

Lattice Boltzmann Method

I. Fluid Model

- Mesoscopic particle description of a fluid, where particle distribution functions evolve and flow across the domain

$$f(\bar{r}, \bar{e}, t) d\bar{r} d\bar{e} = dN(\bar{r}, \bar{e}, t)$$

\bar{r} : spatial degrees of freedom

\bar{e} : particle velocity degrees of freedom

f : particle distribution function

dN : number of particles occupying phase space volume $d\bar{r} d\bar{e}$.

- Macroscopic fluid quantities : velocity moments of f

$$\rho(\bar{r}, t) = \int f(\bar{r}, \bar{e}, t) d\bar{e} \quad \text{number density}$$

$$\bar{u}(\bar{r}, t) = \frac{1}{\rho(\bar{r}, t)} \int \bar{e} f(\bar{r}, \bar{e}, t) d\bar{e} \quad \text{fluid velocity}$$

$$E(\bar{r}, t) = \frac{1}{2} m \frac{1}{\rho(\bar{r}, t)} \int (\bar{e} - \bar{u})^2 f(\bar{r}, \bar{e}, t) d\bar{e} \quad \text{kinetic energy}$$

II. Equilibrium Distribution

- borrow from kinetic theory of gases: spread of velocities of a gas in thermal equilibrium given by the Maxwell-Boltzmann distribution

$$f^{eq}(\bar{r}, \bar{e}, t) = \rho(\bar{r}, t) \left(\frac{m}{2\pi k_B T} \right)^{D/2} \exp \left\{ - \frac{m(\bar{e} - \bar{u})^2}{2k_B T} \right\} \quad \begin{array}{l} D: \text{spatial dimension} \\ (D=2 \text{ for us}) \end{array}$$

- How is Maxwell-Boltzmann distribution adapted for Lattice Boltzmann?

$$1. \text{ Low Mach Expansion : } |\bar{u}| \ll \sqrt{\frac{k_B T}{m}} \equiv c_s : \text{effective speed of sound}$$

$$2. \text{ Phase Space Discretization } f^{eq}(\bar{r}, \bar{e}, t) \rightarrow f^{eq}(\bar{r}_{ij}, \bar{e}_{kl}, t_n) \text{ where}$$

$$\bar{r}_{ij} = \delta_x (i\hat{x} + j\hat{y})$$

$$\bar{e}_{kl} = \frac{\delta_x}{\delta_t} (k\hat{x} + l\hat{y})$$

$$t_n = n\delta_t$$

Start with Low Mach Expansion, retaining terms up to 2nd order in \bar{u}

$$f^{eq}(\bar{r}, \bar{e}, t) = \rho(\bar{r}, t) \frac{m}{2\pi k_B T} \exp \left\{ - \frac{m\bar{e}^2}{2k_B T} \right\} \exp \left\{ \frac{m\bar{e} \cdot \bar{u}}{k_B T} \right\} \exp \left\{ - \frac{m\bar{u}^2}{2k_B T} \right\}$$

$$\approx \rho(\bar{r}, t) \frac{m}{2\pi k_B T} \exp \left\{ -\frac{m\bar{e}^2}{2k_B T} \right\} \left[1 + \frac{m\bar{e} \cdot \bar{u}}{k_B T} + \frac{1}{2} \left(\frac{m\bar{e} \cdot \bar{u}}{k_B T} \right)^2 \right] \left[1 - \frac{m\bar{u}^2}{2k_B T} \right]$$

$$\approx \rho(\bar{r}, t) \frac{m}{2\pi k_B T} \exp \left\{ -\frac{m\bar{e}^2}{2k_B T} \right\} \left[1 + \frac{m\bar{e} \cdot \bar{u}}{k_B T} + \frac{1}{2} \left(\frac{m\bar{e} \cdot \bar{u}}{k_B T} \right)^2 - \frac{m\bar{u}^2}{2k_B T} \right]$$

\therefore With Low Mach Expansion, in 2D

$$f^{eq}(\bar{r}, \bar{e}, t) = \rho(\bar{r}, t) \frac{m}{2\pi k_B T} \exp \left\{ -\frac{m\bar{e}^2}{2k_B T} \right\} \underbrace{\left[1 + \frac{m\bar{e} \cdot \bar{u}}{k_B T} + \frac{1}{2} \left(\frac{m\bar{e} \cdot \bar{u}}{k_B T} \right)^2 - \frac{m\bar{u}^2}{2k_B T} \right]}_{\text{polynomial } \psi(e_x, e_y) \text{ degree 2 in } e_x \text{ and } e_y}$$

Next is phase space discretization

Goal: Discretization must exactly preserve local velocity moments of f

$$\int f(\bar{r}, \bar{e}, t) d\bar{e} = \sum_{\bar{e}_{k1}} f(\bar{r}_{ij}, \bar{e}_{k1}, t_n) = \rho(\bar{r}_{ij}, t_n)$$

$$\frac{1}{\rho(\bar{r}, t)} \int \bar{e} f(\bar{r}, \bar{e}, t) d\bar{e} = \frac{1}{\rho(\bar{r}_{ij}, t_n)} \sum_{\bar{e}_{k1}} \bar{e}_{k1} f(\bar{r}_{ij}, \bar{e}_{k1}, t_n) = \bar{u}(\bar{r}_{ij}, t_n)$$

Look at conserving number density as our example case. Plugging in f^{eq} into the integral gives us

$$\rho \frac{m}{2\pi k_B T} \int \exp \left\{ -\frac{m(e_x^2 + e_y^2)}{2k_B T} \right\} \psi(e_x, e_y) de_x de_y \quad \text{with polynomial } \psi$$

$$\text{Define } \varepsilon_x = \frac{e_x}{\sqrt{2k_B T/m}} \quad \varepsilon_y = \frac{e_y}{\sqrt{2k_B T/m}}$$

$$\rightarrow \frac{\rho}{\pi} \int \exp \left\{ -(\varepsilon_x^2 + \varepsilon_y^2) \right\} \psi d\varepsilon_x d\varepsilon_y$$

Exact Gaussian-type quadrature exists such that

$$\frac{\rho}{\pi} \int \exp \left\{ -(\varepsilon_x^2 + \varepsilon_y^2) \right\} \psi d\varepsilon_x d\varepsilon_y = \frac{\rho}{\pi} \sum_{k,l} w_k w_l \psi(\varepsilon_{x_k}, \varepsilon_{y_l})$$

The exponential weighting function in integrand means this is a case of Gauss-Hermite quadrature. What order quadrature rule to choose? In general,

$n+1$ -point quadrature rule \rightarrow recover integral exactly if ψ is a polynomial of degree $2n+1$ or less. Right now, ψ is a polynomial of degree 2 in e_x, e_y . But we also want our quadrature rule to match higher order velocity moments like fluid velocity and kinetic energy, which would go up to degree 4. So we choose a 3-point quadrature rule.

3-Point Gauss-Hermite Quadrature, in 2D

$$\mathcal{E}_x = \left\{ -\sqrt{\frac{3}{2}}, 0, \sqrt{\frac{3}{2}} \right\} = \mathcal{E}_y \quad \text{Define } c \equiv \sqrt{\frac{3k_B T}{m}} \equiv \frac{\delta_x}{\delta_t} \quad \text{"lattice speed" - how fast the particles move.}$$

$$\mathbf{e}_x = \left\{ -\sqrt{\frac{3k_B T}{m}}, 0, \sqrt{\frac{3k_B T}{m}} \right\} = \mathbf{e}_y$$

$$\text{Notice that } c_s = \sqrt{\frac{k_B T}{m}} \text{ so } c_s^2 = \frac{c^2}{3}$$

$$= \{-c, 0, c\}$$

$$\text{Pressure } p = \rho c_s^2$$

$$w_x = \left\{ \frac{\sqrt{\pi}}{6}, \frac{2\sqrt{\pi}}{3}, \frac{\sqrt{\pi}}{6} \right\} = w_y$$

* Turn to slides for tabulated \bar{e}_α, w_α , now using a single linear index for 2D.

$$\begin{aligned} \therefore \frac{\rho}{\pi} \int \exp \left\{ -(\mathcal{E}_x^2 + \mathcal{E}_y^2) \right\} \psi d\mathcal{E}_x d\mathcal{E}_y &= \frac{\rho}{\pi} \sum_{\alpha=0}^8 w_\alpha \psi(\bar{e}_\alpha) \\ &= \frac{\rho}{\pi} \sum_{\alpha=0}^8 w_\alpha \left[1 + \frac{m \bar{e}_\alpha \cdot \bar{u}}{k_B T} + \frac{1}{2} \left(\frac{m \bar{e}_\alpha \cdot \bar{u}}{k_B T} \right)^2 - \frac{m \bar{u}^2}{2k_B T} \right] \\ &= \frac{\rho}{\pi} \sum_{\alpha=0}^8 w_\alpha \left[1 + 3 \frac{\bar{e}_\alpha \cdot \bar{u}}{c^2} + \frac{9}{2} \left(\frac{\bar{e}_\alpha \cdot \bar{u}}{c^2} \right)^2 - \frac{3}{2} \frac{\bar{u}^2}{c^2} \right] = \rho \end{aligned}$$

Same correspondence should happen for higher moments.

$$\rho(\bar{r}_{ij}, t_n) = \sum_{\alpha=0}^8 f_\alpha(\bar{r}_{ij}, t_n)$$

$$\bar{u}(\bar{r}_{ij}, t_n) = \frac{1}{\rho(\bar{r}_{ij}, t_n)} \sum_{\alpha=0}^8 \bar{e}_\alpha f_\alpha(\bar{r}_{ij}, t_n)$$

$$f_\alpha^{eq}(\bar{r}_{ij}, t_n) = \rho(\bar{r}_{ij}, t_n) \frac{w_\alpha}{\pi} \left[1 + 3 \frac{\bar{e}_\alpha \cdot \bar{u}}{c^2} + \frac{9}{2} \left(\frac{\bar{e}_\alpha \cdot \bar{u}}{c^2} \right)^2 - \frac{3}{2} \frac{\bar{u}^2}{c^2} \right]$$

III. Transport Equation

Flow of particle distribution functions in space and time is governed by Boltzmann transport equation.

$$\frac{\partial f_\alpha}{\partial t} + \bar{e}_\alpha \cdot \nabla f_\alpha = \Omega(f_\alpha) \quad \Omega \text{ is a collision operator}$$

First order explicit Euler step in time, and first order forward finite difference in space discretize the transport equation:

$$\frac{f_\alpha(\bar{r}_{ij}, t_n + \delta_t) - f_\alpha(\bar{r}_{ij}, t_n)}{\delta_t} + c \frac{f_\alpha(\bar{r}_{ij} + \bar{e}_\alpha \delta_t, t_n + \delta_t) - f_\alpha(\bar{r}_{ij}, t_n + \delta_t)}{\delta_x} = \Omega(f_\alpha(\bar{r}_{ij}, t_n))$$

$$\text{recall } c = \frac{\delta_x}{\delta_t}$$

$$\Rightarrow f_\alpha(\bar{r}_{ij} + \bar{e}_\alpha \delta_t, t_n + \delta_t) = f_\alpha(\bar{r}_{ij}, t_n) + \delta_t \Omega(f_\alpha(\bar{r}_{ij}, t_n))$$

Common choice for collision operator is Bhatnagar-Gross-Krook (BGK) operator

$$\rightarrow f_a(\bar{r}_{ij} + \bar{e}_a \delta_t, t_n + \delta_t) = f_a(\bar{r}_{ij}, t_n) - \frac{1}{\tau} (f_a(\bar{r}_{ij}, t_n) - f_a^{eq}(\bar{r}_{ij}, t_n)) \quad (\delta_t \text{ absorbed into relaxation constant})$$

$$\tau \text{ is related to kinematic viscosity: } \nu = \frac{2\tau - 1}{6} c^2 \delta_t$$

Simulation Steps: see slides

Boundary conditions: see slides