Topics

standard Java Collections classes.

, ListIterators
s and maps in the abstract
nalysis of implementing lists with arrays.

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Data Types in the Abstract

time, should *not* worry about implementation of data

search, etc.

o for us—their specification—is important.

eral standard types (in java.util) to represent collec-

aces:

tion: General collections of items.
ndexed sequences with duplication
rtedSet: Collections without duplication
rtedMap: Dictionaries (key
value)

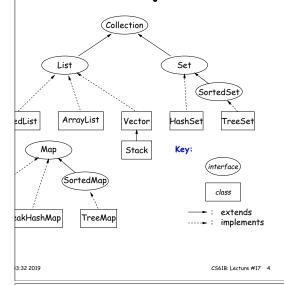
classes that provide actual instances: LinkedList, ArrayList,

TreeSet.

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hange easier, purists would use the concrete types only nterfaces for parameter types, local variables.

Collection Structures in java.util



about Library Design: Optional Operations

ections need to be modifiable; often makes sense just

rations are optional (add, addAll, clear, remove, removeAll,

developers decided to have *all* Collections implement lowed implementations to throw an exception:

UnsupportedOperationException

ve design would have created separate interfaces:

```
lection { contains, containsAll, size, iterator, ... }
andable extends Collection { add, addAll }
inkable extends Collection { remove, removeAll, ... }
ifiableCollection
llection, Expandable, Shrinkable { }
```

ave lots of interfaces. Perhaps that's why they didn't v.

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The Collection Interface

terface. Main functions promised:

```
nip tests: contains (∈), containsAll (⊆)
ries: size, isEmpty
iterator, toArray
```

modifiers: add, addAll, clear, remove, removeAll (set

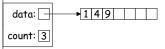
e), retainAll (intersect)

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mplementing Lists (I): ArrayLists

ncrete types in Java library for interface List are nd LinkedList:

t expect, an ArrayList, A, uses an array to hold data. , a list containing the three items 1, 4, and 9 might be like this:



four more items to A, its data array will be full, and data will have to be replaced with a pointer to a new, that starts with a copy of its previous values.

r best performance, how big should this new array be?

se the size by 1 each time it gets full (or by any conthe cost of N additions will scale as $\Theta(N^2)$, which List look much worse than ${\tt LinkedList}$ (which uses an implementation.)

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The List Interface

lection

represent indexed sequences (generalized arrays)

thods to those of Collection:

hip tests: indexOf, lastIndexOf.

get(i), listIterator(), sublist(B, E).

add and addAll with additional index to say where to wise for removal operations. set operation to go with

erator<Item> extends Iterator<Item>:

vious and hasPrevious.

ve, and set allow one to iterate through a list, inserting, or changing as you go.

Question: What advantage is there to saying List L an LinkedList L or ArrayList L?

Amortized Time

t the actual costs of a sequence of N operations are $_{-1}$, which may differ from each other by arbitrary amounts $\in O(f(i))$.

ther sequence $a_0, a_1, \ldots, a_{N-1}$, where $a_i \in O(g(i))$.

$$\sum_{0 \le i < k} a_i \ge \sum_{0 \le i < k} c_i \text{ for all } k,$$

the operations all run in O(g(i)) amortized time.

actual cost of a given operation, c_i , may be arbitrarily the amortized time, a_i , as long as the total amortized ys greater than or equal to the total actual time, no e the sequence of operations stops—i.e., no matter what

nterest, the amortized time bounds are much less than dividual time bounds: $q(i) \ll f(i)$.

case of insertion with array doubling, $f(i) \in O(N)$ and

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Expanding Vectors Efficiently

array for expanding sequence, best to double the size row it. Here's why.

ze s, doubling its size and moving s elements to the new time proportional to 2s.

there is an additional $\Theta(1)$ cost for each addition to actually assigning the new value into the array.

Id up these costs for inserting a sequence of N items, t turns out to be proportional to N, as if each addition t time, even though some of the additions actually take ional to N all by themselves!

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ating Amortized Time: Potential Method

the argument, associate a potential, $\Phi_i \geq 0$, to the i^{th} at keeps track of "saved up" time from cheap operations spend" on later expensive ones. Start with $\Phi_0 = 0$.

end that the cost of the $i^{\dagger h}$ operation is actually a_i , the st, defined

$$a_i = c_i + \Phi_{i+1} - \Phi_i,$$

he real cost of the operation. Or, looking at potential:

$$\Phi_{i+1} = \Phi_i + (a_i - c_i)$$

erations, we artificially set $a_i>c_i$ so that we can in- $_{+1}>\Phi_i$).

ones, we typically have $a_i \ll c_i$ and greatly decrease Φ it go negative—may not be "overdrawn").

all this so that a_i remains as we desired (e.g., O(1) for ray), without allowing $\Phi_i < 0$.

It we choose a_i so that Φ_i always stays ahead of c_i .

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ortization: Expanding Vectors (II)

	Resizing Cost	Cumulative Cost		Array Size After Insertions
	0	0	0	1
	2	2	1	2
	4	6	2	4
	0	6	1.5	4
	8	14	2.8	8
	0	14	2.33	8
	:	:	:	:
	0	14	1.75	8
	16	30	3.33	16
	:	:	:	:
	0	30	1.88	16
	:	:	:	:
- 1	0	$2^{m+2} - 2$ $2^{m+3} - 2$	≈ 2	2^{m+1}
	2^{m+2}	$2^{m+3}-2$	≈ 4	2^{m+2}

out (amortize) the cost of resizing, we average at most units for resizing on each item: "amortized resizing ts." Time to add N elements is $\Theta(N)$, not $\Theta(N^2)$.

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