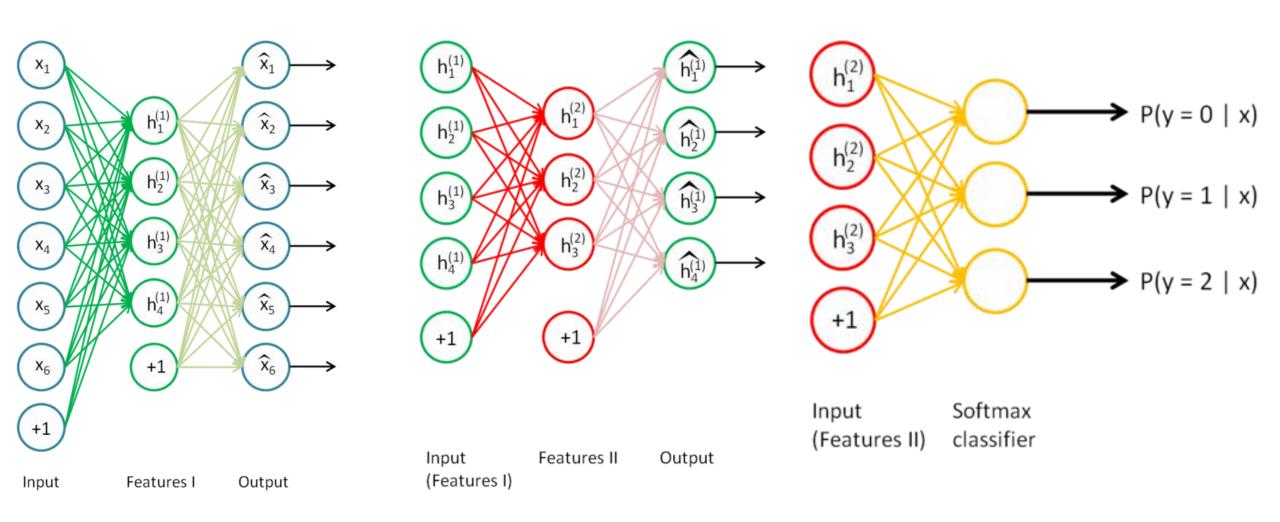


# Auto-encoders / Deep Auto-encoders





## Stacked Auto-Encoders



Use learned weights as initial weights of real training!

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## Denoising Auto-encoders

 Denoising auto-encoders attempt to address identity-function risk by randomly corrupting input (i.e. introducing noise) that the auto-encoder must then reconstruct, or denoise.

- Parameters and Corruption level
  - The amount of noise to apply to the input takes the form of a percentage. Typically, 30% is fine
  - if you have very little data, you may want to consider adding more corruption.

# Color Constancy: This picture has no red pixels.



Why do we see red in this picture?

## "The Dress"

- "The dress" is a photo that became a viral Internet picture on 26 February 2015, when viewers disagreed over whether the item of clothing depicted was "black and blue" or "white and gold".
- The phenomenon revealed differences in human color perception which have been the subject of ongoing scientific investigation in <u>neuroscience</u> and <u>vision</u> <u>science</u>, with a number of papers published in peer-reviewed science journals.



#### Neural Networks

- Capacity of a neuron and neural network
  - Perceptron: A linear neuron
  - Activation functions: required non-linearity
- Learning: Training a Neural Network
  - Cost function for regression
  - Cost function for classification
  - Finding weights: The Learning Algorithm
- Training Problems, Solutions
  - Underfitting / Overfitting / Model Complexity
  - Bias / Variance of a trained network
  - Simplifying the Model (ConvNet)
    - Local Receptive Fields
    - Weight Sharing
  - Regularization
- Recurrent Neural Networks
  - Word Embeddings

## Types of Machine Learning

- Supervised Machine Learning:
  - Regression
  - Classification
    - Two-class classification Logistic Regression
    - Multi-class classification Multinomial Logistic Regression
- Unsupervised Machine learning:
  - Principal Component Analysis (PCA)
  - Standard Auto-encoders
  - Deep (stacked) Auto-encoders
  - Convolutional Auto-encoders
  - Denoising Auto-encoders
  - Variational Auto-encoders
- Reinforcement Learning

## Types of Models

## Discriminative vs Generative Models

- Discriminative Models
  - Discriminative models learn the (hard or soft) boundary between classes
- Generative Models
  - providing a model of how the data is actually generated.
  - model the distribution of individual classes
  - often outperforms discriminative models on smaller datasets because their generative assumptions place some structure on your model that prevent overfitting.

# Generative Adversarial Networks (GANs)

- They have recently been used
  - to model very basic patterns of motion in video.
  - to reconstruct 3D models of objects from images.
  - to improve astronomical images.

#### • Downsides:

- the images are generated off some arbitrary noise. If you wanted to generate a
  picture with specific features, there's no way of determining which initial noise
  values would produce that picture, other than searching over the entire
  distribution.
- It only discriminates between "real" and "fake" images. There's no constraints that an image of a cat has to look like a cat. This leads to results where there's no actual object in a generated image, but the style just looks like picture.
- How to solve these problems?

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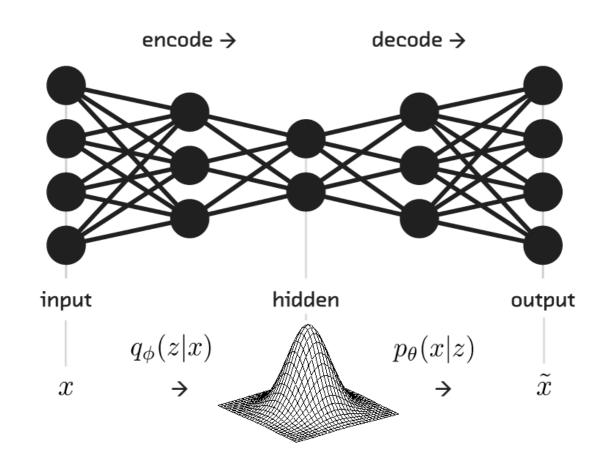
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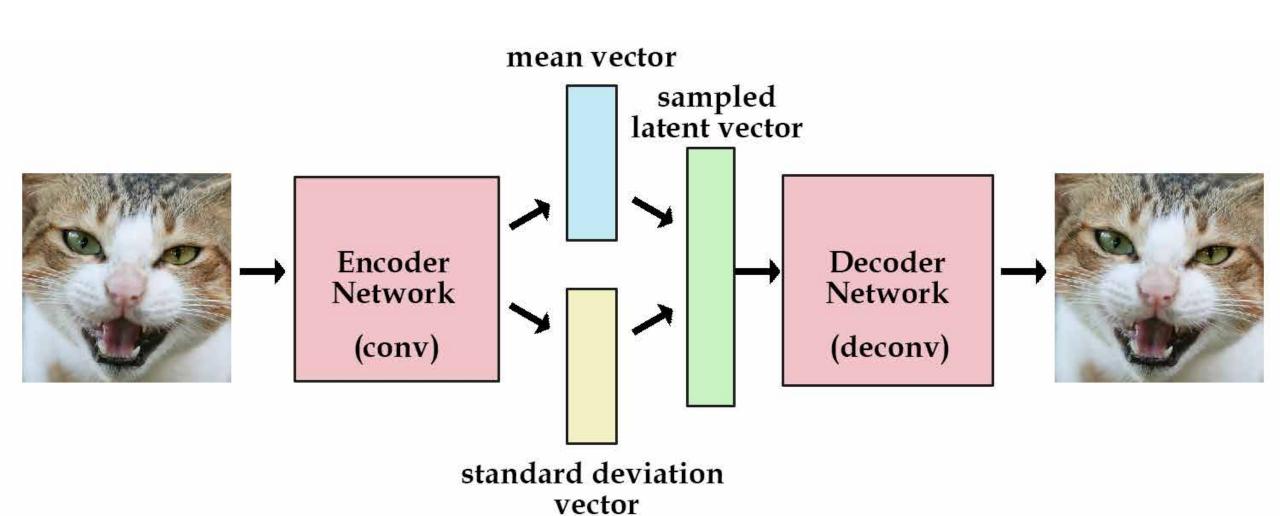
## Types of Models

## Variational Auto-encoders (VAEs)

the lovechild of Bayesian inference and unsupervised deep learning

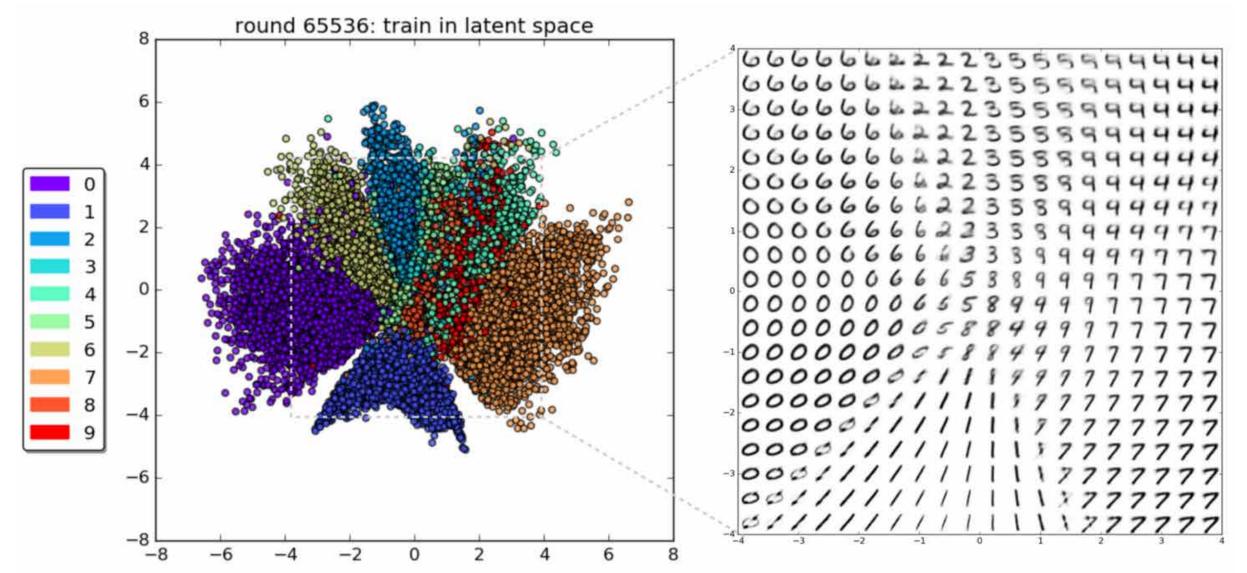


# Variational Auto-encoders (VAEs) re-parameterization trick



## Variational Auto-encoders (VAEs) - MNIST 2D embedding

how optimizing the encoder and decoder in tandem enables efficient pairing of inference and generation



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## Types of Models

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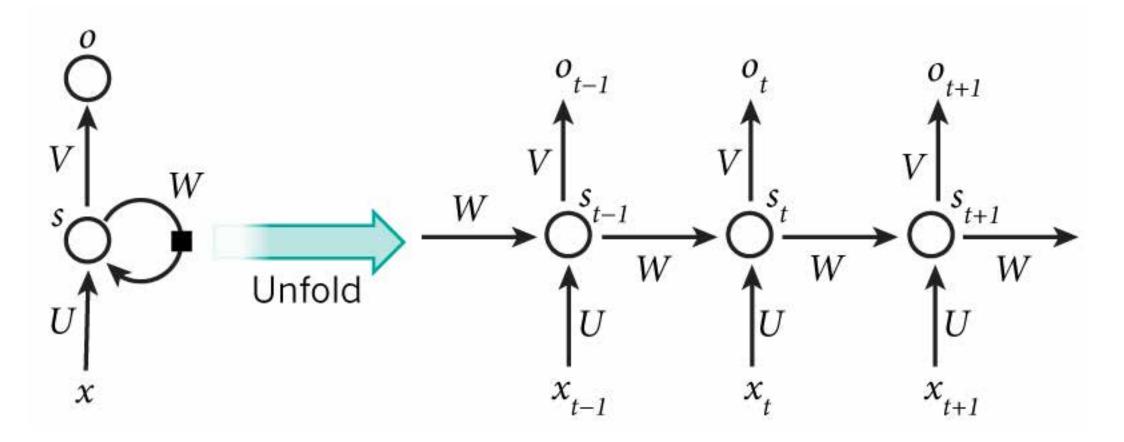
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## Types of Models

# Recurrent NN and Unfolding



By unrolling we simply mean that we write out the network for the complete sequence. For example, if the sequence we care about is a sentence of 5 words, the network would be unrolled into a 5-layer neural network, one layer for each word.

# Word Embeddings: How to represent words?

#### 1 of k encoding:

• What we do instead is generate one boolean column for each category. Only one of these columns could take on the value 1 for each sample.

Sample	Category	Numerical
1	Human	1
2	Human	1
3	Penguin	2
4	Octopus	3
5	Alien	4
6	Octopus	3
7	Alien	4

Sample	Human	Penguin	Octopus	Alien
1	1	0	0	0
2	1	0	0	0
3	0	1	0	0
4	0	0	1	0
5	0	0	0	1
6	0	0	1	0
7	0	0	0	1