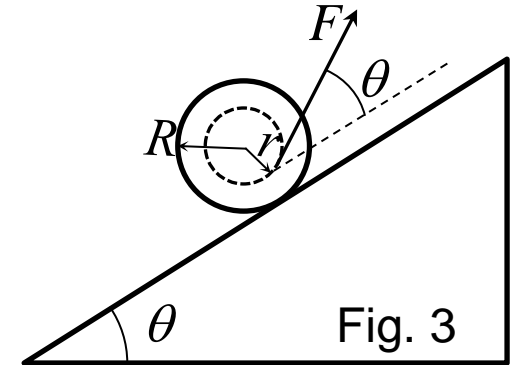
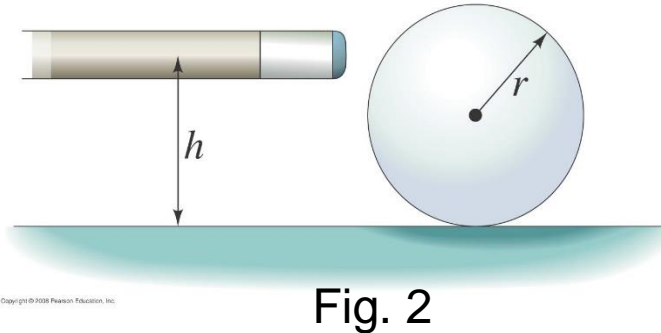
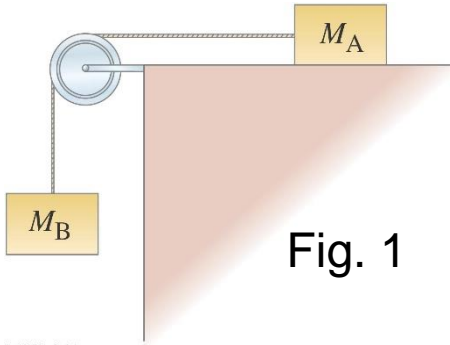


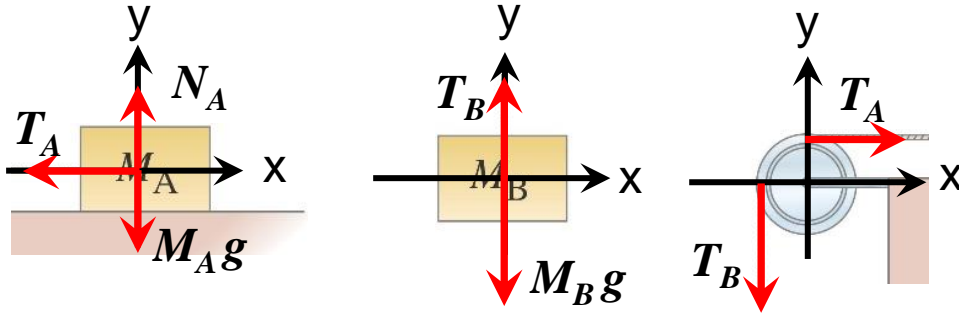
## Homework 9 (Chap 10-11)

1. Fig. 1 shows two masses connected by a cord passing over a pulley of radius  $R_0$  and moment of inertia  $I$ . Mass  $M_A$  slides on a frictionless surface, and  $M_B$  hangs freely. Determine the acceleration of the masses.



2. In Fig. 2, if a billiard ball is hit in just the right way by a cue stick, the ball will roll without slipping immediately after losing contact with the stick. Consider a billiard ball (radius  $r$ , mass  $M$ ) at rest on a horizontal pool table. A cue stick exerts a constant horizontal force  $F$  on the ball for a time  $t$  at a point that is a height  $h$  above the table's surface (see the figure below). Assume that the coefficients of kinetic friction and the static friction between the ball and table are  $\mu_k$  and  $\mu_s$ , respectively. Determine the range for  $h$  so that the ball will roll without slipping immediately after losing contact with the stick.
3. As shown in Fig. 3, on an inclined surface, a dumbbell with outer diameter  $R$  and inner diameter  $r$  ( $r = 3/5 R$ ) is pulled by a force  $F$  with a string wound around its inner post. Give that the inclined angle of the surface  $\theta = 37^\circ$ ,  $m$  the mass of the dumbbell, the moment of inertia of the dumbbell  $I_c = 4/5 m R^2$ , the static friction coefficient  $\mu_s = 3/5$ . For a given magnitude of force  $F$  that makes the dumbbell to execute pure roll motion, draw the free-body diagram and determine the direction and magnitude of the acceleration of the dumbbell, and the friction force.

1. Fig. 1 shows two masses connected by a cord passing over a pulley of radius  $R_0$  and moment of inertia  $I$ . Mass  $M_A$  slides on a frictionless surface, and  $M_B$  hangs freely. Determine the acceleration of the masses.



From the freebody diagram of  $M_A$ , we have

$$\vec{T}_A + \vec{N}_A + \vec{M}_A g = M_A \vec{a}_A$$

$$\Rightarrow x: -T_A = M_A a_A \quad (1)$$

$$y: N_A - M_A g = 0 \quad (2)$$

From the freebody diagram of  $M_B$ , we have

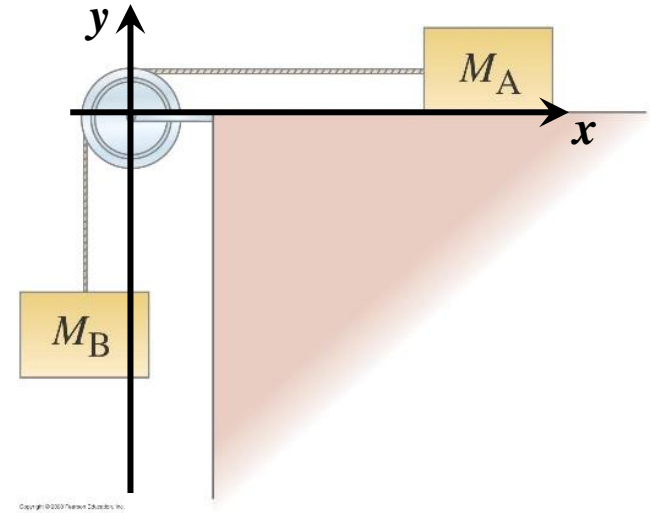
$$\vec{T}_B + \vec{M}_B g = M_B \vec{a}_B \quad (3)$$

$$\Rightarrow y: T_B - M_B g = M_B a_B \quad (4)$$

From the freebody diagram of the pulley, we have

$$\vec{R}_0 \times \vec{T}_A + \vec{R}_0 \times \vec{T}_B = I \vec{\alpha}$$

$$\Rightarrow -R_0 T_A + R_0 T_B = I \alpha \quad (5)$$



The physical relation between  $a_A$ ,  $a_B$ , and  $\alpha$  is (for  $\alpha$ , the positive direction is counter clockwise)

$$a_A = a_B = -R_0 \alpha \equiv a \quad (6)$$

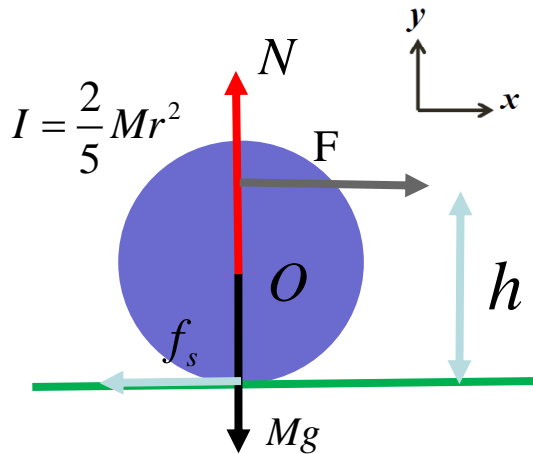
From (1),(4),(5), and (6) we get

$$\Rightarrow R_0 M_A a + R_0 (M_B g + M_B a) = -I \frac{a}{R_0}$$

$$\Rightarrow a = \frac{-M_B g}{M_A + M_B + I/R_0^2}$$

### Problem 1 (solution 1, +torque for rollin to the same direction as $a$ )

If a billiard ball is hit in just the right way by a cue stick, the ball will roll without slipping immediately after losing contact with the stick. Consider a billiard ball (radius  $r$ , mass  $M$ ) at rest on a horizontal pool table. A cue stick exerts a constant horizontal force  $F$  on the ball for a time  $t$  at a point that is a height  $h$  above the table's surface (see the figure below). Assume that the coefficients of kinetic friction and the static friction between the ball and table are  $\mu_k$  and  $\mu_s$ , respectively. Determine the range for  $h$  so that the ball will roll without slipping immediately after losing contact with the stick.



Roll without slipping  $\rightarrow a = r\alpha$

$$\rightarrow \frac{F - f_s}{M} = r \frac{F(h - r) + f_s \cdot r}{I}$$

$$\rightarrow \frac{2}{5} Mr^2 (F - f_s) = Mr [F(h - r) + f_s \cdot r]$$

$$\rightarrow \frac{2}{5} r (F - f_s) = [F(h - r) + f_s \cdot r]$$

$$\rightarrow -\frac{7}{5} r f_s = F(h - \frac{7}{5} r)$$

$$\rightarrow f_s = F(1 - \frac{5}{7} \frac{h}{r}) \quad (|f_s| \leq Mg\mu_s)$$

$$\rightarrow \left[ \frac{7}{5} (1 + \frac{Mg}{F} \mu_s) \geq \frac{h}{r} \geq \frac{7}{5} (1 - \frac{Mg}{F} \mu_s) \right]$$

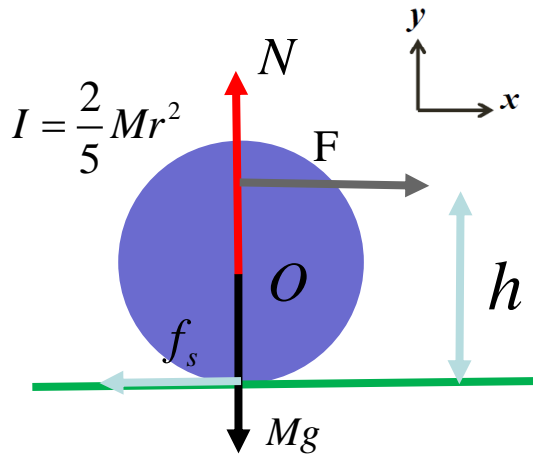
$$\begin{aligned} \sum \vec{F} &= M\vec{a} \\ \sum \vec{\tau} &= \vec{r} \times \vec{F} = I\vec{\alpha} \end{aligned}$$

$$\rightarrow \begin{aligned} \sum F_x &= F - f_s = Ma \\ \sum F_y &= N - Mg = 0 \\ \sum \tau &= F(h - r) + f_s \cdot r = I\alpha \end{aligned}$$

+ torque for rolling to the same direction as  $a$

**Problem 1(solution 2, direction of torque and the angular acceleration follows the coordinate system of the free body diagram)**

If a billiard ball is hit in just the right way by a cue stick, the ball will roll without slipping immediately after losing contact with the stick. Consider a billiard ball (radius  $r$ , mass  $M$ ) at rest on a horizontal pool table. A cue stick exerts a constant horizontal force  $F$  on the ball for a time  $t$  at a point that is a height  $h$  above the table's surface (see the figure below). Assume that the coefficients of kinetic friction and the static friction between the ball and table are  $\mu_k$  and  $\mu_s$ , respectively. Determine the range for  $h$  so that the ball will roll without slipping immediately after losing contact with the stick.



$$\sum \vec{F} = M\vec{a}$$

$$\sum \vec{\tau} = \vec{r} \times \vec{F} = I\vec{\alpha}$$

$$\begin{aligned} \sum F_x &= F - f_s = Ma \\ \sum F_y &= N - Mg = 0 \\ \sum \tau &= -F(h-r) - f_s \cdot r = I\alpha \end{aligned}$$

Roll without slipping  $\rightarrow \mathbf{a} = -r\alpha$

$$a = \frac{F - f_s}{M}, \quad \alpha = -\frac{F(h-r) + f_s \cdot r}{I}$$

$$\rightarrow \frac{F - f_s}{M} = r \frac{F(h-r) + f_s \cdot r}{I}$$

$$\rightarrow \frac{2}{5} Mr^2 (F - f_s) = Mr [F(h-r) + f_s \cdot r]$$

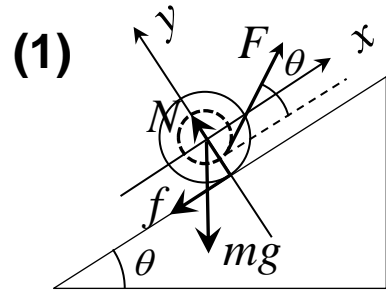
$$\rightarrow \frac{2}{5} r (F - f_s) = [F(h-r) + f_s \cdot r]$$

$$\rightarrow -\frac{7}{5} r f_s = F(h - \frac{7}{5} r)$$

$$\rightarrow f_s = F(1 - \frac{5}{7r} h) \quad (|f_s| \leq Mg\mu_s)$$

$$\rightarrow \frac{7}{5} (1 + \frac{Mg}{F} \mu_s) \geq \frac{h}{r} \geq \frac{7}{5} (1 - \frac{Mg}{F} \mu_s)$$

2. As shown in Fig. x, on a inclined surface, a dumbbell with outer diameter  $R$  and inner diameter  $r$  ( $r = 3/5 R$ ) is pulled by a force  $F$  with a string wound around its inner post. Give that the inclined angle of the surface  $\theta = 37^\circ$ ,  $m$  the mass of the dumbbell, the moment of inertia of the dumbbell  $I_c = 4/5 mR^2$ , the static friction coefficient  $\mu_s = 3/5$ . For a given magnitude of force  $F$  that makes the dumbbell to execute pure roll motion, draw the free-body diagram and determine the direction and magnitude of the acceleration of the dumbbell, and the friction force. ( $\sin 37^\circ = 3/5$ )



$$\sum \vec{F} = m\vec{a}$$

$$x: F \cos \theta - mg \sin \theta - f = ma \quad (1)$$

$$y: F \sin \theta + N - mg \cos \theta = 0 \quad (2)$$

$$\sum \vec{\tau} = I\vec{\alpha}$$

$$\vec{r} \times \vec{F} + \vec{R} \times \vec{f} = I\vec{\alpha}$$

$$z: rF - Rf = I\alpha \quad (3)$$

$$\text{For pure roll, } a = -R\alpha \quad (4)$$

$$(1) \rightarrow \frac{4}{5}F - \frac{3}{5}mg - f = ma \quad (5)$$

$$(3), (4) \rightarrow \frac{3}{5}RF - Rf = \frac{4}{5}mR^2\alpha$$

$$\Rightarrow \frac{3}{5}F - f = -\frac{4}{5}ma \quad (6)$$

$$(5), (6) \rightarrow \frac{1}{5}F - \frac{3}{5}mg = \frac{9}{5}ma$$

$$\Rightarrow a = \frac{F}{9m} - \frac{g}{3}, \text{ in x-direction, (7)}$$

$$(6), (7) \rightarrow f = \frac{3}{5}F + \frac{4}{5}ma$$

$$\Rightarrow f = \frac{3}{5}F + \frac{4}{5}m \left( \frac{F}{9m} - \frac{g}{3} \right)$$

$$\Rightarrow f = \frac{31}{45}F - \frac{4}{15}mg \quad (8)$$