

ECSE 543

Assignment 1

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1 Introduction

The programs for this assignment were created in Python 2.7. The source code is provided as listings in Appendix A. To perform the required tasks in this assignment, a custom matrix package was created, with useful methods such as add, multiply, transpose, etc. This package can be seen in Listing 1. In addition, logs of the output of the programs are provided in Appendix B.

2 Choleski Decomposition

The source code for the Question 1 main program can be seen in Listing 5.

2.a Choleski Program

The code relating specifically to Choleski decomposition can be seen in Listing 2.

2.b Constructing Test Matrices

The matrices were constructed with the knowledge that, if A is positive-definite, then $A = LL^T$ where L is a lower triangular non-singular matrix. The task of choosing valid A matrices then boils down to finding non-singular lower triangular L matrices. To ensure that L is non-singular, one must simply choose nonzero values for the main diagonal.

2.c Test Runs

The matrices were tested by inventing x matrices, and checking that the program solves for that x correctly. The output of the program, comparing expected and obtained values of x , can be seen in Listing 8.

2.d Linear Networks

First, the program was tested on the circuits provided on MyCourses.

3 Finite Difference Mesh

The source code for the Question 2 main program can be seen in Listing 6.

3.a Equivalent Resistance

The code for creating all the network matrices and for finding the equivalent resistance of an N by $2N$ mesh can be seen in Listing 3. The resistances

found by the program for values of N from 2 to 10 can be seen in Table 1.

Table 1: Mesh equivalent resistance R versus mesh size N .

N	R (Omega)
2	1875.000
3	2379.545
4	2741.025
5	3022.819
6	3253.676
7	3449.166
8	3618.675
9	3768.291
10	3902.189

3.b Time Complexity

The runtime data for the mesh resistance solver is tabulated in Table 2 and plotted in Figure 1. Theoretically, the time complexity of the program should be $O(N^6)$, and this matches the obtained data.

Table 2: Runtime of mesh resistance solver program versus mesh size N .

N	Runtime (s)
2	0.001
3	0.017
4	0.103
5	0.411
6	1.246
7	3.299
8	7.425
9	15.091
10	29.251

3.c Sparsity Modification

The runtime data for the banded mesh resistance solver is tabulated in Table 3 and plotted in Figure 2. By inspection of the constructed network matrices, a half-bandwidth of $2N + 1$ was chosen. Theoretically, the banded version should have a time complexity of $O(N^4)$.

The runtime of the banded and non-banded versions of the program are plotted in Figure 3, showing the benefits of banded elimination.

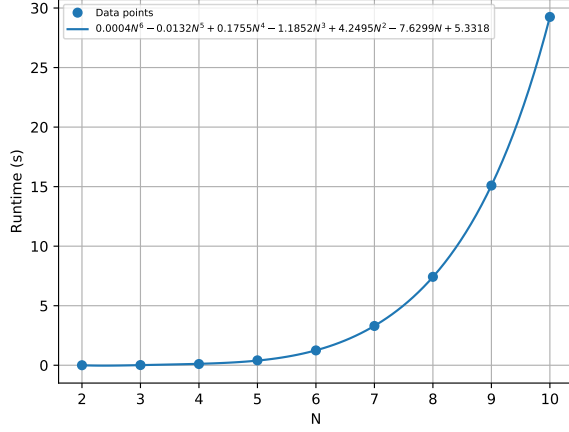


Figure 1: Runtime of mesh resistance solver program versus mesh size N .

Table 3: Runtime of banded mesh resistance solver program versus mesh size N .

N	Runtime (s)
2	0.001
3	0.016
4	0.098
5	0.393
6	1.204
7	3.142
8	6.986
9	14.431
10	27.492

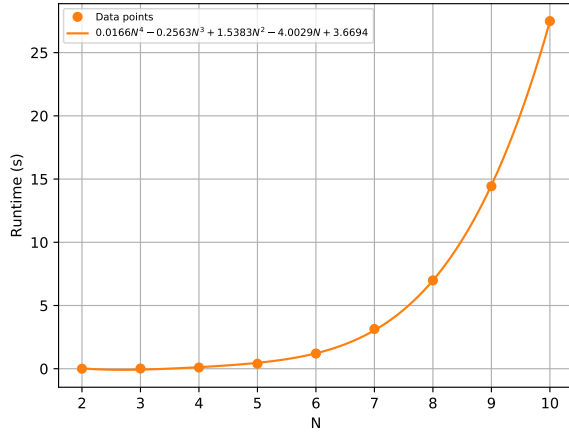


Figure 2: Runtime of banded mesh resistance solver program versus mesh size N .

3.d Resistance vs. Mesh Size

The equivalent mesh resistance R is plotted versus the mesh size N in Figure 4. The function $R(N)$

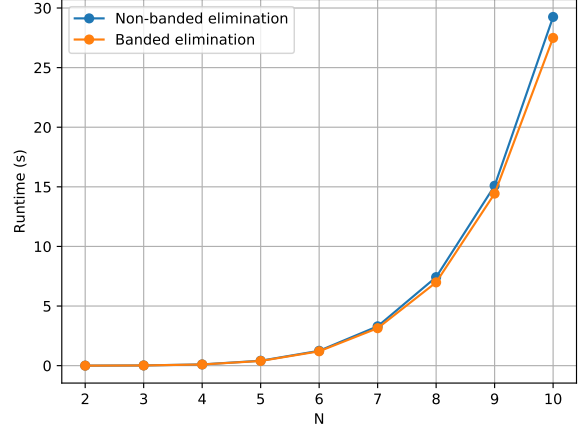


Figure 3: Comparison of runtime of banded and non-banded resistance solver programs versus mesh size N .

appears logarithmic, and a log function does indeed fit the data well.

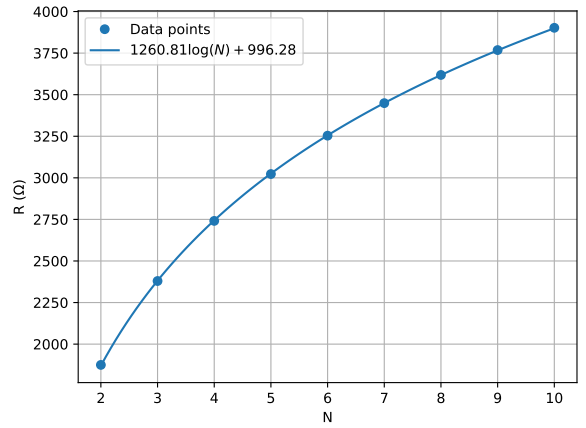


Figure 4: Resistance of mesh versus mesh size N .

4 Coaxial Cable

The source code for the Question 2 main program can be seen in Listing 7.

4.a SOR Program

The source code for the finite difference methods can be seen in Listing 4. Horizontal and vertical symmetries were exploited by only solving for a quarter of the coaxial cable, and reproducing the results where necessary.

4.b Varying ω

The number of iterations to achieve convergence for 10 values of ω between 1 and 2 are tabulated in Table 4 and plotted in Figure 5. Based on these results, the value of ω yielding the minimum number of iterations is 1.3.

Table 4: Number of iterations of SOR versus ω .

Omega	Iterations
1.0	32
1.1	26
1.2	20
1.3	14
1.4	16
1.5	20
1.6	27
1.7	39
1.8	60
1.9	127

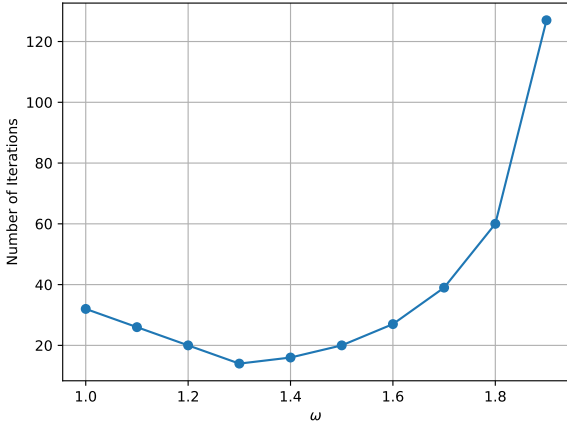


Figure 5: Number of iterations of SOR versus ω .

The potential values found at (0.06, 0.04) versus ω are tabulated in Table 5. It can be seen that all the potential values are identical to 3 decimal places.

4.c Varying h

With $\omega = 1.3$, the number of iterations of SOR versus $1/h$ is tabulated in Table 6 and plotted in Figure 6. It can be seen that the smaller the node spacing is, the more iterations the program will take to run. Theoretically, the time complexity of the program should be $O(N^3)$, where the finite difference mesh is N by N , and this matches the measured data.

Table 5: Potential at (0.06, 0.04) versus ω when using SOR.

Omega	Potential (V)
1.0	5.526
1.1	5.526
1.2	5.526
1.3	5.526
1.4	5.526
1.5	5.526
1.6	5.526
1.7	5.526
1.8	5.526
1.9	5.526

Table 6: Number of iterations of SOR versus $1/h$. Note that $\omega = 1.3$.

1/h	Iterations
50.0	14
100.0	59
200.0	189
400.0	552
800.0	1540
1600.0	4507

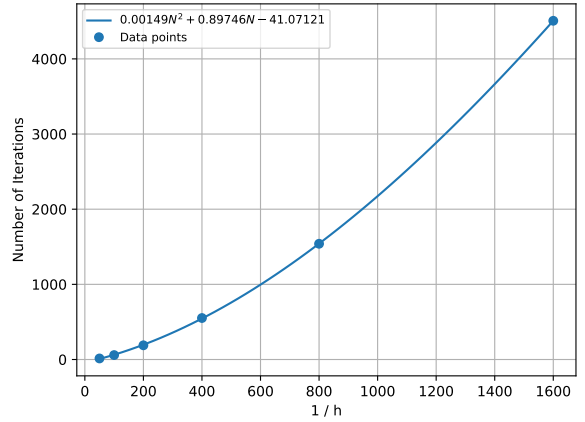


Figure 6: Number of iterations of SOR versus $1/h$. Note that $\omega = 1.3$.

The potential values found at (0.06, 0.04) versus $1/h$ are tabulated in Table 7 and plotted in Figure 7. By examining these values, the potential at (0.06, 0.04) to three significant figures is approximately 5.25 V. It can be seen that the smaller the node spacing is, the more accurate the calculated potential is. However, by inspecting Figure 7 it is apparent that the potential converges relatively quickly to around 5.25 V. There are therefore diminishing returns to decreasing the node spacing.

too much, since this will also increase the runtime of the program.

Table 7: Potential at (0.06, 0.04) versus $1/h$ when using SOR.

$1/h$	Potential (V)
50.0	5.526
100.0	5.351
200.0	5.289
400.0	5.265
800.0	5.254
1600.0	5.247

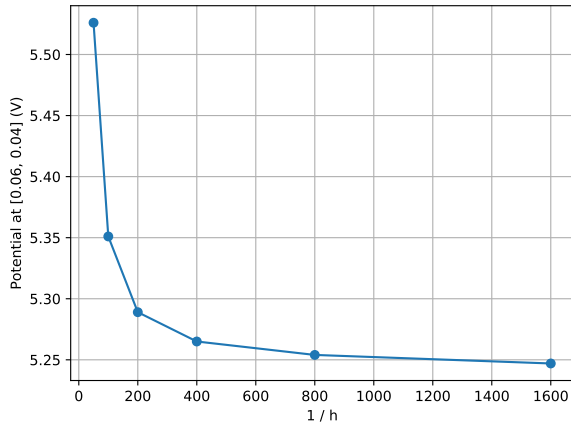


Figure 7: Potential at (0.06, 0.04) found by SOR versus $1/h$. Note that $\omega = 1.3$.

4.d Jacobi Method

The number of iterations of the Jacobi method versus $1/h$ is tabulated in Table 8 and plotted in Figure 8. Similarly to SOR, the smaller the node spacing is, the more iterations the program will take to run. We can see however that the Jacobi method takes a much larger number of iterations to converge. Theoretically, the Jacobi method should have a time complexity of $O(N^4)$, and this matches the data.

The potential values found at (0.06, 0.04) versus $1/h$ with the Jacobi method are tabulated in Table 9 and plotted in Figure 9. These potential values are almost identical to the SOR ones. Similarly to SOR, the smaller the node spacing is, the more accurate the calculated potential is.

The number of iterations of both SOR and the Jacobi method can be seen in Figure 10, which shows the clear benefits of SOR.

Table 8: Number of iterations versus ω when using the Jacobi method.

$1/h$	Iterations
50.0	51
100.0	180
200.0	604
400.0	1935
800.0	5836
1600.0	16864

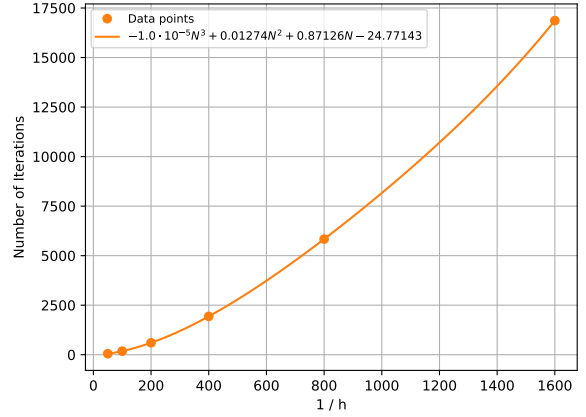


Figure 8: Number of iterations of the Jacobi method versus $1/h$.

Table 9: Potential at (0.06, 0.04) versus $1/h$ when using the Jacobi method.

$1/h$	Potential (V)
50.0	5.526
100.0	5.351
200.0	5.289
400.0	5.265
800.0	5.254
1600.0	5.246

4.e Non-uniform Node Spacing

Theoretically, the five-point difference formula for non-uniform spacing is as follows:

$$\phi_{i,j}^{k+1} = \dots$$

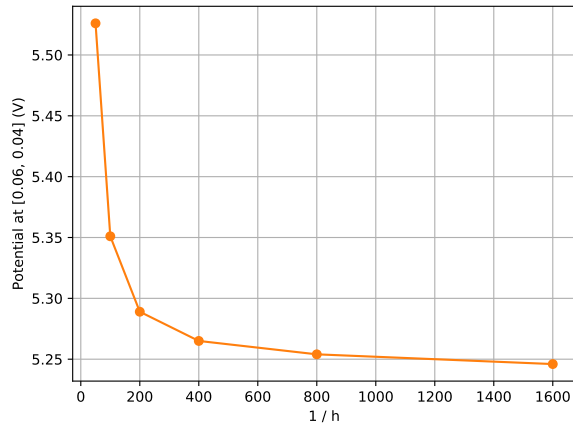


Figure 9: Potential at $(0.06, 0.04)$ versus $1/h$ when using the Jacobi method.

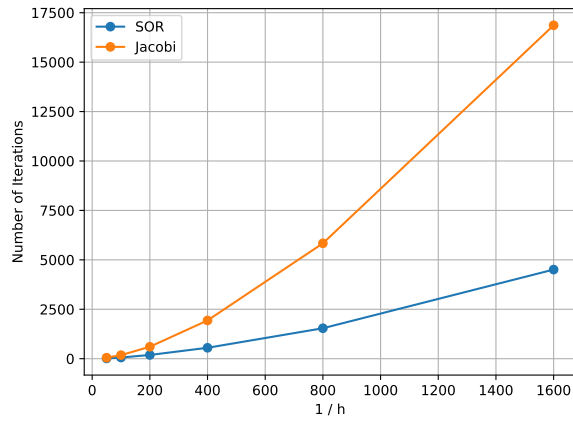


Figure 10: Comparison of number of iterations when using SOR and Jacobi methods versus $1/h$. Note that $\omega = 1.3$ for the SOR program.

A Code Listings

Listing 1: Custom matrix package (*matrices.py*).

```
1  from __future__ import division
2
3  import copy
4  import csv
5  from ast import literal_eval
6
7  import math
8
9
10 class Matrix:
11
12     def __init__(self, data):
13         self.data = data
14
15     def __str__(self):
16         string = ''
17         for row in self.data:
18             string += '\n'
19             for val in row:
20                 string += '{:6.2f} '.format(val)
21         return string
22
23     def __add__(self, other):
24         if len(self) != len(other) or len(self[0]) != len(other[0]):
25             raise ValueError('Incompatible matrix sizes for addition. Matrix A is {}x{}, but matrix B is
26                 ↳ {}x{}.'.format(len(self), len(self[0]), len(other), len(other[0])))
27         rows = len(self)
28         cols = len(self[0])
29
30         return Matrix([[self[row][col] + other[row][col] for col in range(cols)] for row in range(rows)])
31
32     def __sub__(self, other):
33         if len(self) != len(other) or len(self[0]) != len(other[0]):
34             raise ValueError('Incompatible matrix sizes for subtraction. Matrix A is {}x{}, but matrix B
35                 ↳ is {}x{}.'.format(len(self), len(self[0]), len(other), len(other[0])))
36         rows = len(self)
37         cols = len(self[0])
38
39         return Matrix([[self[row][col] - other[row][col] for col in range(cols)] for row in range(rows)])
40
41     def __mul__(self, other):
42         m = len(self[0])
43         n = len(self)
44         p = len(other[0])
45         if m != len(other):
46             raise ValueError('Incompatible matrix sizes for multiplication. Matrix A is {}x{}, but matrix
47                 ↳ B is {}x{}.'.format(n, m, len(other), p))
48
49         # Inspired from https://en.wikipedia.org/wiki/Matrix_multiplication
50         product = Matrix.empty(n, p)
51         for i in range(n):
52             for j in range(p):
53                 row_sum = 0
54                 for k in range(m):
55                     row_sum += self[i][k] * other[k][j]
56                 product[i][j] = row_sum
57         return product
58
59     def __deepcopy__(self, memo):
60         return Matrix(copy.deepcopy(self.data))
61
62     def __getitem__(self, item):
```

```

63         return self.data[item]
64
65     def __len__(self):
66         return len(self.data)
67
68     def is_positive_definite(self):
69         A = copy.deepcopy(self.data)
70         n = len(A)
71         for j in range(n):
72             if A[j][j] <= 0:
73                 return False
74             A[j][j] = math.sqrt(A[j][j])
75             for i in range(j + 1, n):
76                 A[i][j] = A[i][j] / A[j][j]
77                 for k in range(j + 1, i + 1):
78                     A[i][k] = A[i][k] - A[i][j] * A[k][j]
79         return True
80
81     def transpose(self):
82         rows = len(self)
83         cols = len(self[0])
84         return Matrix([[self.data[row][col] for row in range(rows)] for col in range(cols)])
85
86     def mirror_horizontal(self):
87         rows = len(self)
88         cols = len(self[0])
89         return Matrix([[self.data[rows - row - 1][col] for col in range(cols)] for row in range(rows)])
90
91     def empty_copy(self):
92         return Matrix.empty(len(self), len(self[0]))
93
94     @staticmethod
95     def multiply(*matrices):
96         n = len(matrices[0])
97         product = Matrix.identity(n)
98         for matrix in matrices:
99             product = product * matrix
100         return product
101
102     @staticmethod
103     def empty(rows, cols):
104         """
105         Returns an empty matrix (filled with zeroes) with the specified number of columns and rows.
106
107         :param rows: number of rows
108         :param cols: number of columns
109         :return: the empty matrix
110         """
111         return Matrix([[0 for col in range(cols)] for row in range(rows)])
112
113     @staticmethod
114     def identity(n):
115         return Matrix.diagonal_single_value(1, n)
116
117     @staticmethod
118     def diagonal(values):
119         n = len(values)
120         return Matrix([[values[row] if row == col else 0 for col in range(n)] for row in range(n)])
121
122     @staticmethod
123     def diagonal_single_value(value, n):
124         return Matrix([[value if row == col else 0 for col in range(n)] for row in range(n)])
125
126     @staticmethod
127     def column_vector(values):
128         """
129         Transforms a row vector into a column vector.
130
131         :param values: the values, one for each row of the column vector
132         :return: the column vector

```



```

133         """
134         return Matrix([[value] for value in values])
135
136     @staticmethod
137     def csv_to_matrix(filename):
138         with open(filename, 'r') as csv_file:
139             reader = csv.reader(csv_file)
140             data = []
141             for row_number, row in enumerate(reader):
142                 data.append([literal_eval(val) for val in row])
143             return Matrix(data)

```

Listing 2: Choleski decomposition (*choleski.py*).

```

1  from __future__ import division
2
3  import math
4
5  from matrices import Matrix
6
7
8  def choleski_solve(A, b, half_bandwidth=None):
9      n = len(A[0])
10     if half_bandwidth is None:
11         elimination(A, b)
12     else:
13         elimination_banded(A, b, half_bandwidth)
14     x = Matrix.empty(n, 1)
15     back_substitution(A, x, b)
16     return x
17
18
19 def elimination(A, b):
20     n = len(A)
21     for j in range(n):
22         if A[j][j] <= 0:
23             raise ValueError('Matrix A is not positive definite.')
24         A[j][j] = math.sqrt(A[j][j])
25         b[j][0] = b[j][0] / A[j][j]
26         for i in range(j + 1, n):
27             A[i][j] = A[i][j] / A[j][j]
28             b[i][0] = b[i][0] - A[i][j] * b[j][0]
29             for k in range(j + 1, i + 1):
30                 A[i][k] = A[i][k] - A[i][j] * A[k][j]
31
32
33 def elimination_banded(A, b, half_bandwidth): # TODO: Keep limited band in memory, improve time
34     ↪ complexity
35     n = len(A)
36     for j in range(n):
37         if A[j][j] <= 0:
38             raise ValueError('Matrix A is not positive definite.')
39         A[j][j] = math.sqrt(A[j][j])
40         b[j][0] = b[j][0] / A[j][j]
41         for i in range(j + 1, min(j + half_bandwidth, n)):
42             A[i][j] = A[i][j] / A[j][j]
43             b[i][0] = b[i][0] - A[i][j] * b[j][0]
44             for k in range(j + 1, i + 1):
45                 A[i][k] = A[i][k] - A[i][j] * A[k][j]
46
47 def back_substitution(L, x, y):
48     n = len(L)
49     for i in range(n - 1, -1, -1):
50         prev_sum = 0
51         for j in range(i + 1, n):
52             prev_sum += L[j][i] * x[j][0]
53         x[i][0] = (y[i][0] - prev_sum) / L[i][i]

```

Listing 3: Linear resistive networks (*linear_networks.py*).

```

1  from __future__ import division
2
3  import csv
4  from matrices import Matrix
5  from choleski import choleski_solve
6
7
8  def solve_linear_network(A, Y, J, E, half_bandwidth=None):
9      A_new = A * Y * A.transpose()
10     b = A * (J - Y * E)
11     return choleski_solve(A_new, b, half_bandwidth=half_bandwidth)
12
13
14 def csv_to_network_branch_matrices(filename):
15     with open(filename, 'r') as csv_file:
16         reader = csv.reader(csv_file)
17         J = []
18         R = []
19         E = []
20         for row in reader:
21             J_k = float(row[0])
22             R_k = float(row[1])
23             E_k = float(row[2])
24             J.append(J_k)
25             R.append(1 / R_k)
26             E.append(E_k)
27         Y = Matrix.diagonal(R)
28         J = Matrix.column_vector(J)
29         E = Matrix.column_vector(E)
30         return Y, J, E
31
32
33 def create_network_matrices_mesh(rows, cols, branch_resistance, test_current):
34     num_horizontal_branches = (cols - 1) * rows
35     num_vertical_branches = (rows - 1) * cols
36     num_branches = num_horizontal_branches + num_vertical_branches + 1
37     num_nodes = rows * cols - 1
38
39     A = create_incidence_matrix_mesh(cols, num_branches, num_horizontal_branches, num_nodes,
40     ↪ num_vertical_branches)
41     Y, J, E = create_network_branch_matrices_mesh(num_branches, branch_resistance, test_current)
42
43     return A, Y, J, E
44
45 def create_incidence_matrix_mesh(cols, num_branches, num_horizontal_branches, num_nodes,
46 ↪ num_vertical_branches):
47     A = Matrix.empty(num_nodes, num_branches)
48     node_offset = -1
49     for branch in range(num_horizontal_branches):
50         if branch == num_horizontal_branches - cols + 1:
51             A[branch + node_offset + 1][branch] = 1
52         else:
53             if branch % (cols - 1) == 0:
54                 node_offset += 1
55             node_number = branch + node_offset
56             A[node_number][branch] = -1
57             A[node_number + 1][branch] = 1
58     branch_offset = num_horizontal_branches
59     node_offset = cols
60     for branch in range(num_vertical_branches):
61         if branch == num_vertical_branches - cols:
62             node_offset -= 1
63             A[branch][branch + branch_offset] = 1
64         else:
65             A[branch][branch + branch_offset] = 1
66             A[branch + node_offset][branch + branch_offset] = -1

```

```

66     if num_branches == 2:
67         A[0][1] = -1
68     else:
69         A[cols - 1][num_branches - 1] = -1
70     return A
71
72
73 def create_network_branch_matrices_mesh(num_branches, resistance, test_current):
74     Y = Matrix.diagonal([1 / resistance if branch < num_branches - 1 else 0 for branch in
75         ↪ range(num_branches)])
76     # Negative test current here because we assume current is coming OUT of the test current node.
77     J = Matrix.column_vector([0 if branch < num_branches - 1 else -test_current for branch in
78         ↪ range(num_branches)])
79     E = Matrix.column_vector([0 for branch in range(num_branches)])
80     return Y, J, E
81
82 def find_mesh_resistance(n, branch_resistance, half_bandwidth=None):
83     test_current = 0.01
84     A, Y, J, E = create_network_matrices_mesh(n, 2 * n, branch_resistance, test_current)
85     x = solve_linear_network(A, Y, J, E, half_bandwidth=half_bandwidth)
86     test_voltage = x[2 * n - 1 if n > 1 else 0][0]
87     equivalent_resistance = test_voltage / test_current
88     return equivalent_resistance

```

Listing 4: Finite difference method (*finite_diff.py*).

```

1  from __future__ import division
2
3  import math
4  import random
5  from abc import ABCMeta, abstractmethod
6
7  from matrices import Matrix
8
9
10 class Relaxer:
11     __metaclass__ = ABCMeta
12
13     @abstractmethod
14     def relax(self, phi, i, j):
15         raise NotImplementedError
16
17
18 class SimpleRelaxer(Relaxer):
19     """Relaxer which can represent a Jacobi relaxer, if the 'old' phi is given, or a Gauss-Seidel relaxer,
20     ↪ if phi is
21     modified in place."""
22     def relax(self, phi, i, j):
23         return (phi[i + 1][j] + phi[i - 1][j] + phi[i][j + 1] + phi[i][j - 1]) / 4
24
25 class NonUniformRelaxer:
26     def __init__(self):
27         pass
28
29     def relax(self, phi, i, j, a1, a2, b1, b2):
30         return ((phi[i - 1][j] / a1 + phi[i + 1][j] / a2) / (a1 + a2)
31             + (phi[i][j - 1] / b1 + phi[i][j + 1] / b2) / (b1 + b2)) \
32             / (1 / (a1 * a2) + 1 / (b1 * b2))
33
34
35 class SuccessiveOverRelaxer(Relaxer):
36     def __init__(self, omega):
37         self.gauss_seidel = SimpleRelaxer()
38         self.omega = omega
39
40     def relax(self, phi, i, j):
41         return (1 - self.omega) * phi[i][j] + self.omega * self.gauss_seidel.relax(phi, i, j)

```

```

42
43
44 class Boundary:
45     __metaclass__ = ABCMeta
46
47     @abstractmethod
48     def potential(self):
49         raise NotImplementedError
50
51     @abstractmethod
52     def contains_point(self, x, y):
53         raise NotImplementedError
54
55
56 class OuterConductorBoundary(Boundary):
57     def potential(self):
58         return 0
59
60     def contains_point(self, x, y):
61         return x == 0 or y == 0 or x == 0.2 or y == 0.2
62
63
64 class QuarterInnerConductorBoundary(Boundary):
65     def potential(self):
66         return 15
67
68     def contains_point(self, x, y):
69         return 0.06 <= x <= 0.14 and 0.08 <= y <= 0.12
70
71
72 class Guesser:
73     __metaclass__ = ABCMeta
74
75     def __init__(self, minimum, maximum):
76         self.minimum = minimum
77         self.maximum = maximum
78
79     @abstractmethod
80     def guess(self, x, y):
81         raise NotImplementedError
82
83
84 class RandomGuesser(Guesser):
85     def guess(self, x, y):
86         return random.randint(self.minimum, self.maximum)
87
88
89 class LinearGuesser(Guesser):
90     def guess(self, x, y):
91         return 150 * x if x < 0.06 else 150 * y
92
93
94 def radial(k, x, y, x_source, y_source):
95     return k / (math.sqrt((x_source - x)**2 + (y_source - y)**2))
96
97
98 class RadialGuesser(Guesser):
99     def guess(self, x, y):
100         return 0.0225 * (radial(20, x, y, 0.1, 0.1) - radial(1, x, y, 0, y) - radial(1, x, y, x, 0))
101
102
103 class CoaxialCableMeshConstructor:
104     def __init__(self):
105         outer_boundary = OuterConductorBoundary()
106         inner_boundary = QuarterInnerConductorBoundary()
107         self.boundaries = (inner_boundary, outer_boundary)
108         self.guesser = RadialGuesser(0, 15)
109         self.boundary_size = 0.2
110
111     def construct_simple_mesh(self, h):

```

```

112     num_mesh_points_along_axis = int(self.boundary_size / h) + 1
113     phi = Matrix.empty(num_mesh_points_along_axis, num_mesh_points_along_axis)
114     for i in range(num_mesh_points_along_axis):
115         y = i * h
116         for j in range(num_mesh_points_along_axis):
117             x = j * h
118             boundary_pt = False
119             for boundary in self.boundaries:
120                 if boundary.contains_point(x, y):
121                     boundary_pt = True
122                     phi[i][j] = boundary.potential()
123             if not boundary_pt:
124                 phi[i][j] = self.guesser.guess(x, y)
125     return phi
126
127     def construct_symmetric_mesh(self, h):
128         max_index = int(0.1 / h) + 2 # Only need to store up to middle
129         phi = Matrix.empty(max_index, max_index)
130         for i in range(max_index):
131             y = i * h
132             for j in range(max_index):
133                 x = j * h
134                 boundary_pt = False
135                 for boundary in self.boundaries:
136                     if boundary.contains_point(x, y):
137                         boundary_pt = True
138                         phi[i][j] = boundary.potential()
139                 if not boundary_pt:
140                     phi[i][j] = self.guesser.guess(x, y)
141         return phi
142
143     def point_to_indices(x, y, h):
144         i = int(y / h)
145         j = int(x / h)
146         return i, j
147
148
149
150     class IterativeRelaxer:
151         def __init__(self, relaxer, epsilon, phi, h):
152             self.relaxer = relaxer
153             self.epsilon = epsilon
154             self.phi = phi
155             self.boundary = QuarterInnerConductorBoundary()
156             self.h = h
157             self.num_iterations = 0
158             self.rows = len(phi)
159             self.cols = len(phi[0])
160             self.mid_index = int(0.1 / h)
161
162         def relaxation_jacobi(self):
163             # t = time.time()
164
165             while not self.convergence():
166                 self.num_iterations += 1
167
168                 last_row = [0] * (self.cols - 1)
169                 for i in range(1, self.rows - 1):
170                     y = i * self.h
171                     for j in range(1, self.cols - 1):
172                         x = j * self.h
173                         if not self.boundary.contains_point(x, y):
174                             last_val = last_row[j - 2] if j > 1 else 0
175                             relaxed_value = (self.phi[i + 1][j] + last_row[j - 1] + self.phi[i][j + 1] +
176                                             ↪ last_val) / 4
177                             last_row[j - 1] = self.phi[i][j]
178                             self.phi[i][j] = relaxed_value
179                             if i == self.mid_index - 1:
180                                 self.phi[i + 2][j] = relaxed_value
181                             elif j == self.mid_index - 1:

```

```

181         self.phi[i][j + 2] = relaxed_value
182
183     # print('Runtime: {} s'.format(time.time() - t))
184
185     def relaxation_sor(self):
186         while not self.convergence():
187             self.num_iterations += 1
188             for i in range(1, self.rows - 1):
189                 y = i * self.h
190                 for j in range(1, self.cols - 1):
191                     x = j * self.h
192                     if not self.boundary.contains_point(x, y):
193                         relaxed_value = self.relaxer.relax(self.phi, i, j)
194                         self.phi[i][j] = relaxed_value
195                         if i == self.mid_index - 1:
196                             self.phi[i + 2][j] = relaxed_value
197                         elif j == self.mid_index - 1:
198                             self.phi[i][j + 2] = relaxed_value
199
200     def convergence(self):
201         max_i, max_j = point_to_indices(0.1, 0.1, self.h)
202         # Only need to compute for 1/4 of grid
203         for i in range(1, max_i + 1):
204             y = i * self.h
205             for j in range(1, max_j + 1):
206                 x = j * self.h
207                 if not self.boundary.contains_point(x, y) and self.residual(i, j) >= self.epsilon:
208                     return False
209             return True
210
211     def residual(self, i, j):
212         return abs(self.phi[i+1][j] + self.phi[i-1][j] + self.phi[i][j+1] + self.phi[i][j-1] - 4 *
213             ↪ self.phi[i][j])
214
215     def get_potential(self, x, y):
216         i, j = point_to_indices(x, y, self.h)
217         return self.phi[i][j]
218
219     def print_grid(self):
220         header = ''
221         for j in range(len(self.phi[0])):
222             y = j * self.h
223             header += '{:6.2f} '.format(y)
224         print(header)
225         print(self.phi)
226         # for i in range(len(self.phi)):
227         #     x = i * self.h
228         #     print('{:6.2f} '.format(x))
229
230     def successive_over_relaxation(omega, epsilon, phi, h):
231         relaxer = SuccessiveOverRelaxer(omega)
232         iter_relaxer = IterativeRelaxer(relaxer, epsilon, phi, h)
233         iter_relaxer.relaxation_sor()
234         return iter_relaxer
235
236     def jacobi_relaxation(epsilon, phi, h):
237         relaxer = SimpleRelaxer()
238         iter_relaxer = IterativeRelaxer(relaxer, epsilon, phi, h)
239         iter_relaxer.relaxation_jacobi()
240         return iter_relaxer

```

Listing 5: Question 1 (q1.py).

```

1  from __future__ import division
2
3  from linear_networks import solve_linear_network, csv_to_network_branch_matrices
4  from choleski import choleski_solve

```

```

5  from matrices import Matrix
6
7  NETWORK_DIRECTORY = 'network_data'
8
9  L_2 = Matrix([
10     [5, 0],
11     [1, 3]
12 ])
13  L_3 = Matrix([
14     [3, 0, 0],
15     [1, 2, 0],
16     [8, 5, 1]
17 ])
18  L_4 = Matrix([
19     [1, 0, 0, 0],
20     [2, 8, 0, 0],
21     [5, 5, 4, 0],
22     [7, 2, 8, 7]
23 ])
24  matrix_2 = L_2 * L_2.transpose()
25  matrix_3 = L_3 * L_3.transpose()
26  matrix_4 = L_4 * L_4.transpose()
27  positive_definite_matrices = [matrix_2, matrix_3, matrix_4]
28
29  x_2 = Matrix.column_vector([8, 3])
30  x_3 = Matrix.column_vector([9, 4, 3])
31  x_4 = Matrix.column_vector([5, 4, 1, 9])
32  xs = [x_2, x_3, x_4]
33
34
35  def q1b():
36      print('=== Question 1(b) ===')
37      for count, A in enumerate(positive_definite_matrices):
38          n = count + 2
39          print('n={} matrix is positive-definite: {}'.format(n, A.is_positive_definite()))
40
41
42  def q1c():
43      print('=== Question 1(c) ===')
44      for x, A in zip(xs, positive_definite_matrices):
45          b = A * x
46          # print('A: {}'.format(A))
47          # print('b: {}'.format(b))
48
49          x_choleski = choleski_solve(A, b)
50          print('Expected x: {}'.format(x))
51          print('Actual x: {}'.format(x_choleski))
52
53
54  def q1d():
55      print('=== Question 1(d) ===')
56      for i in range(1, 6):
57          A = Matrix.csv_to_matrix('{}incidence_matrix_{}.csv'.format(NETWORK_DIRECTORY, i))
58          Y, J, E = csv_to_network_branch_matrices('{}network_branches_{}.csv'.format(NETWORK_DIRECTORY,
59          ↪ i))
60          # print('Y: {}'.format(Y))
61          # print('J: {}'.format(J))
62          # print('E: {}'.format(E))
63          x = solve_linear_network(A, Y, J, E)
64          print('Solved for x in network {}: {}'.format(i, x)) # TODO: Create my own test circuits here
65
66  def q1():
67      q1b()
68      q1c()
69      q1d()
70
71
72  if __name__ == '__main__':
73      q1()

```

Listing 6: Question 2 (q2.py).

```
1  import csv
2  import time
3
4  import matplotlib.pyplot as plt
5  import numpy.polynomial.polynomial as poly
6
7  import numpy as np
8  import sympy as sp
9  from matplotlib.ticker import MaxNLocator
10 from scipy.interpolate import interp1d
11
12 from linear_networks import find_mesh_resistance
13
14
15 def find_mesh_resistances(banded):
16     branch_resistance = 1000
17     points = {}
18     runtimes = {}
19     for n in range(2, 11):
20         start_time = time.time()
21         half_bandwidth = 2 * n + 1 if banded else None
22         equivalent_resistance = find_mesh_resistance(n, branch_resistance, half_bandwidth=half_bandwidth)
23         print('Equivalent resistance for {}x{} mesh: {:.2f} Ohms.'.format(n, 2 * n,
24             ↪ equivalent_resistance))
25         points[n] = '{:.3f}'.format(equivalent_resistance)
26         runtime = time.time() - start_time
27         runtimes[n] = '{:.3f}'.format(runtime)
28         print('Runtime: {} s.'.format(runtime))
29     plot_runtime(runtimes, banded)
30     return points, runtimes
31
32 def q2ab():
33     print('=== Question 2(a)(b) ===')
34     _, runtimes = find_mesh_resistances(banded=False)
35     save_rows_to_csv('report/csv/q2b.csv', zip(runtimes.keys(), runtimes.values()), header=('N', 'Runtime'
36         ↪ (s)))
37     return runtimes
38
39 def q2c():
40     print('=== Question 2(c) ===')
41     pts, runtimes = find_mesh_resistances(banded=True)
42     save_rows_to_csv('report/csv/q2c.csv', zip(runtimes.keys(), runtimes.values()), header=('N', 'Runtime'
43         ↪ (s)))
44     return pts, runtimes
45
46 def plot_runtime(points, banded=False):
47     """
48     N^6: non-banded
49     N^4: banded
50
51     :param points:
52     :param banded:
53     """
54     f = plt.figure()
55     ax = f.gca()
56     ax.xaxis.set_major_locator(MaxNLocator(integer=True))
57     x_range = [float(x) for x in points.keys()]
58     y_range = [float(y) for y in points.values()]
59     plt.plot(x_range, y_range, '{o}'.format('C1' if banded else 'C0'), label='Data points')
60
61     x_new = np.linspace(x_range[0], x_range[-1], num=len(x_range) * 10)
62     degree = 4 if banded else 6
63     polynomial_coeffs = poly.polyfit(x_range, y_range, degree)
64     polynomial_fit = poly.polyval(x_new, polynomial_coeffs)
```



```

65     N = sp.symbols("N")
66     poly_label = sum(sp.S("{:.4f}".format(v)) * N ** i for i, v in enumerate(polyomial_coeffs))
67     equation = '${}\$'.format(sp.printing.latex(poly_label))
68     plt.plot(x_new, polynomial_fit, '{}-'.format('C1' if banded else 'C0'), label=equation)
69
70     plt.xlabel('N')
71     plt.ylabel('Runtime (s)')
72     plt.grid(True)
73     plt.legend(fontsize='x-small')
74     f.savefig('report/plots/q2{}.pdf'.format('c' if banded else 'b'), bbox_inches='tight')
75
76
77 def plot_runtimes(points1, points2):
78     f = plt.figure()
79     ax = f.gca()
80     ax.xaxis.set_major_locator(MaxNLocator(integer=True))
81     x_range = points1.keys()
82     y_range = points1.values()
83     y_banded_range = points2.values()
84     plt.plot(x_range, y_range, 'o-', label='Non-banded elimination')
85     plt.plot(x_range, y_banded_range, 'o-', label='Banded elimination')
86     plt.xlabel('N')
87     plt.ylabel('Runtime (s)')
88     plt.grid(True)
89     plt.legend()
90     f.savefig('report/plots/q2bc.pdf', bbox_inches='tight')
91
92
93 def q2d(points):
94     print('=== Question 2(d) ===')
95     f = plt.figure()
96     ax = f.gca()
97     ax.xaxis.set_major_locator(MaxNLocator(integer=True))
98     x_range = [float(x) for x in points.keys()]
99     y_range = [float(y) for y in points.values()]
100    plt.plot(x_range, y_range, 'o', label='Data points')
101
102    x_new = np.linspace(x_range[0], x_range[-1], num=len(x_range) * 10)
103    coeffs = poly.polyfit(np.log(x_range), y_range, deg=1)
104    polynomial_fit = poly.polyval(np.log(x_new), coeffs)
105    plt.plot(x_new, polynomial_fit, '{}-'.format('C0'), label='${:.2f} \log(N) + {:.2f}$'.format(coeffs[1],
        ↪ coeffs[0]))
106
107    plt.xlabel('N')
108    plt.ylabel('R ( $\Omega$ )')
109    plt.grid(True)
110    plt.legend()
111    f.savefig('report/plots/q2d.pdf', bbox_inches='tight')
112    save_rows_to_csv('report/csv/q2a.csv', zip(points.keys(), points.values()), header=('N', 'R ( $\Omega$ )'))
113
114
115 def q2():
116     runtimes1 = q2ab()
117     pts, runtimes2 = q2c()
118     plot_runtimes(runtimes1, runtimes2)
119     q2d(pts)
120
121
122 def save_rows_to_csv(filename, rows, header=None):
123     with open(filename, "wb") as f:
124         writer = csv.writer(f)
125         if header is not None:
126             writer.writerow(header)
127         for row in rows:
128             writer.writerow(row)
129
130
131 if __name__ == '__main__':
132     q2()

```

Listing 7: Question 3 (q3.py).

```
1  from __future__ import division
2
3  import csv
4
5  import matplotlib.pyplot as plt
6  import time
7
8  import numpy.polynomial.polynomial as poly
9
10 import numpy as np
11 import sympy as sp
12
13 from finite_diff import CoaxialCableMeshConstructor, successive_over_relaxation, jacobi_relaxation
14
15 epsilon = 0.00001
16 x = 0.06
17 y = 0.04
18
19 NUM_H_ITERATIONS = 6
20
21
22 def q3b():
23     print('=== Question 3(b) ===')
24     h = 0.02
25     min_num_iterations = float('inf')
26     best_omega = float('inf')
27
28     omegas = []
29     num_iterations = []
30     potentials = []
31
32     for omega_diff in range(10):
33         omega = 1 + omega_diff / 10
34         print('Omega: {}'.format(omega))
35         phi = CoaxialCableMeshConstructor().construct_symmetric_mesh(h)
36         # print('Initial guess:')
37         print(phi.mirror_horizontal())
38         iter_relaxer = successive_over_relaxation(omega, epsilon, phi, h)
39         print('Quarter grid: {}'.format(phi.mirror_horizontal()))
40         # print(iter_relaxer.phi)
41         print('Num iterations: {}'.format(iter_relaxer.num_iterations))
42         potential = iter_relaxer.get_potential(x, y)
43         print('Potential at ({}, {}): {:.3f} V'.format(x, y, potential))
44         if iter_relaxer.num_iterations < min_num_iterations:
45             best_omega = omega
46             min_num_iterations = min(min_num_iterations, iter_relaxer.num_iterations)
47
48         omegas.append(omega)
49         num_iterations.append(iter_relaxer.num_iterations)
50         potentials.append('{:.3f}'.format(potential))
51         print('Relaxed:')
52
53     print('Best number of iterations: {}'.format(min_num_iterations))
54     print('Best omega: {}'.format(best_omega))
55
56     f = plt.figure()
57     x_range = omegas
58     y_range = num_iterations
59     plt.plot(x_range, y_range, 'o-', label='Number of iterations')
60     plt.xlabel('$\omega$')
61     plt.ylabel('Number of Iterations')
62     plt.grid(True)
63     f.savefig('report/plots/q3b.pdf', bbox_inches='tight')
64
65     save_rows_to_csv('report/csv/q3b_potential.csv', zip(omegas, potentials), header=('Omega', 'Potential
    ↪ (V)'))
```

```

66     save_rows_to_csv('report/csv/q3b_iterations.csv', zip(omegas, num_iterations), header=('Omega',
        ↪ 'Iterations'))
67
68     return best_omega
69
70
71 def q3c(omega):
72     print('=== Question 3(c): SOR ===')
73     h = 0.04
74     h_values = []
75     potential_values = []
76     iterations_values = []
77     for i in range(NUM_H_ITERATIONS):
78         h = h / 2
79         print('h: {}'.format(h))
80         print('1/h: {}'.format(1 / h))
81         phi = CoaxialCableMeshConstructor().construct_symmetric_mesh(h)
82         iter_relaxer = successive_over_relaxation(omega, epsilon, phi, h)
83         # print(phi.mirror_horizontal())
84         potential = iter_relaxer.get_potential(x, y)
85         num_iterations = iter_relaxer.num_iterations
86
87         print('Num iterations: {}'.format(num_iterations))
88         print('Potential at ({}, {}): {:.3f} V'.format(x, y, potential))
89
90         h_values.append(1 / h)
91         potential_values.append('{:.3f}'.format(potential))
92         iterations_values.append(num_iterations)
93
94     f = plt.figure()
95     x_range = h_values
96     y_range = potential_values
97     plt.plot(x_range, y_range, 'o-', label='Data points')
98
99     plt.xlabel('1 / h')
100    plt.ylabel('Potential at [0.06, 0.04] (V)')
101    plt.grid(True)
102    f.savefig('report/plots/q3c_potential.pdf', bbox_inches='tight')
103
104    f = plt.figure()
105    x_range = h_values
106    y_range = iterations_values
107
108    x_new = np.linspace(x_range[0], x_range[-1], num=len(x_range) * 10)
109    polynomial_coeffs = poly.polyfit(x_range, y_range, deg=3)
110    polynomial_fit = poly.polyval(x_new, polynomial_coeffs)
111    N = sp.symbols("N")
112    poly_label = sum(sp.S("{:.5f}".format(v)) * N ** i for i, v in enumerate(polynomial_coeffs))
113    equation = '${}$'.format(sp.printing.latex(poly_label))
114    plt.plot(x_new, polynomial_fit, '{}-'.format('C0'), label=equation)
115
116    plt.plot(x_range, y_range, 'o', label='Data points')
117    plt.xlabel('1 / h')
118    plt.ylabel('Number of Iterations')
119    plt.grid(True)
120    plt.legend(fontsize='small')
121
122    f.savefig('report/plots/q3c_iterations.pdf', bbox_inches='tight')
123
124    save_rows_to_csv('report/csv/q3c_potential.csv', zip(h_values, potential_values), header=('1/h',
        ↪ 'Potential (V)'))
125    save_rows_to_csv('report/csv/q3c_iterations.csv', zip(h_values, iterations_values), header=('1/h',
        ↪ 'Iterations'))
126
127    return h_values, potential_values, iterations_values
128
129
130 def q3d():
131     print('=== Question 3(d): Jacobi ===')
132     h = 0.04

```

```

133     h_values = []
134     potential_values = []
135     iterations_values = []
136     for i in range(NUM_H_ITERATIONS):
137         h = h / 2
138         print('h: {}'.format(h))
139         phi = CoaxialCableMeshConstructor().construct_symmetric_mesh(h)
140         iter_relaxer = jacobi_relaxation(epsilon, phi, h)
141         potential = iter_relaxer.get_potential(x, y)
142         num_iterations = iter_relaxer.num_iterations
143
144         print('Num iterations: {}'.format(num_iterations))
145         print('Potential at ({}, {}): {:.3f} V'.format(x, y, potential))
146
147         h_values.append(1 / h)
148         potential_values.append('{:.3f}'.format(potential))
149         iterations_values.append(num_iterations)
150
151     f = plt.figure()
152     x_range = h_values
153     y_range = potential_values
154     plt.plot(x_range, y_range, 'C1o-', label='Data points')
155     plt.xlabel('1 / h')
156     plt.ylabel('Potential at [0.06, 0.04] (V)')
157     plt.grid(True)
158     f.savefig('report/plots/q3d_potential.pdf', bbox_inches='tight')
159
160     f = plt.figure()
161     x_range = h_values
162     y_range = iterations_values
163     plt.plot(x_range, y_range, 'C1o', label='Data points')
164     plt.xlabel('1 / h')
165     plt.ylabel('Number of Iterations')
166
167     x_new = np.linspace(x_range[0], x_range[-1], num=len(x_range) * 10)
168     polynomial_coeffs = poly.polyfit(x_range, y_range, deg=4)
169     polynomial_fit = poly.polyval(x_new, polynomial_coeffs)
170     N = sp.symbols("N")
171     poly_label = sum(sp.S("{:.5f}".format(v)) * N ** i for i, v in enumerate(polynomial_coeffs))
172     equation = '$${}'.format(sp.printing.latex(poly_label))
173     plt.plot(x_new, polynomial_fit, '{-}'.format('C1'), label=equation)
174
175     plt.grid(True)
176     plt.legend(fontsize='small')
177
178     f.savefig('report/plots/q3d_iterations.pdf', bbox_inches='tight')
179
180     save_rows_to_csv('report/csv/q3d_potential.csv', zip(h_values, potential_values), header=('1/h',
181     ↪ 'Potential (V)'))
182     save_rows_to_csv('report/csv/q3d_iterations.csv', zip(h_values, iterations_values), header=('1/h',
183     ↪ 'Iterations'))
184
185     return h_values, potential_values, iterations_values
186
187 def plot_sor_jacobi(h_values, potential_values, potential_values_jacobi, iterations_values,
188     ↪ iterations_values_jacobi):
189     f = plt.figure()
190     plt.plot(h_values, potential_values, 'o-', label='SOR')
191     plt.plot(h_values, potential_values_jacobi, 'o-', label='Jacobi')
192     plt.xlabel('1 / h')
193     plt.ylabel('Potential at [0.06, 0.04] (V)')
194     plt.grid(True)
195     plt.legend()
196     f.savefig('report/plots/q3d_potential_comparison.pdf', bbox_inches='tight')
197
198     f = plt.figure()
199     plt.plot(h_values, iterations_values, 'o-', label='SOR')
200     plt.plot(h_values, iterations_values_jacobi, 'o-', label='Jacobi')
201     plt.xlabel('1 / h')

```

```

200     plt.ylabel('Number of Iterations')
201     plt.grid(True)
202     plt.legend()
203     f.savefig('report/plots/q3d_iterations_comparison.pdf', bbox_inches='tight')
204
205
206 def save_rows_to_csv(filename, rows, header=None):
207     with open(filename, "wb") as f:
208         writer = csv.writer(f)
209         if header is not None:
210             writer.writerow(header)
211         for row in rows:
212             writer.writerow(row)
213
214
215 def q3():
216     o = q3b()
217     h_values, potential_values, iterations_values = q3c(o)
218     _, potential_values_jacobi, iterations_values_jacobi = q3d()
219     plot_sor_jacobi(h_values, potential_values, potential_values_jacobi, iterations_values,
220                     ↪ iterations_values_jacobi)
221
222 if __name__ == '__main__':
223     t = time.time()
224     q3()
225     print('Total runtime: {}'.format(time.time() - t))

```

B Output Logs

Listing 8: Output of Question 1 program (q1.txt).

```

1  === Question 1(b) ===
2  n=2 matrix is positive-definite: True
3  n=3 matrix is positive-definite: True
4  n=4 matrix is positive-definite: True
5  === Question 1(c) ===
6  Expected x:
7      8.00
8      3.00
9  Actual x:
10     8.00
11     3.00
12 Expected x:
13     9.00
14     4.00
15     3.00
16 Actual x:
17     9.00
18     4.00
19     3.00
20 Expected x:
21     5.00
22     4.00
23     1.00
24     9.00
25 Actual x:
26     5.00
27     4.00
28     1.00
29     9.00
30 === Question 1(d) ===
31 Solved for x in network 1:
32     5.00
33 Solved for x in network 2:
34     50.00
35 Solved for x in network 3:

```

```

36 55.00
37 Solved for x in network 4:
38 20.00
39 35.00
40 Solved for x in network 5:
41 5.00
42 3.75
43 3.75
44
45 Process finished with exit code 0

```

Listing 9: Output of Question 2 program (q2.txt).

```

1  === Question 2(a)(b) ===
2  Equivalent resistance for 2x4 mesh: 1875.00 Ohms.
3  Runtime: 0.000999927520752 s.
4  Equivalent resistance for 3x6 mesh: 2379.55 Ohms.
5  Runtime: 0.018000125885 s.
6  Equivalent resistance for 4x8 mesh: 2741.03 Ohms.
7  Runtime: 0.102999925613 s.
8  Equivalent resistance for 5x10 mesh: 3022.82 Ohms.
9  Runtime: 0.406000137329 s.
10 Equivalent resistance for 6x12 mesh: 3253.68 Ohms.
11 Runtime: 1.26799988747 s.
12 Equivalent resistance for 7x14 mesh: 3449.17 Ohms.
13 Runtime: 3.23900008202 s.
14 Equivalent resistance for 8x16 mesh: 3618.67 Ohms.
15 Runtime: 7.42700004578 s.
16 Equivalent resistance for 9x18 mesh: 3768.29 Ohms.
17 Runtime: 15.246999979 s.
18 Equivalent resistance for 10x20 mesh: 3902.19 Ohms.
19 Runtime: 29.0559999943 s.
20 === Question 2(c) ===
21 Equivalent resistance for 2x4 mesh: 1875.00 Ohms.
22 Runtime: 0.00200009346008 s.
23 Equivalent resistance for 3x6 mesh: 2379.55 Ohms.
24 Runtime: 0.0160000324249 s.
25 Equivalent resistance for 4x8 mesh: 2741.03 Ohms.
26 Runtime: 0.095999956131 s.
27 Equivalent resistance for 5x10 mesh: 3022.82 Ohms.
28 Runtime: 0.391999959946 s.
29 Equivalent resistance for 6x12 mesh: 3253.68 Ohms.
30 Runtime: 1.21600008011 s.
31 Equivalent resistance for 7x14 mesh: 3449.17 Ohms.
32 Runtime: 3.05900001526 s.
33 Equivalent resistance for 8x16 mesh: 3618.67 Ohms.
34 Runtime: 7.0720000267 s.
35 Equivalent resistance for 9x18 mesh: 3768.29 Ohms.
36 Runtime: 14.5319998264 s.
37 Equivalent resistance for 10x20 mesh: 3902.19 Ohms.
38 Runtime: 28.1089999676 s.
39 === Question 2(d) ===
40
41 Process finished with exit code 0

```

Listing 10: Output of Question 3 program (q3.txt).

```

1  === Question 3(b) ===
2  Omega: 1.0
3  Initial guess:
4
5  0.00  4.14  6.37  15.00  15.00  15.00  15.00
6  0.00  4.27  6.71  15.00  15.00  15.00  15.00
7  0.00  4.05  6.27  15.00  15.00  15.00  15.00
8  0.00  3.53  5.30  7.20  9.41  10.65  9.50
9  0.00  2.81  4.18  5.30  6.27  6.71  6.37
10 0.00  1.73  2.81  3.53  4.05  4.27  4.14
11 0.00  0.00  0.00  0.00  0.00  0.00  0.00

```

```

12 Num iterations: 32
13 Potential at (0.06, 0.04): 5.526 V
14 Relaxed:
15
16 0.00 3.96 8.56 15.00 15.00 15.00 15.00
17 0.00 4.25 9.09 15.00 15.00 15.00 15.00
18 0.00 3.96 8.56 15.00 15.00 15.00 15.00
19 0.00 3.03 6.18 9.25 10.29 10.55 10.29
20 0.00 1.97 3.88 5.53 6.37 6.61 6.37
21 0.00 0.96 1.86 2.61 3.04 3.17 3.04
22 0.00 0.00 0.00 0.00 0.00 0.00 0.00
23 Omega: 1.1
24 Initial guess:
25
26 0.00 4.14 6.37 15.00 15.00 15.00 15.00
27 0.00 4.27 6.71 15.00 15.00 15.00 15.00
28 0.00 4.05 6.27 15.00 15.00 15.00 15.00
29 0.00 3.53 5.30 7.20 9.41 10.65 9.50
30 0.00 2.81 4.18 5.30 6.27 6.71 6.37
31 0.00 1.73 2.81 3.53 4.05 4.27 4.14
32 0.00 0.00 0.00 0.00 0.00 0.00 0.00
33 Num iterations: 26
34 Potential at (0.06, 0.04): 5.526 V
35 Relaxed:
36
37 0.00 3.96 8.56 15.00 15.00 15.00 15.00
38 0.00 4.25 9.09 15.00 15.00 15.00 15.00
39 0.00 3.96 8.56 15.00 15.00 15.00 15.00
40 0.00 3.03 6.18 9.25 10.29 10.55 10.29
41 0.00 1.97 3.88 5.53 6.37 6.61 6.37
42 0.00 0.96 1.86 2.61 3.04 3.17 3.04
43 0.00 0.00 0.00 0.00 0.00 0.00 0.00
44 Omega: 1.2
45 Initial guess:
46
47 0.00 4.14 6.37 15.00 15.00 15.00 15.00
48 0.00 4.27 6.71 15.00 15.00 15.00 15.00
49 0.00 4.05 6.27 15.00 15.00 15.00 15.00
50 0.00 3.53 5.30 7.20 9.41 10.65 9.50
51 0.00 2.81 4.18 5.30 6.27 6.71 6.37
52 0.00 1.73 2.81 3.53 4.05 4.27 4.14
53 0.00 0.00 0.00 0.00 0.00 0.00 0.00
54 Num iterations: 20
55 Potential at (0.06, 0.04): 5.526 V
56 Relaxed:
57
58 0.00 3.96 8.56 15.00 15.00 15.00 15.00
59 0.00 4.25 9.09 15.00 15.00 15.00 15.00
60 0.00 3.96 8.56 15.00 15.00 15.00 15.00
61 0.00 3.03 6.18 9.25 10.29 10.55 10.29
62 0.00 1.97 3.88 5.53 6.37 6.61 6.37
63 0.00 0.96 1.86 2.61 3.04 3.17 3.04
64 0.00 0.00 0.00 0.00 0.00 0.00 0.00
65 Omega: 1.3
66 Initial guess:
67
68 0.00 4.14 6.37 15.00 15.00 15.00 15.00
69 0.00 4.27 6.71 15.00 15.00 15.00 15.00
70 0.00 4.05 6.27 15.00 15.00 15.00 15.00
71 0.00 3.53 5.30 7.20 9.41 10.65 9.50
72 0.00 2.81 4.18 5.30 6.27 6.71 6.37
73 0.00 1.73 2.81 3.53 4.05 4.27 4.14
74 0.00 0.00 0.00 0.00 0.00 0.00 0.00
75 Num iterations: 14
76 Potential at (0.06, 0.04): 5.526 V
77 Relaxed:
78
79 0.00 3.96 8.56 15.00 15.00 15.00 15.00
80 0.00 4.25 9.09 15.00 15.00 15.00 15.00
81 0.00 3.96 8.56 15.00 15.00 15.00 15.00

```

```

82      0.00  3.03  6.18  9.25 10.29 10.55 10.29
83      0.00  1.97  3.88  5.53  6.37  6.61  6.37
84      0.00  0.96  1.86  2.61  3.04  3.17  3.04
85      0.00  0.00  0.00  0.00  0.00  0.00  0.00
86  Omega: 1.4
87  Initial guess:
88
89      0.00  4.14  6.37 15.00 15.00 15.00 15.00
90      0.00  4.27  6.71 15.00 15.00 15.00 15.00
91      0.00  4.05  6.27 15.00 15.00 15.00 15.00
92      0.00  3.53  5.30  7.20  9.41 10.65  9.50
93      0.00  2.81  4.18  5.30  6.27  6.71  6.37
94      0.00  1.73  2.81  3.53  4.05  4.27  4.14
95      0.00  0.00  0.00  0.00  0.00  0.00  0.00
96  Num iterations: 16
97  Potential at (0.06, 0.04): 5.526 V
98  Relaxed:
99
100     0.00  3.96  8.56 15.00 15.00 15.00 15.00
101     0.00  4.25  9.09 15.00 15.00 15.00 15.00
102     0.00  3.96  8.56 15.00 15.00 15.00 15.00
103     0.00  3.03  6.18  9.25 10.29 10.55 10.29
104     0.00  1.97  3.88  5.53  6.37  6.61  6.37
105     0.00  0.96  1.86  2.61  3.04  3.17  3.04
106     0.00  0.00  0.00  0.00  0.00  0.00  0.00
107  Omega: 1.5
108  Initial guess:
109
110     0.00  4.14  6.37 15.00 15.00 15.00 15.00
111     0.00  4.27  6.71 15.00 15.00 15.00 15.00
112     0.00  4.05  6.27 15.00 15.00 15.00 15.00
113     0.00  3.53  5.30  7.20  9.41 10.65  9.50
114     0.00  2.81  4.18  5.30  6.27  6.71  6.37
115     0.00  1.73  2.81  3.53  4.05  4.27  4.14
116     0.00  0.00  0.00  0.00  0.00  0.00  0.00
117  Num iterations: 20
118  Potential at (0.06, 0.04): 5.526 V
119  Relaxed:
120
121     0.00  3.96  8.56 15.00 15.00 15.00 15.00
122     0.00  4.25  9.09 15.00 15.00 15.00 15.00
123     0.00  3.96  8.56 15.00 15.00 15.00 15.00
124     0.00  3.03  6.18  9.25 10.29 10.55 10.29
125     0.00  1.97  3.88  5.53  6.37  6.61  6.37
126     0.00  0.96  1.86  2.61  3.04  3.17  3.04
127     0.00  0.00  0.00  0.00  0.00  0.00  0.00
128  Omega: 1.6
129  Initial guess:
130
131     0.00  4.14  6.37 15.00 15.00 15.00 15.00
132     0.00  4.27  6.71 15.00 15.00 15.00 15.00
133     0.00  4.05  6.27 15.00 15.00 15.00 15.00
134     0.00  3.53  5.30  7.20  9.41 10.65  9.50
135     0.00  2.81  4.18  5.30  6.27  6.71  6.37
136     0.00  1.73  2.81  3.53  4.05  4.27  4.14
137     0.00  0.00  0.00  0.00  0.00  0.00  0.00
138  Num iterations: 27
139  Potential at (0.06, 0.04): 5.526 V
140  Relaxed:
141
142     0.00  3.96  8.56 15.00 15.00 15.00 15.00
143     0.00  4.25  9.09 15.00 15.00 15.00 15.00
144     0.00  3.96  8.56 15.00 15.00 15.00 15.00
145     0.00  3.03  6.18  9.25 10.29 10.55 10.29
146     0.00  1.97  3.88  5.53  6.37  6.61  6.37
147     0.00  0.96  1.86  2.61  3.04  3.17  3.04
148     0.00  0.00  0.00  0.00  0.00  0.00  0.00
149  Omega: 1.7
150  Initial guess:
151

```



```

152    0.00    4.14    6.37    15.00    15.00    15.00    15.00
153    0.00    4.27    6.71    15.00    15.00    15.00    15.00
154    0.00    4.05    6.27    15.00    15.00    15.00    15.00
155    0.00    3.53    5.30    7.20    9.41    10.65    9.50
156    0.00    2.81    4.18    5.30    6.27    6.71    6.37
157    0.00    1.73    2.81    3.53    4.05    4.27    4.14
158    0.00    0.00    0.00    0.00    0.00    0.00    0.00
159    Num iterations: 39
160    Potential at (0.06, 0.04): 5.526 V
161    Relaxed:
162
163    0.00    3.96    8.56    15.00    15.00    15.00    15.00
164    0.00    4.25    9.09    15.00    15.00    15.00    15.00
165    0.00    3.96    8.56    15.00    15.00    15.00    15.00
166    0.00    3.03    6.18    9.25    10.29    10.55    10.29
167    0.00    1.97    3.88    5.53    6.37    6.61    6.37
168    0.00    0.96    1.86    2.61    3.04    3.17    3.04
169    0.00    0.00    0.00    0.00    0.00    0.00    0.00
170    Omega: 1.8
171    Initial guess:
172
173    0.00    4.14    6.37    15.00    15.00    15.00    15.00
174    0.00    4.27    6.71    15.00    15.00    15.00    15.00
175    0.00    4.05    6.27    15.00    15.00    15.00    15.00
176    0.00    3.53    5.30    7.20    9.41    10.65    9.50
177    0.00    2.81    4.18    5.30    6.27    6.71    6.37
178    0.00    1.73    2.81    3.53    4.05    4.27    4.14
179    0.00    0.00    0.00    0.00    0.00    0.00    0.00
180    Num iterations: 60
181    Potential at (0.06, 0.04): 5.526 V
182    Relaxed:
183
184    0.00    3.96    8.56    15.00    15.00    15.00    15.00
185    0.00    4.25    9.09    15.00    15.00    15.00    15.00
186    0.00    3.96    8.56    15.00    15.00    15.00    15.00
187    0.00    3.03    6.18    9.25    10.29    10.55    10.29
188    0.00    1.97    3.88    5.53    6.37    6.61    6.37
189    0.00    0.96    1.86    2.61    3.04    3.17    3.04
190    0.00    0.00    0.00    0.00    0.00    0.00    0.00
191    Omega: 1.9
192    Initial guess:
193
194    0.00    4.14    6.37    15.00    15.00    15.00    15.00
195    0.00    4.27    6.71    15.00    15.00    15.00    15.00
196    0.00    4.05    6.27    15.00    15.00    15.00    15.00
197    0.00    3.53    5.30    7.20    9.41    10.65    9.50
198    0.00    2.81    4.18    5.30    6.27    6.71    6.37
199    0.00    1.73    2.81    3.53    4.05    4.27    4.14
200    0.00    0.00    0.00    0.00    0.00    0.00    0.00
201    Num iterations: 127
202    Potential at (0.06, 0.04): 5.526 V
203    Relaxed:
204
205    0.00    3.96    8.56    15.00    15.00    15.00    15.00
206    0.00    4.25    9.09    15.00    15.00    15.00    15.00
207    0.00    3.96    8.56    15.00    15.00    15.00    15.00
208    0.00    3.03    6.18    9.25    10.29    10.55    10.29
209    0.00    1.97    3.88    5.53    6.37    6.61    6.37
210    0.00    0.96    1.86    2.61    3.04    3.17    3.04
211    0.00    0.00    0.00    0.00    0.00    0.00    0.00
212    Best number of iterations: 14
213    Best omega: 1.3
214    === Question 3(c): SOR ===
215    h: 0.02
216    1/h: 50.0
217    Num iterations: 14
218    Potential at (0.06, 0.04): 5.526 V
219    h: 0.01
220    1/h: 100.0
221    Num iterations: 59

```

```

222 Potential at (0.06, 0.04): 5.351 V
223 h: 0.005
224 1/h: 200.0
225 Num iterations: 189
226 Potential at (0.06, 0.04): 5.289 V
227 h: 0.0025
228 1/h: 400.0
229 Num iterations: 552
230 Potential at (0.06, 0.04): 5.265 V
231 h: 0.00125
232 1/h: 800.0
233 Num iterations: 1540
234 Potential at (0.06, 0.04): 5.254 V
235 h: 0.000625
236 1/h: 1600.0
237 Num iterations: 4507
238 Potential at (0.06, 0.04): 5.247 V
239 === Question 3(d): Jacobi ===
240 h: 0.02
241 Num iterations: 51
242 Potential at (0.06, 0.04): 5.526 V
243 h: 0.01
244 Num iterations: 180
245 Potential at (0.06, 0.04): 5.351 V
246 h: 0.005
247 Num iterations: 604
248 Potential at (0.06, 0.04): 5.289 V
249 h: 0.0025
250 Num iterations: 1935
251 Potential at (0.06, 0.04): 5.265 V
252 h: 0.00125
253 Num iterations: 5836
254 Potential at (0.06, 0.04): 5.254 V
255 h: 0.000625
256 Num iterations: 16864
257 Potential at (0.06, 0.04): 5.246 V
258 Total runtime: 1791.6730001
259
260 Process finished with exit code 0

```