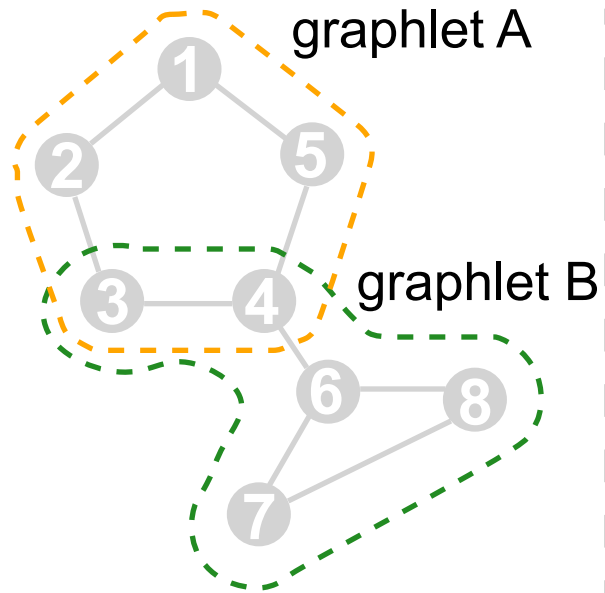


Dynamic t-SNE

Joint t-SNE

t=0



t=1

