MATLAB Homework #2

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ECE 538

Digital Signal Processing I

Fall 2020

(A)
$$h_0^{(2)}[n] = \frac{1}{\sqrt{2}}\{1,1\}$$
 and $h_1^{(2)}[n] = \frac{1}{\sqrt{2}}\{1,-1\}.$

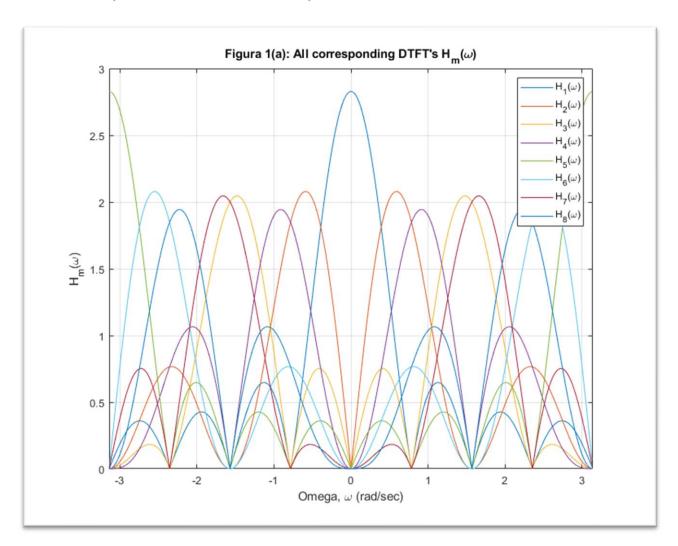


Figure 1(a): All corresponding DTFT's H_m(ω)

1	0	0	0	0	0	0	0
0	1	0	0	0	0	0	0
0	0	1	0	0	0	0	0
0	0	0	1	0	0	0	0
0	0	0	0	1	0	0	0
0	0	0	0	0	1	0	0
0	0	0	0	0	0	1	0
0	0	0	0	0	0	0	1

Table 1: 8x8 matrix of HH^H

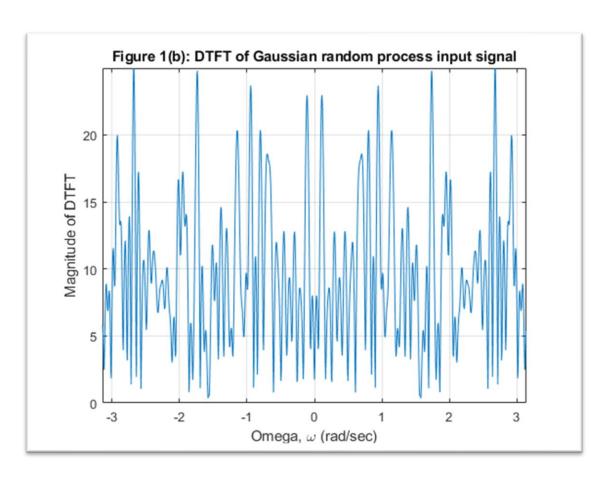


Figure 1(b): DTFT of Gaussian random process input signal

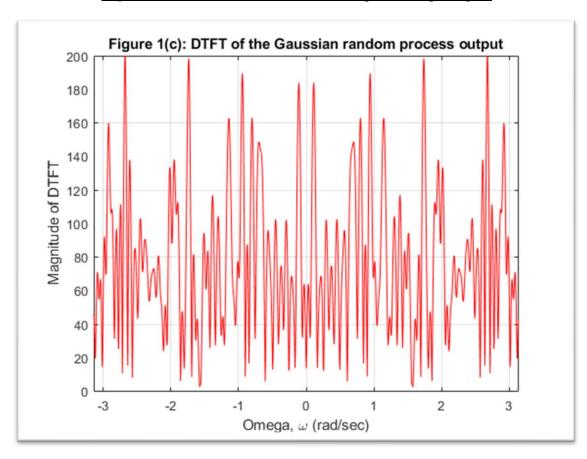


Figure 1(c): DTFT of the Gaussian random process output

(B)
$$h_0^{(2)}[n] = h_{sr}[n-16], n = 0, 1, ..., 31, h_1^{(2)}[n] = (-1)^n h_0^{(2)}[n], \text{ and } \beta = 0.35 \text{ where}$$

$$h_{sr}[n] = \sqrt{2} \left\{ \frac{2\beta \cos[(1+\beta)\pi(n+.5)/2]}{\pi[1-4\beta^2(n+.5)^2]} + \frac{\sin[(1-\beta)\pi(n+.5)/2]}{\pi[(n+.5)-4\beta^2(n+.5)^3]} \right\}, n = -16, ..., 1, ..., 15.$$

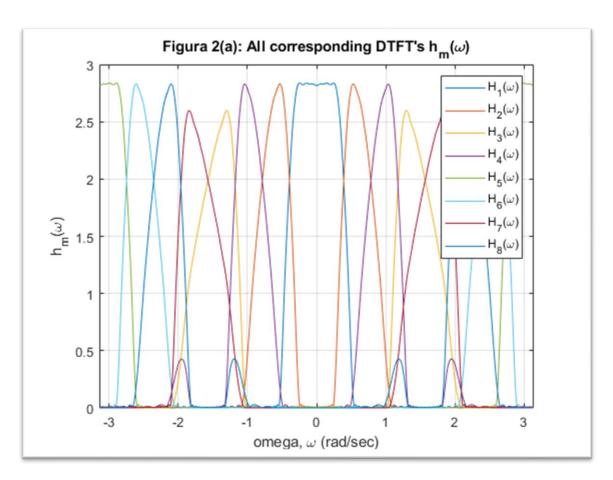


Figure 2(a): All corresponding DTFT's $H_m(\omega)$

1.000002	-4.77E-17	-2.13E-17	7.03E-07	2.15E-16	3.47E-17	-8.43E-17	-1.79E-17
-4.77E-17	0.999864	-7.03E-07	1.11E-16	3.47E-17	6.27E-17	-3.93E-17	-5.70E-17
-2.13E-17	-7.03E-07	1.000164	9.79E-18	-8.43E-17	-3.93E-17	2.03E-16	-1.21E-17
7.03E-07	1.11E-16	9.79E-18	0.999511	-1.79E-17	-5.70E-17	-1.21E-17	-4.44E-17
2.15E-16	3.47E-17	-8.43E-17	-1.79E-17	1.000002	-4.77E-17	-2.13E-17	7.03E-07
3.47E-17	6.27E-17	-3.93E-17	-5.70E-17	-4.77E-17	0.999864	-7.03E-07	1.11E-16
-8.43E-17	-3.93E-17	2.03E-16	-1.21E-17	-2.13E-17	-7.03E-07	1.000164	9.79E-18
-1.79E-17	-5.70E-17	-1.21E-17	-4.44E-17	7.03E-07	1.11E-16	9.79E-18	0.999511

Table 2: 8x8 matrix of HH^H for B

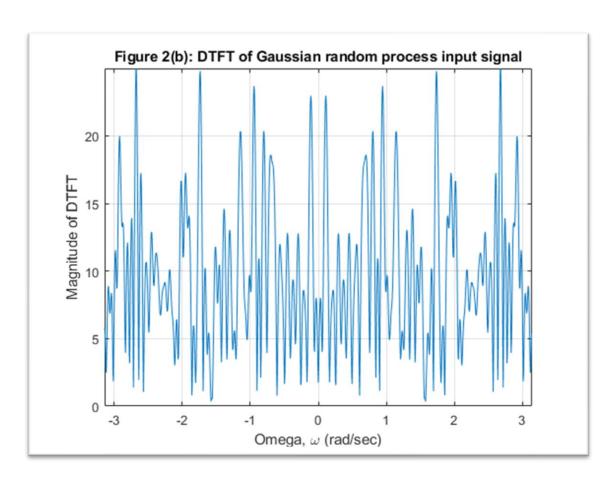


Figure 2(b): DTFT of Gaussian random process input signal

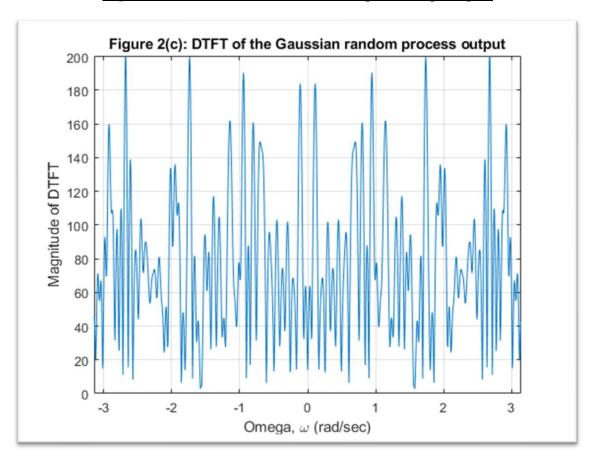


Figure 2(c): DTFT of the Gaussian random process output

(C)
$$h_0^{(2)}[n] = h_{sr}[n-24], n = 0, 1, ..., 47, h_1^{(2)}[n] = (-1)^n h_0^{(2)}[n], \text{ and } \beta = 0.1 \text{ where}$$

$$h_{sr}[n] = \sqrt{2} \left\{ \frac{2\beta \cos[(1+\beta)\pi(n+.5)/2]}{\pi[1-4\beta^2(n+.5)^2]} + \frac{\sin[(1-\beta)\pi(n+.5)/2]}{\pi[(n+.5)-4\beta^2(n+.5)^3]} \right\}, n = -24, ..., 1, ..., 23.$$

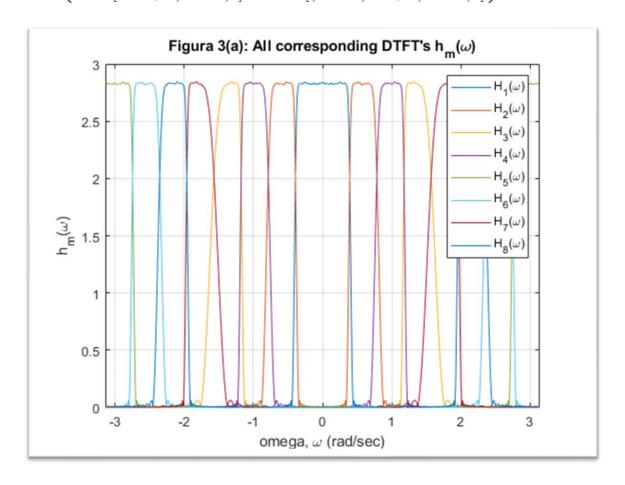


Figure 3(a): All corresponding DTFT's $H_m(\omega)$

0.999892	-2.50E-16	2.91E-16	3.64E-07	-4.86E-17	6.94E-18	2.78E-17	-8.67E-17
-2.50E-16	0.999822	-3.64E-07	1.67E-16	6.94E-18	-3.89E-16	6.94E-18	6.94E-17
2.91E-16	-3.64E-07	0.999833	2.78E-17	5.55E-17	-4.16E-17	1.11E-16	5.55E-17
3.64E-07	1.67E-16	2.78E-17	0.999095	-8.67E-17	6.94E-17	4.16E-17	6.07E-17
-4.86E-17	6.94E-18	5.55E-17	-8.67E-17	0.999892	-2.50E-16	2.91E-16	3.64E-07
6.94E-18	-3.89E-16	-4.16E-17	6.94E-17	-2.50E-16	0.999822	-3.64E-07	-5.55E-17
2.78E-17	6.94E-18	1.11E-16	4.16E-17	2.91E-16	-3.64E-07	0.999833	-8.33E-17
-8.67E-17	6.94E-17	5.55E-17	6.07E-17	3.64E-07	-5.55E-17	-8.33E-17	0.999095

Table 2: 8x8 matrix of HH^H for C

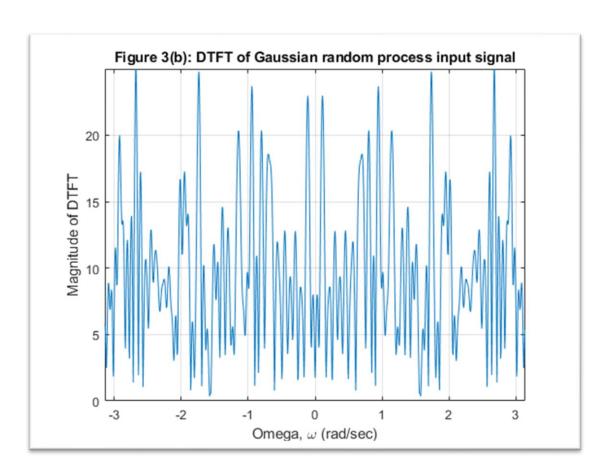


Figure 3(b): DTFT of Gaussian random process input signal

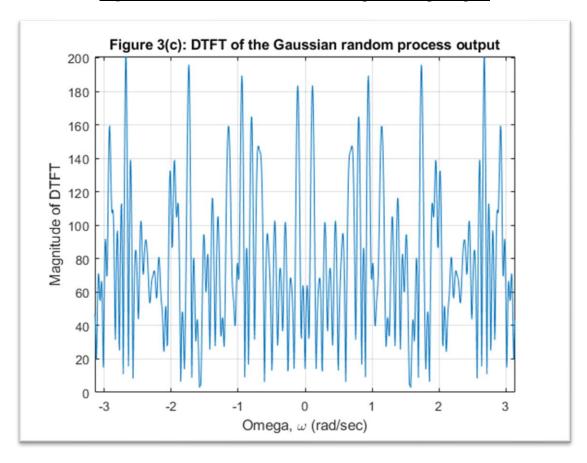


Figure 3(c): DTFT of the Gaussian random process output

Observations and conclusion from the experiment:

The computer experiment was conducted successfully, and a M=8 channel perfect reconstruction filter bank was synthesized from a three stage three-structured PR filter bank. The biggest, and most obvious observation that I was able to make from this experiment was that the DTFT magnitude from the output of filter was 8 times greater than the gaussian random process signal that was inputted to the filter. This is a definitive proof that the three stage tree-structured PR filter bank was successfully synthesized to an M=8 channel uniform PR filter bank according to Noble's Identity. The plot of DTFT of the input signal and the output have an identical shape, but the two plots only differ in the magnitude of signal with output amplified to the factor of 8.

Part D

- i) Problem 2 from Exam 3 for Fall 2015
- ii) Problem 1 from Final Exam for Fall 2011

Digital Signal Processing I

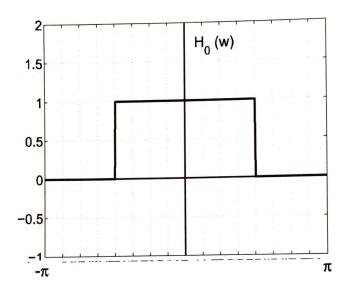
Exam 3

Fall 2015

Problem 2. In Matlab Homework 2, you used Noble's Identities to convert the Tree-Structured subbander on the previous page to the regular maximally decimated subbander, obtaining products of the form:

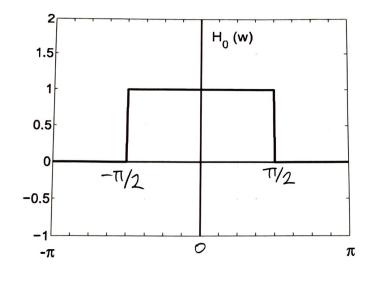
$$H_k(\omega) = H_\ell^{(2)}(\omega) H_m^{(2)}(2\omega) H_n^{(2)}(4\omega) \quad k = 0, 1, ..., 7$$

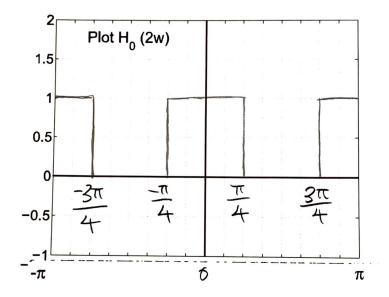
where $\ell \in \{0,1\}$, $m \in \{0,1\}$, and $n \in \{0,1\}$, with $H_0^{(2)}(\omega)$ denoting the lowpass halfband filter below for the two-channel QMF and $H_1^{(2)}(\omega) = H_0^{(2)}(\omega - \pi)$. For this problem, $H_0^{(2)}(\omega)$ is the ideal lowpass filter below (note: a DTFT is always periodic with period 2π .)

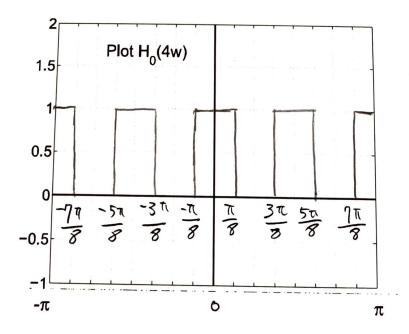


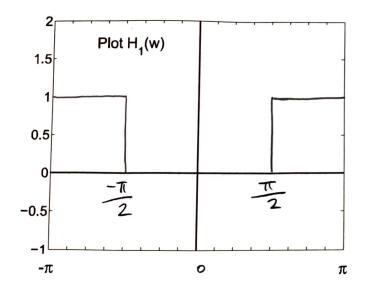
You are required to fill in the table below. **FIRST** you should plot $H_0^{(2)}(2\omega)$ and $H_0^{(2)}(4\omega)$ on the next page, and then plot $H_1^{(2)}(\omega)$, $H_0^{(2)}(2\omega)$ and $H_0^{(2)}(4\omega)$ on the next page after that, in the space provided. In each plot, the abscissa range is from $-\pi$ to $+\pi$ and there is a tic mark and vertical dashed line at every integer multiple of $\pi/8$. These plots will help you fill in the table. I have already filled in the first entry. Only fill in the positive frequency band that is passed; the filters are real-valued and even-symmetric, so their respective frequency responses are real-valued and even-symmetric.

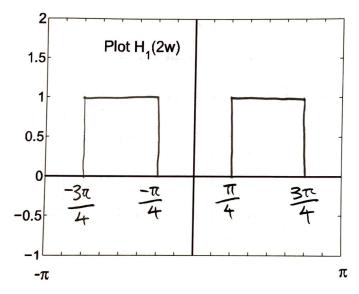
$$\begin{array}{lll} H_{0}^{(2)}(\omega)H_{0}^{(2)}(2\omega)H_{0}^{(2)}(4\omega) & \text{passes: } 0<\omega<\pi/8\\ H_{0}^{(2)}(\omega)H_{0}^{(2)}(2\omega)H_{1}^{(2)}(4\omega) & \text{passes: } \sqrt{8} < \omega < \pi/4\\ H_{0}^{(2)}(\omega)H_{1}^{(2)}(2\omega)H_{0}^{(2)}(4\omega) & \text{passes: } 3\sqrt{8} < \omega < \pi/2\\ H_{0}^{(2)}(\omega)H_{1}^{(2)}(2\omega)H_{0}^{(2)}(4\omega) & \text{passes: } \pi/4 < \omega < \pi/8\\ H_{1}^{(2)}(\omega)H_{0}^{(2)}(2\omega)H_{0}^{(2)}(4\omega) & \text{passes: } \sqrt{\pi/8} < \omega < \pi\\ H_{1}^{(2)}(\omega)H_{0}^{(2)}(2\omega)H_{0}^{(2)}(4\omega) & \text{passes: } 3\pi/4 < \omega < \sqrt{\pi/8}\\ H_{1}^{(2)}(\omega)H_{0}^{(2)}(2\omega)H_{1}^{(2)}(4\omega) & \text{passes: } 3\pi/4 < \omega < \sqrt{\pi/8}\\ H_{1}^{(2)}(\omega)H_{1}^{(2)}(2\omega)H_{0}^{(2)}(4\omega) & \text{passes: } \pi/2 < \omega < \sqrt{\pi/8}\\ H_{1}^{(2)}(\omega)H_{1}^{(2)}(2\omega)H_{0}^{(2)}(4\omega) & \text{passes: } \pi/2 < \omega < \sqrt{\pi/8}\\ H_{1}^{(2)}(\omega)H_{1}^{(2)}(2\omega)H_{1}^{(2)}(4\omega) & \text{passes: } \pi/2 < \omega < \sqrt{\pi/8}\\ \end{array}$$

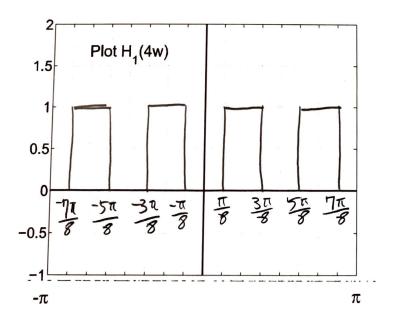












Problem 1. This problem is about determining whether the four-band analysis filter bank and corresponding four-band synthesis filter bank in Figure 1 achieves Perfect Reconstruction when the respective impulse responses for the four filters

$$f_k[n] = e^{j(k\frac{2\pi}{4})n} h_{LP}[n], \quad k = 0, 1, 2, 3$$

are defined in terms of the lowpass filter with impulse response below, which is of length 4.

$$h_{LP}[n] = u[n] - u[n-4].$$
 (1)

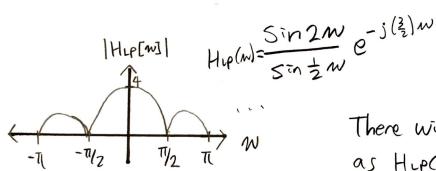
This question is more easily answered examining the efficient version of the overall filter bank in Figure 2.

- (a) Plot the magnitude of the DTFT $H_{LP}(\omega)$ of $h_{LP}[n]$ over $-\pi < \omega < \pi$. Will there be aliasing present in each of the outputs $z_k[n]$?
- (b) The four polyphase components of $h_{LP}[n]$ are defined as

$$h_{\ell}^{+}[n] = h_{LP}[4n + \ell], \quad \ell = 0, 1, 2, 3.$$
 (2)

Do a separate stem plot (time-domain) of each of the four impulse responses $h_{\ell}^{+}[n]$, $\ell = 0, 1, 2, 3$. Are they all the same?

a)



There will be substantial alising as Hup(10) Passes energy outside the band |w| < 11/4.

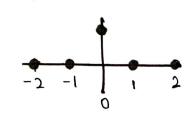
b). hotn] = hup[4n] = f[n]

hit[n] = hup[4n+1] = f[n] = hup[1]

hit[n] = hup[4n+2] = f[n] = hup[2]

hit[n] = hup[4n+3] = f[n] = hup[3]

hit[n] = hup[4n+3] = f[n] = hup[3]



(c) The digital subbanding on the left hand side of Figure 1 is alternatively effected more efficiently with the polyphase filters via the block diagram on the left side of Figure 2, where the respective input signals are defined as below. Fill in the values of $\beta_{k\ell}$ in the table below so that the outputs, $z_k[n]$, k=0,1,2,3, at the output of the left hand side in Figure 2 are exactly the same as the outputs $z_k[n]$ of the left hand side in Figure 1. Show all work.

$$\begin{bmatrix} z_0[n] \\ z_1[n] \\ z_2[n] \\ z_3[n] \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & \beta_{11} & \beta_{12} & \beta_{13} \\ 1 & \beta_{21} & \beta_{22} & \beta_{23} \\ 1 & \beta_{31} & \beta_{32} & \beta_{33} \end{bmatrix} \begin{bmatrix} s_0[n] \\ s_1[n] \\ s_2[n] \\ s_3[n] \end{bmatrix} \quad \Rightarrow \quad \mathbf{B} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & \beta_{11} & \beta_{12} & \beta_{13} \\ 1 & \beta_{21} & \beta_{22} & \beta_{23} \\ 1 & \beta_{31} & \beta_{32} & \beta_{33} \end{bmatrix} \quad (3)$$

$eta_{k\ell}$	$\ell = 1$	$\ell = 2$	$\ell = 3$
k = 1	ر»	-1	17
k = 2	-1	١	-1
k = 3	-3	-1	ئ

$$k=1, \ell=1 = j' = j$$

$$k=3, \ell=3 = (j^3)^{\ell} = (-j)^{3} = j$$

(d) The zero inserts followed by filtering is done more efficiently in a collective manner. First, note, in order to match the inputs with the outputs, we effect the efficient implementation of "L zero inserts followed by filtering" in an alternative fashion relative to the way it was originally derived in class. In this case, we interleave in a **clockwise** fashion the following outputs below for $\ell = 0, 1, 2, 3$.

$$y[Ln-\ell] = x[n] * h[Ln-\ell]$$
 (4)

$$y[Ln-\ell] = x[n] * h_{\ell}^{-}[n]$$

$$\tag{5}$$

(6)

where $h_{\ell}^{-}[n] = h[Ln - \ell], \ \ell = 0, 1, ..., L - 1.$

Thus, the polyphase components of interest for this part of the problem are

$$h_{\ell}^{-}[n] = g_0[4n - \ell], \quad \ell = 0, 1, 2, 3,$$
 (7)

where $g_0[n] = h_{LP}[-n]$ with $h_{LP}[n] = u[n] - u[n-4]$ as before. It follows that

$$h_{\ell}^{-}[n] = h_{LP}[\ell - 4n], \quad \ell = 0, 1, 2, 3,$$
 (8)

where, again, $h_{LP}[n] = u[n] - u[n-4]$ is only of length 4.

With this in mind, determine the value of each of the amplitude coefficients $\alpha_{\ell k}$, k=1,2,3, $\ell=1,2,3$ so that the interleaved output y[n] in Figure 2 is the SAME as the overall output in Figure 1. Show all work on the next page but input your final answers in the table below.

$$\begin{bmatrix} y_0[n] \\ y_1[n] \\ y_2[n] \\ y_3[n] \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & \alpha_{11} & \alpha_{12} & \alpha_{13} \\ 1 & \alpha_{21} & \alpha_{22} & \alpha_{23} \\ 1 & \alpha_{31} & \alpha_{32} & \alpha_{33} \end{bmatrix} \begin{bmatrix} z_0[n] \\ z_1[n] \\ z_2[n] \\ z_3[n] \end{bmatrix} \quad \Rightarrow \quad \mathbf{A} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & \alpha_{11} & \alpha_{12} & \alpha_{13} \\ 1 & \alpha_{21} & \alpha_{22} & \alpha_{23} \\ 1 & \alpha_{31} & \alpha_{32} & \alpha_{33} \end{bmatrix} \quad (9)$$

$$g_{\kappa}[n] = e^{-j\frac{2\pi}{4}\kappa(-n)} h_{\kappa}p[n]$$

$lpha_{\ell k}$	k = 1	k = 2	k = 3	
$\ell = 1$	رُ	-1	Lo	
$\ell=2$	-	l	-1	
$\ell = 3$	۲.	- (-;	

(e) For part (c), we defined the following four polyphase components of $h_{LP}[n]$

$$h_{\ell}^{-}[n] = g_0[4n - \ell], \quad \ell = 0, 1, 2, 3.$$
 (10)

where $g_0[n] = h_{LP}[-n]$ with $h_{LP}[n] = u[n] - u[n-4]$. Do a separate stem plot (time-domain) of each of the four impulse responses $h_{\ell}^-[n]$, $\ell = 0, 1, 2, 3$. Are they all the same?

(f) Does y[n] = 4x[n]? You need to either prove or disprove y[n] = 4x[n] with all that you've developed so far for parts (a) through (e).

Hint: assess if $y[4n - \ell] = 4x[4n - \ell]$, for $\ell = 0, 1, 2, 3$.

e)
$$h_{0}[n] = g[n]$$

 $h_{1}[n] = g[n]$
 $h_{2}[n] = g_{1}[4n-2] = g[n] = g_{0}[-2]$
 $h_{3}[n] = g_{0}[4n-3] = g[n] = g_{0}[-3]$

f) Yes, y[n] = 4x[n]; By Perfect reconstruction. $he^{t}[n] \times he[n] = f[n] \times f[n] = f[n]$

Here, het and he are in series, and if a inverse DFT matrix is cascaded w/ DFJ matrix, we get a Identity matrix.

Therefore, Using previous answers I can say

Y[4n-l]=4x[4n-l] for l=0,1,2,3.

which is ytn]= 4x[m]

Appendix - MATLAB source code for the entire project

```
%----%
% Sean Hwang %
% ECE 538 - MATLAB Project 2 %
% Source Code File %
%----%
clc
clf
clear all
close all
% A) h 0 = \{1/\operatorname{sqrt}(2), 1/\operatorname{sqrt}(2)\} ,, h 1 = \{1/\operatorname{sqrt}(2), -1/\operatorname{sqrt}(2)\}
% Setting up M=8 channel DFT filter bank
M = 8;
h0 = [1 1] / sqrt(2);
h1 = [1 -1] / sqrt(2);
h00 = [1 \ 0 \ 1] / sqrt(2);
h10 = [1 \ 0 \ -1] / sqrt(2);
h000 = [1 \ 0 \ 0 \ 1] / sqrt(2);
h100 = [1 \ 0 \ 0 \ -1] / sqrt(2);
H \text{ temp} = \text{conv}(h0, h00);
H(1,:) = conv(H temp, h000); G(1,:) = H(1, :);
H(2,:) = conv(H temp, h100); G(2,:) = -H(2,:);
H \text{ temp} = \text{conv}(h0, h10);
H(3,:) = conv(H temp, h000); G(3,:) = -H(3,:);
H(4,:) = conv(H temp, h100); G(4,:) = H(4, :);
H \text{ temp} = \text{conv}(h1, h00);
H(5,:) = conv(H temp, h000); G(5,:) = -H(5,:);
H(6,:) = conv(H temp, h100); G(6,:) = H(6,:);
H \text{ temp} = \text{conv}(h1, h10);
H(7,:) = conv(H temp, h000); G(7,:) = H(7, :);
H(8,:) = conv(H temp, h100); G(8,:) = -H(8,:);
% i) All corresponding DTFT's H m(w)
h m(1,:) = abs(fftshift(fft(H(1,:),512)));
h m(2,:) = abs(fftshift(fft(H(2,:),512)));
h m(3,:) = abs(fftshift(fft(H(3,:),512)));
h m(4,:) = abs(fftshift(fft(H(4,:),512)));
h m(5,:) = abs(fftshift(fft(H(5,:),512)));
h m(6,:) = abs(fftshift(fft(H(6,:),512)));
h m(7,:) = abs(fftshift(fft(H(7,:),512)));
h m(8,:) = abs(fftshift(fft(H(8,:),512)));
domega = 2 * pi / 512;
omega = -pi:domega:pi-domega;
```

```
figure(1) %Figure 1(a)
plot(omega, h m(1,:), ...
     omega, h_m(2,:), ...
     omega, h m(3,:), ...
     omega, h m(4,:), ...
     omega, h_m(5,:), ...
     omega, h_m(6,:), ...
     omega, h m(7,:), ...
     omega, h m(8,:));
axis([-pi pi 0 3]);
title('Figura 1(a): All corresponding DTFT''s H m(\omega)')
ylabel('H m(\omega)');
xlabel('Omega, \omega (rad/sec)');
legend('H 1(\omega)', 'H 2(\omega)', ...
       'H_3(\omega)', 'H_4(\omega)', ...
'H_5(\omega)', 'H_6(\omega)', ...
       'H 7 (\omega)', 'H 8 (\omega)');
grid on
%ii) 8x8 matrix HH^H
table1 = H*H';
table1 = round(table1)
%iii) DTFT of the Gaussian random process input signal
x = randn(1, 128);
for m = 1:M
    W(m,:) = conv(x, H(m,:));
    X(m,:) = W(m,1:M:length(W(m,:)));
end
for m = 1:M
    Z(m,:) = zeros(1,M*length(X(m,:)));
    Z(m, 1:M:length(Z(m,:))) = X(m,:);
    Y(m,:) = conv(Z(m,:),G(m,:));
end
y = zeros(1, length(Y(1,:)));
for m = 1:M
    y = y+Y(m,:);
end
domega = 2*pi/1024;
omega = -pi:domega:pi-domega;
yf1 = abs(fftshift(fft(x,1024)));
yf2 = abs(fftshift(fft(y,1024)));
figure(2) %Figure 1(b)
plot(omega, yf1)
axis([-pi pi 0 max(yf1)])
xlabel('Omega, \omega (rad/sec)');
ylabel('Magnitude of DTFT')
title('Figure 1(b): DTFT of Gaussian random process input signal')
grid on
```

```
%iv) DTFT of the corresponding output of the filter
figure(3) %Figure 1(c)
plot(omega, yf2, 'r')
axis([-pi pi 0 max(yf2)])
xlabel('Omega, \omega (rad/sec)');
ylabel('Magnitude of DTFT')
title('Figure 1(c): DTFT of the Gaussian random process output')
grid on
 % B) h 0 = h ,, h 1 = (-1)^n * h 0 ,, beta = 0.35
N = 16;
beta = 0.35;
n = -N: (N-1);
n = n+0.5;
h = 2 * beta * cos((1+beta)*pi*n/2)./(pi*(1-4*beta^2*n.^2));
h = h + \sin((1-beta)*pi*n/2)./(pi*(n-4*beta^2*n.^3));
h = h * sqrt(2);
h0 = h;
h1 = (-1).^{(0:(length(n)-1)).*h};
h00 = zeros(1, 2*length(h));
h10 = h00;
h00(1,1:2:length(h00)) = h0;
h10(1,1:2:length(h10)) = h1;
h000 = zeros(1, 4*length(h));
h100 = h000;
h000(1,1:4:length(h000)) = h0;
h100(1,1:4:length(h100)) = h1;
H \text{ tempB} = \text{conv}(h0, h00);
H_B(1,:) = conv(H_tempB, h000); G_B(1,:) = H_B(1,:);
H B(2,:) = conv(H tempB, h100); G B(2,:) = -H B(2,:);
H \text{ tempB} = \text{conv}(h0, h10);
H B(3,:) = conv(H tempB, h000); G B(3,:) = -H B(3,:);
H B(4,:) = conv(H tempB, h100); G B(4,:) = H B(4,:);
H \text{ tempB} = \text{conv}(h1, h00);
H_B(5,:) = conv(H_tempB, h000); G B(5,:) = -H B(5, :);
H B(6,:) = conv(H tempB, h100); G B(6,:) = H B(6,:);
H \text{ tempB} = \text{conv}(h1, h10);
H B(7,:) = conv(H tempB, h000); G B(7,:) = H B(7,:);
H B(8,:) = conv(H tempB, h100); G B(8,:) = -H B(8,:);
% i) All corresponding DTFT's h mB(w)
h mB(1,:) = abs(fftshift(fft(H B(1,:),512)));
h mB(2,:) = abs(fftshift(fft(H_B(2,:),512)));
h mB(3,:)=abs(fftshift(fft(H B(3,:),512)));
h mB(4,:) = abs(fftshift(fft(H B(4,:),512)));
h mB(5,:) = abs(fftshift(fft(H B(5,:),512)));
h mB(6,:)=abs(fftshift(fft(H B(6,:),512)));
h mB(7,:)=abs(fftshift(fft(H B(7,:),512)));
h mB(8,:)=abs(fftshift(fft(H B(8,:),512)));
domega_B = 2 * pi / 512;
omega B = -pi:domega B:pi-domega B;
```

```
figure (4) %Figure 2(a)
plot(omega B, h mB(1,:), ...
     omega B, h mB(2,:), ...
     omega B, h mB(3,:), \dots
     omega_B, h_mB(4,:), ...
     omega B, h mB(5,:), ...
     omega B, h mB(6,:), ...
     omega B, h mB(7,:), ...
     omega B, h mB(8,:));
axis([-pi pi 0 3]);
title('Figura 2(a): All corresponding DTFT''s h m(\omega)')
ylabel('h m(\omega)');
xlabel('omega, \omega (rad/sec)');
legend('H_1(\omega)', 'H_2(\omega)', ...
       'H_3(\omega)', 'H_4(\omega)', ...
       'H_5(\omega)', 'H_6(\omega)', ...
       'H 7 (\omega)', 'H 8 (\omega)');
grid on
%ii) 8x8 matrix HH^H
table2 = H B*H B'
%iii) DTFT of the Gaussian random process input signal
for m = 1:M
    W B(m, :) = conv(x, H B(m, :));
    X B(m,:) = W B(m,1:M:length(W B(m,:)));
end
for m = 1:M
    Z B(m,:) = zeros(1, M*length(X B(m,:)));
    Z B(m,1:M:length(Z B(m,:))) = X B(m,:);
    Y_B(m,:) = conv(Z_B(m,:),G_B(m,:));
end
y B = zeros(1, length(Y B(1,:)));
for m = 1:M
    y_B = y_B + Y B(m,:);
end
domega B = 2*pi/1024;
omega B = -pi:domega B:pi-domega B;
yf1 B = abs(fftshift(fft(x, 1024)));
yf2 B = M*abs(fftshift(fft(y B, 1024)));
figure(5);
plot(omega B,yf1 B)
axis([-pi pi 0 max(yf1 B)])
xlabel('Omega, \omega (rad/sec)');
ylabel('Magnitude of DTFT')
title('Figure 2(b): DTFT of Gaussian random process input signal')
grid on
%iv) DTFT of the corresponding output of the filter
figure(6);
plot(omega B,yf2 B)
axis([-pi pi 0 max(yf2 B)])
xlabel('Omega, \omega (rad/sec)');
ylabel('Magnitude of DTFT')
title('Figure 2(c): DTFT of the Gaussian random process output')
grid on
```

```
% C) h = h, h = (-1)^n * h = 0, beta = 0.1
N = 24;
beta = 0.1;
n = -N: (N-1);
n = n+0.5;
h = 2 * beta * cos((1+beta)*pi*n/2)./(pi*(1-4*beta^2*n.^2));
h = h + \sin((1-beta)*pi*n/2)./(pi*(n-4*beta^2*n.^3));
h = h * sqrt(2);
h0 = h;
h1 = (-1).^{(0:(length(n)-1)).*h;}
h00 = zeros(1, 2*length(h));
h10 = h00;
h00(1,1:2:length(h00)) = h0;
h10(1,1:2:length(h10)) = h1;
h000 = zeros(1,4*length(h));
h100 = h000;
h000(1,1:4:length(h000)) = h0;
h100(1,1:4:length(h100)) = h1;
H \text{ tempB} = \text{conv}(h0, h00);
H C(1,:) = conv(H tempB, h000); G C(1,:) = H C(1,:);
H_C(2,:) = conv(H_tempB, h100); G_C(2,:) = -H_C(2,:);
H \text{ tempB} = \text{conv}(h0, h10);
H C(3,:) = conv(H tempB, h000); G C(3,:) = -H C(3,:);
H C(4,:) = conv(H tempB, h100); G C(4,:) = H C(4,:);
H \text{ tempB} = \text{conv}(h1, h00);
H_{C}(5,:) = conv(H_{tempB}, h000); G_{C}(5,:) = -H_{C}(5, :);
H_C(6,:) = conv(H_tempB, h100); G_C(6,:) = H_C(6,:);
H \text{ tempB} = \text{conv}(h1, h10);
H C(7,:) = conv(H tempB, h000); G C(7,:) = H C(7,:);
H C(8,:) = conv(H tempB, h100); G C(8,:) = -H C(8,:);
% i) All corresponding DTFT's h mB(w)
h mB(1,:) = abs(fftshift(fft(H C(1,:),512)));
h mB(2,:) = abs(fftshift(fft(H C(2,:),512)));
h mB(3,:)=abs(fftshift(fft(H C(3,:),512)));
h_mB(4,:) = abs(fftshift(fft(H_C(4,:),512)));
h mB(5,:)=abs(fftshift(fft(H C(5,:),512)));
h mB(6,:) = abs(fftshift(fft(H C(6,:),512)));
h mB(7,:)=abs(fftshift(fft(H C(7,:),512)));
h mB(8,:) = abs(fftshift(fft(H C(8,:),512)));
domega C = 2 * pi / 512;
omega C = -pi:domega C:pi-domega C;
figure(7) %Figure 3(a)
plot(omega C, h mB(1,:), ...
     omega C, h mB(2,:), ...
     omega C, h mB(3,:), ...
     omega C, h_mB(4,:), ...
     omega_C, h_mB(5,:), ...
     omega_C, h_mB(6,:), ...
     omega_C, h_mB(7,:), ...
     omega C, h mB(8,:));
```

```
axis([-pi pi 0 3]);
title('Figura 3(a): All corresponding DTFT''s h m(\omega)')
ylabel('h m(\omega)');
xlabel('omega, \omega (rad/sec)');
legend('H_1(\omega)', 'H_2(\omega)', ...
       'H_3(\omega)', 'H_4(\omega)', ...
       'H_5(\omega)', 'H_6(\omega)', ...
       'H 7 (\omega)', 'H 8 (\omega)');
grid on
%ii) 8x8 matrix HH^H
table3 = H C*H C'
%iii) DTFT of the Gaussian random process input signal
for m = 1:M
    W C(m,:) = conv(x, H C(m,:));
    X C(m,:) = W C(m,1:M:length(W C(m,:)));
end
for m = 1:M
    Z C(m,:) = zeros(1,M*length(X C(m,:)));
    Z C(m,1:M:length(Z C(m,:))) = X C(m,:);
    Y_C(m,:) = conv(Z_C(m,:),G_C(m,:));
end
y C = zeros(1, length(Y C(1,:)));
for m = 1:M
    y_C = y_C + Y_C(m,:);
end
domega C = 2*pi/1024;
omega C = -pi:domega C:pi-domega C;
yf1 C = abs(fftshift(fft(x,1024)));
yf2 C = M*abs(fftshift(fft(y C, 1024)));
figure(8);
plot(omega C,yf1 C)
axis([-pi pi 0 max(yf1 C)])
xlabel('Omega, \omega (rad/sec)');
ylabel('Magnitude of DTFT')
title('Figure 3(b): DTFT of Gaussian random process input signal')
grid on
%iv) DTFT of the corresponding output of the filter
figure(9);
plot(omega C,yf2 C)
axis([-pi pi 0 max(yf2 C)])
xlabel('Omega, \omega (rad/sec)');
ylabel('Magnitude of DTFT')
title('Figure 3(c): DTFT of the Gaussian random process output')
grid on
```