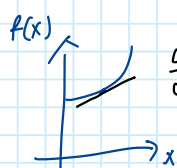


Some remarks on differential operators: gradient, divergence, curl (rot): The Del Operator (Nabla Operator)

Del / Nabla operator : $\vec{\nabla}$

(i) gradient : acts on a scalar function $f(x,y,z)$
result is a vector

Similar to slope of a curve in one-dimensional case



$$\frac{df}{dx} \rightarrow \frac{\partial f}{\partial x}$$

$df = \frac{\partial f}{\partial x} dx$ small change in x
tells how much the function f
changes with respect to x

$$\begin{aligned} \text{grad } f(x,y,z) &= \vec{\nabla} \cdot f(\vec{r}) = \begin{pmatrix} \frac{\partial}{\partial x} \\ \frac{\partial}{\partial y} \\ \frac{\partial}{\partial z} \end{pmatrix} \cdot f(x,y,z) \\ &= \begin{pmatrix} \frac{\partial}{\partial x} f \\ \frac{\partial}{\partial y} f \\ \frac{\partial}{\partial z} f \end{pmatrix} = \frac{\partial}{\partial x} f(x,y,z) \cdot \vec{e}_x + \frac{\partial}{\partial y} f(x,y,z) \cdot \vec{e}_y + \frac{\partial}{\partial z} f(x,y,z) \cdot \vec{e}_z \end{aligned}$$

Gradient points always in the direction of the steepest increase

(ii) Divergence (div) : acts on a vector field $\vec{f}(\vec{r}) = \vec{f}(x,y,z)$

$$\vec{\nabla} \cdot \vec{f}(x,y,z) = \begin{pmatrix} \frac{\partial}{\partial x} \\ \frac{\partial}{\partial y} \\ \frac{\partial}{\partial z} \end{pmatrix} \cdot \begin{pmatrix} f_x \\ f_y \\ f_z \end{pmatrix} = \frac{\partial}{\partial x} f_x + \frac{\partial}{\partial y} f_y + \frac{\partial}{\partial z} f_z = \text{div}(\vec{f}(x,y,z))$$

result is a scalar

div is correlated with the sources of a field and to the flux of a quantity

div corresponds to closed surface integrals \Rightarrow see (1.5) Gauss' Law

(iii) Curl operator

Del-operator applied to a vector field $\vec{f}(x,y,z)$ as a "vector product"

$$\vec{\nabla} \times \vec{f}(x,y,z) = \begin{pmatrix} \frac{\partial}{\partial x} \\ \frac{\partial}{\partial y} \\ \frac{\partial}{\partial z} \end{pmatrix} \times \begin{pmatrix} f_x \\ f_y \\ f_z \end{pmatrix} = \left(\frac{\partial}{\partial y} f_z - \frac{\partial}{\partial z} f_y \right) \vec{e}_x + \left(\frac{\partial}{\partial z} f_x - \frac{\partial}{\partial x} f_z \right) \vec{e}_y + \left(\frac{\partial}{\partial x} f_y - \frac{\partial}{\partial y} f_x \right) \vec{e}_z$$

result is a vector

Tells us something about vorticity of a vector field

Related to closed path integrals \oint

$$\operatorname{div}(\mathbf{v}_1 \wedge \mathbf{v}_2) = \mathbf{v}_2 \cdot \operatorname{rot} \mathbf{v}_1 - \mathbf{v}_1 \cdot \operatorname{rot} \mathbf{v}_2.$$

$$(13.30)$$

13.2.7.3 Expressions of Vector Analysis in Cartesian, Cylindrical, and Spherical Coordinates (see Table 13.3)

Table 13.3 Expressions of vector analysis in Cartesian, cylindrical, and spherical coordinates

| | x, y, z Cartesian coordinates | r, φ, ϑ Cylindrical coordinates | Spherical coordinates |
|--|--|---|---|
| $d\vec{s} = d\vec{r}$ | $\vec{e}_x dx + \vec{e}_y dy + \vec{e}_z dz$ | $\vec{e}_\rho d\rho + \vec{e}_\varphi \rho d\varphi + \vec{e}_z dz$ | $\vec{e}_r dr + \vec{e}_\vartheta r d\vartheta + \vec{e}_\varphi r \sin \vartheta d\varphi$ |
| grad U | $\vec{e}_x \frac{\partial U}{\partial x} + \vec{e}_y \frac{\partial U}{\partial y} + \vec{e}_z \frac{\partial U}{\partial z}$ | $\vec{e}_\rho \frac{\partial U}{\partial \rho} + \vec{e}_\varphi \frac{1}{\rho} \frac{\partial U}{\partial \varphi} + \vec{e}_z \frac{\partial U}{\partial z}$ | $\vec{e}_r \frac{\partial U}{\partial r} + \vec{e}_\vartheta \frac{1}{r} \frac{\partial U}{\partial \vartheta} + \vec{e}_\varphi \frac{1}{r \sin \vartheta} \frac{\partial U}{\partial \varphi}$ |
| div \vec{V} | $\frac{\partial V_x}{\partial x} + \frac{\partial V_y}{\partial y} + \frac{\partial V_z}{\partial z}$ | $\frac{1}{\rho} \frac{\partial}{\partial \rho} (\rho V_\rho) + \frac{1}{\rho} \frac{\partial V_\varphi}{\partial \varphi} + \frac{\partial V_z}{\partial z}$ | $\frac{1}{r^2} \frac{\partial}{\partial r} (r^2 V_r) + \frac{1}{r \sin \vartheta} \frac{\partial}{\partial \vartheta} (V_\vartheta \sin \vartheta) + \frac{1}{r \sin \vartheta} \frac{\partial V_\varphi}{\partial \varphi}$ |
| rot \vec{V} $\operatorname{rot} = \operatorname{rot}$ | $\vec{e}_x \left(\frac{\partial V_z}{\partial y} - \frac{\partial V_y}{\partial z} \right) + \vec{e}_y \left(\frac{\partial V_x}{\partial z} - \frac{\partial V_z}{\partial x} \right) + \vec{e}_z \left(\frac{\partial V_y}{\partial x} - \frac{\partial V_x}{\partial y} \right)$ | $\vec{e}_\rho \left(\frac{1}{\rho} \frac{\partial V_z}{\partial \varphi} - \frac{\partial V_\varphi}{\partial z} \right) + \vec{e}_\varphi \left(\frac{\partial V_\rho}{\partial z} - \frac{\partial V_z}{\partial \rho} \right) + \vec{e}_z \left(\frac{1}{\rho} \frac{\partial}{\partial \rho} (\rho V_\varphi) - \frac{1}{\rho} \frac{\partial V_\rho}{\partial \varphi} \right)$ | $\vec{e}_r \frac{1}{r \sin \vartheta} \left[\frac{\partial}{\partial \vartheta} (V_\varphi \sin \vartheta) - \frac{\partial V_\vartheta}{\partial \varphi} \right] + \vec{e}_\vartheta \frac{1}{r} \left[\frac{1}{\sin \vartheta} \frac{\partial V_r}{\partial \varphi} - \frac{\partial}{\partial r} (r V_\varphi) \right] + \vec{e}_\varphi \frac{1}{r} \left[\frac{\partial}{\partial r} (r V_\vartheta) - \frac{\partial V_r}{\partial \vartheta} \right]$ |
| ΔU | $\frac{\partial^2 U}{\partial x^2} + \frac{\partial^2 U}{\partial y^2} + \frac{\partial^2 U}{\partial z^2}$ | $\frac{1}{\rho} \frac{\partial}{\partial \rho} \left(\rho \frac{\partial U}{\partial \rho} \right) + \frac{1}{\rho^2} \frac{\partial^2 U}{\partial \varphi^2} + \frac{\partial^2 U}{\partial z^2}$ | $\frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial U}{\partial r} \right) + \frac{1}{r^2 \sin \vartheta} \frac{\partial}{\partial \vartheta} \left(\sin \vartheta \frac{\partial U}{\partial \vartheta} \right) + \frac{1}{r^2 \sin^2 \vartheta} \frac{\partial^2 U}{\partial \varphi^2}$ |