# Rotation



# What We Will Learn

 Kinetic energy due to object's rotation must be accounted for when considering energy conservation

Parallel axis theorem

Rotational and translation kinetic energies are related

Newton's Second Law also applies to rotational motion

Conservation of angular momentum

- We start with some familiar concepts that we introduced to describe circular motion:
  - Angular displacement

 $\theta$ 

Angular velocity

$$\omega = \frac{d\theta}{dt}$$

Angular acceleration

$$\alpha = \frac{d\omega}{dt} = \frac{d^2\theta}{dt^2}$$

- We related the variables describing circular motion to the variables describing linear motion:
  - Displacement, velocity, and acceleration:

$$s = r\theta$$

$$v = r\omega$$

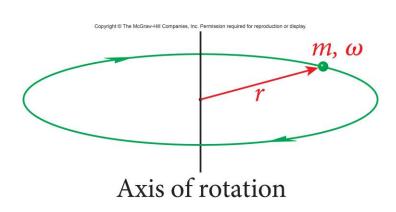
$$a_{t} = r\alpha \quad a_{c} = \omega^{2}r \quad a = \sqrt{a_{c}^{2} + a_{t}^{2}}$$

• Kinetic energy for linear motion:

$$K = \frac{1}{2}mv^2$$

Kinetic energy for rotation (point particle):

$$K = \frac{1}{2}mv^2 = \frac{1}{2}m(r\omega)^2 = \frac{1}{2}mr^2\omega^2$$



Now let's discuss the kinetic energy of several rotating point particles:

$$K = \sum_{i=1}^{n} K_{i} = \frac{1}{2} \sum_{i=1}^{n} m_{i} v_{i}^{2} = \frac{1}{2} \sum_{i=1}^{n} m_{i} r_{i}^{2} \omega_{i}^{2}$$

Copyright @ The McGraw-Hill Companies, Inc. Permission required for reproduction or display  $m_1, \omega_1$  $m_2$ ,  $\omega_2$  $m_3$ ,  $\omega$  $m_4$ ,  $\omega_4$  $m_5$ ,  $\omega_5$ Axis of rotation

• If we assume that these particles keep their distances fixed with respect to each other (solid object, all moving with the same angular velocity) we can write:

$$K = \frac{1}{2} \sum_{i=1}^{n} m_i r_i^2 \omega^2 = \frac{1}{2} \left( \sum_{i=1}^{n} m_i r_i^2 \right) \omega^2 = \frac{1}{2} I \omega^2$$

• Where *I* is the moment of inertia given by:

$$I = \sum_{i=1}^{n} m_i r_i^2$$

• We saw that all quantities associated with circular motion have equivalents in linear motion:

Compare 
$$K_{\text{linear}} = \frac{1}{2}mv^2 \iff K_{\text{rotation}} = \frac{1}{2}I\omega^2$$

- Consider two masses each of mass m.
- They are connected by a thin, massless rod.
- In the three drawings, the two masses spin in a horizontal plane around a vertical axis represented by a dashed line.
- Which of the systems has the highest rotational inertia?

Copyright © The McGraw-Hill Companies, Inc. Permission required for reproduction or display m m(a) 0.8 r **0.2** r m m (b) m

#### SIT Internal

### **Kinetic Energy of Rotation**

$$I = m\left(\frac{r}{2}\right)^2 + m\left(\frac{r}{2}\right)^2$$

$$I = \frac{1}{2}mr^2$$

$$I = m\left(\frac{r}{5}\right)^2 + m\left(\frac{4r}{5}\right)^2$$

$$I = \frac{17}{25}mr^2$$

$$I = m(0)^2 + m(r)^2$$

$$I = mr^2$$

Copyright © The McGraw-Hill Companies, Inc. Permission required for reproduction or display.

