Lab 5 Report

Team Members:

- Shuang Wu (wu1716@purdue.edu)
 - \circ Implement v1 and shared functionality in 1ib.
 - Write and edit the report with plots.
- Alex Hsu (hsu248@purdue.edu)
 - Implement logging for audiocli and audiosrv.
- Li-Yen Yen (yenl@purdue.edu)
 - Implement bonus with self-defined congestion control method E.

Problem 1.5 Performance evaluation

Plots

Method C with pp.au

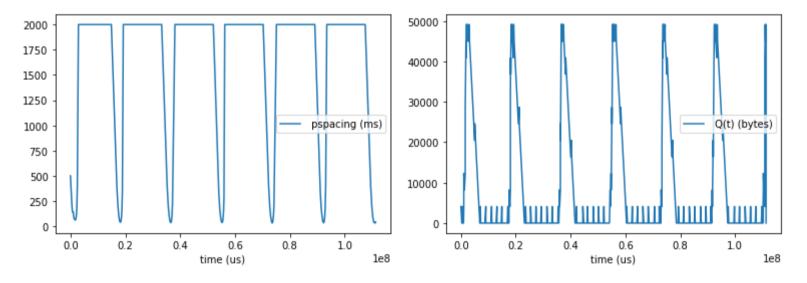
On one server:

```
./audiosrv 128.10.112.135 22222 2 logsrv
```

One one client:

```
./audiocli 128.10.112.135 22222 pp.au 4096 12 6 2 0 logcli
```

- Block size: 4096 bytes
- Buffer size: 48 KB (12 * 4096 bytes)
- Target buffer size: 24KB (6 * 4096 bytes)
- Initial influx rate: 2 packets/s
- Method C
 - Epsilon: 0.5



Method D with pp.au

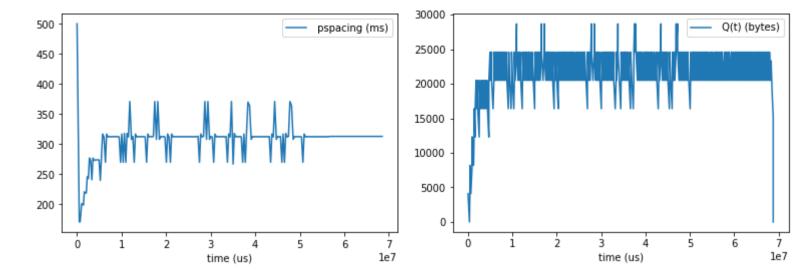
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- Initial influx rate: 2 packets/s
- Method D
 - Epsilon: 0.5
 - Beta: 1.1



Method C with kj.au

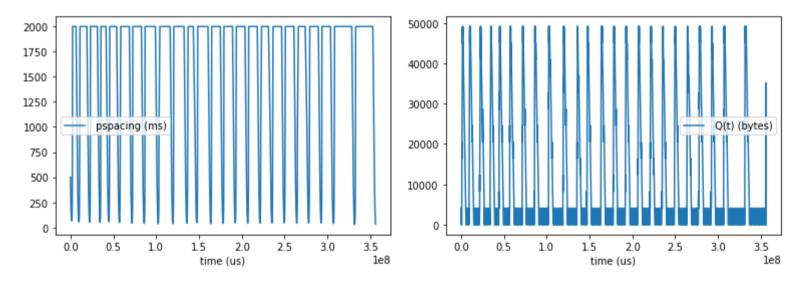
On one server:

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One one client:

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 - Epsilon: 0.5



Method D with kj.au

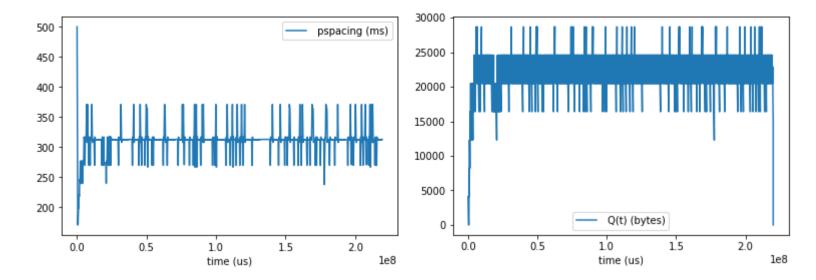
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Analysis

According to the plots, the influx rate (pspacing) and buffer load are unstable with congestion control method C for both files. This causes the audio playing intermittently as the buffer gets empty or full periodically.

On the other hand, with method D, the pspacing and buffer load are both stable though some fluctuations occur due to the network status. Thus, the audio plays smoothly without getting the buffer empty or full.

Bonus Problem

Definition of Method E

To improving the method D, we decide to implement the derivative term of the PID controller. The formula is derived as follows.

$$\lambda(t) = K_p e(t) + K_i \int_0^{\tau} e(\tau) d\tau + K_d \frac{d}{dt} e(t)$$

We can differentiate both sides of the equation.

$$\frac{d}{dt}\lambda(t) = -K_p(\lambda(t) - \gamma) + K_i(Q^* - Q(t)) - K_d\frac{d}{dt}\lambda(t)$$

Assuming Kd is always larger or equal to zero, we can transpose the derivative term and finally get the lambda(t + 1).

$$\lambda(t+1) = \lambda(t) + \frac{-K_{p}(\lambda(t) - \gamma) + K_{i}(Q^{*} - Q(t))}{(1 + K_{d})}$$

Plots

Method E with pp.au

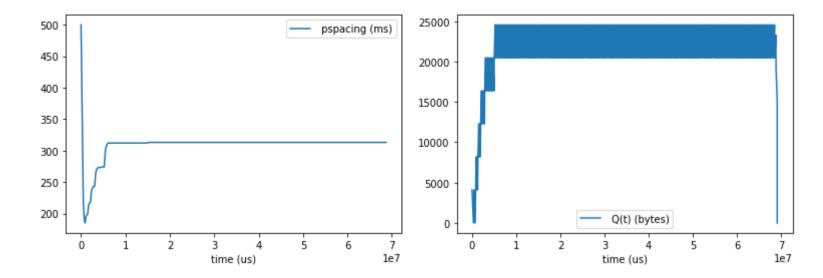
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- Method E
 - Epsilon: 0.5
 - Beta: 1.1
 - Alpha: 0.5



Method E with kj.au

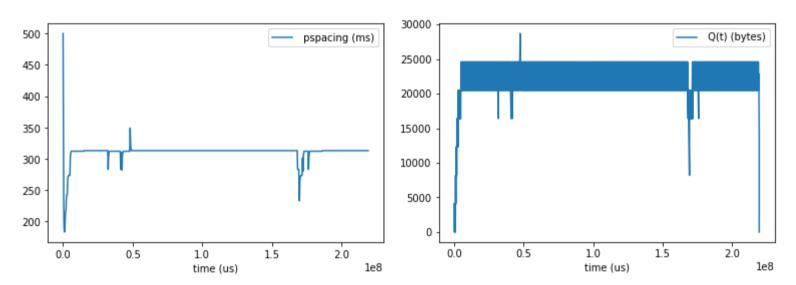
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Analysis

After apply the "D" term of the PID formula, the plots indicate that the transmission is more stable compared to the plots of method D. Though there are several unstable events possibility caused by the network status at the time, the overall congestion control performance is better than other methods.