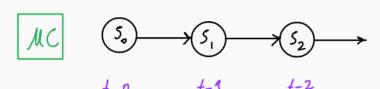
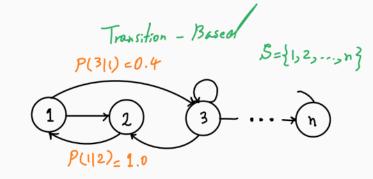
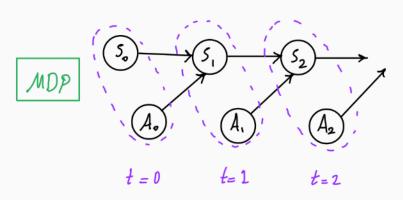
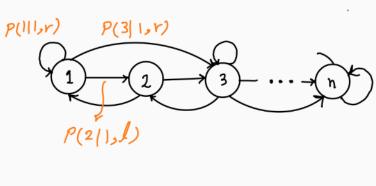
Graphical Representation of MC and MDP





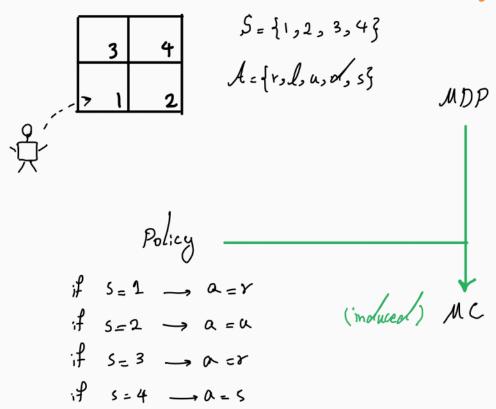


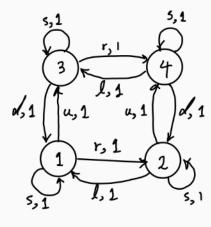


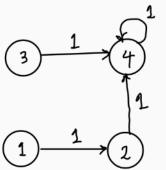


MDP + policy - (induced) MC

edge label: (action, transition probability)







State Distribution over MC

$$\mathcal{N}_{\downarrow}(s) = P \left[s_{\downarrow} = s \right]$$

$$\Delta(S)$$
 $S=0$
 $S=$

$$\mathcal{M}_{\frac{1}{2}+1}(s') = \mathbb{IP}\left[s_{t+1} = s'\right]$$

$$= \sum_{s \in S} \mathbb{IP}\left[s_{t+1} = s', s_{t} = s\right]$$

$$= \sum_{s \in S} \mathbb{IP}\left[s_{t+1} = s' \mid s_{t} = s\right] \mathbb{IP}\left[s_{t} = s\right]$$

$$= \mathcal{P}(s'\mid s) \qquad \mathcal{M}_{\frac{1}{2}}(s)$$

$$\begin{cases} M_{10} (sanny) = 1 \\ M_{10} (nef sunny) = 0 \end{cases}$$

$$\begin{cases} M_{11} (sanny) = 0.6 \\ M_{11} (nef sunny) = 0.4 \\ M_{12} (sanny) = 0.6 \times 0.6 + 0.4 \times 0.7 \\ M_{12} (nof sunny) = 1 - M_{12} (sanny) \end{cases}$$

Let
$$M_{\downarrow} = [P[S_{\downarrow}=1] P[S_{\downarrow}=2] \dots P[S_{\downarrow}=n]]$$

$$P = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

 $\mathcal{M}_{t_{0}+t} = \mathcal{M}_{t_{0}+t-1} P = \mathcal{M}_{t_{0}+t-2} P^{2} = \dots = \mathcal{M}_{t_{0}} P^{t}$

Chapman - Kolmogorov Equation

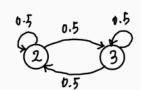
t-step transition matrix

$$\mathcal{M}_{t} = \begin{bmatrix} P[s_{t}=1] \\ P[s_{t}=2] \end{bmatrix}$$

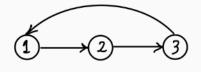
$$[P[s_{t}=n]]$$

$$\mathcal{M}_{t_{o+1}} = P^{\mathsf{T}} \mathcal{M}_{t_{o}} \longrightarrow \mathcal{M}_{t_{o+1}} = (P^{t})^{\mathsf{T}} \mathcal{M}_{t_{o}}$$

Stationary (steady state) distribution: A state distribution I $\overline{MP}^2 = \overline{MPP} = \overline{MP} = \overline{M}$



 $M_{o} = \begin{bmatrix} 1 & 0 & 0 \end{bmatrix}$ stationary $M_{o} = \begin{bmatrix} 0 & 0.5 & 0.5 \end{bmatrix}$ stationary



periodic 2) $M_0 = \begin{bmatrix} 1 & 0 \end{bmatrix} \longrightarrow M_1 = \begin{bmatrix} 0 & 1 & 0 \end{bmatrix} \longrightarrow M_2 = \begin{bmatrix} 0 & 0 & 1 \end{bmatrix}$ $M_3 = \begin{bmatrix} 1 & 0 & 0 \end{bmatrix}$ not stationary

$$\mathcal{M}_{0} = \begin{bmatrix} 0.7 & 0.3 & 0 \end{bmatrix} \longrightarrow \mathcal{M}_{1} = \begin{bmatrix} 0 & 0.7 & 0.3 \end{bmatrix}$$
 not stationary
$$\overline{\mathcal{M}} = \begin{bmatrix} \frac{1}{3} & \frac{1}{3} & \frac{1}{3} \end{bmatrix} \text{ stationary}$$

Theorem: An engodic (irreducible and apprisodic) has a unique stationary distribution I.

Perron -
$$\lim_{t\to\infty} \rho^t = \mathbf{1} \overline{\mathcal{A}}$$

Theorem

Note: The speed of convergence (starting from any M.G D(S)) to the stationary distribution It is characterized by $\frac{\lambda_2}{\lambda}$.

$$\frac{\lambda_2}{\lambda} \downarrow \longrightarrow \frac{\text{speed of }}{\text{convergence}} \uparrow$$

Example:

$$S = \begin{bmatrix} samy & rot samy \\ s & Ns \\ S & N \\ P = \begin{bmatrix} 0.6 & 0.4 \\ 0.7 & 0.3 \end{bmatrix} S$$

$$\mathcal{M}_{o} = \left[\mathcal{M}_{o}(S) \quad \mathcal{M}_{o}(NS) \right]$$

2

$$5 \rightarrow NS \rightarrow NS \rightarrow S$$
 3

$$\overline{\mathcal{M}} = \overline{\mathcal{M}}P \longrightarrow \overline{\mathcal{M}}I = \overline{\mathcal{M}}P \longrightarrow \overline{\mathcal{M}}(P-I) = \mathbf{0}_{1\times h}$$

$$\bar{A} = \begin{bmatrix} 7 & 7 \\ 1 & 7 \end{bmatrix} \qquad \begin{bmatrix} 7 & 7 \\ 1 & 7 \end{bmatrix} \begin{bmatrix} 0.6 & 0.4 \\ 0.7 & 0.3 \end{bmatrix} = \begin{bmatrix} 7 & 7 \\ 1 & 7 \end{bmatrix}$$