



Competitive Programming Reference

First, solve the problem. Then, write the code.

John Johnson

By

Sergio Gabriel Sanchez Valencia

gabrielsanv97@gmail.com

searleser97

Contents

Coding Resources	5
C++	5
Competitive Programming Template	5
Include All Libraries	5
IO Optimization	5
Number To String	5
Output Format	5
Permutations	5
Print Vector	6
Priority Queue Of Object	6
Random	6
Read Line	6
Secure Hash	6
Set of Object	6
Sort Vector Of Object	6
Sort Vector of Pairs	6
Split String	7
String To Int	7
Typedef	7
Unordered Map with pair as key	7
Python	7
Combinations	7
Fast IO	7
Permutations	7
Random	7
Sort List	7
Sort List Of Object	8
BITs Manipulation	8
Bit Count	8
Bits To Int	8
Count Leading Zeroes	8
Count Set Bits	8
Count Trailing Zeroes	8
Divide By 2	8
Is Even	8
Is i-th Bit Set	8
Is Odd	8
Is Power Of 2	9
Least Significant Set Bit	9
Log2	9
Modulo With Power Of 2	9
Most Significant Set Bit	9
Multiply By 2	9
One's Complement	9
Parity Check	9
Print Bits	9
Set i-th Bit	9
Swap Integer Variables	9
To Lower Case	9
To Upper Case	9
Toggle Case	9
Toggle i-th Bit	9
Two's Complement	9
Unset i-th Bit	9
XOR From 1 To N	10

Geometry	10
Data Structures	10
Circle	10
Point	10
Intersection Points Of Segments In A Plane	11
Is Point In Line	11
Is Point In Segment	11
Is Point Inside Polygon	11
Line-Line Intersection	11
Line-Segment Intersection	11
Max Interval Overlap	11
Point Projection On Line	12
Point Reflection On Line	12
Point-Line Distance	12
Point-Line Distance (Signed)	12
Segment-Segment Intersection	12
Sort Points Along Line With Direction	13
Graphs	13
Data Structures	13
Union Find	13
Union Find (Partially Persistent)	13
Articulation Points And Bridges	13
Connected Components	14
Flood Fill	14
Heavy Light Decomposition	14
Is Bipartite	15
Lowest Common Ancestor	15
Minimum Spanning Tree Kruskal	16
Minimum Spanning Tree Prim	16
Strongly Connected Components	17
Topological Sort	17
Topological Sort (All possible sorts)	17
Topological Sort (lowest lexicographically)	18
Tree Diameter (Longest Path Between 2 Nodes)	18
Cycles	18
Get Some Cycles	18
Has Cycle	19
Flow	19
Max Flow Min Cost	19
Max Flow Min Cut Dinic	20
Max Flow Min Cut Edmonds-Karp	20
Maximum Bipartite Matching	21
Shortest Paths	21
0 - 1 BFS	21
Bellman Ford	21
Bellman Ford Fast	22
Dijkstra	22
Floyd Warshall	22
Shortest Path in Directed Acyclic Graph	23

Maths	23	Techniques	35
Data Structures	23	Array Compression (Coordinate Compression)	35
Matrix	23	Map Value To Int	35
Combinatorics	24	Binary Search	35
Binomial Coefficient	24	Binary Search	35
Binomial Coefficient (Pascal's Triangle)	24	Bitonic Search	36
Binomial Coefficient Modulo Large Prime	24	C++ lower bound	36
Factorials Modulo M	24	C++ upper bound	36
Number Theory	24	Lower Bound	36
Binary Exponentiation	24	Upper Bound	36
Convert 10-Based Number To Base B	24	Multiple Queries	36
Convert B-Based Number To Base 10	24	Mo	36
Diophantine Equation (Base Solution)	24	SQRT Decomposition	37
Diophantine Equation (Particular Solution)	25		
Divisibility Criterion	25	Trees And Heaps	38
Divisors	25	Red Black Tree	38
Divisors Pollard Rho	25	Treap	38
Euler's Phi	25	Treap (Implicit)	39
Extended Euclidean Algorithm	26		
GCD	26	Util	41
LCM	26	Ceil Of Division Between Integers	41
Modular Exponentiation	26	Compare 2 Strings	41
Modular Multiplication	26	Double Comparisons With Given Precision	41
Modular Multiplicative Inverse	26	Floor Of Division Between Integers	41
Modular Multiplicative Inverses Modulo M [1, M)	26	Get Sign Of Number	41
Modulo with negative numbers	26	Number To String	41
Primes	27		
Is Prime Miller Rabin	27	Extras	42
Prime Factorization	27	Data Structures	42
Prime Factorization (Sieve)	27	Strings	42
Prime Factorization (Sieve) 2	27	C++	42
Prime Factorization Pollard Rho	27	Automatic Type Conversions	42
Primes Sieve	28	Integer Types Properties	43
		Maths	43
		Common Sums	43
		Logarithm Rules	43
Ranges	28	Problems Solved	44
Data Structures	28	Arrays	44
BIT	28	Inversions Count	44
BIT Range Update	29	Maths	44
Segment Tree	29	N as Sum of different numbers from 1 to M	44
Segment Tree Lazy Propagation	29		
Sparse Table	30		
Wavelet Tree	30		
Strings	31		
Data Structures	31		
Suffix Automaton	31		
Trie	32		
Distinct Substring Count	33		
KMP	33		
Levenshtein Distance (Bottom-Up)	33		
Levenshtein Distance (Top-Down)	33		
Levenshtein-Damerau Distance	33		
Lexicographically K-th Substring	33		
Lexicographically Smallest Cyclic Shift	34		
Longest Common Substring of 2 Strings	34		
Longest Common Substring of Several Strings	34		
Number of Occurrences Of Several Words	34		
Occurrences Positions Of Several Words	34		
Rabin Karp	35		

Coding Resources

C++

Competitive Programming Template

```

/*****
https://searleser97.gitlab.io/algorithms/template.cpp
*****/

#include <bits/stdc++.h>
using namespace std;
#define endl '\n'
#define forr(_, x, n) for (int _ = x; _ > n; _--)
#define fos(_, x, n, s) for (int _ = x; _ < n; _ += s)
#define forn(_, x, n) fos(_, x, n, 1)
#define rep(_, n) forn(_, 0, n)
#define fi first
#define se second
#define pb push_back
#define pairii pair<int, int>
#define all(x) x.begin(), x.end()
#define cerr(s) cerr << "\033[48;5;196m\033[38;5;15m"
→ << s << "\033[0m"
// typedef __int128_t lli;
typedef long long int li;
typedef long double ld;

void _main(int tc) {

}

int main() {
    ios_base::sync_with_stdio(0), cin.tie(0);
    _main(0); return 0;
    int tc;
    cin >> tc;
    rep(i, tc) _main(i + 1);
}

```

Include All Libraries

```

#include <bits/stdc++.h>
using namespace std;

```

IO Optimization

```

int main() {
    ios_base::sync_with_stdio(0);
    cin.tie(0);
}

```

Number To String

```

#include <bits/stdc++.h>
using namespace std;

int main() {
    // to_string method converts any type of number
    // (int, double, long long int, ...) to string
    string str = "str" + to_string(123 + 1);
    cout << str << endl; // output: str+124
    return 0;
}

```

Output Format

```

int main() {
    ios state(nullptr);
    state.copyfmt(cout); // saves current format state
    double D = 13.34567;
    cout << setprecision(4) << D << endl // 13.35
        << fixed << D << endl;           // 13.3457
    cout.copyfmt(state); // restores format
    int N = 13;
    cout << setw(4) << N << endl           // " 13"
        << setfill('0') << N << endl       // "0013"
        << left << N << endl                // "1300"
        << right << N << endl               // "0013"
        << hex << N << endl                 // "000d"
        << uppercase << N << endl          // "000D"
        << nouppercase << N << endl        // "000d"
        << oct << N << endl                // "0015"
        << dec << N << endl;               // "0013"
}

```

Permutations

```

typedef vector<int> T; // typedef string T;

vector<T> permutations(T v) {
    vector<vector<int>> ans;
    sort(v.begin(), v.end());
    do
        ans.push_back(v);
    while (next_permutation(v.begin(), v.end()));
    return ans;
}

```

Print Vector

```
void printv(vector<int> v) {
    if (v.size() == 0) {
        cout << "[]" << endl;
        return;
    }
    cout << "[" << v[0];
    for (int i = 1; i < v.size(); i++)
        cout << ", " << v[i];
    cout << "]" << endl;
}
```

Priority Queue Of Object

```
struct Object {
    char first;
    int second;
};

int main() {
    auto cmp = [](const Object& a, const Object& b) {
        return a.second > b.second;
    };
    priority_queue<Object, vector<Object>,
        decltype(cmp)>
        pq(cmp);
}
```

Random

```
mt19937_64 seed(chrono::steady_clock::now()
    .time_since_epoch()
    .count());

int random(int min, int max) { // [min, max]
    return uniform_int_distribution<int>(min,
        max)(seed);
}

double random(double min, double max) { // [min, max]
    return uniform_real_distribution<double>(min,
        max)(seed);
}
```

Read Line

```
// when reading lines, don't mix 'cin' with
// 'getline' just use getline and split
string input() {
    string ans;
    cin >> ws;
    cin.ignore(numeric_limits<streamsize>::max(), '\n');
    getline(cin, ans);
    return ans;
}
```

Secure Hash

```
struct myhash {
    size_t operator()(uint64_t x) const {
        static const uint64_t FIXED_RANDOM =
            chrono::steady_clock::now()
                .time_since_epoch()
                .count();
        x ^= FIXED_RANDOM;
        return x ^ (x >> 16);
    }
};
```

Set of Object

```
struct Object {
    char first;
    int second;
};

int main() {
    auto cmp = [](const Object& a, const Object& b) {
        return a.second > b.second;
    };
    set<Object, decltype(cmp)> pq(cmp);
}
```

Sort Vector Of Object

```
struct Object {
    char first;
    int second;
};

bool cmp(const Object& a, const Object& b) {
    return a.second > b.second;
}

int main() {
    vector<Object> v = {'c', 3}, {'a', 1}, {'b', 2};
    sort(v.begin(), v.end(), cmp);
}
```

Sort Vector of Pairs

```
vector<pair<int, int>> pairs;
// sorts array on the basis of the first element
sort(pairs.begin(), pairs.end());
```

Split String

```
vector<string> split(string str, char token) {
    stringstream ss(str);
    vector<string> v;
    while (getline(ss, str, token)) v.push_back(str);
    return v;
}
```

String To Int

```
#include <bits/stdc++.h>
using namespace std;

int main() {
    int n = stoi("123") + 1;
    cout << n << endl; // output: 124
    // stoll for long long int
    // stoull for unsigned long int
    // stod for double
    // stold for long double
}
```

Typedef

```
typedef TYPE ALIAS;
// example:
typedef int T;
```

Unordered Map with pair as key

```
typedef int T;

struct pairhash {
    template <class T1, class T2>
    size_t operator()(const pair<T1, T2> &p) const {
        return hash<T1>{}(p.first) ^
            (hash<T2>{}(p.second) << 32);
    }
};

int main() {
    unordered_map<pair<int, int>, T, hash_pair> um;
    um[{1, 2}] = 5;
    cout << um[{1, 2}] << endl;
}
```

Python

Combinations

```
import itertools
# from arr choose k => combinations(arr, k)
print(list(itertools.combinations([1, 2, 3], 3)))
```

Fast IO

```
from sys import stdin, stdout

N = 10
# Reads N chars from stdin(it counts '\n' as char)
stdin.read(N)
# Reads until '\n' or EOF
line = stdin.readline()
# Reads all lines in stdin until EOF
lines = stdin.readlines()
# Writes a string to stdout, it doesn't add '\n'
stdout.write(line)
# Writes a list of strings to stdout
stdout.writelines(lines)
# Reads numbers separated by space in a line
numbers = list(map(int, stdin.readline().split()))
```

Permutations

```
import itertools
print(list(itertools.permutations([1, 2, 3])))
```

Random

```
import random
# Initialize the random number generator.
random.seed(None)
# Returns a random integer N such that a <= N <= b.
random.randint(a, b)
# Returns a random integer N such that 0 <= N < b
random.randrange(b)
# Returns a random integer N such that a <= N < b.
random.randrange(a, b)
# Returns and integer with k random bits.
random.getrandbits(k)
# shuffles a list
random.shuffle(li)
```

Sort List

```
li = ['a', 'c', 'b']
# sorts inplace in descending order
li.sort(reverse=True)
# returns sorted list ascending order
ol = sorted(li)
```

Sort List Of Object

```
class MyObject :
    def __init__(self, first, second, third):
        self.first = first
        self.second = second
        self.third = third

li = [MyObject('b', 3, 1), MyObject('a', 3, 2),
      ↪ MyObject('b', 3, 3)]
# returns list sorted by first then by second then by
↪ third in increasing order
ol = sorted(li, key = lambda x: (x.first, x.second,
↪ x.third), reverse=False)
# sorts inplace by first then by second then by third
↪ in increasing order
li.sort(key = lambda x: (x.first, x.second, x.third),
↪ reverse=False)
```

BITS Manipulation

Bit Count

```
int bitCount(int n) {
    return sizeof(n) * 8 - __builtin_clz(n);
}
```

```
int bitCount(int n) {
    int c = 0;
    while (n) c++, n >>= 1;
    return c;
}
```

Bits To Int

```
typedef __int128_t lli

lli bitsToInt(string bits, bool isneg) {
    lli ans = 0;
    for (int i = bits.size() - 1, j = 0; ~i; i--, j++) {
        if (isneg) bits[i] = bits[i] == '0' ? '1' : '0';
        ans |= (lli)(bits[i] - '0') << j;
    }
    return isneg ? -(++ans) : ans;
}
```

Count Leading Zeroes

```
int clz(int n) {
    return __builtin_clz(n);
    // return __builtin_clzl(n); for long
    // return __builtin_clzll(n); for long long
}
```

```
int clz(int n) {
    // return sizeof(n) * 8 - bitCount(n);
    int c = 0;
    while (n) c++, n >>= 1;
    return sizeof(n) * 8 - c;
}
```

Count Set Bits

```
int popCount(int n) {
    return __builtin_popcount(n);
    // return __builtin_popcountl(n); for long
    // return __builtin_popcountll(n); for long long
}
```

```
int popCount(int n) {
    int c = 0;
    while (n) c++, n &= n - 1;
    return c;
}
```

Count Trailing Zeroes

```
int ctz(int n) {
    return __builtin_ctz(n);
    // return __builtin_ctzl(n); for long
    // return __builtin_ctzll(n); for long long
}
```

```
int ctz(int n) {
    int c = 0;
    n = ~n;
    while(n & 1) c++, n >>= 1;
    return c;
}
```

Divide By 2

```
int divideBy2(int n) { return n >> 1; }
```

Is Even

```
bool isEven(int n) { return ~n & 1; }
```

Is i-th Bit Set

```
bool isIthBitSet(int n, int i) {
    return n & (1 << i);
}
```

Is Odd

```
bool isOdd(int n) { return n & 1; }
```


Is Power Of 2

```
bool isPowerOf2(int n) { return n && !(n & (n - 1)); }
```

Least Significant Set Bit

```
int lsb(int n) { return n & -n; }
```

Log2

```
int Log2(int n) {
    return sizeof(n) * 8 - __builtin_clz(n) - 1;
}
```

```
int Log2(int n) {
    int lg2 = 0;
    while (n >= 1) lg2++;
    return lg2;
}
```

Modulo With Power Of 2

```
// b must be a power of 2
int mod(int a, int b) { return a & (b - 1); }
```

Most Significant Set Bit

```
int msb(int n) {
    return 1 << (sizeof(n) * 8 - __builtin_clz(n) - 1);
}
```

Multiply By 2

```
int multiplyBy2(int n) { return n << 1; }
```

One's Complement

```
int onesComplement(int n) { return ~n; }
```

Parity Check

```
#include "Count Set Bits.cpp"
#include "Is Even.cpp"
bool parityCheck(int n) {
    return !__builtin_parity(n);
    // return !__builtin_parityl(n); for long
    // return !__builtin_parityll(n); for long long
}

bool parityCheck(int n) {
    return isEven(popCount(n));
}
```

Print Bits

```
void printBits(int n) {
    for (int i = sizeof(n) * 8 - 1; ~i; i--)
        cout << ((n >> i) & 1);
    cout << endl;
}
```

Set i-th Bit

```
int setIthBit(int n, int i) { return n | (1 << i); }
```

Swap Integer Variables

```
void swap(int &a, int &b) {
    a ^= b;
    b ^= a;
    a ^= b;
}
```

To Lower Case

```
char lowerCase(char c) { return c | ' '; }
```

To Upper Case

```
char upperCase(char c) { return c & '_'; }
```

Toggle Case

```
char toggleCase(char c) { return c ^ ' '; }
```

Toggle i-th Bit

```
int toggleIthBit(int n, int i) {
    return n ^ (1 << i);
}
```

Two's Complement

```
int twosComplement(int n) { return ~n + 1; }
```

Unset i-th Bit

```
int unsetIthBit(int n, int i) {
    return n & ~(1 << i);
}
```

XOR From 1 To N

```
int xorToN(int n) {
    switch (n & 3) {
        case 0: return n;
        case 1: return 1;
        case 2: return n + 1;
        case 3: return 0;
    }
}
```

Geometry

Data Structures

Circle

```
// c = center, r = radius;
#include "Point.cpp"
```

```
struct Circle {
    Point c;
    ld r;
    Circle(Point c, ld r) : c(c), r(r) {}
};
```

Point

```
#include "../Util/Double Comparisons With Given
→ Precision.cpp"
```

```
const ld pi = acos(-1), inf = 1 << 30;
// (PointB - PointA) = vector from A to B.
struct Point {
    ld x, y;
    Point() : x(0), y(0) {}
    Point(ld x, ld y) : x(x), y(y) {}

    Point operator+(const Point &p) const {
        return Point(x + p.x, y + p.y);
    }

    Point operator-(const Point &p) const {
        return Point(x - p.x, y - p.y);
    }

    Point operator*(const ld &k) const {
        return Point(x * k, y * k);
    }

    Point operator/(const ld &k) const {
        return Point(x / k, y / k);
    }
}
```

```
bool operator==(const Point &p) const {
    return eq(x, p.x) && eq(y, p.y);
}

bool operator!=(const Point &p) const {
    return !(*this == p);
}

bool operator<(const Point &p) const {
    return eq(x, p.x) ? lt(y, p.y) : lt(x, p.x);
}

bool operator>(const Point &p) const {
    return eq(x, p.x) ? gt(y, p.y) : gt(x, p.x);
}

ld norm() const { return sqrt(x * x + y * y); }

ld dot(const Point &p) { return x * p.x + y * p.y; }

ld cross(const Point &p) {
    return x * p.y - y * p.x;
}

Point perpendicularLeft() { return Point(-y, x); }

Point perpendicularRight() { return Point(y, -x); }

Point rotate(ld deg) {
    ld rad = (deg * pi) / 180.0;
    return Point(x * cos(rad) - y * sin(rad),
                x * sin(rad) + y * cos(rad));
}

Point unit() const { return (*this) / norm(); }

Point projectOn(const Point &p) {
    return p.unit() * (dot(p) / p.norm());
}

ld angleWith(const Point &p) {
    ld x = dot(p) / norm() / p.norm();
    return acos(max(-1.0L, min(1.0L, x)));
}

bool isPerpendicularWith(const Point &p) {
    return dot(p);
}

// ans > 0 p is on the left
// ans < 0 p is on the right
// ans == 0 p has our same direction
ld positionOf(const Point &p) { return cross(p); }

istream &operator>>(istream &is, Point &p) {
    return is >> p.x >> p.y;
}

ostream &operator<<(ostream &os, const Point &p) {
    return os << "(" << p.x << ", " << p.y << ")";
}
```

Intersection Points Of Segments In A Plane

```
#include <bits/stdc++.h>
using namespace std;

#include "Data Structures/Point.cpp"

vector<Point> intersections(
    vector<pair<Point, Point>>& segs) {
    return {};
}
```

Is Point In Line

```
#include "Data Structures/Point.cpp"

bool isPointInLine(Point& a, Point& b, Point& p) {
    return !(b - a).cross(p - a);
}
```

Is Point In Segment

```
#include "Data Structures/Point.cpp"

bool isPointInSegment(Point& a, Point& b, Point& p) {
    return !(b - a).cross(p - a) &&
        (a - p).dot(b - p) <= 0;
}
```

Is Point Inside Polygon

```
// assumes the polygon is given counter-clockwise
// if point is exactly in edge, it's considered inside
// change "gt" to "gte" to not consider it inside.
#include "Data Structures/Point.cpp"

bool isPointInPolygon(vector<Point> &ps, Point &p) {
    assert(ps.size() > 2);
    for (int i = 0; i < ps.size(); i++)
        if (gt(0, (ps[(i + 1) % ps.size()] - ps[i])
            .positionOf(p - ps[i])))
            return false;
    return true;
}
```

Line-Line Intersection

```
#include "Data Structures/Point.cpp"

pair<int, Point> llintersection(Point& a, Point& b,
                                Point& u, Point& v) {
    if ((b - a).cross(v - u)) // single point
        return {1, a + (b - a) * ((u - a).cross(v - u) /
            (b - a).cross(v - u))};
    if ((b - a).cross(u - a))
        return {0, Point()}; // no points
    return {-1, Point()}; // infinity points
}
```

Line-Segment Intersection

```
#include "Data Structures/Point.cpp"

int sign(ld x) {
    if (x < 0) return -1;
    return x > 0;
}

// line: a-b, segment: u-v
// 0: no point, 1: single point, -1: infinity points
pair<int, Point> lsintersection(Point& a, Point& b,
                                Point& u, Point& v) {
    if ((b - a).cross(v - u))
        return {sign((b - a).cross(u - a)) !=
            sign((b - a).cross(v - a)),
            a + (b - a) * ((u - a).cross(v - u) /
            (b - a).cross(v - u))};
    if ((u - a).cross(b - a)) return {0, Point()};
    return {-1, Point()};
}
```

Max Interval Overlap

```
typedef pair<double, double> Interval;
vector<Interval> maxIntervals;
```

```
// O(N * lg(N))
int maxOverlap(vector<Interval> &arr) {
    maxIntervals.clear();
    map<double, int> m;
    int maxI = 0, curr = 0, isFirst = 1;
    double l = -1, r = -1;
    for (auto &i : arr) m[i.first]++, m[i.second +
        ↪ 0.1]--;
    for (auto &p : m) {
        curr += p.second;
        if (curr > maxI) maxI = curr, l = p.first;
        if (curr == maxI) r = p.first;
    }
    curr = 0;
    for (auto &p : m) {
        curr += p.second;
        if (curr == maxI && isFirst)
            l = p.first, isFirst = 0;
        if (curr < maxI && !isFirst)
            maxIntervals.push_back({l, p.first - 1}),
            isFirst = 1;
    }
    return maxI;
}

// O(MaxPoint) maxPoint < vector::max_size
int maxOverlap(vector<Interval> &arr) {
    maxIntervals.clear();
    T maxPoint = 0;
    for (auto &i : arr)
        if (i.second > maxPoint) maxPoint = i.second;
    vector<int> x(maxPoint + 2);
    for (auto &i : arr) x[i.first]++, x[i.second + 1]--;
    int maxI = 0, curr = 0, isFirst = 1;
    T l = -1LL, r = -1LL;
    for (int i = 0; i < x.size(); i++) {
        curr += x[i];
        if (curr > maxI) maxI = curr;
    }
    curr = 0;
    for (int i = 0; i < x.size(); i++) {
        curr += x[i];
        if (curr == maxI && isFirst) l = i, isFirst = 0;
        if (curr < maxI && !isFirst)
            maxIntervals.push_back({l, i - 1}), isFirst = 1;
    }
    return maxI;
}
```

Point Projection On Line

```
#include "Data Structures/Point.cpp"
```

```
Point projectionOnLine(Point& a, Point& b, Point& p) {
    Point pr = a + (p - a).projectOn(b - a);
    if (abs(pr.x) < eps) pr.x = 0;
    if (abs(pr.y) < eps) pr.y = 0;
    return pr;
}
```

Point Reflection On Line

```
#include "Data Structures/Point.cpp"
```

```
Point reflectionOnLine(Point& a, Point& b, Point& p) {
    Point r = a * 2 + (p - a).projectOn(b - a) * 2 - p;
    if (abs(r.x) < eps) r.x = 0;
    if (abs(r.y) < eps) r.y = 0;
    return r;
}
```

Point-Line Distance

```
#include "Data Structures/Point.cpp"
```

```
ld pointLineDist(Point& a, Point& b, Point& p) {
    return ((p - a).projectOn(b - a) - (p - a)).norm();
}
```

Point-Line Distance (Signed)

```
#include "Data Structures/Point.cpp"
```

```
// ans > 0 p is on the left of a-b
// ans < 0 p is on the right of a-b
ld pointLineDist(Point& a, Point& b, Point& p) {
    return (b - a).cross(p - a) / (b - a).norm();
}
```

Segment-Segment Intersection

```
#include "Data Structures/Point.cpp"
```

```
int sign(ld x) { return x < 0 ? -1 : x > 0; }
```

```
void swap(Point& a, Point& b) {
    swap(a.x, b.x), swap(a.y, b.y);
}
```

```
// 0: no point, 1: single point, -1: infinity points
pair<int, Point> ssintersection(Point a, Point b,
                                Point u, Point v) {
    if ((b - a).cross(v - u))
        return {sign((b - a).cross(u - a)) !=
                sign((b - a).cross(v - a)) &&
                sign((v - u).cross(a - u)) !=
                sign((v - u).cross(b - u)),
                a + (b - a) * ((u - a).cross(v - u) /
                                (b - a).cross(v - u))};
    if ((b - a).cross(u - a)) return {0, Point()};
    if (a > b) swap(a, b);
    if (u > v) swap(u, v);
    if (a > u) swap(a, u), swap(b, v);
    if (u < b) return {-1, Point()};
    return {b == u, u};
}
```

Sort Points Along Line With Direction

```
#include "Data Structures/Point.cpp"

void sortAlongLine(Point& a, Point& b,
                  vector<Point>& ps) {
    sort(ps.begin(), ps.end(), [&](Point& u, Point& v) {
        return u.dot(b - a) < v.dot(b - a);
    });
}
```

Graphs

Data Structures

Union Find

```
struct UnionFind {
    int n;
    vector<int> dad, size;

    UnionFind(int N) : n(N), dad(N), size(N, 1) {
        while (N--> 0) dad[N] = N;
    }

    // O(lg*(N))
    int root(int u) {
        if (dad[u] == u) return u;
        return dad[u] = root(dad[u]);
    }

    // O(1)
    void join(int u, int v) {
        int Ru = root(u), Rv = root(v);
        if (Ru == Rv) return;
        if (size[Ru] > size[Rv]) swap(Ru, Rv);
        --n, dad[Ru] = Rv;
        size[Rv] += size[Ru];
    }

    // O(lg*(N))
    bool areConnected(int u, int v) {
        return root(u) == root(v);
    }

    int getSize(int u) { return size[root(u)]; }

    int numberOfSets() { return n; }
};
```

Union Find (Partially Persistent)

```
// jTime = join time, t = time
struct UnionFind {
    int Time = 0;
    vector<int> dad, size, jTime;

    UnionFind(int N) : dad(N), size(N, 1), jTime(N) {
        while (N--> 0) dad[N] = N;
    }

    // O(lg(N))
    int root(int u, int t) {
        while (jTime[u] <= t && u != dad[u]) u = dad[u];
        return u;
    }

    // O(1)
    void join(int u, int v, bool newTime = 1) {
        int Ru = root(u, Time), Rv = root(v, Time);
        if (newTime) Time++;
        if (Ru == Rv) return;
        if (size[Ru] > size[Rv]) swap(Ru, Rv);
        jTime[Ru] = Time;
        dad[Ru] = Rv;
        size[Rv] += size[Ru];
    }

    // O(lg(N))
    bool areConnected(int u, int v, int t) {
        return root(u, t) == root(v, t);
    }

    // O(lg(N))
    int getLastVersionSize(int u) {
        return size[root(u, Time)];
    }

    // O(lg(Time) * lg(N))
    int joinTime(int u, int v) {
        int l = 0, r = Time, ans = -1;
        while (l <= r) {
            int mid = (l + r) >> 1;
            if (areConnected(u, v, mid))
                ans = mid, r = mid - 1;
            else
                l = mid + 1;
        }
        return ans;
    }
};
```

Articulation Points And Bridges

```
// APB = articulation points and bridges
// Ap = Articulation Point
// br = bridges, p = parent
// disc = discovery time
// low = lowTime, ch = children
// nup = number of edges from u to p
```

```

typedef pair<int, int> Edge;
int Time;
vector<vector<int>>> adj;
vector<int> disc, low, isAp;
vector<Edge> br;

void init(int N) { adj.assign(N, vector<int>()); }

void addEdge(int u, int v) {
    adj[u].push_back(v);
    adj[v].push_back(u);
}

int dfsAPB(int u, int p) {
    int ch = 0, nup = 0;
    low[u] = disc[u] = ++Time;
    for (int &v : adj[u]) {
        if (v == p && !nup++) continue;
        if (!disc[v]) {
            ch++, dfsAPB(v, u);
            if (disc[u] <= low[v]) isAp[u]++;
            if (disc[u] < low[v]) br.push_back({u, v});
            low[u] = min(low[u], low[v]);
        } else
            low[u] = min(low[u], disc[v]);
    }
    return ch;
}

// O(N)
void APB() {
    br.clear();
    isAp = low = disc = vector<int>(adj.size());
    Time = 0;
    for (int u = 0; u < adj.size(); u++)
        if (!disc[u]) isAp[u] = dfsAPB(u, u) > 1;
}

```

Connected Components

```

// comp = component
int compId;
vector<vector<int>>> adj;
vector<int> getComp;

void init(int N) {
    adj.assign(N, vector<int>());
    getComp.assign(N, -1);
    compId = 0;
}

void addEdge(int u, int v) {
    adj[u].push_back(v);
    adj[v].push_back(u);
}

void dfsCC(int u, vector<int> &comp) {
    if (getComp[u] > -1) return;
    getComp[u] = compId;
    comp.push_back(u);
    for (auto &v : adj[u]) dfsCC(v, comp);
}

```

```

// O(N)
vector<vector<int>>> connectedComponents() {
    vector<vector<int>>> comps;
    for (int u = 0; u < adj.size(); u++) {
        vector<int> comp;
        dfsCC(u, comp);
        if (!comp.empty())
            comps.push_back(comp), compId++;
    }
    return comps;
}

```

Flood Fill

```

int n, m, oldColor = 0, color = 1;
vector<vector<int>>> mat;
vector<vector<int>>> movs = {
    {1, 0}, {0, 1}, {-1, 0}, {0, -1}};

void floodFill(int i, int j) {
    if (i >= mat.size() || i < 0 ||
        j >= mat[i].size() || j < 0 ||
        mat[i][j] != oldColor)
        return;
    mat[i][j] = color;
    for (auto move : movs)
        floodFill(i + move[1], j + move[0]);
}

void floodFill() {
    for (int i = 0; i < n; i++)
        for (int j = 0; j < m; j++)
            if (mat[i][j] == oldColor) floodFill(i, j);
}

```

Heavy Light Decomposition

```

// p = parent;
#include "../Ranges/Data Structures/Segment Tree Lazy
    ↳ Propagation.cpp"
typedef int T;
vector<vector<int>>> adj;
vector<int> p, heavy, depth, root, stPos, vals;
SegmentTree<T> st(0);

void init(int n) {
    adj.assign(n, vector<int>());
    heavy.assign(n, -1);
    vals.assign(n, 0);
    p = root = stPos = depth = heavy;
    st = SegmentTree<T>(n);
}

void addEdge(int u, int v, T val) {
    adj[u].push_back(v);
    p[v] = u, vals[v] = val;
}

T F(T a, T b) { return a + b; }

```

```
// O(N)
int dfs(int u) {
    int size = 1, maxSubtree = 0;
    for (int &v : adj[u]) {
        depth[v] = depth[u] + 1;
        int subtree = dfs(v);
        if (subtree > maxSubtree)
            heavy[u] = v, maxSubtree = subtree;
        size += subtree;
    }
    return size;
}

// O(N)
void initHeavyLight() {
    for (int i = 0; i < adj.size(); i++)
        if (p[i] < 0) dfs(i);
    for (int i = 0, pos = 0; i < adj.size(); i++)
        if (p[i] < 0 || heavy[p[i]] != i)
            for (int j = i; ~j; j = heavy[j]) {
                st.setValAt(vals[j], stPos[j] = pos++);
                root[j] = i;
            }
    st.build();
}

// O(lg^2(N))
template <class Op>
void processPath(int u, int v, Op op) {
    for (; root[u] != root[v]; v = p[root[v]]) {
        if (depth[root[u]] > depth[root[v]]) swap(u, v);
        op(stPos[root[v]], stPos[v]);
    }
    if (depth[u] > depth[v]) swap(u, v);
    // for values on edges
    if (u != v) op(stPos[u] + 1, stPos[v]);
    // for values on nodes
    // op(stPos[u], stPos[v]);
}

// O(lg^2(N))
void update(int u, int v, T val) {
    processPath(u, v, [&val](int l, int r) {
        st.update(l, r, val);
    });
}

// O(lg^2(N))
T query(int u, int v) {
    T ans = T();
    processPath(u, v, [&ans](int l, int r) {
        ans = F(ans, st.query(l, r));
    });
    return ans;
}
```

Is Bipartite

```
vector<vector<int>> adj;

void init(int N) { adj.assign(N, vector<int>()); }
```

```
void addEdge(int u, int v) {
    adj[u].push_back(v);
    adj[v].push_back(u);
}

// O(N)
bool isBipartite() {
    vector<int> color(adj.size(), -1);
    for (int s = 0; s < adj.size(); s++) {
        if (color[s] > -1) continue;
        color[s] = 0;
        queue<int> q;
        q.push(s);
        while (!q.empty()) {
            int u = q.front();
            q.pop();
            for (int &v : adj[u]) {
                if (color[v] < 0)
                    q.push(v), color[v] = !color[u];
                if (color[v] == color[u]) return false;
            }
        }
    }
    return true;
}
```

Lowest Common Ancestor

```
// st = sparse table, p = parent
typedef pair<int, int> T;
int neutro = 0;
vector<vector<T>> st;
vector<int> first;
vector<T> tour;
vector<vector<int>> adj;

void init(int N) { adj.assign(N, vector<int>()); }

void addEdge(int u, int v) {
    adj[u].push_back(v);
    adj[v].push_back(u);
}

T F(T a, T b) { return a.first < b.first ? a : b; }

void build() {
    st.assign(log2(tour.size()),
              vector<T>(tour.size()));
    st[0] = tour;
    for (int i = 1; (1 << i) <= tour.size(); i++)
        for (int j = 0; j + (1 << i) <= tour.size(); j++)
            st[i][j] = F(st[i - 1][j],
                          st[i - 1][j + (1 << (i - 1))]);
}
```



```

void eulerTour(int u, int p, int h) {
    first[u] = tour.size();
    tour.push_back({h, u});
    for (int v : adj[u])
        if (v != p) {
            eulerTour(v, u, h + 1);
            tour.push_back({h, u});
        }
}

// O(N * lg(N))
void preprocess() {
    tour.clear();
    first.assign(adj.size(), -1);
    vector<int> roots = {0};
    for (auto &root : roots) eulerTour(root, -1, 0);
    build();
}

// O(1)
int lca(int u, int v) {
    int l = min(first[u], first[v]);
    int r = max(first[u], first[v]);
    int i = log2(r - l + 1);
    return F(st[i][l], st[i][r + 1 - (1 << i)]).second;
}

```

Minimum Spanning Tree Kruskal

```

// N = number of nodes, Wedge = Weighted Edge
#include "Data Structures/Union Find.cpp"
typedef int T;
typedef pair<int, int> Edge;
typedef pair<T, Edge> Wedge;
vector<Wedge> Wedges;
vector<Wedge> mst;
UnionFind uf(0);

void init(int N) {
    mst.clear();
    Wedges.clear();
    uf = UnionFind(N);
}

void addEdge(int u, int v, T w) {
    Wedges.push_back({w, {u, v}});
}

T kruskal() {
    T cost = 0;
    sort(Wedges.begin(), Wedges.end());
    // reverse(Wedges.begin(), Wedges.end());
    for (Wedge &wedge : Wedges) {
        int u = wedge.second.first,
            v = wedge.second.second;
        if (!uf.areConnected(u, v))
            uf.join(u, v), mst.push_back(wedge),
            cost += wedge.first;
    }
    return cost;
}

```

Minimum Spanning Tree Prim

```

// st = spanning tree, p = parent
// vis = visited, dist = distance
typedef int T;
typedef pair<int, int> Edge;
typedef pair<T, Edge> Wedge;
typedef pair<T, int> DistNode;
long long int inf = (1ll << 62) - 1;
vector<vector<int>> adj;
unordered_map<int, unordered_map<int, T>> weight;
vector<int> p, vis;
vector<T> dist;
vector<vector<Wedge>> msts;

void init(int N) {
    adj.assign(N, vector<int>());
    p.assign(N, 0);
    vis.assign(N, 0);
    dist.assign(N, inf);
    weight.clear();
    msts.clear();
}

void addEdge(int u, int v, T w) {
    adj[u].push_back(v);
    weight[u][v] = w;
    adj[v].push_back(u);
    weight[v][u] = w;
}

// ~ O(E * log(V))
T prim(int s) {
    vector<Wedge> mst;
    vector<T> dist(adj.size(), inf);
    priority_queue<DistNode> q;
    T cost = dist[s] = 0;
    q.push({0, s});
    while (q.size()) {
        pair<int, int> aux = q.top();
        int u = aux.second;
        q.pop();
        if (dist[u] < -aux.first) continue;
        vis[u] = 1, cost += dist[u];
        mst.push_back({dist[u], {p[u], u}});
        for (int &v : adj[u]) {
            T w = weight[u][v];
            if (!vis[v] && w < dist[v])
                q.push({-(dist[v] = w), v});
        }
    }
    msts.push_back(
        vector<Wedge>(mst.begin() + 1, mst.end()));
    return cost;
}

```



```
// O(V + E * log(V))
T prim() {
    T cost = 0;
    map<int, T> q;
    for (int i = 0; i < adj.size(); i++)
        if (!vis[i]) cost += prim(i);
    return cost;
}

// tv = top value from stack
// sccs = strongly connected components
// scc = strongly connected component
// disc = discovery time, low = low time
// s = stack, top = top index of the stack

int Time, top;
vector<vector<int>>> adj, sccs;
vector<int> disc, low, s;

void init(int N) { adj.assign(N, vector<int>()); }

void addEdge(int u, int v) { adj[u].push_back(v); }

void dfsSCCS(int u) {
    if (disc[u]) return;
    low[u] = disc[u] = ++Time;
    s[++top] = u;
    for (int &v : adj[u])
        dfsSCCS(v), low[u] = min(low[u], low[v]);
    if (disc[u] == low[u]) {
        vector<int> scc;
        while (true) {
            int tv = s[top--];
            scc.push_back(tv);
            low[tv] = adj.size();
            if (tv == u) break;
        }
        sccs.push_back(scc);
    }
}

// O(N)
void SCCS() {
    s = low = disc = vector<int>(adj.size());
    Time = 0, top = -1, sccs.clear();
    for (int u = 0; u < adj.size(); u++) dfsSCCS(u);
}
```

Topological Sort

```
// vis = visited
vector<vector<int>>> adj;
vector<int> vis, toposorted;
```

```
void init(int N) {
    adj.assign(N, vector<int>());
    vis.assign(N, 0), toposorted.clear();
}

void addEdge(int u, int v) { adj[u].push_back(v); }
// returns false if there is a cycle
// O(E)
bool toposort(int u) {
    vis[u] = 1;
    for (auto &v : adj[u])
        if (v != u && vis[v] != 2 &&
            (vis[v] || !toposort(v)))
            return false;
    vis[u] = 2;
    toposorted.push_back(u);
    return true;
}

// O(V + E)
bool toposort() {
    for (int u = 0; u < adj.size(); u++)
        if (!vis[u] && !toposort(u)) return false;
    return true;
}
```

Topological Sort (All possible sorts)

```
// indeg0 = indegree 0
vector<int> vis, indegree, path;
vector<vector<int>>> adj, toposorts;
deque<int> indeg0;
void init(int n) {
    adj.assign(n, vector<int>());
    vis.assign(n, 0);
    indegree = vis;
}

void addEdge(int u, int v) {
    adj[u].push_back(v);
    indegree[v]++;
}

// O(V!)
void dfs() {
    for (int i = 0; i < indeg0.size(); i++) {
        int u = indeg0.front();
        indeg0.pop_front();
        path.push_back(u);
        for (auto &v : adj[u])
            if (!--indegree[v]) indeg0.push_back(v);
        if (!indeg0.size()) toposorts.push_back(path);
        dfs();
        for (int v = adj[u].size() - 1; v--;) {
            indegree[adj[u][v]]++;
            if (indeg0.back() == adj[u][v])
                indeg0.pop_back();
        }
        indeg0.push_back(u);
        path.pop_back();
    }
}
```

```
// O(V + V!)
void allToposorts() {
    for (int u = 0; u < adj.size(); u++)
        if (!indegree[u]) indeg0.push_back(u);
    dfs();
}
```

Topological Sort (lowest lexicographically)

```
// indeg0 = indegree 0
vector<vector<int>>> adj;
vector<int> indegree, toposorted;

void init(int n) {
    adj.assign(n, vector<int>());
    indegree.assign(n, 0), toposorted.clear();
}

void addEdge(int u, int v) {
    adj[u].push_back(v);
    indegree[v]++;
}

// returns false if there is a cycle
// O(V * lg(V) + E)
bool toposort() {
    set<int> indeg0;
    for (int u = 0; u < adj.size(); u++)
        if (!indegree[u]) indeg0.insert(u);
    int cnt = 0;
    while (indeg0.size()) {
        auto u = indeg0.begin();
        toposorted.push_back(*u);
        for (auto& v : adj[*u])
            if (!--indegree[v]) indeg0.insert(v);
        cnt++, indeg0.erase(u);
    }
    return cnt < adj.size() ? false : true;
}
```

Tree Diameter (Longest Path Between 2 Nodes)

```
int inf = (1 << 30) - 1;
vector<vector<int>>> adj;

void init(int N) { adj.assign(N, vector<int>()); }

void addEdge(int u, int v) {
    adj[u].push_back(v);
    adj[v].push_back(u);
}
```

```
int bfs(int u) {
    vector<int> dist(adj.size(), inf);
    queue<int> q;
    q.push(u), dist[u] = 0;
    while (q.size()) {
        int u = q.front();
        q.pop();
        for (int& v : adj[u])
            if (dist[v] == inf)
                q.push(v), dist[v] = dist[u] + 1;
    }
    int node, maxx = -inf;
    for (int u = 0; u < adj.size(); u++)
        if (dist[u] > maxx) maxx = dist[u], node = u;
    return node;
}

vector<int> diameter() {
    int u = bfs(0), v = bfs(u);
    vector<int> path = {v}, vis(adj.size());
    function<bool(int)> dfs = [&](int a) {
        if (a == v) return true;
        vis[a] = 1;
        for (int& b : adj[a]) {
            if (vis[b] || !dfs(b)) continue;
            path.push_back(a);
            return true;
        }
        return false;
    };
    dfs(u);
    return path;
}
```

Cycles

Get Some Cycles

```
// at least detects one cycle per component
vector<vector<int>>> adj, cycles;
vector<int> vis, cycle;
bool flag = false, isDirected = false;
int root = -1;

void init(int N) {
    adj.assign(N, vector<int>());
    vis.assign(N, 0);
    cycles.clear();
    root = -1, flag = false;
}

void addEdge(int u, int v) {
    adj[u].push_back(v);
    if (!isDirected) adj[v].push_back(u);
}
```

```
// O(N)
bool hasCycle(int u, int prev) {
    vis[u] = 1;
    for (auto &v : adj[u]) {
        if (v == u || vis[v] == 2 ||
            (!isDirected && v == prev))
            continue;
        if (flag) {
            if (!vis[v]) hasCycle(v, u);
            continue;
        }
        if (vis[v] || hasCycle(v, u)) {
            if (root == -1) root = v, flag = true;
            cycle.push_back(u);
            if (root == u)
                flag = false, root = -1,
                cycles.push_back(cycle), cycle.clear();
        }
    }
    vis[u] = 2;
    return flag;
}

// O(N)
bool hasCycle() {
    for (int u = 0; u < adj.size(); u++)
        if (!vis[u]) cycle.clear(), hasCycle(u, -1);
    return cycles.size() > 0;
}
```

Has Cycle

```
vector<vector<int>>> adj;
vector<int> vis;
bool isDirected = false;

void init(int N) {
    adj.assign(N, vector<int>());
    vis.assign(N, 0);
}

void addEdge(int u, int v) {
    adj[u].push_back(v);
    if (!isDirected) adj[v].push_back(u);
}

bool hasCycle(int u, int prev) {
    vis[u] = 1;
    for (auto &v : adj[u])
        if (v != u && vis[v] != 2 &&
            (isDirected || v != prev) &&
            (vis[v] || hasCycle(v, u)))
            return true;
    vis[u] = 2;
    return false;
}
```

```
// O(N)
bool hasCycle() {
    for (int u = 0; u < adj.size(); u++)
        if (!vis[u] && hasCycle(u, -1)) return true;
}

// cap[a][b] = Capacity left from a to b
// iflow = initial flow, icap = initial capacity
// pathMinCap = capacity bottleneck for a path (s->t)

typedef int T;
vector<int> level;
vector<vector<int>>> adj;
vector<vector<T>>> cap;
T inf = 1 << 30;

void init(int N) {
    adj.assign(N, vector<int>());
    cap.assign(N, vector<T>(N));
}

void addEdge(int u, int v, T icap, T iflow = 0) {
    cap[u][v] = icap - iflow;
    // cap[v][u] = cap[u][v]; // if graph is undirected
    if (!cap[u][v])
        adj[u].push_back(v), adj[v].push_back(u);
}

// O(N)
T sssp(int s, int t, vector<int> &dad) {
    dad.assign(adj.size(), -1);
    queue<pair<int, T>> q;
    dad[s] = s, q.push(s);
    while (q.size()) {
        int u = q.front().first;
        T pathMinCap = q.front().second;
        q.pop();
        for (int v : adj[u])
            if (dad[v] == -1 && cap[u][v]) {
                dad[v] = u;
                T flow = min(pathMinCap, cap[u][v]);
                if (v == t) return flow;
                q.push({v, flow});
            }
    }
    return 0;
}
```

Flow

Max Flow Min Cost

```
// O(E^2 * V)
T maxFlowMinCut(int s, int t) {
    T maxFlow = 0;
    vector<int> dad;
    while (T flow = bfs(s, t, dad)) {
        maxFlow += flow;
        int u = t;
        while (u != s) {
            cap[dad[u]][u] -= flow, cap[u][dad[u]] += flow;
            u = dad[u];
        }
    }
    return maxFlow;
}
```

Max Flow Min Cut Dinic

```
// cap[a][b] = Capacity from a to b
// flow[a][b] = flow occupied from a to b
// level[a] = level in graph of node a
// iflow = initial flow, icap = initial capacity
// pathMinCap = capacity bottleneck for a path (s->t)
```

```
typedef int T;
vector<int> level;
vector<vector<int>> adj;
vector<vector<T>> cap, flow;
T inf = 1 << 30;
```

```
void init(int N) {
    adj.assign(N, vector<int>());
    cap.assign(N, vector<int>(N));
    flow.assign(N, vector<int>(N));
}
```

```
void addEdge(int u, int v, T icap, T iflow = 0) {
    if (!cap[u][v])
        adj[u].push_back(v), adj[v].push_back(u);
    cap[u][v] = icap;
    // cap[v][u] = icap; // if graph is undirected
    flow[u][v] += iflow, flow[v][u] -= iflow;
}
```

```
bool levelGraph(int s, int t) {
    level.assign(adj.size(), 0);
    level[s] = 1;
    queue<int> q;
    q.push(s);
    while (!q.empty()) {
        int u = q.front();
        q.pop();
        for (int &v : adj[u]) {
            if (!level[v] && flow[u][v] < cap[u][v]) {
                q.push(v);
                level[v] = level[u] + 1;
            }
        }
    }
    return level[t];
}
```

```
T blockingFlow(int u, int t, T pathMinCap) {
    if (u == t) return pathMinCap;
    for (int v : adj[u]) {
        T capLeft = cap[u][v] - flow[u][v];
        if (level[v] == (level[u] + 1) && capLeft > 0)
            if (T pathMaxFlow = blockingFlow(
                v, t, min(pathMinCap, capLeft))) {
                flow[u][v] += pathMaxFlow;
                flow[v][u] -= pathMaxFlow;
                return pathMaxFlow;
            }
    }
    return 0;
}
```

```
// O(E * V^2)
T maxFlowMinCut(int s, int t) {
    if (s == t) return inf;
    T maxFlow = 0;
    while (levelGraph(s, t))
        while (T flow = blockingFlow(s, t, inf))
            maxFlow += flow;
    return maxFlow;
}
```

Max Flow Min Cut Edmonds-Karp

```
// cap[a][b] = Capacity left from a to b
// iflow = initial flow, icap = initial capacity
// pathMinCap = capacity bottleneck for a path (s->t)
```

```
typedef int T;
vector<int> level;
vector<vector<int>> adj, cap;
T inf = 1 << 30;
```

```
void init(int N) {
    adj.assign(N, vector<int>());
    cap.assign(N, vector<int>(N));
}
```

```
void addEdge(int u, int v, T icap, T iflow = 0) {
    if (!cap[u][v])
        adj[u].push_back(v), adj[v].push_back(u);
    cap[u][v] = icap - iflow;
    // cap[v][u] = cap[u][v]; // if graph is undirected
}
```

```
// O(N)
T bfs(int s, int t, vector<int> &dad) {
    dad.assign(adj.size(), -1);
    queue<pair<int, T>> q;
    dad[s] = s, q.push(s);
    while (q.size()) {
        int u = q.front().first;
        T pathMinCap = q.front().second;
        q.pop();
        for (int v : adj[u])
            if (dad[v] == -1 && cap[u][v]) {
                dad[v] = u;
                T flow = min(pathMinCap, cap[u][v]);
                if (v == t) return flow;
                q.push({v, flow});
            }
    }
    return 0;
}

// O(E^2 * V)
T maxFlowMinCut(int s, int t) {
    T maxFlow = 0;
    vector<int> dad;
    while (T flow = bfs(s, t, dad)) {
        maxFlow += flow;
        int u = t;
        while (u != s) {
            cap[dad[u]][u] -= flow, cap[u][dad[u]] += flow;
            u = dad[u];
        }
    }
    return maxFlow;
}
```

Maximum Bipartite Matching

```
// mbm = maximum bipartite matching
#include "Max Flow Min Cut Dinic.cpp"

void addEdgeMBM(int u, int v) {
    addEdge(u += 2, v += 2, 1);
    addEdge(0, u, 1);
    addEdge(v, 1, 1);
}

// O(E * V^2)
T mbm() { return maxFlowMinCut(0, 1); }
```

Shortest Paths

0 - 1 BFS

```
// s = source
typedef int T;
long long int inf = (1ll << 62) - 1;
vector<vector<int>> adj;
unordered_map<int, unordered_map<int, T>> weight;
```

```
void init(int N) {
    adj.assign(N, vector<int>());
    weight.clear();
}

void addEdge(int u, int v, T w, bool isDirected = 0) {
    adj[u].push_back(v);
    weight[u][v] = w;
    if (isDirected) return;
    adj[v].push_back(u);
    weight[v][u] = w;
}

// O(E)
vector<T> bfs(int s) {
    vector<long long int> dist(adj.size(), inf);
    dist[s] = 0;
    deque<int> q;
    q.push_front(s);
    while (q.size()) {
        int u = q.front(); q.pop_front();
        for (auto& v : adj[u]) {
            T d = dist[u] + weight[u][v];
            if (d < dist[v])
                weight[u][v] ? q.push_back(v)
                             : q.push_front(v);
        }
    }
    return dist;
}
```

Bellman Ford

```
// s = source
// returns {} if there is a negative weight cycle
typedef int T;
long long int inf = (1ll << 62) - 1;
vector<vector<int>> adj;
unordered_map<int, unordered_map<int, T>> weight;

void init(int N) {
    adj.assign(N, vector<int>());
    weight.clear();
}

void addEdge(int u, int v, T w, bool isDirected = 0) {
    adj[u].push_back(v);
    weight[u][v] = w;
    if (isDirected) return;
    adj[v].push_back(u);
    weight[v][u] = w;
}
```

```
// O(V * E)
vector<T> bellmanFord(int s) {
    vector<long long int> dist(adj.size(), inf);
    dist[s] = 0;
    for (int i = 1; i <= adj.size(); i++)
        for (int u = 0; u < adj.size(); u++)
            for (auto &v : adj[u]) {
                T d = dist[u] + weight[u][v];
                if (dist[u] != inf && d < dist[v]) {
                    if (i == adj.size()) return {};
                    dist[v] = d;
                }
            }
    return dist;
}
```

Bellman Ford Fast

```
// s = source, its = iterations of node u
// returns {} if there is a negative weight cycle
typedef int T;
long long int inf = (1ll << 62) - 1;
vector<vector<int>>> adj;
unordered_map<int, unordered_map<int, T>> weight;

void init(int N) {
    adj.assign(N, vector<int>());
    weight.clear();
}

void addEdge(int u, int v, T w, bool isDirected = 0) {
    adj[u].push_back(v);
    weight[u][v] = w;
    if (isDirected) return;
    adj[v].push_back(u);
    weight[v][u] = w;
}

// O(V * E)
vector<T> bellmanFordFast(int s) {
    vector<long long int> dist(adj.size(), inf);
    vector<int> its(adj.size()), inqueue(adj.size());
    queue<int> q;
    q.push(s), dist[s] = 0, its[s] = 1;
    while (!q.empty()) {
        int u = q.front(); q.pop(), inqueue[u] = 0;
        for (auto &v : adj[u]) {
            T d = dist[u] + weight[u][v];
            if (d < dist[v]) {
                dist[v] = d;
                if (!inqueue[v]) q.push(v), its[v]++;
                if (its[v] == adj.size()) return {};
            }
        }
    }
    return dist;
}
```

Dijkstra

```
// s = source
typedef int T;
typedef pair<T, int> DistNode;
T inf = 1 << 30;
vector<vector<int>>> adj;
unordered_map<int, unordered_map<int, T>> weight;

void init(int N) {
    adj.assign(N, vector<int>());
    weight.clear();
}

void addEdge(int u, int v, T w, bool isDirected = 0) {
    adj[u].push_back(v);
    weight[u][v] = w;
    if (isDirected) return;
    adj[v].push_back(u);
    weight[v][u] = w;
}

// ~ O(E * lg(V))
vector<T> dijkstra(int s) {
    vector<long long int> dist(adj.size(), inf);
    priority_queue<DistNode> q;
    q.push({0, s}), dist[s] = 0;
    while (q.size()) {
        DistNode top = q.top();
        q.pop();
        int u = top.second;
        if (dist[u] < -top.first) continue;
        for (int &v : adj[u]) {
            T d = dist[u] + weight[u][v];
            if (d < dist[v]) q.push({-(dist[v] = d), v});
        }
    }
    return dist;
}
```

Floyd Warshall

```
// d = distance
typedef int T;
long long int inf = (1ll << 62) - 1;
vector<vector<long long int>>> d;

void init(int n) {
    d.assign(n, vector<long long int>(n, inf));
    for (int i = 0; i < n; i++) d[i][i] = 0;
}

void addEdge(int u, int v, T w, bool isDirected = 0) {
    d[u][v] = w;
    if (isDirected) return;
    d[v][u] = w;
}
```

```
// O(V^3)
void floydwarshall() {
    for (int k = 0; k < d.size(); k++)
        for (int u = 0; u < d.size(); u++)
            for (int v = 0; v < d.size(); v++)
                d[u][v] = min(d[u][v], d[u][k] + d[k][v]);
}
```

Shortest Path in Directed Acyclic Graph

```
// s = source
#include "../Topological Sort.cpp"
typedef int T;
long long int inf = (1ll << 62) - 1;
unordered_map<int, unordered_map<int, T>> weight;

void init(int N) {
    adj.assign(N, vector<int>());
    vis.assign(N, 0);
    toposorted.clear();
    weight.clear();
}

void addEdge(int u, int v, int w) {
    adj[u].push_back(v);
    weight[u][v] = w;
}

// O(N)
vector<T> dagsssp(int s) {
    vector<long long int> dist(adj.size(), inf);
    dist[s] = 0;
    toposort(s);
    while (toposorted.size()) {
        int u = toposorted.back();
        toposorted.pop_back();
        for (auto &v : adj[u]) {
            T d = dist[u] + weight[u][v];
            if (d < dist[v]) dist[v] = d;
        }
    }
    return dist;
}
```

Maths

Data Structures

Matrix

```
template <class T>
struct Matrix {
    int rows, cols;
    vector<vector<T>> m;
```

```
Matrix(int r, int c) : rows(r), cols(c) {
    m.assign(r, vector<T>(c));
}

Matrix(const vector<vector<T>>& b)
    : rows(b.size()), cols(b[0].size()), m(b) {}

Matrix(int n) {
    m.assign(n, vector<T>(n));
    while (n--> 0) m[n][n] = 1;
}

vector<T>& operator[](int i) const {
    return const_cast<Matrix*>(this)->m[i];
}

// O(N * M)
Matrix operator+(const Matrix& b) {
    Matrix ans(rows, cols);
    for (int i = 0; i < rows; i++)
        for (int j = 0; j < m[i].size(); j++)
            ans[i][j] = m[i][j] + b[i][j];
    return ans;
}

// O(N * M)
Matrix operator-(const Matrix& b) {
    Matrix ans(rows, cols);
    for (int i = 0; i < rows; i++)
        for (int j = 0; j < m[i].size(); j++)
            ans[i][j] = m[i][j] - b[i][j];
    return ans;
}

// O(N^3)
Matrix operator*(const Matrix& b) {
    if (cols != b.rows) return Matrix(0, 0);
    Matrix ans(rows, b.cols);
    for (int i = 0; i < rows; i++)
        for (int j = 0; j < b[i].size(); j++)
            for (int k = 0; k < b.rows; k++)
                ans[i][j] += m[i][k] * b[k][j];
    return ans;
}

Matrix& operator+=(const Matrix& b) {
    return *this = *this + b;
}

Matrix& operator-=(const Matrix& b) {
    return *this = *this - b;
}

Matrix& operator*=(const Matrix& b) {
    return *this = *this * b;
}
};
```


Combinatorics

Binomial Coefficient

```
typedef long long int li;

// O(k)
li nCk(li n, int k) {
    double ans = 1;
    for (int i = 1; i <= k; i++)
        ans = ans * (n - k + i) / i;
    return (li)(ans + 0.01);
}
```

Binomial Coefficient (Pascal's Triangle)

```
typedef long long int li;

vector<vector<li>> nCk(int maxN) {
    vector<vector<li>> c(++maxN, vector<li>(maxN));
    c[0][0] = 1;
    for (int n = 1; n < maxN; n++) {
        c[n][0] = c[n][n] = 1;
        for (int k = 1; k < n; k++)
            c[n][k] = c[n - 1][k - 1] + c[n - 1][k];
    }
    return c;
}
```

Binomial Coefficient Modulo Large Prime

```
#include "../Number Theory/Modular Multiplicative
  → Inverse.cpp"
#include "Factorials Modulo M.cpp"
```

```
typedef long long int li;

// O(lg(p))
li nCk(int n, int k, li p, vector<li> &fact) {
    return fact[n] * modInv(fact[k], p) % p *
        modInv(fact[n - k], p) % p;
}
```

Factorials Modulo M

```
typedef long long int li;

vector<li> factorials(int n, li m) {
    vector<li> fact(++n);
    fact[0] = 1;
    for (int i = 1; i < n; i++)
        fact[i] = fact[i - 1] * i % m;
    return fact;
}
```

Number Theory

Binary Exponentiation

```
typedef long long int li;

li binPow(li a, li p) {
    li ans = 1LL;
    while (p) {
        if (p & 1LL) ans *= a;
        a *= a, p >>= 1LL;
    }
    return ans;
}
```

Convert 10-Based Number To Base B

```
// O(log(n)) [msb, ..., lsb]
vector<int> toBaseB(int n, int b) {
    vector<int> ans;
    while (n) ans.push_back(n % b), n /= b;
    reverse(ans.begin(), ans.end());
    return ans;
}
```

Convert B-Based Number To Base 10

```
// O(log(n)) [msb, ..., lsb]
int toBase10(vector<int>& n, int b) {
    int ans = 0;
    for (int i = n.size() - 1, p = 1; ~i; i--, p *= b)
        ans += n[i] * p;
    return ans;
}
```

Diophantine Equation (Base Solution)

```
#include "Extended Euclidean Algorithm.cpp"
typedef long long int li;
// ax + by = c = gcd(a, b)
pair<li, li> diophantineBase(li a, li b, li c) {
    li d, x, y;
    tie(d, x, y) = extendedGCD(a, b);
    if (c % d) return {0, 0};
    return {c / d * x, c / d * y};
}
```


Diophantine Equation (Particular Solution)

```
#include "Extended Euclidean Algorithm.cpp"
typedef long long int li;
// ax + by = c
// returns the i-th solution or {0, 0} if no solutions
pair<li, li> diophantineSol(li a, li b, li c, li i) {
    li d, x, y;
    tie(d, x, y) = extendedGCD(a, b);
    if (c % d) return {0, 0};
    return {c / d * x + i / d * b,
           c / d * y - i / d * a};
}
```

Divisibility Criterion

```
def divisorCriteria(n, lim):
    results = []
    tenElevated = 1
    for i in range(lim):
        # remainder = pow(10, i, n)
        remainder = tenElevated % n
        negremainder = remainder - n
        if(remainder <= abs(negremainder)):
            results.append(remainder)
        else:
            results.append(negremainder)
        tenElevated *= 10
    return results

def testDivisibility(dividend, divisor,
    ↪ divisor_criteria):
    dividend = str(dividend)
    addition = 0
    dividendSize = len(dividend)
    i = dividendSize - 1
    j = 0
    while j < dividendSize:
        addition += int(dividend[i]) *
            ↪ divisor_criteria[j]
        i -= 1
        j += 1
    return addition % divisor == 0

if __name__ == '__main__':
    dividend, divisor = map(int, input().split())
    divisor_criteria = divisorCriteria(divisor,
        ↪ len(str(dividend)))
    print(divisor_criteria)
    print(testDivisibility(dividend, divisor,
        ↪ divisor_criteria))
```

Divisors

```
// divs = divisors

typedef long long int li;
typedef vector<li> V;

// O(sqrt(N))
V getDivisors(li n) {
    V divs;
    for (li i = 1; i * i <= n; i++)
        if (!(n % i)) {
            divs.push_back(i);
            if (i * i != n) divs.push_back(n / i);
        }
    return divs;
}
```

Divisors Pollard Rho

```
// pf = primeFactors, divs = divisors

#include "../Primes/Prime Factorization Pollard
    ↪ Rho.cpp"

typedef vector<li> V;

void divisors(Map &pf, V &divs, li ans, li p) {
    auto next = ++pf.find(p);
    int power = pf[p];
    for (li k = 0; k <= power; k++, ans *= p) {
        if (next == pf.end()) divs.push_back(ans);
        else divisors(pf, divs, ans, next->first);
    }
}

// O(number of pf)
V getDivisors(li n) {
    Map pf = getPrimeFactors(n);
    V divs;
    divisors(pf, divs, 1, pf.begin()->first);
    return divs;
}
```

Euler's Phi

```
#include "../Primes/Prime Factorization Pollard
    ↪ Rho.cpp"
// #include "../Primes/Prime Factorization.cpp"

// counts the number of integers (Xi) between 1 and n
// which are coprime (gcd(Xi, n) = 1) to n
li phi(li n) {
    Map pf = getPrimeFactors(n);
    if (pf.count(n)) return n - 1; // if n is prime
    for (auto &p : pf) n -= n / p.first;
    return n;
}
```

Extended Euclidean Algorithm

```
#include "Modulo with negative numbers.cpp"
#include "../Util/Floor Of Division Between
→ Integers.cpp"
typedef long long int li;

// gcd(a, b) = ax + by
tuple<li, li, li> extendedGCD(li a, li b) {
    if (!a) return {b, 0, 1};
    li d, x, y;
    tie(d, x, y) = extendedGCD(mod(b, a), a);
    return {d, y - floor(b, a) * x, x};
} // {gcd(a, b), x, y}
```

GCD

```
typedef long long int li;

li gcd(li a, li b) {
    return !b ? a : gcd(b, a % b);
}

// Iterative version
li gcdI(li a, li b) {
    while (b) a %= b, swap(a, b);
    return a;
}
```

LCM

```
#include "GCD.cpp"

int lcm(li a, li b) {
    int d = gcd(a, b);
    return d ? a / d * b : 0;
}
```

Modular Exponentiation

```
#include "../Modular Multiplication.cpp"

// O(lg(p))
li pow(li a, li p, li m) {
    li ans = 1;
    for (a %= m; p; a = multiply(a, a, m), p >>= 1)
        if (p & 1LL) ans = multiply(ans, a, m);
    return ans;
}
```

Modular Multiplication

```
typedef long long int li;

// O(lg(b))
li multiply(li a, li b, li m) {
    li ans = 0;
    for (a %= m; b;
        b >>= 1, a <= 1, a = (a < m ? a : a - m))
        if (b & 1)
            ans += a, ans = (ans < m ? ans : ans - m);
    return ans;
}
```

Modular Multiplicative Inverse

```
// n = number, m = modulo
#include "Extended Euclidean Algorithm.cpp"

// O(lg(N))
li modInv(li n, li m) {
    li g, x, y;
    tie(g, x, y) = extendedGCD(n, m);
    if (g != 1) throw "No solution";
    return (x % m + m) % m;
}
```

Modular Multiplicative Inverses Modulo M [1, M)

```
// O(m)
vector<int> modinvs(int m) {
    vector<int> inv(m);
    inv[1] = 1;
    for (int i = 2; i < m; i++)
        inv[i] = (m - (m / i) * inv[m % i] % m) % m;
    return inv;
}
```

Modulo with negative numbers

```
typedef long long int li;

// if b is positive the answer is positive
// if b is negative the answer is negative
li mod(li a, li b) { return (b + (a % b)) % b; }
```

Primes

Is Prime Miller Rabin

```
#include "../Number Theory/Modular Exponentiation.cpp"
```

```
bool isPrime(lli p, int k = 20) {
    if (p == 2 || p == 3) return 1;
    if ((~p & 1) || p == 1) return 0;
    lli d = p - 1, phi = d, r = 0;
    while (~d & 1) d >>= 1, r++;
    while (k--) {
        // set seed with: int main() { srand(time(0)); }
        lli a = 2 + rand() % (p - 3); // [2, p - 2]
        lli e = pow(a, d, p), r2 = r;
        if (e == 1 || e == phi) continue;
        bool flag = 1;
        while (--r2) {
            e = multiply(e, e, p);
            if (e == 1) return 0;
            if (e == phi) {
                flag = 0;
                break;
            }
        }
        if (flag) return 0;
    }
    return 1;
}
```

Prime Factorization

```
typedef long long int li;
// if li == __int128_t: use map<li, int> Map;
typedef unordered_map<li, int> Map;

// ~O(sqrt(N) * lg(N))
Map getPrimeFactors(li n) {
    Map pf;
    while (~n & 1) pf[2]++, n >>= 1;
    for (li i = 3; i * i <= n; i += 2)
        while (!(n % i)) pf[i]++, n /= i;
    if (n > 1) pf[n]++;
    return pf;
}
```

Prime Factorization (Sieve)

```
#include "Primes Sieve.cpp"

typedef unordered_map<int, int> Map;

// O(lg(N)) n <= sieve.size()
Map getPrimeFactors(int n) {
    Map pf;
    while (n > 1) {
        int p = n & 1 ? sieve[n] : 2, c;
        if (!p) p = n;
        while (n % p == 0) n /= p, c++;
        pf[p] = c;
    }
    return pf;
}
```

Prime Factorization (Sieve) 2

```
#include "Primes Sieve.cpp"

typedef long long int li;
// if li == __int128_t: use map<li, int> Map;
typedef unordered_map<li, int> Map;

// O(sqrt(N)) n <= sieve.size() ^ 2
Map getPrimeFactors(li n) {
    Map pf;
    for (int& p : primes) {
        if (p * p > n) break;
        int c;
        while (n % p == 0) n /= p, c++;
        if (c) pf[p] = c;
    }
    if (n > 1) pf[n] = 1;
    return pf;
}
```

Prime Factorization Pollard Rho

```
// pf = prime factors

#include "../Number Theory/GCD.cpp"
#include "../Is Prime Miller Rabin.cpp"

typedef long long int li;
// if li == __int128_t: use map<li, int> Map;
typedef unordered_map<li, int> Map;

li _abs(li a) { return a < 0 ? -a : a; }
```

```

li getRandomDivisor(li n) {
    if (~n & 1) return 2;
    li c = 1 + rand() % (n - 1), a = 2, b = 2, d = 1;
    auto f = [&](li x) {
        return multiply(x, x, n) + c) % n;
    };
    while (d == 1)
        a = f(a), b = f(b), d = gcd(_abs(a - b), n);
    return d;
}

void getpf(li n, Map &pf) {
    if (n == 1LL) return;
    if (isPrime(n)) {
        pf[n]++;
        return;
    }
    li divisor = getRandomDivisor(n);
    getpf(divisor, pf), getpf(n / divisor, pf);
}

// ~O(N^(1/4))
Map getPrimeFactors(li n) {
    Map pf;
    getpf(n, pf);
    return pf;
}

```

Primes Sieve

```

vector<int> sieve, primes;

// ~O(N * lg(lg(N)))
void primeSieve(int n) {
    sieve.assign(n + 1, 0);
    primes = {};
    for (int i = 3; i * i <= n; i += 2)
        if (!sieve[i])
            for (int j = i * i; j <= n; j += 2 * i)
                if (!sieve[j]) sieve[j] = i;
    primes.push_back(2);
    for (int i = 3; i < n; i++)
        if (!sieve[i] && (i & 1)) primes.push_back(i);
}

```

Ranges

Data Structures

BIT

```

// 0-indexed
#include "../BITs Manipulation/Most Significant Set
↳ Bit.cpp";

```

```
template <class T>
```

```
struct BIT {
    T neutro = 0;
    vector<T> bit;
```

```
    BIT(int n) { bit.assign(++n, neutro); }
```

```
    inline T F(T a, T b) {
        return a + b;
        // return a * b;
    }

```

```
    // Inverse of F
    inline T I(T a, T b) {
        return a - b;
        // return a / b;
    }

```

```
    // O(N)
    void build() {
        for (int i = 1; i < bit.size(); i++) {
            int j = i + (i & -i);
            if (j < bit.size()) bit[j] = F(bit[j], bit[i]);
        }
    }

```

```
    // O(lg(N))
    void update(int i, T val) {
        for (i++; i < bit.size(); i += i & -i)
            bit[i] = F(bit[i], val);
    }

```

```
    // O(lg(N))
    T query(int i) {
        T ans = neutro;
        for (i++; i; i -= i & -i) ans = F(ans, bit[i]);
        return ans;
    }

```

```
    // O(lg(N)), [l, r]
    T query(int l, int r) {
        return I(query(r), query(--l));
    }

```

```
// O(lg(N)) binary search in prefix sum array
T lowerBound(T x) {
    T acum = neutro;
    int pos = 0;
    for (int i = msb(bit.size() - 1); i; i >>= 1)
        if ((pos | i) < bit.size() &&
            F(acum, bit[pos | i]) < x)
            acum = F(acum, bit[pos | i]);
    return pos;
}

T& operator[](int i) { return bit[++i]; }
};
```

BIT Range Update

```
typedef long long int T;
T neutro = 0;
vector<T> bit1, bit2;

void initVars(int n) {
    bit1.assign(++n, neutro);
    bit2 = bit1;
}

// O(lg(N))
void update(vector<T> &bit, int i, T val) {
    for (i++; i < bit.size(); i += i & -i)
        bit[i] += val;
}

// O(lg(N)), [l, r]
void update(int l, int r, T val) {
    update(bit1, l, val);
    update(bit1, r + 1, -val);
    update(bit2, r + 1, val * r);
    update(bit2, l, -val * (l - 1));
}

// O(lg(N))
T query(vector<T> &bit, int i) {
    T ans = neutro;
    for (i++; i; i -= i & -i) ans += bit[i];
    return ans;
}

// O(lg(N))
T query(int i) {
    return query(bit1, i) * i + query(bit2, i);
}

// O(lg(N)), [l, r]
T query(int l, int r) {
    return query(r) - query(l - 1);
}
```

Segment Tree

```
// st = segment tree. st[1] = root;
// neutro = operation neutral value
// e.g. for sum is 0, for multiplication
// is 1, for gcd is 0, for min is INF, etc.

template <class T>
struct SegmentTree {
    T neutro = 0;
    int N;
    vector<T> st;
    function<T(T, T)> F;

    SegmentTree(int n, int neut,
                T f(T, T) = [](int a, int b) { return a + b; };)
        : neutro(neut), st(2 * n, neutro), N(n), F(f) {}

    // O(2N)
    void build() {
        for (int i = N - 1; i; i--)
            st[i] = F(st[i << 1], st[i << 1 | 1]);
    }

    // O(lg(2N)), works like replacing arr[i] with val
    void update(int i, T val) {
        for (st[i += N] = val; i > 1; i >>= 1)
            st[i >> 1] = F(st[i], st[i ^ 1]);
    }

    // O(lg(2N)), [l, r]
    T query(int l, int r) {
        T ans = neutro;
        for (l += N, r += N; l <= r; l >>= 1, r >>= 1) {
            if (l & 1) ans = F(ans, st[l++]);
            if (~r & 1) ans = F(ans, st[r--]);
        }
        return ans;
    }

    T& operator[](int i) { return st[i + N]; }
};
```

Segment Tree Lazy Propagation

```
// st = segment tree, st[1] = root, H = height of d
// u = updates, d = delayed updates
// neutro = operation neutral val
// e.g. for sum is 0, for multiplication
// is 1, for gcd is 0, for min is INF, etc.

template <class T>
struct SegmentTree {
    T neutro = 0;
    int N, H;
    vector<T> st, d;
    vector<bool> u;
    function<T(T, T)> F;

    SegmentTree(int n, T val,
                T f(T, T) = [](int a, int b) { return a + b; };)
        : st(2 * n, val), d(n), u(n), F(f) {
        H = sizeof(int) * 8 - __builtin_clz(N = n);
    }
};
```

```

void apply(int i, T val, int k) {
    // operation to update st[i] in O(1) time
    st[i] += val * k; // updates the tree
    // operation to update d[i] in O(1) time
    // which updates values for future updates
    if (i < N) d[i] += val, u[i] = 1;
}

void calc(int i) {
    if (!u[i]) st[i] = F(st[i << 1], st[i << 1 | 1]);
}

// O(2N)
void build() {
    for (int i = N - 1; i; i--) calc(i);
}

// O(lg(N))
void build(int p) {
    while (p > 1) p >>= 1, calc(p);
}

// O(lg(N))
void push(int p) {
    for (int s = H, k = 1 << (H - 1); s;
         s--, k >>= 1) {
        int i = p >> s;
        if (u[i]) {
            apply(i << 1, d[i], k);
            apply(i << 1 | 1, d[i], k);
            u[i] = 0, d[i] = 0;
        }
    }
}

// O(lg(N)), [l, r]
void update(int l, int r, T val) {
    push(l += N), push(r += N);
    int ll = l, rr = r, k = 1;
    for (; l <= r; l >>= 1, r >>= 1, k <= 1) {
        if (l & 1) apply(l++, val, k);
        if (~r & 1) apply(r--, val, k);
    }
    build(ll), build(rr);
}

// O(lg(2N)), [l, r]
T query(int l, int r) {
    push(l += N), push(r += N);
    T ans = neutro;
    for (; l <= r; l >>= 1, r >>= 1) {
        if (l & 1) ans = F(ans, st[l++]);
        if (~r & 1) ans = F(ans, st[r--]);
    }
    return ans;
}

T& operator[](int i) { return st[i + N]; }
};

```

Sparse Table

```

// st = sparse table, Arith = Arithmetic
typedef int T;
int neutro = 0;
vector<vector<T>> st;

T F(T a, T b) {
    // return min(a, b);
    return __gcd(a, b);
    // return a + b; // Arith
    // return a * b; // Arith
}

// O(N * lg(N))
void build(vector<T> &arr) {
    st.assign(log2(arr.size()), vector<T>(arr.size()));
    st[0] = arr;
    for (int i = 1; (1 << i) <= arr.size(); i++)
        for (int j = 0; j + (1 << i) <= arr.size(); j++)
            st[i][j] = F(st[i - 1][j],
                          st[i - 1][j + (1 << (i - 1))]);
}

// O(1), [l, r]
T query(int l, int r) {
    int i = log2(r - l + 1);
    return F(st[i][l], st[i][r + 1 - (1 << i)]);
}

// O(lg(N)), [l, r]
T queryArith(int l, int r) {
    T ans = neutro;
    while (true) {
        int k = log2(r - l + 1);
        ans = F(ans, st[k][l]);
        l += 1 << k;
        if (l > r) break;
    }
    return ans;
}

```

Wavelet Tree

```

// pref = prefix sum
// lte = less than or equal, 1-indexed
// A = hi = max_element(from, to)
// lcount = left children count
// lo = min_element(from, to)
struct WaveletTree {
    WaveletTree *l, *r;
    int lo, hi;
    vector<int> lcount, pref;
};

```

```

// O(N*lg(A))
WaveletTree(vector<int>::iterator from,
            vector<int>::iterator to, int lo,
            int hi) {
    this->lo = lo, this->hi = hi;
    if (lo == hi or from == to) return;
    int mid = (lo + hi) >> 1;
    auto f = [mid](int x) { return x <= mid; };
    lcount.reserve(to - from + 1);
    pref.reserve(to - from + 1);
    lcount.push_back(0);
    pref.push_back(0);
    for (auto it = from; it != to; it++)
        lcount.push_back(lcount.back() + f(*it)),
        pref.push_back(pref.back() + *it);
    auto pivot = stable_partition(from, to, f);
    l = new WaveletTree(from, pivot, lo, mid);
    r = new WaveletTree(pivot, to, mid + 1, hi);
}

// O(lg(A)) frequency of k in [a, b]
int freq(int a, int b, int k) {
    if (a > b or k < lo or k > hi) return 0;
    if (lo == hi) return b - a + 1;
    int lc = lcount[a - 1], rc = lcount[b];
    if (k > ((lo + hi) >> 1))
        return r->freq(a - lc, b - rc, k);
    return l->freq(lc + 1, rc, k);
}

// O(lg(A)) kth-Smallest element in [a, b]
int kth(int a, int b, int k) {
    if (a > b) return 0;
    if (lo == hi) return lo;
    int lc = lcount[a - 1], rc = lcount[b],
        inleft = rc - lc;
    if (k > inleft)
        return r->kth(a - lc, b - rc, k - inleft);
    return l->kth(lc + 1, rc, k);
}

// O(lg(A)) count of elements <= to k in [a, b]
int lte(int a, int b, int k) {
    if (a > b or k < lo) return 0;
    if (hi <= k) return b - a + 1;
    int lc = lcount[a - 1], rc = lcount[b];
    return l->lte(lc + 1, rc, k) +
        r->lte(a - lc, b - rc, k);
}

// O(lg(A)) sum of numbers <= to k in [a, b]
int sumlte(int a, int b, int k) {
    if (a > b or k < lo) return 0;
    if (hi <= k) return pref[b] - pref[a - 1];
    int lc = lcount[a - 1], rc = lcount[b];
    return l->sumlte(lc + 1, rc, k) +
        r->sumlte(a - lc, b - rc, k);
}
};

```

Strings

Data Structures

Suffix Automaton

// link[u]: links to the longest suffix which is
// not in the same endpos-equivalence class
// len[u]: length of the longest suffix that
// corresponds to u's endpos-equivalence class
// next[0]: root of suffix automaton

```

struct SuffixAutomaton {
    vector<int> len, link, isClone, first;
    vector<map<char, int>> next;
    int size, last;

    void init(int n) {
        first = isClone = len = link = vector<int>(2 * n);
        next.resize(2 * n);
        len[0] = 0, link[0] = -1, size = 1, last = 0;
    }

    // O(N)
    SuffixAutomaton(const string& s) {
        init(s.size());
        for (const auto& c : s) add(c);
    }

    // O(1)
    void add(const char& c) {
        int p = last, u = size++;
        len[u] = len[p] + 1, first[u] = len[p];
        while (p != -1 && !next[p].count(c))
            next[p][c] = u, p = link[p];
        if (p == -1) link[u] = 0;
        else {
            int q = next[p][c];
            if (len[p] + 1 == len[q]) link[u] = q;
            else {
                int clone = size++;
                first[clone] = first[q];
                len[clone] = len[p] + 1, isClone[clone] = 1;
                link[clone] = link[q], next[clone] = next[q];
                while (p != -1 && next[p][c] == q)
                    next[p][c] = clone, p = link[p];
                link[q] = link[u] = clone;
            }
        }
        last = u;
    }
};

```

```
// O(N)
unordered_set<int> getTerminals() {
    unordered_set<int> terminals;
    for (int p = last; p; p = link[p])
        terminals.insert(p);
    return terminals;
}
};
```

Trie

// wpt = number of words passing through
// w = number of words ending in the node
// c = character

```
struct Trie {

    struct Node {
        // for lexicographical order use 'map'
        // map<char, Node *> ch;
        unordered_map<char, Node *> ch;
        int w = 0, wpt = 0;
    };

    Node *root = new Node();

    // O(STR.SIZE)
    void insert(string str) {
        Node *curr = root;
        for (auto &c : str) {
            if (!curr->ch.count(c))
                curr->ch[c] = new Node();
            curr->wpt++, curr = curr->ch[c];
        }
        curr->wpt++, curr->w++;
    }

    // O(STR.SIZE)
    Node *find(string &str) {
        Node *curr = root;
        for (auto &c : str) {
            if (!curr->ch.count(c)) return nullptr;
            curr = curr->ch[c];
        }
        return curr;
    }

    // O(STR.SIZE) number of words with given prefix
    int prefixCount(string prefix) {
        Node *node = find(prefix);
        return node ? node->wpt : 0;
    }

    // O(STR.SIZE) number of words matching str
    int strCount(string str) {
        Node *node = find(str);
        return node ? node->w : 0;
    }
};
```

```
// O(N)
void getWords(Node *curr, vector<string> &words,
              string &word) {
    if (!curr) return;
    if (curr->w) words.push_back(word);
    for (auto &c : curr->ch) {
        getWords(c.second, words, word += c.first);
        word.pop_back();
    }
}

// O(N)
vector<string> getWords() {
    vector<string> words;
    string word = "";
    getWords(root, words, word);
    return words;
}

// O(N)
vector<string> getWordsByPrefix(string prefix) {
    vector<string> words;
    getWords(find(prefix), words, prefix);
}

// O(STR.SIZE)
bool remove(Node *curr, string &str, int &i) {
    if (i == str.size()) {
        curr->wpt--;
        return curr->w ? !(curr->w = 0) : 0;
    }
    int c = str[i];
    if (!curr->ch.count(c)) return false;
    if (remove(curr->ch[c], str, ++i)) {
        if (!curr->ch[c]->wpt)
            curr->wpt--, curr->ch.erase(c);
        return true;
    }
    return false;
}

// O(STR.SIZE)
int remove(string str) {
    int i = 0;
    return remove(root, str, i);
}
};
```


Distinct Substring Count

```
#include "Data Structures/Suffix Automaton.cpp"

// O(N)
int distinctSubstrCount(const string& s) {
    SuffixAutomaton sa(s);
    vector<int> dp(sa.size());
    function<int(int)> dfs = [&](int u) {
        if (dp[u]) return dp[u];
        for (auto& v : sa.next[u]) dp[u] += dfs(v.second);
        return ++dp[u];
    };
    return dfs(0) - 1;
}
```

KMP

```
// p = pattern, t = text
// f = error function, cf = create error function
// pos = positions where pattern is found in text
```

```
int MAXN = 1000000;
vector<int> f(MAXN + 1);

vector<int> kmp(string &p, string &t, int cf) {
    vector<int> pos;
    if (cf) f[0] = -1;
    for (int i = cf, j = 0; j < t.size(); i = f[i], j++) {
        while (i > -1 && p[i] != t[j]) i = f[i];
        if (cf) f[j] = i;
        if (!cf && i == p.size())
            pos.push_back(j - i), i = f[i];
    }
    return pos;
}

vector<int> search(string &p, string &t) {
    kmp(p, p, -1); // create error function
    return kmp(p, t, 0); // search in text
}
```

Levenshtein Distance (Bottom-Up)

```
int editDistance(string& s, string& t) {
    vector<vector<int>>> dp(t.size() + 1,
                           vector<int>(s.size() + 1));
    for (int i = 1; i <= s.size(); i++) dp[0][i] = i;
    for (int i = 1; i <= t.size(); i++) dp[i][0] = i;
    for (int i = 0; i < t.size(); i++)
        for (int j = 0; j < s.size(); j++)
            dp[i + 1][j + 1] =
                min(dp[i][j] + (t[i] != s[j]),
                   min(dp[i][j + 1], dp[i + 1][j]) + 1);
    return dp[t.size()][s.size()];
}
```

Levenshtein Distance (Top-Down)

```
// i and j are last indexes of s and t respectively
int editDistanceI(string& s, string& t, int i, int j,
                  vector<vector<int>>& dp) {
    if (i < 0) return j + 1;
    if (j < 0) return i + 1;
    if (dp[i][j] != -1) return dp[i][j];
    int replace = editDistance(s, t, i - 1, j - 1, dp);
    int insert = editDistance(s, t, i, j - 1, dp);
    int remove = editDistance(s, t, i - 1, j, dp);
    return dp[i][j] = min(replace + (s[i] != t[j]),
                          min(insert, remove) + 1);
}
```

Levenshtein-Damerau Distance

Lexicographically K-th Substring

```
#include "Data Structures/Suffix Automaton.cpp"

// O(N * ks.size)
vector<string> kthSubstr(string& s, vector<int>& ks) {
    SuffixAutomaton sa(s);
    vector<int> dp(sa.size());
    function<int(int)> dfs = [&](int u) {
        if (dp[u]) return dp[u];
        for (auto& v : sa.next[u]) dp[u] += dfs(v.second);
        return ++dp[u];
    };

    dfs(0);
    vector<string> ans;
    for (auto k : ks) {
        int u = 0;
        string ss;
        while (k)
            for (auto& v : sa.next[u])
                if (k <= dp[v.second]) {
                    ss += v.first, u = v.second, k--;
                    break;
                } else
                    k -= dp[v.second];
        ans.push_back(ss);
    }
    return ans;
}
```

Lexicographically Smallest Cyclic Shift

```
#include "Data Structures/Suffix Automaton.cpp"

// O(N)
string smallestCyclicShift(const string& s) {
    SuffixAutomaton sa(s + s);
    int k = s.size(), u = 0;
    string ans;
    while(k) {
        auto &v = *sa.next[u].begin();
        ans += v.first, u = v.second, k--;
    }
    return ans;
}
```

Longest Common Substring of 2 Strings

```
#include "Data Structures/Suffix Automaton.cpp"

string lcs(string& a, string& b) {
    SuffixAutomaton sa(a);
    int bestLen = 0, bestPos = -1;
    for (int i = 0, u = 0, l = 0; i < b.size(); i++) {
        while (u && !sa.next[u].count(b[i]))
            u = sa.link[u], l = sa.len[u];
        if (sa.next[u].count(b[i]))
            u = sa.next[u][b[i]], l++;
        if (l > bestLen) bestLen = l, bestPos = i;
    }
    return b.substr(bestPos - bestLen + 1, bestLen);
}
```

Longest Common Substring of Several Strings

```
#include <bits/stdc++.h>
using namespace std;

#include "Data Structures/Suffix Automaton.cpp"

string lcs(vector<string>& ss) {
}

int main() {
}
```

Number of Occurrences Of Several Words

```
// t: text, ps: patterns
// cnt[u]: size of u's endpos set

#include "Data Structures/Suffix Automaton.cpp"
```

```
// O(T * Lg(T) + p.size() * ps.size())
vector<int> nOccurrences(string& t,
                        vector<string>& ps) {
    SuffixAutomaton sa(t);
    vector<int> cnt(sa.size(), aux(sa.size), ans;
    for (int u = 0; u < sa.size; aux[u] = u, u++)
        if (!sa.isClone[u]) cnt[u] = 1;
    sort(aux.begin(), aux.end(), [&](int& a, int& b) {
        return sa.len[b] < sa.len[a];
    });
    for (auto& u : aux)
        if (u) cnt[sa.link[u]] += cnt[u];
    for (auto& p : ps)
        for (int u = 0, i = 0; i < p.size(); i++) {
            if (!sa.next[u].count(p[i])) {
                ans.push_back(0);
                break;
            }
            u = sa.next[u][p[i]];
            if (i + 1 == p.size()) ans.push_back(cnt[u]);
        }
    return ans;
}
```

Occurrences Positions Of Several Words

```
// invLink = inverse suffix-link

#include "Data Structures/Suffix Automaton.cpp"

// O(T + OCURRENCES(ps[i]) * ps.size())
vector<vector<int>> occurrencesPos(
    string& t, vector<string>& ps) {
    SuffixAutomaton sa(t);
    vector<vector<int>> ans, invLink(sa.size);
    for (int u = 1; u < sa.size; u++)
        invLink[sa.link[u]].push_back(u);
    function<void(int, int, vector<int>&)> dfs =
        [&](int u, int pLen, vector<int>& oc) {
            if (!sa.isClone[u])
                oc.push_back(sa.first[u] - pLen + 1);
            for (auto& v : invLink[u]) dfs(v, pLen, oc);
        };

    for (auto& p : ps)
        for (int u = 0, i = 0; i < p.size(); i++) {
            if (!sa.next[u].count(p[i])) {
                ans.push_back({});
                break;
            }
            u = sa.next[u][p[i]];
            if (i + 1 == p.size()) {
                vector<int> oc;
                dfs(u, p.size(), oc), ans.push_back(oc);
            }
        }
    return ans;
}
```

Rabin Karp

```
class RollingHash {
public:
    vector<unsigned long long int> pow;
    vector<unsigned long long int> hash;
    unsigned long long int B;

    RollingHash(const string &text) : B(257) {
        int N = text.size();
        pow.resize(N + 1);
        hash.resize(N + 1);
        pow[0] = 1;
        hash[0] = 0;
        for (int i = 1; i <= N; ++i) {
            // in c++ an unsigned long long int is
            // automatically modulated by 2^64
            pow[i] = pow[i - 1] * B;
            hash[i] = hash[i - 1] * B + text[i - 1];
        }
    }

    unsigned long long int getWordHash() {
        return hash[hash.size() - 1];
    }

    unsigned long long int getSubstrHash(int begin,
                                         int end) {
        return hash[end] -
            hash[begin - 1] * pow[end - begin + 1];
    }

    int size() { return hash.size(); }
};

vector<int> rabinKarp(RollingHash &rhStr,
                     string &pattern) {
    vector<int> positions;
    RollingHash rhPattern(pattern);
    unsigned long long int patternHash =
        rhPattern.getWordHash();
    int windowSize = pattern.size(), end = windowSize;
    for (int i = 1; end < rhStr.size(); i++) {
        if (patternHash == rhStr.getSubstrHash(i, end))
            positions.push_back(i);
        end = i + windowSize;
    }
    return positions;
}
```

Techniques

Array Compression (Coordinate Compression)

```
// c = compressed
unordered_map<T, int> Map;
unordered_map<int, T> imap;

template <class T> // don't pass n as param
vector<int> compress(vector<T>& v, int n = 0) {
    set<T> s(v.begin(), v.end());
    vector<int> c(v.size());
    for (auto& e : s) Map[e] = n++;
    for (int i = 0; i < v.size(); i++)
        c[i] = Map[v[i]], imap[c[i]] = v[i];
    return c;
}
```

Map Value To Int

```
// val = value
typedef string Val;
unordered_map<Val, int> intForVal;
unordered_map<int, Val> valForInt;
int mapId = 0;

int Map(Val val) {
    if (intForVal.count(val)) return intForVal[val];
    valForInt[mapId] = val;
    return intForVal[val] = mapId++;
}

Val IMap(int n) { return valForInt[n]; }

void initMapping() {
    mapId = 0;
    intForVal.clear();
    valForInt.clear();
}
```

Binary Search

Binary Search

```
/* if e in v and lower = false (upper_bound):
    r = position of e in v
    l = r + 1
if e in v and lower = true (lower_bound):
    l = position of e in v
    r = l - 1
if e not in v and inv = false it means that:
    v[r] < e < v[l]
if e not in v and inv = true it means that:
    v[r] > e > v[l] */
```

```
// O(lg(r - l)) [l, r]
template <class T>
vector<T> bSearch(vector<T> &v, T e, int l, int r,
                  bool lower = 0, bool inv = 0) {
    int ll = l, rr = r;
    while (l <= r) {
        int mid = l + (r - l) >> 1;
        if (e < v[mid]) inv ? l = mid + 1 : r = mid - 1;
        else if (e > v[mid])
            inv ? r = mid - 1 : l = mid + 1;
        else
            lower ? r = mid - 1 : l = mid + 1;
    } // bSearch[0] tells if the element was found
    return {lower ?
            v[min(rr, l)] == e : v[max(ll, r)] == e, r, l};
}
```

Bitonic Search

```
/* assumes that the bitonic point is the greastest
 * value in v*/

#include "Binary Search.cpp"

template <class T>
vector<vector<int>>> bitonicSearch(vector<T> &v, T e) {
    int l = 0, r = v.size() - 1, mid;
    while (l <= r) {
        mid = l + (r - l) / 2;
        if (!mid || (mid >= v.size() - 1)) break;
        if (v[mid - 1] <= v[mid] && v[mid] > v[mid + 1])
            break;
        if (v[mid - 1] <= v[mid] && v[mid] <= v[mid + 1])
            l = mid + 1;
        if (v[mid - 1] > v[mid] && v[mid] > v[mid + 1])
            r = mid - 1;
    } // at the end of the loop mid = bitonic point
    return {
        bSearch<T>(v, e, 0, mid),
        bSearch<T>(v, e, mid, v.size() - 1, false,
            ↵ true)};
}
```

C++ lower bound

```
// ans[0] = true if e is in v else false
// ans[1] = index pointing to the first element in
// the range [l, r] which compares >= to e.
template <class T>
vector<int> lowerBound(vector<T> &v, T e, int l,
                       int r) {
    auto it = v.begin();
    int i = lower_bound(it + l, it + r, e) - it;
    return {v[i] == e, i};
}
```

C++ upper bound

```
// ans[0] = true if e is in v else false
// ans[1] = index pointing to the first element in
// the range [l, r] which compares > to e.
template <class T>
vector<int> upperBound(vector<T> &v, T e, int l,
                       int r) {
    auto it = v.begin();
    int i = upper_bound(it + l, it + r, e) - it;
    return {v[i - 1] == e, i};
}
```

Lower Bound

```
// ans[0] = true if e is in v else false
// ans[1] = index pointing to the first element in
// the range [l, r] which compares >= to e.
```

```
// O(lg(r - l)) [l, r]
template <class T>
vector<int> lowerBound(vector<T> &v, T e, int l,
                       int r) {
    int rr = r;
    while (l <= r) {
        int mid = l + (r - l) >> 1;
        e <= v[mid] ? r = mid - 1, l = mid + 1;
    }
    return {v[min(rr, l)] == e, l};
}
```

Upper Bound

```
// ans[0] = true if e is in v else false
// ans[1] = index pointing to the first element in
// the range [l, r] which compares > to e.
```

```
// O(lg(r - l)) [l, r]
template <class T>
vector<int> upperBound(vector<T> &v, T e, int l,
                       int r) {
    int ll = l;
    while (l <= r) {
        int mid = l + (r - l) >> 1;
        e < v[mid] ? r = mid - 1, l = mid + 1;
    }
    return {v[max(ll, r)] == e, l};
}
```

Multiple Queries

Mo

```
// q = query
// qs = queries
```

```

struct Query {
    int l, r;
};

int blksize;
vector<Query> qs;
vector<int> arr;

void initVars(int N, int M) {
    arr = vector<int>(N);
    qs = vector<Query>(M);
}

bool cmp(Query &a, Query &b) {
    if (a.l == b.l) return a.r < b.r;
    return a.l / blksize < b.l / blksize;
}

void getResults() {
    blksize = (int)sqrt(arr.size());
    sort(qs.begin(), qs.end(), cmp);
    int prevL = 0, prevR = -1;
    int sum = 0;
    for (auto &q : qs) {
        int L = q.l, R = q.r;
        while (prevL < L) {
            sum -= arr[prevL]; // problem specific
            prevL++;
        }
        while (prevL > L) {
            prevL--;
            sum += arr[prevL]; // problem specific
        }
        while (prevR < R) {
            prevR++;
            sum += arr[prevR]; // problem specific
        }
        while (prevR > R) {
            sum -= arr[prevR]; // problem specific
            prevR--;
        }

        cout << "sum[" << L << ", " << R << "] = " << sum
              << endl;
    }
}

int main() {
    initVars(9, 2);
    arr = {1, 1, 2, 1, 3, 4, 5, 2, 8};
    qs = {{0, 8}, {3, 5}};
    getResults();
}

```

SQRT Decomposition

```

// sum of elements in range
int neutro = 0;
vector<int> arr;
vector<int> blks;

```

```

void initVars(int n) {
    arr.assign(n, neutro);
    blks.assign(sqrt(n), neutro);
}

void preprocess() {
    for (int i = 0, j = 0; i < arr.size(); i++) {
        if (i == blks.size() * j) j++;
        blks[j - 1] += arr[i]; // problem specific
    }
}

// problem specific
void update(int i, int val) {
    blks[i / blks.size()] += val - arr[i];
    arr[i] = val;
}

int query(int l, int r) {
    int sum = 0;
    int lblk = l / blks.size();
    if (l != blks.size() * lblk++)
        while (l < r && l != lblk * blks.size()) {
            sum += arr[l]; // problem specific
            l++;
        }

    while (l + blks.size() <= r) {
        sum += blks[l / blks.size()]; // problem specific
        l += blks.size();
    }
    while (l <= r) {
        sum += arr[l]; // problem specific
        l++;
    }
    return sum;
}

int main() {
    initVars(10);
    arr = {1, 5, 2, 4, 6, 1, 3, 5, 7, 10};
    preprocess();
    for (int i = 0; i < blks.size() + 1; i++)
        cout << blks[i] << " ";
    // output: 8 11 15 10
    cout << endl;
    cout << query(3, 8) << " ";
    cout << query(1, 6) << " ";
    update(8, 0);
    cout << query(8, 8) << endl;
    // output: 26 21 0
    return 0;
}

```

Trees And Heaps

Red Black Tree

```
template <class K, class V>
struct RedBlackTree {
    struct Node {
        K key;
        V val;
        Node *l = nullptr, *r = nullptr; // left, right
        bool isRed;
        Node(K k, V v, bool isRed)
            : key(k), val(v), isRed(isRed) {}
    };

    Node *root = nullptr;

    int compare(K a, K b) { return a < b ? -1 : a > b; }

    // O(lg(N))
    V get(K key) {
        Node *t = root;
        while (t) {
            if (key == t->key) return t->val;
            else if (key < t->key) t = t->l;
            else t = t->r;
            throw "Key doesn't exist";
        }

        Node *rotateLeft(Node *t) {
            Node *x = t->r;
            t->r = x->l;
            x->l = t;
            x->isRed = t->isRed;
            t->isRed = 1;
            return x;
        }

        Node *rotateRight(Node *t) {
            Node *x = t->l;
            t->l = x->r;
            x->r = t;
            x->isRed = t->isRed;
            t->isRed = 1;
            return x;
        }

        void flipColors(Node *t) {
            t->isRed = 1;
            t->l->isRed = 0;
            t->r->isRed = 0;
        }
    };
};
```

```
// O(lg(N))
Node *insert(Node *t, K key, V val) {
    if (!t) return new Node(key, val, 1);
    int cmp = compare(key, t->key);
    if (!cmp) t->val = val;
    if (cmp < 0) t->l = insert(t->l, key, val);
    if (cmp > 0) t->r = insert(t->r, key, val);
    if (t->r && t->r->isRed && !(t->l && t->l->isRed))
        t = rotateLeft(t);
    if (t->l && t->l->isRed && t->l->l &&
        t->l->l->isRed)
        t = rotateRight(t);
    if (t->l && t->l->isRed && t->r && t->r->isRed)
        flipColors(t);
    return t;
}

// O(lg(N))
void insert(K key, V val) {
    root = insert(root, key, val);
}
};
```

Treap

```
template <class K, class V>
struct Treap {
    struct Node {
        Node *l = nullptr, *r = nullptr; // left, right
        K key;
        V val;
        int prior, sz = 1;
        Node(K k, V v, int p = rand())
            : key(k), val(v), prior(p) {}
    };

    Treap() {}
    Node *root = nullptr;

    // O(lg(N))
    V get(K key) {
        Node *t = root;
        while (t) {
            if (key == t->key) return t->val;
            else if (key < t->key) t = t->l;
            else t = t->r;
            throw runtime_error("Treap: Key doesn't exist");
        }

        // O(1)
        void updateSize(Node *t) {
            if (!t) return;
            t->sz = 1;
            if (t->l) t->sz += t->l->sz;
            if (t->r) t->sz += t->r->sz;
        }
    };
};
```

```

// O(lg(N)), first <= key < second
pair<Node *, Node *> split(Node *t, K key) {
    if (!t) return {NULL, NULL};
    Node *left, *right;
    if (key < t->key)
        tie(left, t->l) = split(t->l, key), right = t;
    else
        tie(t->r, right) = split(t->r, key), left = t;
    updateSize(t);
    return {left, right};
}

// O(lg(N))
void insert(Node *&t, Node *v) {
    if (!t) t = v;
    else if (v->prior > t->prior)
        tie(v->l, v->r) = split(t, v->key), t = v;
    else insert(v->key < t->key ? t->l : t->r, v);
    updateSize(t);
}

// O(lg(N))
void insert(K key, V val) {
    insert(root, new Node(key, val));
}

// O(lg(N)) assumes a.keys < b.keys
Node *merge(Node *a, Node *b) {
    Node *ans;
    if (!a || !b) ans = a ? a : b;
    else if (a->prior > b->prior)
        a->r = merge(a->r, b), ans = a;
    else b->l = merge(a, b->l), ans = b;
    updateSize(ans);
    return ans;
}

// O(lg(N))
void erase(Node *&t, K key) {
    if (!t) return;
    if (t->key == key) t = merge(t->l, t->r);
    else erase(key < t->key ? t->l : t->r, key);
    updateSize(t);
}

// O(lg(N))
void erase(K key) { erase(root, key); }

// O(lg(N)) 1-indexed (k-th smallest)
K kth(int k) {
    Node *t = root;
    while (t) {
        int sz = t->l ? t->l->sz : 0;
        if (sz + 1 == k) return t->key;
        else if (k > sz) t = t->r, k -= sz + 1;
        else t = t->l;
    }
    throw runtime_error("Treap: Index out of bounds");
}

```

```

// O(M * lg(N / M))
Node *join(Node *a, Node *b) {
    if (!a || !b) return a ? a : b;
    if (a->prior < b->prior) swap(a, b);
    Node *l, *r;
    tie(l, r) = split(b, a->key);
    a->l = join(a->l, l), a->r = join(a->r, r);
    updateSize(a);
    return a;
}

void join(Treap<K, V> t) {
    root = join(root, t.root);
}

// O(N)
Node *copy(Node *t) {
    if (!t) return nullptr;
    Node *x = new Node(t->key, t->val, t->prior);
    x->l = copy(t->l), x->r = copy(t->r);
    return x;
}

void print(string s, Node *t, bool isleft) {
    if (!t) return;
    cout << s << (isleft ? "|__" : "\\__");
    cout << t->val << "~" << t->prior << endl;
    print(s + (isleft ? "|" : " "), t->l, 1);
    print(s + (isleft ? "|" : " "), t->r, 0);
}

void print() { print("", root, false); }
};

```

Treap (Implicit)

```

// su = sum update, ru = replace update, rev = reverse
// psu = pending sum update, sz = size
// pru = pending replace update
template <class T>
struct ImplicitTreap {
    struct Node {
        Node *l = nullptr, *r = nullptr; // left, right
        T val, minim = (1 << 30), sum = 0, su = 0, ru;
        int prior, sz = 1, rev = 0, psu = 0, pru = 0;
        Node(T e, int p = rand()) : val(e), prior(p) {}
    };
    ImplicitTreap() {}
    Node *root = nullptr;
    // O(1)
    void pull(Node *t) {
        if (!t) return;
        t->sz = 1, t->sum = t->val, t->minim = t->val;
        if (t->l) {
            t->sz += t->l->sz, t->sum += t->l->sum;
            t->minim = min(t->minim, t->l->minim);
        }
        if (t->r) {
            t->sz += t->r->sz, t->sum += t->r->sum;
            t->minim = min(t->minim, t->r->minim);
        }
    }
};

```



```

void applySu(Node *t, T su) {
    if (!t) return;
    t->val += su, t->psu = 1, t->su += su;
    t->sum += su * t->sz, t->minim += su;
}

void applyRev(Node *t) {
    if (!t) return;
    t->rev ^= 1, swap(t->l, t->r);
}

void applyRu(Node *t, T ru) {
    if (!t) return;
    t->val = ru, t->pru = 1, t->ru = ru;
    t->sum = ru * t->sz, t->minim = ru;
}

// O(1)
void push(Node *t) {
    if (!t) return;
    if (t->psu) {
        applySu(t->l, t->su), applySu(t->r, t->su);
        t->psu = t->su = 0;
    }
    if (t->rev)
        applyRev(t->l), applyRev(t->r), t->rev = 0;
    if (t->pru) {
        applyRu(t->l, t->ru), applyRu(t->r, t->ru);
        t->pru = 0;
    }
}

// O(lg(N)), first <= idx < second
pair<Node *, Node *> split(Node *t, int idx,
                           int cnt = 0) {
    if (!t) return {NULL, NULL};
    push(t);
    Node *left, *right;
    int idxt = cnt + (t->l ? t->l->sz : 0);
    if (idx < idxt)
        tie(left, t->l) = split(t->l, idx, cnt),
        right = t;
    else
        tie(t->r, right) = split(t->r, idx, idxt + 1),
        left = t;
    pull(t);
    return {left, right};
}

// O(lg(N))
void insert(Node *&t, Node *v, int idxv, int cnt) {
    int idxt = t ? cnt + (t->l ? t->l->sz : 0) : 0;
    push(t);
    if (!t) t = v;
    else if (v->prior > t->prior)
        tie(v->l, v->r) = split(t, idxv, cnt), t = v;
    else if (idxv < idxt) insert(t->l, v, idxv, cnt);
    else insert(t->r, v, idxv, idxt + 1);
    pull(t);
}

```

```

// O(lg(N)), insert element in i-th position
void insert(T e, int i) {
    insert(root, new Node(e), i - 1, 0);
}

// O(lg(N)) assumes a.indexes < b.indexes
Node *merge(Node *a, Node *b) {
    push(a), push(b);
    Node *ans;
    if (!a || !b) ans = a ? a : b;
    else if (a->prior > b->prior)
        a->r = merge(a->r, b), ans = a;
    else b->l = merge(a, b->l), ans = b;
    pull(ans);
    return ans;
}

// O(lg(N))
void erase(Node *&t, int idx, int cnt = 0) {
    if (!t) return;
    push(t);
    int idxt = cnt + (t->l ? t->l->sz : 0);
    if (idxt == idx) t = merge(t->l, t->r);
    else if (idx < idxt) erase(t->l, idx, cnt);
    else erase(t->r, idx, idxt + 1);
    pull(t);
}

// O(lg(N)), erase element at i-th position
void erase(int i) { erase(root, i); }

// O(lg(N))
void push_back(T e) {
    root = merge(root, new Node(e));
}

// O(lg(N))
void op(int l, int r, function<void(Node *&)> f) {
    Node *a, *b, *c;
    tie(a, b) = split(root, l - 1);
    tie(b, c) = split(b, r - 1);
    f(b), root = merge(a, merge(b, c));
}

// O(lg(N)), reverses [l, ..., r]
void reverse(int l, int r) {
    op(l, r, [&](Node *&t) { applyRev(t); });
}

// O(lg(N)), rotates [l, ..., r] k times
void rotate(int l, int r, int k) {
    op(l, r, [&](Node *&t) {
        Node *l, *r;
        k %= t->sz, tie(l, r) = split(t, t->sz - k - 1);
        t = merge(r, l);
    });
}

// O(lg(N)), adds val to [l, ..., r]
void add(int l, int r, T val) {
    op(l, r,
        [&](Node *&t) { applySu(t, val); });
}

```



```

// O(lg(N)), sets val to [l, ..., r]
void replace(int l, int r, T val) {
    op(l, r,
        [&](Node *t) { applyRu(t, val); });
}

// O(lg(N)), minimum in [l, ..., r]
T getMin(int l, int r) {
    T ans;
    op(l, r, [&](Node *t) { ans = t->minim; });
    return ans;
}

// O(lg(N)), sum in [l, ..., r]
T getSum(int l, int r) {
    T ans;
    op(l, r, [&](Node *t) { ans = t->sum; });
    return ans;
}

// O(N)
void print(Node *t) {
    if (!t) return;
    push(t);
    print(t->l);
    cout << t->val << " ";
    print(t->r);
}

void print() { print(root), cout << endl; }
};

```

Util

Ceil Of Division Between Integers

```

typedef long long int li;

int sign(li x) { return x < 0 ? -1 : x > 0; }

//          a / b
li ceil(li a, li b) {
    if (sign(a) == sign(b) && a % b) return a / b + 1;
    else return a / b;
}

```

Compare 2 Strings

```

// O(min(|a|, |b|)) -1: a < b, 0: a == b, 1: a > b
int comp(string &a, string &b) {
    int ans = -1, same = 1;
    for (int i = 0; i < min(a.size(), b.size()); i++) {
        if (a[i] != b[i]) same = 0;
        if (a[i] > b[i]) ans = 1;
    }
    if (same)
        ans = a.size() < b.size() ? -1
            : a.size() > b.size();
    return ans;
}

```

Double Comparisons With Given Precision

```

typedef long double ld;
const ld eps = 1e-9;

bool eq(ld a, ld b) { return abs(a - b) <= eps; }
bool neq(ld a, ld b) { return abs(a - b) > eps; }
bool gt(ld a, ld b) { return a - b > eps; }
bool lt(ld a, ld b) { return b - a > eps; }
bool gte(ld a, ld b) { return a - b >= -eps; }
bool lte(ld a, ld b) { return b - a >= -eps; }

```

Floor Of Division Between Integers

```

typedef long long int li;

int sign(li x) { return x < 0 ? -1 : x > 0; }

//          a / b
li floor(li a, li b) {
    if (sign(a) != sign(b) && a % b) return a / b - 1;
    else return a / b;
}

```

Get Sign Of Number

```

int sign(int x) { return x < 0 ? -1 : x > 0; }

```

Number To String

```

string toString(int n) {
    string ans = "";
    for (; n; n /= 10) ans += (n % 10) + '0';
    reverse(ans.begin(), ans.end());
    return ans;
}

```

Extras

Data Structures

Strings

Suffix Automaton

- Each node u corresponds to an endpos-equivalence class for which its longest suffix corresponds to the path from root to u .

C++

Automatic Type Conversions

When performing operations with different primitive data types in C++, the operand with smaller rank gets converted to the data type of the operand with the greater rank.

Data Type Ranks	
Rank	Data Type
1	<code>bool</code>
2	<code>char</code> , <code>signed char</code> , <code>unsigned char</code>
3	<code>short int</code> , <code>unsigned short int</code>
4	<code>int</code> , <code>unsigned int</code>
5	<code>long int</code> , <code>unsigned long int</code>
6	<code>long long int</code> , <code>unsigned long long int</code>
7	<code>__int128_t</code>
8	<code>float</code>
9	<code>double</code>
10	<code>long double</code>

Source: <https://en.cppreference.com/w/c/language/conversion>

Integer Types Properties

Properties	
Width in bits	Data Type
8	<code>bool</code>
At least 8	<code>char</code> , <code>signed char</code> , <code>unsigned char</code>
At least 16	<code>short int</code> , <code>unsigned short int</code>
At least 16	<code>int</code> , <code>unsigned int</code>
At least 32	<code>long int</code> , <code>unsigned long int</code>
At least 64	<code>long long int</code> , <code>unsigned long long int</code>
128	<code>__int128_t</code>

Sources:

<https://en.cppreference.com/w/cpp/language/types>

<https://www.geeksforgeeks.org/c-data-types/>

<https://stackoverflow.com/questions/2064550/c-why-bool-is-8-bits-long>

Maths

Common Sums

$\sum_{k=0}^n k = \frac{n(n+1)}{2}$	$\sum_{k=0}^n k^2 = \frac{n(n+1)(2n+1)}{6}$	$\sum_{k=0}^n k^3 = \frac{n^2(n+1)^2}{4}$
$\sum_{k=0}^n k^4 = \frac{n}{30}(n+1)(2n+1)(3n^2+3n-1)$		$\sum_{k=0}^n a^k = \frac{1-a^{n+1}}{1-a}$
$\sum_{k=0}^n ka^k = \frac{a[1-(n+1)a^n+na^{n+1}]}{(1-a)^2}$	$\sum_{k=0}^n k^2a^k = \frac{a[(1+a)-(n+1)^2a^n+(2n^2+2n-1)a^{n+1}-n^2a^{n+2}]}{(1-a)^3}$	
$\sum_{k=0}^{\infty} a^k = \frac{1}{1-a}, a < 1$	$\sum_{k=0}^{\infty} ka^k = \frac{a}{(1-a)^2}, a < 1$	$\sum_{k=0}^{\infty} k^2a^k = \frac{a^2+a}{(1-a)^3}, a < 1$
$\sum_{k=0}^{\infty} \frac{1}{a^k} = \frac{a}{a-1}, a > 1$	$\sum_{k=0}^{\infty} \frac{k}{a^k} = \frac{a}{(a-1)^2}, a > 1$	$\sum_{k=0}^{\infty} \frac{k^2}{a^k} = \frac{a^2+a}{(a-1)^3}, a > 1$
$\sum_{k=0}^{\infty} \frac{a^k}{k!} = e^a$	$\sum_{k=0}^n \binom{n}{k} = 2^n$	$\sum_{k=0}^n \binom{k}{m} = \binom{n+1}{m+1}$

Logarithm Rules

$\log_b(b^k) = k$	$\log_b(1) = 0$	$\log_b(X) = \frac{\log_c(X)}{\log_c(b)}$
$\log_b(X \cdot Y) = \log_b(X) + \log_b(Y)$	$\log_b\left(\frac{X}{Y}\right) = \log_b(X) - \log_b(Y)$	$\log_b(X^k) = k \cdot \log_b(X)$

Problems Solved

Arrays

Inversions Count

```
#include "../Ranges/Data Structures/BIT.cpp"

li invCount(vector<li>& v) {
    BIT<int> bit(*max_element(v.begin(), v.end()) + 1);
    li ans = 0;
    rep(i, v.size()) {
        ans += i - bit.query(v[i]);
        bit.update(v[i], 1);
    }
    return ans;
}
```

Maths

N as Sum of different numbers from 1 to M

```
int main() {
    int t;
    scanf("%d", &t);
    for (int j = 1; j <= t; j++) {
        lli x;
        scanf("%lld", &x);
        lli count = 0;
        V divisors = getDivisors(2LL * x);
        for (auto &div : divisors) {
            double d =
                ((double)x / div) + ((1.00 - div) / 2.00);
            if (d > 0 && div > 1 && d == floor(d) &&
                div < x &&
                (2 * d * div + (div - 1) * div == 2 * x)) {
                count++;
            }
        }
        printf("case %d: %lld\n", j, count);
    }
}
```