

Name: SHUBHVARATA DUTTA

ASU-ID: 1223486849

MAE-598/494 - HW-4

(3)

$$\text{max. } f = x_1x_2 + x_2x_3 + x_1x_3$$

$$\text{s.t.: } h = x_1 + x_2 + x_3 - 3 = 0$$

Using Lagrangian Method -

$$L = -(x_1x_2 + x_2x_3 + x_1x_3) + \lambda(x_1 + x_2 + x_3 - 3)$$

$$\therefore \frac{\partial L}{\partial x} = \begin{pmatrix} \frac{\partial L}{\partial x_1} \\ \frac{\partial L}{\partial x_2} \\ \frac{\partial L}{\partial x_3} \end{pmatrix} = \begin{pmatrix} -x_2 - x_3 + \lambda \\ -x_1 - x_3 + \lambda \\ -x_1 - x_2 + \lambda \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\frac{\partial L}{\partial \lambda} = x_1 + x_2 + x_3 - 3 = 0$$

Solving above system of 4 linear eqⁿ using calculator we obtain

$$x_1 = x_2 = x_3 = 1 \text{ and } \lambda = -2.$$

Now,

$$h_{xx} = \begin{pmatrix} \frac{\partial^2 L}{\partial x_1^2} & \frac{\partial^2 L}{\partial x_1 \partial x_2} & \frac{\partial^2 L}{\partial x_1 \partial x_3} \\ \frac{\partial^2 L}{\partial x_2 \partial x_1} & \frac{\partial^2 L}{\partial x_2^2} & \frac{\partial^2 L}{\partial x_2 \partial x_3} \\ \frac{\partial^2 L}{\partial x_3 \partial x_1} & \frac{\partial^2 L}{\partial x_3 \partial x_2} & \frac{\partial^2 L}{\partial x_3^2} \end{pmatrix} = \begin{pmatrix} 0 & -1 & -1 \\ -1 & 0 & -1 \\ -1 & -1 & 0 \end{pmatrix}$$

$$\frac{\partial h}{\partial x} = \begin{pmatrix} \frac{\partial h}{\partial x_1} & \frac{\partial h}{\partial x_2} & \frac{\partial h}{\partial x_3} \end{pmatrix} = (1 \ 1 \ 1)$$

$$\text{then } \frac{\partial h}{\partial x} \cdot dx = 0 \Rightarrow \begin{pmatrix} \frac{\partial h}{\partial x_1} & \frac{\partial h}{\partial x_2} & \frac{\partial h}{\partial x_3} \end{pmatrix} \begin{pmatrix} dx_1 \\ dx_2 \\ dx_3 \end{pmatrix} = 0$$

$$\Rightarrow (1 \ 1 \ 1) \begin{pmatrix} dx_1 \\ dx_2 \\ dx_3 \end{pmatrix} = 0$$

$$\Rightarrow dx_1 + dx_2 + dx_3 = 0$$

$$\Rightarrow dx_1 = -dx_2 - dx_3 \quad (1)$$

Also,

$$dx^T L_{xx} dx = (dx_1 \ dx_2 \ dx_3) \begin{pmatrix} 0 & -1 & -1 \\ -1 & 0 & -1 \\ -1 & -1 & 0 \end{pmatrix} \begin{pmatrix} dx_1 \\ dx_2 \\ dx_3 \end{pmatrix}$$

$$\Rightarrow dx^T L_{xx} dx = -2dx_1 dx_2 - 2dx_1 dx_3 - 2dx_2 dx_3 \quad (2)$$

Plugging eqⁿ ① in ②,

$$\Rightarrow dx^T L_{xx} dx = -2(-dx_2 - dx_3) dx_2 - 2(-dx_2 - dx_3) dx_3 - 2 dx_2 dx_3$$

$$= 2dx_2^2 + 2dx_2 dx_3 + 2dx_2 dx_3 + 2dx_3^2 - 2dx_2 dx_3$$

$$= 2(dx_2^2 + dx_2 dx_3 + dx_3^2)$$

$$\Rightarrow dx^T L_{xx} dx = 2 \left(\underbrace{(dx_2 + \frac{1}{2} dx_3)^2}_{\geq 0} + \underbrace{\frac{3}{4} dx_3^2}_{\geq 0} \right)$$

Since RHS all terms are sq. so they are ≥ 0 .

If $dx_3 = 0$ & $dx_2 = 0$ then from eqⁿ - ①

$dx_1 = 0 \rightarrow$ which means No Perturbation takes place

therefore

$$2 \left(\left(dx_2 + \frac{1}{2} dx_3 \right)^2 + \frac{3}{4} dx_3^2 \right) > 0, \text{ if } dx_1, dx_2$$

Therefore at $x_1 = x_2 = x_3 = 1$ and $\lambda = -2$ our

(Ans) objective funcⁿ (f) = $-x_1 x_2 + x_2 x_3 + x_1 x_3$

has a max.ⁿ. value i.e. = $1 + 1 + 1 = 3.$

Name - SHUBHENDU DUTTA

ASU-ID - 1223486849

DOP-HW-4

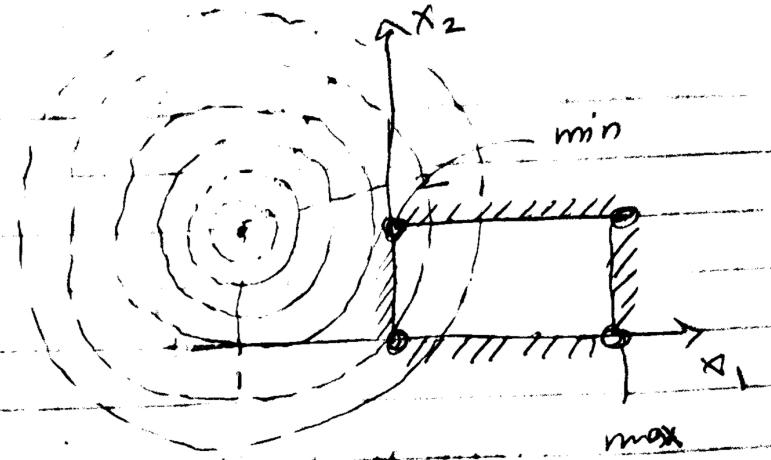
① $\min_{x_1, x_2} (x_1+1)^2 + (x_2-2)^2$

s.t. $-x_1 \leq 0, -x_2 \leq 0$

$x_1 \leq 2, x_2 \leq 1$

g_3

g_4



$$L = (x_1+1)^2 + (x_2-2)^2 + \mu_1(-x_1) + \mu_2(-x_2) + \mu_3(x_1-2) + \mu_4(x_2-1)$$

$$\nabla_L = \begin{pmatrix} 2(x_1+1) - \mu_1 + \mu_3 \\ 2(x_2-2) - \mu_2 + \mu_4 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

* if $-x_1 = 0$ then $\mu_1 > 0$

if $-x_2 = 0$ then $\mu_2 > 0$

" $x_1-2=0$ " $\mu_3 > 0$

" $x_2-1=0$ " $\mu_4 > 0$

if $-x_1 < 0$ then $\mu_1 = 0$

" $-x_2 < 0$ " $\mu_2 = 0$

" $x_1-2 < 0$ " $\mu_3 = 0$

" $x_2-1 < 0$ " $\mu_4 = 0$

Checking diffⁿ cases -

① when $\mu_2 > 0, \mu_3 > 0$ and $\mu_1 = \mu_4 = 0$, then

$$x_1 = 0 \quad \mu_3 = 2 > 0$$

$$x_2 = 1 \quad \mu_2 = 2 > 0$$

Since the objective funcⁿ is a convex funcⁿ and feasible domain is convex set too, the ~~problem~~ problem is convex problem. Therefore, the soln is

$$x_1 = 0, x_2 = 1, \mu_1 = 0, \mu_2 = 2$$

$$\mu_3 = 2, \mu_4 = 0$$

and min. value of objective funcⁿ is 1. (Ans)

(Case-2) when $u_1 > 0$, $u_4 > 0$, $u_2 = u_3 = 0$, then

$$x_1 = 2, u_2 = 0,$$

$$u_1 = -6 < 0; u_4 = -4 < 0$$

As we observe u_1 and u_4 value above contradicts our assumption so $x_1 = 2$ and $x_2 = 0$ is not a min. soln. From figure we can observe this point is max. point.

(Case-3) when $u_1 > 0$, $u_2 > 0$ and $u_3 = u_4 = 0$ then

$$x_1 = 2, u_1 = 1,$$

$$u_1 = -6 < 0 \leftarrow \text{contradict}$$

$$u_2 = 2 > 0$$

so $x_1 = 2, x_2 = 1 \rightarrow$ not min. soln.

(Case-4) when $u_3 > 0$, $u_4 > 0$ and $u_1 = u_2 = 0$ then

$$x_1 = 0, x_2 < 0$$

$$u_3 = 2 > 0 \text{ and } (u_4 = -4 < 0) \leftarrow \text{contradiction}$$

so $x_1 = 0, x_2 = 0 \rightarrow$ not a min. soln

(Ans) Therefore, min. value of given objective funcⁿ is 1 when $x_1 = 0$ and $x_2 = 1$

②

$$\min -x_1$$

$$\text{s.t. } x_2 - (1-x_1)^3 \leq 0 \leftarrow g_1$$

$$x_2 \geq 0 \leftarrow g_2$$

$$\therefore L = -x_1 + u_1 [x_2 - (1-x_1)^3] + u_2 (-x_2)$$

$$\nabla_x L = \begin{pmatrix} -1 + 3(1-x_1)^2 \mu_1 \\ \mu_1 - \mu_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

if $x_2 - (1-x_1)^3 = 0 \rightarrow \mu_1 > 0$; if $x_2 - (1-x_1)^3 < 0 \rightarrow \mu_1 = 0$

" $-x_2 = 0 \rightarrow \mu_2 > 0$; " $-x_2 < 0 \rightarrow \mu_2 = 0$

(Case-1) when $\mu_1 > 0$ and $\mu_2 > 0$, then

$$x_2 - (1-x_1)^3 = 0 \Rightarrow x_1 = 0$$

Substituting in $\nabla_x L$, we get $\boxed{-1 = 0} \rightarrow \text{Not possible}$
Here case-1, not valid.

(Case-2) when $\mu_1 > 0$ and $\mu_2 = 0$, then

$$x_2 - (1-x_1)^3 = 0$$

$$-x_2 < 0 \Rightarrow \boxed{\mu_2 = 0}$$

Again checking in $\nabla_x L$, $\mu_1, \mu_2 > 0 \Rightarrow \boxed{\mu_1 = 0} \rightarrow \text{Not possible (contradict)}$

(Case-3) when $\mu_1 = 0$ and $\mu_2 > 0$, then

$$x_2 - (1-x_1)^3 < 0 \text{ and } -x_2 = 0$$

Checking in $\nabla_x L$, $\mu_1 = \mu_2 = 0 \Rightarrow \boxed{\mu_2 = 0} \rightarrow \text{contradict (reject)}$

(Case-4) when $\mu_1 = 0$ and $\mu_2 = 0$, then

from $\nabla_x L \rightarrow \boxed{-1 = 0} \rightarrow \text{not possible (reject)}$

$$\nabla f + \mu_1 \nabla g_1 + \mu_2 \Delta g_3 = 0$$

$$\Rightarrow \begin{pmatrix} -1 \\ 0 \end{pmatrix} + \mu_1 \begin{pmatrix} 0 \\ 1 \end{pmatrix} + \mu_2 \begin{pmatrix} 0 \\ -1 \end{pmatrix} = 0 \quad \text{feasible region}$$

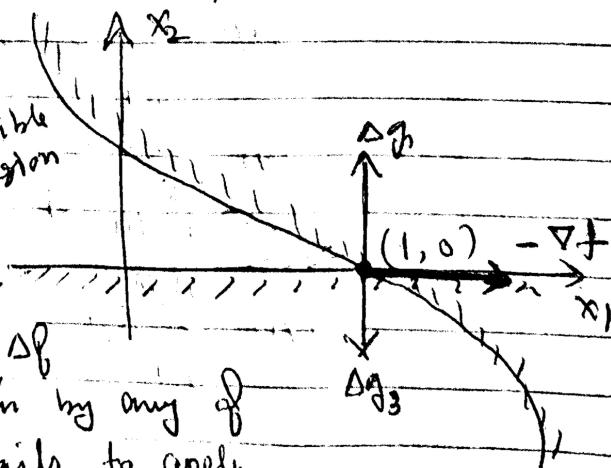
As seen in figure Δg_1 and Δg_2

are linearly independent and $-\nabla f$

does not lie in the plane span by any of

these gradient. KKT cond' fails to apply.

Therefore, no optimal soln exist.



(5) Let c_{ij} = cost to move from edge $i \rightarrow j$

$$x_{ij} = \begin{cases} 0 & \text{for } i \not\rightarrow j \\ 1 & \text{for } i \rightarrow j \end{cases}$$

$\mathcal{V} = N = \text{Node domain}$.

$m = \text{Steps req. to return to station-0 from final destination.}$

$s \rightarrow \text{starting point (station-0)}$

$j \rightarrow \text{any mid node}$

$t \rightarrow \text{target node}$

Problem

Objective : $\min \sum_{\{x_{ij}\}} c_{ij} x_{ij}$

S. To. (i) $\sum_{j=1}^N x_{sj} = 1$ (start to adjacent node)

(ii) $\sum_{j=1}^N x_{js} = 0$

(iii) $\sum_{j=N+1}^{N+M} x_{js} = 1$

(iv) $\sum_{j \geq 1}^N x_{jt} = 1$

(v) $\sum_{j=N+1}^{N+M} x_{tj} = 1$ domain of nodes

(vi) $\sum_{j=1}^{N+M} x_{ij} = \sum_{j=1}^{N+M} x_{ji}$, $\forall i \in \mathcal{V}$ except start and end point.