

T-invariant and T-cyclic subspace

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Theorem 1. *Let \mathbf{T} be a linear operator on a finite-dimensional vector space \mathbf{V} such that the characteristic polynomial of \mathbf{T} splits. Let $\lambda_1, \lambda_2, \dots, \lambda_k$ be the distinct eigenvalues of \mathbf{T} . Then,*

- (1). *\mathbf{T} is diagonalizable if and only if the multiplicity of λ_i is equal to $\dim(\mathbf{E}_{\lambda_i})$ for all i*
- (2). *If \mathbf{T} is diagonalizable and β_i is an ordered basis for \mathbf{E}_{λ_i} , for each i , then $\beta = \beta_1 \cup \dots \cup \beta_k$ is an ordered basis for \mathbf{V} consisting of eigenvectors of \mathbf{T}*

Note. $[\mathbf{T}]_\beta = \begin{pmatrix} \lambda_1 I_{n_1} & & & 0 \\ & \lambda_2 I_{n_2} & & \\ & & \ddots & \\ 0 & & & \lambda_k I_{n_k} \end{pmatrix} : \text{block diagonal matrix}$

Definition 2. $\mathbf{T} : \mathbf{V} \longrightarrow \mathbf{V}$ is linear operator and $\mathbf{W} \leq \mathbf{V}$. If $\mathbf{T}\mathbf{W} \subseteq \mathbf{W}$, then \mathbf{W} is called *T-invariant subspace*. $\mathbf{0}, \mathbf{V}$, and \mathbf{E}_λ are examples of it.

Lemma 3. $M := \begin{pmatrix} A & B \\ 0 & C \end{pmatrix}$, $\det M = \det A \det C$

Proof. 1. if $\det A = 0$

Then there are some linearly dependent column vectors in A , so $\det M = \det A \det C = 0$

2. if $\det A \neq 0$

$$\det \begin{pmatrix} A & B \\ 0 & C \end{pmatrix} = \det \begin{pmatrix} A & 0 \\ 0 & I_m \end{pmatrix} \det \begin{pmatrix} I_n & A^{-1}B \\ 0 & C \end{pmatrix} = \det A \det C$$

□

Note. $\mathbf{v} = \mathbf{W}_1 \oplus \dots \oplus \mathbf{W}_k$, $\mathbf{T} : \mathbf{V} \longrightarrow \mathbf{V}$, and β_i is a basis for \mathbf{W}_i . Then $\beta = \beta_1 \uplus \dots \uplus \beta_k$ is a basis for \mathbf{V} . But $[\mathbf{T}]_\beta$ is not a block matrix because $\mathbf{T}(\beta_i) \not\subseteq \mathbf{W}_i$. But if \mathbf{W}_1 is T-invariant, then $[\mathbf{T}]_\beta = \begin{pmatrix} [\mathbf{T}|_{\mathbf{W}_1}] & B_1 \\ 0 & C \end{pmatrix}$

Moreover if \mathbf{W}_i is T-invariant for all i then, $[\mathbf{T}]_\beta = \begin{pmatrix} [\mathbf{T}|_{\mathbf{W}_1}] & 0 \\ 0 & [\mathbf{T}|_{\mathbf{W}_2}] \\ \vdots & \vdots \\ 0 & [\mathbf{T}|_{\mathbf{W}_k}] \end{pmatrix}$

and by Lemma 3. $\phi_{\mathbf{T}}(t) = \phi_{\mathbf{T}_1}(t) \times \dots \times \phi_{\mathbf{T}_k}(t)$; where $\mathbf{T}_i := \mathbf{T}|_{\mathbf{W}_i}$

Definition 4. $\mathbf{T} : \mathbf{V} \longrightarrow \mathbf{V}$ linear. $\text{span}\{\mathbf{v}, \mathbf{T}\mathbf{v}, \mathbf{T}^2\mathbf{v}, \dots\}$ is *T-cyclic subspace* of $\mathbf{v} \in \mathbf{V}$

Note. *T-cyclic subspace* of $\mathbf{v} \in \mathbf{V}$ is the smallest T-invariant of \mathbf{V} containing \mathbf{v} .

Proof. 1. T -invariant.

$$W := \text{span}\{\mathbf{v}, T\mathbf{v}, T^2\mathbf{v}, \dots\} \text{ and } \mathbf{w} = \sum_{i=0}^{\infty} a_i T^i \mathbf{v} \in W$$

$$T\mathbf{w} = \sum_{i=0}^{\infty} a_i T^{i+1} \mathbf{v} \in W$$

$\therefore W$ is T -invariant.

2. Let U be any T -invariant subspace of V containing \mathbf{v} . Since U is T -invariant and $\mathbf{v} \in V$, $T\mathbf{v} \in U$. Repeatedly $T^k \mathbf{v} \in U$ for all k . Thus $\{\mathbf{v}, T\mathbf{v}, T^2\mathbf{v}, \dots\} \subset U \therefore \text{span}\{\mathbf{v}, T\mathbf{v}, T^2\mathbf{v}, \dots\} \leq U$

□

Theorem 5. W is T -cyclic subspace of V generated by a nonzero vector $\mathbf{v} \in V$ and $\dim W = k$

1. $\{\mathbf{v}, T\mathbf{v}, \dots, T^{k-1}\mathbf{v}\}$ is a basis for W

$$2. a_0 \mathbf{v} + a_1 T\mathbf{v} + \dots + a_{k-1} T^{k-1} \mathbf{v} + a_k T^k \mathbf{v} = 0 \implies \phi_{T|_W}(t) = t^k + a_{k-1} t^{k-1} + \dots + a_1 t + a_0$$

Proof. 1. Let l be the largest integer such that $\beta := \{\mathbf{v}, T\mathbf{v}, \dots, T^{l-1}\mathbf{v}\}$ is linearly independent.

Let $Z := \text{span}\beta$. Then β is a basis for Z . Since β is linearly independent set and $\beta \cup \{T^i \mathbf{v}\}$ is linearly dependent, $T^i \mathbf{v} \in \text{span}\beta$ for $i = l, l+1, \dots$. So, $T^l \mathbf{v} \in Z$. Note that Z is T -invariant because of the following reason.

$$\mathbf{w} = b_0 \mathbf{v} + b_1 T\mathbf{v} + \dots + b_{l-1} T^{l-1} \mathbf{v} \in Z$$

$$T\mathbf{w} = b_0 T\mathbf{v} + b_1 T^2 \mathbf{v} + \dots + b_{l-2} T^{l-1} \mathbf{v} + b_{l-1} T^l \mathbf{v} \in Z$$

Moreover Z is T -invariant subspace containing \mathbf{v} and W is the smallest T -invariant subspace containing \mathbf{v} , $W \leq Z$ which implies that $k \leq l$. But $\dim W = k$ and $l \leq k$, thus $k = l$

$\therefore \beta$ is linearly independent subset of W .

Since β is linearly independent and $\beta \cup \{T^i \mathbf{v}\}$ is linearly dependent $\implies T^i \mathbf{v} \in \text{span}\beta$ for $i \geq k$.

$\therefore \beta$ is a basis for W

$$2. [T|_W]_{\beta} = \begin{pmatrix} 0 & 0 & \cdots & 0 & -a_0 \\ 1 & 0 & \cdots & 0 & -a_1 \\ 0 & 1 & \cdots & 0 & -a_2 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \cdots & 1 & -a_{k-1} \end{pmatrix} \text{ and } \phi_{[T|_W]_{\beta}}(t) = \det \begin{pmatrix} t & 0 & \cdots & 0 & a_0 \\ -1 & t & \cdots & 0 & a_1 \\ 0 & -1 & \cdots & 0 & a_2 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \cdots & -1 & t + a_{k-1} \end{pmatrix}$$

$$\begin{aligned}
\text{Put } b_i &:= \det \begin{pmatrix} t & 0 & \cdots & 0 & a_i \\ -1 & t & \cdots & 0 & a_{i+1} \\ 0 & -1 & \cdots & 0 & a_{i+2} \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \cdots & -1 & t + a_{k-1} \end{pmatrix}_{(k-i) \times (k-i)} \\
b_0 &= \begin{pmatrix} t & 0 & \cdots & 0 & a_0 \\ -1 & t & \cdots & 0 & a_1 \\ 0 & -1 & \cdots & 0 & a_2 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \cdots & -1 & t + a_{k-1} \end{pmatrix} \\
b_0 &= t \det \begin{pmatrix} t & 0 & \cdots & 0 & a_1 \\ -1 & t & \cdots & 0 & a_2 \\ 0 & -1 & \cdots & 0 & a_3 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \cdots & -1 & t + a_{k-1} \end{pmatrix} + (-1)^{k+1} a_0 \det \begin{pmatrix} -1 & t & \cdots & 0 \\ 0 & -1 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & -1 \end{pmatrix} \\
b_0 &= tb_1 + (-1)^{k+1+k-1} a_0 \\
b_0 &= tb_1 + a_0 \\
b_1 &= tb_2 + a_1 \\
&\vdots \\
b_{k-2} &= tb_{k-1} + a_{k-2} \\
b_{k-1} &= t + a_{k-1} \\
b_0 &= t^k + a_{k-1}t^{k-1} + \cdots + a_1t + a_0
\end{aligned}$$

$$\therefore \phi_{[T]_{\mathcal{W}}}(t) = t^k + a_{k-1}t^{k-1} + \cdots + a_1t + a_0$$

□

Theorem 6. If $F = \mathbb{C}$ and $T \in \mathcal{L}(V, V)$, then $\exists \mathfrak{B}$ such that \mathfrak{B} is a basis for V and $[T]_{\mathfrak{B}}$ is upper-triangular matrix.

Proof. Induction on matrix size n . Since (1×1) matrix is upper-triangular matrix, let's assume $n \geq 2$. Since $F = \mathbb{C}$, $\exists \mathbf{v}_1$ such that $T\mathbf{v}_1 = \lambda\mathbf{v}_1$. Construct a basis $\mathfrak{C} = \{\mathbf{v}_1, \dots, \mathbf{v}_n\}$ by Basis Extension Theorem. Then $[T]_{\mathfrak{C}} = \left(\begin{array}{c|c} \lambda & * \\ \hline 0 & B \end{array} \right)$, where $B \in \mathfrak{M}_{n-1, n-1}(\mathbb{C})$. By Induction hypothesis, $\exists P \in \mathfrak{M}_{n-1, n-1}(\mathbb{C})$

such that $p^{-1}BP$ is upper-triangular matrix. Put $U := \left(\begin{array}{c|c} 1 & 0 \\ \hline 0 & P \end{array} \right)$.

Since, $U^{-1} = \left(\begin{array}{c|c} 1 & 0 \\ \hline 0 & P^{-1} \end{array} \right)$, $[T]_{\mathfrak{C}} \sim U^{-1} \left(\begin{array}{c|c} \lambda & * \\ \hline 0 & B \end{array} \right) U = \left(\begin{array}{c|c} 1 & 0 \\ \hline 0 & P^{-1} \end{array} \right) \left(\begin{array}{c|c} \lambda & * \\ \hline 0 & B \end{array} \right) \left(\begin{array}{c|c} 1 & 0 \\ \hline 0 & P \end{array} \right) = \left(\begin{array}{c|c} \lambda & * \\ \hline 0 & P^{-1}BP \end{array} \right)$
 Since $P^{-1}BP$ is upper-triangular matrix, $[T]_{\mathfrak{C}}$ is similar to upper-triangular matrix. □

Example 1. Let $A \in \mathbf{M}_{n \times n}(\mathbb{R})$ be the matrix defined by $A_{ij} = 1$ for all i and j . Find the characteristic polynomial of A . $\phi_A(t) = t^{n-1}(t - n)$

Proof. Since, $\text{rank} A = 1$, $\dim(\ker A) = n-1$, which implies that $\exists \mathbf{x}$ such that $A\mathbf{x} = 0\mathbf{x}$ and $\mathbf{x} \neq 0$. Thus $\dim E_0 = n-1$. Since multiplicity of eigenvalue 0 is greater than or equal to $n-1$, $\phi_A(t) = t^{n-1}(t - \lambda)$. Since there exists at least eigenvalue, which is 0, of A , A is similar to upper triangular matrix U by Theorem 6. Since U is upper-triangular matrix and $\text{trace } A = \text{trace } U = n$, $-(\lambda + 0) = -n$.

$$U = \begin{pmatrix} 0 & & & \\ & 0 & & * \\ & & \ddots & \\ & \mathbf{0} & & \ddots \\ & & & & \lambda \end{pmatrix}$$

$$\therefore \phi_A(t) = \phi_U(t) = t^{n-1}(t - n)$$

□