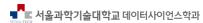
Lecture A1. Math Review

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- I. Differentiation and Integration
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- IV. Series and Others

I. Differentiation and Integration

I. Differentiation and Integration

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Differentiation

Definition 1 (differentiation)

Differentiation is the action of computing a derivative.

Definition 2 (derivative) 况某

The derivative of a function y = f(x) of a variable x is a measure of the rate at which the value y of the function changes with respect to (wrt., hereafter) the change of the variable x. It is notated as f'(x) and called derivative of f wrt. x.

Remark 1

If x and y are real numbers, and if the graph of f is plotted against x, the derivative is the slope of this graph at each point.

Definition 3 (differentiable) 미남기나

If $\lim_{h\to 0} \frac{f(x+h/2)-f(x-h/2)}{h}$ exists for a function f at x, we say the function f is differentiable at x. That is, $f'(x) = \lim_{h\to 0} \frac{f(x+h/2)-f(x-h/2)}{h}$. If f is differentiable for all x, then we say f is differentiable (everywhere).

Remark 2

The followings are popular derivatives.

- $f(x) = x^p \Rightarrow f'(x) = px^{p-1}$ (polyomial)
- $f(x) = e^x \Rightarrow f'(x) = e^x$ (exponential) African
- $f(x) = log(x) \Rightarrow f'(x) = 1/x$ (log function; not differentiable at x = 0)

Theorem 1

Differentiation is linear. That is,
$$h(x) = f(x) + g(x)$$
 implies $h'(x) = f'(x) + g'(x)$.

If
$$h(x) = f(x)g(x)$$
, then $h'(x) = f'(x)g(x) + f(x)g'(x)$.

Exercise 1

I. Differentiation and Integration

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Suppose $f(x) = xe^x$, find f'(x).

$$\int (x) = \frac{\chi(e^x)}{\int (x) = 1 \cdot e^x} + \chi(e^x)$$

$$\int (x) = 1 \cdot e^x + \chi(e^x)$$

$$\int (x) = (1 + \chi) e^x$$

Theorem 3 (differentiation of fraction)

If
$$h(x)=rac{f(x)}{g(x)}$$
, then $h'(x)=rac{f'(x)g(x)-f(x)g'(x)}{(g(x))^2}$.

Theorem 4 (composite function)

If
$$h(x) = f(g(x))$$
, then $h'(x) = f'(g(x)) \cdot g'(x)$.

Exercise 2

Suppose
$$f(x) = e^{2x}$$
 find $f'(x)$.

$$\left(e^{f(x)}\right)' = e^{f(x)} \cdot f'(x)$$

$$\left(e^{2x}\right)' = \left(e^{2x}\right)' \cdot \left(\mathcal{Y}_{\ell}\right)'$$

$$= 2e^{2x}$$

Integration

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I. Differentiation and Integration



Definition 4 (integration)

Integration is the computation of an integral, which is a reverse operation of differentiation up to an additive constant.

Definition 5 (antiderivative)

Let's say a function f is a derivative of g, or g'(x) = f(x), then we say g is an antiderivative of f , written as $g(x)=\int f(x)dx+C$, where \widehat{C} is a integration constant.

Remark 3

The followings are popular antiderivatives.

- For $p \neq 1$, $f(x) = x^p \Rightarrow \int f(x) dx = \frac{1}{n+1} x^{p+1} + C$ (polyomial)
- $f(x) = \frac{1}{x} \Rightarrow \int f(x)dx = log(x) + C$ (fraction)
- $f(x) = e^x \Rightarrow \int f(x)dx = e^x + C$ (exponential)
- $f(x) = \frac{g'(x)}{g(x)} \Rightarrow \int f(x)dx = log(g(x)) + C$ (See Theorem 4 above)

Exercise 3

Derive
$$\int f'(x)g(x) dx = f(x)g(x) - \int f(x)g(x)' dx$$
. (Hint: Use Theorem 2 above.)
$$\int f(x)g(x) + \int f(x)g(x) dx = \int \frac{d}{dx} f(x)g(x)$$

$$\int (f'(x)g(x))dx + \int (f(x)g(x))dx = \int (\frac{d}{dx}f(x)g(x))dx$$

$$\int (f'(x)g(x))dx + \int (f(x)g'(x))dx = f(x)g(x)$$

$$\int (f'(x)g(x))dx = f(x)g(x) - \int (f(x)g(x)')dx$$

Exercise 4

Find $\int xe^x dx$, and evaluate $\int_0^1 xe^x dx$. (Hint: Use Exercise 3 above.)

Exercise 3
$$\int (x)g(x) dx = \int (x)g(x) - \int (e^x \cdot 1) dx$$

$$= e^x x - e^x + c$$

$$\int_{0}^{1} xe^{x} dx = \left[e^{x}x - e^{x} - c\right]_{0}^{1}$$

$$= (e^{1} - e^{1} - c) - (e^{0} - e^{0} - c)$$

$$= (0 - c) - (0 - 1 - c)$$

$$= 1$$

II. Numerical Methods

Differentiation

 Oftentimes, finding analytic derivative is hard, but finding numerical derivative is often possible.

Definition 6

For a function f and small constant h,

- ullet $f'(x)pprox rac{f(x+h)-f(x)}{h}$ (forward difference formula)
- $f'(x) \approx \frac{f(x) f(x-h)}{h}$ (backward difference formula)
- $f'(x) \approx \frac{f(x+h)-f(x-h)}{2h}$ (centered difference formula)

Solving an equation

• For the rest of this section, we consider a nonlinear and differentiable (thus, continuous) function $f: \mathbb{R} \to \mathbb{R}$, we aim to find a point $x^* \in \mathbb{R}$ such that $f(x^*) = 0$. We call such x^* as a solution or a root.

Bisection Method

- The bisection method aims to find a very short interval [a, b] in which f changes a sign.
- Why? Changing a sign from a to b means the function crosses the $\{y=0\}$ -axis, (a.k.a. x-axis), at least once. It means x^* such that $f(x^*) = 0$ is in this interval. Since [a, b] is a very short interval, We may simply say $x^* = \frac{a+b}{2}$.

Definition 7 (sign function)

 $sgn(\cdot)$ is called a sign function that returns 1 if the input is positive, -1 if negative, and 0 if zero.

Bisection algorithm

8: end

- Let *tol* be the maximum allowable length of the *short interval* and an initial interval [a,b] be such that $sqn(f(a)) \neq sqn(f(b))$.
- The *bisection algorithm* is the following.

```
1: while ((b-a) > tol) do
      m=\frac{a+b}{2}
2:
       if sgn(f(a)) = sgn(f(m)) then
3:
4:
            a=m
5:
       else
            b=m
6:
7:
       end
```

 At each iteration, the interval length is halved. As soon as the interval length becomes smaller than tol, then the algorithm stops.

Newton Method

- The bisection technique makes no used of the function values other than their signs, resulting in slow but sure convergence.
- More rapid convergence can be achieved by using the function values to obtain a more accurate approximation to the solution at each iteration.
- Newton method is a method that use both the function value and derivative value.

• Newton method approximates the function f near x_k by the tangent line at $f(x_k)$.

- 1: x_0 = initial guess
- 2: for k=0,1,2,...
- $x_{k+1} = x_k f(x_k)/f'(x_k)$ 3:
- break if $|x_{k+1} x_k| < tol$ 4:
- 5: end

- Root-finding numerical methods such as bisection method and newton method has a few common properties.
 - ① It is characterized as a *iterative process* (such as $x_0 \to x_1 \to x_2 \to \cdots$).
 - 2 In each *iteration*, the current candidate *gets closer* to the true value.
 - It converges. That is, it is theoretically reach the *exact value* up to tolerance.
- Many iterative numerical methods share the properties above.
- The famous back propagation in deep neural network is also motivated by Newton method.
- Major algorithms for dynamic programming are called *policy iteration* and *value iteration* that also share the properties above.

III. Matrix Algebra

Matrix multiplication

Exercise 5

Solve the followings.

$$(.6 \quad .4) \begin{pmatrix} .7 & | & .3 \\ .5 & | & .5 \end{pmatrix} = (...) \begin{pmatrix} .3 & .3 \\ .5 & | & .3 \end{pmatrix}$$

Exercise 6

What is P^2 ?

$$P = \begin{pmatrix} \frac{.7}{.5} & .3 \end{pmatrix} \begin{pmatrix} \uparrow & 3 \\ 5 & 5 \end{pmatrix}$$

$$P^{2} = \begin{pmatrix} 49 + 15 & 21 + 15 \\ 351 + 25 & 15 + 25 \end{pmatrix}$$
$$= \begin{pmatrix} .64 & .36 \\ .60 & .40 \end{pmatrix}$$

III. Matrix Algebra 000000000

Solution to system of linear equations

Exercise 7

Solve the followings.

Solve the following system of equations.

$$x = y$$

$$y = 0.5z$$

$$z = 0.6 + 0.4x$$

$$x + y + z = 1$$

III. Matrix Algebra

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Solve the following system of equations.

$$(\pi_0 \quad \pi_1 \quad \pi_2) \begin{pmatrix} -2 & 2 \\ 3 & -5 & 2 \\ & 3 & -3 \end{pmatrix} = (0 \ \ 0 \ \ 0)$$

III. Matrix Algebra 000000000

$$\pi_0 + \pi_1 + \pi_2 = 1$$

5 - 35 T4 + 8 - 20 4 + 3 T4 + T7= 1

Exercise 10

Solve the following system of equations.

$$(\pi_{1} \ \pi_{2} \ \pi_{3} \ \pi_{4}) \begin{pmatrix} .7 \ .3 \\ .5 \ .5 \end{pmatrix} \begin{pmatrix} .6 \ .4 \\ .3 \ .7 \end{pmatrix} = (\pi_{1} \ \pi_{2} \ \pi_{3} \ \pi_{4}) \begin{pmatrix} .6 \ .4 \\ .3 \ .7 \end{pmatrix} = (\pi_{1} \ \pi_{2} \ \pi_{3} \ \pi_{4}) \begin{pmatrix} .6 \ .4 \\ .3 \ .7 \end{pmatrix}$$

Exercise 11

Solve following and express π_i for i=0,1,2,...

$$\begin{array}{rcl} \pi_0 + \pi_1 + \pi_2 + \dots & = & 1 \\ 0.02\pi_0 + 0.02\pi_1 + 0.02\pi_2 + \dots & = & \pi_0 \\ 0.98\pi_0 & = & \pi_1 \\ 0.98\pi_1 & = & \pi_2 \\ 0.98\pi_2 & = & \pi_3 \\ \dots & = & \dots \end{array}$$

IV. Series and Others

Simplify the following. When |r| < 1, $S = (a) + ar + ar^2 + ar^3 + ...$

Simplify the following. When
$$r \neq 1$$
, $S = a + ar + ar^2 + ar^3 + ... + ar^{n-1}$

$$S_{n} = 0 + \alpha r + \alpha r^{2} + \cdots + \alpha r^{n}$$

$$- \sum_{n} = \alpha r + \alpha r^{2} + \cdots + \alpha r^{n}$$

$$(|-r|)S = 0 - \alpha r^{n}$$

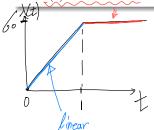
$$\vdots S_{n} = \frac{\alpha (1 - r^{n})}{1 - r}, r \neq 1$$

Simplify the following. When |r| < 1, $S = r + 2r^2 + 3r^3 + 4r^4 + \dots$

Formulation of time varying function

Exercise 15

During the first hour $(0 \le t \le 1)$, $\lambda(t)$ increases linearly from 0 to 60. After the first hour, $\lambda(t)$ is constant at 60. Draw plot for $\lambda(t)$ and express the function in math form.



"Man can learn nothing unless he proceeds from the known to the unknown. - Claude Bernard"