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_{第1部} 真空中のマクスウェル方程式		
	$F=egin{array}{ccc} 1 & Qq \end{array}$	F = 1 q

$$F = \frac{1}{4\pi\epsilon_0} \frac{Qq}{r^2} \qquad \qquad E = \frac{1}{4\pi\epsilon_0} \frac{q}{r^2}$$

1. ガウスの法則

S S'

$$\int E \cdot n \ dS = \frac{q}{4\pi\epsilon_0} \frac{1}{|r|^3} \int |r||n| \cos \theta \ dS'$$
$$= \frac{q}{4\pi\epsilon_0} \frac{1}{|r|^2} \int dS'$$
$$= \frac{q}{\epsilon_0}$$

 $q = \int \rho dV$

$$\int E \cdot n \ dS = \int \text{div} E dV = \frac{1}{\epsilon_0} \int \rho dV$$
$$\text{div} E = \frac{\rho}{\epsilon_0}$$

■帯電球の静電場

a

 $r \leq a$

$$4\pi r^2 \cdot E = \frac{r^3}{a^3} \cdot \frac{q}{\epsilon_0}$$
$$E = \frac{1}{4\pi \epsilon_0} \frac{qr}{a^3}$$

r > a

$$4\pi r^2 \cdot E = \frac{q}{\epsilon_0}$$

$$E = \frac{1}{4\pi \epsilon_0} \frac{q}{r^2}$$

$$E = \begin{cases} \frac{1}{4\pi\epsilon_0} \frac{qr}{a^3} & (r \le a) \\ \frac{1}{4\pi\epsilon_0} \frac{q}{r^2} & (r > a) \end{cases}$$

2. ファラデーの法則

F 0

E = 0

$$\oint E \cdot ds = \int \operatorname{rot} E \cdot n dS = 0$$

$$\operatorname{rot} E = 0$$

■ポアソン方程式

E

$$\begin{split} E &= -\nabla \phi (= -\text{grad}\phi) \\ &= \left(-\frac{\partial \phi}{\partial x}, -\frac{\partial \phi}{\partial y}, -\frac{\partial \phi}{\partial z} \right) \end{split}$$

–div grad
$$\phi = -\frac{\rho}{\epsilon_0}$$

$$\Delta \phi = -\frac{\rho}{\epsilon_0}$$

Λ

$$\Delta = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2}{\partial \phi^2}$$

$$\frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial \phi}{\partial r} \right) = -\frac{\rho}{\epsilon_0}$$

$$\phi = -k \frac{d\Phi}{dt}$$

$$\phi = \int E \cdot ds$$

$$\Phi = \int B \cdot ndS$$

$$\int \operatorname{rot} E \cdot n dS = -k \frac{d}{dt} \int B \cdot n dS$$
$$\int \left(\operatorname{rot} E + k \frac{\partial B}{\partial t} \right) \cdot n dS = 0$$

k = 1

$$rotE + \frac{\partial B}{\partial t} = 0$$

3. 磁束保存の法則

$$dB = \frac{\mu_0}{4\pi} \frac{Ids \times r}{|r|^3}$$

$$B(r) = \frac{\mu_0}{4\pi} \int \frac{i(r') \times (r - r')}{|r - r'|^3} dr'$$

$$A = \frac{\mu_0}{4\pi} \int \frac{i(r')}{|r - r'|} dr'$$

B = rot A

$$div B = div rot A = 0$$

4. アンペールの法則

$$rot B = rot \ rot A$$

= grad div $A - \Delta A$
= $\mu_0 i$

 $\operatorname{div}\,i = -\tfrac{\partial\rho}{\partial t}$

$$rot B - \epsilon_0 \mu_0 \frac{\partial E}{\partial t} = \mu_0 i$$

5. ローレンツカ

$$|F| = \frac{\mu_0}{2\pi} \frac{I_1 I_2}{r}$$

 $dF = I \ ds \times B$

1 m n

I = qnv

 $dF = qnv \ ds \times B$

n ds

$$F = qv \times B$$

$$F = q(E + v \times B)$$

第Ⅱ部

物質中の電磁場

E B

$$\mathrm{div}E = \frac{\rho}{\epsilon_0}$$

$$\mathrm{rot}B - \epsilon_0\mu_0\frac{\partial E}{\partial t} = \mu_0 i$$

1. 電東密度

D

$$\int D \cdot dS = q$$
$$\operatorname{div} D = \rho$$

$$P$$

$$\int \epsilon_0 E \cdot dS = q - \int P \cdot dS$$

$$\int (\epsilon_0 E + P) \cdot dS = q$$

$$D = \epsilon_0 E + P$$

 $\epsilon = \epsilon_0 + \chi$

$$P = \chi E$$
$$D = \epsilon E$$

 χ

2. 磁場

H

$$\int H \cdot dl = I$$
$$rot H = i$$

 i_m

$$rot B = \mu_0(i + i_m)$$

 $rot J = \mu_0 i_m$

0

$$rot(B-J) = \mu_0 i$$

$$H = \frac{1}{\mu_0}(B - J)$$

 $J = \chi_m H$

 χ_m

$$\mu = \mu_0 + \chi_m$$

$$B = \mu H$$

$$rot H - \frac{\partial D}{\partial t} = i$$

$$\operatorname{div} i = -\frac{\partial \rho}{\partial t}$$
$$= -\operatorname{div} \left(\frac{\partial D}{\partial t}\right)$$

$$rot H - \frac{\partial D}{\partial t} = i$$

$$\mathrm{div}D=\rho$$

$${\rm div} B=0$$

$$rotE + \frac{\partial B}{\partial t} = 0$$
$$rotH - \frac{\partial D}{\partial t} = i$$

$$rot H - \frac{\partial D}{\partial t} = 0$$

第Ⅲ部

電磁ポテンシャル

1. 電磁ポテンシャル

 ϕ A

$$E = -\cot\phi - \frac{\partial A}{\partial t}$$
$$B = \cot A$$

$$\begin{aligned} \mathrm{rot}E + \frac{\partial B}{\partial t} &= \mathrm{rot}E + \frac{\partial (\mathrm{rot}A)}{\partial t} \\ &= \mathrm{rot}\left(E + \frac{\partial A}{\partial t}\right) \\ &= -\mathrm{rot} \ \mathrm{grad}\phi \\ &= 0 \end{aligned}$$

$$div B = div rot A$$
$$= 0$$

2. ゲージ変換

 χ

$$\phi \to \phi - \frac{\partial \chi}{\partial t}$$
$$A \to A + \operatorname{grad} \chi$$

3. ローレンツゲージにおけるマクスウェル方程式

$$\mathrm{rot}E = \frac{\rho}{\epsilon_0}$$

$$\mathrm{rot}B - \mu_0 \epsilon_0 \frac{\partial E}{\partial t} = \mu_0 i$$

$$\Delta \phi + \operatorname{div} \frac{\partial A}{\partial t} = -\frac{\rho}{\epsilon_0}$$

$$\left(\Delta - \epsilon_0 \mu_0 \frac{\partial^2}{\partial t^2}\right) A - \operatorname{grad} \left(\operatorname{div} A + \epsilon_0 \mu_0 \frac{\partial \phi}{\partial t}\right) = -\mu_0 i$$

$$\operatorname{div} A + \epsilon_0 \mu_0 \frac{\partial \phi}{\partial t} = 0$$

$$\left(\Delta - \epsilon_0 \mu_0 \frac{\partial^2}{\partial t^2}\right) \phi = \frac{\rho}{\epsilon_0}$$

$$\left(\Delta - \epsilon_0 \mu_0 \frac{\partial^2}{\partial t^2}\right) A = -\mu_0 i$$

$$\phi, A$$

$$\chi$$

$$\left(\Delta - \epsilon_0 \mu_0 \frac{\partial^2}{\partial t^2}\right) \chi = -\operatorname{div} A + \epsilon_0 \mu_0 \frac{\partial \phi}{\partial t}$$

$$\left(\Delta - \epsilon_0 \mu_0 \frac{\partial^2}{\partial t^2}\right) \phi = \frac{\rho}{\epsilon_0}$$
$$\left(\Delta - \epsilon_0 \mu_0 \frac{\partial^2}{\partial t^2}\right) A = -\mu_0 i$$
$$\operatorname{div} A + \epsilon_0 \mu_0 \frac{\partial \phi}{\partial t} = 0$$

第IV部

マクスウェル方程式の解

1. 電磁波

波動方程式

$$rotE + \frac{\partial B}{\partial t} = 0$$

$$rotB - \mu_0 \epsilon_0 \frac{\partial E}{\partial t} = 0$$

$$divE = 0$$

$$divB = 0$$

 rot

$$rot \ rot E + \frac{\partial}{\partial t}(rot B) = 0$$

 $rot rot X = grad div X - \Delta X$

grad div
$$E - \Delta E + \frac{\partial}{\partial t}(\text{rot}B) = 0$$
$$\left(\Delta - \mu_0 \epsilon_0 \frac{\partial^2}{\partial t^2}\right) E = 0$$

$$\left(\Delta - \mu_0 \epsilon_0 \frac{\partial^2}{\partial t^2}\right) B = 0$$

$$c = \frac{1}{\sqrt{\mu_0 \epsilon_0}}$$

3

$$E = F(e \cdot r - ct) + G(e \cdot r + ct)$$

e

電磁波の性質

$$div E = 0$$

$$\begin{aligned} \operatorname{div} F(e \cdot r - ct) + G(e \cdot r + ct) \\ &= \frac{\partial}{\partial x} (F_x + G_x) + \frac{\partial}{\partial y} (F_y + G_y) + \frac{\partial}{\partial z} (F_z + G_z) \\ &= e_x (F_x' + G_x') + e_y (F_y' + G_y') + e_z (F_z' + G_z') \\ &= e \cdot (F' + G') = 0 \end{aligned}$$

z

$$(E_x, E_y, E_z) = (F(z - ct) + G(z + ct), 0, 0)$$

$$\left(\frac{\partial B_x}{\partial t}, \frac{\partial B_y}{\partial t}, \frac{\partial B_z}{\partial t}\right) = (0, -F'(z - ct) - G'(z + ct), 0)$$

$$(B_x, B_y, B_z) = (0, -\frac{1}{c}F(z - ct) - \frac{1}{c}G(z + ct), 0)$$

2. 遅延ポテンシャル

$$\bullet$$
 ρ i r,t

•

$$\bullet \ \rho, i$$
 0

 $\bullet \rho, i$

•

•

$$t_r = t - \frac{|r - r'|}{c}$$

$$\phi(r, t) = \frac{1}{4\pi\epsilon_0} \int \frac{\rho(r', t_r)}{|r - r'|} dr'$$

$$A(r, t) = \frac{\mu_0}{4\pi} \int \frac{i(r', t_r)}{|r - r'|} dr'$$

$$t_r = t - \frac{|r - r'|}{c} \qquad \qquad t_r = t + \frac{|r - r'|}{c}$$

$$R = r - r'$$

$$\begin{split} E(r,t) &= \frac{1}{4\pi\epsilon_0} \int \left[\frac{\rho(r',t_r)R}{|R|^3} + \frac{\rho(r',t_r)R}{c|R|^2} - \frac{i(r',t_r)R}{c^2|R|^2} \right] dr' \\ B(r,t) &= \frac{\mu_0}{4\pi} \int \left[\frac{i(r',t_r)R}{|R|^3} + \frac{i(r',t_r)R}{c|R|^2} \right] dr' \end{split}$$

3. リエナール・ヴィーヘルト・ポテンシャル

s(t)

$$\rho(r,t) = q\delta(r - s(t))$$
$$i(r,t) = q\dot{s}(t)\delta(r - s(t))$$

$$\phi(r,t) = \frac{q}{4\pi\epsilon_0} \frac{1}{|r - s(t_r)| - \beta(t_r) \cdot (r - s(t_r))}$$
$$A(r,t) = \frac{\mu_0 q}{4\pi} \frac{\dot{s}(t_r)}{|r - s(t_r)| - \beta(t_r) \cdot (r - s(t_r))}$$

$$t_r = t - \frac{|r - s(t)|}{c}$$
$$\beta(t_r) = \frac{\dot{s}(t_r)}{c}$$

4. 等速運動する点電荷

$$x \hspace{1cm} t = 0$$

$$\phi = \frac{q}{4\pi\epsilon_0} \frac{1}{\sqrt{(x-vt)^2 + (1-\frac{v^2}{c^2})(y^2+z^2)}}$$

$$A = \frac{\mu_0 q}{4\pi} \frac{v}{\sqrt{(x-vt)^2 + (1-\frac{v^2}{c^2})(y^2+z^2)}}$$

$$(x-vt,y,z) \hspace{1cm} x$$

yz

5. 加速運動する点電荷

$$S(t)$$

$$R = |r - s(r)|, n = (r - s(r))/|r - s(r)|$$

$$S(r,t) = \frac{q^2}{16\pi^2 \epsilon_0 c} \frac{n}{(1 - n \cdot v)^6 R^2} [n \times \{(n - v) \times \dot{v}\}]^2$$

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第V部

電磁場の力と保存量

1. 電磁場のエネルギー

静電場のエネルギー

q

 $\phi \qquad \qquad E = \frac{1}{4\pi\epsilon_0} \frac{q'}{r^2}$

 $\phi = \frac{q'}{4\pi\epsilon_0 r}$

0

dq'

 $U(r) = \int_0^q \frac{q'}{4\pi\epsilon_0 r}$ $= \frac{q^2}{8\pi\epsilon_0 r}$

r, r + dr u(E)

$$\begin{split} U(r+dr) - U(r) &= -u(E) \cdot 4\pi r^2 dr \\ \frac{U(r+dr) - U(r)}{dr} &= -u(E) \cdot 4\pi r^2 \end{split}$$

$$\begin{split} u(E) &= -\frac{1}{4\pi r^2} \frac{dU}{dr} \\ &= -\frac{1}{4\pi r^2} \cdot -\frac{q^2}{8\pi \epsilon_0 r^2} = \frac{q^2}{32\pi^2 \epsilon_0 r^4} \\ &= \frac{1}{2} \epsilon_0 \left(\frac{1}{4\pi \epsilon_0} \frac{q}{r^2} \right)^2 \\ &= \frac{1}{2} \epsilon_0 E^2 \end{split}$$

r

q'

静磁場のエネルギー

電磁場のエネルギー

$$m\frac{dv}{dt} = q(E(r) + v \times B(r))$$

v

$$mv \cdot \frac{dv}{dt} = E(r) \cdot (qv) + qv \cdot (v \times B(r))$$

$$\frac{d}{dt} \left(\frac{1}{2}mv^2\right) = E(r) \cdot i(r)$$

$$v \quad v \times B(r) \qquad v \cdot (v \times B(r)) = 0$$

$$\frac{d}{dt} \left(\sum_j \frac{1}{2}m_jv_j^2\right) = E \cdot i$$

$$E$$

$$\begin{split} i &= \text{rot} H - \frac{\partial D}{\partial t} \\ E \cdot (\nabla \times H) &= H \cdot (\nabla \times E) - \nabla \cdot (E \times H) \\ &= -H \cdot \frac{\partial B}{\partial t} - \nabla \cdot (E \times H) \end{split}$$

i

$$\begin{split} E \cdot i &= E \cdot \left(\mathrm{rot} H - \frac{\partial D}{\partial t} \right) \\ &= -E \cdot \frac{\partial D}{\partial t} - H \cdot \frac{\partial B}{\partial t} - \nabla \cdot (E \times H) \\ &= -\frac{\partial}{\partial t} \left(\frac{1}{2} E \cdot D + \frac{1}{2} H \cdot B \right) - \nabla \cdot (E \times H) \end{split}$$

$$u = \frac{1}{2}(E \cdot D + H \cdot B)$$
 $S = E \times H$
$$-\frac{\partial u}{\partial t} = E \cdot i + \text{div}S$$

(Poynting)

2. マクスウェルの応力

V

$$dF = \rho(r)E(r) + i(r) \times B(r)$$

$$F = \int_{V} \rho(r) E(r) + i(r) \times B(r) dV$$

$$\begin{aligned} \mathbf{div}\ D &= \rho \\ \mathbf{rot}\ H - \frac{\partial D}{\partial t} &= i \end{aligned}$$

$$\begin{split} F &= \int \left[E \mathbf{div} \ D + \left(\mathbf{rot} \ H - \frac{\partial D}{\partial t} \right) \times B \right] dV \\ &= \int \left[E \mathbf{div} \ D - B \times \mathbf{rot} \ H - \frac{\partial D}{\partial t} \times B \right] dV \\ &- \frac{\partial D}{\partial t} \times B = -D \times \mathbf{rot} \ E - \frac{d}{dt} (D \times B) \end{split}$$

$$\begin{split} &= \int \left[\epsilon_0 E \mathbf{div} \ E - \frac{1}{\mu_0} B \times \mathbf{rot} \ B - \epsilon_0 E \times \mathbf{rot} \ E - \epsilon_0 \mu_0 \frac{d}{dt} (E \times H) \right] dV \\ \mathbf{div} \ B = 0 & B \mathbf{div} \ B \\ &= \int \left[\epsilon_0 (E \mathbf{div} \ E - E \times \mathbf{rot} \ E) + \frac{1}{\mu_0} (B \mathbf{div} \ B - B \times \mathbf{rot} \ B) \right] dV \\ &- \frac{1}{c^2} \frac{d}{dt} \left[\int (E \times H) dV \right] \end{split}$$

 $E \times H$

E**div** $E - E \times$ **rot** E

x

$$(E \mathbf{div} \ E - E \times \mathbf{rot} \ E)_x = E_x \left(\frac{\partial E_x}{\partial x} + \frac{\partial E_y}{\partial y} + \frac{\partial E_z}{\partial z} \right)$$

$$-E_y \left(\frac{\partial E_y}{\partial x} - \frac{\partial E_x}{\partial y} \right)$$

$$+E_z \left(\frac{\partial E_x}{\partial z} - \frac{\partial E_z}{\partial x} \right)$$

$$= E_x \frac{\partial E_x}{\partial x} - E_y \frac{\partial E_y}{\partial x} - E_z \frac{\partial E_z}{\partial x}$$

$$+E_x \frac{\partial E_y}{\partial y} + E_y \frac{\partial E_x}{\partial y}$$

$$+E_x \frac{\partial E_z}{\partial z} + E_z \frac{\partial E_x}{\partial z}$$

$$= \frac{1}{2} \frac{\partial E_x^2}{\partial x} - \frac{1}{2} \frac{\partial E_y^2}{\partial x} - \frac{1}{2} \frac{\partial E_z^2}{\partial x}$$

$$+ \frac{\partial (E_x E_y)}{\partial y} + \frac{\partial (E_x E_z)}{\partial z}$$

$$= \frac{\partial (E_x^2 - \frac{1}{2} E^2)}{\partial x} + \frac{\partial (E_x E_y)}{\partial y} + \frac{\partial (E_x E_z)}{\partial z}$$

$$\begin{split} T &= T_e + T_m \\ T_e &= \epsilon_0 \begin{bmatrix} E_x^2 - \frac{1}{2}E^2 & E_x E_y & E_x E_z \\ E_y E_x & E_y^2 - \frac{1}{2}E^2 & E_y E_z \\ E_z E_x & E_z E_y & E_z^2 - \frac{1}{2}E^2 \end{bmatrix} \\ T_m &= \frac{1}{\mu_0} \begin{bmatrix} B_x^2 - \frac{1}{2}B^2 & B_x B_y & B_x B_z \\ B_y B_x & B_y^2 - \frac{1}{2}B^2 & B_y B_z \\ B_z B_x & B_z B_y & B_z^2 - \frac{1}{2}B^2 \end{bmatrix} \end{split}$$

$$F = \int \mathbf{div} \ T \ dV - \frac{1}{c^2} \frac{d}{dt} \int S dV$$
$$= \int T \cdot dS - \frac{1}{c^2} \frac{d}{dt} \int S dV$$

T

3. 電磁場の運動量

m q

$$m\frac{d^2r}{dt^2} = \int \left[q\delta(r-r')E + q\delta(r-r')\frac{dr}{dt} \times B \right] dr'$$

$$\sum_{i} m_{i} \frac{d^{2}r_{i}}{dt^{2}} = \int \left[q_{i}\delta(r_{i} - r')E + q_{i}\delta(r_{i} - r')\frac{dr_{i}}{dt} \times B \right] dr'$$

$$\label{eq:div} \begin{split} \mathbf{div}\ D &= \sum_i q_i \delta(r_i - r') \\ \mathbf{rot}\ H - \frac{\partial D}{\partial t} &= \sum_i q_i \delta(r_i - r') \frac{dr_i}{dt} \end{split}$$

V

$$\sum_{i} m_{i} \frac{d^{2} r_{i}}{dt^{2}} = \int T \cdot dS - \frac{1}{c^{2}} \frac{d}{dt} \int (E \times H) dV$$
$$\frac{d}{dt} \left[\sum_{i} m_{i} \frac{dr_{i}}{dt} + \frac{1}{c^{2}} \int (E \times H) dV \right] = \int T \cdot dS$$

第 VI 部

諸現象

1. 電気双極子モーメント

+q,-q $\qquad \qquad p$ $\qquad p=qs$

$$U = -\left[q\frac{s}{2}|E|\cos\theta + (-q)\left(-\frac{s}{2}\right)|E|\cos\theta\right]$$

$$= -p \cdot E$$

$$(-\frac{s}{2},0)(+\frac{s}{2},0)$$

$$T = (x,y,z)$$

$$U(r) = \frac{q}{4\pi\epsilon_0}\left(\frac{1}{r_1} - \frac{1}{r_2}\right)$$

$$r_1 = \sqrt{r^2 + (s/2)^2 - rs\cos\theta}$$

$$r_2 = \sqrt{r^2 + (s/2)^2 + rs\cos\theta}$$

 $s \ll r$

$$\frac{1}{r_1} = \frac{1}{\sqrt{r^2 + (s/2)^2 - rs\cos\theta}}$$

$$= \frac{1}{r} \left(1 + \left(\frac{s}{2r}\right)^2 - \frac{s}{r}\cos\theta \right)^{-\frac{1}{2}}$$

$$= \frac{1}{r} \left(1 - \frac{1}{2} \left[\left(\frac{s}{2r}\right)^2 - \frac{s}{r}\cos\theta \right] \right)$$

$$= \frac{1}{r} \left(1 - \frac{s^2}{8r^2} + \frac{s}{2r}\cos\theta \right)$$

$$\frac{1}{r_2} = \frac{1}{r} \left(1 - \frac{s^2}{8r^2} - \frac{s}{2r} \cos \theta \right)$$

$$U(r) = \frac{q}{4\pi\epsilon_0} \frac{s}{r^2} \cos \theta$$
$$= \frac{p \cdot r}{4\pi\epsilon_0 r^3}$$

$$E(r) = -\frac{\partial U}{\partial r}$$

$$\begin{split} -\frac{\partial U}{\partial x} &= -\frac{\partial}{\partial x} \left(\frac{1}{4\pi\epsilon_0} \frac{p_x x + p_y y + p_z z}{(x^2 + y^2 + z^2)^{3/2}} \right) \\ &= -\frac{1}{4\pi\epsilon_0} \left[\frac{p_x}{(x^2 + y^2 + z^2)^{3/2}} - (p_x x + p_y y + p_z z) (\frac{3}{2}) (x^2 + y^2 + z^2)^{5/2} (2x) \right] \\ &= -\frac{1}{4\pi\epsilon_0} \left[\frac{p_x}{r^3} - \frac{3x(p \cdot r)}{r^5} \right] \end{split}$$

y, z

$$E(r) = \frac{1}{4\pi\epsilon_0} \left[\frac{p}{r^3} - \frac{3r(p \cdot r)}{r^5} \right]$$

2. 磁気モーメント

$$N S$$

$$+q_m(N), -q_m(S) Wb F = q_m H S N$$

s

$$m = q_m s$$

$$U = -m \cdot H$$

$$H(r) = -\frac{1}{4\pi\mu_0} \left[\frac{m}{r^3} - \frac{3r(m \cdot r)}{r^5} \right]$$

m'

$$U = -m' \cdot B$$

$$m'=m/\mu_0$$

$$B(r) = -\frac{\mu_0}{4\pi} \left[\frac{m'}{r^3} - \frac{3r(m' \cdot r)}{r^5} \right]$$