

1) Linear System:
No solution ↔ Last col is pivot col
One solution ↔ All cols except last is pivo
∞ solution ↔ ≥ 1 non – pivot column

parameters ↔ # non – pivot cols in LHS

2) Matrices:
Diagonal Matrix: $A = (a_{ij})_{m \times n} = \begin{cases} = 0 & \text{if } i \neq j \\ \neq 0 & \text{if } i = j \end{cases}$
Triangular Matrix: **Lower:** $\begin{pmatrix} 1 & 0 \\ & 1 \end{pmatrix}$ or **Upper:** $\begin{pmatrix} 1 & \\ 0 & 1 \end{pmatrix}$
Symmetrical Matrix: $\forall i, j, a_{ij} = a_{ji}$ or $A^T = A$

Multiplication of Matrices:
Pre-multiply: $AB = A$ onto B
Post-multiply: $BA = A$ onto B
Formulae: If $A = (a_{ij})_{m \times p}$ and $B = (b_{ij})_{p \times n}$, then $AB = \sum_{k=1}^p a_{ik} b_{ki}$

Matrix Notation:
 $A = \begin{pmatrix} a_{11} \\ a_{21} \\ \vdots \\ a_{n1} \end{pmatrix}$ where a_i is the i^{th} row
 $= (a_{11} \ a_{12} \ \dots \ a_{1p})$
 $B = (b_1 \ b_2 \ \dots \ b_n)$ where b_i is the i^{th} col $= \begin{pmatrix} b_{11} \\ \vdots \\ b_{pi} \end{pmatrix}$

$A(B_1 \ B_2) = (AB_1 \ AB_2); A \begin{pmatrix} B_1 \\ B_2 \end{pmatrix} = \begin{pmatrix} AB_1 \\ AB_2 \end{pmatrix}$

Transpose Matrices:
 $A = (a_{ij})_{m \times n}$ and $A^T = (a_{ji})_{n \times m}$
 $(A^T)^T = A$ and $(A+B)^T = A^T + B^T$ and $(AB)^T = B^T A^T$

Inverse Matrices:
 B is left inverse of A if $BA = I$; B is right inverse of A if $AB = I$
 $AA^{-1} = A^{-1}A = I$; $(cA)^{-1} = \frac{1}{c} A^{-1}$; $(AB)^{-1} = B^{-1}A^{-1}$
 $\det(A) \neq 0$
Singular matrix ↔ 0 row or 0 col → $\det(A) = 0$

Elementary Row Operations:
 $E_k E_{k-1} \dots E_2 E_1 A = B$ and $A = E_1^{-1} E_2^{-1} \dots E_{k-1}^{-1} E_k^{-1} B$
 A and B are row – equivalent ↔ A and B have the same RREF
 $(A \ I) \xrightarrow{\text{Gaussian}} (I \ A)$ refers $A^{-1} = E_k \dots E_2 E_1$; $A = E_1^{-1} \dots E_{k-1}^{-1} E_k^{-1}$

Determinants:
 $\det(A) = \begin{cases} a_{11} & \text{if } N = 1 \\ \sum_{k=1}^N a_{1k} A_{1k} & \text{if } N > 1 \end{cases}$ where
 $A_{ij} = (-1)^{i+j} \det(M_{ij})$ or Δ matrix, $\det(A) = \prod_{i=1}^N a_{ii}$
 $\det(A) = ad - bc \leftrightarrow A$ is 2×2 matrix
 $\det(A) = aei - afh \mp bfg - bdi + cdh - ceg \leftrightarrow A$ is 3×3 matrix

Determinant Formulae:
 $\det(E_{add}) = 1$; $\det(E_{mult}) = c$; $\det(E_{\text{swap}}) = -1$;
 $\det(A^{-1}) = (\det(A))^{-1}$; $\det(cA) = c^n \det(A)$; $\det(AB) = \det(A) * \det(B)$;

Adjoints:
 $\text{adj}(A) = (A_{ij})_{m \times n}^T$; $A \text{ adj}(A) = \det(A) I$; $A^{-1} = (\det(A))^{-1} \text{adj}(A)$

Cramer's Rule:
If A is invertible, $Ax = b \leftrightarrow \frac{1}{\det(A)} \begin{pmatrix} \det(A_1) \\ \vdots \\ \det(A_n) \end{pmatrix}$
where $A_i = (a_1 \ \dots \ a_{i-1} \ b \ a_{i+1} \ \dots \ a_n)$
For example: $x = \frac{\begin{vmatrix} b & a_2 & a_3 \\ a_1 & a_2 & a_3 \end{vmatrix}}{\begin{vmatrix} a_1 & a_2 & a_3 \end{vmatrix}}$, $y = \frac{\begin{vmatrix} a_1 & b & a_3 \\ a_1 & a_2 & a_3 \end{vmatrix}}{\begin{vmatrix} a_1 & a_2 & a_3 \end{vmatrix}}$

3) Vector Spaces:
Vectors:
row vector: $(u_1 \ u_2 \ \dots \ u_n)$; col vector: $\begin{pmatrix} u_1 \\ \vdots \\ u_n \end{pmatrix} = \text{row vector}^T$
Solutions Sets:
Implicit: $\{ (x, y, z) \mid x + y + z = 0 \text{ \& } x - y + 2z = 1 \}$
Explicit: $\left\{ \left(\frac{1}{2} - \frac{3}{2}t, -\frac{1}{2} + \frac{1}{2}t, t \right) \mid t \in \mathbb{R} \right\}$

Linear Spans:
Linear spans ↔ $\{ \sum_{i=1}^m c_i u_i \mid c_1 \dots c_m \in \mathbb{R} \}$
 $\text{span}(k) \leftrightarrow \text{span} \{ u_1, u_2 \dots u_k \}$

Theorem 3.2.10:
Let $S_1 = \{ u_1 \dots u_k \}$ and $S_2 = \{ v_1 \dots v_m \} \subseteq \mathbb{R}^n$
 $\text{span}(S_1) \subseteq \text{span}(S_2) \leftrightarrow \forall v_i \text{ is a l.i.c of } \{ u_1 \dots u_k \}$
 $\leftrightarrow (v_1 \ v_2 \dots v_m \mid u_1 \mid u_2 \dots u_k) \text{ is a consistent linear system}$

Redundant Vectors:
If $u_k = c_1 u_1 + \dots + c_{k-1} u_{k-1}$, u_k is known as a redundant vector

Solution Spaces:
Homogeneous System has trivial sol ↔ solution set is $\{0\}$
Homogeneous System has ∞ sol ↔ solution set is general sol

Subspaces:
 $V \subseteq \mathbb{R}^n$ and V is a subspace ↔ $V = \text{span}(S)$ for some $S \subseteq \mathbb{R}^n$
 $\forall \alpha, \beta \in \mathbb{R}, u, v \in V, \alpha u + \beta v \in V$ and thus, S spans V
 $0 \in V$ given V is non – empty

Linear Independence:
 S is called a l.i set if $\forall u_i$ to $u_k \in \mathbb{R}^n$ s.t. from $c_1 u_1$ to $c_k u_k$, c_1 to $c_k = 0$
If vector set is not l.i, $\exists \geq 1$ redundant vector
If vector set is l.i, $\exists 0$ redundant vectors

Basis:
 V is a vector space ↔ $V = \mathbb{R}^n$ OR V is a subspace of \mathbb{R}^n
 V is a subspace of $W \leftrightarrow V$ is a vector space AND $V \subseteq W$
Let S be a subset of vector space V , S is a basis for V
 $\leftrightarrow S$ is l.i AND $(S \text{ spans } V \text{ OR } V = \text{span}(S))$
If A is invertible:
The rows of A OR The cols of A form a basis for \mathbb{R}^n

Standard Basis:
 $E = \{ e_1, \dots, e_k \}$ is the standard basis for \mathbb{R}^n , $e_1 = \begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix} \dots e_k = \begin{pmatrix} 0 \\ \vdots \\ 1 \end{pmatrix}$

Co-ordinate Systems:
Let $S = \{ u_1, \dots, u_k \}$ be a basis for a vector space V and $v \in V$
 $v = c_1 u_1 + \dots + c_k u_k$ and $(v)_S = (c_1 \ \dots \ c_k) \in \mathbb{R}^k$
 $\forall u, v \in V, u = v \leftrightarrow (u)_S = (v)_S$
 $\forall u, v \in V, c, d \in \mathbb{R} : (cu + dv)_S = c(u)_S + d(v)_S$
 u_1, \dots, u_k are l.i. $\leftrightarrow (u_i)_S \dots (u_k)_S$ are also l.i

Dimensions:
Let $S \subseteq V$,
 $S > k$ vectors: $S \neq \text{l.i.}$ AND $S < k$ vecotrs: $V \neq \text{span}(S)$
 $\dim(V) = \text{of vectors for basis of } V$
 $f U$ is a subspace of vector space V , $\dim(U) \leq \dim(V)$

Theorem 3.6.7:
Let V be a vector space where $\dim(V) = k$, $S \subseteq V$,
 S is a basis for V ; S is l.i. and $|S| = k$; $V = \text{span}(S)$ and $|S| = k$;

Transition Matrices:
 $(v)_S = (c_1 \ \dots \ c_k)$ AND $[v]_S = \begin{bmatrix} c_1 \\ \vdots \\ c_k \end{bmatrix}$
 $P_{S,T}$ is the transition matrix = $([s_1]_T, \dots [s_k]_T)$
 P^T is the transition matrix from T to S
 $[v]_T = P_{S,T} [v]_S$ AND $[v]_S = P_{S,T}^{-1} [v]_T$ where $[v]_T = \begin{pmatrix} v_1 \cdot u_1 \\ \vdots \\ v_1 \cdot u_n \end{pmatrix}$

4) Spaces:
Row Space:
 $\text{row}(A)$ is the subspaces spanned by the rows of A
The non – zero rows of $\text{rref}(A)$ form a basis for $\text{row}(A)$
 A and B are row – equivalent, $\text{row}(A)$ and $\text{row}(B)$ are identical

Col Space:
 $\text{col}(A)$ is the subspace spanned by the cols of A
Pivot cols of $\text{rref}(A)$ form a basis for $\text{col}(A)$
If A and B are row – equivalent,
cols of A that are l.i ↔ corresponding cols of B that are l.i.

Ranks:
 $\text{rank}(A) = \dim(\text{row}(A)) = \dim(\text{col}(A))$
 $\text{rank}(A) = \text{rank}(A^T) = \min\{m, n\}$ if $A = (a_{ij})_{m \times n}$
 $\text{rank}(AB) = \min\{\text{rank}(A), \text{rank}(B)\}$
Square matrices are of full rank where $m = n$
Linear system is consistent ↔ A and $|A/B|$ have same rank

Nullspaces:
Nullspace = Sol space of $Ax = 0$
 $\dim(\text{nullspace}) = \text{nullity}(A) \leq \dim(\mathbb{R}^n) = n$
 $\text{rank}(A) + \text{nullity}(A) = n$

Solution Set:
If v is a sol to $Ax = b$, sol set is $M = \{ u + v \mid u \in \text{nullspace of } A \}$

5) Orthogonality:
Vectors:
 $d(u, v) = \|u - v\|$;
 $\cos(u, v) = \frac{u \cdot v}{\|u\| \|v\|}$;
 $\|u + v\| \leq \|u\| + \|v\|$
If u and v are col vectors, $u \cdot v = u^T v = \text{dot product}$

Orthogonality:
 u and v are orthogonal vectors ↔ $u \cdot v = 0$ AND $u, v \in \mathbb{R}^n \leftrightarrow u \perp v$
Set of Vectors in \mathbb{R}^n is orthogonal ↔ every pair is orthogonal
Set is only orthonormal ↔ \forall vectors are unit vectors

Bases:
 S is an orthogonal – orthonormal basis:
 $\leftrightarrow S$ is orthogonal – orthonormal
 $\leftrightarrow |S| = \dim(V)$ OR $\text{span}(S) = V$

Projections:
Let V be a subspace of \mathbb{R}^n . Every vector $u \in \mathbb{R}^n$
can be written uniquely as $u = n + p$
s.t. n is a vector orthogonal to V and p is a vector in V

If $\{ u_1, \dots, u_k \}$ is an orthogonal basis for V , then $\forall w \in \mathbb{R}^n$
 $p = \frac{w \cdot u_1}{u_1 \cdot u_1} u_1 + \frac{w \cdot u_2}{u_2 \cdot u_2} u_2 + \dots + \frac{w \cdot u_k}{u_k \cdot u_k} u_k$ is the projection of w onto V

Gram-Schmidt Process:
Let $\{ u_1, \dots, u_k \}$ be a basis for a vector space V :
 $v_i = u_i$ only if $i = 1$
 $v_i = u_i - \sum_{j=1}^{i-1} \frac{u_i \cdot v_j}{v_j \cdot v_j} v_j$
 $\{ v_1, \dots, v_k \}$ form an orthogonal basis

Least Square Solutions:
 u is a sol to $Ax = b \leftrightarrow u$ is a soln to $A^T Ax = A^T b$

Orthogonal Matrices:
Square matrix is orthogonal ↔ $A^T = A^{-1}$
Rows and cols form orthonormal basis for \mathbb{R}^n
 $P_{T,S} = (P_{S,T})^{-1} = (P_{S,T})^T$, similar to transpose matrices

6) Diagonalization:
Eigenvalues:
For a square matrix A , $u \in \mathbb{R}^n$ is an eigenvector of A if $Au = \lambda u \rightarrow \lambda$ is an eigenvalue of A
 $\det(\lambda I - A) = 0$ is the characteristic equation
 $\det(\lambda I - A)$ is the characteristic polynomial
For Δ matrix, diagonal entries are the eigenvalues

NOTE: 0 is not an eigenvalue of A
 $(\lambda I - A)x = 0 \leftrightarrow$ eigenspace of the associated eigenvalue

To find characteristic polynomial, work backwards:
1) Find basis for the eigenspaces of their eigenvalues
2) # of vectors for basis for eigne space = degree in polynomial

Diagonalizable Matrices:
Let A be a square matrix, A is diagonalizable
 $\leftrightarrow \exists$ invertible matrix P s.t. $P^{-1}AP$ is a diagonal matrix
 $\leftrightarrow A$ has n l.i. eigenvectors
 $\leftrightarrow \dim(\text{Eig}(A)) = \text{multiplicity of associated eigenvalue}$
 $\leftrightarrow A$ has n distinct eigenvalues

Orthogonal Diagonalization:
Let A be a square matrix, A is orthogonally diagonalizable
 $\leftrightarrow \exists$ orthogonal matrix P s.t. $P^{-1}AP$ is a diagonal matrix
 $\leftrightarrow A$ is a symmetric matrix
 $P^T AP = D \leftrightarrow A = PDP^T$
Steps:
1) Find all distinct eigenvalues
2) Find an orthonormal basis for each unique eigenvalue
3) $A = PDP^T$ where $P =$ all basis vectors and
 $D =$ all eigenvalues placed diagonally

7) Linear Transformations:
Basic Properties:
 $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is a linear transformation
 $\leftrightarrow T(0) = 0 \leftrightarrow T(c_1 u_1, \dots, c_k u_k) = (c_1 T u_1, \dots, c_k T u_k)$
 $T(u) = Au \rightarrow A$ is the standard matrix
 $(T \cdot S)(u) = T(S(u)) \rightarrow BA$ is the standard matrix for $T \cdot S$
 $(S \cdot T)(u) = S(T(u)) \rightarrow AB$ is the standard matrix for $S \cdot T$

Standard Matrices:
 $\begin{matrix} V & \xrightarrow{P_{u \rightarrow v}} & [V]_S \\ | & \swarrow \searrow & \\ \mathbb{R}^n & & \mathbb{R}^m \end{matrix}$
Suppose $T: V \rightarrow W$ is a linear transformation,
 $S = \{ u_1, \dots, u_n \}$ is a basis for V
 $T(e_i) = Ae_i \rightarrow A = [T(e_1) \ \dots \ T(e_n)]$
Able to find standrad matrix using
images of basic vectors of standard basis

Ranger and Kernels:
 $R(T) = \text{set of images of } T$
 $R(T) = \text{span}\{ T(u_1) \dots T(u_k) \} = \text{col space}$
 $\text{rank}(T) = \dim(R(T))$
 $\text{Ker}(T) = \text{set of vectors where image is the } 0 \text{ vector}$
 $\text{Ker}(T) = \text{nullspace}$
 $\text{nullity}(T) = \dim(\text{Ker}(T))$
Find nullity of T , find the basis for kernel of T using $Tx = 0$
If A is the standard matrix for T : $\text{nullity}(A) = \text{nullity}(T)$
If $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$, $\text{rank}(T) + \text{nullity}(T) = n$

Invertible Matrix Theorem:
Let A be an $n \times n$ matrix. The following statements are equivalent:
1. A is invertible.
2. The linear system $Ax = 0$ has only the trivial solution.
3. The reduced row-echelon form of A is an identity matrix.
4. A can be expressed as a product of elementary matrices.
5. $\det(A) \neq 0$.
6. The rows of A form a basis for n .
7. The columns of A form a basis for n .
8. $\text{rank}(A) = n$.
9. 0 is not an eigenvalue of A .

Tutorial 1:
An inconsistent linear system with more unknowns than equations exists.

Tutorial 2:
Suppose B commutes with A ,
 B must be in the form $\begin{pmatrix} a & b \\ 0 & a \end{pmatrix}$ given A is $\begin{pmatrix} a & b \\ 0 & a \end{pmatrix}$
 $\begin{pmatrix} D_1 \\ D_2 \end{pmatrix} A = \begin{pmatrix} D_1 A \\ D_2 A \end{pmatrix}$ and $A \begin{pmatrix} D_1 & D_2 \end{pmatrix} = (A D_1 \quad A D_2)$
 $(A + B)^2 = A^2 + B^2 + AB \leftrightarrow AB = BA$
If $AA^T = 0, A = 0$

Tutorial 3:
If $A^n = 0$ for some $n \geq 2$, then $(I - A)^{-1} = I + \sum_{i=1}^{n-1} A^i$
Let $A = m \times n$ matrix and $B = n \times m$ matrix,
if A, B equivalent to $\begin{pmatrix} R & 0 \\ 0 & \dots & 0 \end{pmatrix}$, AB is singular $\leftrightarrow m < n$

Tutorial 4:
If A and B are $n \times n$ matrices of same size, $\det(AB) = \det(BA)$ if A is a $n \times n$ matrix w integer entries,
 $\det(A) = 1, A^{-1}$ also has integer entries
If A is invertible, $\text{adj}(A)$ is invertible
1) $\det(\text{adj}(A)) = \det(A)^{n-1}$ and $\text{adj}(A)^{-1} = \frac{A}{\det(A)}$
2) $\text{adj}(\text{adj}(A)) = \det(\text{adj}(A)) \cdot \text{adj}(A)^{-1} = A$

Tutorial 5:
 $\text{span}\{u_1, \dots, u_k\} = R^n \leftrightarrow (A|v)$ is consistent for all $v \in R^n$

Tutorial 6:
To prove that S is a basis for V , $(s_1 \dots s_k | v_1 | \dots | v_j)$ is consistent
To find coordinate vector for u , solve for $(s_1 \dots s_k | u)$
Let W be a subspace of R^n and $v \in R^n$, if $W' = \{u + v \mid u \in W\} \subseteq R^n$
1) if $v \notin W$, W' is not a subspace of R^n
2) if $v \in W$, $W' = W$ is a subspace of R^n

If Au, Av, Aw are l.i.; u, v and w must be l.i.
If u, v, w are l.i. vectors in R^4 , Au, Av and Aw are l.i.

Tutorial 7:
Let V be a vector space:
Suppose $S \subseteq V$ s.t. $\text{span}(S) = V, \exists S' \subseteq S$ s.t. S' is a basis for V
Suppose $T \subseteq V$ s.t. T is l.i., \exists a basis T' for V s.t. $T \subseteq T'$

Let A be a $n \times n$ matrix, Suppose $A^m = 0$ and $A^{m-1} \neq 0$ where $m \geq 2$,
Since $A^{m-1} \neq 0, A^{m-1}$ must have ≥ 1 non-zero col
 $c_k = 0, \forall k = 1, \dots, m-1$ Suppose $c_1 u + \dots + c_k A^{m-1} u = 0$

Tutorial 8:
Let $S = \{u_1, \dots, u_k\}$ be an orthonormal basis for subspace V of R^n
 $\forall v, w \in V, v \cdot w = (v)_S \cdot (w)_S$

Tutorial 9:
Let P be a $n \times n$ orthogonal matrix
 $\forall x, y \in R^n, (Px) \cdot (Py) = x \cdot y$
If $\{u_1, \dots, u_k\}$ is an orthonormal basis for R^n ,
 $\{Pu_1, \dots, Pu_k\}$ is also an orthonormal basis for R^n .

Let $V = \text{span}\{u_1, \dots, u_k\}$ be a vector space s.t. u_i are all unit vectors
if $u_i \cdot u_j < 0$, if $i \neq j, 90^\circ \leq \theta_{ij} \leq 180^\circ$
no two vectors among $\{u_1, \dots, u_k\}$ are l.i. and $\dim(V) \geq 3$

Tutorial 10:
If A is orthogonally diagonalizable, eigenspaces are orthogonal
 λ is eigenvalue of A, λ^n is eigenvalue of A^n, λ is eigenvalue of A^T

Tutorial 11:
Let $T: R^n \rightarrow R^m$ and $S: R^m \rightarrow R^n$ such that $S \cdot T = I$,
 $R(S) = R^n$ and $\text{Ker}(T) = \{0\}$

Homework 1:
 A is a matrix C is anti-symmetric $\leftrightarrow C^T = -C$
if $B = \frac{A+A^T}{2}$ and $C = \frac{A-A^T}{2}$, B is symmetric and C is anti-symmetric

If A and B are symmetric, $A + B, rA$ and rB are all symmetric
if A and B are symmetric, $AB = BA, AB$ is symmetric

Homework 2:
Vandermonde matrix: $V = (a_i^{j-1})_{n \times n}$ and $\det(V) = \prod_{1 \leq i < j \leq n} (a_j - a_i)$

If $A^3 = A, \det(A) = -1, 0, 1$

If sum of entries in each column is 0, $\det(A) = 0$
If $n > 2, a_{ij} = i + j, \det(A) = 0$

Homework 3:
 $V \subseteq R^n$ is a subspace of $R^n \leftrightarrow V \neq \emptyset$ and $cv + du \in V$
If U and V are subspaces of $R^n, U + V$ is also a subspace of R^n

If $S = \{u, \dots, v\} \subseteq R^n$, if $x \notin \text{span}(S), S$ is not l.i.
If $S = \{u, \dots, v\} \subseteq R^n, uB + \dots + vB = 0, S$ is not l.i.
if S and T are both l.i. sets of vectors,
 $\{s_1 \dots s_k, t_1 \dots t_k\}$ is l.i. $\leftrightarrow \text{span}(S) \cap \text{span}(T) = \{0\}$

Homework 4:
If $V \subseteq R^n$ be a subspace. V^\perp is a subspace of R^n and $(V^\perp)^\perp = V$
Let $v \in R^n, p_1, p_2 \in V$ and $n_1, n_2 \in V^\perp$ s.t. $v = p_1 + n_1 = p_2 + n_2$,
thus $p_1 = p_2$ and $n_1 = n_2$

Assuming $u \cdot v = 0, \|u + v\|^2 = \|u\|^2 + \|v\|^2$
 $(u \cdot v)^2 = \|u\|^2 \|v\|^2 - \|u - v\|^2 \|v\|^2$ and $\|u \cdot v\| \leq \|u\| \|v\|$

If λ be an eigenvalue of AB, λ is also an eigenvalue of BA

Past Midterms:
Let $B = \begin{pmatrix} 2 & 2 & 4 \\ 1 & 1 & 2 \\ 6 & 6 & 12 \end{pmatrix}$, if $AX = B$ has no soln, A must be 0

If A is row equivalent to B and B is invertible, then A is invertible
 $\forall r \in R$, there is a 2×2 matrix A with $\det(A) = r$
 \forall matrices A, B , if $A^T A = A$, then $A^T = A$

If $Ax = b$ and $Ax = c$ are consistent, $Ax = b + c$ is also consistent
If $AB = I_m$ and $BA = I_n, m = n$

If $Ax = b$ has only one solution, then $Ax = 0$ has only the trivial soln
 $\det(A) = \det(B^{-1}AB)$
If A is a $n \times n$ matrix w integer entries, A^{-1} also has integer entries
 A is invertible $\leftrightarrow A^T$ is also invertible

Past Finals:
 $\forall u, w \in R^n, (Au) \cdot w = u \cdot (A^T w)$ and given v_1 to v_n are orthonormal
Given $b_i = (Av_i) \cdot w$ and $q = \sum_{i=1}^n b_i v_i \rightarrow v_i \cdot q = b_i$

Adjoint Proofs:
 $\text{adj}(B)\text{adj}(A) = \det(B)B^{-1}\det(A)A^{-1} = \det(B)\det(A)(AB)^{-1} = \text{adj}(AB)$

To prove $\text{adj}(A) = 0$ if $\text{rank}(A) < n-1$,
Every $(n-1)$ submatrix, every A_{ij} is singular, thus $\text{adj}(A) = 0$

Bases Proofs:
If V and W are subspaces of R^n ,
 $V \cap W$ is a subspace of R^n
 $V \cup W$ is a subspace of $R^n \leftrightarrow V \subseteq W$ or $W \subseteq V$
 \exists a basis S_1 for V and S_2 for W s.t. $S_1 \cap S_2$ is a basis for $V \cap W$
 \exists a basis S_1 for V and S_2 for W s.t. $S_1 \cup S_2$ is a basis for $V + W$

Row space and Col Space Proofs:
If A and B are row-equivalent matrices,
cols of A are l.i. \leftrightarrow corresponding cols of B are l.i.
cols of A form a basis for $\text{col}(A) \leftrightarrow$
corresponding cols of B form basis for $\text{col}(B)$

If P is invertible, $\text{rank}(PA) = \text{rank}(A)$

$\text{nullspace of } A = \text{nullspace of } A^T A$
 $\text{nullity}(A) = \text{nullity}(A^T A)$ and $\text{rank}(A) = \text{rank}(A^T A) = \text{rank}(AA^T)$

Vector Proofs:
 $\|u + v\|^2 + \|u - v\|^2 = 2\|u\|^2 + 2\|v\|^2$
 $u \cdot v = \frac{1}{4} \|u + v\|^2 - \frac{1}{4} \|u - v\|^2$

Diagonalization Proofs:
 $\begin{pmatrix} a & 1 \\ 0 & b \end{pmatrix}$ is diagonalizable $\leftrightarrow a \neq b$
 $n \times n$ matrix is stochastic if \forall entries ≥ 0 and $\forall j, \sum_{i=1}^n a_{ij} = 1$

If A and B are same size diagonalizable matrices:
 $A + B$ and AB may not all be diagonalizable
However, if A and B are same size matrices and
orthogonally diagonalizable matrices:
 $A + B$ is also orthogonally diagonalizable

Linear Transformation Proofs:
Let $T: R^n \rightarrow R^n$ s.t. $T \cdot T = T$:
Standard matrix is: $\begin{pmatrix} r & s \\ t & 1-r \end{pmatrix}$
If T is not the zero transformation, $\exists u \neq 0 \in R^n$ s.t. $T(u) = u$
If T is not the identity transformation, $\exists u \neq 0 \in R^n$ s.t. $T(u) = 0$

Let $S: R^n \rightarrow R^m$ and $T: R^m \rightarrow R^k$ be linear transformations:
 $\text{Ker}(S) \subseteq \text{Ker}(T \cdot S)$ and $R(T \cdot S) \subseteq R(T)$

2x2 matrices:

$\begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$	$\begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}$	$\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$	$\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$
$\begin{pmatrix} 0 & 0 \\ 1 & 1 \end{pmatrix}$	$\begin{pmatrix} 1 & 0 \\ 1 & 0 \end{pmatrix}$	$\begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix}$	$\begin{pmatrix} 0 & 1 \\ 0 & 1 \end{pmatrix}$
$\begin{pmatrix} 0 & 1 \\ 1 & 1 \end{pmatrix}$	$\begin{pmatrix} 1 & 0 \\ 1 & 1 \end{pmatrix}$	$\begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix}$	$\begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$
	lower triangular		upper triangular
$\begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$	$\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$	$\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$	$\begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$
zero		diagonal	one

Computations:
Inverse Matrices:
($A|I$) Gaussian ($I|A^{-1}$)

Projection of w onto V , given a basis $S = \{u_1, \dots, u_n\}$
 $\sum_{i=1}^n (v_i \cdot u_i) u_i$
Or solve for Least Square solutions $\rightarrow Ax = w$

Rank and Nullity:
 $\text{rank}(A) \rightarrow \#$ of pivot cols in $\text{rref}(A)$
 $\text{nullity}(A) \rightarrow \#$ of non-pivot cols in $\text{rref}(A)$

$\text{PDP}^{-1} = A$
 $P = (v \text{ for } E_2 \quad \dots \quad v \text{ for } E_k)$
 $D = \begin{pmatrix} \lambda & 0 & 0 \\ 0 & \ddots & 0 \\ 0 & 0 & \lambda \end{pmatrix}$

Standard Matrix:
 $T(x) \rightarrow Ax, A$ is standard matrix