## Inotes2\_Exercises

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## 차례

| Markorv Process p.3 Mars rover 그림 마코프체인 문제 다이어그램, 메트릭스를 작성하고         |   |
|--|---|
| 이때까지 배운것 적용해보기   | 2 |
| Mars Rover Markov Process MC로 파이썬 구현해서 reward 계산하기(Time Horizon 10일이 |   |
| 라 가정, S4에서 시작)   | 3 |

Markorv Process p.3 Mars rover 그림 마코프체인 문제 다이어그램, 메트릭스를 작성하고 이때까지 배운것 적용해보기

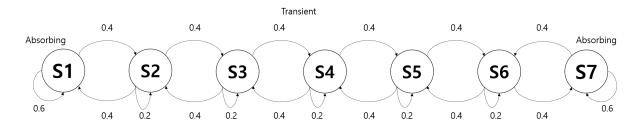


그림 1: Diagram

$$P = \begin{pmatrix} 0.6 & 0.4 & 0 & 0 & 0 & 0 & 0 \\ 0.4 & 0.2 & 0.4 & 0 & 0 & 0 & 0 \\ 0 & 0.4 & 0.2 & 0.4 & 0 & 0 & 0 \\ 0 & 0 & 0.4 & 0.2 & 0.4 & 0 & 0 \\ 0 & 0 & 0 & 0.4 & 0.2 & 0.4 & 0 \\ 0 & 0 & 0 & 0 & 0.4 & 0.2 & 0.4 \\ 0 & 0 & 0 & 0 & 0 & 0.4 & 0.6 \end{pmatrix}$$

Mars Rover Markov Process MC로 파이썬 구현해서 reward 계산하기(Time Horizon 10일이라 가정, S4에서 시작)

```
import numpy as np
MC_N = 100000
H=10
def mars_simul(state):
    n=np.random.rand()
    if(state==0 and n<=0.6):</pre>
        state=0
    elif(state==0 and n>0.6):
        state+=1
    elif(state>=1 and state<=8):</pre>
        if(n<=0.4):
            state-=1
        elif(n>0.4 and n<=0.8):</pre>
            state+=1
    if(state==H-1 and n<=0.6):</pre>
        state=H-1
    elif(state==H-1 and n>0.6):
        state-=1
    return state
def reward_eval(path):
    reward = path.count(0)*1 + path.count(9)*10
    return reward
reward = np.array([])
result = []
start_state = 4
for i in range(MC_N):
    state = start_state
    for t in range(H):
        result.append(state)
        state = mars_simul(state)
    reward=np.append(reward, reward_eval(result))
    result=[]
```

```
print(np.mean(reward))
## 1.04876
import numpy as np
P = np.array([[0.6,0.4,0,0,0,0,0,0,0],[0.4,0.2,0.4,0,0,0,0,0],[0,0.4,0.2,0.4,0,0,0,0]],[0,0.4,0.2,0.4,0,0,0,0],[0,0.4,0.2,0.4,0,0,0],[0,0.4,0.2,0.4,0,0],[0,0.4,0.2,0.4,0,0],[0,0.4,0.2,0.4,0,0],[0,0.4,0.2,0.4,0,0],[0,0.4,0.2,0.4,0,0],[0,0.4,0.2,0.4,0],[0,0.4,0.2,0.4,0],[0,0.4,0.2,0.4,0],[0,0.4,0.2,0.4,0],[0,0.4,0.2,0.4,0],[0,0.4,0.2,0.4,0],[0,0.4,0.2,0.4,0],[0,0.4,0.2,0.4,0],[0,0.4,0.2,0.4,0],[0,0.4,0.2,0.4,0],[0,0.4,0.2,0.4,0],[0,0.4,0.2,0.4,0],[0,0.4,0.2,0.4,0],[0,0.4,0.2,0.4,0],[0,0.4,0.2,0.4,0],[0,0.4,0.2,0.4,0],[0,0.4,0.2,0.4,0],[0,0.4,0.2,0.4,0],[0,0.4,0.2,0.4,0],[0,0.4,0.2,0.4,0],[0,0.4,0.2,0.4,0],[0,0.4,0.2,0.4,0],[0,0.4,0.2,0.4,0],[0,0.4,0.2,0.4,0],[0,0.4,0.2,0.4,0],[0,0.4,0.2,0.4,0],[0,0.4,0.2,0.4,0],[0,0.4,0.2,0.4,0],[0,0.4,0.2,0.4,0],[0,0.4,0.2,0.4,0],[0,0.4,0.2,0.4,0],[0,0.4,0.2,0.4,0],[0,0.4,0.2,0.4,0],[0,0.4,0.2,0.4,0],[0,0.4,0.2,0.4,0],[0,0.4,0.2,0.4,0],[0,0.4,0.2,0.4,0],[0,0.4,0.2,0.4,0],[0,0.4,0.2,0.4,0],[0,0.4,0.2,0.4,0],[0,0.4,0.2,0.4,0],[0,0.4,0.2,0.4,0.2,0.4,0],[0,0.4,0.2,0.4,0.2,0.4],[0,0.4,0.2,0.4,0.4,0.2,0.4],[0,0.4,0.2,0.4,0.4,0.2,0.4],[0,0.4,0.2,0.4,0.4],[0,0.4,0.4,0.4,0.4],[0,0.4,0.4,0.4],[0,0.4,0.4,0.4],[0,0.4,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,0.4,0.4],[0,
 [0,0,0.4,0.2,0.4,0,0,0,0], [0,0,0,0.4,0.2,0.4,0,0,0], [0,0,0,0,0.4,0.2,0.4,0,0,0], \\
[0,0,0,0,0,0.4,0.2,0.4,0,0],[0,0,0,0,0,0,0.4,0.2,0.4,0],[0,0,0,0,0,0,0,0.4,0.2,0.4],
[0,0,0,0,0,0,0,0,0.4,0.6]])
R = np.array([1,0,0,0,0,0,0,0,0,10]).reshape(10,1)
H=10
v_{t1} = np.array([0,0,0,0,0,0,0,0,0]).reshape(10,1)
t=H-1
while(t>=0):
              v_t = R + np.dot(P,v_t1)
               t=t-1
              v_t1 = v_t
print(v_t)
## [[ 4.55105331]
## [ 2.74013082]
## [ 1.59748096]
## [ 1.1463639 ]
## [ 1.57961421]
## [ 3.38123162]
## [ 7.42157517]
## [14.90427904]
## [27.19369011]
## [45.48458086]]
```

```
"C3 Exercises"
```

thus, 1.1463639