Mars Rover Markorv Process

Son Min Sang

2021-01-13

차 례

rs Rover Markov Process	2	2
Diagram	2	2
Transition matrix	2	2
MC simulation	3	3

Mars Rover Markov Process

Diagram

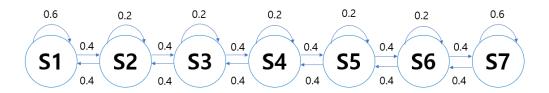


그림 1: Mars Rover MarkovProcess diagram

Transition matrix

$$P = \begin{pmatrix} 0.6 & 0.4 & 0 & 0 & 0 & 0 & 0 \\ 0.4 & 0.2 & 0.4 & 0 & 0 & 0 & 0 \\ 0 & 0.4 & 0.2 & 0.4 & 0 & 0 & 0 \\ 0 & 0 & 0.4 & 0.2 & 0.4 & 0 & 0 \\ 0 & 0 & 0 & 0.4 & 0.2 & 0.4 & 0 \\ 0 & 0 & 0 & 0 & 0.4 & 0.2 & 0.4 \\ 0 & 0 & 0 & 0 & 0 & 0.4 & 0.6 \end{pmatrix}$$

All state is recurrent

MC_simulation

```
import numpy as np
def MC_simul(this_state):
    u=np.random.random()
    state =["S1","S2","S3","S4","S5","S6","S7"]
    index=state.index(this_state)
    if this_state=="S1":
        if u<=0.4:</pre>
            next_state=state[index+1]
        else:
            next_state="S1"
    elif this_state=="S7":
        if u<=0.4:</pre>
            next_state=state[index-1]
        else:
            next_state='S7'
    else :
        if u<=0.4:</pre>
            next_state=state[index+1]
        elif u<=0.8:</pre>
            next_state=state[index-1]
            next_state=this_state
    return next_state
def reward_eval(path):
    reward=path.count('S1')*1+path.count('S7')*10
    return reward
MC_N=10000
spending_records=np.zeros((MC_N,))
for i in range(MC_N):
    path=['S4'] # starting point
```

```
for t in range(9):
    this_state=path[-1]
    next_state=MC_simul(this_state)
    path.append(next_state)

spending_records[i]=reward_eval(path)

print(np.mean(spending_records))
```

8.0335