



الأكاديمية العربية للعلوم والتكنولوجيا والنقل البحري
Arab Academy for Science, Technology & Maritime Transport

Satellite Remote Sensing Image -RSI-CB256

Satellite image Classification Dataset-RSI-CB256

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Introduction

The analysis of remote sensing (RS) images and its numerous applications have made significant strides in recent years. There is a growing need for the automatic interpretation of RS photos as they are now more readily available than previously. The benchmark datasets are crucial building blocks for creating and evaluating clever interpretation algorithms in this situation. This article discusses the issue of how to quickly create a good benchmark dataset for RS image interpretation after examining the existing benchmark datasets in the research community of RS image interpretation. To be more precise, using bibliometric analyses, we first assess the difficulties encountered when creating intelligent algorithms for RS picture interpretation. The general advice on producing benchmark datasets effectively is then presented.

In addition to the offered guidelines, we provide an example of how to develop an RS image dataset, namely Million-AID, a new large-scale benchmark dataset containing a million examples for RS image scene classification. Finally, certain obstacles and opportunities in RS picture annotation are highlighted to aid research in benchmark dataset construction. We expect that our study will give the RS community a broader view on creating large-scale and useful image collections for future research, particularly data-driven ones.

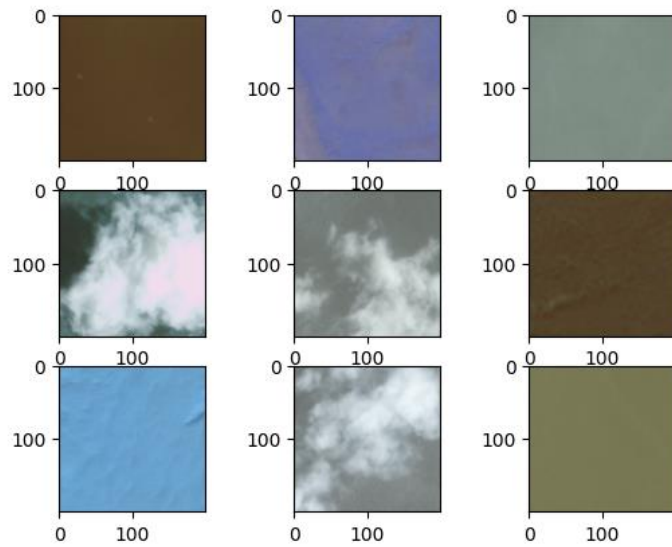
Related Work

Datasets with Annotations for RS Image Interpretation The interpretation of RS pictures has become increasingly relevant in a wide range of applications, attracting significant academic attention. As a result, numerous datasets have been created to aid in the development of RS image interpretation algorithms. We provide a systematic evaluation of existing RS image datasets concerning the current mainstream of RS image interpretation tasks, such as scene categorization, object detection, semantic segmentation, and change detection, using material published over the last decade.

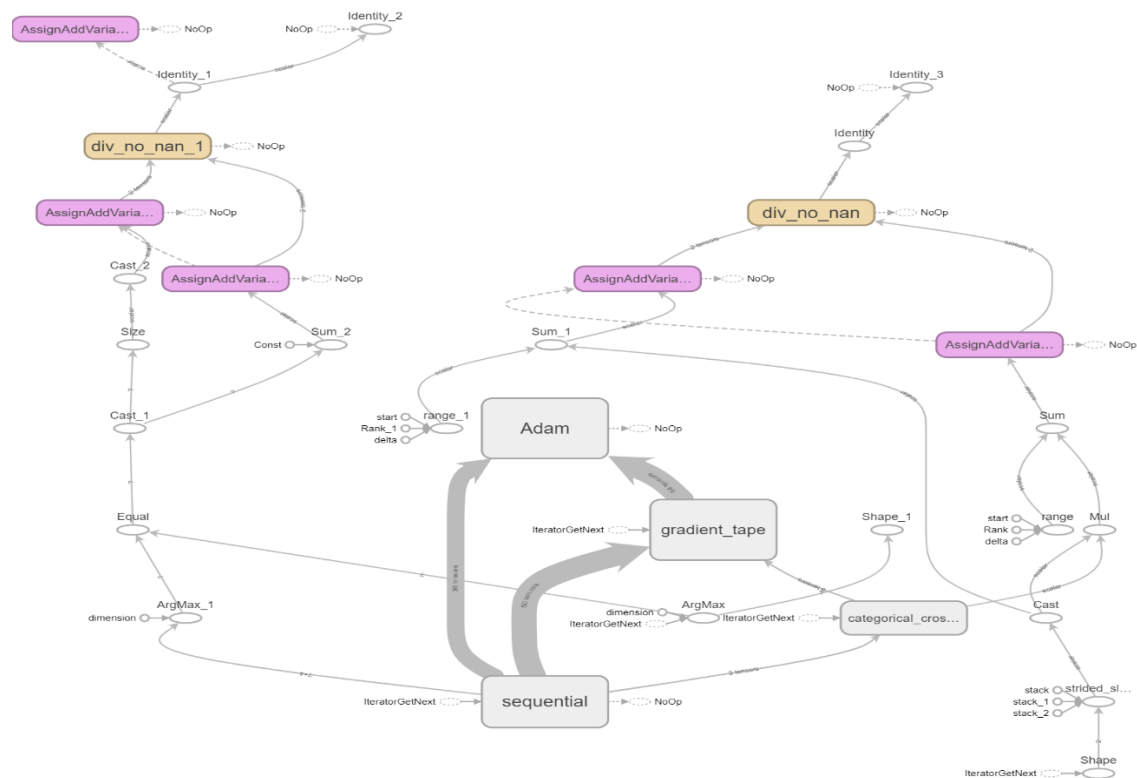
Satellite image Classification Dataset-RSI-CB256 classes

Classes	Size
Cloudy	1500 image
Desert	1131 image
Green-area	1500 image
Water	1500 image

Dataset Sample



Model Graph



Keras Model structure

```
model = Sequential()

model.add(Conv2D(96, (3, 3), padding = 'same', input_shape=(200, 200, 3)))
model.add(Activation('relu'))
model.add(Conv2D(96, (3, 3), padding = 'same'))
model.add(Activation('relu'))
model.add(Conv2D(96, (3, 3), padding = 'same', strides = (2,2)))
model.add(Dropout(0.5))

model.add(Conv2D(192, (3, 3), padding = 'same'))
model.add(Activation('relu'))
model.add(Conv2D(192, (3, 3), padding = 'same'))
model.add(Activation('relu'))
model.add(Conv2D(192, (3, 3), padding = 'same', strides = (2,2)))
model.add(Dropout(0.5))

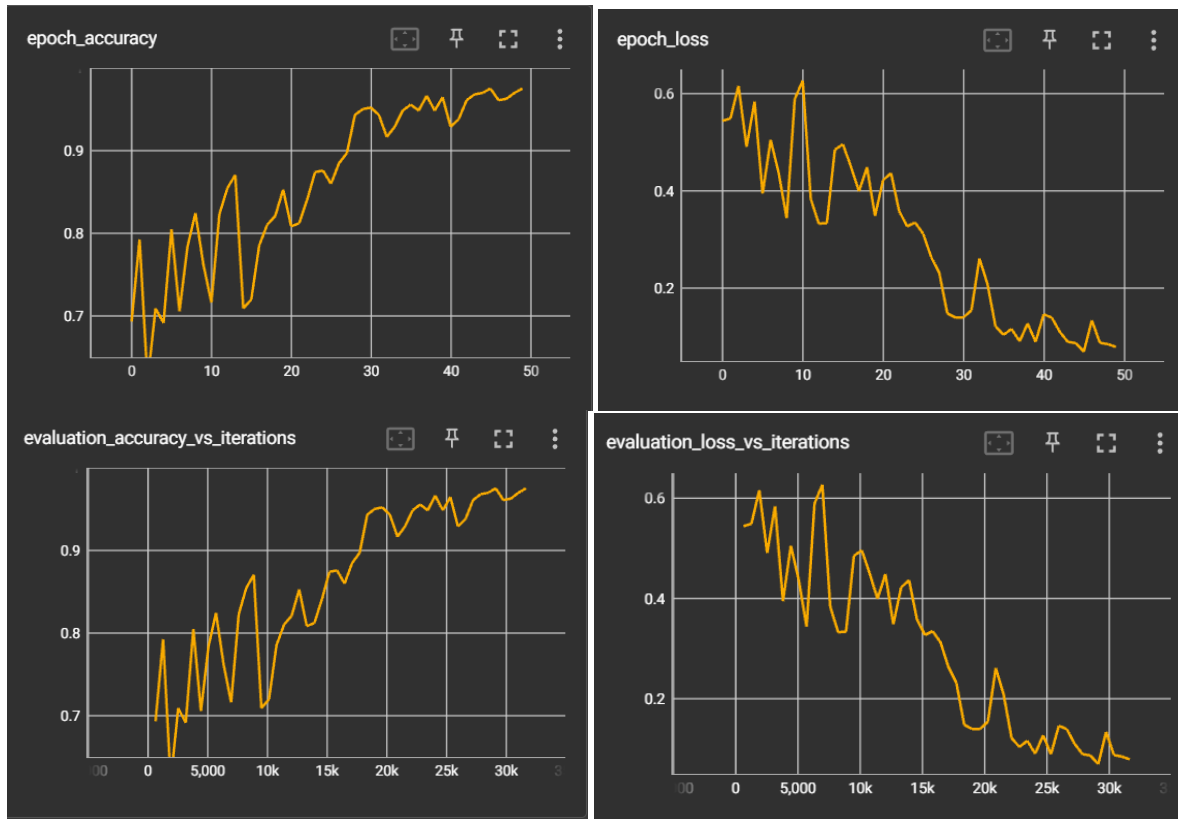
model.add(Conv2D(192, (3, 3), padding = 'same'))
model.add(Activation('relu'))
model.add(Conv2D(192, (1, 1), padding = 'valid'))
model.add(Activation('relu'))
model.add(Conv2D(4, (1, 1), padding = 'valid'))

model.add(GlobalAveragePooling2D())
model.add(Activation('sigmoid'))
```

Model summary

Layer (type)	Output Shape	Param #
conv2d (Conv2D)	(None, 200, 200, 96)	2688
activation (Activation)	(None, 200, 200, 96)	0
conv2d_1 (Conv2D)	(None, 200, 200, 96)	83040
activation_1 (Activation)	(None, 200, 200, 96)	0
conv2d_2 (Conv2D)	(None, 100, 100, 96)	83040
dropout (Dropout)	(None, 100, 100, 96)	0
conv2d_3 (Conv2D)	(None, 100, 100, 192)	166080
activation_2 (Activation)	(None, 100, 100, 192)	0
conv2d_4 (Conv2D)	(None, 100, 100, 192)	331968
activation_3 (Activation)	(None, 100, 100, 192)	0
conv2d_5 (Conv2D)	(None, 50, 50, 192)	331968
dropout_1 (Dropout)	(None, 50, 50, 192)	0
conv2d_6 (Conv2D)	(None, 50, 50, 192)	331968
activation_4 (Activation)	(None, 50, 50, 192)	0
conv2d_7 (Conv2D)	(None, 50, 50, 192)	37056
activation_5 (Activation)	(None, 50, 50, 192)	0
conv2d_8 (Conv2D)	(None, 50, 50, 4)	772
global_average_pooling2d (GlobalAveragePooling2D)	(None, 4)	0
activation_6 (Activation)	(None, 4)	0
Total params: 1,368,580		
Trainable params: 1,368,580		
Non-trainable params: 0		

Model Evaluation Metrics

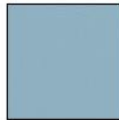


Model Results

Prediction: desert
Actual: desert



Prediction: desert
Actual: desert



Prediction: desert
Actual: water



Prediction: desert
Actual: desert



Prediction: desert
Actual: desert



Prediction: water
Actual: water



Prediction: cloudy
Actual: cloudy



Prediction: green_area
Actual: green_area

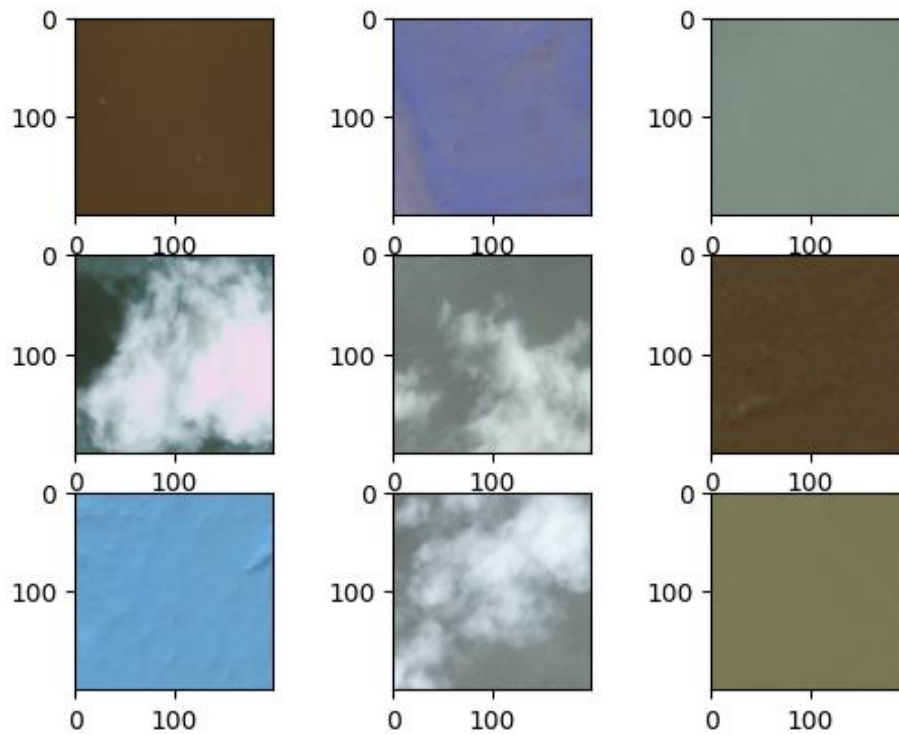


Prediction: green_area
Actual: green_area



Proposed Model & Experimental Work – TF Model

Dataset Sample



Model structure

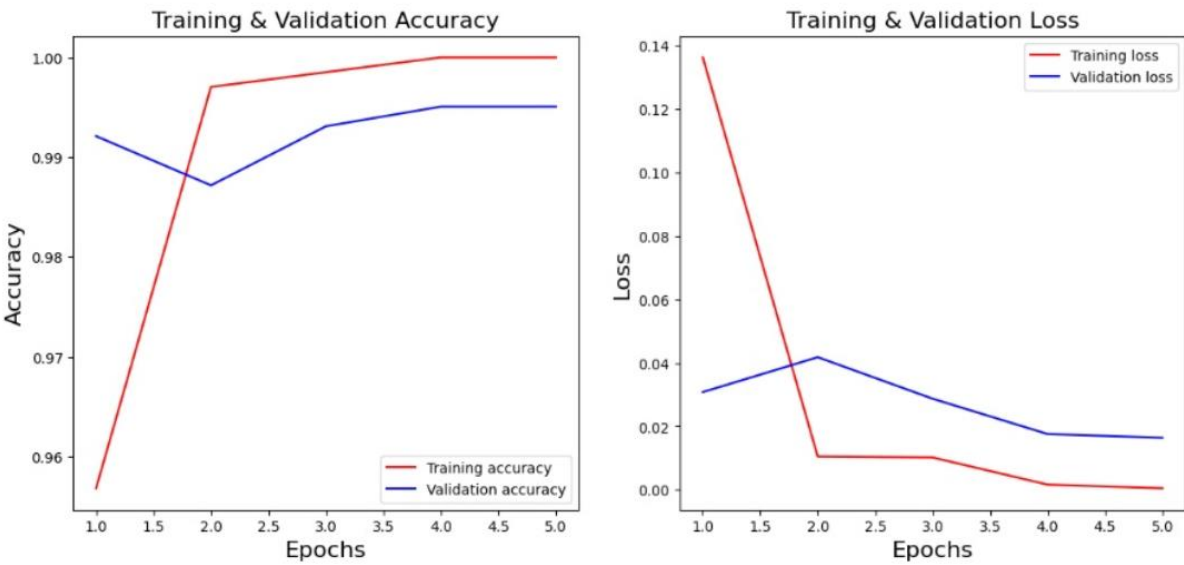
```
flatten_layer = layers.Flatten()
dense_layer_1 = layers.Dense(50, activation='relu')
dense_layer_2 = layers.Dense(20, activation='relu')
prediction_layer = layers.Dense(4, activation='softmax')

model = models.Sequential([
    base_model,
    flatten_layer,
    dense_layer_1,
    dense_layer_2,
    prediction_layer])
```

Model Summary

Model: "sequential"		
Layer (type)	Output Shape	Param #
vgg16 (Functional)	(None, 6, 6, 512)	14714688
flatten (Flatten)	(None, 18432)	0
dense (Dense)	(None, 50)	921650
dense_1 (Dense)	(None, 20)	1020
dense_2 (Dense)	(None, 4)	84
Total params: 15,637,442		
Trainable params: 922,754		
Non-trainable params: 14,714,688		

Model Evaluation Metrics



Model Results

Prediction: green_area
Actual: green_area



Prediction: cloudy
Actual: cloudy



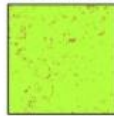
Prediction: green_area
Actual: green_area



Prediction: water
Actual: water



Prediction: desert
Actual: desert



Prediction: green_area
Actual: green_area



Prediction: green_area
Actual: green_area



Prediction: water
Actual: water



Prediction: water
Actual: water



Conclusion

In conclusion both models are quite accurate but TF model needs much less computation power. Training the hand-crafted model required extensive GPU performance, with multiple training trials crashing mid-session. This is most probably due to the intrinsic properties of the dataset images, as well as possible outlier corrupt images in the original files. However, once trained, the model provides satisfactory results that could easily be extrapolated upon for future use.

References

Remote Sensing: Models and Methods for Image Processing

By Robert A. Schowengerdt

https://books.google.com.eg/books?hl=en&lr=&id=KOXNaDH0X-IC&oi=fnd&pg=PP1&dq=Satellite+Remote+Sensing+Image+classification+-RSI-CB256&ots=sonWEOCaOC&sig=tr4NVPJ_UcVsjIovF9qmjHOE5ts&redir_esc=y#v=onepage&q&f=false

Convolutional Neural Networks for Large-Scale Remote-Sensing Image Classification

By Emmanuel Maggiori; Yuliya Tarabalka; Guillaume Charpiat; Pierre Alliez

<https://ieeexplore.ieee.org/abstract/document/7592858/authors#authors>