

1 Category Theory

1.1 Categories

Definition 1 (Category). A category \mathcal{C} is a collection of **objects**, such that:

- (i.) for each pair of objects $A, B \in \text{Ob}(\mathcal{C})$;
- (ii.) a collection of morphisms is given by $\text{Mor}(A, B)$;
- (iii.) there exists operation titled *composition of morphisms* given by

$$\text{Mor}(A, B) \times \text{Mor}(B, C) \rightarrow \text{Mor}(A, C)$$

such that $f, g \mapsto g \circ f$;

- (iv.) Category Theory Axioms:

- (a) every object A has an identity morphism $\text{id}_A \in \text{Mor}(A, A)$ such that

$$\forall f \in \text{Mor}(A, B), f \circ \text{id}_A = \text{id}_B \circ f = f;$$

- (b) composition (of morphisms) is associative, i.e., $(f \circ g) \circ h = f \circ (g \circ h)$.

We can think of categories and sets as, for the most part, the same thing, except for the fact that a category may include the category of all sets; this is where we deliniate sets and categories in order to avoid pesky paradoxes.

Some examples of categories, for purposes of clarity:

1. category of sets, $\text{Mor}(A, B) = \text{all maps } A \rightarrow B$
2. Vect_k as a fin. dim. vector space over k , then $\text{Mor} = \text{linear maps}$
3. groups, group homomorphisms
4. topological spaces, continuous maps
5. and more...

There exists a relationship called **isomorphism** not too dissimilar from group-theoretic isomorphisms.

Definition 2 (Isomorphism). $f \in \text{Mor}(A, B)$ is an *isomorphism* if has inverse, i.e., $\exists g \in \text{Mor}(B, A)$ s.t. $g \circ f = \text{id}_A$ and $f \circ g = \text{id}_B \Rightarrow$ if $\exists g \Rightarrow \exists! g$ and that id_A is an isomorphism. $f \Rightarrow f^{-1}$ (gf^{-1}) are both called isomorphisms, individually.

Concequentially the automorphisms $\text{Aut}(A)$ is always a group.

sets :permutations, groups: automs, vec: invertible lin op.

Isomorphic objects of \mathcal{C} have isomorphic automorphic groups. Given $f \in \text{Mor}(A, B)$ as an isomorphism $c_f : \text{Aut}(A) \rightarrow \text{Aut}(B)$ which maps $g \mapsto f \circ g \circ f^{-1}$.

We may define sum, product, and quotient objects in categories. Consider a product $A \times B := \mathcal{C}$ of objects $A, B \in \mathcal{C}$ characterized by \mathcal{P} projects $\pi_1 \in \text{Mor}(\mathcal{P}, A), \pi_2 \in \text{Mor}(\mathcal{P}, B)$ s.t. \forall object T , $\forall f_1 \in \text{Mor}(T, A), f_2 \in \text{Mor}(T, B), \exists$ unique $f \in \text{Mor}(T, \mathcal{P})$ s.t. $\pi_1 \circ f = f_1, \pi_2 \circ f = f_2$.

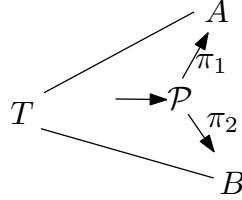


Figure 1

Definition 3 (functor). \mathcal{C}, \mathcal{D} categories, a (covariant) functor $F : \mathcal{C} \rightarrow \mathcal{D}$ is an assignment:

1. for every object X of \mathcal{C} an object $F(X)$ of \mathcal{D}
2. for each morphism $f \in \text{Mor}_{\mathcal{C}}(X, Y)$, a morphism $F(f) \in \text{Mor}_{\mathcal{D}}(F(X), F(Y))$ s.t.
 - (a) $F(id_X) = id_{F(X)}$
 - (b) $F(g \circ f) = F(g) \circ F(f)$

Consider Forgetful functors, on a vector space over k given vector space V $F : \text{Vect}_k \rightarrow \text{Vect}_k$ objects: $W \mapsto \text{Hom}(V, W)$ lin. maps $V \rightarrow W$, morphism $f : W \rightarrow W' \Rightarrow$??

Anywhos. He's going on about linear maps as morphisms for categories and functors but I don't care all that much at the moment. As a functor $F : \text{Vect}_k \rightarrow \text{Vect}_k$ can be shown as $\text{Hom}(V, \circ)$. What the hell does obj. $V \mapsto V_{\mathbb{C}} = V \oplus iV$

Definition 4. A contravariant functor $F : \mathcal{C} \rightarrow \mathcal{D}$ is the same except reverses direction of morphism:

$$f \in \text{Mor}_{\mathcal{C}}(X, Y) \mapsto F(f) \in \text{Mor}_{\mathcal{D}}(F(Y), F(X)) \mid F(g \circ f) = F(f) \circ F(g).$$

So for example, consider $V \rightarrow V^*$ s.t. $f \in \text{Hom}(V, W) \mapsto f^* \in \text{Hom}(W^*, V^*)$.

Definition 5. Given two functors $F, G : \mathcal{C} \rightarrow \mathcal{D}$ a natural transformation t from F to G is the data $\forall X \in \text{Ob}(\mathcal{C})$, a morphism $t_X \in \text{Mor}_{\mathcal{D}}(F(X), G(X))$ s.t.

$$\begin{array}{ccc} \forall X, Y \in \text{Ob}(\mathcal{C}), \forall f \in \text{Mor}_{\mathcal{C}}(X, Y), & & \\ F(X) & \xrightarrow{F(f)} & F(Y) \\ t_X \downarrow & & \downarrow t_Y \\ G(X) & \xrightarrow{G(f)} & G(Y) \end{array} \cdot$$

Definition 6 (Bilinear forms). A **bilinear form** on a vector space V over a field k is a map $b : V \times V \rightarrow k$ (this is to say we take $(v, w) \mapsto b(v, w)$) that is linear in each variable, i.e., $\forall u, v, w \in V, \lambda \in k, b(\lambda v, w) = b(v, \lambda w) = \lambda b(v, w)$ ("multiplied" on both sides separately).

Definition 7 (symmetric). Say b is symmetric if $b(v, w) = b(w, v) \forall v, w \in V$ and is skew symmetric if $b(v, w) = -b(w, v)$.

I have mentally clocked out, I spent last night and this morning going over the notes for today and ngl i understood it better before he started explaining it

AWWWWWW

$$\begin{array}{ccc} A & \xrightarrow{f} & B \\ & \searrow & \downarrow g \\ & & C \end{array}$$

$g \circ f$