

ME40064 System Modelling and Simulation - Coursework 2

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1. Introduction

Finite Element Method (FEM) is a powerful numerical technique for solving equations over a discrete domain. The simulated system is split into small regions called **elements**, connected by **nodes** which represent discrete points in the domain, together making up a **mesh**. Elements are evaluated using **basis functions** which approximate the solution within each element based on node values [1]. This approach allows for practical solutions to problems that may be difficult or impossible to solve analytically. In addition to this, the size and shape of elements can be adjusted to improve accuracy or reduce computational cost, making FEM a powerful and flexible tool for modelling (Figure 1).



Figure 1: Finite Element Modelling of a Wrench under a Test Load Scenario [2]

This coursework focuses on the implementation and verification of a FEM solver for the transient diffusion-reaction equation, given by

$$\frac{\delta c}{\delta t} = D \frac{\delta^2 c}{\delta x^2} + \lambda c + f, \quad (1)$$

where c is the concentration level, D is the diffusion coefficient, λ is the reaction rate and f is a source term [3].

The transient diffusion-reaction equation models processes where substances diffuse through a medium while undergoing reactions or being influenced by boundary interactions. Examples of situations modelled by this equation include the transfer of heat through a material or (as explored in Part 3 of this report) the diffusion of a drug through biological tissue.

This coursework describes the development and validation of a FEM solver for the transient diffusion-reaction equation. To keep the scope manageable, the solver was implemented in 1D, using MATLAB as the scripting language [4].

2. Part 1: Software Verification

2.1. Background

A static FEM solver was implemented in a previous coursework for the steady-state diffusion-reaction equation. This solver was subsequently adapted to solve the transient form of the equation (Equation 1).

For the initial case, the values of $D = 1$ and $\lambda = 0$ were used, representing a pure diffusion scenario with linear behaviour. The **Crank-Nicolson** finite difference method was used for time integration. It has unconditional stability but no damping of oscillations, providing a good compromise between accuracy and stability at this stage [5].

The problem space was further defined with the following conditions:

Problem Space	$0 \leq x \leq 1$
Left Boundary Condition	Dirichlet: $c(0, t) = 0$
Right Boundary Condition	Dirichlet: $c(1, t) = 1$
Initial Condition	$c(x, 0) = 0$

Table 1: Initial Case Conditions

These conditions have a known analytical solution, given by Equation 2:

$$c(x, t) = x + \frac{2}{\pi} \sum_{n=1}^{\infty} \frac{(-1)^n}{n} e^{-n^2 \pi^2 t} \sin(n\pi x) \quad (2)$$

The analytical solution allows for direct comparison of results between the FEM solver and expected values, providing a quantitative measure of accuracy.

2.2. Software Architecture

The solver was implemented with a modular, object-oriented software architecture to improve readability and control flow. Classes were created to encapsulate well-defined functions of the solver, such as mesh generation or plotting (Figure 2).

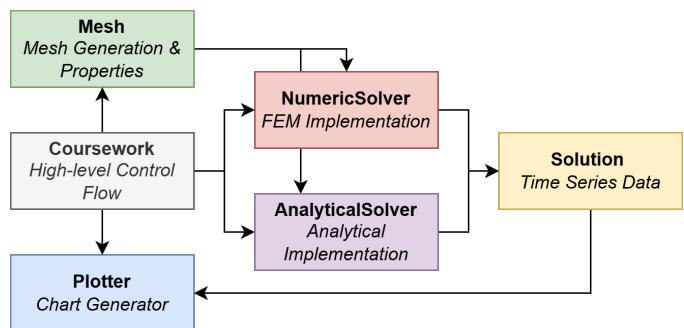


Figure 2: High-Level Software Architecture of the FEM Solver

2.3. Results

Having implemented the FEM solver as described above, a simulation was run using a mesh size of 50 elements and a time step of 0.01s, over the time period $0 < t \leq 1s$.

After this, the results were plotted on a series of charts for a visual comparison of the two solutions. The first of these were heatmaps which are an effective method for visualising the 1D diffusion over time (Figure 4, Figure 3).

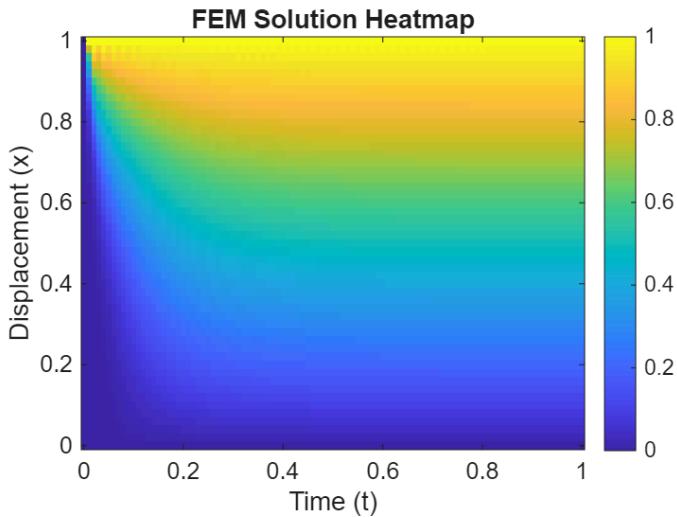


Figure 3: FEM Solution of Diffusion Equation over using the Crank-Nicolson method over $0 \leq x \leq 1$ and $0 \leq t \leq 1s$

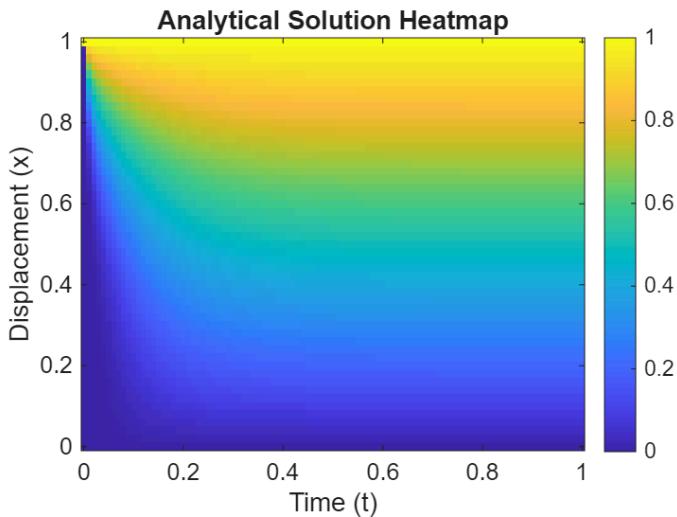


Figure 4: Analytical Solution of Diffusion Equation over $0 \leq x \leq 1$ and $0 \leq t \leq 1s$

The data was also represented in a 2D plot, showing the concentration through the mesh at sample times of $t = 0.05s, 0.1s, 0.3s, 1.0s$, shown in Figure 5 and Figure 6.

Additionally, a chart was created for both solutions at a single point in the mesh ($x = 0.8$), shown in Figure 7. Unlike previous plots, this shows both methods on the same axes for direct comparison, demonstrating the agreement between the two solutions.

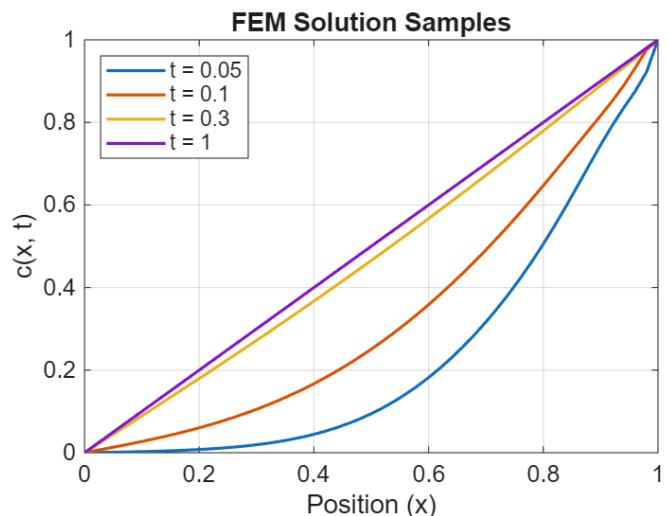


Figure 5: FEM Solution of Diffusion Equation over using the Crank-Nicolson method over $0 \leq x \leq 1$ and at $t = 0.05s, 0.1s, 0.3s, 1.0s$

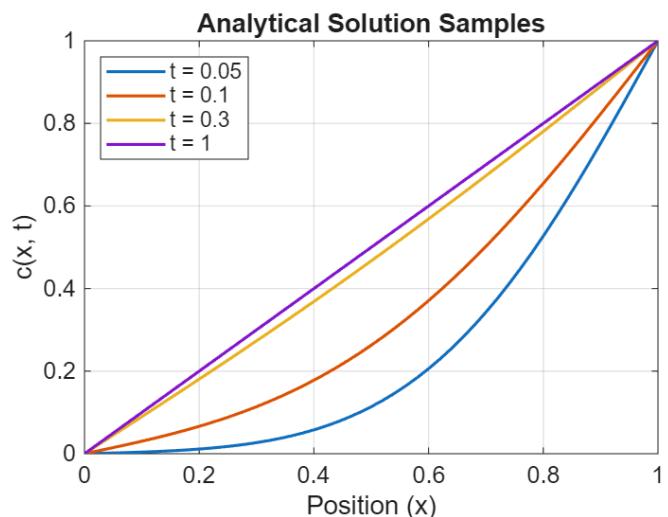


Figure 6: Analytical Solution of Diffusion Equation over $0 \leq x \leq 1$ and at $t = 0.05s, 0.1s, 0.3s, 1.0s$

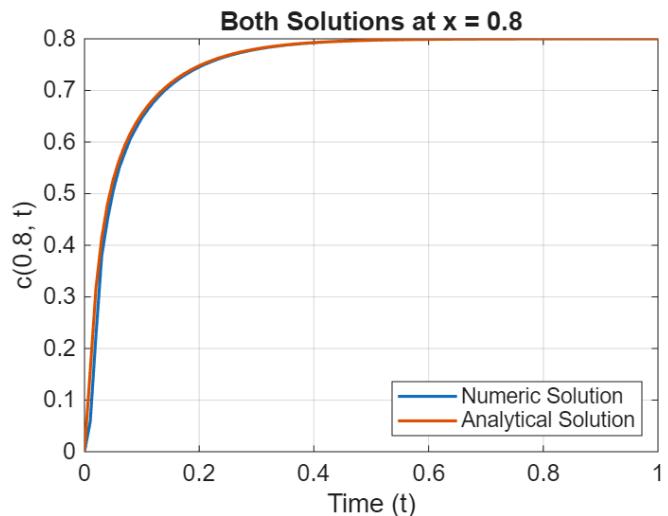


Figure 7: Comparison of Analytical and FEM Solutions at $x = 0.8$ over $0 \leq t \leq 1s$

2.4. Spacial and Temporal Convergence

To quantitatively assess the accuracy of the FEM solver, the **Root Mean Square (RMS)** error between numerical and analytical solutions was evaluated over a range of element and time step sizes. As shown in Figure 8 and Figure 9, the RMS error decreases with both smaller element sizes and smaller time steps, demonstrating convergence of the numerical solution towards the analytical solution with increasing resolution.

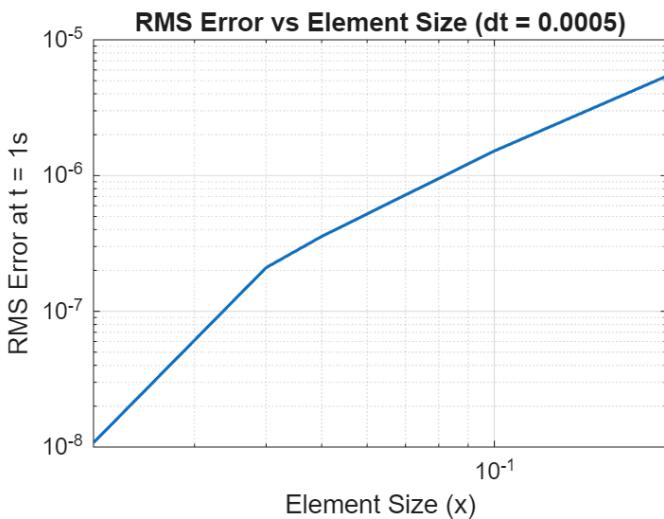


Figure 8: Comparison of RMS errors at $t = 1s$ for Varying Element Sizes

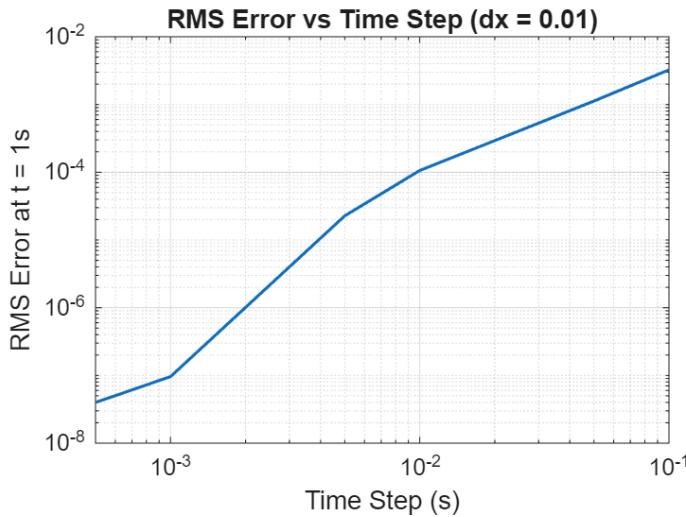


Figure 9: Comparison of RMS errors at $t = 1s$ for Varying Time Steps

2.5. Testing and Validation

A set of unit tests were created alongside the FEM solver, to verify the functionality of individual components such as mesh generation, element assembly, and time integration. As part of the development process, the project was continuously tested to ensure it passed all scenarios.

In particular, a unit test was created to validate the solver against a manufactured solution of the transient diffusion-reaction equation. This involved selecting specific values for D , λ , and f such that the solution could be expressed in a simple analytical form.

3. Part 2: Software features

3.1. Error Evaluation

In Part 1 of the coursework, the RMS error term was used to evaluate the accuracy of the FEM solver. While RMS is a useful metric, it can be sensitive to outliers and therefore may not always provide a complete picture of the solution accuracy. L₂ norm doesn't suffer as much from this, and is more widely used in literature as a result [3]. To address this, a dedicated L₂ error evaluation class was added to the solver, allowing for more robust error analysis.

3.2. Integration Methods

Using the L₂ norm error evaluation class, the performance of three different time integration methods was compared: Forward (Explicit) Euler, Backward (Implicit) Euler, and Crank-Nicolson. The comparison test was run using a mesh with 10 elements and a time step size of 0.0001s.

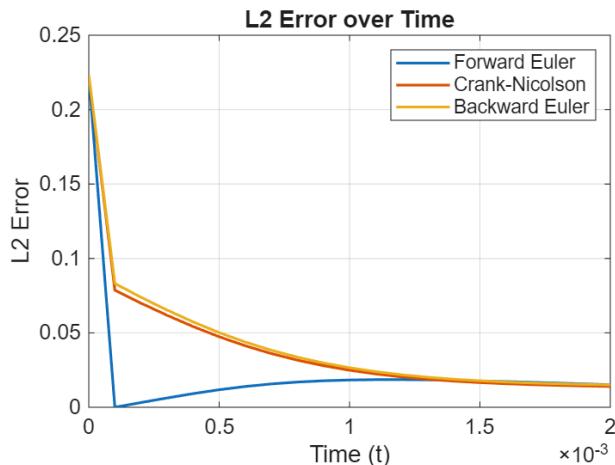


Figure 10: Comparison of L₂ Errors for Different Time Integration Methods

This shows that the Forward Euler method had a higher initial accuracy, approaching the solution more quickly than the other two methods, but that it started to decrease in accuracy again afterwards. This was likely caused by instability in the method, as it is only conditionally stable.

To illustrate this further, a stability analysis was performed for all three methods, using a larger mesh of 50 elements. The stability results are shown in Table 2:

dt	Forward Euler	Backward Euler	Crank-Nicolson
0.0001	Stable	Stable	Stable
0.001	Unstable	Stable	Stable
0.01	Unstable	Stable	Stable
0.1	Unstable	Stable	Stable
0.25	Unstable	Stable	Stable

Table 2: Integration Method Stability Comparison

This shows that the Forward Euler method was only stable for very small time steps, while the other two methods demonstrated **unconditional stability**, remaining stable across all tested time steps.

For linear finite elements, the stability condition for the Forward Euler method is given by the following equation [6]:

$$dt \leq \frac{dx^2}{2D} \quad (3)$$

Therefore, for a mesh with 50 elements over the domain $0 \leq x \leq 1$ and $D = 1$, the value of dt must be no more than 0.0002s for stability, which aligns with the results shown in Table 2.

3.3. Gaussian Quadrature

So far, the solver has only been used with a simple 2-point trapezoidal integration method for evaluating element matrices. While this method is easy to implement, it treats all elements as linear, requiring meshes with high numbers of elements to achieve good accuracy for non-linear problems.

Gaussian Quadrature is an alternative integration method that can provide a more accurate result with the same number of integration points as trapezoidal integration, resulting in a more efficient solution [7].

3.4. Quadratic Basis Functions

For 2-point basis functions like those used in the coursework so far, Gaussian Quadrature with 2 points will produce an identical result to trapezoidal integration. The mesh was therefore updated to support higher-order basis functions, such as quadratic (3-point) elements, where each element has a node at each end and one in the middle.

The L2 error of a quadratic mesh with both trapezoidal and Gaussian integration methods is shown below in Figure 11:

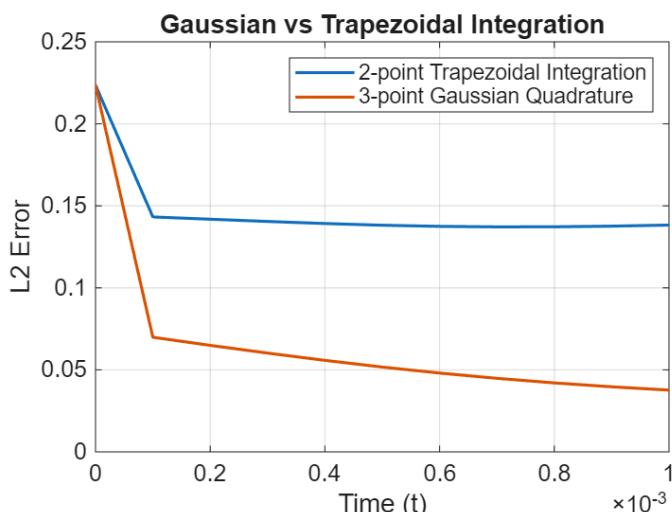


Figure 11: Comparison of L2 Errors for Gaussian Quadrature and Trapezoidal Integration

This shows a clear improvement in accuracy when using Gaussian Quadrature over trapezoidal integration with quadratic basis functions, approaching the analytical solution in a shorter time.

The reason for this improved performance is that Gaussian Quadrature evaluates the integrand at specially chosen points, capturing a more accurate representation of the function being integrated. Figure 12 shows a visual comparison of a trapezoidal integration, alongside a Gaussian Quadrature with 2 intermediary points.

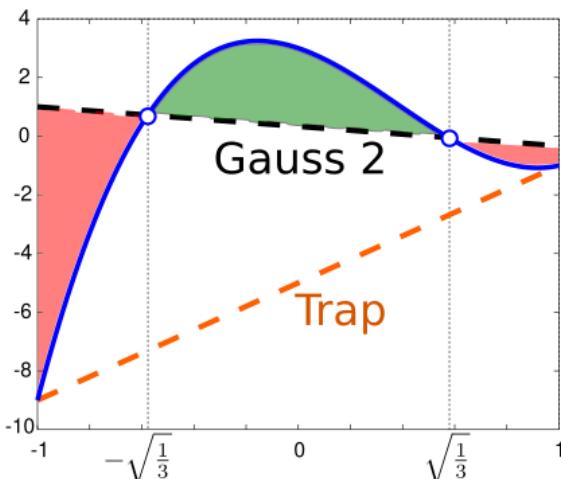


Figure 12: Visualisation of Gaussian Quadrature vs Trapezoidal Integration [8]

In the code implementation, the mesh was implemented with an arbitrary order parameter, dynamically calculating the number of nodes based off the baseline element count and order. In comparison, the code for Gaussian Quadrature was implemented with pre-defined functions for 1, 2 and 3 integration points, and shape functions for linear and quadratic elements.

3.5. Summary of Features

The addition of L2 error evaluation was an effective way to quantitatively assess the accuracy of the FEM solver, with varying configurations. It was found that the Crank-Nicolson method remained a suitable choice for time integration, balancing accuracy and stability, while the addition of Gaussian Quadrature and higher-order basis functions showed a significant improvement to solution accuracy.

Together these features enhance the capability and robustness of the FEM solver, allowing it to tackle a wider range of problems with improved accuracy and efficiency.

The robust, object-oriented software architecture introduced in Part 1 was also extended, with new classes and tests for the additional functionality.

4. Part 3: Modelling & Simulation Results

4.1. Overview

The transient FEM solver developed in Parts 1 and 2 was then applied to a practical problem: modelling the diffusion of a drug through a multilayer skin structure, as shown in the diagram below:

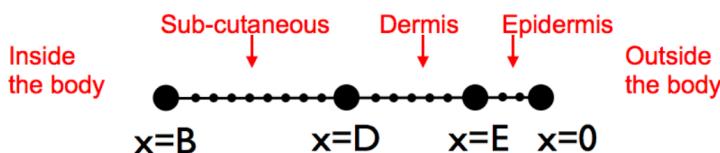


Figure 13: 1D Multilayer Finite Element Mesh of Skin Tissue Layers [9]

The concentration of the drug is modelled by the transient diffusion-reaction equation

$$\frac{\delta c}{\delta t} = D \frac{\delta^2 c}{\delta x^2} - \beta c - \gamma c, \quad (4)$$

where c is the drug concentration, D is the diffusion coefficient, β is the extra-vascular diffusivity, and γ is the drug degradation rate. For the purposes of modelling, β and γ are combined into a single reaction rate term i.e $\lambda = \beta + \gamma$, as they both act as sink terms that reduce the drug concentration.

4.2. Solver Modification

The main difference between the skin application and previous problems is the use of a multilayer mesh. A new **MultilayerMesh** class was created, inheriting from the original **Mesh** class, and overriding a method to generate a mesh made up of discrete layers (**MeshLayer** class), each with different properties.

In addition to variable diffusion and reaction rates, a ‘density ratio’ property was added to each layer, allowing for a non-uniform distribution of elements across the mesh. Thinner layers can therefore be assigned a higher density ratio, resulting in a local mesh with higher resolution, and improved solution accuracy.

This was implemented in three passes. First, the total density of all layers was calculated. Then, the number of elements in each layer was found by multiplying the total element count by the ratio of the layer density to total density. As an example, if there were two layers with density ratios of 1 and 3 respectively, and a total of 40 elements, the layers would be assigned 10 and 30 elements respectively. After this, the node co-ordinates were generated for each layer in sequence, with a uniform distribution according to the number of elements assigned to that layer, and its range of x values.

4.3. Simulation Results

The modified solver was then configured to solve the coursework-specified problem, with the following conditions:

Problem Space	$0 \leq x \leq 0.01$
Left Boundary Condition	Dirichlet: $c(0, t) = 30$
Right Boundary Condition	Dirichlet: $c(0.01, t) = 0$
Initial Condition	$c(x, 0) = 0$

Table 3: Drug Concentration Problem Conditions

This used a multilayer mesh with three layers representing the epidermis, dermis and sub-cutaneous tissue, with the following parameters:

Parameter	Epidermis	Dermis	Sub-Cutaneous
x Range	$0 \leq x < 0.00166667$	$0.00166667 \leq x < 0.005$	$0.005 \leq x \leq 0.01$
D	4e-6	5e-6	2e-6
β	0.0	0.01	0.01
γ	0.02	0.02	0.02
Density Ratio	2.0	1.0	1.0

Table 4: Mesh Layer Parameters

The simulation was then run using an initial mesh size of 50 elements and a time step of 0.01s, over the specified time period of $0 < t \leq 30s$.

The results were plotted as a heatmap (Figure 14), showing the diffusion of the drug through the multilayer skin structure over time. Additionally marked on this plot are the approximate boundaries between each layer.

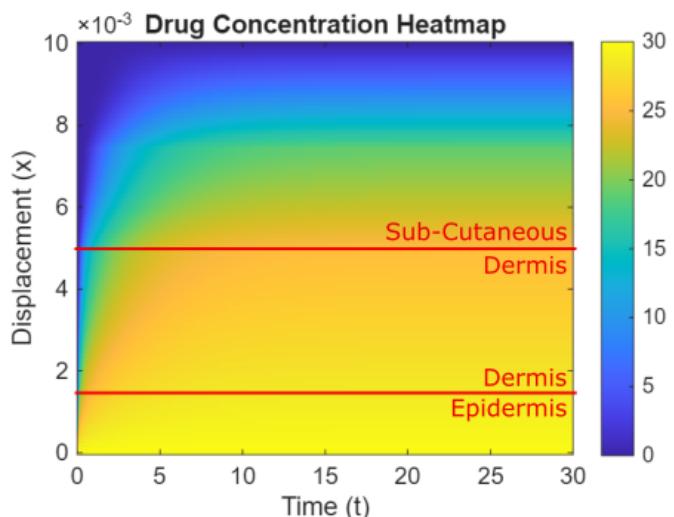


Figure 14: FEM Solution of Drug Diffusion through Multilayer Skin Structure over $0 \leq x \leq 0.01$ and $0 \leq t \leq 30s$

A stable profile is visible after around 10 seconds, with the epidermis layer almost immediately saturated to a high level, and the dermis soon after with a slightly lower concentration. The sub-cutaneous layer shows a much more gradual concentration gradient, mainly due to the Dirichlet boundary at $x = 0.01$ of $c(0.01, t) = 0$ forcing a perfect sink along the far edge of the mesh.

4.4. Dose Evaluation

After establishing a baseline simulation profile, the next step was to calculate the effectiveness of the drug diffusion. This was evaluated using the **kappa** metric, defined as the integral of the concentration above a threshold level over a specified time period, given by

$$K = \int_{t_{\text{eff}}}^{t=30} c \, dt \quad (5)$$

where t_{eff} is the time at which the concentration first exceeds the threshold level (here 4.0), $t = 30$ is the end of the simulation period, and c is the drug concentration at a target point in the mesh.

A new class, **DoseEvaluator**, was created to provide this functionality, with a static method **EvaluateSolution** that returns the kappa value for a given solution dataset, target location and threshold concentration. The logic is quite simple; first the node closest to the target location is identified, and then the concentration values for that node are checked against the target threshold. If the concentration exceeds the threshold, the solution is integrated between the time this occurs and the end of the simulation, using a trapezoidal method.

4.5. Minimum Dose Search

The **DoseEvaluator** class was then modified to add a new function, **FindMinimumDose**. The purpose of this was to identify the minimum required dose of the drug that would achieve a sufficient value of kappa.

This process was achieved with a **binary search** algorithm, which iteratively narrows down the range of possible dose values, converging on the minimum effective dose. It relies on having a correct initial upper and lower bound for the dose, but provides an effective search method with relatively few iterations.

The minimum effective dose, c_{DOSE} , was defined as the value at which the concentration at $x = 0.005$ exceeds a threshold of $K > 1000$. A search was run with an initial search range of $0 \leq c \leq 100$, using a tolerance of 0.1 for convergence. The results of this search are shown below in Figure 15:

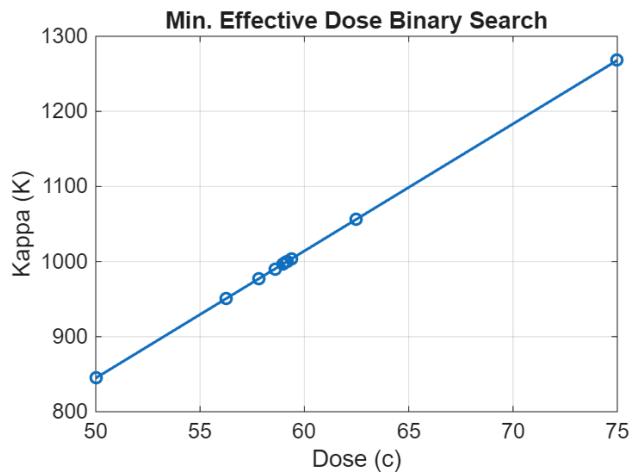


Figure 15: Binary Search for Minimum Effective Dose

This shows that the relationship between dose and kappa is linear, and that the minimum effective dose was found to be approximately **59.18**.

4.6. Dose Sensitivity Analysis

A sensitivity analysis was then performed on the model, investigating the impact of varying the diffusion coefficient D , extra-vascular diffusivity β , and drug degradation rate γ on the concentration at $x = 0.005$ over time, and the resulting dose effectiveness K (Kappa).

4.6.1. Diffusion Coefficient

The diffusion coefficient D was investigated by scaling the original values for each layer by factors of 0.5, 0.75, 1.0, 1.5 and 2.0. The results of this analysis are shown below in Figure 16 and Figure 17, illustrating the effect of varying D on concentration over time, and of the resultant dose effectiveness. These plots show a clear trend of increasing diffusion coefficient leading to higher concentrations at the target point, and therefore higher dose effectiveness K .

This is expected, as a higher diffusion coefficient allows the drug to spread more rapidly through the tissue layers, reaching the target point in a shorter time, with less degradation.

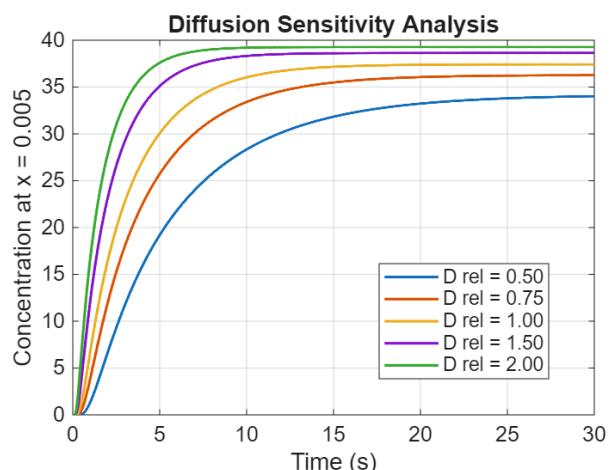
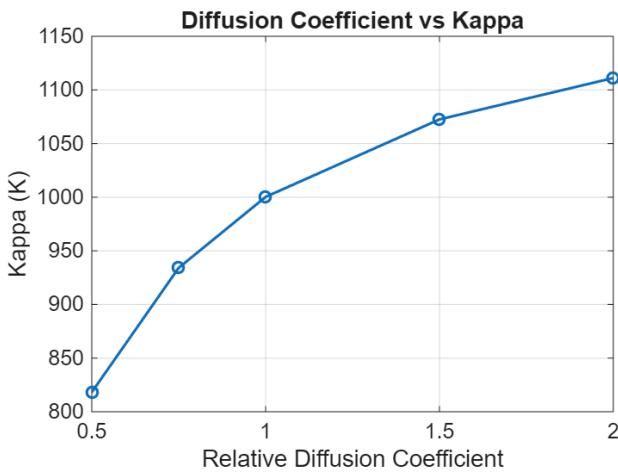
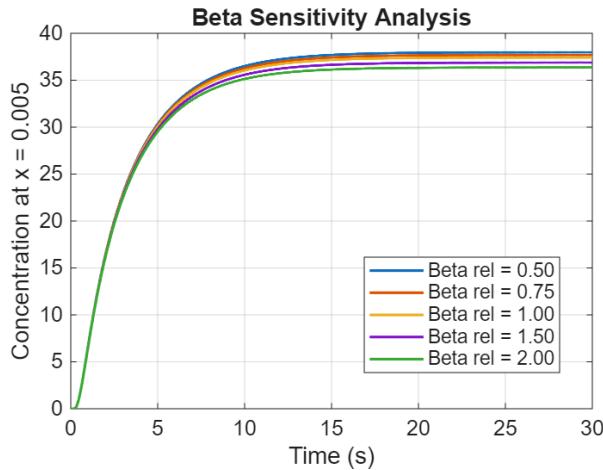
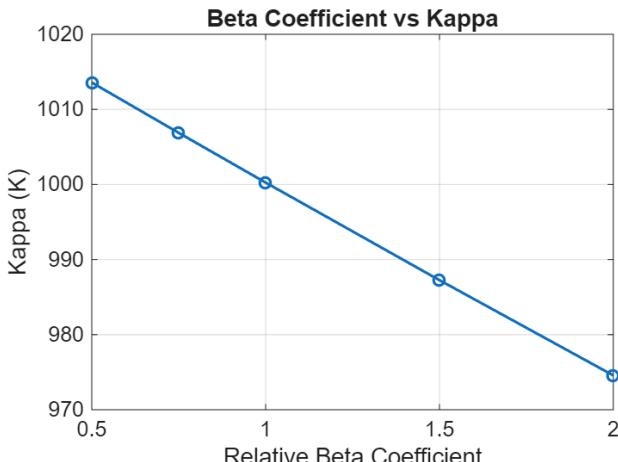


Figure 16: Concentration at $x = 0.005$ for Varying Values of D

Figure 17: Dose Effectiveness for Varying Values of D

4.6.2. Extra-Vascular Diffusivity

The next parameter to be investigated was extra-vascular diffusivity (β), varied in the same way as the diffusion coefficient. The results of this analysis are shown below in Figure 18 and Figure 19.

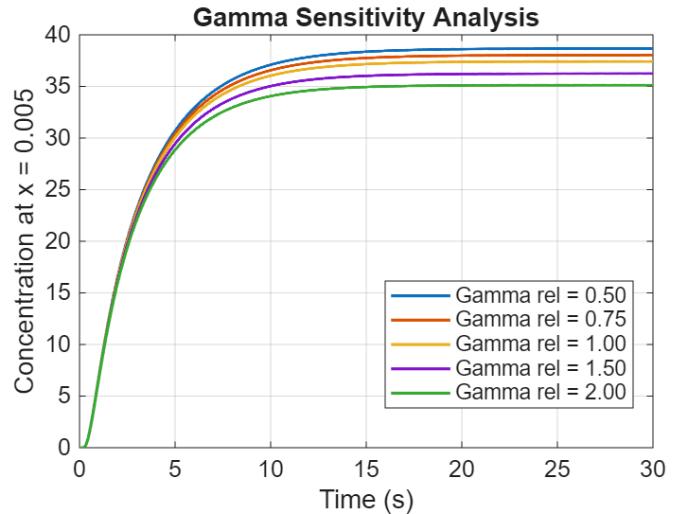
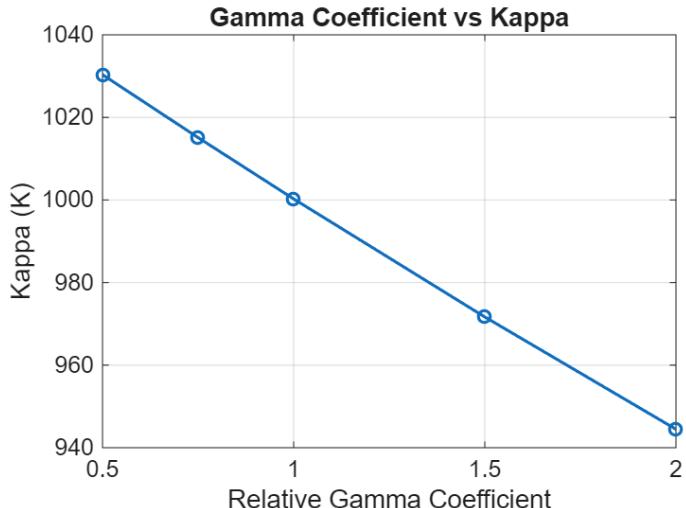
Figure 18: Concentration at $x = D$ for Varying Values of β Figure 19: Dose Effectiveness for Varying Values of β

These plots show an inverse, linear relationship between β and dose effectiveness. As β increases, the faster the drug diffuses out of the vascular system into surrounding

tissue, reducing the concentration at the target point and therefore lowering K .

4.6.3. Drug Degradation Rate

Finally, the drug degradation rate (γ) was investigated, again varied in the same way as previous parameters. The results of this analysis are shown below Figure 20 and Figure 21.

Figure 20: Concentration at $x = D$ for Varying Values of γ Figure 21: Dose Effectiveness for Varying Values of γ

As with β , these plots show an inverse, linear relationship between γ and dose effectiveness. A higher degradation rate results in the drug breaking down more quickly, reducing the concentration at the target point and lowering K .

From a mathematical perspective, this is also expected as both β and γ act as sink terms in the diffusion-reaction equation, reducing the overall concentration. However, as the original values of γ were larger than those of β , the impact of varying γ was more pronounced.

4.7. Further Work

While the FEM solver developed in this coursework has proved effective for modelling the 1D drug diffusion problem, there are several areas where further work could improve its performance.

One example is the implementation of continuous diffusion-reaction parameters across the mesh, instead of the discrete steps that are currently used. This would more accurately represent the gradual changes in tissue properties that occur in real biological systems.

Alongside this, the boundary conditions of a perfect source at one side and a perfect sink at the other are idealised scenarios. More realistic boundary conditions, such as Neumann or Robin conditions that vary over time, could be implemented to better simulate real-world situations [10].

The values chosen for the model parameters were based on the values provided in the coursework brief. However, these were stated as approximate or in some places unrealistic. More researched and physically accurate values would therefore improve the validity of the simulation results.

Increasing the mesh or time fidelity would also be likely improve accuracy, although both result in higher computational cost. More advanced meshing techniques could be explored, taking the multi-density approach further by implementing adaptive techniques that refine the mesh further in areas of high gradient.

Finally, the solver could be extended to 2D or 3D problems [11], allowing for more complex geometries and diffusion scenarios to be modelled. This would require significant changes to the mesh generation and element assembly processes, but would greatly expand the range of applications for the solver.

5. Conclusion

The FEM solver developed in this coursework was successfully implemented and validated against an analytical solution for the transient diffusion-reaction equation in Part 1. It was then improved in Part 2 with the addition of more advanced features such as L2 error evaluation, higher-order basis functions, and Gaussian Quadrature integration.

In Part 3, the solver was then applied to a practical problem, modelling the diffusion of a drug through a multi-layer skin structure. The initial results and subsequent analysis demonstrated a physically plausible diffusion profile, with a binary search method effectively identifying the minimum effective drug dose level.

Changes to key parameters in a sensitivity analysis produced results that aligned with both mathematical and physical interpretations of the sample problem, further validating the solver's performance.

Finally, several areas for further work were discussed and identified, providing a roadmap for future improvements to the solver. These further demonstrate the flexibility and suitability of the FEM approach for solving complex diffusion-reaction problems.

6. References

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7. Appendix - MATLAB Source Code

8. Main

8.1. main.m

```
1 %%%%%%
2 %
3 % ME40064 Coursework 2
4 %
5 % File      : main.m
6 % Author    : 11973
7 % Created   : 2025-11-24 (YYYY-MM-DD)
8 % License   : MIT
9 % Description : Main function for solving transient diffusion equation
10 %
11 %%%%%%
12
13 function main()
14     fprintf("ME40064 Coursework 2 Starting...\n");
15
16     % Part 1: Software Verification
17     Coursework.Part1Plots();
18     Coursework.Part1Convergence();
19
20     % Part 2: Software Features
21     Coursework.Part2TimeIntegrationComparison();
22     Coursework.Part2GaussianQuadrature();
23
24     % Part 3: Modelling & Simulation Results
25     Coursework.Part3InitialResults();
26     Coursework.Part3MinimumEffectiveDose();
27     Coursework.Part3DoseSensitivityAnalysis();
28
29     fprintf(...ME40064 Coursework 2 Complete\n");
30 end
31
```

9. Coursework

9.1. Coursework.m

```
1 %%%%%%
2 %
3 % ME40064 Coursework 2
4 %
5 % File      : Coursework.m
6 % Author    : 11973
7 % Created   : 2025-11-27 (YYYY-MM-DD)
8 % License   : MIT
9 % Description : Static methods for each part of the coursework.
10 %
11 %%%%%%
12
13 classdef Coursework
14
15     methods (Static)
16
17         function Part1Plots()
18             %%%%%%
19             %
20             % Function:      Part1Plots()
21             %
22             % Arguments:    None
23             % Returns:      None
24             %
25             % Description: Runs the start Part 1 of the coursework,
26             %                 generating a simple mesh, running numeric and
27             %                 analytical solvers, and plotting the results.
28             %
29 %%%%%%
30
31         % time parameters
32         tmax = 1.0;
33         dt = 0.01;
34
35         % mesh parameters
36         xmin = 0.0;
37         xmax = 1.0;
38         element_count = 50;
39         order = 1;
40
41         % Crank-Nicholson method
42         theta = 0.5;
43
44         % diffusion and reaction coefficients
45         D = 1.0;
46         lambda = 0.0;
47
48         % concentrations
49         c_max = 1.0;
50         c_min = 0.0;
51
52
53         % generate mesh
54         mesh = Mesh(xmin, xmax, element_count, order, D, lambda);
55         mesh.Generate();
56
57         % solver parameters
58         lhs_boundary = BoundaryCondition();
59         lhs_boundary.Type = BoundaryType.Dirichlet;
60         lhs_boundary.Value = c_min;
61
62         rhs_boundary = BoundaryCondition();
63         rhs_boundary.Type = BoundaryType.Dirichlet;
```

```
64     rhs_boundary.Value = c_max;
65
66     integration_method = IntegrationMethod();
67     integration_method.type = IntegrationType.Trapezoidal;
68     integration_method.gauss_points = 0; % not used for trapezoidal
69
70     % solve numerically
71     numeric_solution = NumericSolver.SolveNumeric(... ...
72         mesh, tmax, dt, theta, lhs_boundary, rhs_boundary, ...
73         @(~, ~) 0.0, integration_method);
74
75     % solve analytically
76     analytical_solution = AnalyticalSolver.SolveAnalytical(mesh, tmax, dt);
77
78     % plot solutions as a heatmaps
79     Plotter.PlotHeatMap(numeric_solution, "FEM Solution Heatmap", ...
80         "cw2/report/resources/part1/NumericHeatmap", c_max);
81
82     Plotter.PlotHeatMap(analytical_solution, "Analytical Solution Heatmap", ...
83         "cw2/report/resources/part1/AnalyticalHeatmap", c_max);
84
85     % plot solution samples at specified times
86     sample_times = [0.05, 0.1, 0.3, 1.0];
87
88     Plotter.PlotTimeSamples(numeric_solution, dt, sample_times, ...
89         "FEM Solution Samples", "cw2/report/resources/part1/NumericSamples");
90
91     Plotter.PlotTimeSamples(analytical_solution, dt, sample_times, ...
92         "Analytical Solution Samples", "cw2/report/resources/part1/AnalyticalSamples");
93
94     % plot both solutions at a specific position over time
95     sample_x = 0.8;
96     legend_strings = {"Numeric Solution", "Analytical Solution"};
97
98     Plotter.PlotSampleOverTime(numeric_solution, analytical_solution, ...
99         sample_x, "Both Solutions at x = 0.8", ...
100        "cw2/report/resources/part1/BothX08", legend_strings);
101
102 end
103
104 function Part1Convergence()
105 %%%%%%
106 %
107 % Function:      Part1Convergence()
108 %
109 % Arguments:    None
110 % Returns:      None
111 %
112 % Description:   Runs a convergence study for Part 1 of the
113 %                 coursework, calculating RMS error between numeric
114 %                 and analytical solutions over a range of element
115 %                 counts and time steps.
116 %
117 %%%%%%
118
119     % time parameters
120     tmax = 1.0;
121
122     % mesh parameters
123     xmin = 0.0;
124     xmax = 1.0;
125     element_count = 50;
126     order = 1;
127
128     % Crank-Nicholson method
129     theta = 0.5;
```

```
131      % diffusion and reaction coefficients
132      D = 1.0;
133      lambda = 0.0;
134
135      % concentrations
136      c_max = 1.0;
137      c_min = 0.0;
138
139
140      % generate mesh
141      mesh = Mesh(xmin, xmax, element_count, order, D, lambda);
142      mesh.Generate();
143
144      % solver parameters
145      lhs_boundary = BoundaryCondition();
146      lhs_boundary.Type = BoundaryType.Dirichlet;
147      lhs_boundary.Value = c_min;
148
149      rhs_boundary = BoundaryCondition();
150      rhs_boundary.Type = BoundaryType.Dirichlet;
151      rhs_boundary.Value = c_max;
152
153      integration_method = IntegrationMethod();
154      integration_method.type = IntegrationType.Trapezoidal;
155      integration_method.gauss_points = 0; % not used for trapezoidal
156
157      % calculate RMS error with varying mesh sizes and time steps
158
159      element_counts = [5, 10, 20, 25, 50];
160      time_steps = [0.1, 0.05, 0.01, 0.005, 0.001, 0.0005];
161
162      num_cases = length(element_counts) * length(time_steps);
163
164      % columns: elem_count, dt, dx, RMS error
165      rms_errr_table_elem_count = zeros(num_cases, 4);
166
167      % columns: elem_count, dt, dx, RMS error
168      rms_errr_table_time_step = zeros(num_cases, 4);
169
170      k = 1;
171
172      % vary element count with fixed time step
173      for i = 1:length(element_counts)
174          elem_count = element_counts(i);
175          dt = 0.0005;
176
177          % generate mesh
178          mesh = Mesh(xmin, xmax, elem_count, order, D, lambda);
179          mesh.Generate();
180
181          % solve numerically
182          numeric_solution = NumericSolver.SolveNumeric...
183              mesh, tmax, dt, theta, lhs_boundary, rhs_boundary, ...
184              @(~, ~) 0.0, integration_method);
185
186          % solve analytically
187          analytical_solution = AnalyticalSolver.SolveAnalytical(mesh, tmax, dt);
188
189          % compute RMS error
190          [~, final_time] = min(abs(analytical_solution.time - tmax));
191
192          c_numeric = numeric_solution.values(:, final_time);
193          c_analytical = analytical_solution.values(:, final_time);
194
195          error = c_numeric - c_analytical;
196          rms_error = sqrt(mean(error.^2));
197
```

```

198     rms_errr_table_elem_count(k,:) = [elem_count, dt, ...
199                               (xmax-xmin)/elem_count, rms_error];
200
201     k = k + 1;
202
203     fprintf("Elements: %d, dt: %.4f, dx: %.4f, RMS Error: %.6f\n", ...
204             elem_count, dt, (xmax-xmin)/elem_count, rms_error);
205 end
206
207 k = 1;
208
209 % vary time step with fixed element count
210 for j = 1:length(time_steps)
211
212     elem_count = 1 / 0.01;
213     dt = time_steps(j);
214
215     % generate mesh
216     mesh = Mesh(xmin, xmax, elem_count, order, D, lambda);
217     mesh.Generate();
218
219     % solve numerically
220     numeric_solution = NumericSolver.SolveNumeric(...
221         mesh, tmax, dt, theta, lhs_boundary, rhs_boundary, ...
222         @(~, ~) 0.0, integration_method);
223
224     % solve analytically
225     analytical_solution = AnalyticalSolver.SolveAnalytical(mesh, tmax, dt);
226
227     % compute RMS error
228     [~, final_time] = min(abs(analytical_solution.time - tmax));
229
230     c_numeric = numeric_solution.values(:, final_time);
231     c_analytical = analytical_solution.values(:, final_time);
232
233     error = c_numeric - c_analytical;
234     rms_error = sqrt(mean(error.^2));
235
236     rms_errr_table_time_step(k,:) = [elem_count, dt, ...
237                                     (xmax-xmin)/elem_count, rms_error];
238
239     k = k + 1;
240
241     fprintf("Elements: %d, dt: %.4f, dx: %.4f, RMS Error: %.6f\n", ...
242             elem_count, dt, (xmax-xmin)/elem_count, rms_error);
243 end
244
245 % plot element counts
246 dx = rms_errr_table_elem_count(:, 3); % element size
247 err_spatial = rms_errr_table_elem_count(:, 4);
248
249 Plotter.PlotConvergenceError(dx, err_spatial, ...
250     "RMS Error vs Element Size (dt = 0.0005)", ...
251     "cw2/report/resources/part1/ElementSizeConvergence", ...
252     "Element Size (x)", "RMS Error at t = 1s");
253
254 % plot time steps
255 dt_vals = rms_errr_table_time_step(:, 2); % time steps
256 err_temporal = rms_errr_table_time_step(:, 4);
257
258 Plotter.PlotConvergenceError(dt_vals, err_temporal, ...
259     "RMS Error vs Time Step (dx = 0.01)", ...
260     "cw2/report/resources/part1/TimeStepConvergence", ...
261     "Time Step (s)", "RMS Error at t = 1s");
262
263 end
264

```

```

265     function Part2TimeIntegrationComparison()
266 %%%%%%
267 %
268 % Function:      Part2TimeIntegrationComparison()
269 %
270 % Arguments:    None
271 % Returns:      None
272 %
273 % Description:   Runs a study comparing different time integration
274 %                  methods for Part 2 of the coursework.
275 %
276 %%%%%%
277
278     % time parameters
279 tmax = 0.002;
280 dt = 0.0001;
281
282     % mesh parameters
283 xmin = 0.0;
284 xmax = 1.0;
285 element_count = 10;
286 order = 1;
287
288     % diffusion and reaction coefficients
289 D = 1.0;
290 lambda = 0.0;
291
292     % concentrations
293 c_max = 1.0;
294 c_min = 0.0;
295
296     % generate mesh
297 mesh = Mesh(xmin, xmax, element_count, order, D, lambda);
298 mesh.Generate();
299
300     % solve analytically
301 analytical_solution = AnalyticalSolver.SolveAnalytical(mesh, tmax, dt);
302
303     % solver parameters
304 lhs_boundary = BoundaryCondition();
305 lhs_boundary.Type = BoundaryType.Dirichlet;
306 lhs_boundary.Value = c_min;
307
308 rhs_boundary = BoundaryCondition();
309 rhs_boundary.Type = BoundaryType.Dirichlet;
310 rhs_boundary.Value = c_max;
311
312 integration_method = IntegrationMethod();
313 integration_method.type = IntegrationType.Trapezoidal;
314 integration_method.gauss_points = 0; % not used for trapezoidal
315
316
317 l2_errors = [];
318
319 thetas = [0.0, 1.0, 0.5]; % Explicit Euler, Implicit Euler, Crank-Nicholson
320 method_names = {"Forward Euler", "Crank-Nicolson", "Backward Euler"};
321
322 for i = 1:length(thetas)
323     theta = thetas(i);
324
325     % solve numerically
326 numeric_solution = NumericSolver.SolveNumeric(
327         mesh, tmax, dt, theta, lhs_boundary, rhs_boundary, @(~, ~) 0.0, ...
328         integration_method);
329
330     % compute L2 error
331     l2_error = L2Error(analytical_solution, numeric_solution);

```

```

332         l2_errors = [l2_errors, l2_error];
333     end
334
335     Plotter.PlotL2Errors(l2_errors, "L2 Error over Time", ...
336         "cw2/report/resources/part2/L2ErrorTimeIntegration", ...
337         method_names);
338
339     % perform stability analysis
340
341     tmax = 1.0;
342     element_count = 50;
343     dt_list = [0.0001, 0.001, 0.01, 0.1, 0.25];
344
345     % generate mesh
346     mesh = Mesh(xmin, xmax, element_count, order, D, lambda);
347     mesh.Generate();
348
349     l2_errors_stability = [];
350
351     for i = 1:length(thetas)
352         theta = thetas(i);
353
354         l2_errors_dt = [];
355
356         for j = 1:length(dt_list)
357             dt = dt_list(j);
358
359             try
360
361                 fprintf("Testing %s with dt = %.4f...\n", method_names{i}, dt);
362
363                 numeric_solution = NumericSolver.SolveNumeric(...
364                     mesh, tmax, dt, theta, lhs_boundary, rhs_boundary, ...
365                     @(~, ~) 0.0, integration_method);
366
367                 % CHECK FOR NaN/Inf at each timestep
368                 for t_idx = 1:length(numeric_solution.time)
369                     vals = numeric_solution.values(:, t_idx);
370                     if any(isnan(vals))
371                         fprintf("%s: NaN at step %d (t=%.4f)\n", ...
372                             method_names{i}, t_idx, numeric_solution.time(t_idx));
373                         break;
374                     end
375                     if any(isinf(vals))
376                         fprintf("%s: Inf at step %d (t=%.4f)\n", ...
377                             method_names{i}, t_idx, numeric_solution.time(t_idx));
378                         break;
379                     end
380
381                     if max(abs(vals)) > 1e10
382                         fprintf("%s: Explosion at step %d (t=%.4f), max=%.2e\n",
383                             method_names{i}, t_idx, numeric_solution.time(t_idx), max(abs(vals)));
384                         break;
385                     end
386
387                     analytical_solution = AnalyticalSolver.SolveAnalytical(...
388                         mesh, tmax, dt);
389
390                     l2_error = L2Error(analytical_solution, numeric_solution);
391
392                     l2_errors_dt = [l2_errors_dt, l2_error];
393                 catch
394                     l2_errors_dt = [l2_errors_dt, NaN];
395                     fprintf("%s EXPLDED \n", method_names{i});
396                 end
397             end
398         end

```

```
398
399         l2_errors_stability = [l2_errors_stability; l2_errors_dt];
400     end
401
402     end
403
404     function Part2GaussianQuadrature()
405     %%%%%%
406     %
407     % Function:      Part2GaussianQuadrature()
408     %
409     % Arguments:    None
410     % Returns:      None
411     %
412     % Description:   Runs a study comparing L2 error with and without
413     %                  Gaussian Quadrature.
414     %
415     %%%%%%
416
417
418     % time parameters
419     tmax = 0.001;
420     dt = 0.0001;
421
422     % mesh parameters
423     xmin = 0.0;
424     xmax = 1.0;
425     element_count = 5;
426     order = 2;
427
428     % diffusion and reaction coefficients
429     D = 0.5;
430     lambda = 0.0;
431
432     % concentrations
433     c_max = 1.0;
434     c_min = 0.0;
435
436     % generate mesh
437     mesh = Mesh(xmin, xmax, element_count, order, D, lambda);
438     mesh.Generate();
439
440     % solve analytically
441     analytical_solution = AnalyticalSolver.SolveAnalytical(mesh, tmax, dt);
442
443     % solver parameters
444
445     theta = 0.5; % Crank-Nicholson
446
447     lhs_boundary = BoundaryCondition();
448     lhs_boundary.Type = BoundaryType.Dirichlet;
449     lhs_boundary.Value = c_min;
450
451     rhs_boundary = BoundaryCondition();
452     rhs_boundary.Type = BoundaryType.Dirichlet;
453     rhs_boundary.Value = c_max;
454
455     % trapezoidal method
456     trapezoidal_method = IntegrationMethod();
457     trapezoidal_method.type = IntegrationType.Trapezoidal;
458     trapezoidal_method.gauss_points = 0; % not used for trapezoidal
459
460     trapezoidal_solution = NumericSolver.SolveNumeric(
461         mesh, tmax, dt, theta, lhs_boundary, rhs_boundary, @(~, ~) 0.0, ...
462         trapezoidal_method);
463
464     % gaussian quadrature method
```

```
465 gaussian_method = IntegrationMethod();
466 gaussian_method.type = IntegrationType.Gaussian;
467 gaussian_method.gauss_points = 3; % 3-point Gaussian quadrature
468
469 gaussian_solution = NumericSolver.SolveNumeric(...  
    mesh, tmax, dt, theta, lhs_boundary, rhs_boundary, @(~, ~) 0.0, ...  
    gaussian_method);
470
471 % compute L2 error
472 l2_error_trapezoidal = L2Error(analytical_solution, trapezoidal_solution);
473 l2_error_gaussian = L2Error(analytical_solution, gaussian_solution);
474 l2_errors = [l2_error_trapezoidal, l2_error_gaussian];
475
476 method_names = {"2-point Trapezoidal Integration", ...
477     "3-point Gaussian Quadrature"};
478
479 Plotter.PlotL2Errors(l2_errors, "Gaussian vs Trapezoidal Integration", ...
480     "cw2/report/resources/part2/L2ErrorGaussianTrapezoidal", ...
481     method_names);
482
483 end
484
485 function Part3InitialResults()
486 %%%%%%
487 %
488 % Function:      Part3InitialResults()
489 %
490 % Arguments:    None
491 % Returns:      None
492 %
493 % Description:   Runs a basic case for Part 3 of the coursework
494 %
495 %%%%%%
496
497 % Generate mesh
498 xmin = 0;
499 xmax = 0.01;
500 element_count = 50;
501 order = 2;
502
503 theta = 0.5; % Crank-Nicholson
504 D = 1;
505 lambda = 0;
506
507 epidermis_layer = MeshLayer(0.0, 4e-6, 0.0, 0.02, 2.0);
508 dermis_layer = MeshLayer(0.00166667, 5e-6, 0.01, 0.02, 1.0);
509 sub_cutaneous_layer = MeshLayer(0.005, 2e-6, 0.01, 0.02, 1.0);
510
511 layers = [epidermis_layer, dermis_layer, sub_cutaneous_layer];
512
513 mesh = MultilayerMesh(xmin, xmax, element_count, order, D, lambda, layers);
514 mesh.Generate();
515
516 tmax = 30.0;
517 dt = 0.01; % works well with element_count = 50
518
519 % concentrations
520 c_max = 30.0;
521 c_min = 0.0;
522
523 lhs_boundary = BoundaryCondition();
524 lhs_boundary.Type = BoundaryType.Dirichlet;
525 lhs_boundary.Value = c_max;
526
527 rhs_boundary = BoundaryCondition();
528 rhs_boundary.Type = BoundaryType.Dirichlet;
529 rhs_boundary.Value = c_min;
530
531
```

```
532     integration_method = IntegrationMethod();
533     integration_method.type = IntegrationType.Gaussian;
534     integration_method.gauss_points = order + 1;
535
536     numeric_solution = NumericSolver.SolveNumeric(...  
      mesh, tmax, dt, theta, lhs_boundary, rhs_boundary, @(~, ~) 0.0,  
      integration_method);
537
538     Plotter.PlotHeatMap(numeric_solution, "Drug Concentration Heatmap", ...  
      "cw2/report/resources/part3/InitialNumericHeatmap", c_max);
539   end
540
541
542   function Part3MinimumEffectiveDose()
543 %%%%%%
544 %
545 % Function:      Part3MinimumEffectiveDose()
546 %
547 % Arguments:    None
548 % Returns:      None
549 %
550 %
551 % Description:  Runs a study to find the minimum effective dose for
552 %                 Part 3 of the coursework
553 %
554 %%%%%%
555
556   % Generate mesh
557   xmin = 0;
558   xmax = 0.01;
559   element_count = 50;
560   order = 2;
561
562   theta = 0.5; % Crank-Nicholson
563   D = 1;
564   lambda = 0;
565
566   epidermis_layer = MeshLayer(0.0, 4e-6, 0.0, 0.02, 2.0);
567   dermis_layer = MeshLayer(0.00166667, 5e-6, 0.01, 0.02, 1.0);
568   sub_cutaneous_layer = MeshLayer(0.005, 2e-6, 0.01, 0.02, 1.0);
569
570   layers = [epidermis_layer, dermis_layer, sub_cutaneous_layer];
571
572   mesh = MultilayerMesh(xmin, xmax, element_count, order, D, lambda, layers);
573   mesh.Generate();
574
575   tmax = 30.0;
576   dt = 0.01; % works well with element_count = 50
577
578   % concentrations
579   c_max = 30.0;
580   c_min = 0.0;
581
582   lhs_boundary = BoundaryCondition();
583   lhs_boundary.Type = BoundaryType.Dirichlet;
584   lhs_boundary.Value = c_max;
585
586   rhs_boundary = BoundaryCondition();
587   rhs_boundary.Type = BoundaryType.Dirichlet;
588   rhs_boundary.Value = c_min;
589
590   integration_method = IntegrationMethod();
591   integration_method.type = IntegrationType.Gaussian;
592   integration_method.gauss_points = order + 1;
593
594   % Find minimum dose
595   [c_dose_min, dose_vals, kappa_vals] = DoseEvaluator.FindMinimumDose(...  
      mesh, tmax, dt, theta, integration_method, ...  
      0.005, 4.0, 1000.0);
```

```
598
599     Plotter.PlotDoseEffectiveness(dose_vals, kappa_vals, ...
600         "Min. Effective Dose Binary Search", ...
601         "cw2/report/resources/part3/MinDoseBinarySearch", ...
602         "Dose (c)", "Kappa (K)");
603
604     fprintf("Minimum Effective Dose: %.2f\n", c_dose_min);
605 end
606
607 function Part3DoseSensitivityAnalysis()
608 %%%%%%
609 %
610 % Function:      Part3DoseSensitivityAnalysis()
611 %
612 % Arguments:    None
613 % Returns:      None
614 %
615 % Description:   Runs a study to plot the sensitivity of dose to
616 %                  diffusion, beta, and gamma coefficients for
617 %                  Part 3 of the coursework
618 %
619 %%%%%%
620
621     % common mesh parameters
622     xmin = 0;
623     xmax = 0.01;
624     element_count = 50;
625     order = 2;
626
627     tmax = 30.0;
628     dt = 0.01; % works well with element_count = 50
629
630     % concentrations
631     c_max = 59.18;
632     c_min = 0.0;
633
634     theta = 0.5; % Crank-Nicholson
635     D = 1;
636     lambda = 0;
637
638
639     lhs_boundary = BoundaryCondition();
640     lhs_boundary.Type = BoundaryType.Dirichlet;
641     lhs_boundary.Value = c_max;
642
643     rhs_boundary = BoundaryCondition();
644     rhs_boundary.Type = BoundaryType.Dirichlet;
645     rhs_boundary.Value = c_min;
646
647     integration_method = IntegrationMethod();
648     integration_method.type = IntegrationType.Gaussian;
649     integration_method.gauss_points = order + 1;
650
651     % diffusion coefficients analysis
652     relative_diffusions = [0.5, 0.75, 1.0, 1.5, 2.0];
653
654     target_x = 0.005; % use x = D as an example
655
656     x_values = [];
657     y_values = zeros(length(relative_diffusions), tmax/dt + 1);
658
659     kappa_values = [];
660
661     for d = 1:length(relative_diffusions)
662         D_rel = relative_diffusions(d);
663
664
```

```

665     epidermis_layer = MeshLayer(0.0, 4e-6 * D_rel, 0.0, 0.02, 2.0);
666     dermis_layer = MeshLayer(0.00166667, 5e-6 * D_rel, 0.01, 0.02, 1.0);
667     sub_cutaneous_layer = MeshLayer(0.005, 2e-6 * D_rel, 0.01, 0.02, 1.0);
668
669     layers = [epidermis_layer, dermis_layer, sub_cutaneous_layer];
670
671     mesh = MultilayerMesh(xmin, xmax, element_count, order, D, lambda, layers);
672     mesh.Generate();
673
674     numeric_solution = NumericSolver.SolveNumeric(...  

675         mesh, tmax, dt, theta, lhs_boundary, rhs_boundary, ...  

676         @(~, ~) 0.0, integration_method);
677
678     kappa_values = [kappa_values, DoseEvaluator.EvaluateSolution(...  

679         numeric_solution, 0.005, 4.0, 0.0)];
680
681     % first, find the closest node to the target
682     node_index = 0;
683
684     for i = 1:numeric_solution.mesh.node_count  

685         x = numeric_solution.mesh.node_coords(i);  

686         if x >= target_x  

687             node_index = i;  

688             break;  

689         end  

690     end
691
692     if d == 1  

693         x_values = numeric_solution.time;  

694     end
695
696     y_values(d, :) = numeric_solution.values(node_index, :);
697 end
698
699 legend_strings = [];
700
701 for d = 1:length(relative_diffusions)
702     legend_strings = [legend_strings, ...
703         sprintf("D rel = %.2f", relative_diffusions(d))];
704 end
705
706 fprintf("Plotting Dose Sensitivity Analysis...\n");
707
708 Plotter.PlotSensitivityAnalysis(x_values, y_values, ...
709     "Diffusion Sensitivity Analysis", ...
710     "cw2/report/resources/part3/DiffusionSensitivityAnalysis", ...
711     "Time (s)", "Concentration at x = 0.005", legend_strings);
712
713 Plotter.PlotKappaValues(relative_diffusions, kappa_values, ...
714     "Diffusion Coefficient vs Kappa", ...
715     "cw2/report/resources/part3/DiffusionKappa", ...
716     "Relative Diffusion Coefficient", "Kappa (K)");
717
718
719     % beta coefficients analysis
720
721     relative_betas = [0.5, 0.75, 1.0, 1.5, 2.0];
722
723     target_x = 0.005; % use x = D as an example
724
725     x_values = [];
726     y_values = zeros(length(relative_betas), tmax/dt + 1);
727     kappa_values = [];
728
729     for d = 1:length(relative_betas)
730
731         beta_rel = relative_betas(d);

```

```

732
733     epidermis_layer = MeshLayer(0.0, 4e-6, 0.0 * beta_rel, 0.02, 2.0);
734     dermis_layer = MeshLayer(0.00166667, 5e-6, 0.01 * beta_rel, 0.02, 1.0);
735     sub_cutaneous_layer = MeshLayer(0.005, 2e-6, 0.01 * beta_rel, 0.02, 1.0);
736
737     layers = [epidermis_layer, dermis_layer, sub_cutaneous_layer];
738
739     mesh = MultilayerMesh(xmin, xmax, element_count, order, D, lambda, layers);
740     mesh.Generate();
741
742     numeric_solution = NumericSolver.SolveNumeric(...,
743         mesh, tmax, dt, theta, lhs_boundary, rhs_boundary, ...
744         @(~, ~) 0.0, integration_method);
745
746     kappa_values = [kappa_values, ...
747         DoseEvaluator.EvaluateSolution(numeric_solution, 0.005, 4.0, 0.0)];
748
749     % first, find the closest node to the target
750     node_index = 0;
751
752     for i = 1:numeric_solution.mesh.node_count
753         x = numeric_solution.mesh.node_coords(i);
754         if x >= target_x
755             node_index = i;
756             break;
757         end
758     end
759
760     if d == 1
761         x_values = numeric_solution.time;
762     end
763
764     y_values(d, :) = numeric_solution.values(node_index, :);
765 end
766
767 legend_strings = [];
768
769 for d = 1:length(relative_betas)
770     legend_strings = [legend_strings, ...
771         sprintf("Beta rel = %.2f", relative_betas(d))];
772 end
773
774 fprintf("Plotting Dose Sensitivity Analysis...\n");
775
776 Plotter.PlotSensitivityAnalysis(x_values, y_values, ...
777     "Beta Sensitivity Analysis", ...
778     "cw2/report/resources/part3/BetaSensitivityAnalysis", ...
779     "Time (s)", "Concentration at x = 0.005", legend_strings);
780
781 Plotter.PlotKappaValues(relative_betas, kappa_values, ...
782     "Beta Coefficient vs Kappa", ...
783     "cw2/report/resources/part3/BetaKappa", ...
784     "Relative Beta Coefficient", "Kappa (K)");
785
786 % gamma coefficients analysis
787 relative_gammas = [0.5, 0.75, 1.0, 1.5, 2.0];
788
789 target_x = 0.005; % use x = D as an example
790
791 x_values = [];
792 y_values = zeros(length(relative_gammas), tmax/dt + 1);
793 kappa_values = [];
794
795 for d = 1:length(relative_gammas)
796     gamma_rel = relative_gammas(d);
797
798     % calculate concentration at target_x
799     % ...
800
801     % calculate dose at target_x
802     % ...
803
804     % calculate relative beta coefficient
805     % ...
806
807     % calculate kappa values
808     % ...
809
810     % store results
811     % ...
812
813     % plot results
814     % ...
815
816     % save results
817     % ...
818
819     % clean up
820     % ...
821
822     % repeat for all nodes
823     % ...
824
825     % calculate average kappa value
826     % ...
827
828     % calculate standard deviation of kappa values
829     % ...
830
831     % calculate confidence interval
832     % ...
833
834     % calculate p-value
835     % ...
836
837     % calculate effect size
838     % ...
839
840     % calculate power
841     % ...
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843     % calculate sample size
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1948
1949    % calculate sample variance
1950    % ...
1951
1952    % calculate sample mean
1953    % ...
1954
1955    % calculate sample size
1956    % ...
1957
1958    % calculate sample variance
1959    % ...
1960
1961    % calculate sample mean
1962    % ...
1963
1964    % calculate sample size
1965    % ...
1966
1967    % calculate sample variance
1968    % ...
1969
1970    % calculate sample mean
1971    % ...
1972
1973    % calculate sample size
1974    % ...
1975
1976    % calculate sample variance
1977    % ...
1978
1979    % calculate sample mean
1980    % ...
1981
1982    % calculate sample size
1983    % ...
1984
1985    % calculate sample variance
1986    % ...
1987
1988    % calculate sample mean
1989    % ...
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1991    % calculate sample size
1992    % ...
1993
1994    % calculate sample variance
1995    % ...
1996
1997    % calculate sample mean
1998    % ...
1999
2000    % calculate sample size
2001    % ...
2002
2003    % calculate sample variance
2004    % ...
2005
2006    % calculate sample mean
2007    % ...
2008
2009    % calculate sample size
2010    % ...
2011
2012    % calculate sample variance
2013    % ...
2014
2015    % calculate sample mean
2016    % ...
2017
2018    % calculate sample size
2019    % ...
2020
2021    % calculate sample variance
2022    % ...
2023
2024    % calculate sample mean
2025    % ...
2026
2027    % calculate sample size
2028    % ...
2029
2030    % calculate sample variance
2031    % ...
2032
2033    % calculate sample mean
2034    % ...
2035
2036    % calculate sample size
2037    % ...
2038
2039    % calculate sample variance
2040    % ...
2041
2042    % calculate sample mean
2043    % ...
2044
2045    % calculate sample size
2046    % ...
2047
2048    % calculate sample variance
2049    % ...
2050
2051    % calculate sample mean
2052    % ...
2053
2054    % calculate sample size
2055    % ...
2056
2057    % calculate sample variance
2058    % ...
2059
2060    % calculate sample mean
2061    % ...
2062
2063    % calculate sample size
2064    % ...
2065
2066    % calculate sample variance
2067    % ...
2068
2069    % calculate sample mean
2070    % ...
2071
2072    % calculate sample size
2073    % ...
2074
2075    % calculate sample variance
2076    % ...
2077
2078    % calculate sample mean
2079    % ...
2080
2081    % calculate sample size
2082    % ...
2083
2084    % calculate sample variance
2085    % ...
2086
2087    % calculate sample mean
2088    % ...
2089
2090    % calculate sample size
2091    % ...
2092
2093    % calculate sample variance
2094    % ...
2095
2096    % calculate sample mean
2097    % ...
2098
2099    % calculate sample size
2100    % ...
2101
2102    % calculate sample variance
2103    % ...
2104
2105    % calculate sample mean
2106    % ...
2107
2108    % calculate sample size
2109    % ...
2110
2111    % calculate sample variance
2112    % ...
2113
2114    % calculate sample mean
2115    % ...
2116
2117    % calculate sample size
2118    % ...
2119
2120    % calculate sample variance
2121    % ...
2122
2123    % calculate sample mean
2124    % ...
2125
2126    % calculate sample size
2127    % ...
2128
2129    % calculate sample variance
2130    % ...
2131
2132    % calculate sample mean
2133    % ...
2134
2135    % calculate sample size
2136    % ...
2137
2138    % calculate sample variance
2139    % ...
2140
2141    % calculate sample mean
2142    % ...
2143
2144    % calculate sample size
2145    % ...
2146
2147    % calculate sample variance
2148    % ...
2149
2150    % calculate sample mean
2151    % ...
2152
2153    % calculate sample size
2154    % ...
2155
2156    % calculate sample variance
2157    % ...
2158
2159    % calculate sample mean
2160    % ...
2161
2162    % calculate sample size
2163    % ...
2164
2165    % calculate sample variance
2166    % ...
2167
2168    % calculate sample mean
2169    % ...
2170
2171    % calculate sample size
2172    % ...
2173
2174    % calculate sample variance
2175    % ...
2176
2177    % calculate sample mean
2178    % ...
2179
2180    % calculate sample size
2181    % ...
2182
2183    % calculate sample variance
2184    % ...
2185
2186    % calculate sample mean
2187    % ...
2188
2189    % calculate sample size
2190    % ...
2191
2192    % calculate sample variance
2193    % ...
2194
2195    % calculate sample mean
2196    % ...
2197
2198    % calculate sample size
2199    % ...
2200
2201    % calculate sample variance
2202    % ...
2203
2204    % calculate sample mean
2205    % ...
2206
2207    % calculate sample size
2208    % ...
2209
2210    % calculate sample variance
2211    % ...
2212
2213    % calculate sample mean
2214    % ...
2215
2216    % calculate sample size
2217    % ...
2218
2219    % calculate sample variance
2220   
```

```
799
800     epidermis_layer = MeshLayer(0.0, 4e-6, 0.0, 0.02 * gamma_rel, 2.0);
801     dermis_layer = MeshLayer(0.00166667, 5e-6, 0.01, 0.02 * gamma_rel, 1.0);
802     sub_cutaneous_layer = MeshLayer(0.005, 2e-6, 0.01, 0.02 * gamma_rel, 1.0);
803
804     layers = [epidermis_layer, dermis_layer, sub_cutaneous_layer];
805
806     mesh = MultilayerMesh(xmin, xmax, element_count, order, D, lambda, layers);
807     mesh.Generate();
808
809     numeric_solution = NumericSolver.SolveNumeric(...,
810         mesh, tmax, dt, theta, lhs_boundary, rhs_boundary, ...
811         @(~, ~) 0.0, integration_method);
812     kappa_values = [kappa_values, ...
813         DoseEvaluator.EvaluateSolution(numeric_solution, 0.005, 4.0, 0.0)];
814
815
816     % first, find the closest node to the target
817     node_index = 0;
818
819     for i = 1:numeric_solution.mesh.node_count
820         x = numeric_solution.mesh.node_coords(i);
821         if x >= target_x
822             node_index = i;
823             break;
824         end
825     end
826
827     if d == 1
828         x_values = numeric_solution.time;
829     end
830
831     y_values(d, :) = numeric_solution.values(node_index, :);
832 end
833
834 legend_strings = [];
835
836 for d = 1:length(relative_gammas)
837     legend_strings = [legend_strings, ...
838         sprintf("Gamma rel = %.2f", relative_betas(d))];
839 end
840
841 fprintf("Plotting Dose Sensitivity Analysis...\n");
842
843 Plotter.PlotSensitivityAnalysis(x_values, y_values, ...
844     "Gamma Sensitivity Analysis", ...
845     "cw2/report/resources/part3/GammaSensitivityAnalysis", ...
846     "Time (s)", "Concentration at x = 0.005", legend_strings);
847
848 Plotter.PlotKappaValues(relative_gammas, kappa_values, ...
849     "Gamma Coefficient vs Kappa", ...
850     "cw2/report/resources/part3/GammaKappa", ...
851     "Relative Gamma Coefficient", "Kappa (K)");
852
853 end
854
855 end
856
857 end
858
```

10. Mesh

10.1. Mesh.m

```
1 %%%%%%
2 %
3 % ME40064 Coursework 2
4 %
5 % File      : Mesh.m
6 % Author    : 11973
7 % Created   : 2025-11-26 (YYYY-MM-DD)
8 % License   : MIT
9 % Description : A class defining a one-dimensional mesh for
10 %                finite element analysis.
11 %
12 %%%%%%
13
14 classdef Mesh < handle
15     % inherit from handle to allow pass-by-reference
16
17     properties
18
19         xmin          double % min x coordinate
20         xmax          double % max x coordinate
21         dx            double % element size
22
23         order         double % element order (1=linear, 2=quadratic etc)
24
25         D             double % diffusion coefficient
26         lambda        double % reaction coefficient
27
28         node_count    uint64 % total number of global nodes
29         node_coords   double % coordinates of global nodes
30
31         element_count uint64
32         elements      MeshElement % array of mesh elements
33
34     end
35
36     methods
37
38         function obj = Mesh(xmin, xmax, element_count, order, D, lambda)
39         %%%%%%
40         %
41         % Function:      Mesh()
42         %
43         % Arguments:    parameters to initialise
44         % Returns:       Mesh handle
45         %
46         % Description:  Initialises a one-dimensional mesh object
47         %
48         %%%%%%
49
50         % assign properties
51         obj.xmin = xmin;
52         obj.xmax = xmax;
53         obj.dx = (xmax - xmin) / element_count;
54         obj.D = D;
55         obj.lambda = lambda;
56
57         obj.order = order;
58
59         % total number of nodes
60         obj.node_count = (element_count * order) + 1;
61         obj.node_coords = zeros(1, obj.node_count);
62
63         obj.element_count = element_count;
```

```

64         obj.elements = MeshElement.empty(element_count, 0);
65
66     end
67
68     function obj = Generate(obj)
69 %%%%%%
70 %
71 % Function:      Generate()
72 %
73 % Arguments:    Mesh handle
74 % Returns:       Mesh handle
75 %
76 % Description: Generates the mesh for the given object
77 %
78 %%%%%%
79
80     disp('Generating normal mesh...');
81
82     % generate uniform node coordinates
83     obj.node_coords = linspace(obj.xmin, obj xmax, obj.node_count);
84
85     % generate elements
86     for e = 1:obj.element_count
87
88         % determine global node IDs for this element
89         node_start = (e - 1) * obj.order + 1;
90         node_ids = node_start:(node_start + obj.order);
91
92         % coordinates for this element
93         coords = obj.node_coords(node_ids);
94
95         % create MeshElement object
96         obj.elements(e) = MeshElement(
97             node_ids, coords, obj.order, obj.D, obj.lambda);
98     end
99
100    end
101 end
102 end
103

```

10.2. MeshElement.m

```

1 %%%%%%
2 %
3 % ME40064 Coursework 2
4 %
5 % File          : MeshElement.m
6 % Author        : 11973
7 % Created       : 2025-11-26 (YYYY-MM-DD)
8 % License       : MIT
9 % Description   : A class defining a one-dimensional mesh element
10 %
11 %%%%%%
12
13 classdef MeshElement
14
15     properties
16
17         order      uint8    % polynomial order (1 = linear, 2 = quadratic)
18         node_ids   uint64   % global node IDs
19         node_coords double  % node coordinates
20         jacobian   double  % element jacobian d(x)/d(xi)
21         D          double  % diffusion coefficient
22         lambda     double  % reaction coefficient

```

```

23 end
24
25 methods
26
27 function obj = MeshElement(ids, coords, order, D, lambda)
28 %%%%%%
29 %
30 % Function:      MeshElement()
31 %
32 % Arguments:    parameters to initialise
33 % Returns:       MeshElement handle
34 %
35 % Description:  Initialises a one-dimensional mesh element object
36 %
37 %%%%%%
38
39 % assign properties
40 obj.node_ids = ids;
41 obj.node_coords = coords;
42 obj.order = order;
43 obj.D = D;
44 obj.lambda = lambda;
45
46 % linear mapping from [-1, 1] to [x1, x2]
47 % jacobian = dx/dxi = (x2 - x1) / 2
48 obj.jacobian = (coords(end) - coords(1)) / 2;
49
50 end
51 end
52 end
53
54

```

10.3. MultilayerMesh.m

```

1 %%%%%%
2 %
3 % ME40064 Coursework 2
4 %
5 % File        : MultilayerMesh.m
6 % Author      : 11973
7 % Created     : 2025-11-26 (YYYY-MM-DD)
8 % License     : MIT
9 % Description : A class defining a multilayer one-dimensional mesh for
10 %                finite element analysis.
11 %
12 %%%%%%
13
14
15 classdef MultilayerMesh < Mesh
16     % inherit from Mesh
17
18     properties
19         layers          MeshLayer % array of layer properties
20         total_density   double % total density ratio across all layers
21     end
22
23     methods
24
25         function obj = MultilayerMesh(xmin, xmax, element_count, order, D, lambda, layers)
26             %%%%%%
27             %
28             % Function:      MultilayerMesh()
29             %
30             % Arguments:    initialisation parameters including layers

```

```
31      % Returns:      MultilayerMesh handle
32      %
33      % Description: Initialises a multilayer one-dimensional mesh object
34      %
35      %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
36
37      % call superclass constructor
38      obj = obj@Mesh(xmin, xmax, element_count, order, D, lambda);
39      obj.layers = layers;
40
41
42      % recalculate nodes and element counts based on layer densities
43      obj.total_density = 0.0;
44
45      for l = 1:length(layers)
46          obj.total_density = obj.total_density + layers(l).density_ratio;
47      end
48
49      obj.element_count = 0;
50
51      for l = 1:length(layers)
52
53          layer_density = obj.layers(l).density_ratio;
54          layer_element_count = round(...
55              (layer_density / obj.total_density) * element_count);
56
57          obj.layers(l).element_count = layer_element_count;
58
59          % starting index for this layer
60          obj.layers(l).layer_offset = obj.element_count + 1;
61
62          obj.element_count = obj.element_count + layer_element_count;
63      end
64
65      obj.node_count = (obj.element_count * order) + 1;
66      obj.node_coords = zeros(1, obj.node_count);
67
68      obj.elements = MeshElement.empty(obj.element_count, 0);
69
70  end
71
72  function obj = Generate(obj)
73  %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
74  %
75  % Function:      Generate()
76  %
77  % Arguments:     MultilayerMesh handle
78  % Returns:       MultilayerMesh handle
79  %
80  % Description:   Generates the mesh for the given object,
81  %                 overriding the base Mesh.Generate() method.
82  %
83  %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
84
85      disp('Generating multilayer mesh... ');
86
87      % generate per-layer uniform node coordinates
88
89      current_node = 1;
90
91      for l = 1:length(obj.layers)
92
93          % calculate layer xmin and xmax
94
95          layer_xmin = obj.layers(l).x;
96
97          if l < length(obj.layers)
```

```

98
99
100
101
102
103     layer_xmax = obj.layers(l + 1).x;
104
105     layer_xmax = obj.xmax;
106
107
108     if l == 1
109         nodes_to_add = layer_coords;
110     else
111         nodes_to_add = layer_coords(2:end); % Skip duplicate boundary node
112     end
113
114     % Add nodes to global coordinate array
115     num_new_nodes = length(nodes_to_add);
116     obj.node_coords(current_node : current_node + num_new_nodes - 1)...
117         = nodes_to_add;
118
119     current_node = current_node + num_new_nodes;
120
121
122 end
123
124 % Generate elements
125 for e = 1:obj.element_count
126
127     % Determine global node IDs for this element
128     node_start = (e - 1) * obj.order + 1;
129     node_ids = node_start:(node_start + obj.order);
130
131     % Coordinates for this element
132     coords = obj.node_coords(node_ids);
133
134     midpoint = (coords(1) + coords(end)) / 2;
135
136     % Determine which layer this element is in
137     layer_index = 1;
138     for l = 1:length(obj.layers)
139         if midpoint >= obj.layers(l).x
140             layer_index = l;
141         end
142     end
143
144     D = obj.layers(layer_index).D;
145     lambda = -(obj.layers(layer_index).beta + obj.layers(layer_index).gamma);
146
147     % Create MeshElement object
148     obj.elements(e) = MeshElement(node_ids, coords, obj.order, D, lambda);
149
150 end
151
152 end
153 end

```

10.4. MeshLayer.m

```
5 % File      : MeshLayer.m
6 % Author    : samh25
7 % Created   : 2025-11-29 (YYYY-MM-DD)
8 % License   : MIT
9 % Description : A class defining a layer in a multi-layer mesh
10 %
11 %%%%%%
12
13 classdef MeshLayer
14     properties
15         x           double % min x coordinate for this layer
16         density_ratio double % density ratio for this layer
17         D           double % diffusion coefficient
18         beta        double % extra-vascular diffusivity
19         gamma       double % drug degradation rate
20
21         element_count uint64 % number of elements in this layer
22         layer_offset  uint64 % starting element index for this layer
23     end
24
25     methods
26
27         function obj = MeshLayer(x, D, beta, gamma, density_ratio)
28             %%%%%%
29             %
30             % Function:      MeshLayer()
31             %
32             % Arguments:    parameters to initialise
33             % Returns:       MeshLayer handle
34             %
35             % Description:  Initialises a mesh layer object
36             %
37             %%%%%%
38
39         obj.x = x;
40         obj.D = D;
41         obj.beta = beta;
42         obj.gamma = gamma;
43         obj.density_ratio = density_ratio;
44
45         obj.element_count = 0;
46     end
47
48 end
49 end
```

11. Analytical

11.1. AnalyticalSolver.m

```

1 %%%%%%
2 %
3 % ME40064 Coursework 2
4 %
5 % File      : AnalyticalSolver.m
6 % Author    : 11973
7 % Created   : 2025-11-26 (YYYY-MM-DD)
8 % License   : MIT
9 % Description : A static class defining an analytical solver
10 %           for the transient diffusion equation
11 %
12 %%%%%%
13
14 classdef AnalyticalSolver
15
16     methods (Static)
17
18         function solution = SolveAnalytical(mesh, tmax, dt)
19             %%%%%%
20             %
21             % Function:      SolveAnalytical()
22             %
23             % Arguments:    mesh, max time and time step
24             % Returns:       solution to the equation
25             %
26             % Description:  Solves the transient diffusion equation using
27             %                 the analytical solution.
28             %
29             %%%%%%
30
31             % time vector
32             time_vector = 0:dt:tmax;
33             solution = Solution(mesh, time_vector);
34
35             % loop over time steps
36             for step = 1:length(time_vector)
37
38                 t = time_vector(step);
39                 timestep_results = zeros(1, mesh.node_count);
40
41                 % loop over nodes
42                 for i = 1:mesh.node_count
43                     x = mesh.node_coords(i);
44                     timestep_results(i) = TransientAnalyticSoln(x, t);
45                 end
46
47                 solution.SetValues(timestep_results, step);
48             end
49
50         end
51     end
52 end

```

11.2. TransientAnalyticSoln.m

```

1 %%%%%%
2 %
3 % ME40064 Coursework 2
4 %
5 % File      : TransientAnalyticSoln.m
6 % Author    : A. N. Cookson
7 % Created   : 2025-11-11 (YYYY-MM-DD)

```

```
8 % License      : -
9 % Description   : Analytical solution to transient diffusion equation
10%                      provided in the coursework materials.
11%
12%%%%%%%%%%%%%%%
13
14 function [ c ] = TransientAnalyticSoln(x,t)
15 %TransientAnalyticSoln Analytical solution to transient diffusion equation
16 % Computes the analytical solution to the transient diffusion equation for
17 % the domain x=[0,1], subject to initial condition: c(x,0) = 0, and Dirichlet
18 % boundary conditions: c(0,t) = 0, and c(1,t) = 1.
19 % Input Arguments:
20 % x is the point in space to evaluate the solution at
21 % t is the point in time to evaluate the solution at
22 % Output Argument:
23 % c is the value of concentration at point x and time t, i.e. c(x,t)
24
25 trans = 0.0;
26
27 for k=1:1000
28     trans = trans + ((((-1)^k)/k) * exp(-k^2*pi^2*t)*sin(k*pi*x));
29 end
30
31 c = x + (2/pi)*trans;
32
33 end
```

12. Plotter

12.1. Plotter.m

```
1 %%%%%%
2 %
3 % ME40064 Coursework 2
4 %
5 % File      : Plotter.m
6 % Author    : 11973
7 % Created   : 2025-11-26 (YYYY-MM-DD)
8 % License   : MIT
9 % Description : A collection of static methods for plotting
10 %           results for the coursework.
11 %
12 %%%%%%
13
14 classdef Plotter
15
16     methods (Static)
17
18         function PlotHeatMap(solution, title_str, name, c_max)
19             %
20             %
21             % Function: PlotHeatMap()
22             %
23             % Arguments: Plotting parameters
24             % Returns: None
25             %
26             % Description: Plots a 2D heat map of solution values
27             %
28             %%%%%%
29
30             set(0, "DefaultAxesFontSize", 12);
31             set(0, "DefaultTextFontSize", 12);
32
33             % Plot a heat map of the solution values over time
34             figure;
35             imagesc(solution.time, solution.mesh.node_coords, solution.values);
36             colorbar;
37             xlabel("Time (t)");
38             ylabel("Displacement (x)");
39             caxis([0 c_max]) % lock color axis for consistency
40             axis xy; % ensure y-axis is oriented correctly
41             title(title_str);
42             grid off;
43
44             set(gcf, 'Position', [0, 0, 500, 350]);
45
46             % Save figure
47             saveas(gcf, name, "png");
48             saveas(gcf, name, "fig");
49             openfig(name + ".fig");
50
51     end
52
53         function PlotTimeSamples(solution, dt, time_samples, title_str, name)
54             %
55             %
56             % Function: PlotTimeSamples()
57             %
58             % Arguments: Plotting parameters
59             % Returns: None
60             %
61             % Description: Plots a solution at multiple time samples
62             %
63             %%%%%%
```

```
64      set(0, "DefaultAxesFontSize", 12);
65      set(0, "DefaultTextFontSize", 12);
66
67      figure;
68      plot_handle = 0;
69
70      for i = 1:length(time_samples)
71          t_sample = time_samples(i);
72
73          step_index = round(t_sample / dt) + 1; % +1 for MATLAB indexing
74
75          plot_handle = plot(solution.mesh.node_coords, ...
76              solution.values(:, step_index));
77          set(plot_handle, "LineWidth", 1.5);
78
79          hold on;
80      end
81
82      xlabel("Position (x)");
83      ylabel("c(x, t)");
84      title(title_str);
85
86      grid on;
87
88      legend_strings = cell(1, length(time_samples));
89      for i = 1:length(time_samples)
90          legend_strings{i} = ['t = ', num2str(time_samples(i))];
91      end
92
93      legend(legend_strings, "Location", "northwest");
94
95      set(gcf, 'Position', [0, 0, 500, 350]);
96
97      % Save figure
98      saveas(gcf, name, "png");
99      saveas(gcf, name, "fig");
100     openfig(name + ".fig");
101
102    end
103
104    function PlotSampleOverTime(solution_1, solution_2, x_sample, title_str, name,
105    legend_strings)
106        %%%%%%
107        %
108        % Function:      PlotSampleOverTime()
109        %
110        % Arguments:    Plotting parameters
111        % Returns:       None
112        %
113        % Description: Plots two solutions at a given spatial sample over time
114        %
115        %%%%%%
116
117        set(0, "DefaultAxesFontSize", 12);
118        set(0, "DefaultTextFontSize", 12);
119
120        % find x index, +1 for MATLAB indexing
121        x_index = round((x_sample - solution_1.mesh.xmin) / (solution_1.mesh.xmax ...
122            - solution_1.mesh.xmin) * solution_1.mesh.element_count) + 1;
123
124        figure;
125        plot_handle = plot(solution_1.time, solution_1.values(x_index, :));
126        set(plot_handle, "LineWidth", 1.5);
127
128        hold on;
```

```
130         plot_handle = plot(solution_2.time, solution_2.values(x_index, :));
131         set(plot_handle, "LineWidth", 1.5);
132
133         xlabel("Time (t)");
134
135         ylabel("c(" + num2str(x_sample) + ", t)");
136         title(title_str);
137
138         grid on;
139
140         legend(legend_strings, "Location", "southeast");
141         set(gcf, 'Position', [0, 0, 500, 350]);
142
143         % Save figure
144         saveas(gcf, name, "png");
145         saveas(gcf, name, "fig");
146         openfig(name + ".fig");
147
148     end
149
150     function PlotConvergenceError(x_values, y_values, title_str, name, x_label,
151     y_label)
152         %%%%%%
153         %
154         % Function:      PlotConvergenceError()
155         %
156         % Arguments:    Plotting parameters
157         % Returns:      None
158         %
159         % Description: Plots convergence error on a log-log scale
160         %
161         %%%%%%
162         set(0, "DefaultAxesFontSize", 12);
163         set(0, "DefaultTextFontSize", 12);
164
165         figure;
166
167         plot_handle = loglog(x_values, y_values);
168         set(plot_handle, "LineWidth", 1.5);
169
170         xlabel(x_label);
171         ylabel(y_label);
172         title(title_str);
173         grid on;
174
175         set(gcf, 'Position', [0, 0, 500, 350]);
176
177         % Save figure
178         saveas(gcf, name, "png");
179         saveas(gcf, name, "fig");
180         openfig(name + ".fig");
181
182     end
183
184     function PlotL2Errors(l2_errors, title_str, name, legend_strings)
185         %%%%%%
186         %
187         % Function:      PlotL2Errors()
188         %
189         % Arguments:    Plotting parameters
190         % Returns:      None
191         %
192         % Description: Plots L2 errors over time for multiple simulations
193         %
194         %%%%%%
```

```
196     set(0, "DefaultAxesFontSize", 12);
197     set(0, "DefaultTextFontSize", 12);
198
199     figure;
200
201     for i = 1:length(l2_errors)
202         l2_error = l2_errors(i);
203         plot_handle = plot(l2_error.time, l2_error.l2_error);
204         set(plot_handle, "LineWidth", 1.5);
205         hold on;
206     end
207
208     xlabel("Time (t)");
209     ylabel("L2 Error");
210     title(title_str);
211
212     grid on;
213
214     legend(legend_strings, "Location", "northeast");
215     set(gcf, 'Position', [0, 0, 500, 350]);
216
217     % Save figure
218     saveas(gcf, name, "png");
219     saveas(gcf, name, "fig");
220
221     openfig(name + ".fig");
222
223 end
224
225 function PlotTwoConvergenceLines(x_values, y1_values, y2_values, title_str, name,
226 x_label, y_label, legend_strings)
227 %%%%%%
228 %
229 % Function:      PlotTwoConvergenceLines()
230 %
231 % Arguments:    Plotting parameters
232 % Returns:      None
233 %
234 % Description: Plots two convergence lines on a log-log scale
235 %
236 %%%%%%
237
238     set(0, "DefaultAxesFontSize", 12);
239     set(0, "DefaultTextFontSize", 12);
240
241     figure;
242
243     loglog(x_values, y1_values, '-o', 'LineWidth', 1.5, 'MarkerSize', 8);
244     hold on;
245     loglog(x_values, y2_values, '-s', 'LineWidth', 1.5, 'MarkerSize', 8);
246
247     xlabel(x_label);
248     ylabel(y_label);
249     title(title_str);
250     legend(legend_strings, 'Location', 'best');
251     grid on;
252
253     set(gcf, 'Position', [0, 0, 500, 350]);
254
255     saveas(gcf, name, "png");
256     saveas(gcf, name, "fig");
257     openfig(name + ".fig");
258
259 end
260
261 function PlotDoseEffectiveness(dose_values, kappa_values, title_str, name, x_label,
262 y_label)
263 %%%%%%
```

```
261      %
262      % Function:      PlotDoseEffectiveness()
263      %
264      % Arguments:    Plotting parameters
265      % Returns:      None
266      %
267      % Description: Plots dose vs effectiveness
268      %
269      %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
270
271      set(0, "DefaultAxesFontSize", 12);
272      set(0, "DefaultTextFontSize", 12);
273
274      figure;
275
276      plot_handle = plot(dose_values, kappa_values, "-o", 'LineWidth', 1.5);
277      xlabel(x_label);
278      ylabel(y_label);
279      title(title_str);
280      grid on;
281
282      set(gcf, 'Position', [0, 0, 500, 350]);
283
284      % Save figure
285      saveas(gcf, name, "png");
286      saveas(gcf, name, "fig");
287      openfig(name + ".fig");
288
289
290      function PlotSensitivityAnalysis(x_values, y_values, title_str, name, x_label,
291      y_label, legend_strings)
292      %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
293      %
294      % Function:      PlotSensitivityAnalysis()
295      %
296      % Arguments:    Plotting parameters
297      % Returns:      None
298      %
299      % Description: Plots sensitivity analysis results
300      %
301      %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
302
303      set(0, "DefaultAxesFontSize", 12);
304      set(0, "DefaultTextFontSize", 12);
305
306      figure;
307
308      % y_values is a matrix where each row is a different series
309      for i = 1:size(y_values, 1)
310          plot_handle = plot(x_values, y_values(i, :));
311          set(plot_handle, "LineWidth", 1.5);
312          hold on;
313      end
314
315      xlabel(x_label);
316      ylabel(y_label);
317      title(title_str);
318      legend(legend_strings, 'Location', 'best');
319      grid on;
320
321      set(gcf, 'Position', [0, 0, 500, 350]);
322
323      % Save figure
324      saveas(gcf, name, "png");
325      saveas(gcf, name, "fig");
326      openfig(name + ".fig");
327
328
```

```
327
328     function PlotKappaValues(x_values, y_values, title_str, name, x_label, y_label)
329     %%%%%%
330     %
331     % Function:      PlotKappaValues()
332     %
333     % Arguments:    Plotting parameters
334     % Returns:       None
335     %
336     % Description: Plots kappa values
337     %
338     %%%%%%
339
340     set(0, "DefaultAxesFontSize", 12);
341     set(0, "DefaultTextFontSize", 12);
342
343     figure;
344
345     plot_handle = plot(x_values, y_values, "-o");
346     set(plot_handle, "LineWidth", 1.5);
347     hold on;
348
349     xlabel(x_label);
350     ylabel(y_label);
351     title(title_str);
352     grid on;
353
354     set(gcf, 'Position', [0, 0, 500, 350]);
355
356     % Save figure
357     saveas(gcf, name, "png");
358     saveas(gcf, name, "fig");
359     openfig(name + ".fig");
360
361 end
362 end
363 end
```

13. Solution

13.1. Solution.m

```
1 %%%%%%
2 %
3 % ME40064 Coursework 2
4 %
5 % File      : Solution.m
6 % Author    : 11973
7 % Created   : 2025-11-26 (YYYY-MM-DD)
8 % License   : MIT
9 % Description : A class defining a solution to the transient
10 %                diffusion equation
11 %
12 %%%%%%
13
14 classdef Solution < handle
15     % inherit from handle to allow pass-by-reference behaviour
16
17     properties
18
19         mesh      Mesh      % handle to mesh object
20         time     double    % time series - 1 x Nsteps
21         values    double    % solution values - Nnodes x Nsteps
22
23     end
24
25     methods
26
27         function obj = Solution(mesh, time_vector)
28             %%%%%%
29             %
30             % Function:      Solution()
31             %
32             % Arguments:    parameters to initialise
33             % Returns:       Solution handle
34             %
35             % Description:  Initialises a Solution object
36             %
37             %%%%%%
38
39             % assign properties
40             obj.mesh = mesh;
41             obj.time = time_vector;
42             obj.values = zeros(mesh.node_count, length(time_vector));
43
44     end
45
46
47
48         function obj = SetValues(obj, values, step)
49             %%%%%%
50             %
51             % Function:      SetValues()
52             %
53             % Arguments:    object, values to set, time step index
54             % Returns:       Solution handle
55             %
56             % Description:  Helper function to set solution values at a
57             %                given time step
58             %
59             %%%%%%
60
61             % set solution values at given time step
62             obj.values(:, step) = values(:, );
63     end
```

```
64     end
65 end
66
67
```

13.2. L2Error.m

```
1 %%%%%%
2 %
3 % ME40064 Coursework 2
4 %
5 % File      : L2Error.m
6 % Author    : 11973
7 % Created   : 2025-11-26 (YYYY-MM-DD)
8 % License   : MIT
9 % Description : A class defining an L2 error calculator between
10 %                 a numerical and reference solution
11 %
12 %%%%%%
13
14 classdef L2Error < handle
15     % inherit from handle to allow pass-by-reference behaviour
16
17     properties
18
19         ref_solution    Solution % handle to reference solution object
20         num_solution    Solution % handle to solution object
21
22         time            double   % time series - 1 x Nsteps
23         l2_error        double   % L2 error at each time step - 1 x Nsteps
24
25     end
26
27     methods
28
29
30         function obj = L2Error(ref_solution, num_solution)
31             %%%%%%
32             %
33             % Function:    L2Error()
34             %
35             % Arguments:   reference and numerical solutions
36             % Returns:     L2Error handle
37             %
38             % Description: Initialises an L2Error object and computes the
39             %                 L2 error between the two solutions
40             %
41             %%%%%%
42
43             % assign properties
44             obj.ref_solution = ref_solution;
45             obj.num_solution = num_solution;
46             obj.time = ref_solution.time;
47
48             % check compatibility
49             if ref_solution.mesh.node_count ~= num_solution.mesh.node_count
50                 error('Reference and error solutions must have the same number of nodes');
51             end
52
53             if length(ref_solution.time) ~= length(num_solution.time)
54                 error('Reference and error solutions must have the same number of time
55             steps');
56             end
57
58             step_count = length(ref_solution.time);
```

```

58     obj.l2_error = zeros(1, step_count);
59
60     % compute L2 error at each time step
61     for step = 1:step_count
62
63         c_ref = ref_solution.values(:, step);
64         c_num = num_solution.values(:, step);
65         x = ref_solution.mesh.node_coords;
66
67         % compute L2 norm using trapezoidal rule
68         integrand = (c_ref - c_num).^2;
69         obj.l2_error(step) = sqrt(trapz(x, integrand));
70     end
71
72     end
73 end
74
75 end
76 end
77
78

```

13.3. DoseEvaluator.m

```

1 %%%%%%
2 %
3 % ME40064 Coursework 2
4 %
5 % File      : DoseEvaluator.m
6 % Author    : 11973
7 % Created   : 2025-11-26 (YYYY-MM-DD)
8 % License   : MIT
9 % Description : A static class defining a evaluation methods
10 %                 for dose effectiveness
11 %
12 %%%%%%
13
14 classdef DoseEvaluator
15
16     methods (Static)
17
18         function K = EvaluateSolution(solution, target_x, c_threshold, dt)
19             %%%%%%
20             %
21             % Function:      EvaluateSolution()
22             %
23             % Arguments:    solution, target x location, concentration
24             % Returns:       kappa value
25             %
26             % Description: Evaluates the solution at a target location
27             %
28             %%%%%%
29
30             % first, find the closest node to the target
31             node_index = 0;
32
33             for i = 1:solution.mesh.node_count
34                 x = solution.mesh.node_coords(i);
35                 if x >= target_x
36                     node_index = i;
37                     break;
38                 end
39             end
40
41             fprintf("node index %d\n", node_index);

```

```
42         c = solution.values(node_index, :);
43
44         effective_t_index = 0;
45
46         for i = 1:length(c)
47             if c(i) >= c_threshold
48                 effective_t_index = i;
49                 break
50             end
51         end
52
53         if effective_t_index == 0
54             K = 0; % never exceeds threshold
55             return;
56         end
57
58         t_effective = solution.time(effective_t_index);
59
60         % integrate concentration over time until effective_t_index
61         time_range = effective_t_index:length(solution.time);
62         K = trapz(solution.time(time_range), c(time_range));
63     end
64
65     function [c_dose_min, dose_vals, kappa_vals] = FindMinimumDose(mesh, tmax, dt,
theta, integration_method, target_x, c_threshold, K_target)
66     %%%%%%
67     %
68     % Function:      FindMinimumDose()
69     %
70     % Arguments:    mesh, max time, time step, theta value,
71     % Returns:       minimum effective dose, results from search
72     %
73     % Description:   Performs a binary search to find the minimum
74     %                  effective dose to achieve a target kappa value
75     %
76     %%%%%%
77
78     % Binary search for minimum effective dose - high and low starting bounds
79     c_dose_low = 0;
80     c_dose_high = 100;
81
82     tolerance = 0.1;
83
84     dose_vals = [];
85     kappa_vals = [];
86
87     while (c_dose_high - c_dose_low) > tolerance
88         c_dose_test = (c_dose_low + c_dose_high) / 2;
89
90         fprintf("Testing dose = %.2f...\n", c_dose_test);
91
92         % Run simulation with this dose
93         lhs_boundary = BoundaryCondition();
94         lhs_boundary.Type = BoundaryType.Dirichlet;
95         lhs_boundary.Value = c_dose_test;
96
97         rhs_boundary = BoundaryCondition();
98         rhs_boundary.Type = BoundaryType.Dirichlet;
99         rhs_boundary.Value = 0.0;
100
101        solution = NumericSolver.SolveNumeric(
102            mesh, tmax, dt, theta, lhs_boundary, rhs_boundary, ...
103            @(~, ~) 0.0, integration_method);
104
105        % Evaluate K at target location
106        K = DoseEvaluator.EvaluateSolution(solution, target_x, ...
107            c_threshold, dt);
```

```
108
109     if K > K_target
110         c_dose_high = c_dose_test;
111         fprintf("K = %.2f > %.0f: dose too high\n", K, K_target);
112     else
113         c_dose_low = c_dose_test;
114         fprintf("K = %.2f < %.0f: dose too low\n", K, K_target);
115     end
116
117     dose_vals = [dose_vals, c_dose_test];
118     kappa_vals = [kappa_vals, K];
119 end
120
121     c_dose_min = c_dose_high; % Use upper bound to ensure K > target
122
123 end
124 end
125 end
```

14. Solver

14.1. NumericSolver.m

```
1 %%%%%%
2 %
3 % ME40064 Coursework 2
4 %
5 % File      : NumericSolver.m
6 % Author    : 11973
7 % Created   : 2025-11-24 (YYYY-MM-DD)
8 % License   : MIT
9 % Description : Class definition for generic solver for the
10 %                transient diffusion-reaction equation
11 %
12 %%%%%%
13
14
15 classdef NumericSolver
16
17     methods (Static)
18
19         function solution = SolveNumeric(mesh, tmax, dt, theta, left_boundary,
20             right_boundary, source_fn, integration_method)
21             %
22             % Function:      SolveNumeric()
23             %
24             % Arguments:    parameters for solver
25             % Returns:       solution object
26             %
27             % Description:  Runs a numeric solver for the transient
28             %                diffusion-reaction equation using the
29             %                finite element method and theta-method for
30             %                time integration.
31             %
32 %%%%%%
33
34         % time vector
35         time_vector = 0:dt:tmax;
36         solution = Solution(mesh, time_vector);
37
38         % initial condition: c(x,0) = 0
39         c0 = zeros(mesh.node_count, 1);
40         solution.SetValues(c0, 1); % column 1 = t=0
41
42         % create global matrices
43         [K, M] = NumericSolver.CreateGlobalMatrices(mesh, theta, integration_method);
44
45         % loop over time steps
46         for step = 1:length(time_vector) - 1
47
48             % solve for next time step
49             c_next = NumericSolver.SolveStep(mesh, solution, step, dt, theta, ...
50                 K, M, left_boundary, right_boundary, source_fn, integration_method);
51
52             solution.SetValues(c_next, step + 1);
53
54         end
55
56     end
57
58     function c = SolveStep(mesh, solution, step, dt, theta, K, M, left_boundary,
59         right_boundary, source_fn, integration_method)
60         %
61         % Function:      SolveStep()
```

```

62      %
63      % Arguments:    parameters for solver
64      % Returns:     solution at next time step
65      %
66      % Description: Solves for the solution at the next time step
67      %
68      %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
69
70      c_current = solution.values(:, step);
71
72      t = (step - 1) * dt; % current time, converted to 0-based index
73
74      % assemble system matrix and rhs vector
75      system_matrix = M + theta * dt * K;
76      rhs_vector = (M - (1 - theta) * dt * K) * c_current;
77
78      % add source term
79      f_current = NumericSolver.CreateSourceVector(mesh, t, ...
80          source_fn, integration_method);
81
82      f_next = NumericSolver.CreateSourceVector(mesh, t + dt, ...
83          source_fn, integration_method);
84
85      rhs_vector = rhs_vector + dt * (theta * f_next + (1 - theta) * f_current);
86
87      % apply boundary conditions
88      [system_matrix, rhs_vector] = NumericSolver.ApplyBoundaryConditions(...
89          system_matrix, rhs_vector, t + dt, left_boundary, right_boundary);
90
91      % solve system
92      c = system_matrix \ rhs_vector;
93
94  end
95
96  function [K, M] = CreateGlobalMatrices(mesh, theta, integration_method)
97  %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
98  %
99  % Function:    CreateGlobalMatrices()
100 %
101 % Arguments:    parameters for solver
102 % Returns:     global stiffness and mass matrices
103 %
104 % Description: Creates the global stiffness and mass matrices
105 %
106 %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
107
108  num_elements = mesh.element_count;
109  num_nodes = mesh.node_count;
110
111  % initialise global matrix (use sparse for efficiency with large systems)
112  K = sparse(num_nodes, num_nodes);
113  M = sparse(num_nodes, num_nodes);
114
115  for element_id = 1:num_elements
116
117      element = mesh.elements(element_id);
118      nodes = element.node_ids;
119      local_size = length(nodes);
120
121      diff_matrix = ElementMatrices.DiffusionElemMatrix(element, ...
122          integration_method);
123      react_matrix = ElementMatrices.ReactionElemMatrix(element, ...
124          integration_method);
125
126      k_matrix = diff_matrix - react_matrix;
127
128      elem_size = element.node_coords(end) - element.node_coords(1);

```

```

129         m_matrix = ElementMatrices.MassElemMatrix(element, integration_method);
130
131         % assemble into global matrices
132         for i = 1:local_size
133             for j = 1:local_size
134                 gi = nodes(i); gj = nodes(j);
135                 K(gi, gj) = K(gi, gj) + k_matrix(i, j);
136                 M(gi, gj) = M(gi, gj) + m_matrix(i, j);
137             end
138         end
139     end
140
141
142     function F = CreateSourceVector(mesh, t, source_fn, integration_method)
143         %%%%%%
144         %
145         % Function:      CreateSourceVector()
146         %
147         % Arguments:    parameters for solver
148         % Returns:       global source vector
149         %
150         % Description: Creates the global source vector
151         %
152         %%%%%%
153
154         F = zeros(mesh.node_count, 1);
155
156         % return if no source function defined
157         if (isempty(source_fn))
158             return;
159         end
160
161         for element_id = 1:mesh.element_count
162
163             element = mesh.elements(element_id);
164
165             elem_size = element.node_coords(end) - element.node_coords(1);
166             midpoint = (element.node_coords(1) + element.node_coords(end)) / 2;
167
168             f_val = source_fn(midpoint, t);
169
170             % Local Force Vector for linear element (Int N^T * s dx)
171             f_local = f_val * ElementMatrices.ForceMatrix(element, integration_method);
172
173             nodes = element.node_ids;
174             F(nodes) = F(nodes) + f_local;
175         end
176
177     end
178
179
180     function [lhs, rhs] = ApplyBoundaryConditions(lhs, rhs, t, left_boundary,
181 right_boundary)
182         %%%%%%
183         %
184         % Function:      ApplyBoundaryConditions()
185         %
186         % Arguments:    parameters for solver
187         % Returns:       modified system matrix and rhs vector
188         %
189         % Description: Applies boundary conditions to the system
190         %
191         %%%%%%
192
193         % Store diagonal values before modification
194         diag_left = lhs(1,1);

```

```

195     diag_right = lhs(end,end);
196
197     % apply left boundary condition
198     switch left_boundary.Type
199
200         case BoundaryType.Dirichlet
201             lhs(1, :) = 0;                      % clear row
202             lhs(1, 1) = diag_left;            % keep diagonal
203             rhs(1) = left_boundary.Value * diag_left; % scale by diagonal
204
205         case BoundaryType.Neumann
206             rhs(1) = rhs(1) + left_boundary.ValueFunction(t); % apply flux
207
208     end
209
210     % apply right boundary condition
211     switch right_boundary.Type
212
213         case BoundaryType.Dirichlet
214             lhs(end, :) = 0;                  % clear row
215             lhs(end, end) = diag_right;    % set diagonal to 1
216             rhs(end) = right_boundary.Value * diag_right; % set value
217
218         case BoundaryType.Neumann
219             rhs(end) = rhs(end) + right_boundary.ValueFunction(t); % apply flux
220
221     end
222
223 end
224 end
225

```

14.2. BoundaryCondition.m

```

1 %%%%%%
2 %
3 % ME40064 Coursework 2
4 %
5 % File      : BoundaryCondition.m
6 % Author    : 11973
7 % Created   : 2025-11-26 (YYYY-MM-DD)
8 % License   : MIT
9 % Description : A class defining a boundary condition for the
10 %                transient diffusion reaction equation
11 %
12 %%%%%%
13
14 classdef BoundaryCondition
15
16     properties
17
18         Type      BoundaryType % Boundary condition type
19         Value     double % Boundary condition value for Dirichlet
20         ValueFunction function_handle % Boundary condition function for Neumann
21
22     end
23
24 end

```

14.3. BoundaryType.m

```

1 %%%%%%
2 %
3 % ME40064 Coursework 2

```

```

4 %
5 % File      : BoundaryType.m
6 % Author    : 11973
7 % Created   : 2025-11-26 (YYYY-MM-DD)
8 % License   : MIT
9 % Description : A class defining a boundary type enumeration for
10 %                 the transient diffusion reaction equation.
11 %
12 %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
13
14 classdef BoundaryType
15
16     enumeration
17
18     Dirichlet, Neumann
19
20 end
21
22 end

```

14.4. ElementMatrices.m

```

1 %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
2 %
3 % ME40064 Coursework 2
4 %
5 % File      : ElementMatrices.m
6 % Author    : 11973
7 % Created   : 2025-11-26 (YYYY-MM-DD)
8 % License   : MIT
9 % Description : A static class defining element matrix
10 %                 helper functions for the transient diffusion
11 %
12 %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
13
14 classdef ElementMatrices
15
16     methods (Static)
17
18         function matrix = DiffusionElemMatrix(element, method)
19         %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
20         %
21         % Function:      DiffusionElemMatrix()
22         %
23         % Arguments:    element and integration method
24         % Returns:       diffusion element matrix
25         %
26         % Description:  Computes the diffusion element matrix
27         %
28         %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
29
30         elem_size = element.node_coords(end) - element.node_coords(1);
31
32         % check integration method
33         if method.type == IntegrationType.Trapezoidal
34
35             % create base matrix
36             matrix = eye(element.order + 1);
37
38             for i = 1:(element.order + 1)
39                 for j = 1:(element.order + 1)
40                     if i ~= j
41                         matrix(i, j) = -1;
42                     end
43                 end

```

```
44         end
45
46         % apply matrix scaling
47         matrix = matrix * (element.D / elem_size);
48
49     else
50         % handle Gaussian quadrature
51
52         matrix = zeros(element.order + 1);
53         [xi, wi] = ElementMatrices.GaussQuadraturePoints(method.gauss_points);
54
55         for i = 1:length(xi)
56             dN_dx = ElementMatrices.ShapeFunctionDerivatives(element.order,
57 xi(i));
58
59             J = element.jacobian;
60             dN_dx = dN_dx / J;
61
62             % compute contribution to stiffness matrix
63             matrix = matrix + (element.D * (dN_dx' * dN_dx)) * (wi(i) * J);
64         end
65     end
66
67 end
68
69 function matrix = ReactionElemMatrix(element, method)
70 %%%%%%
71 %
72 % Function:      ReactionElemMatrix()
73 %
74 % Arguments:    element and integration method
75 % Returns:       reaction element matrix
76 %
77 % Description:   Computes the reaction element matrix
78 %
79 %%%%%%
80
81 elem_size = element.node_coords(end) - element.node_coords(1);
82
83 % check integration method
84 if method.type == IntegrationType.Trapezoidal
85
86     % create base matrix
87     matrix = eye(element.order + 1) * 2;
88
89     for i = 1:(element.order + 1)
90         for j = 1:(element.order + 1)
91             if i ~= j
92                 matrix(i, j) = 1;
93             end
94         end
95     end
96
97     % apply matrix scaling
98     matrix = matrix * (element.lambda * elem_size / 6);
99
100 else
101     % handle Gaussian quadrature
102
103     matrix = zeros(element.order + 1);
104     [xi, wi] = ElementMatrices.GaussQuadraturePoints(method.gauss_points);
105
106     for i = 1:length(xi)
107         N = ElementMatrices.ShapeFunctions(element.order, xi(i));
108
109         J = element.jacobian;
```

```

110
111             % compute contribution to stiffness matrix
112             matrix = matrix + (element.lambda * (N' * N)) * (wi(i) * J);
113         end
114     end
115 end
116
117 function matrix = MassElemMatrix(element, method)
118 %%%%%%
119 %
120 % Function:      MassElemMatrix()
121 %
122 % Arguments:    element and integration method
123 % Returns:       mass element matrix
124 %
125 % Description:   Computes the mass element matrix
126 %
127 %%%%%%
128
129 elem_size = element.node_coords(end) - element.node_coords(1);
130
131 % check integration method
132 if method.type == IntegrationType.Trapezoidal
133
134     % create base matrix
135     matrix = eye(element.order + 1) * 2;
136
137     for i = 1:(element.order + 1)
138         for j = 1:(element.order + 1)
139             if i ~= j
140                 matrix(i, j) = 1;
141             end
142         end
143     end
144
145     % apply matrix scaling
146     matrix = matrix * (elem_size / 6);
147
148 else
149     % handle Gaussian quadrature
150
151     matrix = zeros(element.order + 1);
152     [xi, wi] = ElementMatrices.GaussQuadraturePoints(method.gauss_points);
153
154     for i = 1:length(xi)
155         N = ElementMatrices.ShapeFunctions(element.order, xi(i));
156
157         J = element.jacobian;
158
159         % compute contribution to stiffness matrix
160         matrix = matrix + (N' * N) * (wi(i) * J);
161     end
162
163 end
164
165 end
166
167
168 function matrix = ForceMatrix(element, method)
169 %%%%%%
170 %
171 % Function:      ForceMatrix()
172 %
173 % Arguments:    element and integration method
174 % Returns:       force element matrix
175 %
176 % Description:   Computes the force element matrix

```

```

177      %
178      %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
179
180      elem_size = element.node_coords(end) - element.node_coords(1);
181
182      % check integration method
183      if method.type == IntegrationType.Trapezoidal
184
185          % create base matrix
186          matrix = ones(element.order + 1, 1);
187
188          % apply matrix scaling
189          matrix = matrix * (elem_size / 2);
190
191      else
192          % handle Gaussian quadrature
193
194          matrix = zeros(element.order + 1, 1);
195          [xi, wi] = ElementMatrices.GaussQuadraturePoints(method.gauss_points);
196
197          for i = 1:length(xi)
198              N = ElementMatrices.ShapeFunctions(element.order, xi(i));
199
200              J = element.jacobian;
201
202              % compute contribution to stiffness matrix
203              matrix = matrix + N' * (wi(i) * J);
204          end
205
206      end
207
208  end
209
210
211 methods (Static, Access = private)
212
213     function [xi, wi] = GaussQuadraturePoints(n)
214     %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
215     %
216     % Function:    GaussQuadraturePoints()
217     %
218     % Arguments:   number of points
219     % Returns:     quadrature points and weights
220     %
221     % Description: Looks up Gauss quadrature points and weights
222     %
223     %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
224
225     % look up points and weights, limited to n = 1, 2, 3
226     switch n
227         case 1
228             xi = 0;
229             wi = 2;
230         case 2
231             xi = [-1/sqrt(3), 1/sqrt(3)];
232             wi = [1, 1];
233         case 3
234             xi = [-sqrt(3/5), 0, sqrt(3/5)];
235             wi = [5/9, 8/9, 5/9];
236         otherwise
237             error('Gauss quadrature for n > 3 not implemented.');
238         end
239
240     end
241
242     function N = ShapeFunctions(order, xi)
243     %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%

```

```

244      %
245      % Function:      ShapeFunctions()
246      %
247      % Arguments:    order and local coordinate
248      % Returns:      shape function values
249      %
250      % Description:  Computes shape function values at given local
251      %                  coordinate
252      %
253      %%%%%%
254
255      % switch based on element order, limited to linear and quadratic
256      switch order
257          case 1 % linear
258              N = [(1 - xi) / 2, (1 + xi) / 2];
259          case 2 % quadratic
260              N = [xi * (xi - 1) / 2, (1 - xi^2), xi * (xi + 1) / 2];
261          otherwise
262              error('Shape functions for order > 2 not implemented.');
263      end
264
265  end
266
267  function dN_dx = ShapeFunctionDerivatives(order, xi)
268  %%%%%%
269  %
270  % Function:      ShapeFunctionDerivatives()
271  %
272  % Arguments:    order and local coordinate
273  % Returns:      shape function derivative values
274  %
275  % Description:  Computes shape function derivative values at
276  %                  given local coordinate
277  %
278  %%%%%%
279
280      % switch based on element order, limited to linear and quadratic
281      switch order
282          case 1 % linear
283              dN_dx = [-0.5, 0.5];
284          case 2 % quadratic
285              dN_dx = [xi - 0.5, -2 * xi, xi + 0.5];
286          otherwise
287              error('Shape function derivatives for order > 2 not implemented.');
288      end
289
290  end
291 end
292 end

```

14.5. IntegrationMethod.m

```

1 %%%%%%
2 %
3 % ME40064 Coursework 2
4 %
5 % File        : IntegrationMethod.m
6 % Author      : 11973
7 % Created     : 2025-11-26 (YYYY-MM-DD)
8 % License     : MIT
9 % Description : A class defining an integration method for element
10 %                 matrix calculations
11 %
12 %%%%%%
13

```

```
14 classdef IntegrationMethod
15
16     properties
17
18         type          IntegrationType
19         gauss_points uint8
20
21     end
22
23 end
```

14.6. IntegrationType.m

```
1 %%%%%%
2 %
3 % ME40064 Coursework 2
4 %
5 % File      : IntegrationType.m
6 % Author    : 11973
7 % Created   : 2025-11-26 (YYYY-MM-DD)
8 % License   : MIT
9 % Description : A class defining an integration type for element
10 %                  matrix calculations
11 %
12 %%%%%%
13
14 classdef IntegrationType
15
16     enumeration
17
18         Trapezoidal, Gaussian
19     end
20
21 end
```

15. Tests

15.1. UnitTests.m

```
1 %%%%%%
2 %
3 % ME40064 Coursework 2
4 %
5 % File      : UnitTests.m
6 % Author    : 11973
7 % Created   : 2025-11-27 (YYYY-MM-DD)
8 % License   : MIT
9 % Description : Test suite for FEM transient diffusion solver
10 %
11 %%%%%%
12
13 function tests = UnitTests
14     % run unit tests for transient diffusion solver
15     tests = functiontests(localfunctions);
16 end
17
18 function TestSolveNumericReactionOnly(testCase)
19 %%%%%%
20 %
21 % Function:      TestSolveNumericReactionOnly()
22 %
23 % Arguments:    test case
24 % Returns:      none
25 %
26 % Description:  Tests NumericSolver for pure reaction case
27 %
28 %%%%%%
29
30     % mesh parameters
31     xmin = 0.0;
32     xmax = 1.0;
33     element_count = 6;
34     order = 1;
35     lambda = -1.0;
36     D = 0.0;
37
38     % time parameters
39     tmax = 0.5;
40     dt = 0.02;
41     theta = 0.5; % Crank-Nicholson
42
43     % generate mesh
44     mesh = Mesh(xmin, xmax, element_count, order, D, lambda);
45     mesh.Generate();
46
47     % solver parameters
48     lhs_boundary = BoundaryCondition();
49     lhs_boundary.Type = BoundaryType.Neumann;
50     lhs_boundary.ValueFunction = @(t) 0.0;
51
52     rhs_boundary = BoundaryCondition();
53     rhs_boundary.Type = BoundaryType.Neumann;
54     rhs_boundary.ValueFunction = @(t) 0.0;
55
56     integration_method = IntegrationMethod();
57     integration_method.type = IntegrationType.Trapezoidal;
58     integration_method.gauss_points = 0; % not used for trapezoidal
59
60     numeric_solution = NumericSolver.SolveNumeric(
61         mesh, tmax, dt, theta, lhs_boundary, rhs_boundary, @(~, ~) 10, integration_method);
62
63     % analytical solution
```

```
64 t_analytic = 0:dt:tmax;
65 c_exact = 10 * (1 - exp(lambda * t_analytic));
66
67 % chose random node (3 in this case) to compare
68 c_numeric = numeric_solution.values(3,:);
69 error = norm(c_numeric - c_exact) / norm(c_exact);
70
71 tolerance = 1e-3;
72 verifyLessThan(testCase, error, tolerance);
73 end
74
75 function TestSteadyStateConvergence(testCase)
76 %%%%%%
77 %
78 % Function:      TestSteadyStateConvergence()
79 %
80 % Arguments:    test case
81 % Returns:      none
82 %
83 % Description:  Tests that NumericSolver converges to steady
84 %                 state for pure diffusion with Dirichlet BCs
85 %
86 %%%%%%
87
88 xmin = 0; xmax = 1;
89 mesh = Mesh(xmin, xmax, 20, 1, 1.0, 0.0);
90 mesh.Generate();
91
92 % Run to steady state
93 tmax = 10.0; dt = 0.1; theta = 0.5;
94
95 lhs_bc = BoundaryCondition();
96 lhs_bc.Type = BoundaryType.Dirichlet;
97 lhs_bc.Value = 0.0;
98
99 rhs_bc = BoundaryCondition();
100 rhs_bc.Type = BoundaryType.Dirichlet;
101 rhs_bc.Value = 1.0;
102
103 integration_method = IntegrationMethod();
104 integration_method.type = IntegrationType.Trapezoidal;
105
106 solution = NumericSolver.SolveNumeric(mesh, tmax, dt, theta, ...
107                                         lhs_bc, rhs_bc, @(x,t) 0, integration_method);
108
109 % Check final solution is linear
110 c_final = solution.values(:, end);
111 c_expected = mesh.node_coords';
112
113 error = norm(c_final - c_expected) / norm(c_expected);
114 verifyLessThan(testCase, error, 1e-3);
115 end
116
117 function TestGaussianQuadratureAccuracy(testCase)
118 %%%%%%
119 %
120 % Function:      TestGaussianQuadratureAccuracy()
121 %
122 % Arguments:    test case
123 % Returns:      none
124 %
125 % Description:  Tests that Gaussian quadrature gives better
126 %                 accuracy than trapezoidal for the same problem
127 %
128 %%%%%%
129
130 xmin = 0; xmax = 1;
```

```

131 element_count = 5;
132 order = 2; % quadratic elements
133
134 mesh = Mesh(xmin, xmax, element_count, order, 1.0, 0.0);
135 mesh.Generate();
136
137 tmax = 0.1; dt = 0.01; theta = 0.5;
138
139 lhs_bc = BoundaryCondition();
140 lhs_bc.Type = BoundaryType.Dirichlet;
141 lhs_bc.Value = 0.0;
142
143 rhs_bc = BoundaryCondition();
144 rhs_bc.Type = BoundaryType.Dirichlet;
145 rhs_bc.Value = 1.0;
146
147 % Solve with trapezoidal
148 trap_method = IntegrationMethod();
149 trap_method.type = IntegrationType.Trapezoidal;
150
151 trap_solution = NumericSolver.SolveNumeric(mesh, tmax, dt, theta, ...
152     lhs_bc, rhs_bc, @(x,t) 0, trap_method);
153
154 % Solve with Gaussian
155 gauss_method = IntegrationMethod();
156 gauss_method.type = IntegrationType.Gaussian;
157 gauss_method.gauss_points = 3;
158
159 gauss_solution = NumericSolver.SolveNumeric(mesh, tmax, dt, theta, ...
160     lhs_bc, rhs_bc, @(x,t) 0, gauss_method);
161
162 % Get analytical solution
163 analytical_solution = AnalyticalSolver.SolveAnalytical(mesh, tmax, dt);
164
165 % Compute errors
166 trap_error = L2Error(analytical_solution, trap_solution);
167 gauss_error = L2Error(analytical_solution, gauss_solution);
168
169 % Gaussian should be more accurate (lower final error)
170 verifyLessThan(testCase, gauss_error.l2_error(end), ...
171     trap_error.l2_error(end));
172 end
173
174 function TestQuadraticVsLinearElements(testCase)
175 %%%%%%
176 %
177 % Function:      TestQuadraticVsLinearElements()
178 %
179 % Arguments:    test case
180 % Returns:      none
181 %
182 % Description:  Tests that quadratic elements give better
183 %                 accuracy than linear elements for the same
184 %                 problem
185 %
186 %%%%%%
187
188 xmin = 0; xmax = 1;
189 element_count = 5;
190
191 tmax = 0.1; dt = 0.01; theta = 0.5;
192
193 lhs_bc = BoundaryCondition();
194 lhs_bc.Type = BoundaryType.Dirichlet;
195 lhs_bc.Value = 0.0;
196
197 rhs_bc = BoundaryCondition();

```

```
198 rhs_bc.Type = BoundaryType.Dirichlet;
199 rhs_bc.Value = 1.0;
200
201 integration_method = IntegrationMethod();
202 integration_method.type = IntegrationType.Gaussian;
203 integration_method.gauss_points = 3;
204
205 % Linear elements
206 mesh_linear = Mesh(xmin, xmax, element_count, 1, 1.0, 0.0);
207 mesh_linear.Generate();
208
209 solution_linear = NumericSolver.SolveNumeric(mesh_linear, tmax, dt, ...
210     theta, lhs_bc, rhs_bc, @(x,t) 0, integration_method);
211
212 analytical_linear = AnalyticalSolver.SolveAnalytical(mesh_linear, tmax, dt);
213 error_linear = L2Error(analytical_linear, solution_linear);
214
215 % Quadratic elements
216 mesh_quadratic = Mesh(xmin, xmax, element_count, 2, 1.0, 0.0);
217 mesh_quadratic.Generate();
218
219 solution_quadratic = NumericSolver.SolveNumeric(mesh_quadratic, tmax, dt, ...
220     theta, lhs_bc, rhs_bc, @(x,t) 0, integration_method);
221
222 analytical_quadratic = AnalyticalSolver.SolveAnalytical(mesh_quadratic, tmax, dt);
223 error_quadratic = L2Error(analytical_quadratic, solution_quadratic);
224
225 % Quadratic should have lower error
226 verifyLessThan(testCase, error_quadratic.l2_error(end), ...
227     error_linear.l2_error(end));
228 end
```