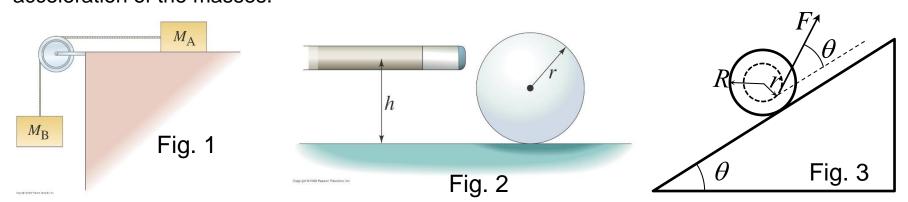
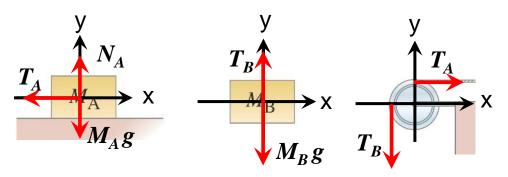
## Homework 9 (Chap 10-11)

1. Fig. 1 shows two masses connected by a cord passing over a pulley of radius  $R_0$  and moment of inertia I. Mass  $M_A$  slides on a frictionless surface, and  $M_B$  hangs freely. Determine the acceleration of the masses.



- 2. In Fig. 2, if a billiard ball is hit in just the right way by a cue stick, the ball will roll without slipping immediately after losing contact with the stick. Consider a billiard ball (radius r, mass M) at rest on a horizontal pool table. A cue stick exerts a constant horizontal force F on the ball for a time t at a point that is a height h above the table's surface (see the figure below). Assume that the coefficients of kinetic friction and the static friction between the ball and table are  $\mu_k$  and  $\mu_s$ , respectively. Determine the range for h so that the ball will roll without slipping immediately after losing contact with the stick.
- 3. As shown in Fig. 3, on an inclined surface, a dumbbell with outer diameter R and inner diameter r (r = 3/5R) is pulled by a force F with a string winded around its inner post. Give that the inclined angle of the surface  $\theta = 37^{\circ}$ , m the mass of the dumbbell, the moment of inertia of the dumbbell  $I_c = 4/5 \ mR^2$ , the static friction coefficient  $\mu_s = 3/5$ . For a given magnitude of force F that makes the dumbbell to execute pure roll motion, draw the free-body diagram and determine the direction and magnitude of the acceleration of the dumbbell, and the friction force.

1. Fig. 1 shows two masses connected by a cord passing over a pulley of radius  $R_0$  and moment of inertia I. Mass  $M_A$  slides on a frictionless surface, and  $M_B$  hangs freely. Determine the acceleration of the masses.



From the freebody diagram of  $M_A$ , we have

$$\vec{T}_A + \vec{N}_A + \vec{M}_A g = M_A \vec{a}_A$$

$$\Rightarrow x: -T_A = M_A a_A \quad (1)$$

$$y: N_A - M_A g = 0 \quad (2)$$

From the freebody diagram of M<sub>B</sub>, we have

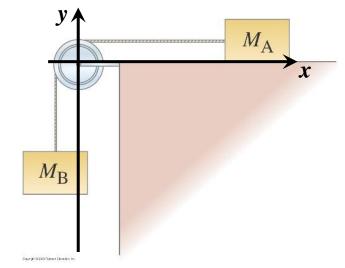
$$\vec{T}_B + \vec{M}_B g = M_B \vec{a}_B \quad (3)$$

$$\Rightarrow y: T_B - M_B g = M_B a_B$$
 (4)

From the freebody diagram of the pulley, we have

$$\vec{R}_0 \times \vec{T}_A + \vec{R}_0 \times \vec{T}_B = I\vec{\alpha}$$

$$\Rightarrow -R_0 T_A + R_0 T_B = I\alpha \quad (5)$$



The physical relation between  $a_A$ ,  $a_B$ , and  $\alpha$  is (for  $\alpha$ , the positive direction is counter clockwise)

$$a_A = a_B = -R_0 \alpha \equiv a$$
 (6)

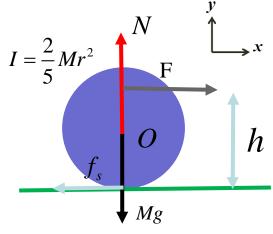
From (1),(4),(5), and (6) we get

$$\Rightarrow R_0 M_A a + R_0 (M_B g + M_B a) = -I \frac{a}{R_0}$$

$$\Rightarrow a = \frac{-M_B g}{M_A + M_B + I/R_0^2}$$

## Problem 1 (solution 1, +torque for rollin to the same direction as a)

If a billiard ball is hit in just the right way by a cue stick, the ball will roll without slipping immediately after losing contact with the stick. Consider a billiard ball (radius r, mass M) at rest on a horizontal pool table. A cue stick exerts a constant horizontal force F on the ball for a time t at a point that is a height h above the table's surface (see the figure below). Assume that the coefficients of kinetic friction and the static friction between the ball and table are  $\mu_k$  and  $\mu_s$ , respectively. Determine the range for h so that the ball will roll without slipping immediately after losing contact with the stick.



$$\sum \vec{F} = M\vec{a}$$

$$\sum \vec{\tau} = \vec{r} \times \vec{F} = I\vec{\alpha}$$

$$\sum F_x = F - f_s = Ma$$

$$\sum F_y = N - Mg = 0$$

$$\sum \tau = F(h - r) + f_s \cdot r = I\alpha$$

Roll without slipping  $\rightarrow a = r\alpha$ 

$$\frac{F - f_s}{M} = r \frac{F(h - r) + f_s \cdot r}{I}$$

$$\frac{2}{5} Mr^2 (F - f_s) = Mr \left[ F(h - r) + f_s \cdot r \right]$$

$$\Rightarrow \frac{2}{5}r(F-f_s) = \left[F(h-r) + f_s \cdot r\right]$$

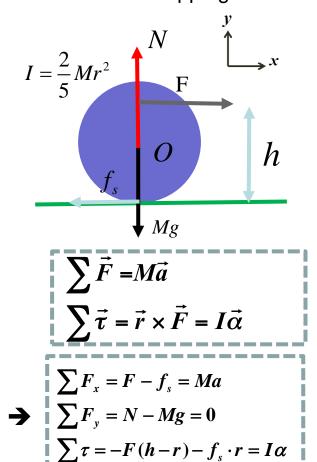
$$-\frac{7}{5}rf_s = F(h - \frac{7}{5}r)$$

$$\Rightarrow \frac{7}{5}(1 + \frac{Mg}{F}\mu_s) \ge \frac{h}{r} \ge \frac{7}{5}(1 - \frac{Mg}{F}\mu_s)$$

+ torque for rolling to the same direction as *a* 

## <u>Problem 1(solution 2, direction of torque and the angular acceleration follows the coordinate system of the free body diagram)</u>

If a billiard ball is hit in just the right way by a cue stick, the ball will roll without slipping immediately after losing contact with the stick. Consider a billiard ball (radius r, mass M) at rest on a horizontal pool table. A cue stick exerts a constant horizontal force F on the ball for a time t at a point that is a height h above the table's surface (see the figure below). Assume that the coefficients of kinetic friction and the static friction between the ball and table are  $\mu_k$  and  $\mu_s$ , respectively. Determine the range for h so that the ball will roll without slipping immediately after losing contact with the stick.



Roll without slipping 
$$\Rightarrow \alpha = r\alpha$$

$$a = \frac{F - f_s}{M}, \quad \alpha = -\frac{F(h - r) + f_s \cdot r}{I}$$

$$\Rightarrow \frac{F - f_s}{M} = r \frac{F(h - r) + f_s \cdot r}{I}$$

$$\Rightarrow \frac{2}{5}Mr^2(F - f_s) = Mr[F(h - r) + f_s \cdot r]$$

$$\Rightarrow \frac{2}{5}r(F - f_s) = [F(h - r) + f_s \cdot r]$$

$$\Rightarrow -\frac{7}{5}rf_s = F(h - \frac{7}{5}r)$$

$$\Rightarrow f_s = F(1 - \frac{5}{7r}h) \qquad (|f_s| \le Mg\mu_s)$$

$$\Rightarrow \frac{7}{5}(1 + \frac{Mg}{F}\mu_s) \ge \frac{h}{r} \ge \frac{7}{5}(1 - \frac{Mg}{F}\mu_s)$$

2.As shown in Fig. x, on a inclined surface, a dumbbell with outer diameter  $\mathbf{R}$  and inner diameter  $\mathbf{r}$  ( $\mathbf{r} = 3/5\mathbf{R}$ ) is pulled by a force  $\mathbf{F}$  with a string winded around its inner post. Give that the inclined angle of the surface  $\theta = 37^{\circ}$ ,  $\mathbf{m}$  the mass of the dumbbell, the moment of inertia of the dumbbell  $I_c = 4/5$   $\mathbf{m}\mathbf{R}^2$ , the static friction coefficient  $\mu_s = 3/5$ . For a given magnitude of force  $\mathbf{F}$  that makes the dumbbell to execute pure roll motion, draw the free-body diagram and determine the direction and magnitude of the acceleration of the dumbbell, and the friction force. ( $\sin 37^{\circ} = 3/5$ )

$$\sum \vec{F} = m\vec{a}$$
X:  $F\cos\theta - mg\sin\theta - f = ma$  (1)

y: 
$$F \sin \theta + N - mg \cos \theta = 0$$
 (2) 
$$\sum \vec{\tau} = I \vec{\alpha}$$

$$\sum \vec{\tau} = I\vec{\alpha}$$

$$\vec{r} \times \vec{F} + \vec{R} \times \vec{f} = I\vec{\alpha}$$
z:  $rF - Rf = I\alpha$  (3)

For pure roll,  $a = -R\alpha$  (4)

(1) 
$$\Rightarrow \frac{4}{5}F - \frac{3}{5}mg - f = ma$$
 (5)  
(3),(4)  $\Rightarrow \frac{3}{5}RF - Rf = \frac{4}{5}mR^2\alpha$   
 $\Rightarrow \frac{3}{5}F - f = -\frac{4}{5}ma$  (6)  
(5),(6)  $\Rightarrow \frac{1}{5}F - \frac{3}{5}mg = \frac{9}{5}ma$   
 $\Rightarrow a = \frac{F}{9m} - \frac{g}{3}$ , in x-direction,(7)  
(6),(7)  $\Rightarrow f = \frac{3}{5}F + \frac{4}{5}ma$   
 $\Rightarrow f = \frac{3}{5}F + \frac{4}{5}m\left(\frac{F}{9m} - \frac{g}{3}\right)$   
 $\Rightarrow f = \frac{31}{45}F - \frac{4}{15}mg$  (8)