Project 1 program, is a code designed with MPLAB X IDE v5.40, with the pic-as compiler v2.30, for the PIC18F452 microcontroller. It's configured to use a 4MHz crystal oscillator, to achieve a 1MHz instruction frequency. PORTB and PORTC were chosen because they are easier to configure, PORTA wasn't chosen because several of his pins are analog inputs and that means a little bit more code lines to achieve his correct configuration. PORTB is the output and bits 0 and 1 from PORTC are inputs. PORTC's bit 0 is to change the sequence and bit 1 is for reverse the direction. A 0.5 seconds delay is implemented on code using the Timer0 to make possible to see the sequences and the direction changes due to the program execution speed, it's too high and we need to introduce the delay to see changes on the output. This delay can be done with an iterative loop and some variables that can be decremented to wait until they become zero, introducing a delay meanwhile, but the delay with TimerO is more accurate, that's why was chosen. The algorithm executed by code is as similar as the statement, start showing a pattern on PORTB, if a logical 1 is detected on bit 0 of PORTC, then shows the next pattern on PORTB and so on, if a logical 1 is detected on bit 1 of PORTC, the direction of the pattern is reversed. Before change the output the delay is executed.

The code effectiveness is good, it uses as less instructions as were possible, resulting in less execution time added to the fact that the objects of the task were achieved.

```
#include "ECE332_assembly_includes_00.inc"
#include <xc.inc>
```

PSECT udata_acs

GLOBAL flags

flags: DS 1 ; place for value

; flags(0): sequence change

; flags(1): reverse direction

; flags(2): left(0) or right(1) direction

; flags(3): off pattern

; flags(4): pattern1 in use

; flags(5): pattern2 in use

; flags(6): pattern3 in use

PSECT resetVec,class=CODE,reloc=2

resetVec: goto main ; goto entry

PSECT code

main:

setf BSR,a ; select bank 14

movlw 0b00000111 ; move 00000111 to w register

movwf T0CON,a ; configures Timer0

; Timer0 stopped for now, configured as a 16 bit timer

; internal instruction cycle selected

; prescaler assigned to TimerO, his clock input comes from

prescaler output

movlw 0xF8; move F8 to w register

movwf TMR0H,a ; move F8 to TMR0H for a 0.5s delay

movlw 0x5E; move 5E to w register

movwf TMR0L,a ; move 5E to TMR0L register for a 0.5s delay

clrf TRISB,a ; clear all TRISB bits, configuring all PORTB pins as outputs

movlw 0x01; copy value 0x01 in w register

movwf PORTB,a; move the value on w register to PORTB

bsf flags,4,a ; indicates pattern1 is in use

bsf T0CON,7,a ; enables Timer0

movlw 0b00000011 ; move 00000011 to w register

movwf TRISC,a; configures bits 0 and 1 as inputs of PORTC

; bit 0 for change sequence, bit 1 for reverse direction

loop:call delay ; delay to make possible to see the sequences

btfss flags,1,a ; if reverse direction flag is not 1

goto 13 ; go to 13 label to continue, else...

rev:bcf flags,1,a ; clear flag before reverse

btfsc flags,2,a ; if sequence is not rotating to the right(1), skip next line

goto I5; if rotating to the right go to I5 label

rrncf PORTB,f,a; right rotate

bsf flags,2,a ; set the flags(2) to indicate rotation to the right(1)

goto I4 ; go to label I4 to continue

I5: rlncf PORTB,f,a ; rotate to left

bcf flags,2,a ; clear flags(2) to indicate left(0) rotation

goto I4 ; go to I4 label to continue

13: btfss flags,2,a ; if sequence is left(0) rotating

rlncf PORTB,f,a; keep left rotating

btfsc flags,2,a ; if sequence is right(1) rotating

rrncf PORTB,f,a; keep rotating to the right

14: btfss flags,0,a ; if sequence change flag is 0

goto loop ; go to loop label, else:

btfsc flags,3,a ; if off pattern is in use

goto I7 ; go to I7 label

btfsc flags,4,a ; if pattern1 is in use

goto I8 ; go to I8 label

btfsc flags,5,a ; if pattern2 is in use

goto I9 ; go to I9 label

btfsc flags,6,a ; if pattern3 is in use

goto I10 ; go to I10 label

goto loop ; repeat all again

17: bcf flags,3,a ; if off pattern is in use, first clear his flag

bsf flags,4,a ; set the pattern1 flag to indicate its been used

bcf flags,0,a ; clear the sequence change flag

movlw 0x01; copy value 0x01 in w register (pattern1)

movwf PORTB,a ; move the value on w register to PORTB

goto loop ; repeat all again

18: bcf flags,4,a ; if pattern1 is in use, first clear his flag

bsf flags,5,a ; set the pattern2 flag to indicate its been used

bcf flags,0,a; clear the sequence change flag

rlncf PORTB,w,a ; creating the pattern2

iorwf PORTB,f,a ; pattern2 created

goto loop ; repeat all again

19: bcf flags,5,a ; if pattern2 is in use, first clear his flag

bsf flags,6,a; set the pattern3 flag to indicate its been used

bcf flags,0,a ; clear the sequence change flag

rlncf PORTB,w,a ; creating the pattern3

iorwf PORTB,f,a ; pattern3 created

goto loop ; repeat all again

110:bcf flags,6,a ; if pattern3 is in use, first clear his flag

bsf flags,3,a ; set the off pattern flag to indicate its been used

```
clrf PORTB,a ; off pattern
16: goto loop
               ; repeat all again
delay:btfsc PORTC,0,a ; if change sequence button is pressed
  bsf
       flags,0,a; set flags(0) to indicate that sequence must be changed
  btfsc PORTC,1,a ; if reverse direction button is pressed
  bsf
       flags,1,a; set flags(1) to indicate that direction must be reversed
  btfss INTCON,2,a
                     ; if the interruption flag of Timer0 is set, 0.5s delay is
complete
  goto delay ; wait for Timer0 overflow
  bcf
       INTCON,2,a
                     ; clear the Timer0 interrupt flag bit
  movlw 0xF8; move F8 to w register
  movwf TMR0H,a
                     ; move F8 to TMR0H for a 0.5s delay
  movlw 0x5E; move 5E to w register
  movwf TMR0L,a ; move 5E to TMR0L register for a 0.5s delay
                ; delay end
  return
; TMR0H and TMR0L values calculation
     Fosc=4MHz, Fcpu=1MHz, prescaler 1:256,
  Ftimer=1MHz/256=3906.25Hz
```

Ttimer=1/3906.25Hz=0.000256=256us

flags,0,a ; clear the sequence change flag

bcf

; number of count for 0.5s delay: 0.5/0.000256=1953.125=7A1h

; value for Timer0 16 bits register= FFFFh-07A1h=F85E

; TMR0H=F8, TMR0L=5E

END resetVec ; start address