

## The Derivation of EM algorithm

The model is

$$Y = X\gamma + G_A + G_B + e$$

$Y$ :  $N \times 1$  matrix, records trait value.

$X$ :  $N \times p$  matrix, records the covariant.

$\gamma$ :  $p \times 1$ , the effect of covariant.

$G_A$ : the gene effect for Gene A, treated as an random effect.  $G_A \sim N(0, \tau_A S_A)$ ,  $S_A$  is the similarity matrix which records the genetic similarity between individuals.

$G_B$ : the gene effect for Gene B, also treated as an random effect.  $G_A$  and  $G_B$  are assumed to be independent.

$e$ :  $N \times 1$  matrix, the error term.  $e \sim N(0, \sigma I)$ .

Define  $U = A^T Y$  with the restriction that  $A^T A = I_{N-p}$  and  $AA^T = I - P_X$ .

It is easy to find out that :  $E(U) = 0$  and  $Var(U) = A^T V A$  where  $V = Var(Y) = \tau_A S_A + \tau_B S_B + \sigma I$ .

$$\begin{aligned} Cov(U, G_A) &= Cov(A^T X \gamma + A^T G_A + A^T G_B + A^T e, G_A) \\ &= Cov(A^T G_A, G_A) \\ &= A^T Cov(G_A, G_A) \\ &= \tau_A A^T S_A \end{aligned}$$

In the same way, we have  $Cov(U, G_B) = \tau_B A^T S_B$  and  $Cov(G_A, G_B) = 0$  since they are independent.

Therefore, the joint distribution of  $(U, G_A, G_B)^T$  is

$$\begin{pmatrix} U \\ G_A \\ G_B \end{pmatrix} \sim MN \left( \mu = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}, \quad \Sigma = \begin{pmatrix} A^T V A & \tau_A A^T S_A & \tau_B A^T S_B \\ \tau_A S_A A & \tau_A S_A & 0 \\ \tau_B S_B A & 0 & \tau_B S_B \end{pmatrix} \right)$$

so we can have the following conditional mean and variance,

1. the conditional mean and variance for  $U$  are

$$\begin{aligned} E(U|G_A, G_B) &= A^T (G_A + G_B) \\ Var(U|G_A, G_B) &= \sigma I_{N-p} \end{aligned}$$

2. the conditional mean and variance for  $G_A$ , since  $Cov(G_A, G_B) = 0$

$$\begin{aligned} E(G_A|G_B, U) &= E(G_A|U) \\ &= \tau_A S_A A (A^T V A)^{-1} A^T Y \\ Var(G_A|G_B, U) &= Var(G_A|U) \\ &= \tau_A S_A - \tau_A^2 S_A A (A^T V A)^{-1} A^T S_A \end{aligned}$$

Simple algebra shows that  $A(A^T V A)^{-1} A^T = P = V^{-1} - V^{-1} X (X^T V^{-1} X)^{-1} X^T V^{-1}$ , so that

$$\begin{aligned} E(G_A|G_B, U) &= \tau_A S_A P Y = g_A \\ Var(G_A|G_B, U) &= \tau_A S_A - \tau_A^2 S_A P S_A = v_A \end{aligned}$$

3. Similarly, the conditional mean and variance for  $G_B$  are

$$\begin{aligned} E(G_B|G_A, U) &= \tau_B S_B P Y = g_B \\ \text{Var}(G_B|G_A, U) &= \tau_B S_B - \tau_B^2 S_B P S_B = v_B \end{aligned}$$

Define  $\theta = \{\sigma, \tau_A, \tau_B\}$ , according to the EM algorithm, we need to first compute the  $\log L(\theta^{(t)}|U, G_A, G_B)$ ,

$$\begin{aligned} \log L(\theta^{(t)}|U, G_A, G_B) &= f(U, G_A, G_B|\theta^{(t)}) \\ &= \log f(U|G_A, G_B, \theta^{(t)}) + \log f(G_A|\theta^{(t)}) + \log f(G_B|\theta^{(t)}) \end{aligned}$$

Since  $S_A$  and  $S_B$  are singular, we have,

$$f(G_A) = \frac{1}{((2\pi)^{\text{rank}(S_A)} |\tau_A S_A|_+)^{\frac{1}{2}}} \exp\left(-\frac{1}{2} G_A^T (\tau_A S_A)^- G_A\right)$$

where  $|\tau_A S_A|_+$  is the Pseudo-Determinant, and  $(\tau_A S_A)^-$  is the Generalized inverse.

Define  $\text{rank}(S_A) = q_A$ ,  $\text{rank}(S_B) = q_B$ , we have,

$$\begin{aligned} f(G_A) &= \frac{1}{((2\pi)^{q_A} \tau_A^{q_A} |S_A|_+)^{\frac{1}{2}}} \exp\left(-\frac{1}{2\tau_A} G_A^T (S_A)^- G_A\right) \\ f(G_B) &= \frac{1}{((2\pi)^{q_B} \tau_B^{q_B} |S_B|_+)^{\frac{1}{2}}} \exp\left(-\frac{1}{2\tau_B} G_B^T (S_B)^- G_B\right) \end{aligned}$$

therefore,

$$\begin{aligned} \log f(G_A) &= \text{constant} - \frac{q_A}{2} \log \tau_A - \frac{1}{2} \log(|S_A|_+) - \frac{1}{2\tau_A} G_A^T S_A^- G_A \\ \log f(G_B) &= \text{constant} - \frac{q_B}{2} \log \tau_B - \frac{1}{2} \log(|S_B|_+) - \frac{1}{2\tau_B} G_B^T S_B^- G_B \\ \log f(U|G_A, G_B) &= \text{constant} - \frac{N-p}{2} \log \sigma - \frac{1}{2\sigma} \left[ (Y - G_A - G_B)^T (I - P_X) (Y - G_A - G_B) \right] \end{aligned}$$

EM algorithm treats  $G_A$  and  $G_B$  as missing values. So instead of estimating  $G_A$  and  $G_B$  and then plugging them into the  $\log L$ , EM algorithm calculate the expectation of  $\log L$  given  $U$  and  $\theta^{(t-1)}$ , then based on  $E(\log L|U, \theta^{(t-1)})$ ,  $\theta^{(t)}$  are calculated by taking partial derivative.

$$E(\log L|U, \theta^{(t-1)}) = E(\log f(G_A)|U, \theta^{(t-1)}) + E(\log f(G_B)|U, \theta^{(t-1)}) + E(\log f(U|G_A, G_B)|\theta^{(t-1)})$$

It is easy to find out that to estimate  $\tau_A^{(t)}$ , we just need to consider  $E(\log f(G_A)|U, \theta^{(t-1)})$ , so let

$$\frac{\partial E(\log f(G_A)|U, \theta^{(t-1)})}{\partial \tau_A} = 0$$

we have,

$$-\frac{q_A}{2\tau_A} + \frac{1}{2\tau_A^2} E(G_A^T S_A^- G_A|U, \theta^{(t-1)}) = 0$$

$$E(G_A^T S_A^- G_A|U, \theta^{(t-1)}) = (g_A^{(t-1)})^T S_A^- g_A^{(t-1)} + \text{tr}(S_A^- v_A^{(t-1)})$$

plugging the expression of  $g_A^{(t-1)}$  and  $v_A^{(t-1)}$ , finally we have

$$\tau_A^{(t)} = \tau_A^{(t-1)} + \frac{[\tau_A^{(t-1)}]^2}{q_A} \left[ Y^T P S_A P Y - \text{tr}(S_A P) \right]$$

In the same way, we can estimate  $\tau_B^{(t)}$  by

$$\tau_B^{(t)} = \tau_B^{(t-1)} + \frac{[\tau_B^{(t-1)}]^2}{q_B} \left[ Y^T P S_B P Y - \text{tr}(S_B P) \right]$$

To estimate  $\sigma^{(t)}$ , we just need to consider  $E\left(\log f(U|G_A, G_B) \middle| \theta^{(t-1)}\right)$ , so the final expression of  $\sigma^{(t)}$  is

$$\sigma^{(t)} = \frac{1}{N-p} \left\{ \left[ (Y^*)^T (I - P_X) Y^* \right] + \text{tr} \left[ (I - P_X) \left( \tau_A^{(t-1)} S_A - (\tau_A^{(t-1)})^2 S_A P S_A + \tau_B^{(t-1)} S_B - (\tau_B^{(t-1)})^2 S_B P S_B \right) \right] \right\}$$

where  $Y^* = Y - \tau_A^{(t-1)} S_A P Y - \tau_B^{(t-1)} S_B P Y$