Computation II: embedded system design (5EIBO)

Dashbo... / My cour... / 5El... / Final Exam 2024-04... / Part 2c - 2024-04-12 Finite State Machine (Debug FSM Moore UART Frame Detect...

Description

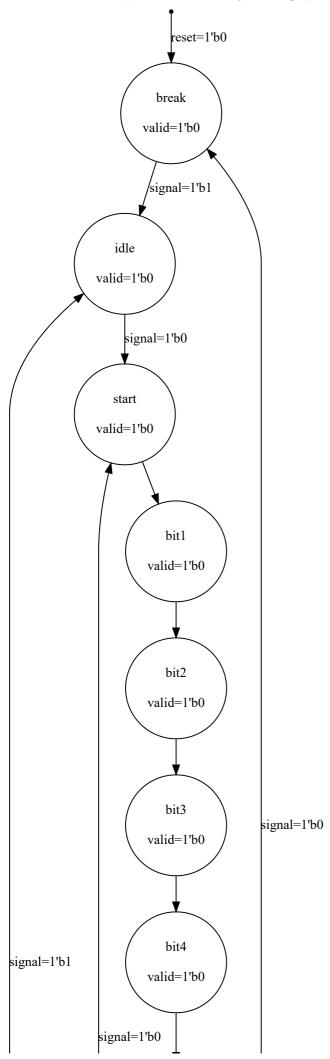
Submission view

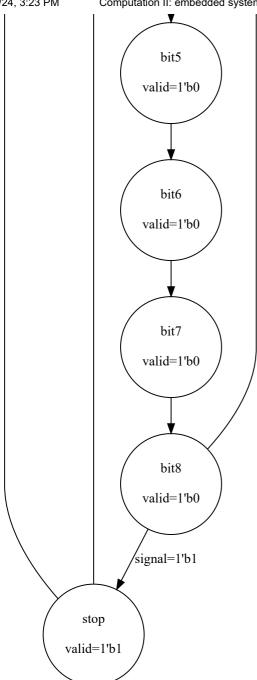
♣ Available from: Friday, 12 April 2024, 1:30 PM
 Due date: Friday, 12 April 2024, 4:30 PM
 Requested files: uart.v (♣ Download)
 Type of work: ♣ Individual work

Assignment

Universal Asynchronous Receiver/Transmitter (UART) is a simple serial protocol that is commonly used to communicate between two devices that do not share the same synchronous clock. Data is communicated as frames from one device to the other device along a single wire. The line is idle when it is high. The start of a frame is signalled by pulling the line low for a single data bit duration. This is followed by 8 data bits (this number can vary between implementations, but we will consider 8 here) that can be high or low, representing a byte of data in binary. This must be immediately followed by the stop bit where the line is held high for at least a single data bit duration. A break signal can be communicated by pulling the line low, such that the stop bit is not signalled.

In this assignment you will debug a Verilog implementation of a Finite State Machine (FSM) to detect correctly formed UART frames of data with the following specifications. Including the clock (clk) and reset signals, the implemented FSM will have 3 input signals and 1 output signal.





The clk input signal is 1-bit wide, the reset input signal is 1-bit wide and the signal input signal is 1-bit wide. The state elements of the FSM are to capture their inputs on the positive clock (clk) edge and reset their state when the synchronous reset signal is high. A reset can be asserted (synchronously) at any time causing all state elements to reset and hence a transition to the initial state.

The valid output signal is 1-bit wide. Initial values of the output signals upon reset are shown in the FSM diagram.

Your solution will be tested using bounded model checking against a golden reference implementation. The model checking software will stop at the earliest moment that your implementation diverges from the behaviour of the golden reference implementation. If a divergence takes place, a waveform will be created showing a trace of the module signals resulting in the divergent state. This waveform also shows the behaviour of the golden reference (REF) so that you can see what your implementation (DUT) should have done differently.

Please note that the golden reference implementation supersedes all other implementation descriptions. If the output from your solution implementation does not diverge from the golden reference implementation then your solution is marked as correct. Otherwise, your solution is incorrect and you should use the waveform that is produced to assist you to correct your implementation.

Requested files

uart.v

```
module uart (
           input clk.
            input reset
            input signal
  1
  5
           output valid
      );
  6
  8
      // define unique constants to identify each state
      localparam BREAK = 4'd0:
      localparam IDLE = 4'd1;
 10
      localparam START = 4'd2
 11
      localparam BIT1 = 4'd3;
localparam B1T2 = 4'd4;
 12
 13
      localparam BIT3 = 4'd5;
 15
      localparam BIT4 = 4'd6;
      localparam BIT5 = 4'd7;
 16
      localparam BIT6 = 4'd8;
 17
      localparam BIT7 = 4'd9;
      localparam BIT8 = 4'd10;
 19
 20
 21
      // declare verilog variables of type reg for use in always blocks
      // <name>_r is used to infer a register in the clocked always block
// <name>_nxt is used assign the next state of the register in the combinational always block
 22
 23
      reg [3 : 0] state_r, state_nxt;
 25
      reg valid_r, valid_nxt;
 26
      // clock synchronous always block will only be evaluated on the positive edge of the clock
 27
      // only use non-blocking assignments (<=) in this block
 28
      always @(posedge reset) begin

// check for the reset signal on the clk edge, infering a synchronous reset

// if the module is not being reset, assign all of the derived combinational <name>_nxt values to <name>_r
 29
 30
 31
           // if the module is being reset, assign initial constant values to the <name>_r variables
// this will infer a register for <name>_r if it is assigned defined values at all times
 33
34
            // otherwise an unintentional latch will be inferred
 35
           if (clk == 1'b0) begin
                // module is not being reset
// assign all of the derived combinational <name>_nxt values to the respective <name>_r
 36
37
                state_r <= state_nxt;
valid_r <= valid_nxt;</pre>
 38
 39
 40
           end else begin
 41
                // module is being reset
                 // assign constant values to each <name>_r variable
                state_r <= IDLE;
valid r <= 1'b0;</pre>
 43
 44
 45
           end
 46
      end
 47
      // combinational always block will evaluate whenever any signal in its sensitivity list changes
// here we use the wildcard * sensitivity list, which means that the list will be inferred from the assignments in the block
 48
 50
      // only use blocking assignments (=) in this block
      always @(*) begin
 51
            // make sure that <name>_nxt signals are always defined to avoid latches
 52
 53
            // to ensure register elements minimally retain their last value, assign each <name>_nxt its respective <name>_r value
 54
           state_nxt = state_r;
valid_nxt = valid_r;
 55
 57
           // case statement is used to perform different logical derivations depending on current state
 58
           // state r stores the current state of this FSM
            // the unique state identifiers that were defined near the top of this file are used to identify the current state
 59
 60
           case (state_nxt)
                // state_r will remain constant between positive clock edges
// only one unique state can match at any time
 61
 62
                BREAK: // evaluate logic for state BREAK
 64
                begin
 65
                     valid nxt = 1'b0;
 66
                      if (signal == 1'b1)
 67
 68
                          state_nxt = IDLE;
 69
                     end
 70
                end
 71
72
                IDLE: // evaluate logic for state IDLE
 73
                begin
 74
75
                     valid nxt = 1'b0:
                     if (signal == 1'b0)
 76
                     begin
 77
                          state_nxt = START;
 78
79
                     end
                end
 80
 81
                START: // evaluate logic for state START
 82
                begin
                     valid nxt = 1'b0:
                     state_nxt = BIT1;
 84
 85
 86
 87
                BIT1: // evaluate logic for state BIT1
 88
                     valid nxt = 1'b0:
 89
 90
                     state_nxt = BIT3;
 91
                end
 92
 93
                BIT2: // evaluate logic for state BIT2
 94
                begin
                     valid_nxt = 1'b0;
 95
                     state_nxt = BIT4;
 96
 97
 98
99
                BIT4: // evaluate logic for state BIT4
100
                begin
101
                     valid_nxt = 1'b0;
102
                     state_nxt = BIT8;
103
```

```
104
105
               BIT5: // evaluate logic for state BIT5
106
               begin
                   valid_nxt = 1'b0;
state_nxt = BIT5;
107
108
109
               end
110
               BIT6: // evaluate logic for state BIT6
111
112
               begin
                   valid_nxt = 1'b0;
state_nxt = BIT7;
113
114
115
116
               BIT7: // evaluate logic for state BIT7
117
118
               begin
119
               begin
                   valid_nxt = 1'b0;
if (signal == 1'b0)
120
121
122
                   state_nxt = IDLE;
end
                   begin
123
124
125
                   else if (signal == 1'b1)
126
                   begin
                        state_nxt = BIT8;
127
128
                   end
129
130
               end
131
132
133
               STOP: // evaluate logic for state STOP
134
135
               begin
                   valid_nxt = 1'b0;
if (signal == 1'b1)
136
137
                   state_nxt = START;
end
138
139
140
                   else if (signal == 1'b0)
141
142
                   begin
143
                        state_nxt = IDLE;
                   end
144
145
               end
146
               default: // should not be reachable if the state register is initialised and updated correctly
147
148
                   valid_nxt = 1'b0;
state_nxt = BREAK;
149
150
               end
151
152
          endcase
     end
153
154
155
      // assign values to output ports
      assign valid = state_nxt;
156
157
      endmodule
158
159
```

<u>VPL</u>

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You are logged in as Thomas Stirling Valdez (Log out) 5EIBO

Data retention summary

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