

# Decomposing physics-informed neural networks

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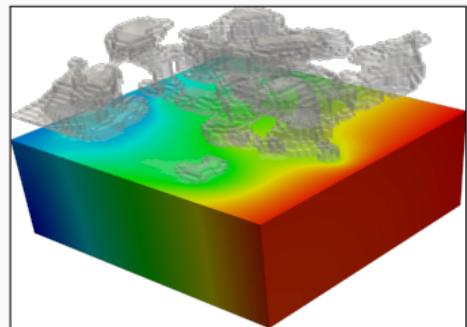
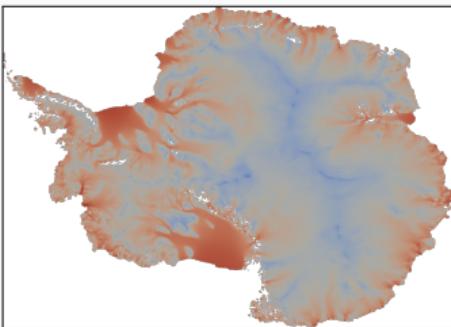
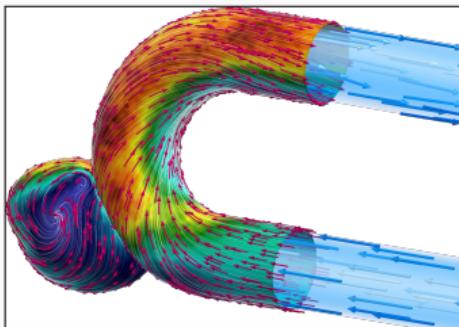
Alexander Heinlein<sup>1</sup>

Dutch Computational Science Day, Utrecht, November 10, 2023

<sup>1</sup>Delft University of Technology

Based on joint work with Victorita Dolean (University of Strathclyde & University Côte d'Azur) and Sid Mishra and Ben Moseley (ETH Zürich)

# Scientific Machine Learning in Computational Science and Engineering



## Numerical methods

### Based on physical models

- + Robust and generalizable
- Require availability of mathematical models

## Machine learning models

### Driven by data

- + Do not require mathematical models
- Sensitive to data, limited extrapolation capabilities

## Scientific machine learning (SciML)

Combining the strengths and compensating the weaknesses of the individual approaches:

numerical methods	<b>improve</b>	machine learning techniques
machine learning techniques	<b>assist</b>	numerical methods

# Lagaris et. al's Method – Motivation

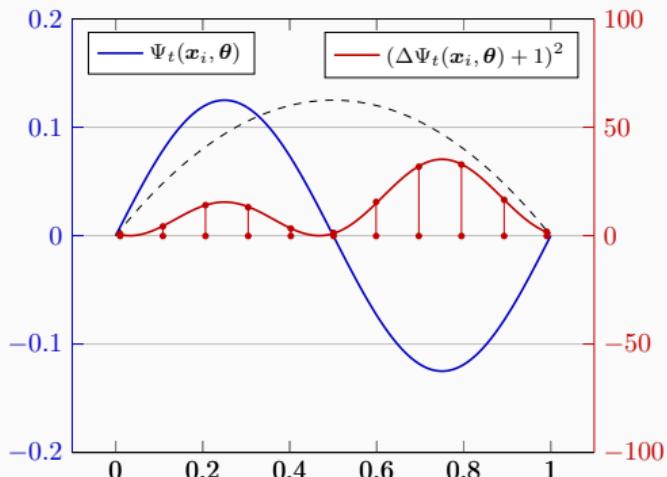
Solve the boundary value problem

$$\Delta \Psi_t(x, \theta) + 1 = 0, \quad \text{on } [0, 1],$$

$$\Psi_t(0, \theta) = \Psi_t(1, \theta) = 0,$$

via a **collocation approach**:

$$\min_{\theta} \sum_{x_i} (\Delta \Psi_t(x_i, \theta) + 1)^2$$

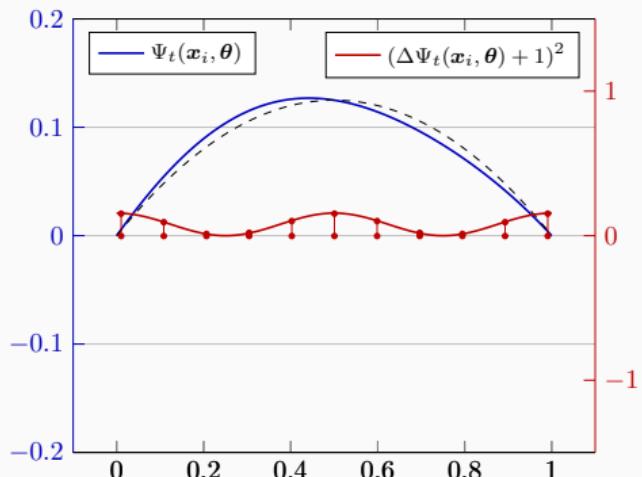


$$(\Delta \Psi_t(x_i, \theta) + 1)^2 \gg 0$$

## Boundary conditions

The boundary conditions can be **enforced explicitly**, for instance, via the ansatz:

$$\Psi_t(x, \theta) = \sin(\pi x) \cdot F(x, N(x, \theta))$$



$$(\Delta \Psi_t(x_i, \theta) + 1)^2 \approx 0$$

# Physics-Informed Neural Networks (PINNs)

Physics-informed neural networks (PINNs) by Raissi et al. (2019) are based on the approach by Lagaris et al. (1998). The main novelty of PINNs is the use of a **hybrid loss function**:

$$\mathcal{L} = \omega_{\text{data}} \mathcal{L}_{\text{data}} + \omega_{\text{PDE}} \mathcal{L}_{\text{PDE}},$$

where  $\omega_{\text{data}}$  and  $\omega_{\text{PDE}}$  are **weights** and

$$\mathcal{L}_{\text{data}} = \frac{1}{N_{\text{data}}} \sum_{i=1}^{N_{\text{data}}} (u(\hat{x}_i, \hat{t}_i) - u_i)^2,$$

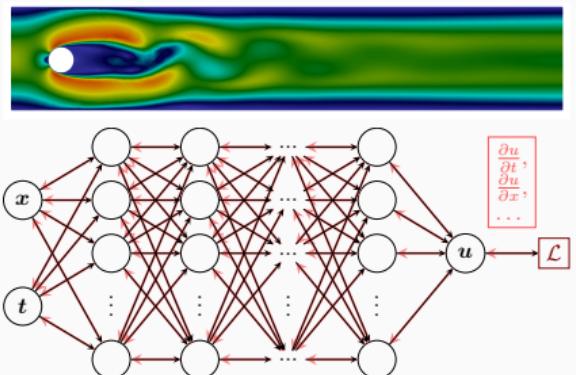
$$\mathcal{L}_{\text{PDE}} = \frac{1}{N_{\text{PDE}}} \sum_{i=1}^{N_{\text{PDE}}} (\Delta u(x_i, t) + 1)^2.$$

## Advantages

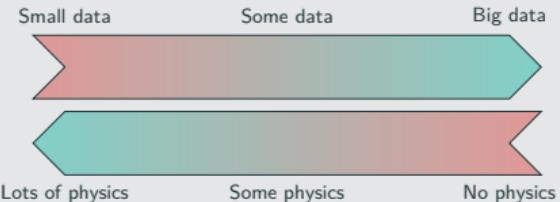
- “Meshfree”
- Small data
- Generalization properties
- High-dimensional problems
- Inverse and parameterized problems

## Drawbacks

- Training cost and robustness
- Convergence not well-understood
- Difficulties with scalability and multi-scale problems



## Hybrid loss



- Known solution values can be included in  $\mathcal{L}_{\text{data}}$
- Initial and boundary conditions are also included in  $\mathcal{L}_{\text{data}}$

# Motivation – Some Observations on the Performance of PINNs

Solve

$$\begin{aligned} u' &= \cos(\omega x), \\ u(0) &= 0, \end{aligned}$$

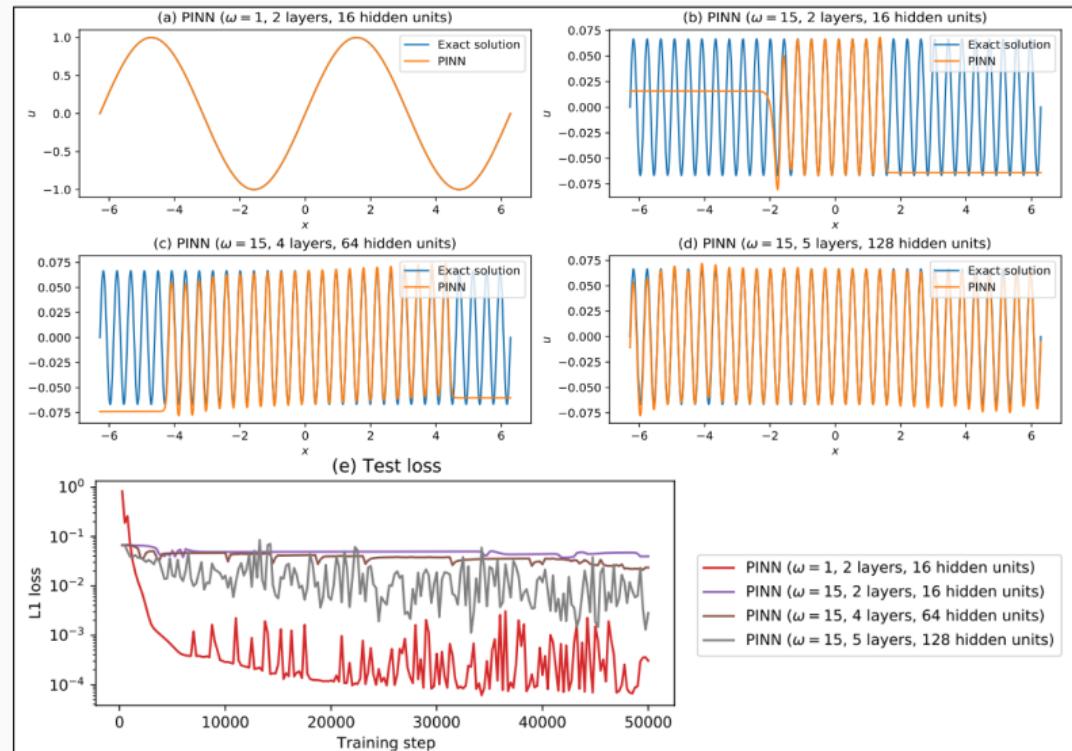
for different values of  $\omega$   
using PINNs with  
varying network  
capacities.

## Scaling issues

- Large computational domains
- Small frequencies

(related to so-called  
spectral bias)

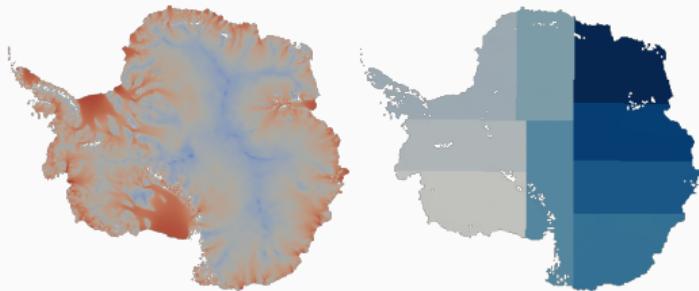
Cf. Moseley, Markham, and  
Nissen-Meyer (2023)



(a) 321 free parameters

(d) 66 433 free parameters

# Domain Decomposition Methods



Images based on Heinlein, Perego, Rajamanickam (2022)

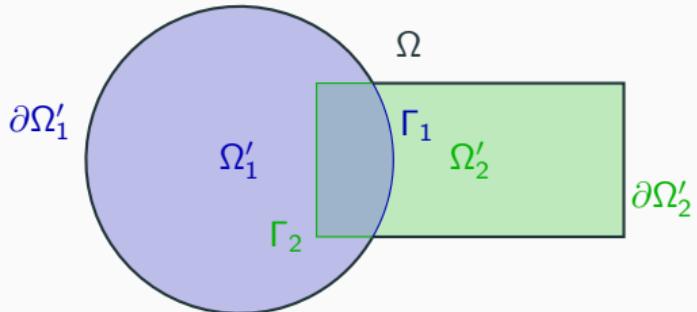
**Historical remarks:** The **alternating Schwarz method** is the earliest **domain decomposition method (DDM)**, which has been invented by **H. A. Schwarz** and published in **1870**:

- Schwarz used the algorithm to establish the **existence of harmonic functions** with prescribed boundary values on **regions with non-smooth boundaries**.

## Idea

Decomposing a large **global problem** into smaller **local problems**:

- Better robustness** and **scalability** of numerical solvers
- Improved computational efficiency**
- Introduce **parallelism**



# Finite Basis Physics-Informed Neural Networks (FBPINNs)

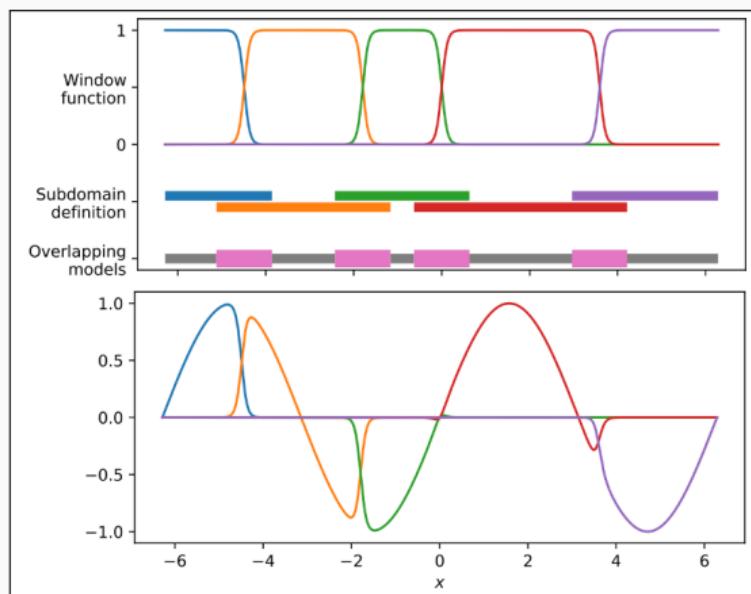
Finite basis physics informed neural network (FBPINNs) method introduced in [Moseley, Markham, and Nissen-Meyer \(2023\)](#) use the network architecture

$$u(\theta_1, \dots, \theta_J) = \mathcal{C} \sum_{j=1}^J \omega_j u_j(\theta_j)$$

and the loss function

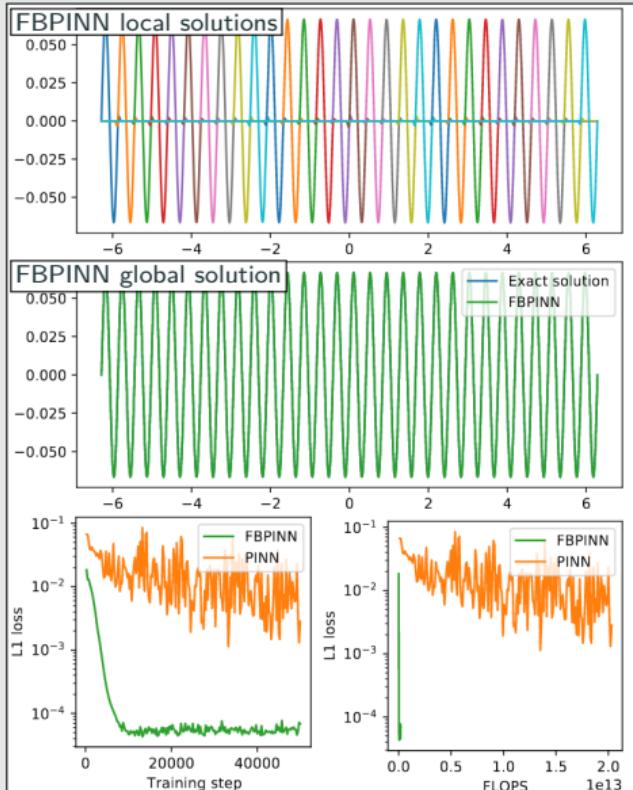
$$\mathcal{L}(\theta_1, \dots, \theta_J) = \frac{1}{N} \sum_{i=1}^N \left( n[\mathcal{C} \sum_{x_i \in \Omega_j} \omega_j u_j(x_i, \theta_j) - f(x_i)] \right)^2.$$

using window functions  $\omega_j$  with  $\text{supp}(\omega_j) \subset \Omega_j$  and  $\sum_{j=1}^J \omega_j \equiv 1$  on  $\Omega$ .



# Numerical Results for FBPINNs

## PINN vs FBPINN (Moseley et al. (2023))



## Scalability of FBPINNs

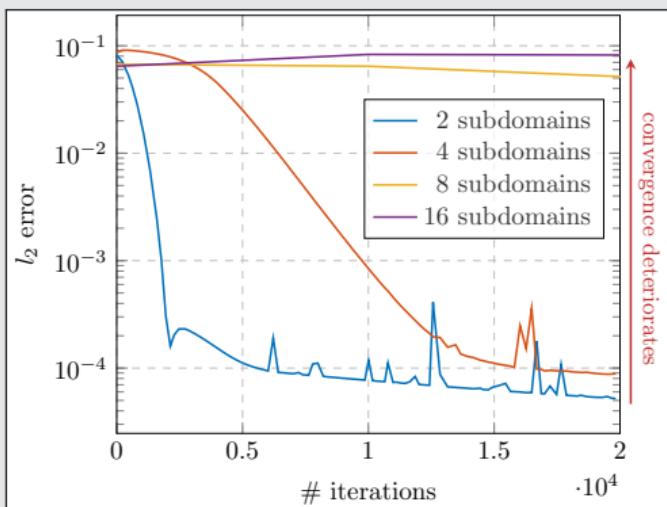
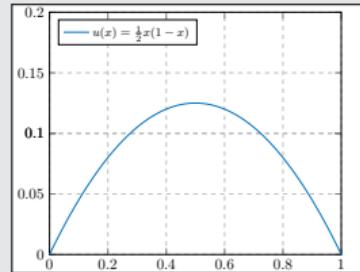
Consider the simple boundary value problem

$$-u'' = 1 \quad \text{in } [0, 1],$$

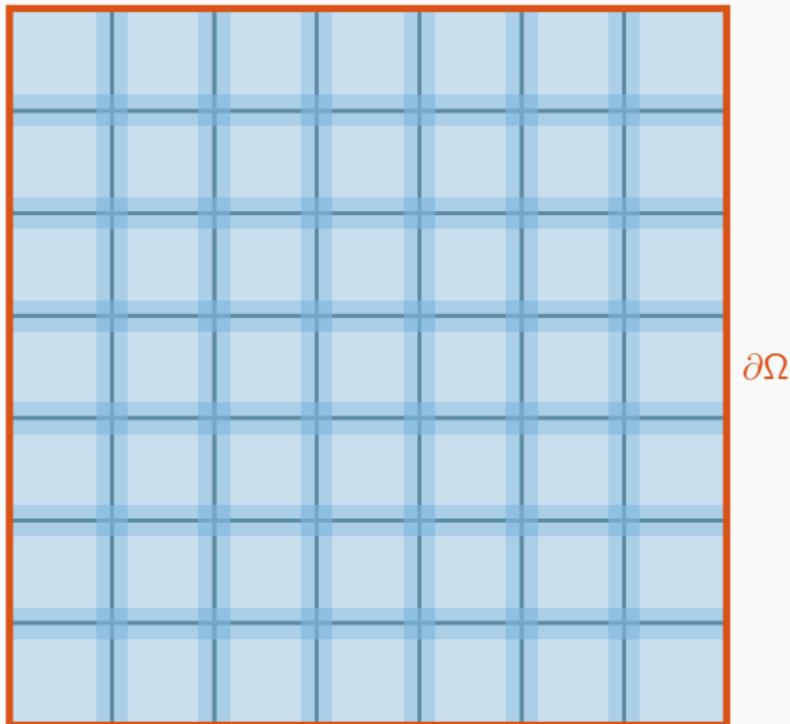
$$u(0) = u(1) = 0,$$

which has the solution

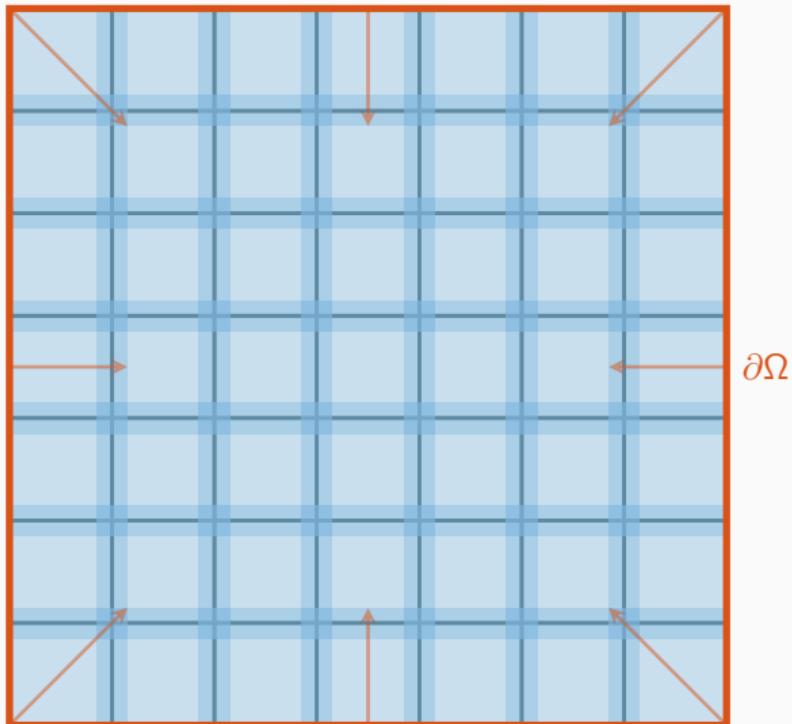
$$u(x) = \frac{1}{2}x(1 - x).$$



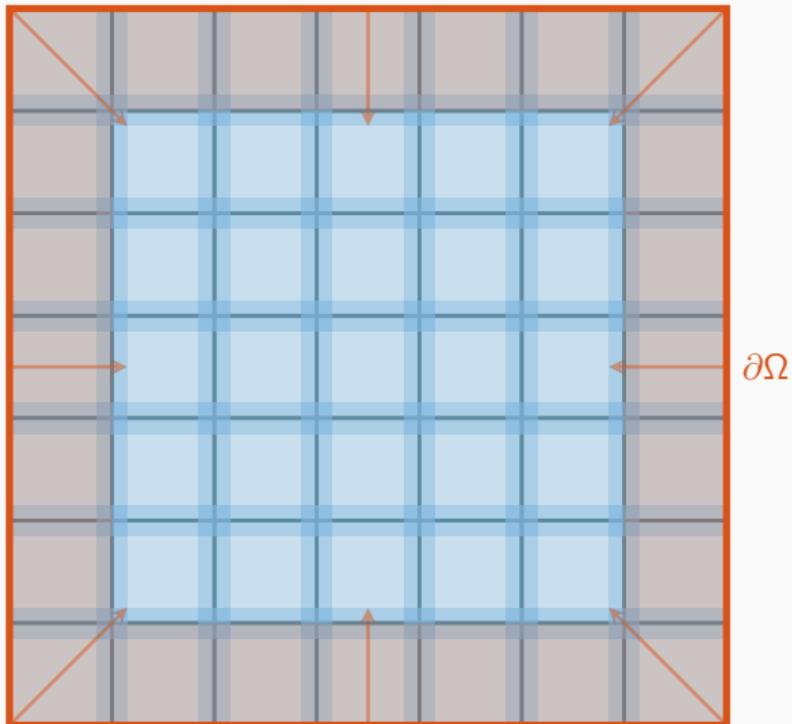
# Transport of Information in the One-Level FBPINN Algorithm



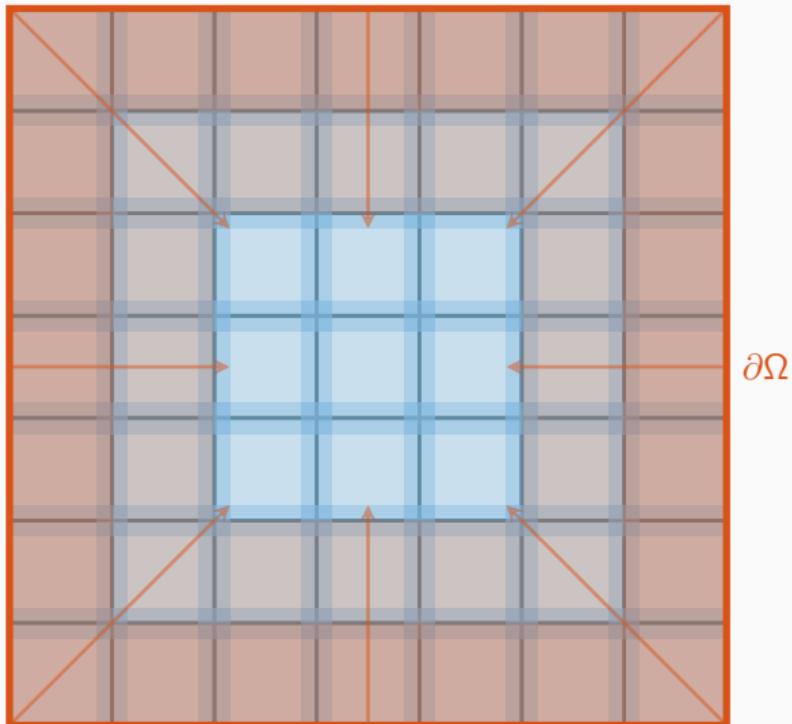
# Transport of Information in the One-Level FBPINN Algorithm



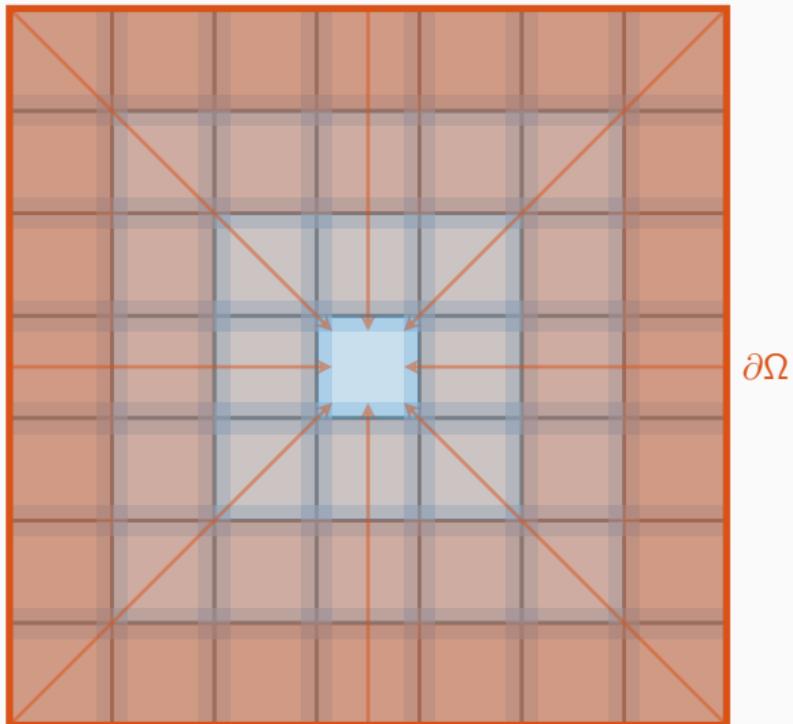
# Transport of Information in the One-Level FBPINN Algorithm



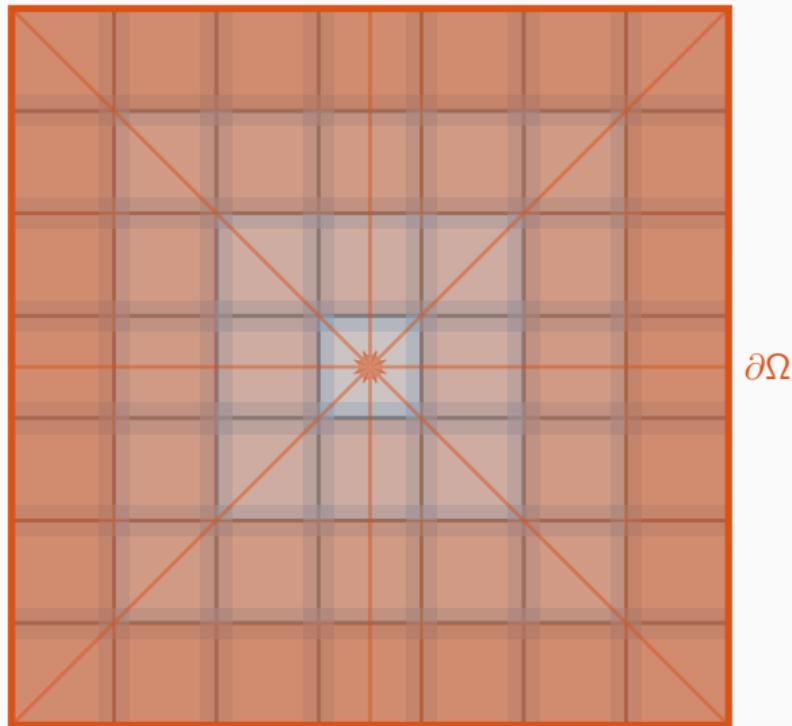
# Transport of Information in the One-Level FBPINN Algorithm



# Transport of Information in the One-Level FBPINN Algorithm



# Transport of Information in the One-Level FBPINN Algorithm



Information (in particular, boundary data) is **only exchanged via the overlapping regions**, leading to **slow convergence** → establish a faster / global transport of information.

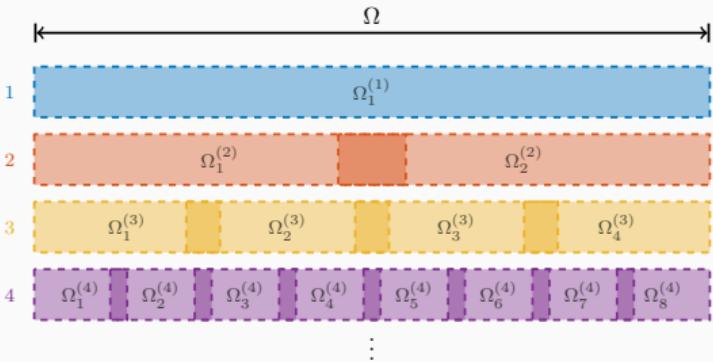
# Multi-Level FBPINN Algorithm

We introduce a **hierarchy of  $L$  overlapping domain decompositions**

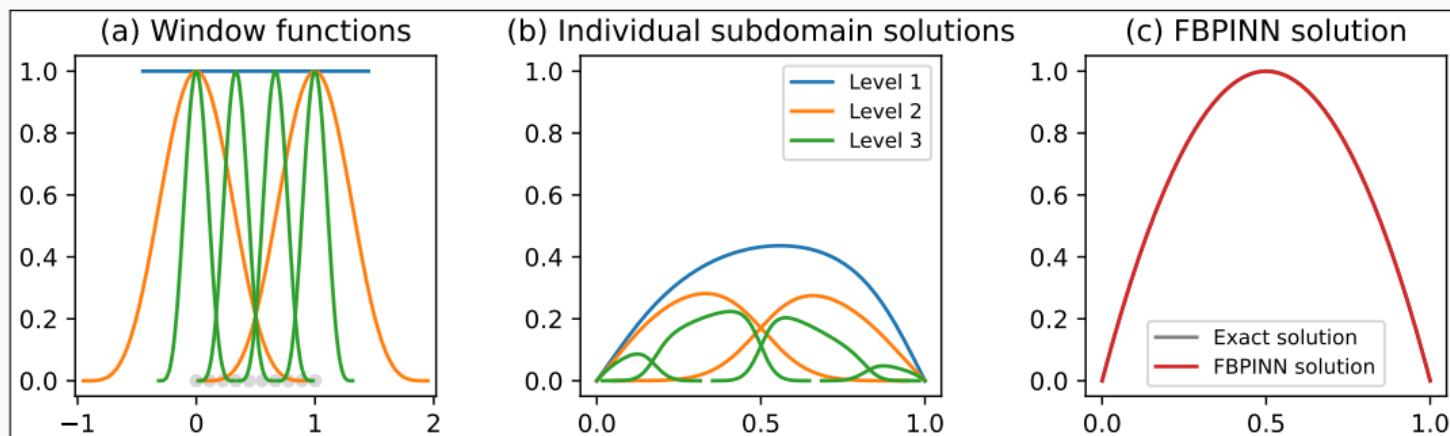
$$\Omega = \bigcup_{j=1}^{J^{(l)}} \Omega_j^{(l)}$$

and corresponding window functions  $\omega_j^{(l)}$  with

$$\text{supp}(\omega_j^{(l)}) \subset \Omega_j^{(l)} \text{ and } \sum_{j=1}^{J^{(l)}} \omega_j^{(l)} \equiv 1 \text{ on } \Omega.$$



This yields the  **$L$ -level FBPINN algorithm**:



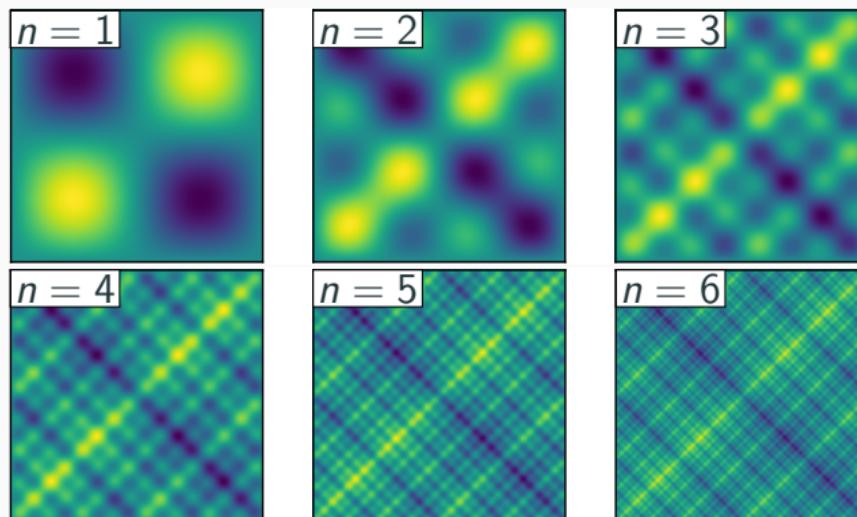
# Multi-Frequency Problem

Let us now consider the two-dimensional multi-frequency Laplace boundary value problem

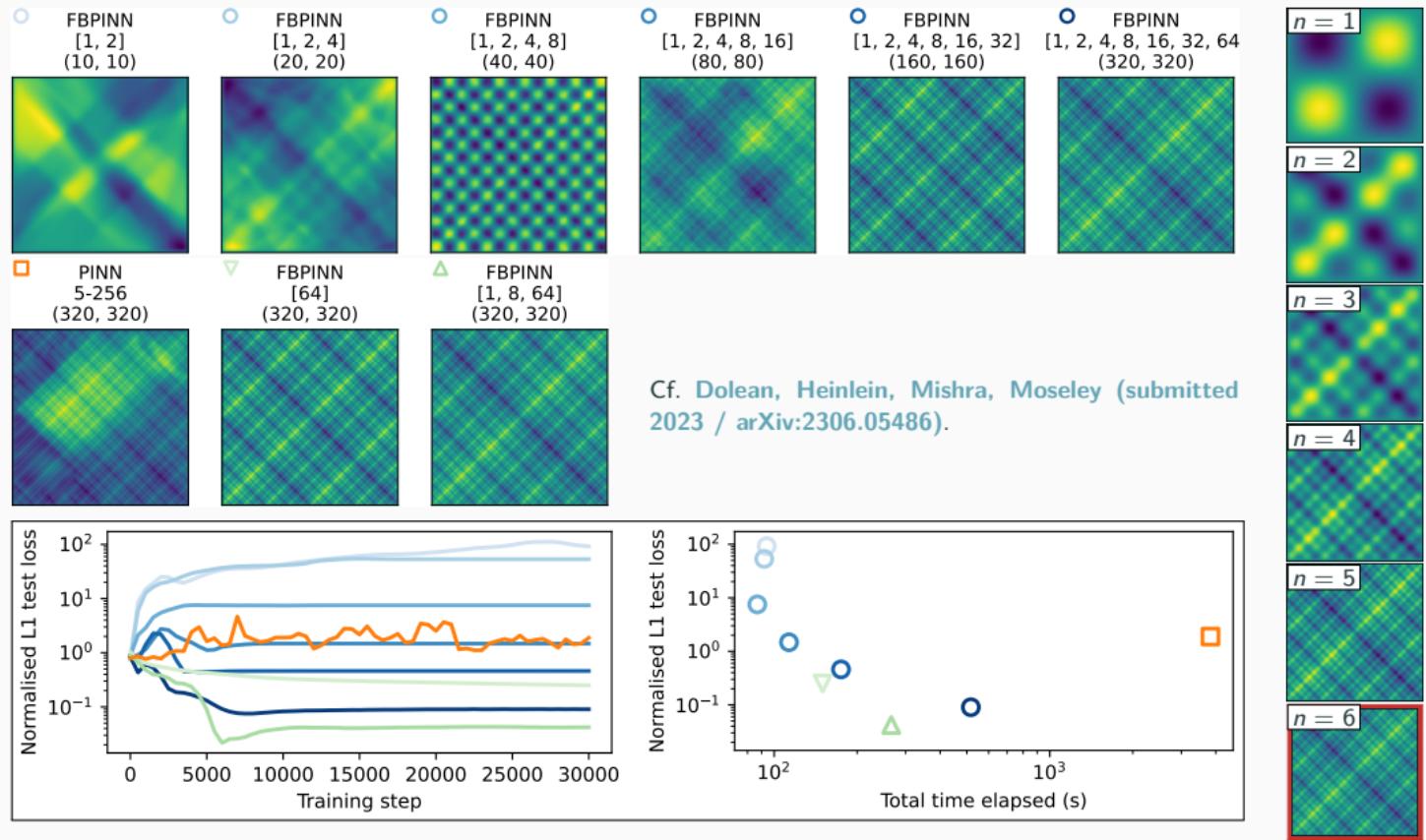
$$\begin{aligned} -\Delta u &= 2 \sum_{i=1}^n (\omega_i \pi)^2 \sin(\omega_i \pi x) \sin(\omega_i \pi y) && \text{in } \Omega = [0, 1]^2, \\ u &= 0 && \text{on } \partial\Omega, \end{aligned}$$

with  $\omega_i = 2^i$ .

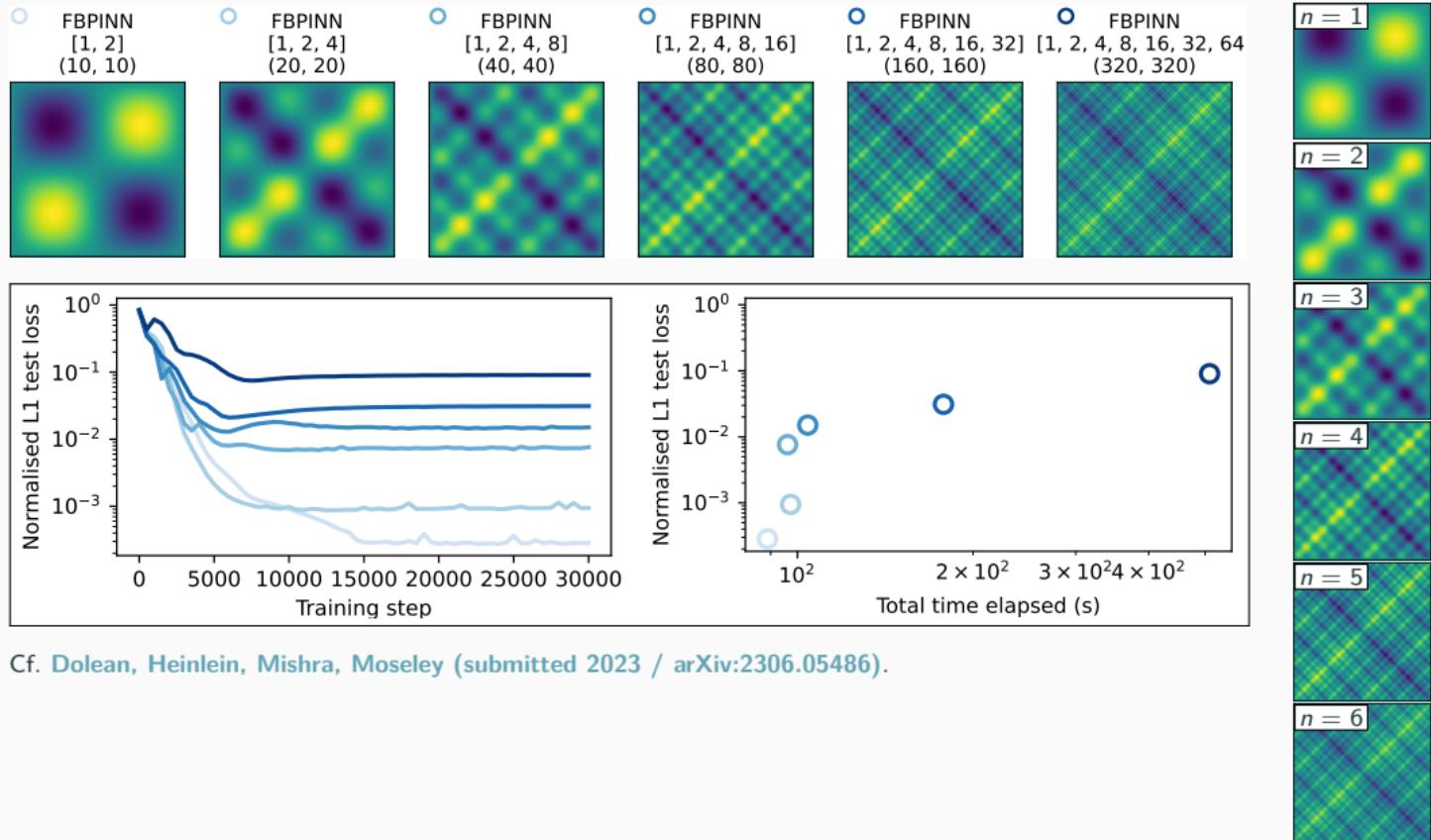
For increasing values of  $n$ , we obtain the **analytical solutions**:



# Multi-Level FBPINNs for a Multi-Frequency Problem – Strong Scaling

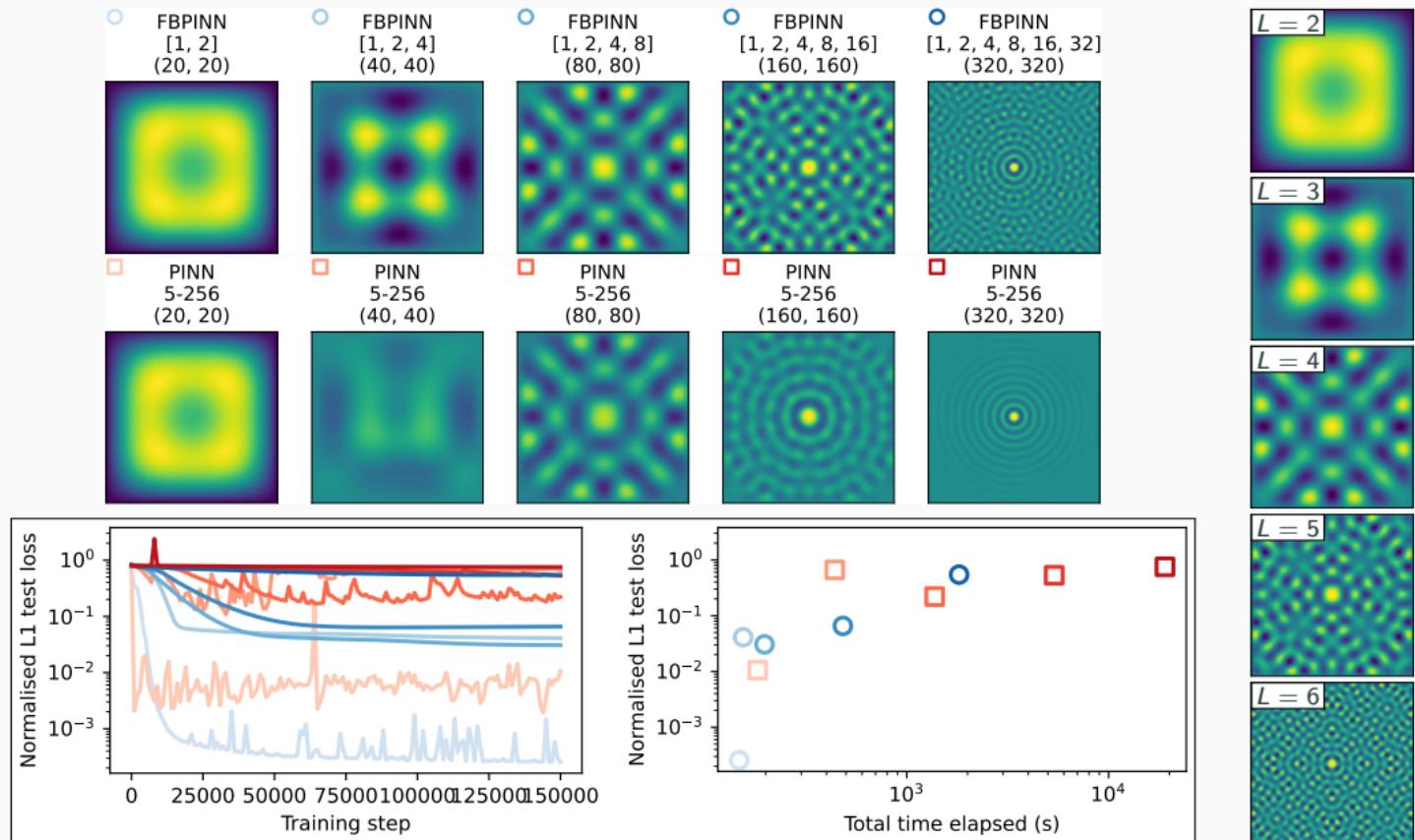


# Multi-Level FBPINNs for a Multi-Frequency Problem – Weak Scaling



Cf. Dolean, Heinlein, Mishra, Moseley (submitted 2023 / arXiv:2306.05486).

# Multi-Level FBPINNs for the Helmholtz Problem – Weak Scaling



# SRI “Bridging Numerical Analysis and Machine Learning” Event

## Workshop – Scientific Machine Learning

Dates: December 6 – 9, 2023

Location: CWI, Amsterdam

### Invited speakers

- Machine-learning-enhanced numerical methods,  
physics-informed machine learning
  - Jan Hesthaven (EPFL Lausanne),
  - Stefania Fresca (Politecnico di Milano)
- Scientific computing for machine learning
  - Sid Mishra (ETH Zurich)
  - Andrea Walther (Humboldt University Berlin)
- Scientific machine learning in applications
  - Dirk Hartmann (Siemens)
  - Elías Cueto (Universidad de Zaragoza)

### Organizers

- Benjamin Sanderse (CWI)
- Mengwu Guo (University of Twente)
- Alexander Heinlein (TU Delft)

