

PyAutoCTI: Open-Source Charge Transfer Inefficiency Calibration

James. W. Nightingale¹, Richard J. Massey¹, Jacob Kegerreis², and Richard G. Hayes¹

¹ Institute for Computational Cosmology, Stockton Rd, Durham DH1 3LE 2 NASA Ames Research Center, Moffett Field, CA 94035, USA

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Summary

Over the past half a century, space telescopes have given us an extraordinary view of the Universe, for example detecting the faint spectra of the first galaxies in the Universe (Dunlop et al., 2013) (Bouwens et al., 2015), measuring tiny distortions in galaxy shapes due to gravitational lensing (Massey et al., 2007) (Schrabback et al., 2010) and a high precision map of stars within the Milky Way (Brown et al., 2018) (Gaia Collaboration et al., 2021). These observations require a deep understanding of the telescope's instrumental characteristics, including the calibration and correction of charge transfer inefficiency (hereafter CTI) (Massey et al., 2010) (Massey et al., 2014), a phenomena where radiation damage to the telescope's charge-coupled device (CCD) sensors leads to gradually increased smearing in acquired exposures over the telescope's lifetime.

PyAutoCTI is an open-source Python 3.8 - 3.11 package for the calibration of CTI for space telescopes. By interfacing with arCTIc (the algorithm for Charge Transfer Inefficiency correction) the calibrated CTI models can straightforwardly be used to correct and remove CTI in every science image taken throughout the telescope's lifetime. Core features include fully automated Bayesian model-fitting of CTI calibration data, support for different calibration datasets such as warm pixels used for Hubble Space Telescope calibration (Massey et al., 2010) (Massey, 2010) and a database for building a temporal model of CTI over the telescope's lifetime. The software places a focus on big data analysis, including support for graphical models that simultaneously fits large CTI calibration datasets and an SQLite3 database that allows extensive suites of calibration results to be loaded, queried and analysed. Accompanying PyAutoCTI is the [autocti workspace](#), which includes example scripts, datasets and an overview of core PyAutoCTI functionality. Readers can checkout the [readthedocs](#) for a complete overview of PyAutoCTI's features.

Background

During an exposure, photons hitting a CCD generate photo-electrons that are held in discrete clouds (pixels) by a grid of electrostatic potentials. At the end of the exposure, the potentials are varied so as to move clouds of electrons first in the 'parallel' direction to the edge of the CCD, then along the perpendicular 'serial' register to an amplifier and read-out electronics that count the number of electrons. The CCD substrate through which the electrons move is built of a silicon lattice. However, defects in the lattice known as 'traps' can temporarily capture electrons. If this time is longer than the time taken to move a cloud of electrons to the next pixel, an electron may not be released back into its original charge cloud, but to a subsequent one: creating a characteristic 'trailing' or 'smearing' effect behind sources in the image. The CTI properties of a CCD can be calibrated, using image data that has sharp edges

whose position and flux are known (or can be determined) prior to readout. PyAutoCTI fits a CTI model to these sharp edges and their preceding trails which form due to CTI.

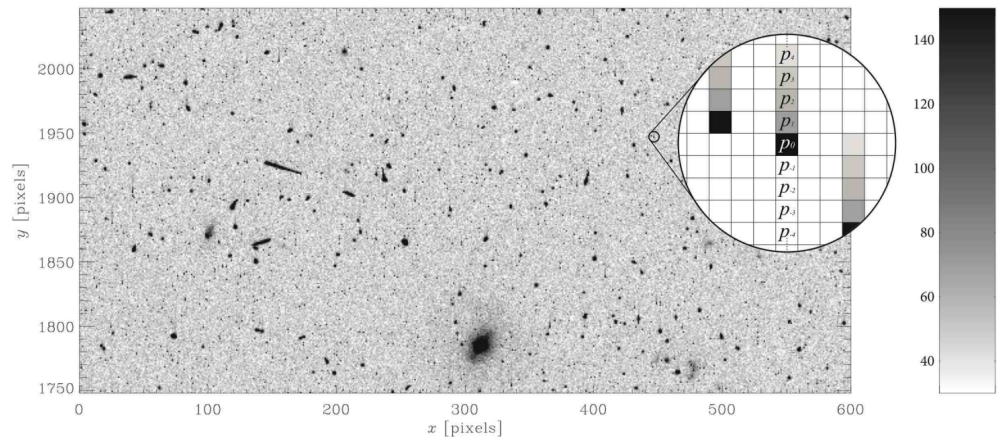


Figure 1: A typical, raw HST ACS / WFC image, in units of electrons. This 30" x 15" (600 x 300 pixels) region contains warm pixels, with an example warm pixel towards the right zoomed in on. This reveals CTI trailing behind (above) the warm pixel, which PyAutoCTI fits to calibrate CTI. This figure is taken from (Massey et al., 2010) and has been used with the author's permission.

Figure 1 shows an example of the CTI calibration data which PyAutoCTI was originally developed to fit – warm pixels in the Hubble Space Telescope (Massey et al., 2010). Warm pixels are similar to short circuits in the CCD electrostatic potentials used to collect charge, which continuously inject spurious charge into specific pixels. These should appear as delta functions in the data, with CTI trails appearing in Fig 1 in the parallel clocking direction (upwards in Figure 1) next to each warm pixel. PyAutoCTI has dedicated functionality for fitting 1D calibration datasets such as those extracted from warm pixels. PyAutoCTI also supports for 2D calibration datasets, for example charge injection line imaging calibration data, which will be used to calibrate CTI for the European Space Agency's Euclid space mission. After CTI calibration has inferred an accurate CTI model, this can be passed to arCTIc in order to correct CTI from science imaging data.

Statement of Need

Space based telescopes planned for launch over the coming decades will map out the Universe's dark matter via weak gravitational lensing (Massey et al., 2007), make precision detections of exoplanets that are further from Earth than ever seen before (Halverson et al., 2016) and perform astrometry of moving objects (Bellini et al., 2013). For these ambitious projects to be successful they all require CTI is removed from science imaging with very stringent requirements, necessitating that CTI calibration provides in-depth knowledge about CTI on every CCD. PyAutoCTI ensures that large CTI calibration datasets can be exploited to measure the CTI model over the telescope's life and it provides tools which maximally extract information from these datasets using contemporary Bayesian inference techniques. The intended audience for PyAutoCTI is therefore the astronomical community, including instrument scientists, who are responsible for maintaining the calibration of space telescopes and the scientific community, who can use PyAutoCTI to perform CTI calculations for their science data.

The majority of software packages for CTI, such as arCTIc, C3TM and CDM03, do not perform CTI calibration. They instead model the CCD clocking procedure, including a CTI model describing the traps on a CCD, enabling the addition and correction of CTI to imaging data. PyAutoCTI wraps one of these algorithm (specifically arCTIc) in order to measure the CTI

model from calibration data. The open-source software Pyxel has a “calibration mode” which also wraps these algorithms to perform CTI calibration. However, Pyxel is more general purpose and has tools for the entire CCD clocking procedure (e.g. bias, dark frames, flat fields). PyAutoCTI is therefore more specialized and has a more extensive suite of tools for CTI calibration.

Software API and Features

At the heart of the PyAutoCTI API are Trap objects, which represent the populations of traps on a CCD which cause CTI. The volume filling behaviour of a CCD is modeled via CCD objects, which are combined with traps to compose CTI models which add CTI to a mock CTI calibration data via arCTIc. PyAutoCTI has dedicated objects for specific CTI calibration datasets and bespoke tools for visualizing these datasets and masking them before fitting. The astropy cosmology module handles unit conversions and calculations are optimized using the packages NumPy (van der Walt et al., 2011) and numba (Lam et al., 2015).

To perform model-fitting, PyAutoCTI adopts the probabilistic programming language PyAutoFit (https://github.com/rhayes777/PyAutoFit). PyAutoFit allows users to compose a CTI model from Trap and CCD objects, customize the model parameterization and fit it to data via a non-linear search, for example dynesty (Speagle, 2020), emcee (Foreman-Mackey et al., 2013) or PySwarms (Miranda, 2018). PyAutoFit’s graphical modeling framework allows one to fit a temporal model to a suite of CTI calibration data. Using a technique called expectation propagation (Vehtari et al., 2020), the framework fits each dataset one-by-one and combines the results of every fit into a temporal model using a self-consistent Bayesian framework. To ensure the analysis and interpretation of fits to large datasets is feasible, PyAutoFit’s database tools write modeling results to a relational database which can be queried from a storage drive to a Python script or Jupyter notebook. This uses memory-light Python generators, ensuring it is practical for use over a telescope’s entire lifetime, where CTI calibration data taken with a daily cadence may consist of thousands of datasets.

Workspace

PyAutoCTI is distributed with the [autocti workspace](#), which contains example scripts for modeling and simulating CTI. The workspace is accessible on [Binder](#) and example scripts can therefore be run without a local PyAutoCTI installation.

Software Citations

PyAutoCTI is written in Python 3.8 - 3.11 (Van Rossum & Drake, 2009) and uses the following software packages:

- Astropy (Astropy Collaboration et al., 2013) (Price-Whelan et al., 2018)
- corner.py (Foreman-Mackey, 2016)
- dynesty (Speagle, 2020)
- emcee (Foreman-Mackey et al., 2013)
- Matplotlib (Hunter, 2007)
- numba (Lam et al., 2015)
- NumPy (van der Walt et al., 2011)
- PyAutoFit (Nightingale et al., 2021)
- pyprojroot (https://github.com/chendaniely/pyprojroot)
- PySwarms (Miranda, 2018)
- scikit-image (Van der Walt et al., 2014)
- scikit-learn (Pedregosa et al., 2011)
- Scipy (Virtanen et al., 2020)

Related Software

- arCTIC <https://github.com/jkeger/arctic> (Massey et al., 2014)
- C3TM (Skottfelt et al., 2018)
- CDM03 (Short et al., 2010)
- Pyxel <https://esa.gitlab.io/pyxel/page/introduction/>
- STScI algorithm (Anderson & Bedin, 2010) (Anderson & Ryon, 2018) (Anderson et al., 2021)

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