

- Selection sorts, heap sort
- Merge sorts
- Quicksort

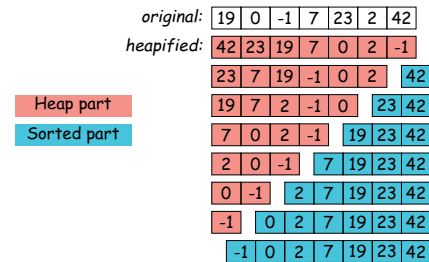
Readings: Today: *DS(IJ)*, Chapter 8; Next topic: Chapter 9.

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ement.

- Really bad idea on a simple list or vector.
- But we've already seen it in action: use heap.
- Gives $O(N \lg N)$ algorithm (N remove-first operations).
- Since we remove items from end of heap, we can use that area to accumulate result:



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- When covering heaps before, we created them by insertion in an initially empty heap.
- When given an array of unheaped data to start with, there is a faster procedure (assume heap indexed from 0):

```
void heapify(int[] arr) {
    int N = arr.length;
    for (int k = N / 2; k >= 0; k -= 1) {
        for (int p = k, c = 0; 2*p + 1 < N; p = c) {
            c = 2k+1 or 2k+2, whichever
            is < N
            and indexes larger value
            in arr;
            swap elements c and k of arr;
        }
    }
}
```

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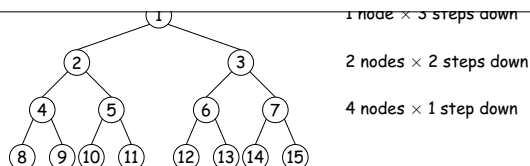
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is removed, repeated $N/2$ times.

- But instead of being $\Theta(N \lg N)$, it's just $\Theta(N)$.

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- In general, worst-case cost for a heap with $h+1$ levels is

$$\begin{aligned}
 & 2^0 \cdot h + 2^1 \cdot (h-1) + \dots + 2^{h-1} \cdot 1 \\
 &= (2^0 + 2^1 + \dots + 2^{h-1}) + (2^0 + 2^1 + \dots + 2^{h-2}) + \dots + (2^0) \\
 &= (2^h - 1) + (2^{h-1} - 1) + \dots + (2^1 - 1) \\
 &= 2^{h+1} - 1 - h \\
 &\in \Theta(2^h) = \Theta(N)
 \end{aligned}$$

- Alas, since the rest of heapsort still takes $\Theta(N \lg N)$, this does not improve its asymptotic cost.

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sort halves, merge results.

- Already seen analysis: $\Theta(N \lg N)$.
- Good for *external sorting*:
 - First break data into small enough chunks to fit in memory and sort.
 - Then repeatedly merge into bigger and bigger sequences.
- Can merge K sequences of *arbitrary size* on secondary storage using $\Theta(K)$ storage:


```
Data[] V = new Data[K];
For all i, set V[i] to the first data item of sequence i;
while there is data left to sort:
    Find k so that V[k] is smallest;
    Output V[k], and read new value into V[k] (if present).
```

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orchestrate:

L: (9, 15, 5, 3, 0, 6, 10, -1, 2, 20, 8)

0:	0
1:	0
2:	0
3:	0

0 elements processed

0:	1	•	→ (9)
1:	0		
2:	0		
3:	0		

1 element processed

0:	0		
1:	1	•	→ (9, 15)
2:	0		
3:	0		

2 elements processed

0:	1	•	→ (5)
1:	1	•	→ (9, 15)
2:	0		
3:	0		

3 elements processed

0:	0		
1:	0		
2:	1	•	→ (3, 5, 9, 15)
3:	0		

4 elements processed

0:	0		
1:	1	•	→ (0, 6)
2:	1	•	→ (3, 5, 9, 15)
3:	0		

6 elements processed

0:	1	•	→ (8)
1:	1	•	→ (2, 20)
2:	0		
3:	1	•	→ (-1, 0, 3, 5, 6, 9, 10)

11 elements processed

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Idea:

- **Partition** data into pieces: everything $>$ a **pivot** value at the high end of the sequence to be sorted, and everything \leq on the low end.
- Repeat recursively on the high and low pieces.
- For speed, stop when pieces are "small enough" and do insertion sort on the whole thing.
- Reason: insertion sort has low constant factors. By design, no item will move out of its will move out of its piece [why?], so when pieces are small, #inversions is, too.
- Have to choose pivot well. E.g.: **median** of first, last and middle items of sequence.

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size ≤ 4 .

- Pivots for next step are starred. Arrange to move pivot to dividing line each time.
- Last step is insertion sort.

16	10	13	18	-4	-7	12	-5	19	15	0	22	29	34	-1*
-4	-5	-7	-1	18	13	12	10	19	15	0	22	29	34	16*
-4	-5	-7	-1	15	13	12*	10	0	16	19*	22	29	34	18
-4	-5	-7	-1	10	0	12	15	13	16	18	19	29	34	2

- Now everything is "close to" right, so just do insertion sort:

-7	-5	-4	-1	0	10	12	13	15	16	18	19	22	29	34
----	----	----	----	---	----	----	----	----	----	----	----	----	----	----

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- If choice of pivots good, divide data in two each time: $\Theta(N \lg N)$ with a good constant factor relative to merge or heap sort.
- If choice of pivots bad, most items on one side each time: $\Theta(N^2)$.
- $\Omega(N \lg N)$ in best case, so insertion sort better for nearly ordered input sets.
- Interesting point: randomly shuffling the data before sorting makes $\Omega(N^2)$ time **very** unlikely!

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smallest element in data.

- Obvious method: sort, select element $\#k$, time $\Theta(N \lg N)$.
- If $k \leq$ some constant, can easily do in $\Theta(N)$ time:
 - Go through array, keep smallest k items.
- Get **probably** $\Theta(N)$ time for all k by adapting quicksort:
 - Partition around some pivot, p , as in quicksort, arrange that pivot ends up at dividing line.
 - Suppose that in the result, pivot is at index m , all elements \leq pivot have indices $\leq m$.
 - If $m = k$, you're done: p is answer.
 - If $m > k$, recursively select k^{th} from left half of sequence.

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tion of array:

Initial contents:

51	60	21	-4	37	4	49	10	40*	59	0	13	2	39	11	46	31
----	----	----	----	----	---	----	----	-----	----	---	----	---	----	----	----	----

Looking for #10 to left of pivot 40:

13	31	21	-4	37	4*	11	10	39	2	0	40	59	51	49	46	60
----	----	----	----	----	----	----	----	----	---	---	----	----	----	----	----	----

Looking for #6 to right of pivot 4:

-4	0	2	4	37	13	11	10	39	21	31*	40	59	51	49	46	60
----	---	---	---	----	----	----	----	----	----	-----	----	----	----	----	----	----

Looking for #1 to right of pivot 31:

-4	0	2	4	21	13	11	10	31	39	37	40	59	51	49	46	60
----	---	---	---	----	----	----	----	----	----	----	----	----	----	----	----	----

Just two elements; just sort and return #1:

-4	0	2	4	21	13	11	10	31	37	39	40	59	51	49	46	60
----	---	---	---	----	----	----	----	----	----	----	----	----	----	----	----	----

Result: 39

each time, cost is

$$C(N) = \begin{cases} 1, & \text{if } N = 1, \\ N + C(N/2), & \text{otherwise.} \end{cases}$$
$$= N + N/2 + \dots + 1$$
$$= 2N - 1 \in \Theta(N)$$

- But in worst case, get $\Theta(N^2)$, as for quick-sort.
- By another, non-obvious algorithm, can get $\Theta(N)$ worst-case time for all k (take CS170).