

# Solution of Quantum Graphs by Physics-Informed DeepONets

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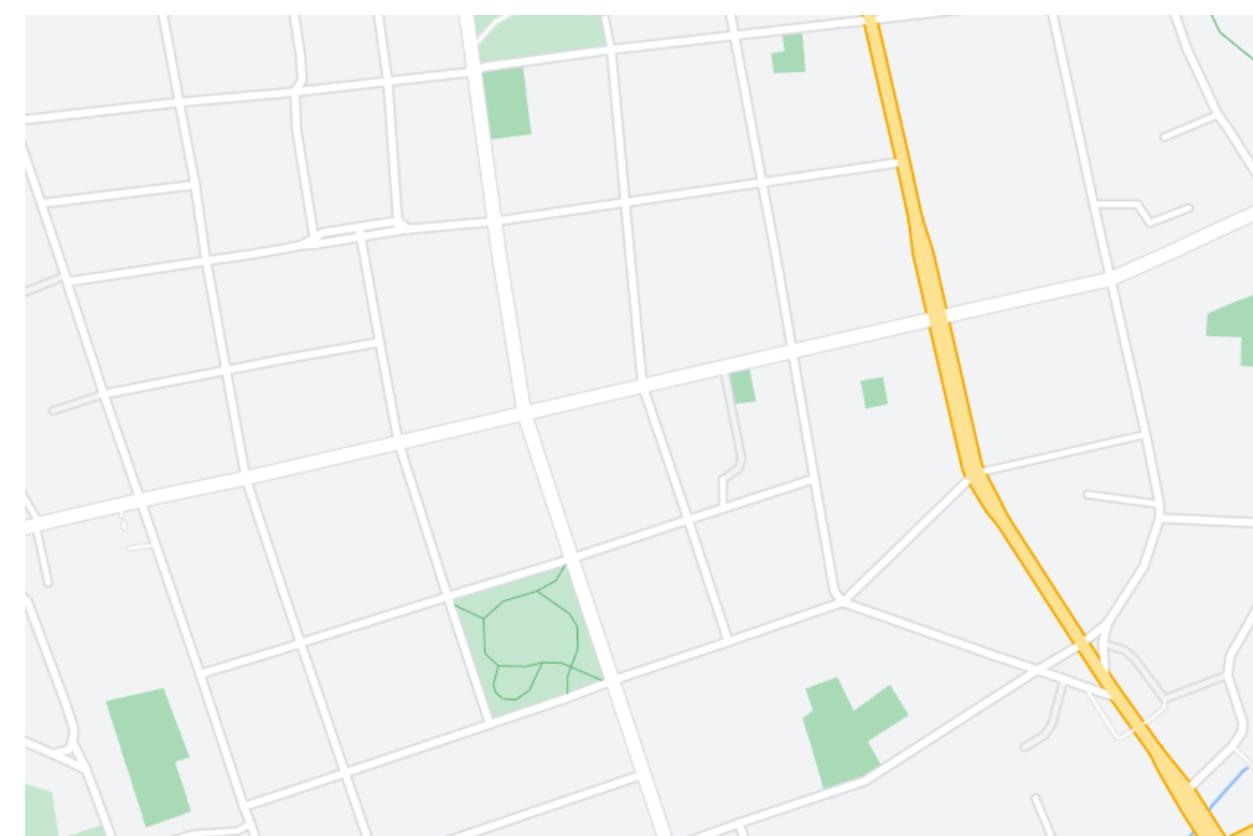
## Abstract

We focus on a machine learning approach for **quantum graphs**, i.e. metric graphs with an associated differential operator.

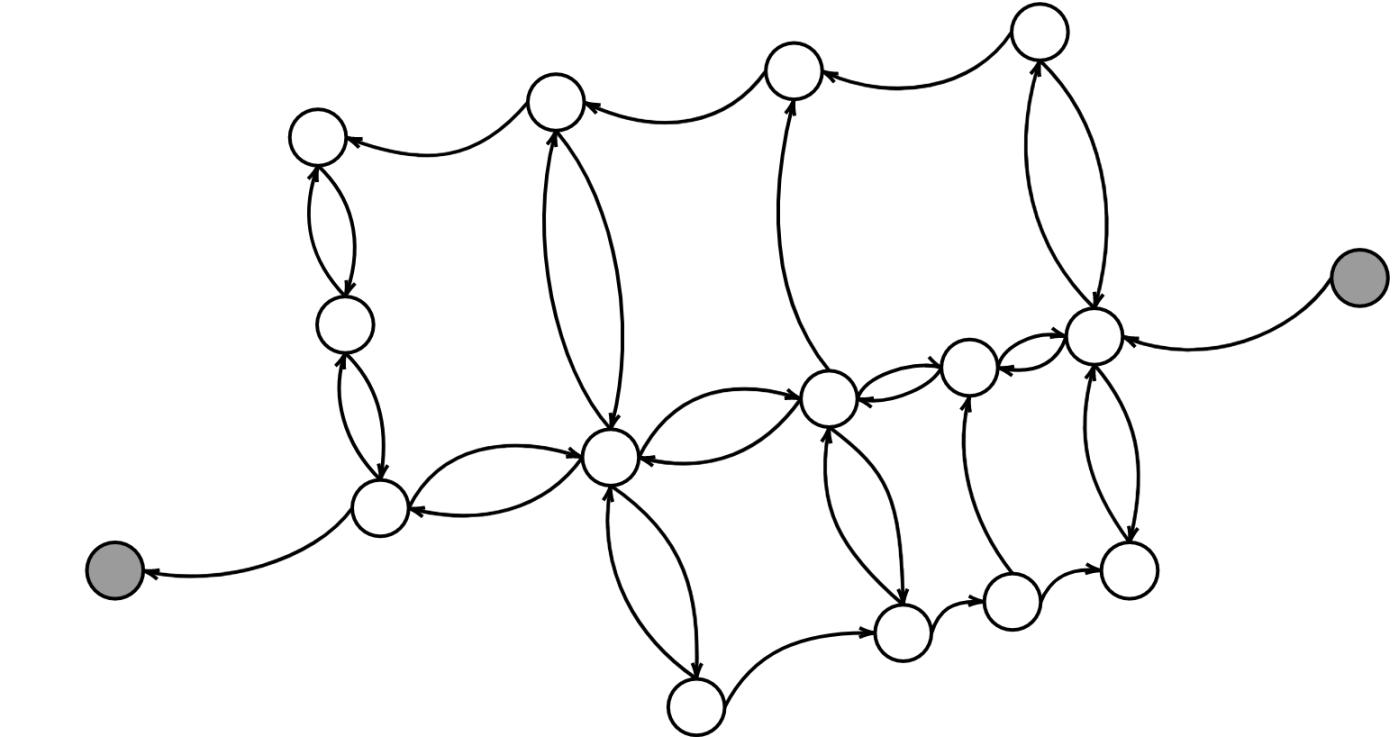
In our case the differential equation is a **nonlinear drift-diffusion equation**. Computational methods for quantum graphs require a careful discretization of the differential operator that also incorporates the node conditions, in our case **Kirchhoff-Neumann** conditions. Traditional numerical schemes are rather mature but have to be tailored manually when the differential equation becomes the constraint in an optimization problem.

We train **physics-informed DeepONet** models on a simple reference graph and show how to combine them for the solution of quantum graphs.

## Example: Road network map with modeling metric graph



(a) A street network in Chemnitz, Saxony, Germany. Image from Google maps. Central point coordinates: 50.83, 12.90.



(b) A metric graph modeling a compact road network within the left road network. Empty circles are interior vertices while filled ones depict exterior ones.

## Quantum Graph Model: PDE, initial conditions ...

Given a graph  $\Gamma = (\mathcal{V}, \mathcal{E})$  consisting of vertices  $v \in \mathcal{V}$  and edges  $e \in \mathcal{E}$  with associated lengths  $\ell_e > 0$ , we consider the non-linear drift-diffusion equation

$$\partial_t \rho_e = \partial_x(\epsilon \partial_x \rho_e - f(\rho_e)), \quad \text{for all } x \in (0, \ell_e), e \in \mathcal{E},$$

with  $f(\rho) = \rho(1 - \rho)$  and *initial conditions*

$$\rho_e(0, x) = u_e^{\text{init}}(x), \quad \text{for all } x \in (0, \ell_e), e \in \mathcal{E}.$$

## ... and coupling conditions

Furthermore, there hold *homogeneous Kirchhoff-Neumann cond's and continuity*

$$\sum_{e \in \mathcal{E}_v} J_e(v) n_e(v) = 0 \quad \text{and} \quad \rho_e(v) = \rho_{e'}(v), \quad \text{for all } e, e' \in \mathcal{E}_v, v \in \mathcal{V}_K \subset \mathcal{V},$$

with  $J_e = -\epsilon \partial_x \rho_e + f(\rho_e)$  and *flux boundary conditions (inflow and outflow)*

$$\sum_{e \in \mathcal{E}_v} J_e(v) n_e(v) = -u_v^{\text{inflow}}(t)(1 - \rho_v) + u_v^{\text{outflow}}(t)\rho_v, \quad \text{for all } v \in \mathcal{V}_D := \mathcal{V} \setminus \mathcal{V}_K.$$

## 1st step – Learning an edge surrogate model on a reference graph by physics-informed DeepONets

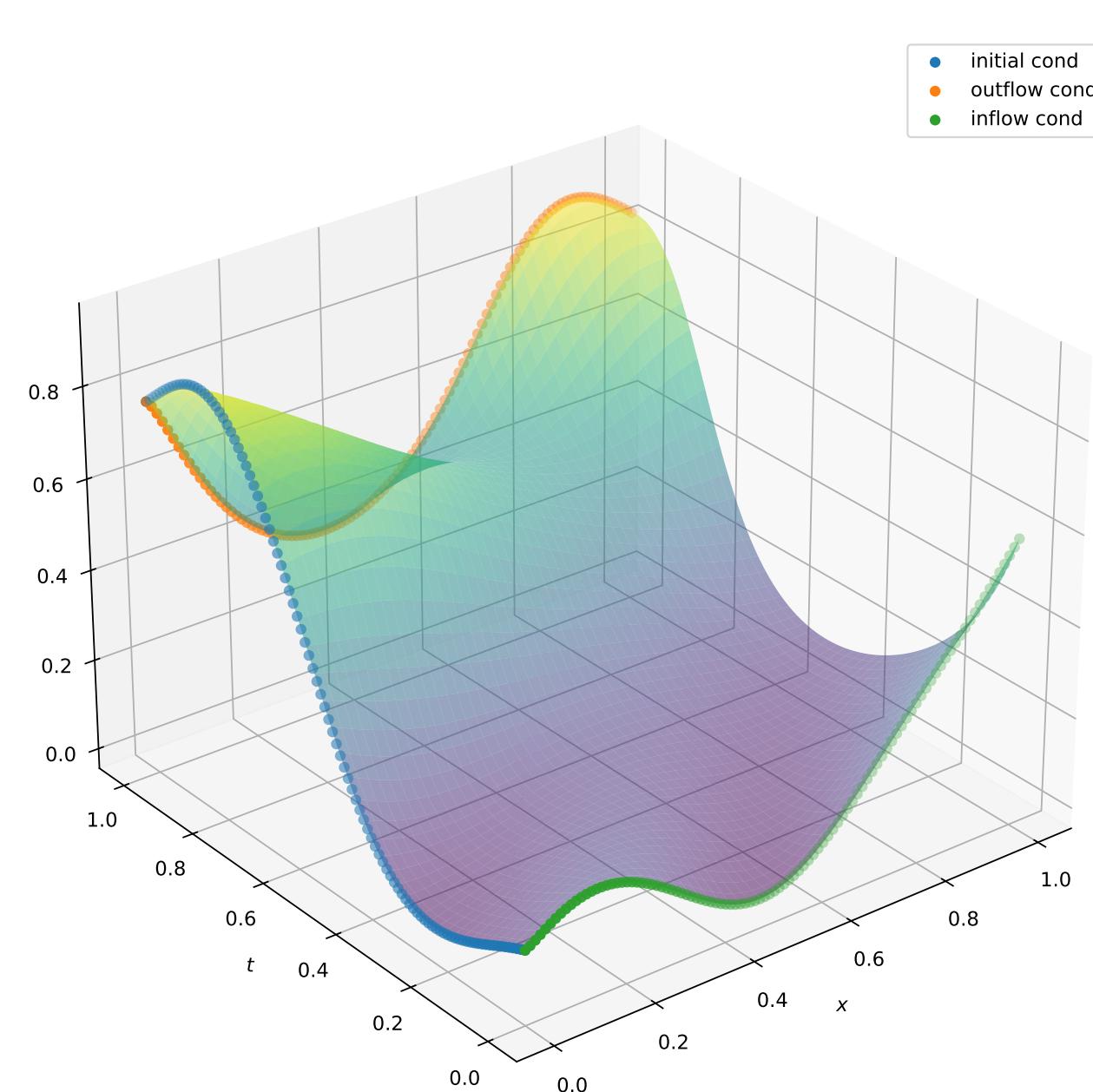


Figure: Illustration of random GP training data.

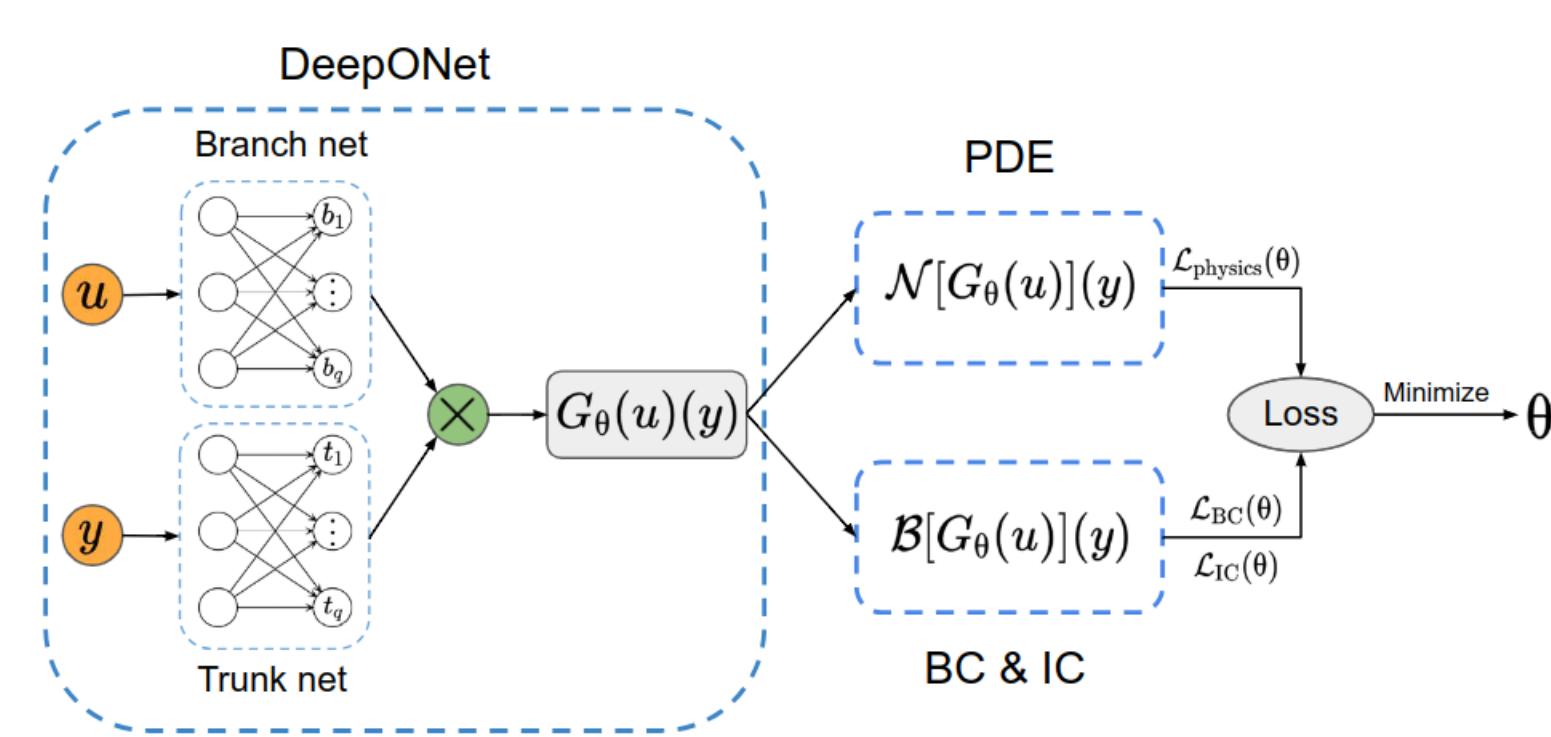


Figure: Illustration of PIDeepONet taken from [1].

Learning of an operator approximation  $G_\theta(u)(y)$  by minimization of

$$\mathcal{L}_{\text{physics}}(\theta; u, y) + \mathcal{L}_{\text{init}}(\theta; u, y) + \mathcal{L}_{\text{flow}}(\theta; u, y)$$

using 5K training samples, 10K steps of ADAM, **no** Kirchhoff-Neumann and continuity cond's here.

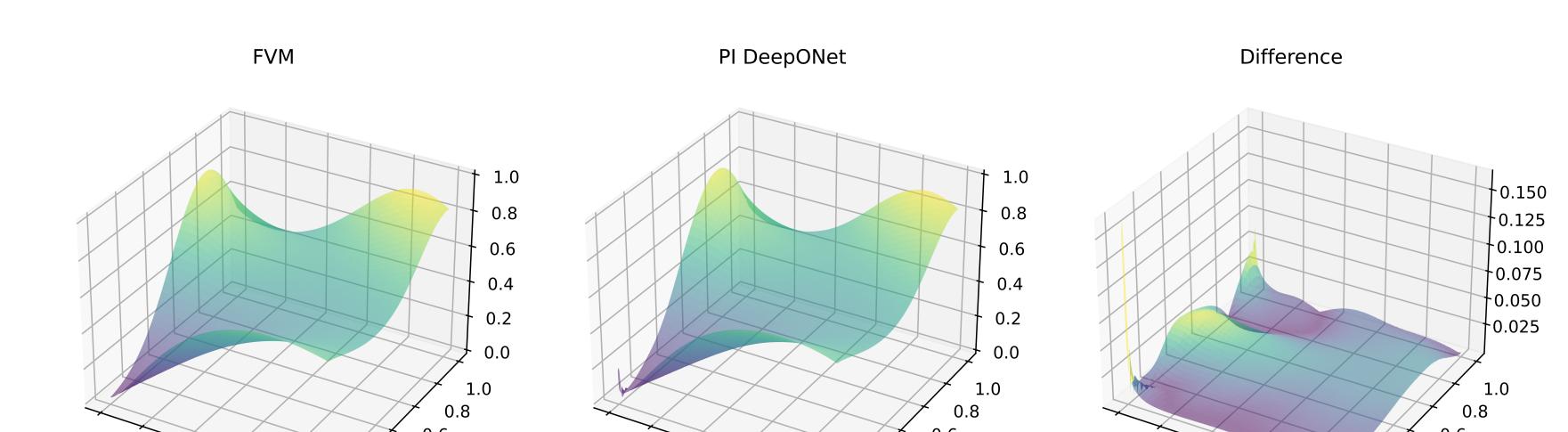


Figure: Example solution on reference edge by FVM (left), PI DeepONet (middle), abs. difference (right)

**Result 1st step:** Approximation of the nonlinear drift-diffusion operator which maps

$$(u, y) = ((u_{\text{inflow}}, u_{\text{outflow}}, u_{\text{init}}), (t, x)) \mapsto \hat{\rho}_e^u(t, x)$$

for  $(t, x) \in [0, 1] \times [0, 1]$ , i.e., its solution on reference edge.

## 2nd Step – Applying the model to more complex graphs and ensuring coupling conditions (KN, continuity, in-/outflow)

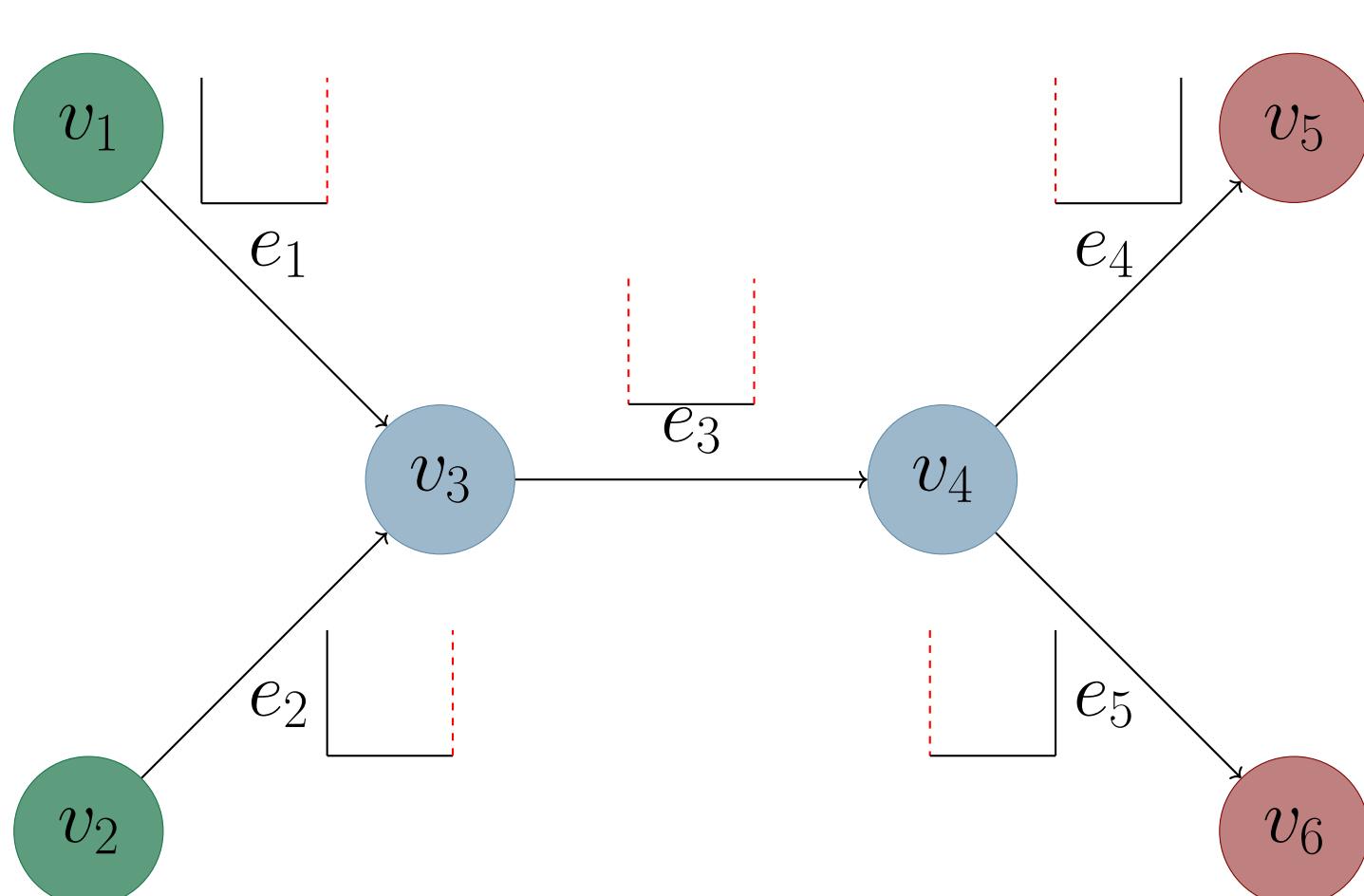


Figure: Model metric graph with known (solid black) and unknown data (dashed red).

Learning unknown flow parameters  $z \in \mathbb{R}^{m \times n_t}$  with  $m = \sum_{v \in \mathcal{V}_K} |\mathcal{E}_v|$  by minimization of

$$\underbrace{\sum_{v \in \mathcal{V}_K} \sum_{e, e' \in \mathcal{E}_v} (\hat{\rho}_e^u(z)(v) - \hat{\rho}_{e'}^u(z)(v))^2}_{\text{continuity loss}} + \underbrace{\sum_{v \in \mathcal{V}_K} \left( \sum_{e \in \mathcal{E}_v} (\hat{J}_e^u(z)(v) n_e(v))^2 \right)^2}_{\text{Kirchhoff-Neumann loss}} + \lambda \underbrace{\sum_{v \in \mathcal{V}_K} \sum_{e \in \mathcal{E}_v} \|z_{v,e}\|_{H^1}^2}_{\text{regularization}}$$

- ▶ approach allows for solution of inverse problems by incorporation of measured data
- ▶ faster and more flexible than PINN approach considered in [3].

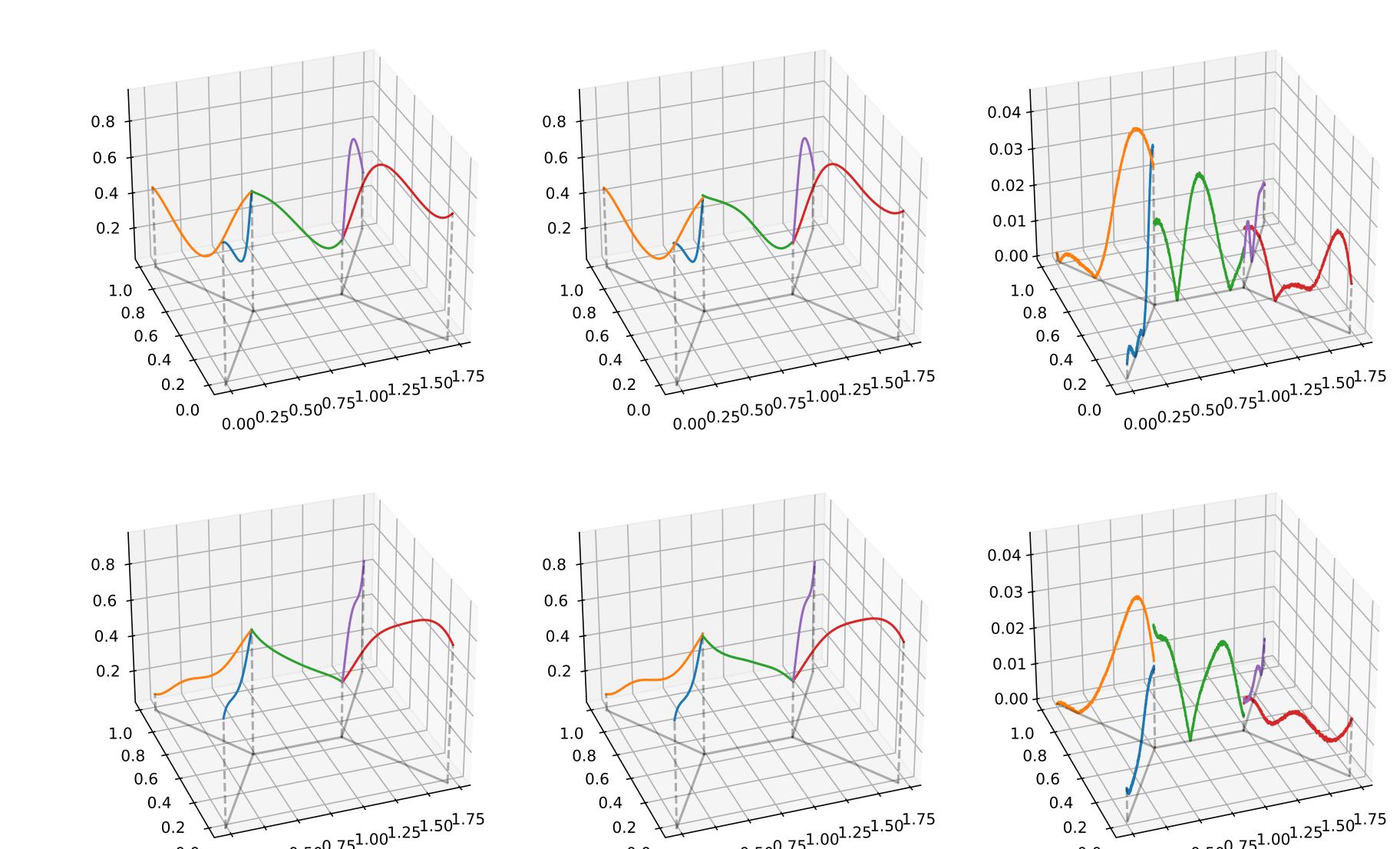


Figure: Solution on model graph at  $t = 0.25$  and  $t = 0.75$  by FVM (left), PI DeepONet (middle), abs. difference (right)

[1] S. Wang, H. Wang, and P. Perdikaris.

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[2] L. Lu, P. Jin, G. Pang, Z. Zhang, and G. E. Karniadakis.

Learning nonlinear operators via deeponet based on the universal approximation theorem of operators.  
*Nature machine intelligence*, 3(3):218–229, 2021.

[3] J. Blechschmidt, J.-F. Pietschmann, T.-C. Riemer, M. Stoll, and M. Winkler.

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