

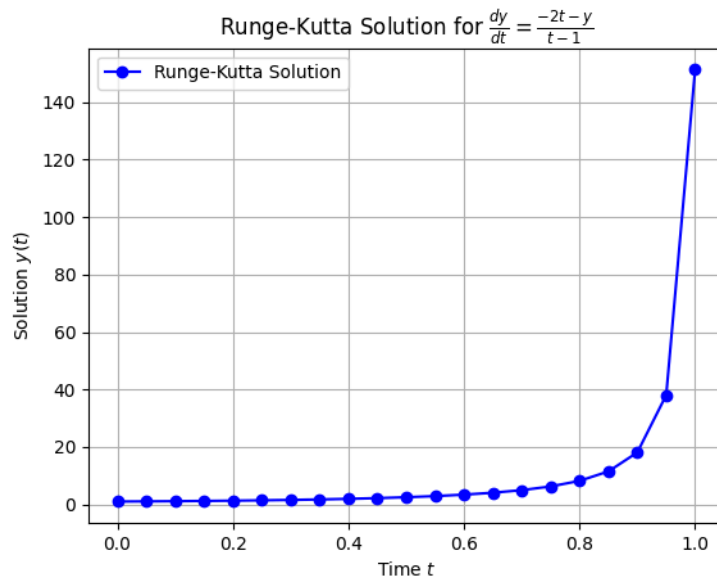
# Final Math 5712

Sean Dudley

December 3, 2024

## Problem 1:

Graph:



Code:

```
1 #PBM1: Runge-Kutta Method
2
3 import numpy as np
4 import matplotlib.pyplot as plt
5
6 #function
7 def f(t, y): 1 usage
8     return (-2 * t - y) / (t - 1) if t != 1 else 0
9 #Runge-Kutta Method
10 def runge_kutta(f, y0, t0, k, T): 1 usage
11     M = int((T - t0) / k)
12     t = np.arange(t0, T + k, k)
13     y = np.zeros(len(t))
14     y[0] = y0
15     #Runge-Kutta steps
16     for n in range(M):
17         t_n, y_n = t[n], y[n]
18         k1 = f(t_n, y_n)
19         k2 = f(t_n + k / 2, y_n + (k / 2) * k1)
20         k3 = f(t_n + k / 2, y_n + (k / 2) * k2)
21         k4 = f(t_n + k, y_n + k * k3)
22         y[n + 1] = y_n + (k / 6) * (k1 + 2 * k2 + 2 * k3 + k4)
23     return t, y
24 #Parameters
25 y0 = 1
26 t0 = 0
27 k = 0.05
28 T = 1
29 #Solve the ODE
30 t_values, y_values = runge_kutta(f, y0, t0, k, T)
```

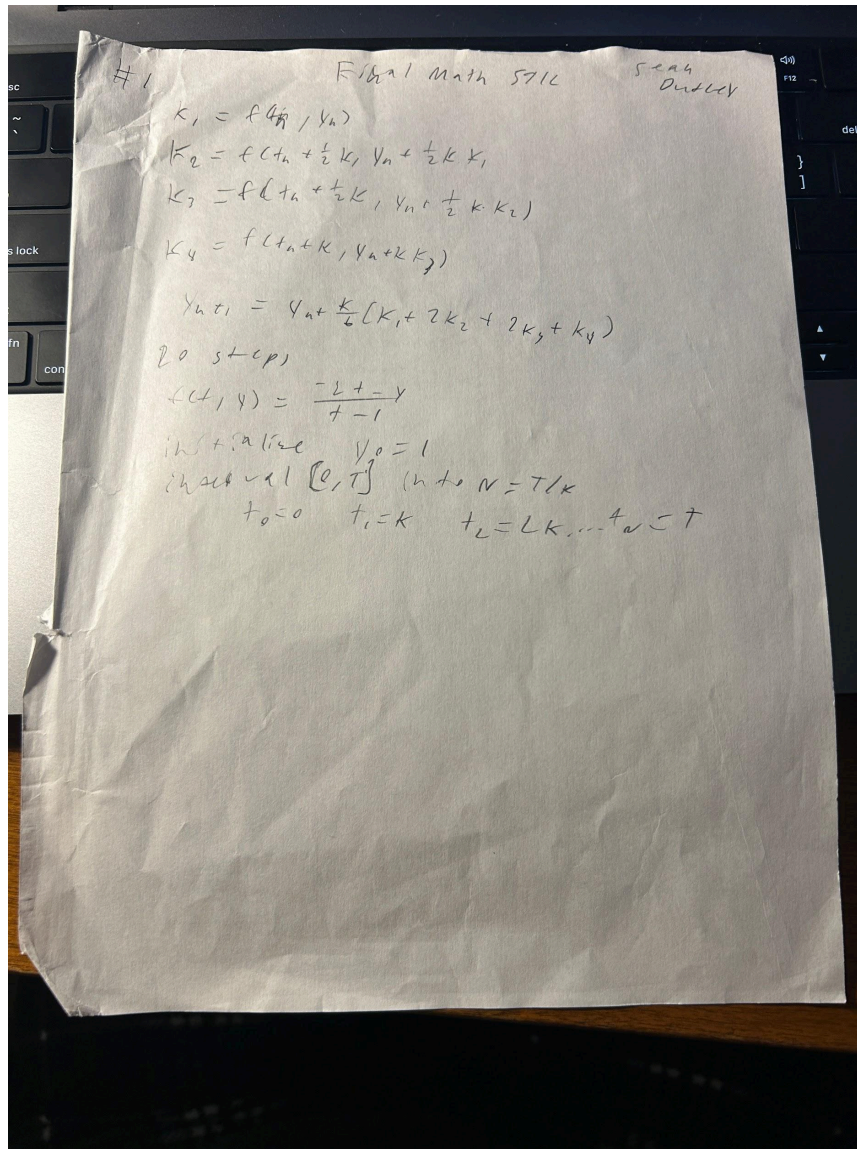
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```
31
32 #Plot
33 plt.plot(*args: t_values, y_values, 'b-o', label='Runge-Kutta Solution')
34 plt.title("Runge-Kutta Solution for  $\frac{dy}{dt} = \frac{-2t - y}{t - 1}$ ")
35 plt.xlabel("Time  $t$ ")
36 plt.ylabel("Solution  $y(t)$ ")
37 plt.legend()
38 plt.grid()
39 plt.show()
```

Written steps:



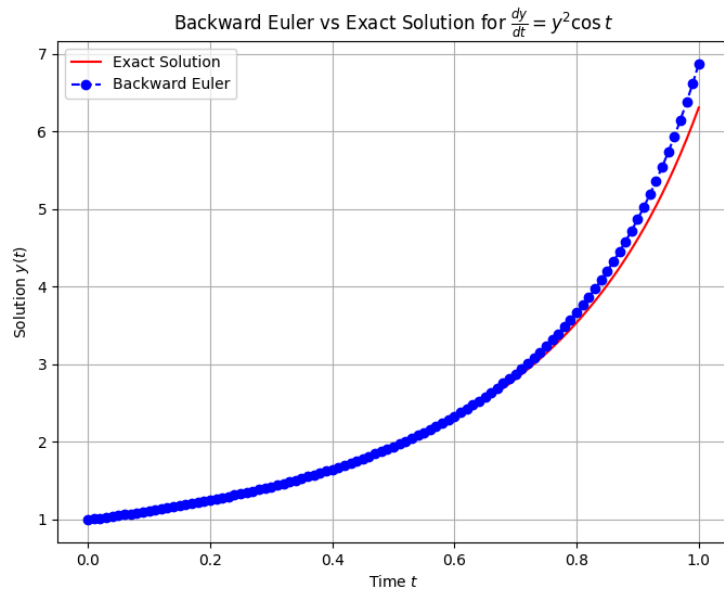
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## Problem 2:

Graph:



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Code:

```
42 #PBM2: Backward Euler and Newton method
43 #exact solution
44 def exact_solution(t): 1 usage
45     return -1 / (np.sin(t) - 1)
46 #ODE function for Backward Euler
47 def f(t, y): 1 usage
48     return y**2 * np.cos(t)
49
50 #Newton Method
51 def newton_method(y_n, t_next, k, max_iter=3): 1 usage
52     #Initial guess
53     y_guess = y_n
54     for _ in range(max_iter):
55         g = y_guess - y_n - k * y_guess**2 * np.cos(t_next)
56         g_prime = 1 - 2 * k * y_guess * np.cos(t_next)
57         y_guess -= g / g_prime
58     return y_guess
59 #Backward Euler Method
60 def backward_euler(f, y0, t0, k, T, max_iter=3): 1 usage
61     #Time and solution arrays
62     t_values = np.arange(t0, T + k, k)
63     y_values = np.zeros(len(t_values))
64     y_values[0] = y0
65     #solve using Backward Euler
66     for n in range(len(t_values) - 1):
67         t_next = t_values[n + 1]
68         y_values[n + 1] = newton_method(y_values[n], t_next, k, max_iter)
69     return t_values, y_values
70 #Parameters
71 y0 = 1
72 t0 = 0
73 k = 0.01
74 T = 1
75 #Solve with Backward Euler
76 t_values, y_numerical = backward_euler(f, y0, t0, k, T)
77 #exact solution
78 y_exact = exact_solution(t_values)
79 #error at T=1
80 error_at_T = abs(y_exact[-1] - y_numerical[-1])
81
82 #Plot
83 plt.figure(figsize=(8, 6))
84 plt.plot(*args: t_values, y_exact, 'r-', label='Exact Solution')
85 plt.plot(*args: t_values, y_numerical, 'b--o', label='Backward Euler')
86 plt.title("Backward Euler vs Exact Solution for  $\frac{dy}{dt} = y^2 \cos t$ ")
87 plt.xlabel("Time  $t$ ")
88 plt.ylabel("Solution  $y(t)$ ")
89 plt.legend()
90 plt.grid()
91 plt.show()
92 # error
93 print(f"Error at T={T}: {error_at_T:.6f}")
```

Error at T=1: 0.563184  
Option Price 10.4043

Output:



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Witten Steps:

#2

exact:  $\frac{dy}{dt} = y^2 \cos(t)$

$$\frac{1}{y^2} dy = \cos(t) dt$$

$$\int \frac{1}{y^2} dy = \int \cos(t) dt$$

$$-\frac{1}{y} = \sin(t) + C$$

$$y(t) = \frac{-1}{\sin(t) + C} \quad C = -1$$

$$y(t) = \frac{-1}{\sin(t) - 1}$$

(or stop)

Backward Euler

$$\frac{y_{i+1} - y_i}{k} = y_{i+1}^2 \cos(t_{i+1})$$

$$F(y_{i+1}) = y_{i+1} - k y_{i+1}^2 \cos(t_{i+1}) - y_i = 0$$

Newton's method:  $F(y_{i+1}) = y_{i+1} - k y_{i+1}^2 \cos(t_{i+1}) - y_i$

$$\text{derivative } F'(y_{i+1}) = 1 - 2k y_{i+1} \cos(t_{i+1})$$

$$y_{i+1}^{(k)} = y_{i+1}^{(k-1)} - \frac{F(y_{i+1}^{(k-1)})}{F'(y_{i+1}^{(k-1)})}$$

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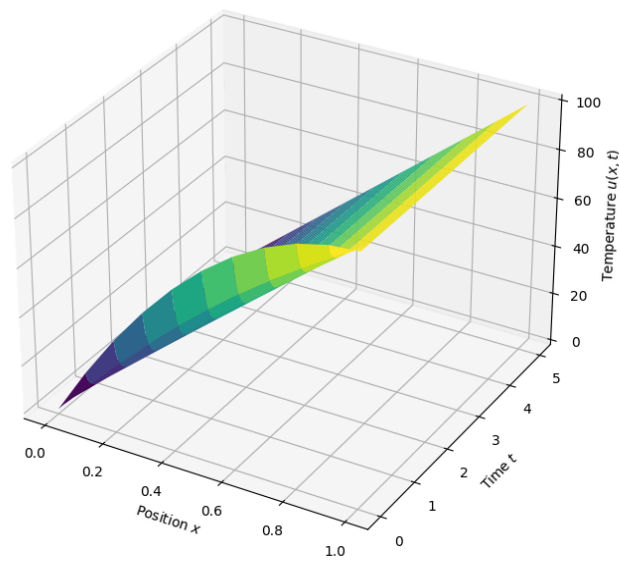
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## Problem 3:

Graph:

Heat Equation Solution (Implicit Scheme)



Code:

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```
96 #PBM 3 Implicit scheme for Heat equation
97
98 import numpy as np
99 import matplotlib.pyplot as plt
100 from mpl_toolkits.mplot3d import Axes3D
101
102 # Parameters
103 L = 1
104 T = 5
105 h = 1 / 10
106 k = h / 2
107 s = h**2 / k
108 tau = 2 + s
109 r = 1
110 # Discretization
111 x = np.arange(0, L + h, h)
112 t = np.arange(0, T + k, k)
113 N_x = len(x)
114 N_t = len(t)
115 # Initial and boundary conditions
116 u = np.zeros((N_t, N_x))
117 u[0, :] = 100 * x * (2 - x)
118 u[:, 0] = 0
119 u[:, -1] = 100
120 # Tridiagonal matrix A
121 main_diag = tau * np.ones(N_x - 2)
122 lower_diag = -r * np.ones(N_x - 3)
123 upper_diag = -r * np.ones(N_x - 3)
```

```
124 # Thomas Algorithm
125 def thomas_algorithm(a, b, c, d): 1 usage
126     n = len(b)
127     c_prime = np.zeros(n - 1)
128     d_prime = np.zeros(n)
129     c_prime[0] = c[0] / b[0]
130     d_prime[0] = d[0] / b[0]
131     for i in range(1, n - 1):
132         temp = b[i] - a[i - 1] * c_prime[i - 1]
133         c_prime[i] = c[i] / temp
134         d_prime[i] = (d[i] - a[i - 1] * d_prime[i - 1]) / temp
135     d_prime[-1] = (d[-1] - a[-2] * d_prime[-2]) / (b[-1] - a[-2] * c_prime[-2])
136     x = np.zeros(n)
137     x[-1] = d_prime[-1]
138     for i in range(n - 2, -1, -1):
139         x[i] = d_prime[i] - c_prime[i] * x[i + 1]
140     return x
141 # Time-stepping loop
142 for n in range(N_t - 1):
143     # Right-hand side
144     b = s * u[n, 1:-1]
145     b[0] += r * 0
146     b[-1] += r * 100
147 # Solve the system for the next time step
148 u[n + 1, 1:-1] = thomas_algorithm(lower_diag, main_diag, upper_diag, b)
```

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```
150 # 3D Plot
151 X, T_mesh = np.meshgrid(*xi: x, t)
152 fig = plt.figure(figsize=(12, 8))
153 ax = fig.add_subplot(111, projection='3d')
154 ax.plot_surface(X, T_mesh, u, cmap='viridis')
155 ax.set_title("Heat Equation Solution (Implicit Scheme)")
156 ax.set_xlabel("Position  $x$ ")
157 ax.set_ylabel("Time  $t$ ")
158 ax.set_zlabel("Temperature  $u(x, t)$ ")
159 plt.show()
```

Written steps:



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#3

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$$\frac{u_{i,h+1} - u_{i,h}}{h} = \frac{1}{10} \frac{u_{i,h+1}^2 - 2u_{i,h+1} + u_{i,h+1}}{h^2}$$

$$1 - \frac{1}{10h^2} = -r u_{i-1}^{h+1} + (1 + 2r) u_{i,h+1} - r u_{i+1}^{h+1} = u_i^n$$

for diagonal

$$A = \begin{pmatrix} 1+2r & -r & 0 & \dots & 0 \\ 0 & 1+2r & -r & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & \dots & -r & 1+2r \end{pmatrix}$$

2x2 block form

rearranging

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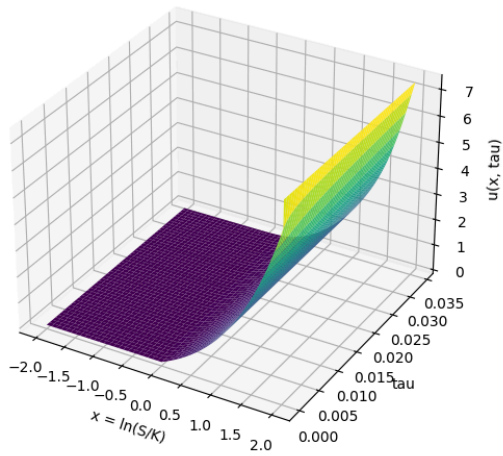
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## Problem 4:

Graph:

Heat Equation Solution (Explicit Scheme)



Code:

## Final Math 5712

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```
161  # PBM 4
162
163  #Import necessary libraries
164  import numpy as np
165  import matplotlib.pyplot as plt
166  #Parameters
167  S = 85
168  K = 85
169  r = 0.04
170  sigma = 0.5
171  T = 100 / 365
172  h = 0.004
173  x_min = -2
174  x_max = 2
175  k = (sigma**2 * T) / (2 * 10000)
176  tau_max = sigma**2 * T / 2
177  #discretization
178  x = np.arange(x_min, x_max + h, h)
179  tau = np.arange(0, tau_max + k, k)
180  N_x = len(x)
181  N_tau = len(tau)
182  sigma_explicit = k / h**2
183  #sol array
184  u = np.zeros((N_tau, N_x))
185  #initial/boundary condition
186  u[0, :] = np.maximum(np.exp(x) - 1, 0)
187  u[:, 0] = 0
188  u[:, -1] = np.exp(x_max)
```

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```
189 #Explicit scheme
190 for n in range(N_tau - 1):
191     for i in range(1, N_x - 1):
192         u[n + 1, i] = (
193             sigma_explicit * u[n, i - 1] +
194             (1 - 2 * sigma_explicit) * u[n, i] +
195             sigma_explicit * u[n, i + 1] )
196 #compute
197 k_transformed = 2 * r / sigma**2
198 tau_final = tau_max
199 ln_S_K = np.log(S / K)
200 index = np.argmin(np.abs(x - ln_S_K))
201 u_interpolated = u[-1, index]
202
203 #Option price
204 C = K * u_interpolated * np.exp(
205     -0.5 * (k_transformed - 1) * ln_S_K -
206     0.25 * (k_transformed + 1)**2 * tau_final)
207 #Price
208 print(f"The price call option is {C:.4f}")
209 #Plot
210 X, T_mesh = np.meshgrid(*xi: x, tau)
211 fig = plt.figure(figsize=(12, 8))
212 ax = fig.add_subplot(111, projection='3d')
213 ax.plot_surface(X, T_mesh, u, cmap='viridis')
214 ax.set_title("Heat Equation Solution (Explicit Scheme)")
215 ax.set_xlabel("x = ln(S/K)")
216 ax.set_ylabel("tau")
217 ax.set_zlabel("u(x, tau)")
218 plt.show()
```

Error at T=1: 0.563184  
Option Price 10.4043

Output of call price:

Written steps:



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#4

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explicit

$$u_i^{n+1} = \sigma u_{i-1}^n + (1-2\sigma)u_i^n + \sigma u_{i+1}^n$$

$$\sigma = \frac{\tau}{h^2}$$

$$u(x, 0) = \max(e^x - 1, 0)$$

$$2) x \rightarrow -\infty u(x, t) = 0 \quad x \rightarrow \infty u(x, t) = e^x$$

0 < t < 100 + 100h

$$N_x = \frac{x_{\max} - x_{\min}}{h} + 1$$

$$\text{time step } k = \frac{0.2}{2 \cdot 10.109}$$

$$\text{total steps } N_t = \frac{0.2}{2k} + 1 \text{ (approx)}$$

$$N_x = \frac{x_{\max} - x_{\min}}{h} + 1$$

$u_i^{n+1}$  for interior points

$$u_i^{n+1} = \sigma u_{i-1}^n + (1-2\sigma)u_i^n + \sigma u_{i+1}^n$$

$$u(s, 0) = K u(\ln(s/K), \tau) e^{-\frac{1}{2}(K-1)\ln(s/K) - \frac{1}{4}K \ln^2(s/K)}$$

$$\gamma_n = h \cdot K \quad n = 0, 1, \dots, N_T$$

$$u_0^{n+1} = 0$$

$$u_{N_x}^{n+1} = e^{x_{\max}}$$