Steven R. Dunbar Department of Mathematics 203 Avery Hall University of Nebraska-Lincoln Lincoln, NE 68588-0130

http://www.math.unl.edu

Voice: 402-472-3731 Fax: 402-472-8466

Topics in Probability Theory and Stochastic Processes Steven R. Dunbar

Lévy's Construction of Brownian Motion



Study Tip



Rating

Mathematicians Only: prolonged scenes of intense rigor.



Section Starter Question

If Z_1 and Z_2 are independent $N(0, \sigma^2)$ random variables, then what can be said about $Z_1 + Z_2$ and $Z_1 - Z_2$?



Key Concepts

- 1. Brownian Motion can be defined in a natural way by first constructing a set of independent normal random variables on the dyadic rationals and then combining them inductively to have the right incremental distributions for Brownian Motion.
- 2. The resulting construction of a continuous function B_t on [0,1] has the properties:
 - (a) $B_0 = 0$,
 - (b) for all $t_1 < t_2 < \dots t_{k-1} < t_k$ in [0,1], $B_{t_k} B_{t_{k-1}}, \dots B_{t_2} B_{t_1}$ are independent with joint distribution $(N(0, t_k t_{k-1}), \dots, N(0, t_2 t_1),$
 - (c) and almost surely $t \mapsto B_t$ is continuous on [0,1].



Vocabulary

- 1. A one-dimensional **standard Brownian Motion** is a stochastic process $B: \Omega \times [0, \infty) \to \mathbb{R}$ (alternatively a collection of random variables (indexed by $x \in [0, \infty)$) with the following properties:
 - (a) B(0) = 0 almost surely.
 - (b) For all $t_1 < t_2 < \dots t_{k-1} < t_k$ in [0,1], $B_{t_k} B_{t_{k-1}}, \dots B_{t_2} B_{t_1}$ are independent with joint distribution $(N(0, t_k t_{k-1}), \dots, N(0, t_2 t_1),$
 - (c) Almost surely, the path $x \to B(x)$ (called a sample path) is a continuous function on $[0, \infty)$.
- 2. $D_n = \{k/2^n : 0 \le k \le 2^n\}$ and $D = \bigcup_n D_n$ are the **dyadic rationals**, a countable dense set in [0, 1].

Notation

- 1. $Z \sim N(0,1)$ A normally distributed random variable with mean 0 and variance 1.
- 2. $\{A_i\}_{i=0}^{\infty}$ A sequence of events in some probability space.
- 3. $\limsup_{i\to\infty} A_i = \bigcap_{i=0}^{\infty} \bigcup_{j=i}^{\infty} A_i = \{A_i, \text{i.o.}\}$ An event which occurs "infinitely often".
- 4. $B: \Omega \times [0, \infty) \to \mathbb{R}$ or B_t The standard one-dimensional Brownian Motion as a stochastic process.
- 5. $D_n = \{k/2^n : 0 \le k \le 2^n\}$ and $D = \bigcup_n D_n$ are the **dyadic rationals**, a countable dense set in [0, 1].
- 6. $\{Z_d\}$ A countable collection of N(0,1) independent random variables indexed by D.
- 7. B_d Random variables derived from Z_d , indexed by D with the independent increments property on D.

- 8. $d^+ = d + 2^{-n}$ and $d^- = d 2^{-n}$ The neighbors of d, which are actually members of D_{n-1} .
- 9. r < s < t Arbitrary points in D.
- 10. $F_0(t)$ for $n = 0, 1, 2, \ldots$ Piecewise linear functions defined in terms of the random variables Z_d .
- 11. $t_1 < t_2 < t_3$ Points in [0, 1].
- 12. $t_i = \lim_{n\to\infty} t_{i,n}$ for i = 1, 2, 3 Sequences of dyadics from D with limit t_i .
- 13. $B_t^{(n)}$ Independent standard Brownian Motion stochastic processes on the unit interval.



Mathematical Ideas

Preliminary Lemmas

Lemma 1. If $Z \sim N(0,1)$ then $\mathbb{P}[Z \geq x] \leq \frac{1}{\sqrt{2\pi}} \cdot \frac{1}{x} \cdot e^{-x^2/2}$.

Proof.

$$\mathbb{P}[Z \ge x] = \int_x^\infty \frac{1}{\sqrt{2\pi}} e^{-u^2/2} du$$

$$\le \int_x^\infty \frac{1}{\sqrt{2\pi}} \frac{u}{x} e^{-u^2/2} du$$

$$= \frac{1}{\sqrt{2\pi}} \cdot \frac{1}{x} \int_x^\infty u e^{-u^2/2} du$$

$$= \frac{1}{\sqrt{2\pi}} \cdot \frac{1}{x} \cdot e^{-x^2/2}$$

Remark. For $x \ge 1/(\sqrt{2\pi}) \approx 0.398$, the simpler but cruder estimate is useful: $\mathbb{P}[Z \ge x] \le \mathrm{e}^{-x^2/2}$.

Lemma 2 (Borel-Cantelli). Let $\{A_i\}_{i=0}^{\infty}$ be a sequence of events in some probability space. Let $\limsup_{i\to\infty} A_i = \bigcap_{i=0}^{\infty} \bigcup_{j=i}^{\infty} A_i = \{A_i, i.o.\}$, where i.o. stands for infinitely often.

- 1. If $\sum_{i=0}^{\infty} \mathbb{P}[A_i] < \infty$, then $\mathbb{P}[\{A_i, i.o.\}] = 0$.
- 2. If the events $\{A_i\}_{i=0}^{\infty}$ are pairwise independent, and $\sum_{i=0}^{\infty} \mathbb{P}[A_i] = \infty$, then $\mathbb{P}[\{A_i, i.o.\}] = 1$.

Proof. Omitted here.

Lévy's Construction of Brownian Motion

Definition. A one-dimensional standard Brownian Motion is a stochastic process $B: \Omega \times [0, \infty) \to \mathbb{R}$ (alternatively a collection of random variables indexed by $x \in [0, \infty)$) with the following properties:

- 1. $B_0 = 0$,
- 2. for all $t_1 < t_2 < \ldots t_{k-1} < t_k$ in [0,1], $B_{t_k} B_{t_{k-1}}, \ldots B_{t_2} B_{t_1}$ are independent with joint distribution $(N(0, t_k t_{k-1}), \ldots, N(0, t_2 t_1),$
- 3. and almost surely $t \mapsto B_t$ is continuous on [0,1].

Theorem 3 (Wiener, 1923). One-dimensional standard Brownian Motion B_t exists.

Remark. Although Norbert Wiener mathematically described Brownian Motion first in 1923, the following construction is due to Paul Lévy in 1948.

*Proof*step 1: Construct a set of random values on the dyadics in [0, 1] satisfying the independent normal increments property.

- (a) Let $D_n = \{k/2^n : 0 \le k \le 2^n\}$ and $D = \bigcup_n D_n$ be the **dyadic** rationals, a countable dense set in [0, 1].
- (b) Let $\{Z_d\}$ be a countable collection of N(0,1) independent random variables indexed by D.

- (c) Inductively define a some new values B_d indexed by D with the independent increments property on D. Begin by defining $B_0 = 0$ and $B_1 = Z_1$.
- (d) Claim: It is possible to make a collection B_d , with $d \in D$, such that for r < s < t in D, $B_t B_s \sim N(0, t s)$ is independent of $B_s B_r \sim N(0, s r)$ and furthermore, that the B_d with $d \in D_n$ are globally independent of Z_d for $d \in D \setminus D_n$.
- (e) Proof of Claim by Induction: The base case for n=0 with D_0 holds since r=0, t=1 and there is no s. Then $B_1-B_0=Z_1-0=Z_1\sim N(0,1)$. $B_1=Z_1$ is independent of all other B_d by constructions and $B_0=0$ is independent of all other B_d . The induction step assumes the claim is true for n-1. Define for $d\in D_n\setminus D_{n-1}$

$$B_d = \frac{B_{d^-} + B_{d^+}}{2} + \frac{Z_d}{2^{(n+1)/2}}$$

where $d^+=d+2^{-n}$ and $d^-=d-2^{-n}$ are the neighbors of d, which are actually members of D_{n-1} . Since $B_{d^-}-B_{d^+}\sim N(0,1/2^{n-1})$ by the induction hypothesis, then $\frac{B_{d^-}-B_{d^+}}{2}\sim N(0,1/2^{n+1})$. Furthermore, since $Z_d\sim N(0,1)$, then $\frac{Z_d}{2^{(n+1)/2}}\sim N(0,1/2^{n+1})$. Together, these mean $B_d-B_{d^-}=\frac{B_{d^+}-B_{d^-}}{2}+\frac{Z_d}{2^{(n+1)/2}}\sim N(0,1/2^n)$ and $B_{d^+}-B_d=\frac{B_{d^+}-B_{d^-}}{2}-\frac{Z_d}{2^{(n+1)/2}}\sim N(0,1/2^n)$. This is enough to establish the first part of the induction claim. Note that B_d depends only on values from D_n so it is independent of all other values in $D\setminus D_n$. This establishes the second part of the induction claim.

- Step 2: Using the B_d values, define some functions by linear interpolation between some values in D_n .
 - (a) Let $F_0(x) = xZ_1$. Let

$$F_n(x) = \begin{cases} 2^{-(n+1)/2} Z_d & x \in D_n \setminus D_{n-1} \\ 0 & x \in D_{n-1} \\ \text{linear} & \text{between adjacent points in } D_n \end{cases}$$

These functions are continuous on [0,1]. A graph of $F_i(t)$ for $i=0,\ldots 6$ for some random normal values selected with a pseudo random number generator are in Figure 1.

- (b) Claim: $B_d = \sum_{i=0}^n F_i(d) = \sum_{i=0}^\infty F_i(d)$.
- (c) Proof of Claim by Induction: The base case is n=0 with $F_0(0)=0=B_0$ and $F_0(1)=Z_1=B_1$. The induction step supposes the claim holds for n-1. Let $d\in D_n\setminus D_{n-1}$ which is where new values of $\sum_{i=0}^n F_i(d)$ need to be checked. For $0\leq i\leq n-1$, F_i is linear on $[d^-,d^+]$ so

$$\sum_{i=0}^{n-1} F_i(d) = \sum_{i=0}^{n} \frac{F_i(d^-) + F^+(d^+)}{2} = \frac{B_{d^-} + B_{d^+}}{2}.$$

Additionally, $F_n(d) = 2^{-(n+1)/2} Z_d$, so together

$$\sum_{i=0}^{n} F_i(d) = \frac{B_{d^-} + B_{d^+}}{2} + 2^{-(n+1)/2} Z_d = B_d$$

establishing the claim.

- Step 3: Apply the Borel-Cantelli Lemma to show that $|Z_d| \sim c\sqrt{n}$ cannot happen infinitely often.
 - (a) Using the estimate for normal random variables in the Lemma, $\mathbb{P}\left[|Z_d| \geq c\sqrt{n}\right] \leq \frac{2}{c\sqrt{n}} \frac{1}{\sqrt{2\pi}} \mathrm{e}^{-c^2n/2} < \mathrm{e}^{-c^2n/2}$ for all $n \geq 1$ (as long as $c > \sqrt{\frac{2}{\pi}} \approx 0.798$).
 - (b) Then

$$\sum_{n=0}^{\infty} \sum_{d \in D_n} \mathbb{P}\left[|Z_d| \ge c\sqrt{n} \right] \le \sum_{n=0}^{\infty} 2^n e^{-c^2 n/2} = \sum_{n=0}^{\infty} e^{(\log 2 - c^2/2)n}.$$

- (c) So if $c > \sqrt{2 \log 2} \approx 1.177$, the series converges.
- (d) By the Borel-Cantelli Lemma, then there is a random but finite N so that for n > N, $d \in D_n$, $|Z_d| \le c\sqrt{n}$.
- (e) This means $\max_{t \in [0,1]} |F_n(t)| \le c\sqrt{n}2^{-n/2}$.
- (f) Then by the Weierstrass M-test, $\sum_{n=0}^{\infty} F_n(t)$ is uniformly and absolutely convergent on [0,1] to a continuous function, say $B_t = \sum_{n=0}^{\infty} F_n(t)$. A suggestive graph of $\sum_{n=0}^{\infty} F_n(t)$ approximating B_t in Figure 2.

- Step 4: Check that all increments have the correct finite dimensional joint distributions.
 - (a) Let $t_1 < t_2 < t_3$ be 3 points in [0,1]. Each is the limit of sequences of dyadics from D, $t_i = \lim_{n \to \infty} t_{i,n}$ for i = 1, 2, 3.
 - (b) Then

$$B_{t_3} - B_{t_2} = \lim_{n \to \infty} (B_{t_{3,n}} - B_{t_{2,n}})$$

is the limit of Gaussian sequences with mean 0 and variance $\lim_{n\to\infty}(t_{3,n}-t_{2,n})=t_3-t_2$. Likewise for $B_{t_2}-B_{t_1}$.

(c) The sequential increments are independent since $t_{1,n} < t_{2,n} < t_{3,n}$ (for sufficiently large n), and therefore the limit increments $B_{t_3} - B_{t_2}$ and $B_{t_2} - B_{t_1}$ are independent.

Step 5: Finally construct Brownian Motion on $[0, \infty)$.

- (a) By the preceding construction, for $n \ge 1$ let $B_t^{(n)}$ be independent standard Brownian Motion processes on the unit interval.
- (b) Let $B_t = B_{t-\lfloor t \rfloor}^{(\lfloor t \rfloor)} + \sum_{0 \le i \le \lfloor t \rfloor} B_1^{(i)}$

Remark. The slopes of the linear parts of $F_n(x)$ are

$$\frac{\pm 2^{-(n+1)/2} Z_d}{1/2^n} = \pm 2^{(n-1)/2} Z_d = O(2^{n/2})$$

which suggests that the limit function $\sum_{i=0}^{\infty} F_i(d)$ will be non-differentiable. See Figure 2. This is not enough to prove non-differentiability, but is suggestive.



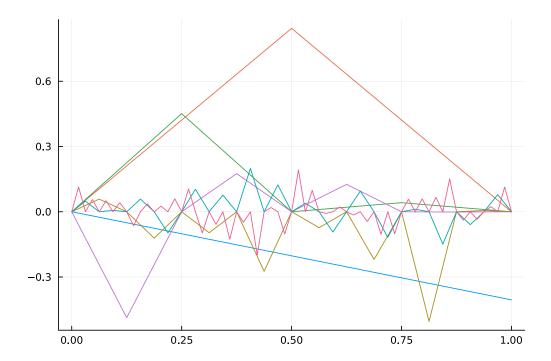


Figure 1: Graphs of $F_n(t)$ for n = 0, ..., 6.

Figure 2: Graph of $\sum_{n=0}^{6} F_n(t)$ suggesting the form of Brownian Motion and its non-differentiability.

Section Ending Answer

 $Z_1 + Z_2$ and $Z_1 - Z_2$ and independent random variables each having the distribution $N(0, 2\sigma^2)$.

Sources

This section is adapted from: An Invitation to Sample Paths of Brownian Motion, Chapter 3, by Yuval Peres, An Invitation to Sample Paths of Brownian Motion.



Algorithms, Scripts, Simulations

Algorithm

Scripts

Data: Depth of approximation

Result: Plots of approximation of Brownian Motion

- 1 Initializations
- 2 Load interpolation and plotting packages
- 3 Set the depth of approximation
- 4 Set Z_1 and define function F_0
- 5 Create list of dyadic rationals to depth
- 6 Function Creation Define the values of F_i on D_i to depth
- 7 Use linear interpolation to create functions F_i
- 8 Create Plots
- 9 Plot the functions F_i and save the plot
- 10 Create the Brownian Motion function as a sum of F_i
- 11 Plot the Brownian Motion approximation and save the plot

Scripts

```
using Plots, DataInterpolations
 N = 6
 Z1 = randn()
 FO = t \rightarrow t * Z1
 D = [ [j//2^i \text{ for } j=0:2^i] \text{ for } i = 1:N]
 Fdata = [ [ iseven(j) ? 0 : randn()/2^((i+1)/2) ]
    for j=0:2^i] for i = 1:N]
Finterps = [ LinearInterpolation(Fdata[i], D[i
    ]) for i in 1:N ]
|12| ts = range(0, 1, length=2^(N+1)+1)
_{13}|F0s = F0.(ts)
15 Fs = [Finterps[i].(ts) for i in 1:6]
16 plot(ts, [F0s, Fs[1,:], Fs[2,:], Fs[3,:], Fs
     [4,:], Fs[5,:], Fs[6,:]], label=false)
savefig("individualFs.pdf")
|sumF = F0s + Fs[1] + Fs[2] + Fs[3] + Fs[4] + Fs
     [5] + Fs[6]
plot(ts, sumF, label=false)
21 savefig("LevyBrownianMotion.pdf")
```



Problems to Work for Understanding



Reading Suggestion:

References



Outside Readings and Links:

- 1. An Invitation to Sample Paths of Brownian Motion, by Yuval Peres, An Invitation to Sample Paths of Brownian Motion
- 2. Brownian Motion by Peter Mörters and Yuval Peres, Brownian Motion

Solutions

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