

# Automated SAT-based Analysis of Relational Models and Code

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# Contents

- SAT-solving
- Alloy and the Alloy Analyzer
- KodKod
- TACO: Translation of Annotated CQode
- Conclusions and further work

# SAT-Solving

- The SAT problem: given a propositional formula  $A$ , find a satisfying valuation  $v : \text{Vars} \rightarrow \{\top, \perp\}$ .
- First problem to be known as NP-complete.

# SAT-Solving

- A *literal* is a variable  $v$  or its negation ( $\text{not } v$ )
- A literal is *pure* if it appears always with the same sign.
- A clause is a disjunction of literals:  
 $v_1 \text{ or not } v_2 \text{ or ... or not } v_k \{v_1, \text{not } v_2, \dots, \text{not } v_k\}$
- A *unit clause* contains a single literal.
- A formula is in *conjunctive normal form* (CNF) if it has the form

$$f = c_1 \text{ and } c_2 \text{ and } \dots \text{ and } c_n$$

where the  $c_i$  are clauses.  $f = \{c_1, c_2, \dots, c_n\}$

# SAT-Solving

The Davis-Putnam-Logemann-Loveland algorithm (1960, 1962):

```
DPLL( $\Phi$ ) =
  if  $\Phi$  is a consistent set of literals then return
    true;
  if  $\Phi$  contains an empty clause then
    return false;
  for every unit clause  $l$  in  $\Phi$ 
     $\Phi :=$  unit-propagate( $l$ ,  $\Phi$ );
  for every literal  $l$  that occurs pure in  $\Phi$ 
     $\Phi :=$  pure-literal-assign( $l$ ,  $\Phi$ );
   $l :=$  choose-literal( $\Phi$ );
  return DPLL( $\Phi \wedge l$ ) OR DPLL( $\Phi \wedge \neg l$ ));
```

# SAT-Solving: Examples

$\phi_1 \wedge v_1 = \{\phi_1 \wedge v_1\} \cap \{\text{not } v_2, v_3\} \cup \{\text{not } v_2, v_3\}$

```
DPLL( $\Phi$ ) =
    if  $\Phi$  is a consistent set of literals then return
        true;
    if  $\Phi$  contains an empty clause then
        return false;
    for every unit clause  $l$  in  $\Phi$ 
         $\Phi := \text{unit-propagate}(l, \Phi)$ ;
    for every literal  $l$  that occurs pure in  $\Phi$ 
         $\Phi := \text{pure-literal-assign}(l, \Phi)$ ;
    if there are literals left then
         $l := \text{choose-literal}(\Phi)$ ;
        return DPLL( $\Phi \wedge l$ ) OR DPLL( $\Phi \wedge \text{not}(l)$ );
```

# The Alloy Modeling Language (Jackson)

- Allows to describe data domains, and operations on such domains.
- The Alloy Analyzer allows to analyze whether properties hold in the models (but within bounded sizes for data domains).

# A Simple Alloy Model

```
sig A
one sig B
fact reflexive { B in A }
fact transitive { (Rel.r) in Rel & B in A implies exists C in A (Rel.r = B <::* (Rel.r)) }
```

a field  
containing a  
binary relation  
only “one”  
facts are axioms  
relation composition of  
n-ary relations  
property to be verified  
using the reflexive-transitive  
closure

```
assert rEqualsItsClosure { Rel.r = A<::*(Rel.r) }
check rEqualsItsClosure for 5
```

gives instructions to the Alloy  
Analyzer on the sizes of data domains

# Alloy: Relational Semantics

A is a set, unary      r is a

relation      Rel is a ternary relation

singleton [Rel]

r in Rel x A

sig A { }

one sig Rel { r : A -> A }

fact reflexive { A<:iden in Rel.r }

fact transitive { (Rel.r).(Rel.r) in Rel.r }

“.” is composition.

assert rEqualsItsClosure { Rel.r = A<:\*(Rel.r) }

check rEqualsItsClosure for 5

= {Rel}.{(Rel,a1,a2): (Rel,a1,a2) in r}

= {(a1,a2): (Rel,a1,a2) in r}.

# The Alloy Analyzer

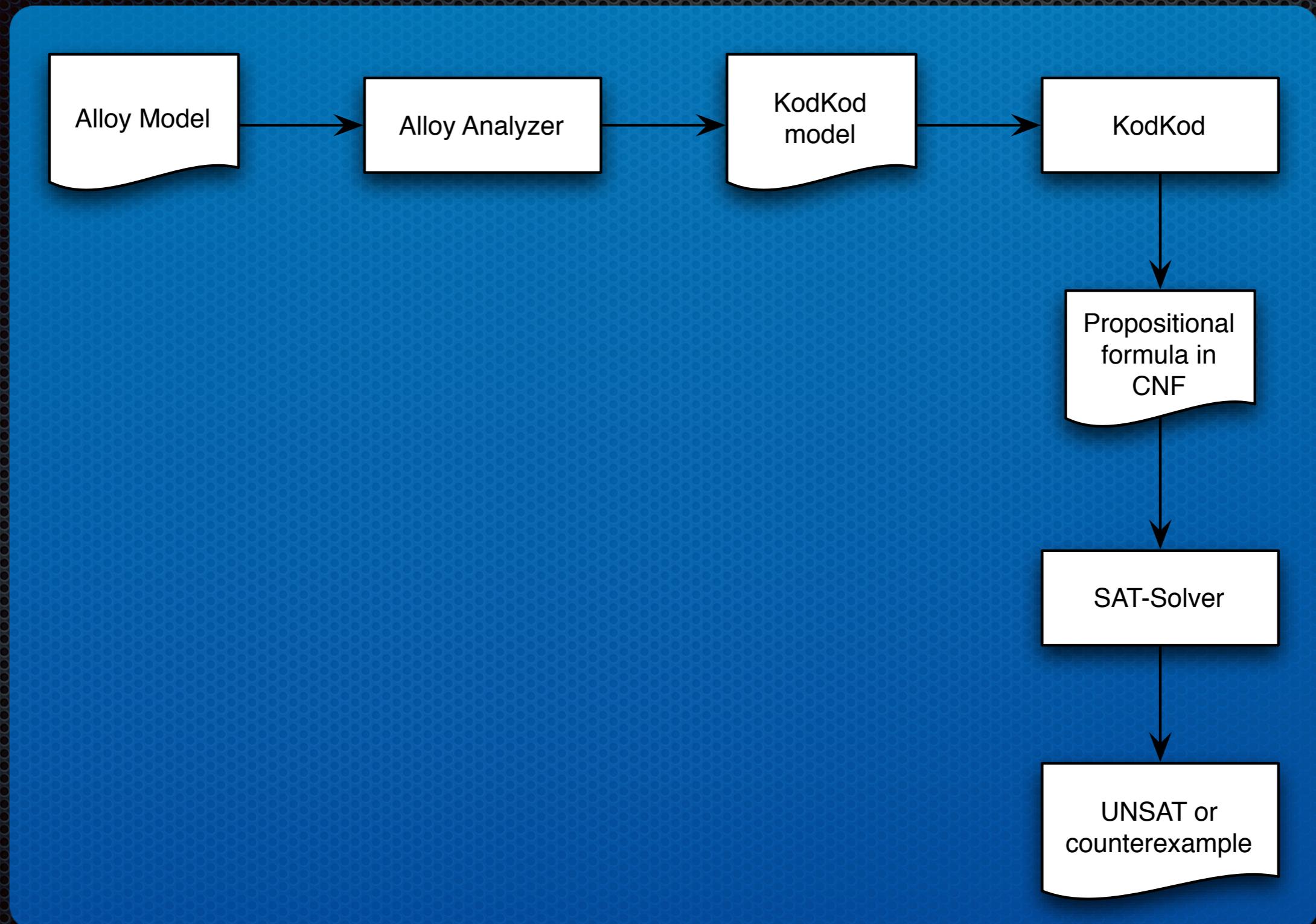
- open rEqualsItsClosure

# The Alloy Analyzer

- For increasing scopes we get the following analysis times (TO means > 48hours).

8	9	10	11	12	13	14
00:00:04	00:05:22	00:58:58	04:05:41	36:34:13	TO	TO

# The Alloy Analyzer

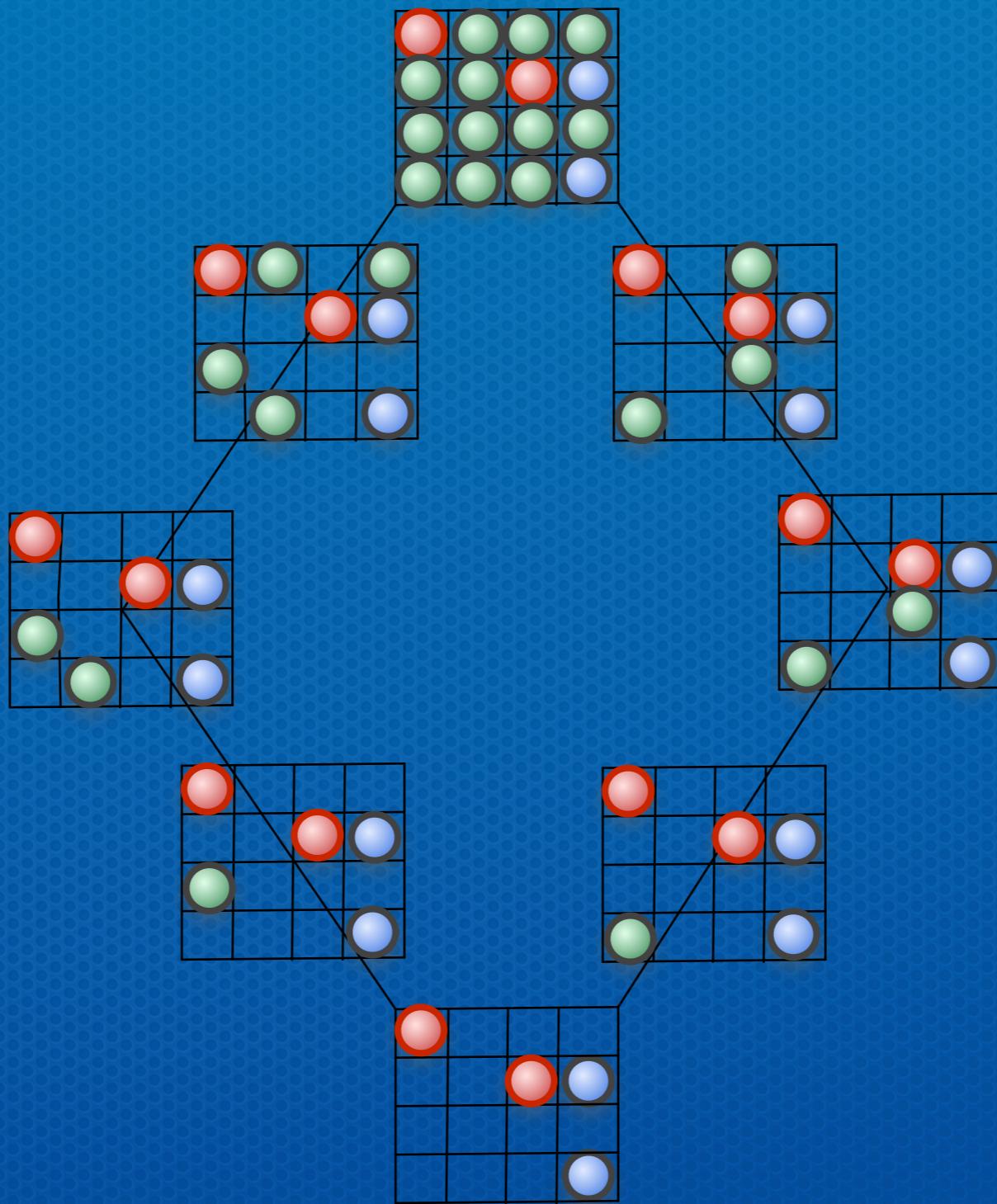


# KodKod (Torlak, Jackson)

- For each relation symbol  $R$ , there are lower and upper bounds  $l_R$  and  $u_R$ .
- If a tuple  $t$  in  $l_R$ , then  $t$  must occur in every interpretation for  $R$ .
- If  $t$  does not occur in  $u_R$ , then  $t$  cannot occur in any interpretation for  $R$ .

# KodKod

Intuitively,



# KodKod: From Relational to Propositional

- Let  $R$  and  $S$  be binary relations on a set  $A$ . Let  $A$ 's scope be 3. Then:

$$R \rightsquigarrow \begin{pmatrix} r_{11} & r_{12} & r_{13} \\ r_{21} & r_{22} & r_{23} \\ r_{31} & r_{32} & r_{33} \end{pmatrix} \quad S \rightsquigarrow \begin{pmatrix} s_{11} & s_{12} & s_{13} \\ s_{21} & s_{22} & s_{23} \\ s_{31} & s_{32} & s_{33} \end{pmatrix}$$

$r_{ij}$  is a propositional variable modeling whether pair  $(i,j)$  is in  $R$ . Similar for  $s_{ij}$ .

# KodKod: From Relational to Propositional

- For transposition (converse), we have:

Relational terms are mapped  
to matrices of  
propositional  
formulas

 $\check{S}$ 

$$\begin{pmatrix} s_{11} & s_{21} & s_{31} \\ s_{12} & s_{22} & s_{32} \\ s_{13} & s_{23} & s_{33} \end{pmatrix}$$

- For join (union), we have:

$$R + \check{S} \rightsquigarrow \begin{pmatrix} r_{11} \vee s_{11} & r_{12} \vee s_{21} & r_{13} \vee s_{31} \\ r_{21} \vee s_{12} & r_{22} \vee s_{22} & r_{23} \vee s_{32} \\ r_{31} \vee s_{13} & r_{32} \vee s_{23} & r_{33} \vee s_{33} \end{pmatrix}$$

# KodKod: From Relational to Propositional

- For equalities between terms:

It is extended to connectives and quantifiers

$$(r_{11} \vee s_{11} \Leftrightarrow t_{11}) \wedge (r_{12} \vee s_{21} \Leftrightarrow t_{12}) \wedge (r_{13} \vee s_{31} \Leftrightarrow t_{13}) \wedge \dots$$
$$\left( \begin{array}{ccc} r_{12} \vee s_{21} & r_{13} \vee s_{31} \\ r_{22} \vee s_{22} & r_{23} \vee s_{32} \\ r_{32} \vee s_{23} & r_{33} \vee s_{33} \end{array} \right) = \left( \begin{array}{ccc} t_{11} & t_{12} & t_{13} \\ t_{21} & t_{22} & t_{23} \\ t_{31} & t_{32} & t_{33} \end{array} \right)$$

# DynAlloy (Frias et al.)

- Is an extension of Alloy to model behavior.
- Semantics inspired on Dynamic logic.
- Allows to define atomic and composite actions.

# DynAlloy: Atomic Actions

```
action Increment[x : Int] {  
    pre { gt[x,0] }  
    post { x' = add[x,1] }  
}
```

Precondition

to be satisfied by input

Postcondition.

Primed variables denote values  
in the final state

# DynAlloy: Complex actions

- $A_1 + A_2$  : Nondeterministic choice
- $A_1 ; A_2$  : sequential composition
- $\alpha ?$  : test action ( $\alpha$  is an Alloy formula)
- $*A$  : reflexive transitive closure

# DynAlloy: Analyzability

- We can analyze partial correctness assertions within domain scopes.
- We bound the number of iterations of the  $*$ .

```
assertCorrectness IncrementTwiceAdds2[x : Int] {  
    pre = { gt[x,0] }  
    program = {  
        Increment[x];  
        Increment[x]  
    }  
    post = { x' = add[x,2] }  
}
```

# Automated Analysis of Java Code

- Map the Java class hierarchy to the Alloy signatures hierarchy.
- Map Java atomic sentences to atomic actions.
- Map Java programs to DynAlloy.

# Java to DynAlloy: Atomic

```
act NewC[o : C]
  pre = { true }
  post = {o' !in ObjectsC and o' in ObjectsC'}
```

```
act Setf[o : C, v : C', f : C -> C']
  pre = { o in ObjectsC }
  post = { f' = f ++ (o -> v) }
```

```
act VarAssign[v1, v2 : c]  (abbreviated v1 := v2)
  pre = { true }
  post = { v1' = v2 }
```

# Java to DynAlloy: Code

`stmt1 ; stmt2`       $\mapsto$     `stmt1;stmt2,`

`if (pred) stmt1 else stmt2`    $\mapsto$    `(pred?;stmt1) +`  
                                       `((!pred)?;stmt2)`

`while (pred) {stmt}`       $\mapsto$     `*(pred?;stmt);(!pred)?,`

# Java to DynAlloy: Example

Ensures: property to be established by the method.

“result = true iff x is the value of  
a node in the list”

```
public class LNode extends Object {  
    LNode next;  
    int key;  
}
```

```
public class List extends Object {  
    /*@  
     * invariant (\forall LNode n;  
     *   \reach(this.head, LNode, next).has(n) &&  
     *   !\reach(n.next, LNode, next).has(n));  
     */  
    LNode head;
```

JML syntax.

```
/*@  
 @ ensures (\exists LNode n;  
 @   \reach(this.head, LNode, next).has(n) &&  
 @   n.val==x) <==> \result == true;  
 @*/  
 boolean find(int x) {  
     LNode current;  
     boolean output;  
     current = this.head;  
     output = false;  
     while (output==false && current!=null) {  
         if (current.val == x) {  
             output = true; }  
         current = current.next;  
     }  
     return output;  
 }
```

# Class Hierarchy and Code

```
boolean find(int x) {  
    LNode current;  
    sig Object {}  
    one sig null {} head;  
    sig List extends Object {}  
    sig LNode extends Object {}  
    sig Throwable extends Object {}  
    sig Exception extends Throwable {}  
    sig RuntimeException extends Exception {}  
    one sig NullPointerException extends RuntimeException {}  
}  
return output;
```

```
program find[  
    this_L>List, result:Boolean, x:Int,  
    head>List->one(LNode+null),  
    next:LNode->one(LNode+null),  
    val:LNode->one Int]{  
    var [current:LNode, output:Boolean]  
    current := this_L.head;  
    output := False[];  
    while (output=False[] && current!=null) {  
        if (current.val = x) {  
            output := True[]  
        }  
        result := output  
    }  
}
```

# Java to DynAlloy: Checking Correctness

```
assertCorrectness find[this_L>List, result:Boolean,  
x:Int,  
head : List -> one (LNode + null),  
next : LNode -> one (LNode + null),  
key : LNode -> one Int ]{  
pre { List_Inv[this_L, head, next] }  
program { find[this_L, result, x, head, next, key] }  
post {ensures_find[this_L,head,next,key,x,result']  
  && List_Inv[this_L, head, next] }  
}
```

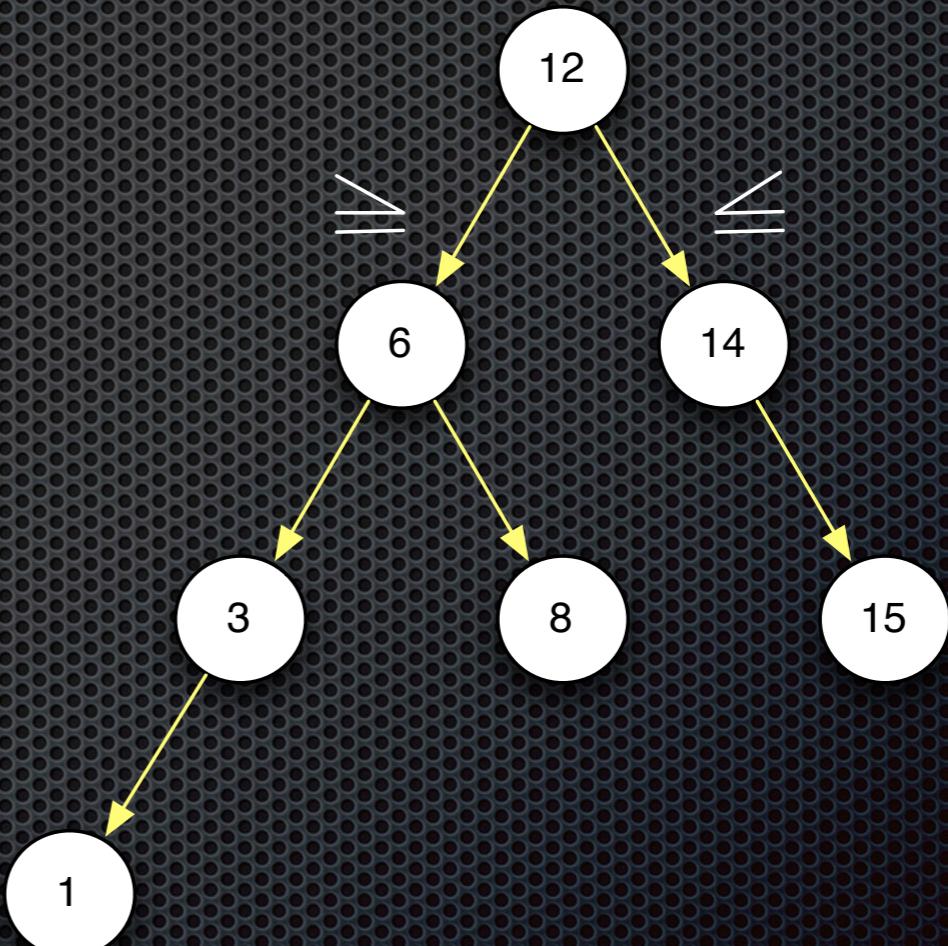
check find for 5

# TACO: Efficient Analysis of Java Code

- TACO: Translation of Annotated COde.
- Uses an efficient technique for reducing KodKod upper bounds.
- Analysis speeds up by several orders of magnitude.
- Experiments show that it improves over state-of-the-art tools based on model checking or SMT-solving.

# A Sample Problem

Generating an instance of AVL-tree.



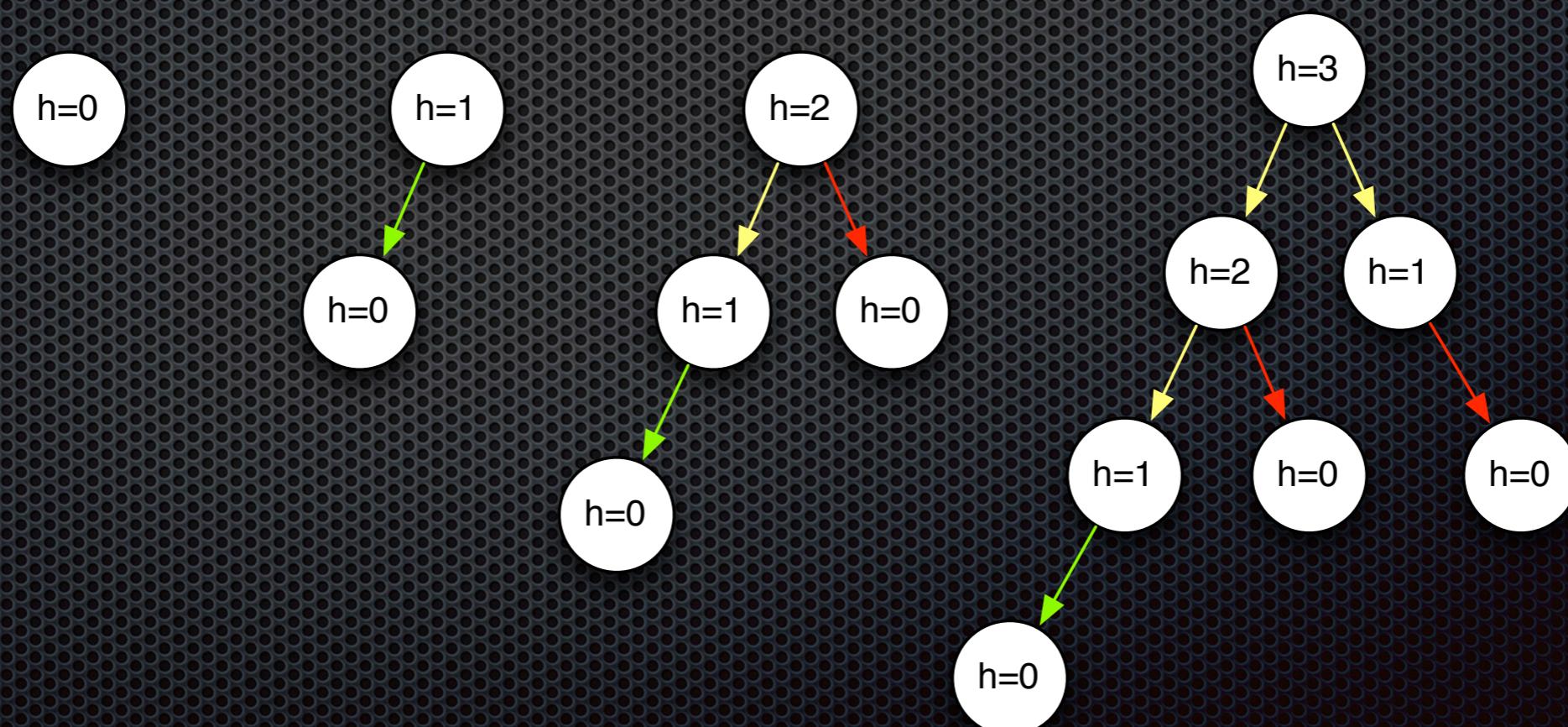
1. Binary tree,
2. Ordered,
3. Balanced:  $|h(\text{left}(n)) - h(\text{right}(n))| \leq 1$

# Technique: Fully Automated Bound Refinement

- To find an instance the SAT-solver attempts to find (using strategies for pruning the state space) a tree **this**, and functions for fields **root**, **h**, **left** and **right** such that the invariant is satisfied.

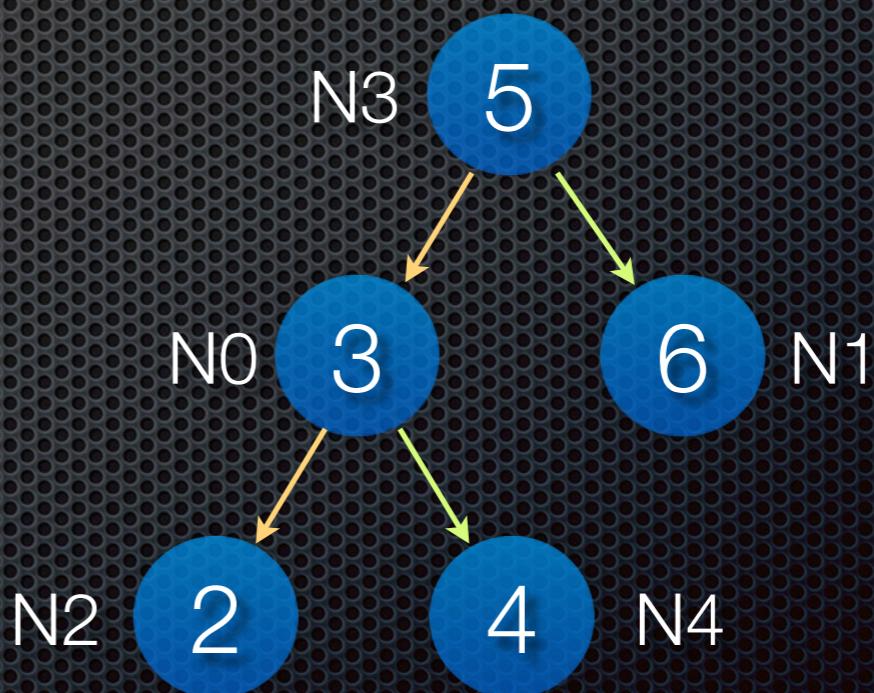
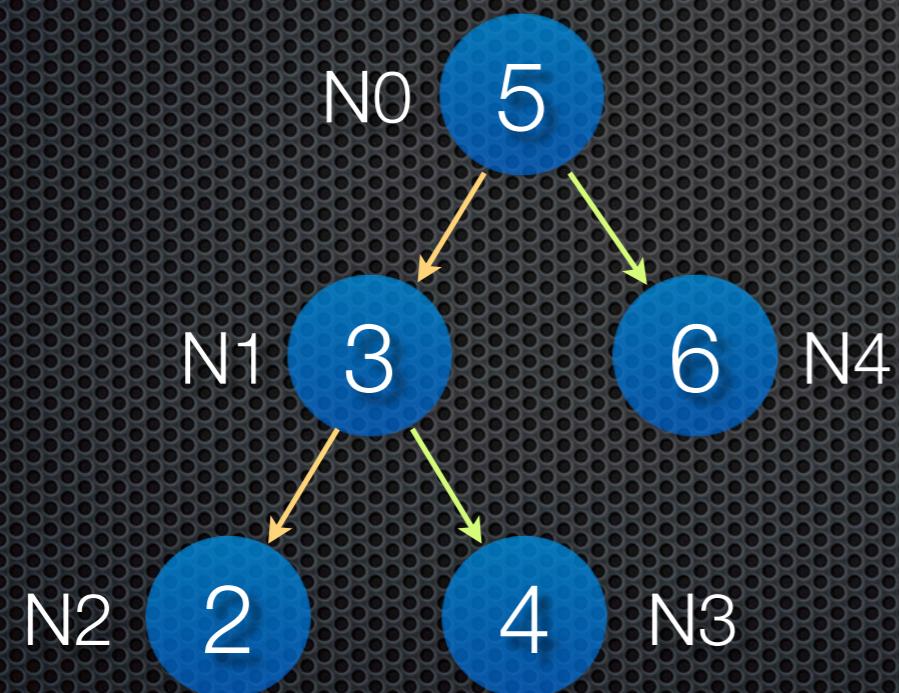
# For AVL trees...

- Regarding field  $h$ , notice that all leaves have  $h = 0$ . Besides, since these are balanced trees, for up to 7 nodes no node satisfies  $h(n)$  greater than 3.



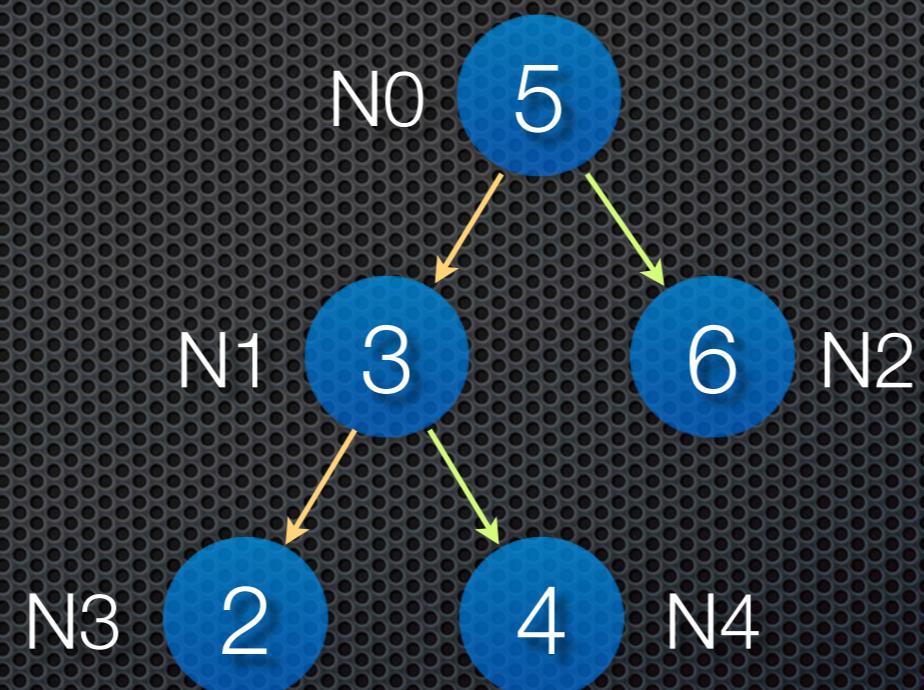
# For AVL trees...

- Since nodes are objects, a node can hold different values (at different times). For instance:

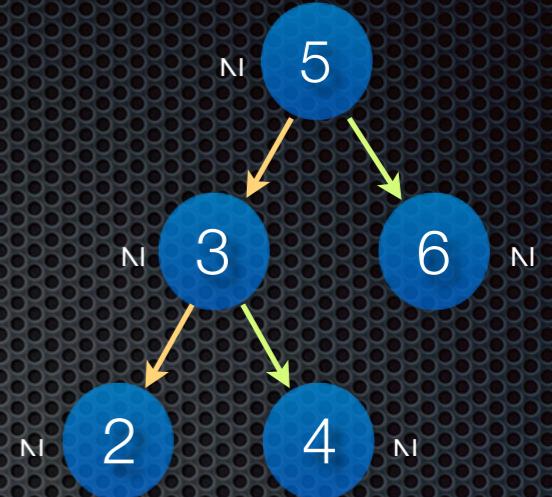


# For AVL trees...

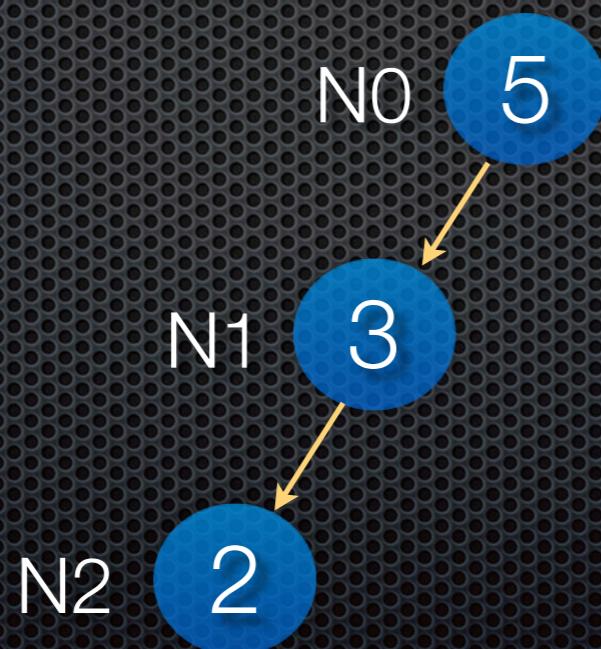
- But if we **force** nodes to be traversed in BFS order...



# For AVL trees...



- Is it possible for N0 to point to a node that is neither N1 nor N2?
- Is it possible for N2 to be pointed to by a node other than N0?



Is not AVL!

# Therefore, there are infeasible values...

- For instance, for a tree with up to 7 nodos,  $h(n) \leq 3$  for all node  $n$ .
- $\text{Left}(N_0)$  is either  $N_1$  or null (but not  $N_2, N_3, \dots$ )
- $\text{Right}(N_0)$  is  $N_1, N_2$  or null (but not  $N_3, N_4, \dots$ )
- $\text{Right}(N_i) \neq N_2$  for  $i \neq 0$ .

# Therefore, there are infeasible values...

- These values correspond to tuples in fields, and therefore, correspond to propositional variables in the KodKod translation.
- If we can remove these infeasible variables, the SAT-solver has fewer assignments to try.

# Refining bounds reduces to:

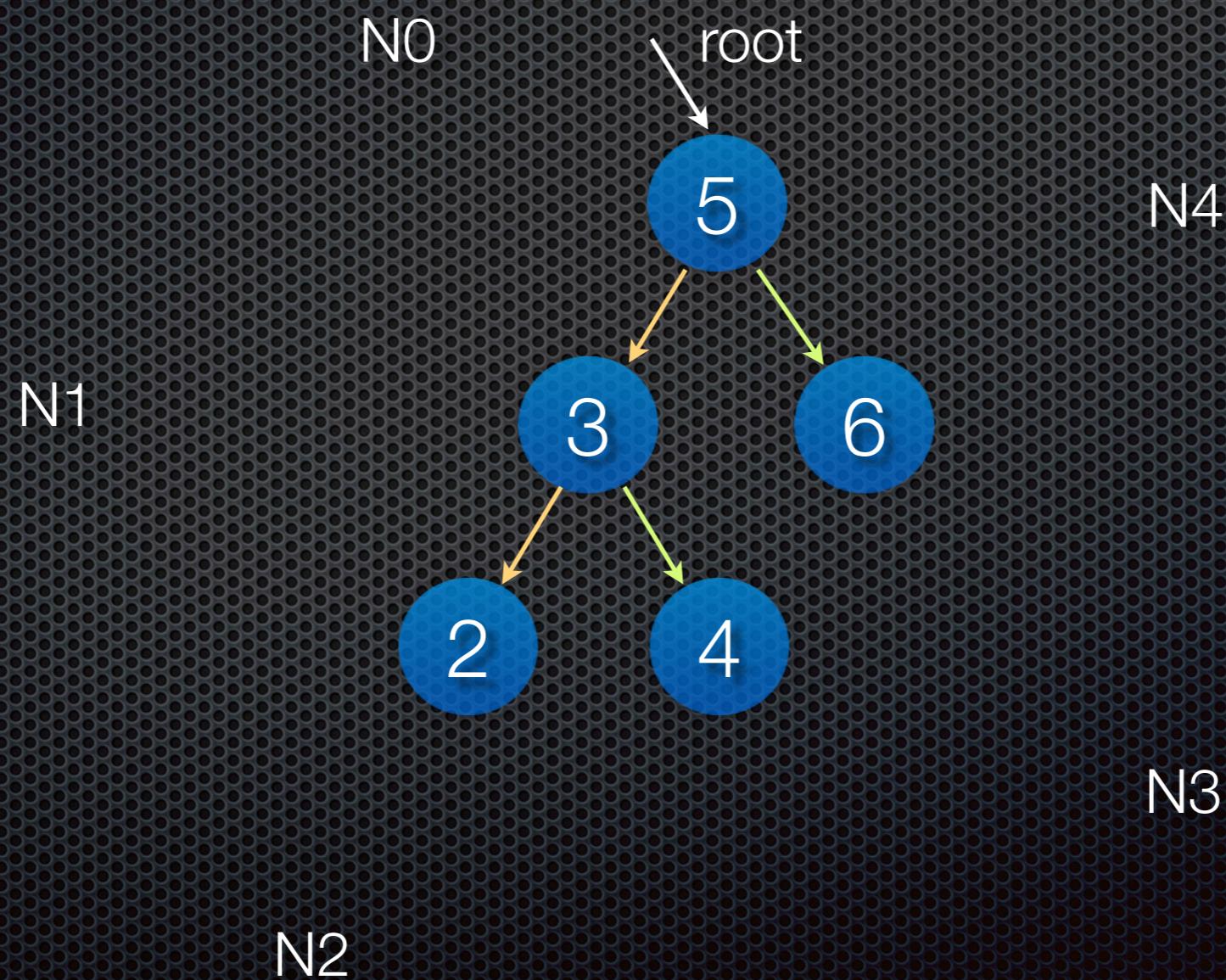
- Forcing nodes to be allocated using a BFS traversal.
- Establishing the infeasible variables for each field.
- Doing all this in a **fully automatic manner**.

# Hints:

- Instrument the relational model with new formulas forcing nodes to be allocated using a BFS ordering.
- Check feasibility for each pair in a class field.

# Instrumenting the model

Rule2: Two nodes with the same parent are labeled from left to right.  
Applying once again Rule 2,



# Testing feasibility

Naive approach: use a cluster to analyze all pair in fields in parallel.

N0.left = N0,  
N0.left = N1,  
...

N0.h = 0,  
N0.h = 1,  
...

For 20 nodes, there are  
2120 analyses to be performed.

Problem...  
generating an AVL tree with  
20 nodes does not  
finish.  
No refined  
bounds yet!

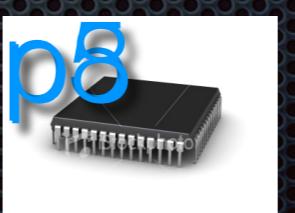
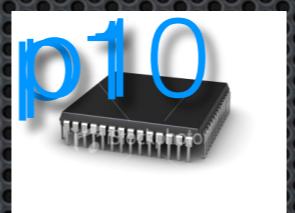
SATs

# An Effective Approach

p11 p10 p9 p8 p7 p6 p5 p4 p3 p2 p1 p0

Bound

p0	p1	p2
p3	p4	p5
p6	p7	p8
p9	p10	p11



UNSATs

TIMEOUTS

# Demo 2: Instances from refined bounds.

open generateAVL10Nodes.als (aprox. 1 minute)

open instGenerateAVL15Nodes.als

# Code Analysis: Experimental Results

We compare with:

- JForge (MIT)
- Java Pathfinder (NASA)
- KIASAN (Kansas State University)
- ESC/Java2 (University College Dublin)
- Jahob (ETH - Zurich)

# Code Analysis: Experimental Results

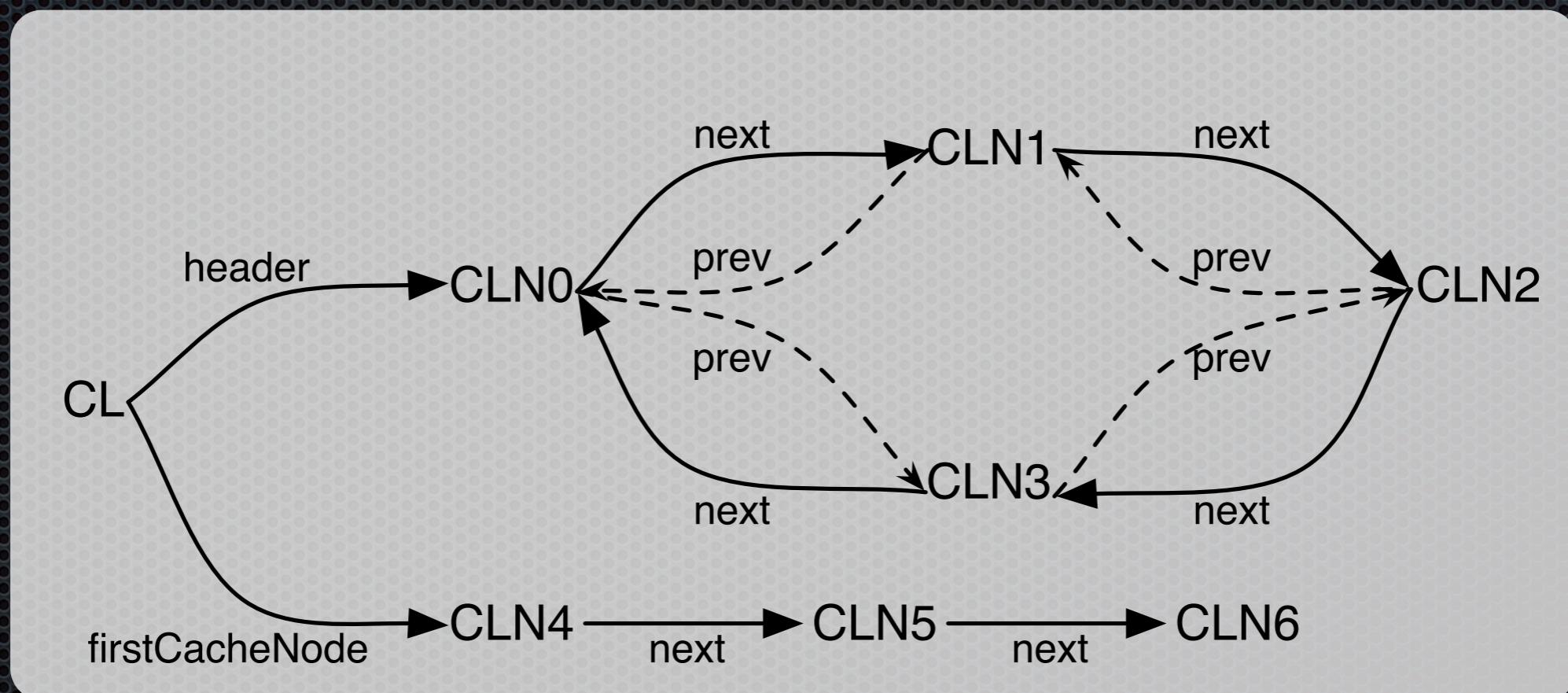
			5	7	10	12	15	17
LList	Cont	NI	00:03	00:05	00:08	00:11	00:13	00:22
		JF	00:01	02:00	TO	TO	TO	TO
		I	00:03	00:04	00:05	00:06	00:07	00:09
	Ins	NI	00:04	00:09	01:14	00:33	04:26	01:25
		JF	00:02	04:56	TO	TO	TO	TO
		I	00:04	00:05	00:07	00:08	00:13	00:26
	Rem	NI	00:05	00:27	TO	TO	TO	TO
		JF	00:04	21:51	TO	TO	TO	TO
		I	00:04	00:06	00:11	00:12	00:17	00:33
AList	Cont	NI	00:05	00:11	00:29	00:38	00:42	01:20
		JF	00:02	05:01	TO	TO	TO	TO
		I	00:04	00:06	00:16	00:22	00:27	00:58
	Ins	NI	00:04	00:05	01:02	26:22	TO	TO
		JF	00:03	11:52	TO	TO	TO	TO
		I	00:04	00:05	00:07	00:08	00:12	00:16
	Rem	NI	00:06	00:14	11:25	05:47:39	TO	TO
		JF	00:18	01:13:27	TO	TO	TO	TO
		I	00:05	00:06	00:17	00:31	01:08	03:13
TreeSet	Find	NI	02:13	04:36:49	TO	TO	TO	TO
		JF	00:42	01:57:49	TO	TO	TO	TO
		I	00:04	00:10	01:56	12:43	58:54	05:05:06
	Ins	NI	21:38	TO	TO	TO	TO	TO
		JF	OofM	OofM	OofM	OofM	OofM	OofM
		I	00:43	08:44	TO	TO	TO	TO

# Code Analysis: Experimental Results

AVL	Find	NI	00:14	27:06	TO	TO	TO	TO
		JF	00:26	03:10:10	TO	TO	TO	TO
		I	00:03	00:06	00:36	01:41	08:20	33:06
	FMax	NI	00:02	00:04	46:12	TO	TO	TO
		JF	00:06	49:49	TO	TO	TO	TO
		I	00:01	00:01	00:03	00:04	00:09	00:13
	Ins	NI	01:20	05:35:51	TO	TO	TO	TO
		JF	OofM	OofM	OofM	OofM	OofM	OofM
		I	00:07	00:34	04:47	21:53	02:53:57	TO
BHeap	Min	NI	00:03	00:41	TO	TO	TO	TO
		JF	00:22	01:23:07	TO	TO	TO	TO
		I	00:02	00:04	00:11	00:20	02:29	00:07
	DecK	NI	00:30	38:58	TO	TO	TO	TO
		JF	01:48	TO	TO	TO	TO	TO
		I	00:10	00:59	24:05	02:42:30	TO	00:26
	Ins	NI	01:55	51:22	TO	TO	TO	TO
		JF	01:13:47	TO	TO	TO	TO	TO
		I	00:16	01:05	10:44	21:31	01:20:09	51:55

# Finding a Nontrivial Bug

- Cache Lists: include a cache where removed nodes are stored so that they are not garbage collected.



# Experimental Results

```

public Object remove(int index) {
    Node node = getNode(index, false);
    Object oldValue = node.getValue();
    super.removeNode(node);
    if (cacheSize >= maximumCacheSize){ 
        return;
    }
    Node nextCacheNode = firstCacheNode;
    node.previous = null;
    node.next = nextCacheNode;
    firstCacheNode = node;
    return oldValue;
}

```

```

public Object remove(int index) {
    Node node = getNode(index, false);
    Object oldValue = node.getValue();
    super.removeNode(node);
    if (cacheSize > maximumCacheSize){ 
        return;
    }
    Node nextCacheNode = firstCacheNode;
    node.previous = null;
    node.next = nextCacheNode;
    firstCacheNode = node;
    return oldValue;
}

```

LU	JForge	ESC/Java2	JPF	Kiasan	Jahob	TACO
4	OofM(227)	OofM(206)	TO	OofM(4)	03:03:19	03:52 + 03:56
6	TO	OofM(207)	TO	OofM(4)	05:05:29	03:52 + 31:14
8	OofM(287)	OofM(213)	TO	OofM(4)	07:39:01	03:52 + 33:23
10	05:40:22	OofM(215)	TO	OofM(4)	TO	03:52 + 00:11
12	06:53:04	OofM(219)	TO	OofM(4)	TO	03:52 + 03:30
15	24:08	OofM(219)	TO	OofM(4)	TO	03:52 + 15:00
20	TO	OofM(218)	TO	OofM(4)	TO	03:52 + 00:06

• Thanks!

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