

# F1

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```
import numpy as np
import pandas as pd

states = np.arange(0,80,10).astype('str')

P_normal = pd.DataFrame(np.matrix([[0,1,0,0,0,0,0,0],
                                     [0,0,1,0,0,0,0,0],
                                     [0,0,0,1,0,0,0,0],
                                     [0,0,0,0,1,0,0,0],
                                     [0,0,0,0,0,1,0,0],
                                     [0,0,0,0,0,0,1,0],
                                     [0,0,0,0,0,0,0,1],
                                     [0,0,0,0,0,0,0,1]]), index=states, columns=states)

P_speed=pd.DataFrame(np.matrix([[.1,0,.9,0,0,0,0,0],
                                 [.1,0,0,.9,0,0,0,0],
                                 [0,.1,0,0,.9,0,0,0],
                                 [0,0,.1,0,0,.9,0,0],
                                 [0,0,0,.1,0,0,.9,0],
                                 [0,0,0,0,.1,0,0,.9],
                                 [0,0,0,0,0,.1,0,.9],
                                 [0,0,0,0,0,0,0,1]]), index=states, columns=states)

R_s_a=pd.DataFrame(np.matrix([[-1,-1,-1,-1,0.0,-1,-1,0,-1.5,-1.5,-1.5,-1.5,-0.5,-1.5,-1.5,0]].reshape(len(states),len(states)))).T

print(R_s_a.T)

##      0   10   20   30   40   50   60   70
## n -1.0 -1.0 -1.0 -1.0  0.0 -1.0 -1.0  0.0
## s -1.5 -1.5 -1.5 -1.5 -0.5 -1.5 -1.5  0.0

pi_speed=pd.DataFrame(np.c_[np.repeat(0,len(states)),np.repeat(1,len(states))], index=states, columns=states)

pi_50=pd.DataFrame(np.c_[np.repeat(0.5,len(states)), np.repeat(0.5,len(states))],index=states, columns=states)

print(pi_speed.T)

##      0   10   20   30   40   50   60   70
```

```
## n 0 0 0 0 0 0 0 0
## s 1 1 1 1 1 1 1 1
```

```
print(pi_50.T)
```

```
#simulator pi_speed
```

```
##      0  10  20  30  40  50  60  70
## n 0.5 0.5 0.5 0.5 0.5 0.5 0.5 0.5
## s 0.5 0.5 0.5 0.5 0.5 0.5 0.5 0.5
```

```
pi = pi_speed
np.random.seed(1234)
history = list()
MC_N = 10000
for MC_i in range(MC_N):
    s_now = '0'
    history_i = list(s_now)

    while s_now != '70':
        if np.random.uniform(0, 1) < pi.loc[s_now]['n']:
            a_now = 'n'
            P = P_normal
        else:
            a_now = 's'
            P = P_speed

        r_now = str(R_s_a.loc[s_now][a_now])
        s_next = states[np.argmin(P.loc[s_now].cumsum() < np.random.uniform(0, 1))].item()
        history_i.extend([a_now, r_now, s_next])
        s_now = s_next

    history.append(history_i)

history_speed = history
func = np.vectorize(lambda x: ','.join(x))
print(pd.Series(func(history_speed[:20])))
```

```
#simulator pi_50
```

```
## 0      0,s,-1.5,20,s,-1.5,40,s,-0.5,60,s,-1.5,70
## 1      0,s,-1.5,20,s,-1.5,40,s,-0.5,60,s,-1.5,70
## 2      0,s,-1.5,0,s,-1.5,20,s,-1.5,40,s,-0.5,60,s,-1...
## 3      0,s,-1.5,20,s,-1.5,40,s,-0.5,60,s,-1.5,70
## 4      0,s,-1.5,20,s,-1.5,40,s,-0.5,60,s,-1.5,70
## 5      0,s,-1.5,20,s,-1.5,40,s,-0.5,60,s,-1.5,70
## 6      0,s,-1.5,20,s,-1.5,10,s,-1.5,30,s,-1.5,50,s,-1...
## 7      0,s,-1.5,20,s,-1.5,40,s,-0.5,30,s,-1.5,50,s,-1...
## 8      0,s,-1.5,20,s,-1.5,40,s,-0.5,60,s,-1.5,70
## 9      0,s,-1.5,20,s,-1.5,40,s,-0.5,60,s,-1.5,70
## 10     0,s,-1.5,20,s,-1.5,40,s,-0.5,60,s,-1.5,70
## 11     0,s,-1.5,20,s,-1.5,40,s,-0.5,60,s,-1.5,70
## 12     0,s,-1.5,20,s,-1.5,40,s,-0.5,60,s,-1.5,70
```

```

## 13      0,s,-1.5,20,s,-1.5,40,s,-0.5,60,s,-1.5,70
## 14      0,s,-1.5,20,s,-1.5,40,s,-0.5,60,s,-1.5,70
## 15      0,s,-1.5,20,s,-1.5,10,s,-1.5,30,s,-1.5,50,s,-1...
## 16      0,s,-1.5,20,s,-1.5,40,s,-0.5,60,s,-1.5,70
## 17      0,s,-1.5,20,s,-1.5,40,s,-0.5,60,s,-1.5,70
## 18      0,s,-1.5,20,s,-1.5,40,s,-0.5,60,s,-1.5,70
## 19      0,s,-1.5,20,s,-1.5,40,s,-0.5,60,s,-1.5,70
## dtype: object
##
## C:\Users\user\AppData\Local\R-MINI~1\envs\R-RETI~1\lib\site-packages\numpy\core\_asarray.py:83: Visi
## return array(a, dtype, copy=False, order=order)

```

```

pi = pi_50
np.random.seed(1234)
history = list()
MC_N = 10000
for MC_i in range(MC_N):
    s_now = '0'
    history_i = list(s_now)

    while s_now != '70':
        if np.random.uniform(0, 1) < pi.loc[s_now]['n']:
            a_now = 'n'
            P = P_normal
        else:
            a_now = 's'
            P = P_speed

        r_now = str(R_s_a.loc[s_now][a_now])
        s_next = states[np.argmin(P.loc[s_now].cumsum() < np.random.uniform(0, 1))].item()
        history_i.extend([a_now, r_now, s_next])
        s_now = s_next

    history.append(history_i)

history_50 = history
func = np.vectorize(lambda x: ', '.join(x))
pd.Series(func(history_50[:20]))

```

*#implementation pi\_speed (vectorized)*

```

## 0      0,n,-1.0,10,n,-1.0,20,s,-1.5,40,n,0.0,50,s,-1...
## 1      0,n,-1.0,10,s,-1.5,30,n,-1.0,40,s,-0.5,30,s,-1...
## 2      0,s,-1.5,20,n,-1.0,30,n,-1.0,40,s,-0.5,60,s,-1...
## 3      0,s,-1.5,20,n,-1.0,30,n,-1.0,40,n,0.0,50,n,-1...
## 4      0,n,-1.0,10,n,-1.0,20,n,-1.0,30,s,-1.5,20,s,-1...
## 5      0,n,-1.0,10,n,-1.0,20,n,-1.0,30,n,-1.0,40,n,0...
## 6      0,n,-1.0,10,n,-1.0,20,n,-1.0,30,n,-1.0,40,n,0...
## 7      0,s,-1.5,20,s,-1.5,40,s,-0.5,60,n,-1.0,70
## 8      0,s,-1.5,20,n,-1.0,30,s,-1.5,50,n,-1.0,60,s,-1...
## 9      0,s,-1.5,20,s,-1.5,40,n,0.0,50,n,-1.0,60,n,-1...
## 10     0,n,-1.0,10,s,-1.5,30,n,-1.0,40,s,-0.5,60,s,-1...
## 11     0,s,-1.5,20,n,-1.0,30,n,-1.0,40,n,0.0,50,n,-1...
## 12     0,n,-1.0,10,s,-1.5,30,n,-1.0,40,n,0.0,50,s,-1...

```

```

## 13      0,n,-1.0,10,s,-1.5,30,s,-1.5,50,s,-1.5,70
## 14      0,n,-1.0,10,s,-1.5,30,s,-1.5,50,s,-1.5,70
## 15      0,n,-1.0,10,s,-1.5,30,s,-1.5,50,s,-1.5,70
## 16      0,s,-1.5,20,s,-1.5,40,n,0.0,50,n,-1.0,60,n,-1...
## 17      0,s,-1.5,20,s,-1.5,40,s,-0.5,60,n,-1.0,70
## 18      0,n,-1.0,10,n,-1.0,20,s,-1.5,40,n,0.0,50,n,-1...
## 19      0,s,-1.5,20,s,-1.5,40,s,-0.5,60,s,-1.5,70
## dtype: object
##
## C:\Users\user\AppData\Local\R-MINI~1\envs\R-RETI~1\lib\site-packages\numpy\core\_asarray.py:83: Visi
## return array(a, dtype, copy=False, order=order)

```

```

pol_eval = pd.DataFrame(np.zeros((len(states), 2)), index=states, columns=['count', 'sum'])
print(pol_eval.T)

```

```

##          0    10    20    30    40    50    60    70
## count  0.0  0.0  0.0  0.0  0.0  0.0  0.0  0.0
## sum    0.0  0.0  0.0  0.0  0.0  0.0  0.0  0.0

```

```

for MC_i in range(len(history_speed)):
    history_i = history_speed[MC_i]

    for j in range(0, len(history_i), 3):
        pol_eval.loc[history_i[j]]['count'] += 1

        if j < len(history_i):
            pol_eval.loc[history_i[j]]['sum'] += pd.Series(history_i)[range(j + 2, len(history_i) - 1, 3)]
            .astype('float').sum()

        else:
            pol_eval.loc[history_i[j]]['sum'] += 0

print(pol_eval.T)

```

```

##          0         10         20         30         40         50         60         70
## count 11225.0 1076.0 10291.0 1887.0 9485.0 2563.0 8563.0 10000.0
## sum  -65136.0 -5619.0 -42703.0 -6539.0 -22275.5 -4472.5 -14355.0 0.0

```

```

print((pol_eval['sum'] / pol_eval['count']))

```

```

#implementation pi_speed (running estimate)

```

```

## 0      -5.802762
## 10     -5.222119
## 20     -4.149548
## 30     -3.465289
## 40     -2.348498
## 50     -1.745025
## 60     -1.676398
## 70      0.000000
## dtype: float64

```

```
pol_eval = pd.DataFrame(np.zeros((len(states), 2)), index=states, columns=['count', 'est'])
print(pol_eval.T)
```

```
##          0   10   20   30   40   50   60   70
## count  0.0  0.0  0.0  0.0  0.0  0.0  0.0  0.0
## est    0.0  0.0  0.0  0.0  0.0  0.0  0.0  0.0
```

```
for MC_i in range(len(history_speed)):
    history_i = history_speed[MC_i]

    for j in range(0, len(history_i), 3):
        pol_eval.loc[history_i[j]]['count'] += 1
        current_cnt = pol_eval.loc[history_i[j]]['count']

        if j < len(history_i):
            new_info = pd.Series(history_i)[range(j + 2, len(history_i) - 1, 3)].astype('float').sum()

        else:
            new_info = 0

        alpha = 1 / current_cnt
        pol_eval.loc[history_i[j]]['est'] += alpha * (new_info - pol_eval.loc[history_i[j]]['est'])

print(np.round(pol_eval.T, 2))
```

*#implementation pi\_50 (vectorized)*

```
##          0      10      20      30      40      50      60      70
## count 11225.0 1076.00 10291.00 1887.00 9485.00 2563.00 8563.00 10000.0
## est   -5.8   -5.22   -4.15   -3.47   -2.35   -1.75   -1.68    0.0
```

```
pol_eval = pd.DataFrame(np.zeros((len(states), 2)), index=states, columns=['count', 'sum'])
print(pol_eval.T)
```

```
##          0   10   20   30   40   50   60   70
## count  0.0  0.0  0.0  0.0  0.0  0.0  0.0  0.0
## sum    0.0  0.0  0.0  0.0  0.0  0.0  0.0  0.0
```

```
for MC_i in range(len(history_50)):
    history_i = history_50[MC_i]

    for j in range(0, len(history_i), 3):
        pol_eval.loc[history_i[j]]['count'] += 1

        if j < len(history_i):
            pol_eval.loc[history_i[j]]['sum'] += pd.Series(history_i)[range(j + 2, len(history_i) - 1, 3)].astype('float').sum()

        else:
            pol_eval.loc[history_i[j]]['sum'] += 0

print(pol_eval.T)
```

```
##          0          10          20          30          40          50          60          70
## count  10863.0   5792.0   8140.0   7121.0   7549.0   7363.0   6991.0  10000.0
## sum    -64904.5 -29662.5 -33549.0 -24133.0 -15410.0 -14874.5 -9436.5      0.0
```

```
print(pol_eval['sum'] / pol_eval['count'])
```

```
#implementation pi_speed (running estimate)
```

```
## 0      -5.974823
## 10     -5.121288
## 20     -4.121499
## 30     -3.388990
## 40     -2.041330
## 50     -2.020168
## 60     -1.349807
## 70      0.000000
## dtype: float64
```

```
pol_eval = pd.DataFrame(np.zeros((len(states), 2)), index=states, columns=['count', 'est'])
print(pol_eval.T)
```

```
##          0   10   20   30   40   50   60   70
## count  0.0  0.0  0.0  0.0  0.0  0.0  0.0  0.0
## est    0.0  0.0  0.0  0.0  0.0  0.0  0.0  0.0
```

```
for MC_i in range(len(history_50)):
    history_i = history_50[MC_i]

    for j in range(0, len(history_i), 3):
        pol_eval.loc[history_i[j]]['count'] += 1
        current_cnt = pol_eval.loc[history_i[j]]['count']

        if j < len(history_i):
            new_info = pd.Series(history_i)[range(j + 2, len(history_i) - 1, 3)].astype('float').sum()

        else:
            new_info = 0

        alpha = 1 / current_cnt
        pol_eval.loc[history_i[j]]['est'] += alpha * (new_info - pol_eval.loc[history_i[j]]['est'])

print(np.round(pol_eval.T, 2))
```

```
##          0          10          20          30          40          50          60          70
## count  10863.00   5792.00   8140.00   7121.00   7549.00   7363.00   6991.00  10000.0
## est     -5.97     -5.12     -4.12     -3.39     -2.04     -2.02     -1.35      0.0
```