

Talk on 2010-06-24: The EM-REML algorithm

Model:

$$Y_i = X_i\beta + Z_i b_i + e_i$$

where $b_i \sim N(0, D)$ and $e_i \sim N(0, \sigma I)$.

Define $U = H_1^T Y_i = H_1^T (X_i\beta + Z_i b_i + e_i) = H_1^T X_i\beta + H_1^T Z_i b_i + H_1^T e_i$, we have,

$$\begin{aligned} E(U) &= E(H_1^T X_i\beta + H_1^T Z_i b_i + H_1^T e_i) = E(H_1^T X_i\beta) \\ (H_1^T X_i\beta)^T (H_1^T X_i\beta) &= \beta^T X_i^T H_1 H_1^T X_i\beta \\ &= \beta^T X_i^T \underbrace{(I - P_X)}_0 X_i\beta \\ &= 0 \\ \Rightarrow H_1^T X_i\beta &= 0 \\ \Rightarrow E(U) &= 0 \end{aligned}$$

Let $\text{Var}(Y) = V = Z_i D Z_i^T + \sigma I$, so we have $\text{Var}(U) = H_1^T V H_1$. Since U and b are normal distributed, the joint distribution of them is also normal distributed, the covariance of U and b is

$$\begin{aligned} \text{Cov}(U, b) &= \text{Cov}(H_1^T X_i\beta + H_1^T Z_i b_i + H_1^T e_i, b) \\ &= \text{Cov}(H_1^T Z_i b_i, b) \\ &= H_1^T Z_i \text{Var}(b) = H_1^T Z_i D \end{aligned}$$

Therefore, the distribution of $(U, b)^T$ is

$$\begin{pmatrix} U \\ b \end{pmatrix} \sim MN\left(\mu = \begin{pmatrix} 0 \\ 0 \end{pmatrix}, \Sigma = \begin{pmatrix} H_1^T V H_1 & H_1^T Z_i D \\ D Z_i^T H_1 & D \end{pmatrix}\right)$$

therefore, we have

$$\begin{aligned} E(b|U) &= 0 + (D Z_i^T H_1)(H_1^T V H_1)^{-1}(H_1^T Y_i) \\ &= D Z_i^T \underbrace{H_1 H_1^T V H_1}_P^{-1} H_1^T Y_i \\ &= D Z_i^T P Y_i \end{aligned} \tag{1}$$

and

$$\begin{aligned} \text{Var}(b|U) &= D - D Z_i^T \underbrace{H_1 H_1^T V H_1}_P^{-1} H_1^T Z_i D \\ &= D - D Z_i^T P Z_i D \end{aligned} \tag{2}$$

In the same way, we have the conditional expectation and covariance for e_i ,

$$E(e_i|U) = \sigma PY_i \quad (3)$$

$$Var(e|U) = \sigma I - \sigma^2 P \quad (4)$$

Question: how to get the REML estimation of \hat{D} in terms of b ? We have the REML log-likelihood function:

$$L_{REML} = -\frac{1}{2}(\ln|V| + \ln|X^T V^{-1} X| + Y^T P Y)$$

To get the estimation, we should set

$$\frac{\partial \log L_{REML}}{\partial \hat{D}} = 0$$

but how is the above equation related to b ?

According to the paper "Random-Effect Model for Longitudinal Data" by Nan M. Laird(1982), we can use the sufficient estimator \mathbf{t}_1 to estimate \hat{D}

$$\hat{D} = \frac{\sum_1^n b_i b_i^T}{n} = \frac{\mathbf{t}_1}{n} \quad (5)$$

where

$$\begin{aligned} \hat{\mathbf{t}}_1 &= E\left(\sum_1^n b_i b_i^T | y, D, \sigma\right) \\ &= \sum_1^n [E(b_i | y, D, \sigma) E(b_i | y, D, \sigma^T) + var(b | y, D, \sigma)] \end{aligned} \quad (6)$$

In the same, we can use the sufficient estimator \mathbf{t}_2 to estimate σ by

$$\hat{\sigma} = \frac{\sum_1^n e_i^T e_i}{n} = \frac{\mathbf{t}_2}{n} \quad (7)$$

where

$$\begin{aligned} \hat{\mathbf{t}}_2 &= E\left(\sum_1^n e_i e_i^T | y, D, \sigma\right) \\ &= \sum_1^n [E(e_i | y, D, \sigma) E(e_i | y, D, \sigma^T) + tr(var(e | y, D, \sigma))] \end{aligned} \quad (8)$$

So the EM algorithm can be described as:

1. Set the initial value for D and σ .
2. Compute the conditional expectation and variance of b_i and e_i using (1)-(4).
3. Compute the sufficient estimator \mathbf{t}_1 and \mathbf{t}_2 using (6) and (8).
4. Compute the estimation of \hat{D} and $\hat{\sigma}$.
5. Repeat step 2-4 until \hat{D} and $\hat{\sigma}$ converge.