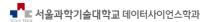
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- I. Motivation estimation of π
- II. Simulation approach
- III. Discussion
- IV. Confidence interval

I. Motivation - estimation of π

What is π ?

 \bullet π is defined as

$$\pi = \frac{\text{a circle's circumference}}{\text{a circle's diameter}}$$

- To list a few reasons why π is such an important quantity:
 - In Architecture
 - In Construction
 - In Art
 - In Military operation
 - so many...

How to estimate?

I. Motivation - estimation of π

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• In your elemetary school



• From your high school, you learned that

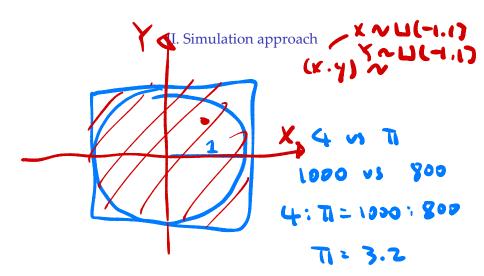


(quarter size of a unit circle)
$$= \int_0^1 \sqrt{1-x^2} dx$$
$$= \pi/4$$

• In ancient days, people used $\pi/4 = \int_0^1 \sqrt{1-x^2} dx$ to estimate π .

I. Motivation - estimation of π

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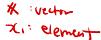


• Step 1.

- Let $X \sim U(-1, 1)$ and $Y \sim U(-1, 1)$.
- Generate two vectors length of N, i.e. $\mathbf{x}=(x_1,x_2,...,x_N)$ and $\mathbf{y}=(y_1,y_2,...,y_N)$, where x_i is a sample of X and y_i is a sample of Y for all i.

Step 2.

• Let $t_i := \sqrt{x_i^2 + y_i^2}$ for all i, that is,





$$\begin{array}{ccc} t_1 & := & \sqrt{x_1^2 + y_1^2} \\ t_2 & := & \sqrt{x_2^2 + y_2^2} \\ \cdots & \cdots \end{array}$$

$$t_{N} := \sqrt{x_N^2 + y_N^2}$$

• Step 3.



$$\underbrace{\frac{\text{number of }\{t_i \leq 1\}}{(N)}}_{\text{N}} = 4 \times \underbrace{\sum_{i=1}^{N} I_{\{t_i \leq 1\}}}_{N}$$

The function $I_{\{\cdot\}}$ is called an *indicator function* that returns 1 if the statement is true and 0 if false.

$$\underbrace{ \sum_{i=1}^N I_{\{t_i \leq 1\}} }_{N}$$

counts the number of t_i that is less than or equal to 1, among all i.

A statistical software, R

- I am a firm believer of that you should comfortably interchange between R and python. R for Pythin wer
- Resources 1 datacamp.com
 - datacamp.com allows access for >100 courses for R and python.
 - I suggest you at least do 'Introduction to R' and 'Intermediate R'.
 - You can subscribe for free using your @seoultech.ac.kr email with the following link. https://www.datacamp.com/groups/shared links/b3b5fc6f798aaf54ada0c03cee875c009 9c34e300f5be6b8375e4850646b0b59
 - The above link expires at March 2021, but I always renew it.
 - You can always request me for an invitation link if yours is expired.
- Resources 2 lecture material for data visualization
 - From the following repository, study L01-L03 for installation and basic usage.
 - https:

//github.com/aceMKSim/teaching/tree/master/Data%20Visualization/Lecture%20Notes

Implementation - basic

• Implementation with 1000 repetitions.

```
MC-N
set.seed(1234) # fix the random seed
N <- 10^3
x <- runif(N)*2-1 # runif() generates U(0,1)
                  the thin what year. UC-1.1)
t < - sqrt(x^2+y^2)
head(cbind(x,y,t)) # always display and check!
   [1,] -0.7725932
                  0.6752678 1.0261028
         0.2445988 -0.0250675 0.2458800
   [3,]
        0.2185495 -0.7793260 0.8093904
   [4,]
         0.2467589 -0.2972740 0.3863441
   [5,]
         0.7218308 0.5221261 0.8908733
         0.2806212 -0.2206703 0.3569925
## [6,]
pi_hat <- 4*sum(t<=1)/N
pi hat
## [1] 3.188
```

- set.seed() fixes randomization, which is often convenient to get consistent outcome.
 - N, where each element follows U(0,1).
- \bullet runif(N)*2 follows U(0,2), and runif(N)*2 1 follows U(-1,1).
- t<=1 returns the 0-1 vector of length same as t, where an element is 1 if corresponding element in t is less than or equal to 1, and 0 otherwise.
- **o** cbind() combines (column) vectors into a matrix.
- head() displays the first six observations.

Vectorized programming

• From the previous slide

```
beg_time <- Sys.time()
set.seed(1234)
N <- 10^6
x <- runif(N)*2-1
y <- runif(N)*2-1
t <- sqrt(x^2+y^2)
pi_hat <- 4*sum(t<=1)/N
end_time <- Sys.time()
print(end_time-beg_time)
## Time difference of 0.145758) secs</pre>
```

• What first-timer would write.

```
beg_time <- Sys.time()
set.seed(1234)
N <- 10^6
count <- 0
for (i in 1:N) {
    x_i <- runif(1)*2-1
    y_i <- runif(1)*2-1
    t_i <- sqrt(x_i^2+y_i^2)
    if (t_i <= 1) count <- count + 1
}
pi_hat <- 4*count/N
end_time <- Sys.time()
print(end_time-beg_time)</pre>
```

Time difference of 6.264948 secs

- The style of the code on the left is called *vectorized programming*.
- It is elegant, economic, and efficient.
- You must be able to write as the left side and communicate as the right side (to non-expert).

Implementation - varying number of trials

Approach with a custom function

```
i_simulator <- function(N)
  set.seed(1234)
  x <- runif(N)*2-1 ✓
  y <- runif(N)*2-1 ✓
  t \leftarrow sqrt(x^2+y^2)
  pi_hat <-_4*sum(t<=1)/N
  return(pi hat)
pi simulator(100)
## [1] 3.04
pi simulator(1000)
## [1] 3.188
pi simulator(10000)
## [1] 3.1876
pi_simulator(100000)
## [1] 3.13432
```

```
### p.13 wde
   PUtho-
```

• How many repetition is necessary to get closer?

```
Yum_trials <- 10^(2:7)</pre>
outcomes <- sapply(num trials, pi simulator)
results <- cbind(num trials, outcomes)
results
##
        num trials outcomes
## [1,]
                100 3.040000
## [2,]
               1000 3.188000
## [3,]
             10000 3.187600
```

100000 3.134320

1000000 3.137616

10000000 3.140733

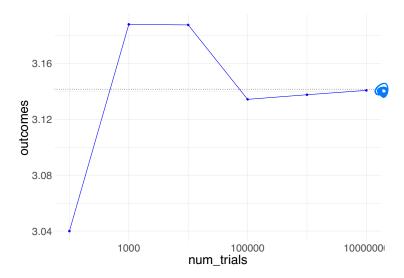
```
sapply(num_trials, pi_simulator)
  applies the function pi simulator()
  to each element of num_trials.
```

[4,]

[5,]

[6,]

• How many repetition is necessary to get closer?



```
results <- data.frame(results)
library(tidyverse)
ggplot(results, aes(x=num_trials, y=outcomes)) +
    geom_point(color = "blue") + geom_path(color = "blue") +
    geom_abline(slope = 0, intercept = 3.14159, linetype = "dotted") +
    scale_x_log10() +
    theme_minimal() + theme(text = element_text(size=25))</pre>
```

III. Discussion

Computation time

- In this implementation, number of trials were increased from 10² to 10⁷. No wonder that this increases the computational time.
- Following modified function displays the elapsed time.

```
pi simulator2 <- function(N) { # name change</pre>
  beg time <- Sys.time() # newly added
  set.seed(1234)
  x \leftarrow runif(N)*2-1
  y <- runif(N)*2-1
  t \leftarrow sart(x^2+v^2)
  pi hat <-4*sum(t<=1)/N
  end time <- Sys.time() # newly added
  print(N)
  print(end time-beg time) # newly added
  return(pi_hat)
```

```
sapply(num trials, pi simulator2)
## [1] 100
## Time difference of 0 secs
## [1] 1000
## Time difference of 0.0007610321 secs
## [1] 10000
## Time difference of 0.002549887 secs
## [1] 100000
## Time difference of 0.01874018 secs
## [1] 1000000
## Time difference of 0.202595 secs
## [1] 10000000
## Time difference of 1.864766 secs 4
## [1] 3.040000 3.188000 3.187600 3.134320 3.137616 3
```

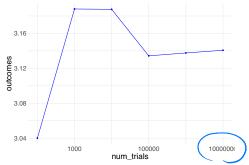
III. Discussion 0000

Confidence on the result

• In estimation of π example, we were in the luxurious situation because we already knew the correct value of π , 3.14159.

III. Discussion 0000

- In reality, this situation is rare. Rather, you shouldn't be in need of doing simulation after all if you already know the exact value.
- In reality, following figure is what you would normally face. Notice that the correct value indicating line is gone.



• One legimate way to have some confidence is to observe the plot and say 'It seems converging with good degree'. Then, present a number that seems to be within the tolerance.

III. Discussion 0000

• Are there any way to present a confidence interval, just as good statistical estimations should present?

IV. Confidence interval

0471 26 MC-N

- Building a confidence interval from experiment generally involves repetitive experiments. But in the simulation approach, we already do have the repetitive simulation experiments? Isn't this enough?
- Not really so. In order to build a confidence interval, we should treat one entire simulation experiment as one observation. For example, we treat the result from a $\overline{N}=1000$ simulation experiment as a single observation on the true value. Then repeat this simulation experiment, say, n times, to build a confidence interval.
- Let's set N=1,000 for a simulation experiment and do this for n=100 times.



Repetitive simulation experiments

- Let's set N=1,000 for a simulation experiment and do this for n=100 times.
- For each experiment, record the result to collect n = 100 samples.

```
pi simulator3 <- function(N) { # name change</pre>
  # set.seed(1234) # seed must not be fixed
  x \leftarrow runif(N)*2-1
  y <- runif(N)*2-1
  t \leftarrow sqrt(x^2+y^2)
  pi hat <-4*sum(t<=1)/N
  return(pi hat)
n <- 100 # number of experiments to repeat
N <- 1000 # number of simulation repetition in a single experiment
set.seed(1234)
samples <- rep(0, n) # create an empty zero vector_
for (i in 1:n) { # do this for n times
  samples[i] <- pi simulator3(N)</pre>
head(samples)
## [1] 3.188 3.144 3.060 3.240 3.148 3.172
```

1.96

From LN.A4.p13,

$$\mathbb{P}[\overline{X} - t_{0.975, n-1} \cdot s / \sqrt{n} \le \mu \le \overline{X} + t_{0.975, n-1} \cdot s / \sqrt{n}] = 0.95$$

X bar

Obtain the numbers as follows:

 \leftarrow qt(p=0.975, df = n-1)

[1] 0.05186579

[1] 1.984217

[1] 3.137

Thus,

$$\mathbb{P}[3.137 - 1.984 \cdot 0.0519/\sqrt{100} \leq \mu \leq 3.137 + 1.984 \cdot 0.0519/\sqrt{100}] = 0.95$$

$$\mathbb{P}[3.127 \leq \mu \leq 3.147] = 0.95$$

• Note that the length of interval was 0.020 (=3.147-3.127)

MC-N

 Obviously, increasing X and/or increasing n should narrow the confidence interval.

Exercise 1

Do the above experiment with ncreased by the factor of ten, and present the confidence interval. (Use set.seed(1234))

```
n <- 100 # number of exp. to rep.
                                                        1b
 N <- 10000 # number of sim. rep. in a single exp.
                                                         ## [1] 3.137164
  set.seed(1234)
                                                        ub
  samples <- rep(0, n)
                                                         ## [1] 3.143788
  for (i in 1:n) {
                                                        ub-1b
    samples[i] <- pi simulator3(N)</pre>
                                                         ## [1] 0.006624215
 X bar <- mean(samples)</pre>
  s <- sqrt(sum((X bar-samples)^2)/(n-1))</pre>
 t \leftarrow qt(p=0.975, df = n-1)
Vlb <- X bar-t*s/sqrt(n) # Lower bound
 ub <- X bar+t*s/sqrt(n) # upper bound
```

Exercise 2

Do the Exercise 1 above with n increased by the factor of ten, and present the confidence interval. (Use set.seed(1234))

```
n <-1000 # number of exp. to rep.
N <- 10000 # number of sim. rep. in a single exp.
set.seed(1234)
samples <- rep(0, n)
for (i in 1:n) {
    samples[i] <- pi_simulator3(N)
}
X_bar <- mean(samples)
s <- sqrt(sum((X_bar-samples)^2)/(n-1))
t <- qt(p=0.975, df = n-1)
lb <- X_bar-t*s/sqrt(n) # Lower bound
ub <- X_bar+t*s/sqrt(n) # upper bound</pre>
```

```
1b

## [1] 3.139777

ub

## [1] 3.141834

ub-1b

## [1] 0.002057237
```



N	n 1	ength of CI	
1,000	100	0.020	1/50
1,0000	100	0.0066	100
1,0000	1000	0.00205	1/50

- Increasing N or n gives the same effect.
 - When N was increased by the factor of 10, the length of CI was decreased by the factor
 - ullet When n was increased by the factor of 10, the length of CI was decreased by the factor of $\sqrt{10}$.
- Repetitive simulation experiments is beneficial if ···
 - when you need confidence interval.
 - ullet when you face memory issue that prevents increasing N any more.

If I only had an hour to chop down a tree, I would spend the first 45 minutes sharpening my axe. - A. Lincoln